

Systems Biology

Dynamic Flux Balance Analysis Models in SBML

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Abstract

Motivation: Systems biology models are typically simulated using a single formalism such as ordinary differential equations (ODE) or stochastic methods. However, more complex models require the coupling of multiple formalisms since different biological concepts are better described using different methods, e.g., stationary metabolism is often modeled using flux-balance analysis (FBA) whereas dynamic changes of model components are better described via ODEs. The coupling of FBA and ODE frameworks results in dynamic FBA models. A major challenge is how to describe such hybrid models coupling multiple frameworks in a standardized way, so that they can be exchanged between tools and simulated consistently and in a reproducibly.

Results: This paper presents a scheme and implementation for encoding dynamic FBA models in the Systems Biology Markup Language (SBML), which allows multi-framework computational models to be exchanged between software tools. The paper shows the feasibility of the approach using various example models and demonstrates that different tools are able to simulate the hybrid models and agree on the results. As part of this work, two independent implementations of a multi-framework simulation method for dynamic FBA have been developed supporting such models: *iBioSim* and *sbmlutils*.

Availability: All materials and models are available from <https://github.com/matthiaskoenig/dfba>. The tools used in this project are freely available: *iBioSim* at <http://www.async.ece.utah.edu/ibiosim> and *sbmlutils* at <https://github.com/matthiaskoenig/sbmlutils/>.

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Supplementary information: Supplementary data is available at *Bioinformatics* online.

1 Introduction

In systems biology, mathematical modeling has been widely used to describe biological systems (Kitano, 2002). The resulting computational models can be simulated and analyzed *in silico* and allow researchers to make predictions which subsequently can be validated experimentally. Furthermore, such models can provide insights in biological systems that would be difficult to obtain in a wet lab. A key challenge, however, is ensuring that these modeling efforts are reproducible and easily exchanged between research groups such that and results can be validated and existing models can be reused to build more complex models. To achieve these goals, standard model representation formats for the model exchange, such as the Systems Biology Markup Language (SBML) (Hucka *et al.*, 2003) or CellML (Hedley *et al.*, 2001), have been established. Both

SBML and CellML have been successfully applied to the encoding of models using a single modeling framework, but the support of multiple framework adds new challenges. This paper addresses this problem by developing a methodology and corresponding implementations to support such hybrid modeling efforts, and it demonstrates the successful exchange and reproducibility of such models between two simulation tools.

1.1 Multi-framework computational models

Various simulation and analysis methods have been developed in systems biology, and depending on the biological question different methods are preferred. Kinetic time-course simulation based on ordinary differential equations (ODE) is often employed to observe the dynamics of the entities in a model over time. Depending on the research question and biological system, such simulations can be either deterministic or non-deterministic (stochastic). Other simulation frameworks are boolean (Thomas, 1973;

Kauffman, 1969) models, logical models (Morris *et al.*, 2010) and constraint-based approaches (Bordbar *et al.*, 2014), among others.

Metabolic networks, in particular, are often challenging to model dynamically using ODE approaches because kinetic parameters needed for ODE models are often unavailable (Varma and Palsson, 1994). Hence, steady-state approaches that do not need kinetic information are employed to model metabolism, so called *flux balance analysis* (FBA) (Savinell and Palsson, 1992; Varma *et al.*, 1993) based on constraint-based optimization assuming steady state. This method only requires the connectivity of the reactions and metabolites along with the respective stoichiometry, an objective function (e.g. cell growth), and additional constraints like flux constraints. The idea is to constrain the model based on the stoichiometry of the reactions and optimize the objective function while satisfying the flux constraints. The advantages of using such method include its efficiency and not requiring any kinetic information.

Biological research questions often require the coupling of different model formalisms. One such recent example is the whole-cell model for the *Mycoplasma genitalium* (Karr *et al.*, 2012) that is encoded using a mixture of boolean networks, stochastic processes, differential equations, and FBA.

1.2 Dynamic flux balance analysis

One disadvantage of FBA is that it cannot express the dynamics of the metabolites since it does not change amounts or concentrations of species, but only provides information about the optimal flux distribution for the given optimization problem. Due to this limitation, the field of *dynamic FBA* (DFBA) (Varma and Palsson, 1994) has emerged, which couples the stationary flux distribution resulting from FBA with the kinetic update of the metabolites taken up or consumed by the FBA network, i.e., the FBA submodel is coupled to a kinetic model (ODE) via a multi-framework approach.

Besides the whole-cell model which uses DFBA as a core module, many DFBA models have been constructed for different metabolic pathways. DFBA has been applied in small-scale examples (Varma and Palsson, 1994; Mahadevan *et al.*, 2002; Luo *et al.*, 2006), over medium-size models (Pizarro *et al.*, 2007; Lequeux *et al.*, 2010; Meadows *et al.*, 2010), and up to genome-scale DFBA applications (Hanly and Henson, 2011; Hjersted *et al.*, 2007). For a recent overview, see Table 1 in (Höffner *et al.*, 2013).

The coupling between FBA and kinetic model parts has hereby been implemented via three main approaches, i.e., *static optimization approach* (SOA), *dynamic optimization approach* (DOA), or *direct approach* (DA) Gomez *et al.* (2014). DOA approaches discretize the simulation time and optimize simultaneously over the entire time period by solving a nonlinear programming problem (NLP). The DA approach directly includes the LP solver in the right-hand side of the ordinary differential equations (ODEs). The SOA approach solves the LP at each time step using a Euler forward method assuming constant fluxes over the time step Gomez *et al.* (2014). Most of the published DFBA models use the SOA approach, which is relatively simple to implement and not as computationally demanding (see methods algorithm).

1.3 Exchangeability & reproducibility of models

Despite the multitude of published DFBA models, currently no standard for the exchange of such models exists. Existing models are hard-coded in programming code, e.g., the whole-cell model in MATLAB. Hereby, the mathematical models in their respective formalisms are embedded in the script along with the connections between the kinetic and flux balance parts of the models. As a consequence, it is not possible to exchange existing DFBA models between different software tools. Thus, they cannot be reproduced or validated. This is especially problematic in the case

of DFBA models because often multiple optima can exist for the FBA model part (and the various time steps), and the resulting DFBA solutions are not unique, but depend on the actual implementation, i.e., how an implementation or solver selects one of the possible solutions.

While it is possible to replicate the same scripts in different programming languages, it is impractical to do so as replication is error prone, requires unnecessary work, needs conversions that can lead to data loss, and most importantly does not solve the underlying problem of exchangeability of such models. For these reasons, script replication makes achieving reproducibility difficult and often infeasible. The necessity of an exchange format for DFBA resulted from efforts trying to encode and reproduce the DFBA submodel of the whole-cell model using standards during the whole-cell workshop (Waltemath *et al.*, 2016).

1.4 Model standards

In order to achieve exchangeability and reproducibility of models, standards for the encoding of models have been created. The *de-facto* standard for systems biology models is SBML Hucka *et al.* (2003). SBML core elements are used to describe mathematical models of reaction-based networks and provide the means to encode computational models based on ODEs (deterministic and stochastic). SBML uses packages for extending the functionality of the core elements. While SBML is used to encode mathematical models of biological networks, there are different standards for other purposes: the *Simulation Experiment Description Markup Language* (SED-ML) is used for describing simulations (Waltemath *et al.*, 2011), the *Systems Biology Graphical Notation* (SBGN) is used for describing visualizations (Le Novère *et al.* (2009))), and Combine Archives are used for exchanging collections of modeling files Bergmann *et al.* (2014). The main advantage of using these standards over hard-coding models in code is the ability to exchange models between research groups and reproduce results using various tools that support these standards.

SBML core in combination with the *hierarchical model composition* (comp) package (Smith *et al.*, 2015) and the *flux balance constraints* (fbc) package (Olivier and Bergmann, 2015) is used for describing the multi-framework DFBA models in this work. The comp package is used to construct hierarchical models, providing the means to build built models from submodels and define the interfaces between them. The fbc package is used to encode the FBA submodel consisting of the metabolic network, the flux bounds for the reactions, and an objective function, allowing to perform FBA. In addition, SED-ML is used to describe how each SBML model should be simulated, i.e., provide reproducible example simulation experiments by encoding which simulation algorithm to use and its corresponding parameters, as well as the defining the time course simulations for the DFBA. COMBINE archives are used for the exchange of the encoded models, simulation descriptions and reference solutions.

One of the challenges in current SBML models is the limitation on the expression of models using different formalisms. Although there are several tools that support ODE simulation and FBA, they all support them independently. In order to overcome this challenge, this paper introduces a scheme that allows the coupling of ODE and FBA models. This paper demonstrates that this scheme provides exchangeability and reproducibility by encoding and simulating DFBA models in both iBioSim (Madsen *et al.*, 2012) and sbmlutils König (2017).

2 Methods

2.1 Model encoding

The DFBA models presented in this paper were created in the proposed scheme either using a graphical user interface in iBioSim or a script-based approach in sbmlutils. For a given model, the TOP, FBA,

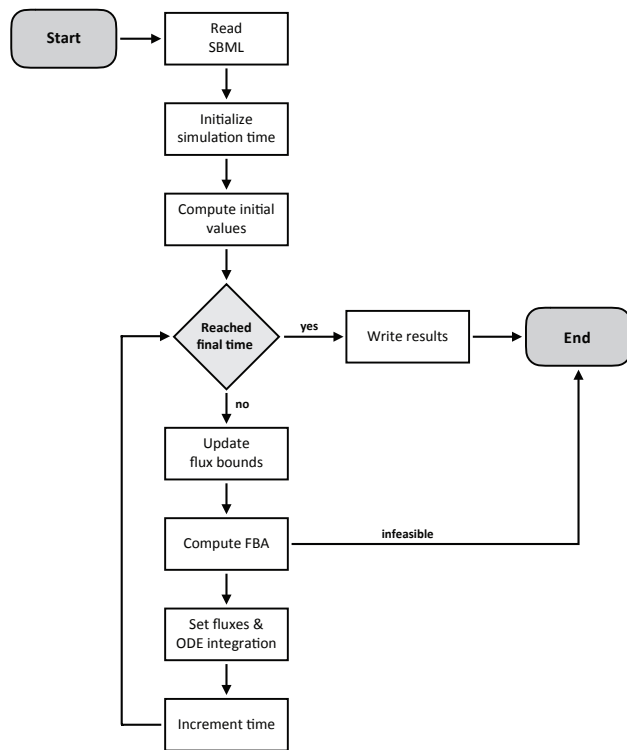


Fig. 1: Overview of the implemented SOA algorithm for DFBA. After initialization of the model, the FBA and kinetic simulations are run in an iterative manner until the simulation end point. In every step, FBA is used to compute the reaction rates of the FBA network. Subsequently, based on the computed FBA rates, the values of the species are updated dynamically. In the SOA approach, FBA fluxes are assumed to be constant within a time step. For a detailed description see the methods section.

BOUNDS, and UPDATE submodels were packaged with respective simulation files using SED-ML in COMBINE archives for the exchange between tools. All models and simulation results are available from <https://github.com/matthiaskoenig/dfba>.

2.2 Stationary optimization approach (SOA)

A stationary optimization approach for DFBA was implemented as a simulation algorithm in *iBioSim* and *sbmlutils* following the simulation scheme depicted in Figure 1.

The first step is the initialization of the model. All of the species and parameters in the model are initialized, where each variable’s initial value is computed. After the initialization step, the FBA submodel is executed. During the FBA step, reaction fluxes are computed using the initial flux bound values where the flux bounds for the reactions come from the top-level using SBML comp *replacements*. In SBML, replacements of parameters and species indicate the top-level entities are the same entity as the one being replaced. Once the fluxes are computed, they are assigned to parameters using assignment rules on the top-level. These parameters are assigned reaction rates computed as functions of the fluxes.

After computing reaction fluxes, the update step is performed concurrently with the dynamic step by computing the time-evolution of every species in the UPDATE and KINETIC submodels. Species that affect any flux bound in the FBA submodel are updated in the top-level. The new bounds are used in the FBA submodel for the next time step. Simulation

time is incremented at the end. If the time limit is reached, then simulation is complete. Otherwise, all of the steps are repeated.

The SOA simulation algorithm has been implemented in *iBioSim* and *sbmlutils*. The *iBioSim* tool uses the structure of (Watanabe and Myers, 2014) for simulation. The *sbmlutils* tool uses *roadrunner* (Somogyi *et al.*, 2015) for the kinetic simulation and *cobrapy* (Ebrahim *et al.*, 2013) to solve the FBA problem. Both *iBioSim* and *sbmlutils* take an SBML file that describes a DFBA model and a SED-ML file that describes the simulation experiment. In the proposed approach, SED-ML is mainly used to indicate which simulation algorithm to use, the time points in which tools should print out the values of the variables, the initial time and the time limit. The SED-ML files provide a minimal simulation experiment to check reproducibility between implementations. The value of each time increment for SOA is defined as a parameter with id *dt* in the SBML model, which can be overwritten by the SED-ML file for the actual simulation. Ontology terms for the description of DFBA simulation algorithms have been introduced in the Kinetic Simulation Algorithm Ontology (KISAO) (Zhukova *et al.*, 2011) and are used in the SED-ML descriptions, i.e., KISAO:0000499 (DFBA) and KISAO:0000500 (SOA-DFBA).

All example models are available as COMBINE Archives with example results from the two implementations. The COMBINE archives include the SBML model files, a SED-ML file, and the results created by each software.

2.3 Reproducibility between tools

In order to test interoperability based on the proposed scheme, models were built in both the *iBioSim* and the *sbmlutils* tools. Models built in *iBioSim* were then imported into *sbmlutils* and vice-versa to check whether models could be interpreted by both tools consistently. This was done in an iterative manner and resulting issues were solved by clarifying the encoding scheme, e.g., by adding additional rules which resolved ambiguities.

Reproducibility of DFBA models is challenging because there may exist several possible outcomes that satisfy the objective function and constraints of the FBA models. Depending on how a solver and implementation selects one of the multiple optima different trajectories can result from the DFBA simulation. The issue of multiple optima was solved by guaranteeing uniqueness of the solution based on *Flux Variability Analysis* (FVA) in every time step. FVA gives the possible minimal and maximal fluxes for each reaction in each step of the simulation. If all minimal fluxes are equal to all maximal fluxes for a time point a solution is unique in the time point. If all time points are unique the solution is unique. As a practical note: If the solution is not unique, the addition of additional constraints to the FBA problem allows to make the solution unique.

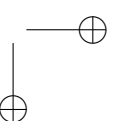
Reproducibility of the model simulations was tested by comparing the numerical SOA results between the two tools for models with unique solutions. Namely, simulators should produce the same results (within some tolerance) for models with unique solutions.

3 Results

The major result of this work is the creation of the first schema for encoding DFBA in SBML, demonstrating multi-framework computational models to be exchanged and reproduced between tools. In the following the schema and its application to multiple DFBA models is presented.

3.1 Schema for dynamic flux balance analysis

This paper proposes for the first time a schema to encode hybrid models, such as DFBA models, in SBML. The developed schema



The top-level model ties together the three different submodels using SBML comp replacements and replacedBy constructs with the interface

The next example is an encoding and reproduction of results from a published DFBA model of diauxic growth of *E. coli* (Mahadevan *et al.*, 2002) consisting of four reactions between four metabolites, i.e. glucose (*Glcxt*), oxygen (O_2), acetate (A_c) and biomass (X). The model can grow either aerobically on acetate (v_1), aerobically on glucose (v_2 or v_3) or anaerobically convert glucose to acetate:

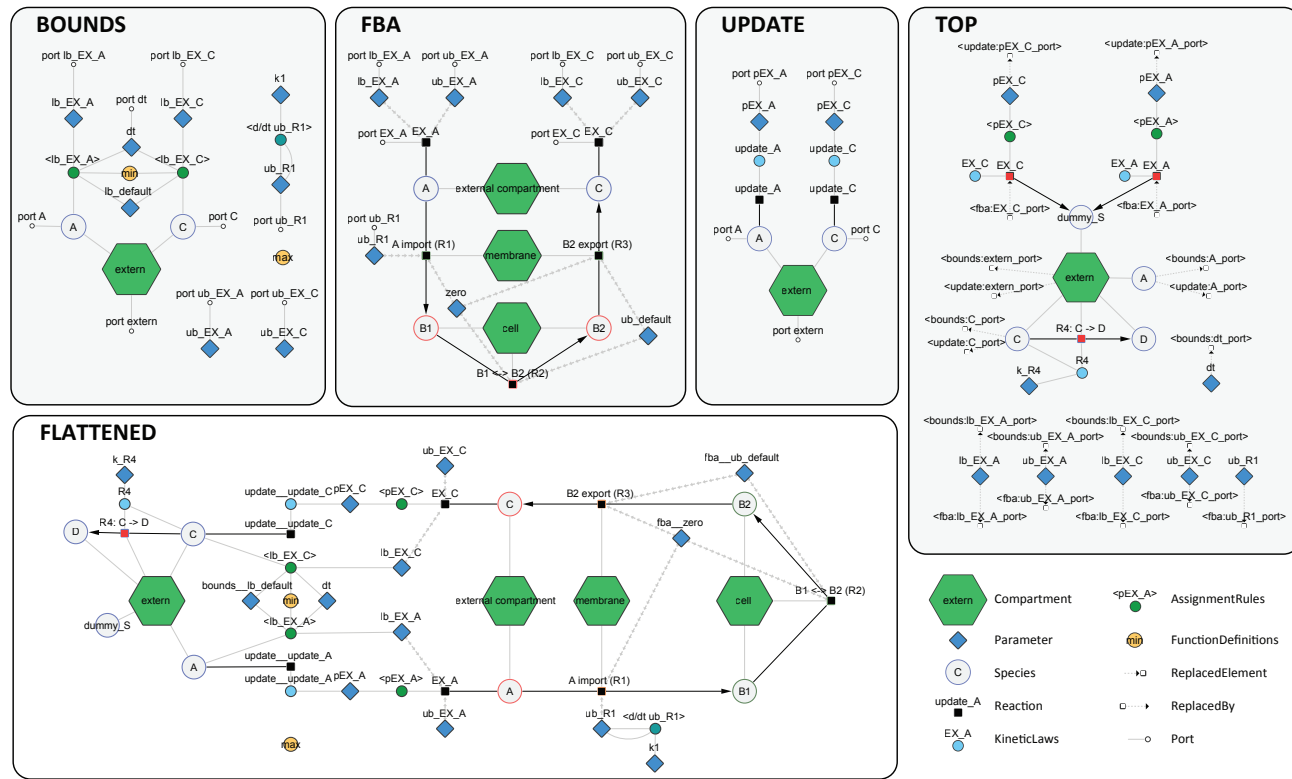


Fig. 3: Detailed schema of the toy wholecell model. The figure shows the components in the TOP, UPDATE, BOUNDS and FBA submodels and their connection via the respective ports. The flattened model shows the connections between the different submodels. The figures are available as interactive graphs in Cytoscape as Supplementary Material 4. The figure was created with cy3sbml using the SBML models (König *et al.*, 2012).

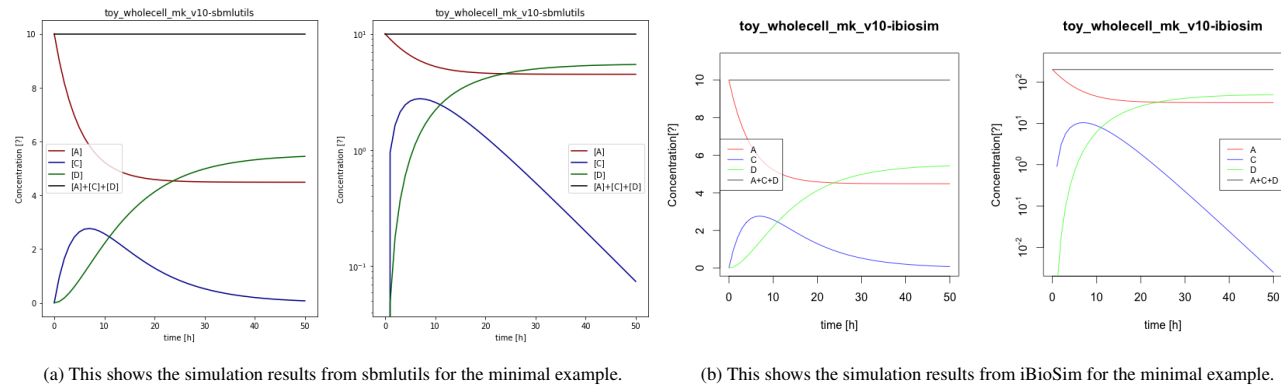


Fig. 4: These figures show the simulation results for the same model in two different tools. This demonstrates that models can be exchanged by different tools using standards and the results can be reproduced when using the same simulation algorithm.

The kinetic part of the model is described by the following differential equations:

$$\begin{aligned}
 v1 : 39.43A_c + 35O_2 &\rightarrow X \\
 v2 : 9.46Glxt + 12.92O_2 &\rightarrow X \\
 v3 : 9.84Glxt + 12.73O_2 &\rightarrow 1.24A_c + X \\
 v4 : 19.23Glxt &\rightarrow 12.12A_c + X
 \end{aligned}$$

$$\begin{aligned}
 \frac{dGlxt}{dt} &= A^{Glxt} \nu X \\
 \frac{dA_c}{dt} &= A^{A_c} \nu X \\
 \frac{dO_2}{dt} &= A^{O_2} \nu X + k_L a (0.21 - O_2) \\
 \frac{dX}{dt} &= (v1 + v2 + v3 + v4) X
 \end{aligned}$$

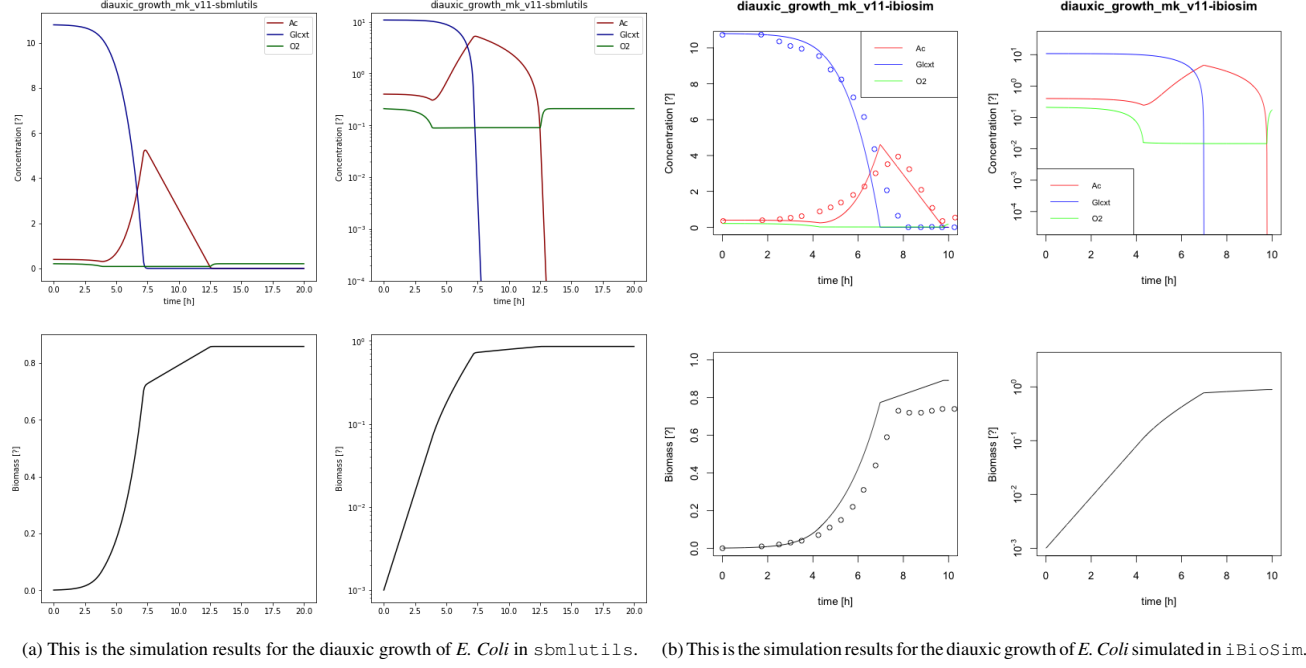


Fig. 5: This plot shows the results for the model representing diauxic growth in *E. coli*. The model is able to reproduce the general behavior captured from experiment data. There is an exponential cell growth while glucose is present in the model, but when the cell runs out of glucose, growth slows down and is affected mostly by oxygen. However, when the cell runs out of glucose and oxygen, growth diminishes significantly.

where A^{Glcxt} , A^{Ac} , A^{O_2} are the respective rows of each variable in the stoichiometry matrix and k_{La} is the mass transfer coefficient of oxygen. For a detailed description see (Mahadevan et al., 2002).

The model is available as COMBINE archive in Supplementary Material 4, the Cytoscape visualization as Supplementary Material 4.

The results in Figure 5 show that the cell has an exponential growth until the cell runs out of glucose, which at this point the cell grows linearly due to oxygen. When both oxygen and glucose run out, the cell growth stagnates. Experimental data from (Varma and Palsson, 1994) is plotted alongside the simulation results. The model is able to capture the behavior observed in the experimental data. The results are equivalent to the models in (Mahadevan et al., 2002).

3.4 *E. coli* core

To demonstrate the feasibility of the proposed scheme and method for real-world examples of DFBAs, a larger metabolic network for the core metabolism of *E. coli* (Orth J, 2010) is encoded in the proposed schema and simulated as shown in Figure 6. The model is available as COMBINE archive in Supplementary Material 4.

The encoding of larger scale examples demonstrates the scalability of the proposed approach. While *sbmlutils* is able to find a solution for the model, *iBioSim* cannot as it runs into an unfeasible solution in the middle of simulation. This captures the well-known problem of DFBA with multiple solutions. Depending on the solutions the simulator dynamically picks, different solutions may arise. Even though multiple solutions may exist, tools typically pick solutions deterministically. Hence, tools can reproduce their own results, but results will vary if different tools use different solvers. Without the use of standards, this could never be demonstrated because variations in results could be due to discrepancies in the model, and not in the tool.

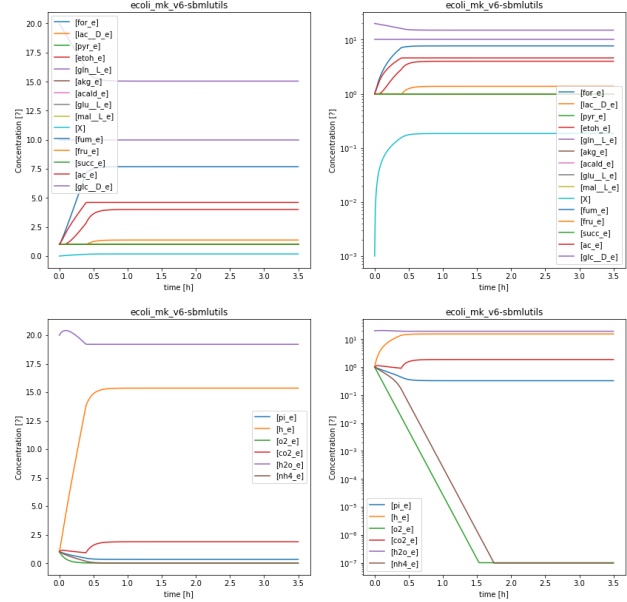


Fig. 6: We demonstrate that the proposed approach can be used in larger models, such as the *E. coli* model described in the paper. This model shows one of the problems of DFBA, where multiple solutions that realize an objection function is obtained. While *sbmlutils* can find a solution for the model, *iBioSim* runs into an unfeasible solution.

4 Discussion

Modularity of models, the ability to encode multi-framework models, and reproducibility of models is indispensable for encoding more complex models in computational biology. In this work we presented such an approach, which allows a clear separation of the different modeling frameworks via comp submodels and defining the interfaces between the submodels. To our knowledge, this paper proposes and implements for the first time an exchangeable and reproducible multi-framework scheme. This scheme for encoding DFBA models in a standard way has been implemented in two different tools, demonstrating the exchangeability and reproducibility of our approach on various examples models like diauxic growth in *E.coli*. `iBioSim` and `sbmlUtils` are freely available for download and offer the necessary infrastructure for anyone to develop DFBA models using the proposed scheme.

Currently, the proposed approach supports the modeling of DFBA models based on the SOA simulation algorithm. Hence, our approach only covers a subset of DFBA algorithms and possible frameworks which could be coupled.

Most DFBA models are stiff and small time steps are required for stability, making the SOA approach computationally expensive. Another disadvantage of the SOA approach is that it requires a fixed time step that has to be small enough to give accurate results. Future directions are to explore adaptive time steps for executing the DFBA with SOA and alternative DFBA approaches, such as DOA or DA and extending our scheme to encode such models.

Our current is limited to the coupling of ODE and FBA frameworks. Different types of hybrid model, such as a mixture of differential equations, stochastic processes, and boolean models still need further study. The proposed approach of decoupling frameworks via hierarchical model composition could work similarly for other modeling frameworks like boolean models.

So far, only small to medium-size DFBA models have been encoded in our proposed approach. For future work, we will encode genome-scale metabolic models. This would allow us to assess the scalability and performance of the proposed approach.

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Supplementary Material

- Schema for DFBA encoding in SBML
- Minimal DFBA model - COMBINE archive
- Minimal DFBA model - Cytoscape session file for cy3sbml.
- Toy glycolysis DFBA model - COMBINE archive
- Toy glycolysis DFBA model - Cytoscape session file for cy3sbml.
- Diauxic DFBA model - COMBINE archive
- Diauxic DFBA model - Cytoscape session file for cy3sbml.

- *E.coli* core DFBA model - COMBINE archive

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