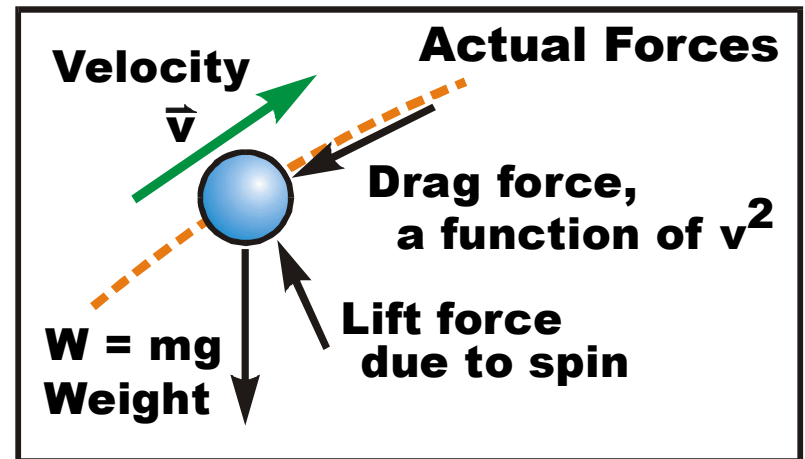


# Projectile Notes

1. **Definition of a Projectile:** An object that is “projected” or thrown, which has no capacity for self-propulsion.

2. **Actual forces on a Projectile:**  
Drag, lift due to spin, weight, wind.

3. Are the forces on a projectile (other than weight) significant?  
In other words, does the ideal projectile model “fit” or not?

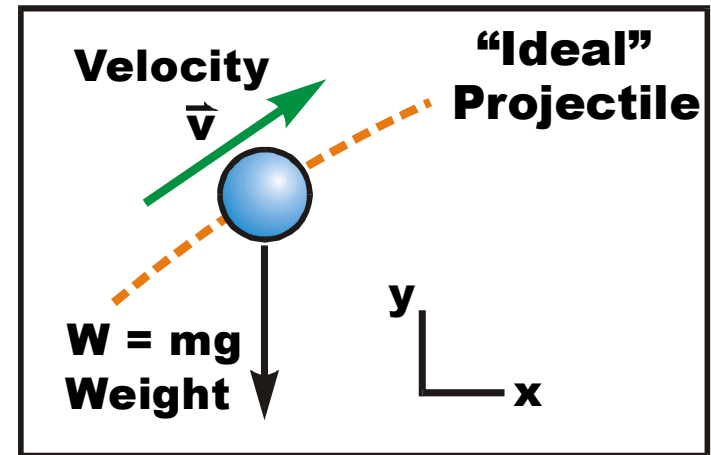


For low speed objects with reasonable mass, e.g. a shot put, or a baseball, tennis ball or golf ball tossed softly across a room, the ideal projectile model “fits” relatively well.

For high speed objects, e.g. a hit or thrown baseball, a well-hit golf ball or tennis ball, etc., drag and other forces are significant and our ideal model is not accurate. For example, a well-hit home run, by ideal theory, will travel nearly 750 ft. In reality it only travels around 450 ft—a significant difference!

Light objects, e.g. a ping pong ball, feather, foam ball, etc., do not fit the ideal model very well. **A relatively small drag or spin force markedly affects the ball because the ball has such low mass.**

**Interesting fact:** A well-hit golf ball travels farther than ideal theory predicts because of lift due to spin.



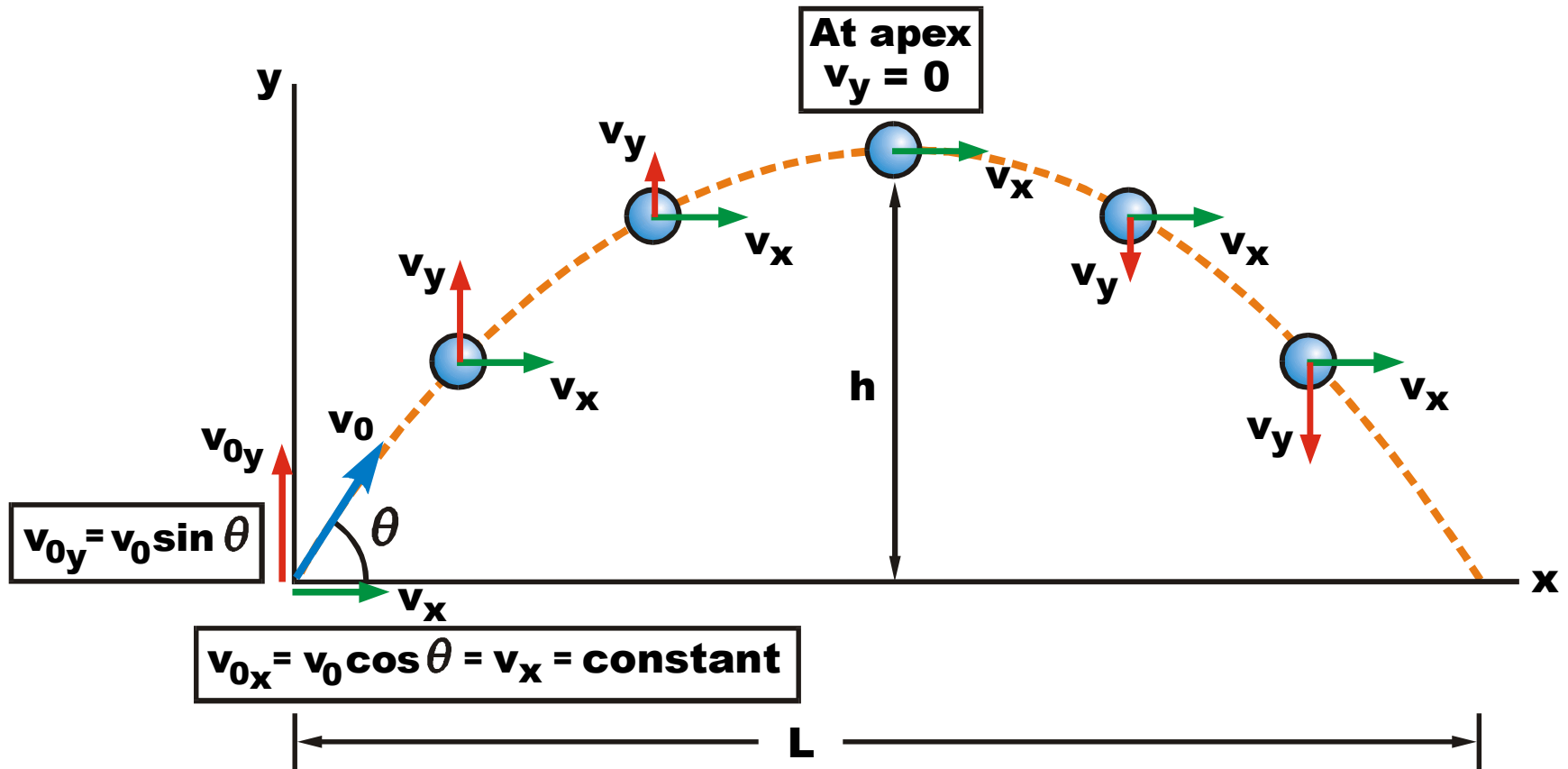
**4. "Ideal" Projectile:** The only force is weight.  
(This is what we will cover in this class.)

**5. Ideal Projectile:** If the only force is weight, then the **x** velocity stays constant. The **y** velocity changes with time and position.

6. Ideal Projectile: If the only force is weight, then...

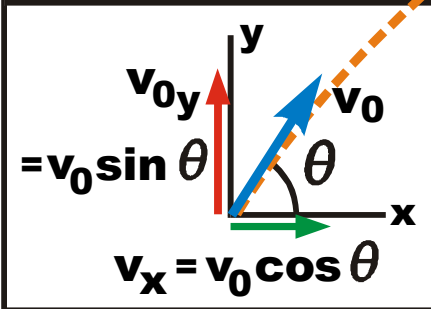
The **x** velocity stays constant.

The **y** velocity changes with time and position.



**7. Ideal Projectile Equations:** If the only force is weight, then the **x velocity stays constant** ( $a_x = 0$ ). The **y velocity changes with time and position** (y acceleration  $a_y = -g$ ).

Remember to use the correct  $g$  for your units!



**(Ideal) Projectile Equations**

	<u>x</u>	<u>y</u>
<b>Accel:</b>	0	-g
<b>Velocity:</b>	$v_x = v_0 \cos \theta$	$v_y = v_{0y} - gt$
(where, $v_{0y} = v_0 \sin \theta$ )		
<b>Position:</b>	$x = x_0 + v_x t$	$y = y_0 + v_{0y} t - \frac{1}{2} g t^2$
<b>An additional y equation:</b>		$v_y^2 = v_{0y}^2 - 2g(y - y_0)$

**SI Units:**  
 $g = 9.81 \text{ m/s}^2$

**US Units:**  
 $g = 32.2 \text{ fps}^2$

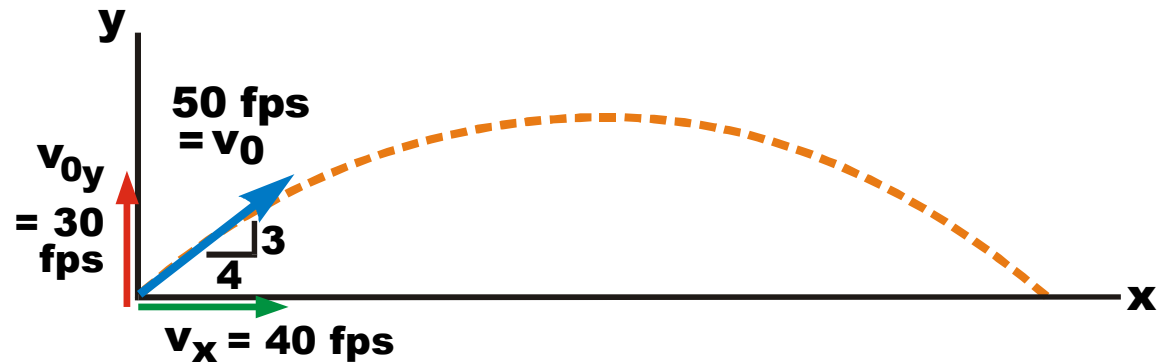
## 8. An ideal projectile trajectory is a *parabola*.

The position eqns  
are **parametric eqns**:

$$x = f(t) \text{ and } y = g(t^2)$$

Eliminating  $t$  from  
these yields a  
parabola:  $y = f(x^2)$

**A simple numerical example:**



**Position Eqns:**

$$x = x_0 + v_x t$$

$$y = y_0 + v_{0y}t - \frac{1}{2}gt^2$$

$$x = 40t$$

$$y = 30t - 16.1t^2$$

**Eliminate  $t$  :**

$$t = \frac{x}{40}$$

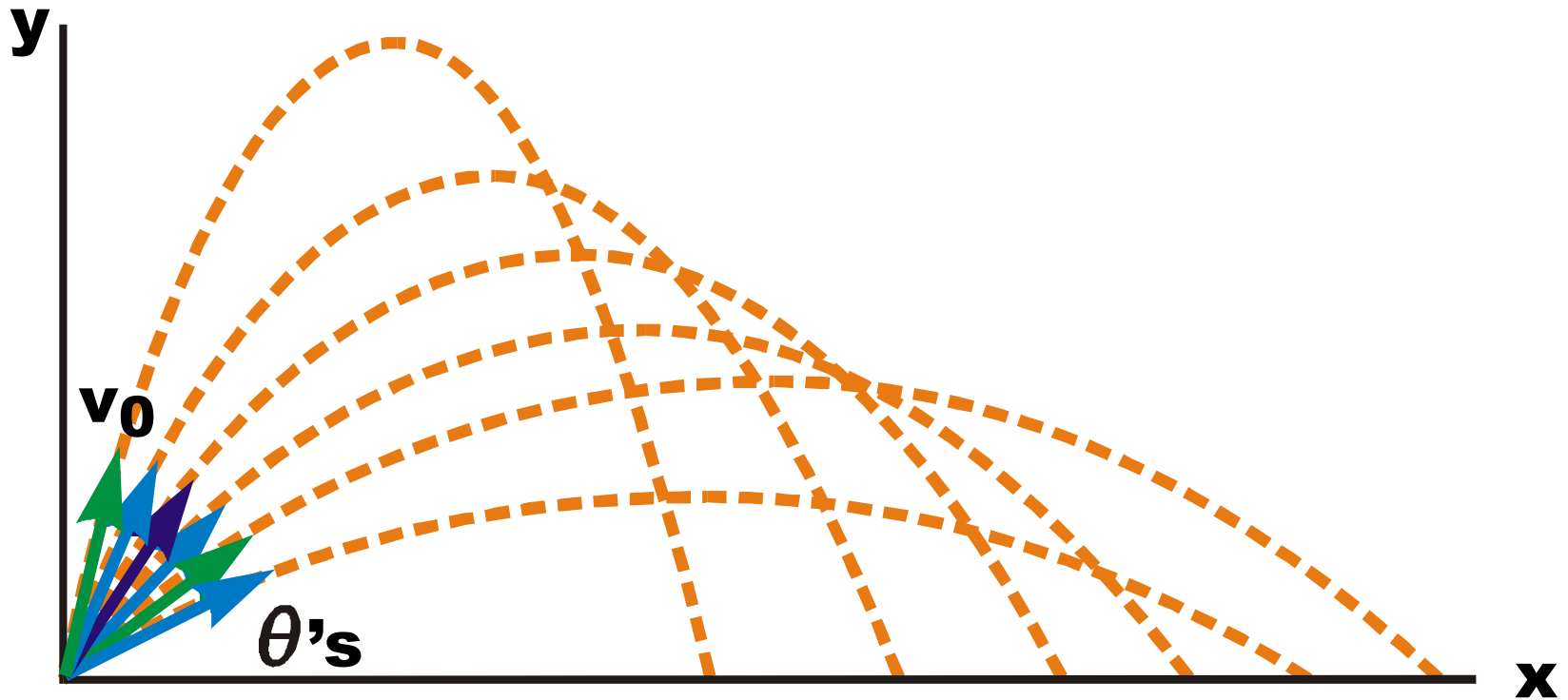
$$y = \frac{30}{40}x - \frac{16.1}{40^2}x^2$$

**The result is a parabola :**

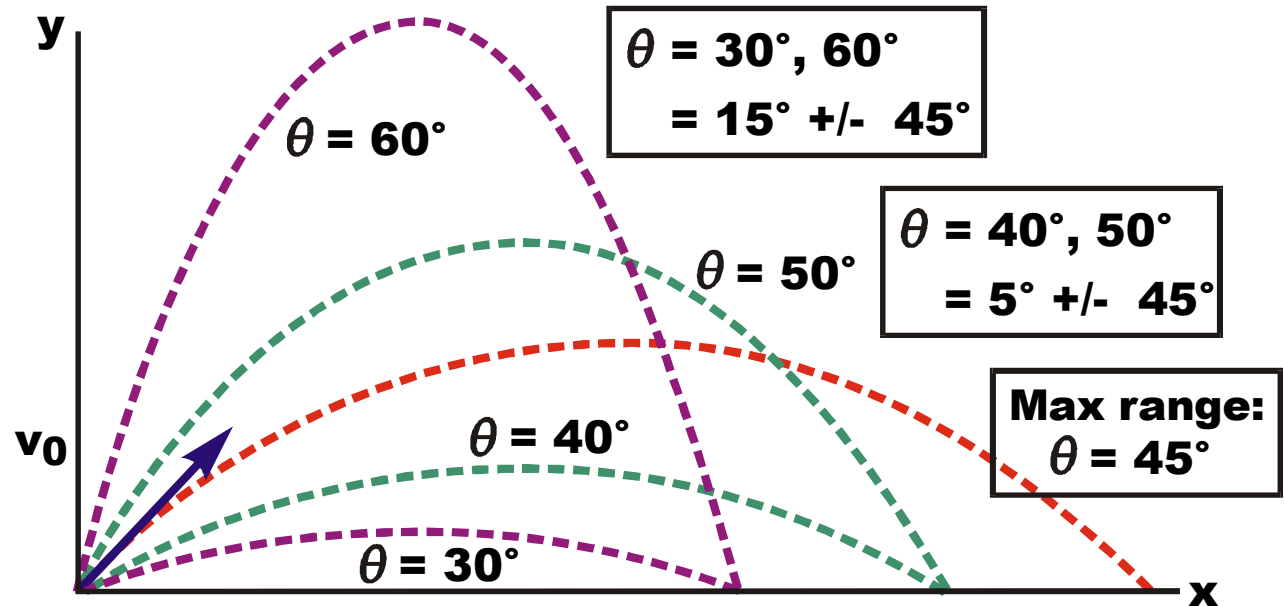
$$y = .75x - .010063x^2$$

We rarely use this fact to solve a problem,  
but you should know it.

9. For each launch speed,  $v_0$ , and angle  $\theta$  there is a different parabolic trajectory.



10. For a given launch speed,  $v_0$ , the max range is at  $\theta = 45^\circ$ . For the same  $v_0$ , launch angles at equal angular increments above and below 45 give (equal) ranges shorter than the max range.



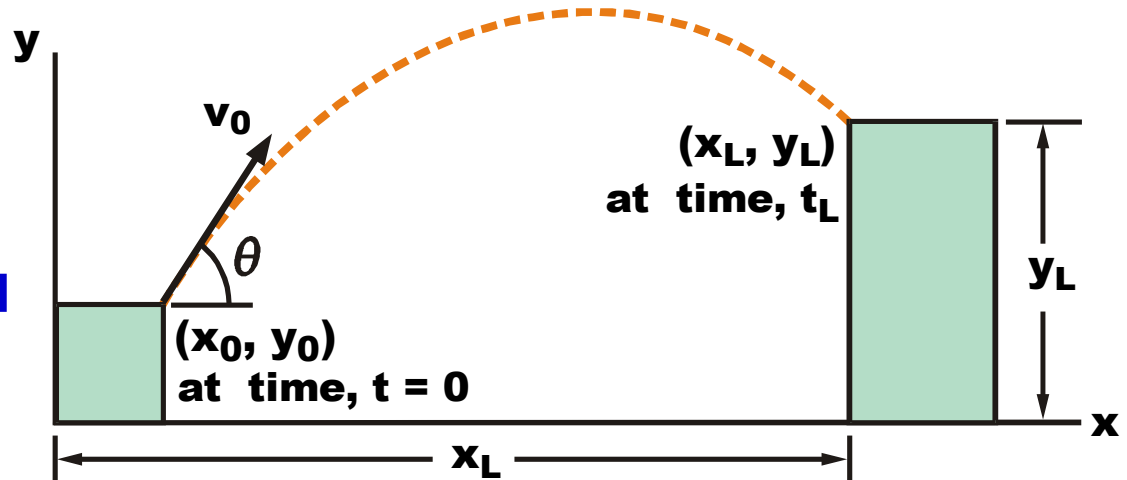
**For a given  $v_0$ , max range at  $\theta = 45^\circ$   
(on level ground)**

**For a given  $v_0$ , launch angles at equal  
angular increments above and below  $45^\circ$   
give (equal) ranges shorter than the  
max range.**

11. A general projectile motion problem involves seven “pieces” of information [  $x_0$ ,  $y_0$ ,  $\theta$ ,  $x_L$ ,  $y_L$ , and  $t_L$  ].

### General Projectile Problem

Usually you are given **five** of these and asked to **find the remaining two**, usually applying the two **position equations**.



**Projectile Problem Variables: (7 pieces of info)**

**Launch Location: ( $x_0$ ,  $y_0$ )**

**Launch Velocity and Angle: ( $v_0$  at  $\theta$ )**

**Landing Location and Time: ( $x_L$ ,  $y_L$ ) at time  $t_L$**

**General Problem: Given 5 out of 7 of these “pieces” of info. Use the two position equations to solve for the remaining two:**

**Position:**

$$x = x_0 + v_x t$$

$$y = y_0 + v_{0y} t - \frac{1}{2} g t^2$$

**where,**

$$v_x = v_0 \cos \theta$$

$$v_{0y} = v_0 \sin \theta$$