

IT/PC/B/T/411

Machine Learning

Deep Learning Basics
Lecture 06: Convolutional NN

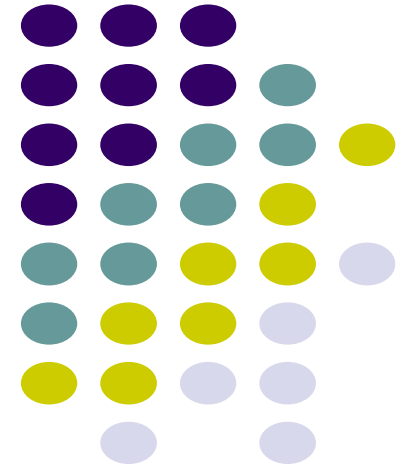
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Review: convolutional layers

Convolution: two dimensional case

Input

a	b	c	d
e	f	g	h
i	j	k	l

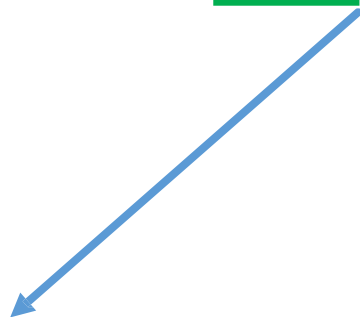
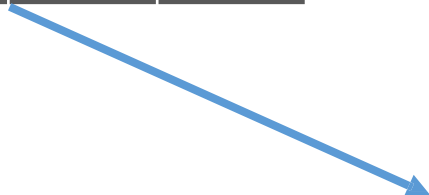
Kernel/filter

w	x
y	z

$wa + bx +$
 $ey + fz$

$bw + cx +$
 $fy + gz$

Feature map



Convolutional layers

the same weight shared for all output nodes

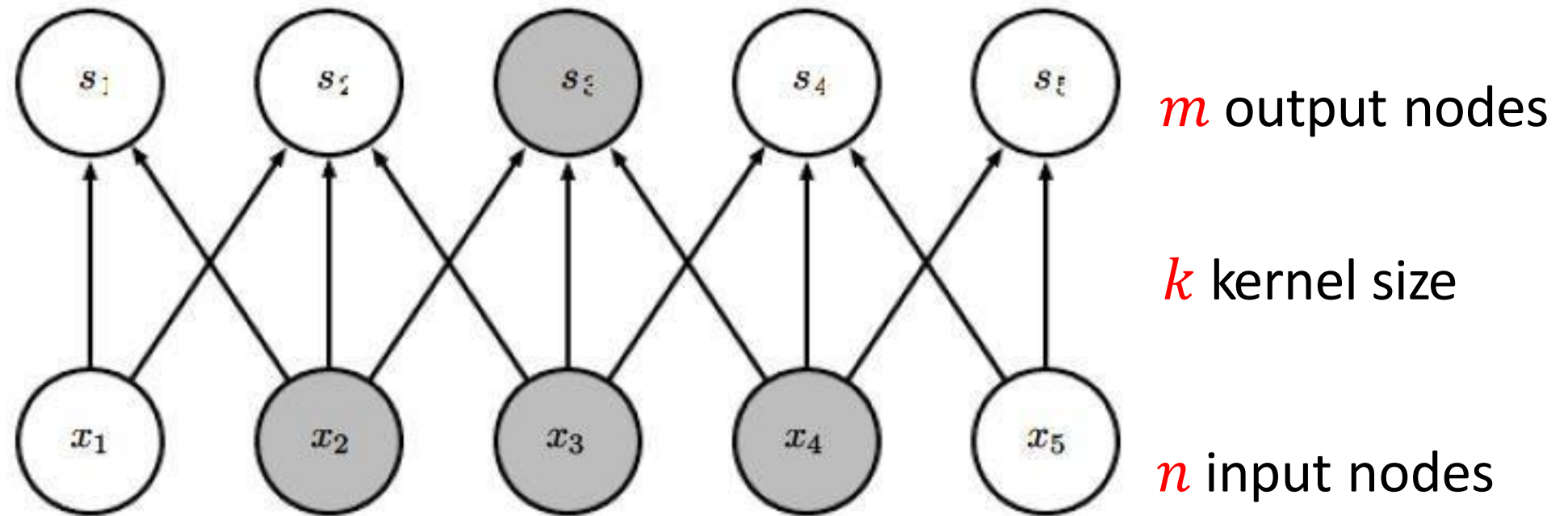


Figure from *Deep Learning*, by Goodfellow, Bengio, and Courville

Terminology

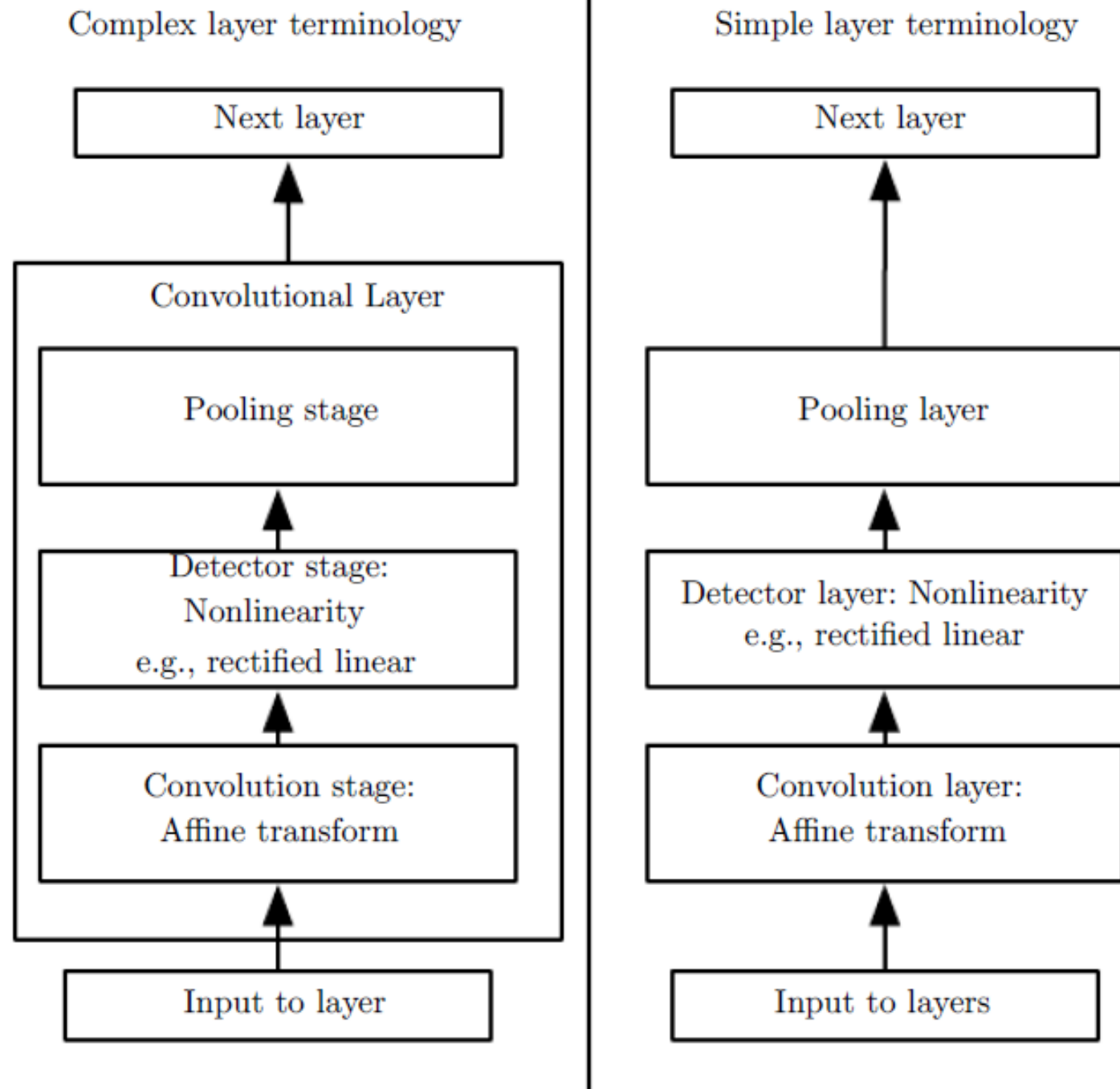


Figure from *Deep Learning*,
by Goodfellow, Bengio, and
Courville

Case study: LeNet-5

LeNet-5

- Proposed in “Gradient-based learning applied to document recognition”, by Yann LeCun, Leon Bottou, Yoshua Bengio and Patrick Haffner, in *Proceedings of the IEEE*, 1998

LeNet-5

- Proposed in “Gradient-based learning applied to document recognition”, by Yann LeCun, Leon Bottou, Yoshua Bengio and Patrick Haffner, in *Proceedings of the IEEE*, 1998
- Apply **convolution** on 2D images (MNIST) and use **backpropagation**

LeNet-5

- Proposed in “Gradient-based learning applied to document recognition”, by Yann LeCun, Leon Bottou, Yoshua Bengio and Patrick Haffner, in *Proceedings of the IEEE*, 1998
- Apply convolution on 2D images (MNIST) and use backpropagation
- Structure: 2 convolutional layers (with pooling) + 3 fully connected layers
 - Input size: 32x32x1
 - Convolution kernel size: 5x5
 - Pooling: 2x2

LeNet-5

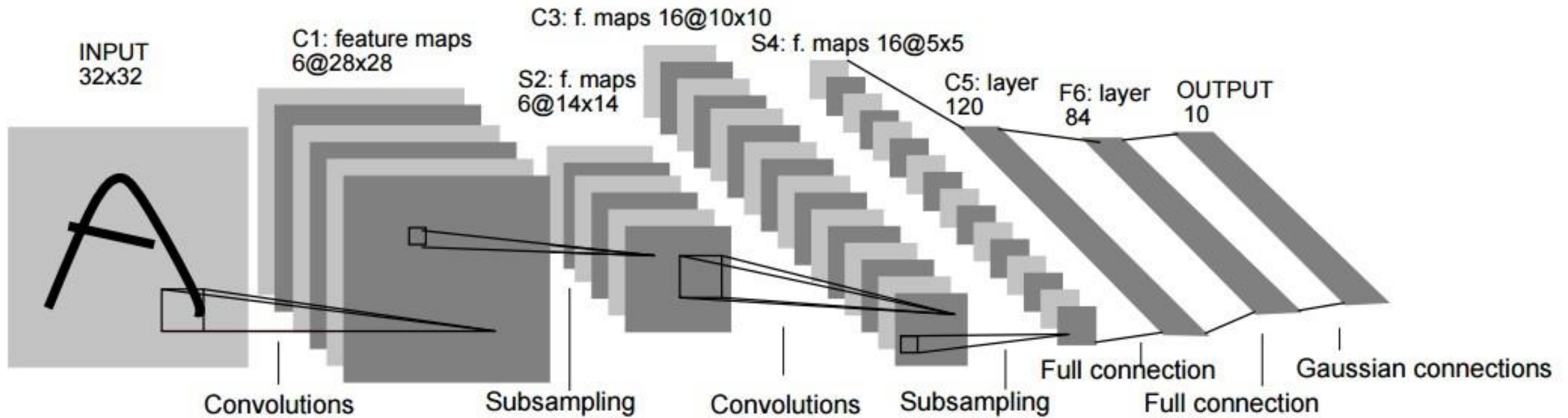


Figure from Gradient-based learning applied to document recognition,
by Y. LeCun, L. Bottou, Y. Bengio and P. Haffner

LeNet-5

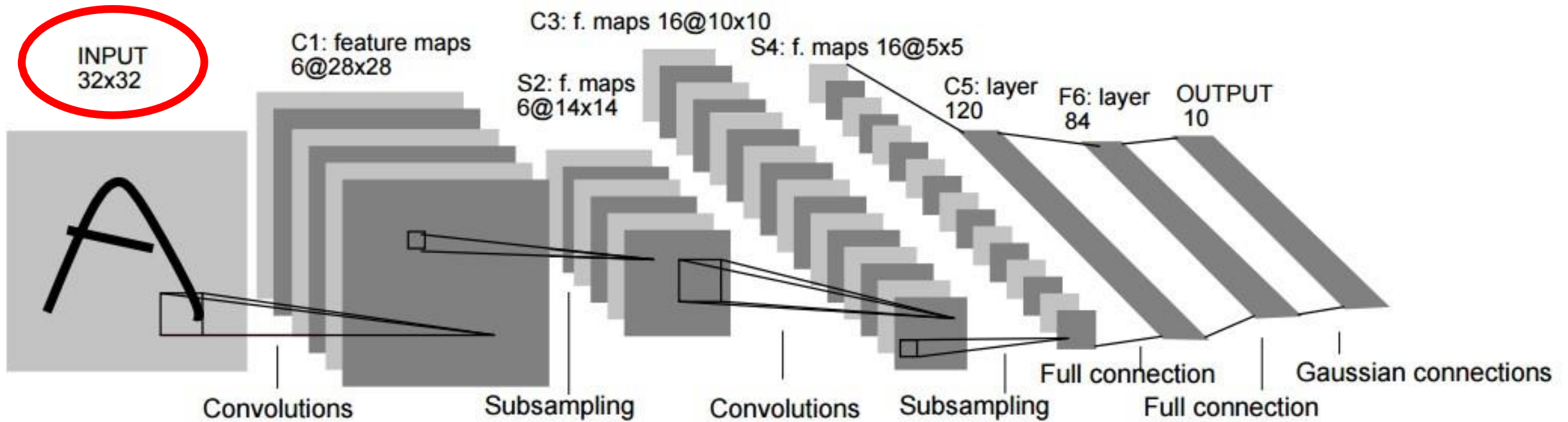


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LeNet-5

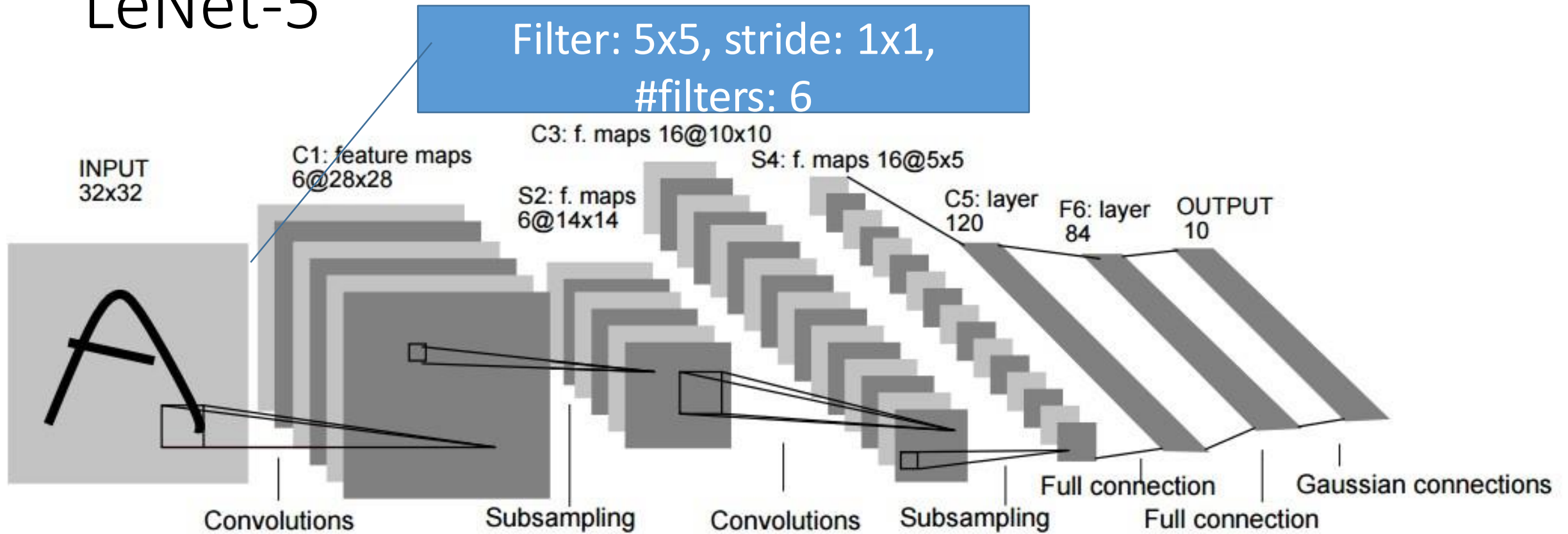


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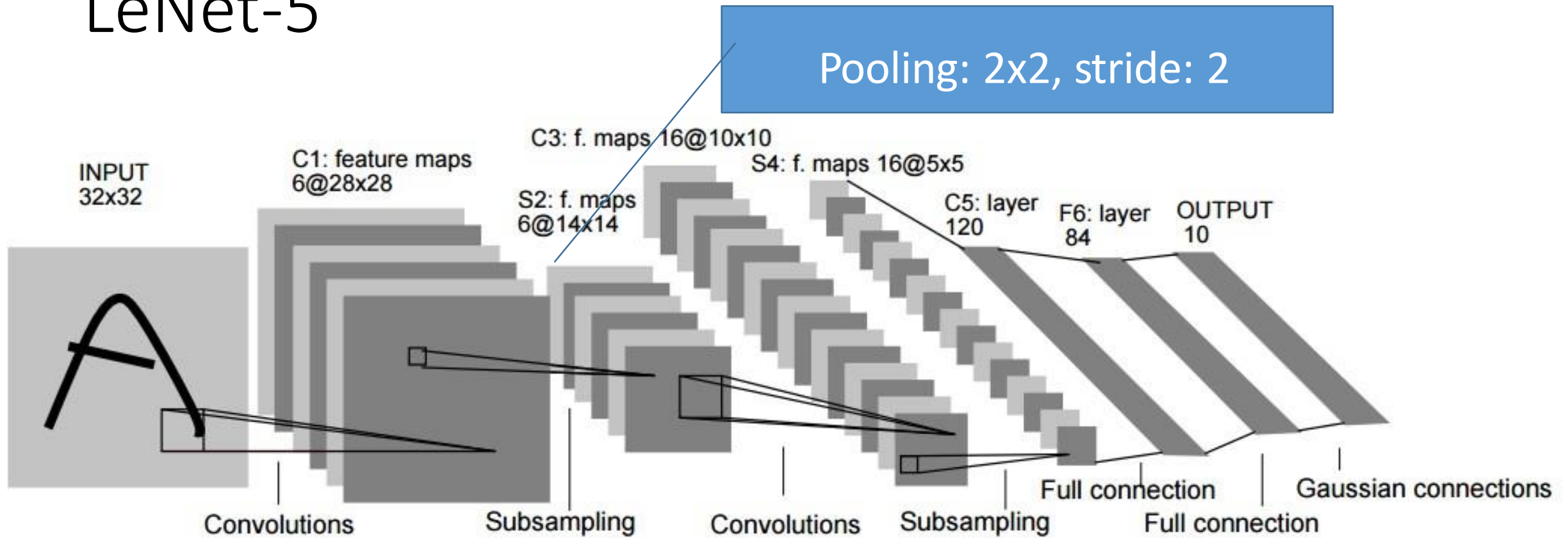


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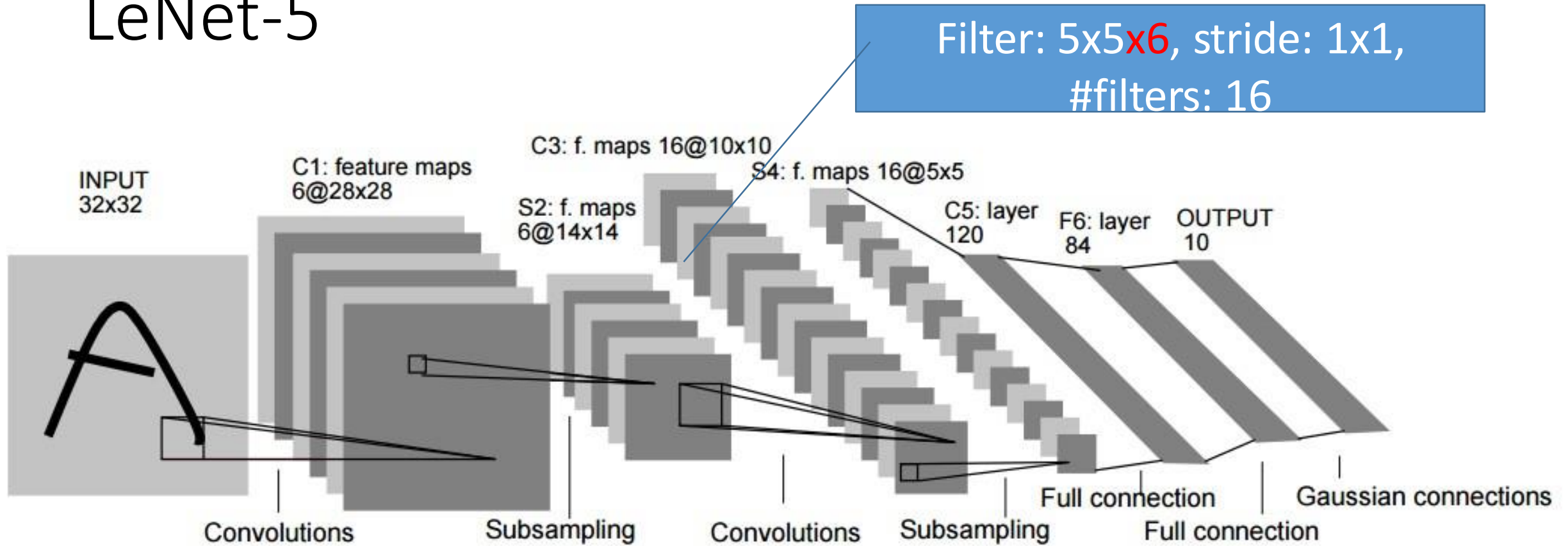


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LeNet-5

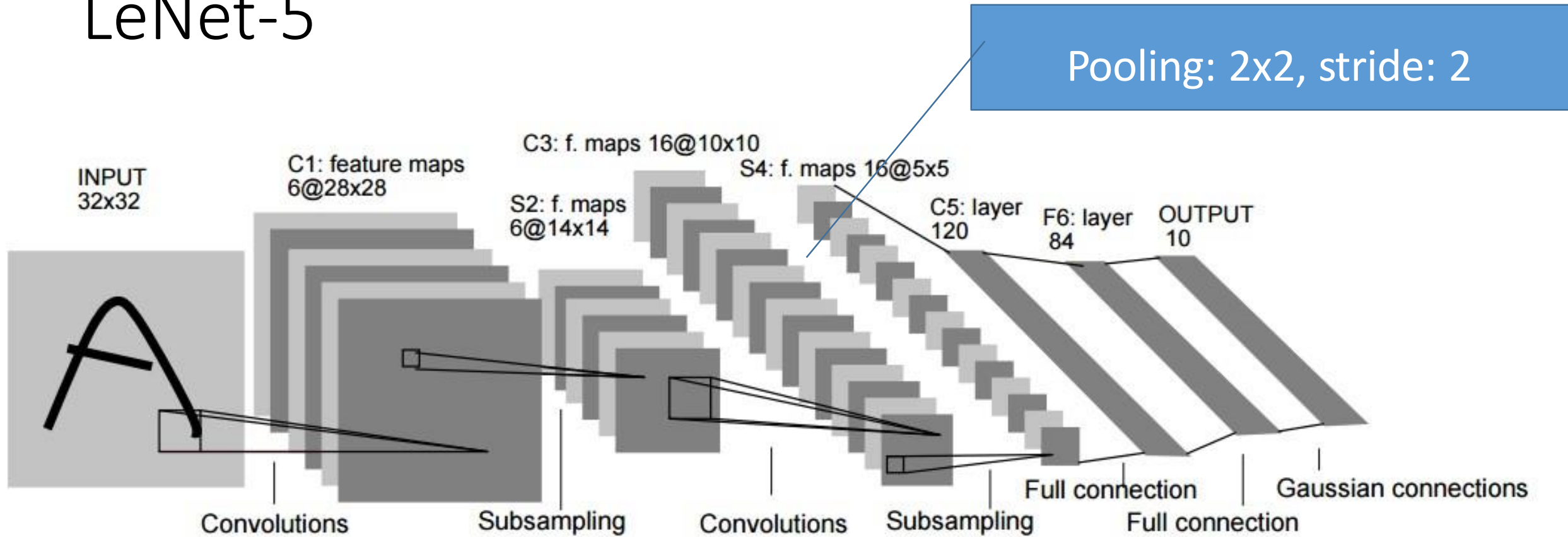


Figure from Gradient-based learning applied to document recognition,
by Y. LeCun, L. Bottou, Y. Bengio and P. Haffner

LeNet-5

Weight matrix: 400x120

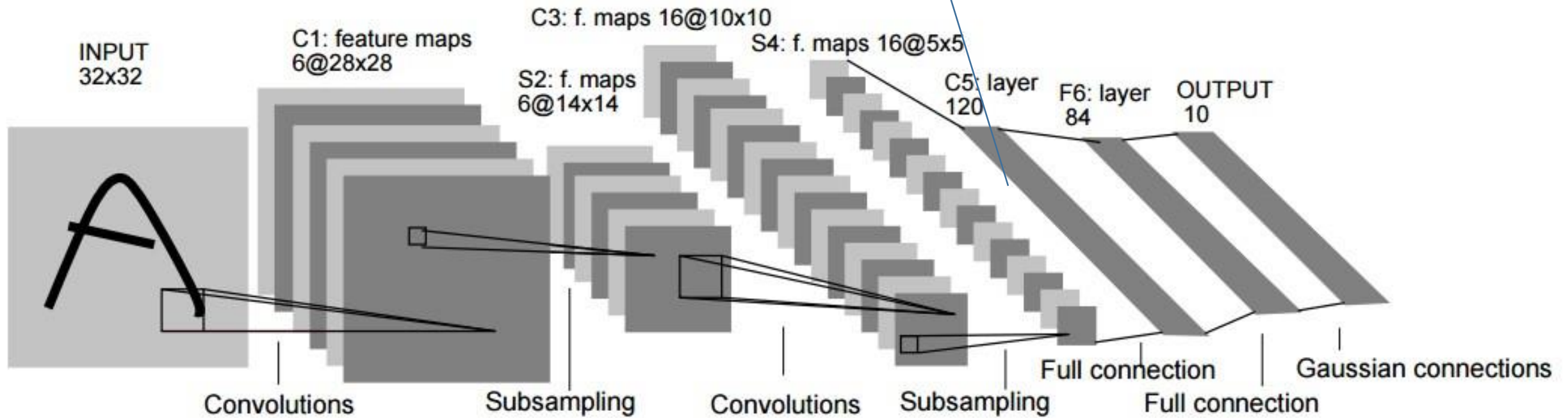


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LeNet-5

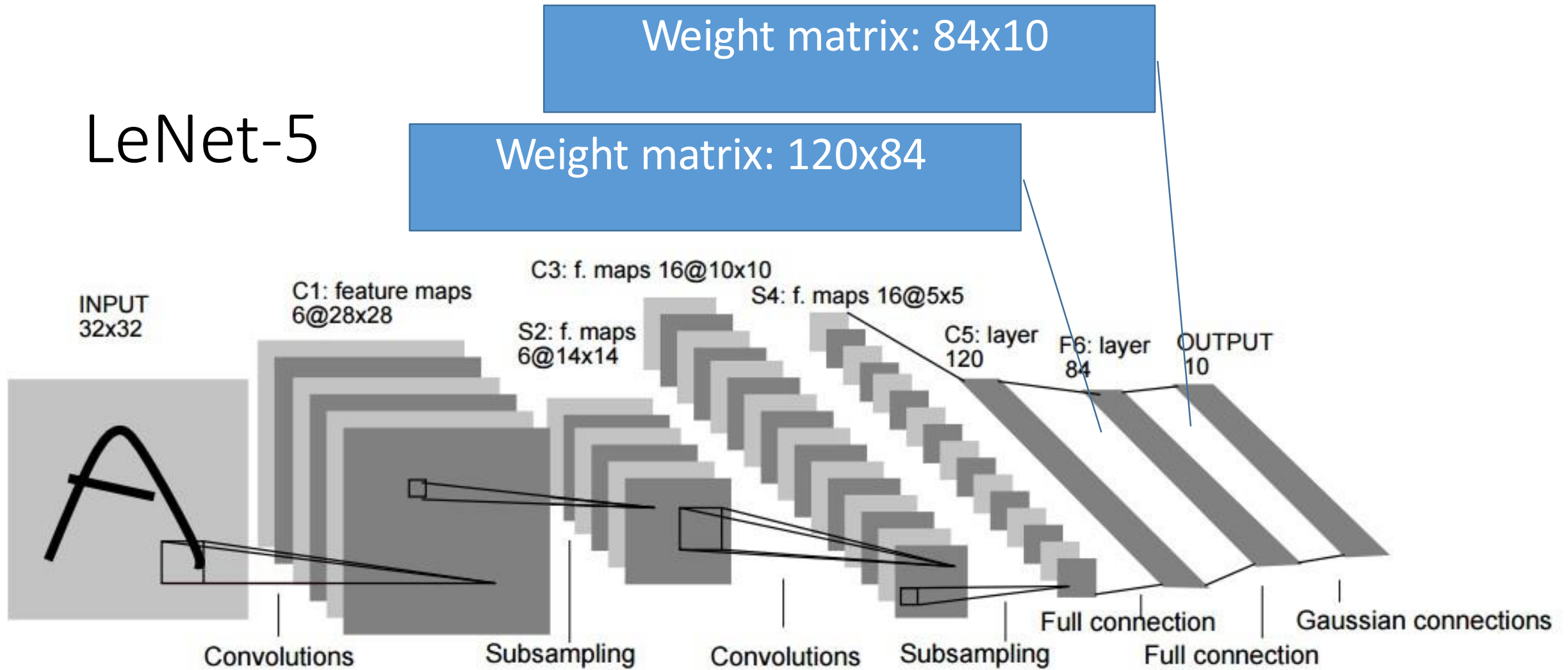
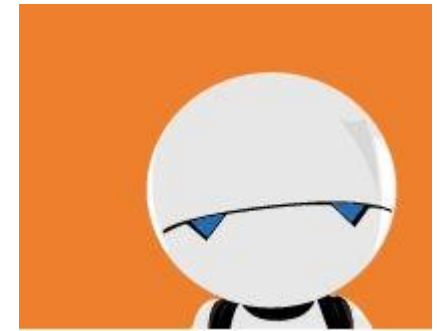


Figure from Gradient-based learning applied to document recognition,
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Software platforms for CNN

Updated in April 2016; checked more recent ones online

Platform: Marvin (marvin.is)



Marvin

A minimalist GPU-only N-dimensional ConvNet framework

[Learn more](#)

[Questions?](#)

Marvin thinks, therefore Marvin is.

Never before has it been so easy to learn so deeply. Marvin was born to be hacked, relying on few dependencies and basic C++. All code lives in two files (`marvin.hpp` and `marvin.cu`) and all numbers take up two bytes (FP16). Win friends and influence people in four easy steps:

Platform: Marvin by



Home



Research



Publications



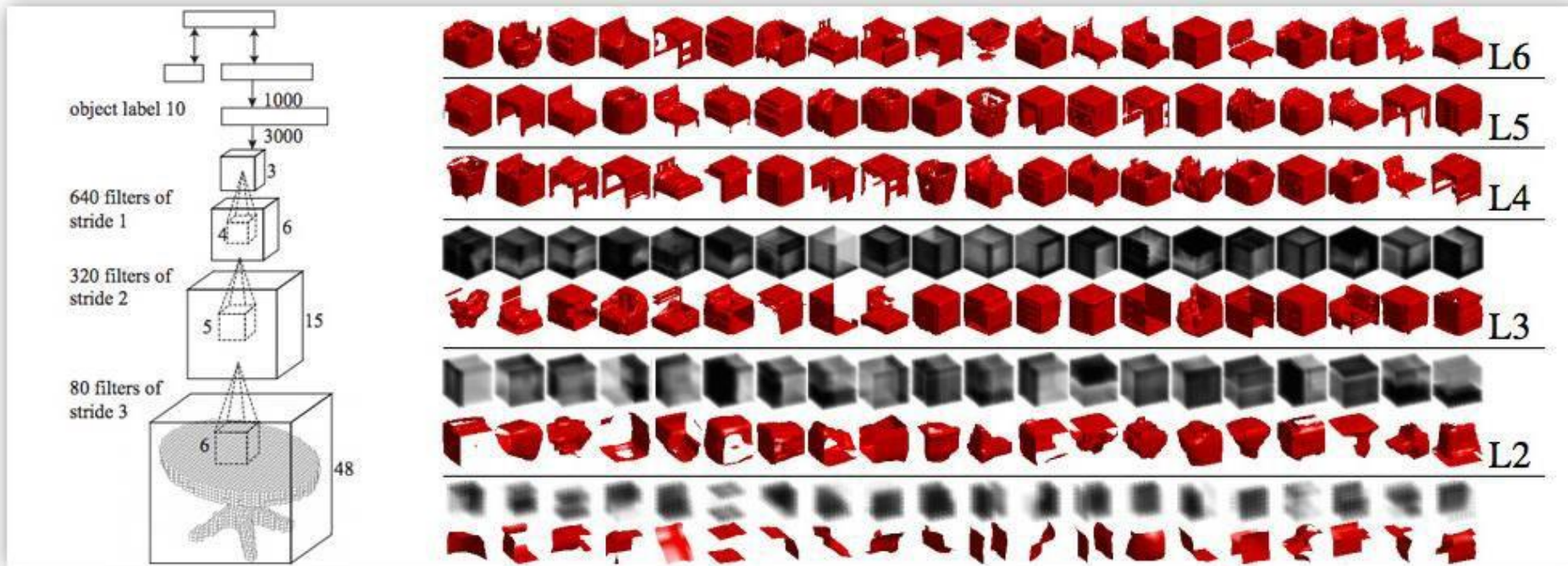
Code



Courses



People



LeNet in Marvin: convolutional layer

```
{  
  "in": ["data"],  
  "type": "Convolution",  
  "name": "conv1",  
  "num_output": 20,  
  "window": [5, 5],  
  "padding": [0, 0],  
  "stride": [1, 1],  
  "upscale": [1, 1],  
  "weight_lr_mult": 1.0,  
  "weight_filler": "Xavier",  
  "bias_lr_mult": 2.0,  
  "bias_filler": "Constant",  
  "bias_filler_param": 0.0,  
  "out": ["conv1"]  
},
```

LeNet in Marvin: pooling layer

```
{  
    "in": ["conv1"],  
    "type": "Pooling",  
    "name": "pool1",  
    "mode": "max",  
    "window": [2, 2],  
    "padding": [0, 0],  
    "stride": [2, 2],  
    "out": ["pool1"]  
},
```

LeNet in Marvin: fully connected layer

```
{  
  "in": ["pool2"],  
  "type": "InnerProduct",  
  "name": "ip1",  
  "num_output": 500,  
  "weight_lr_mult": 1.0,  
  "weight_filler": "Xavier",  
  "bias_lr_mult": 2.0,  
  "bias_filler": "Constant",  
  "bias_filler_param": 0.0,  
  "out": ["ip1"]  
},
```

Platform: Caffe (caffe.berkeleyvision.org)

Caffe

Deep learning framework
by the [BVLC](#)

Created by
[Yangqing Jia](#)
Lead Developer
[Evan Shelhamer](#)

Caffe

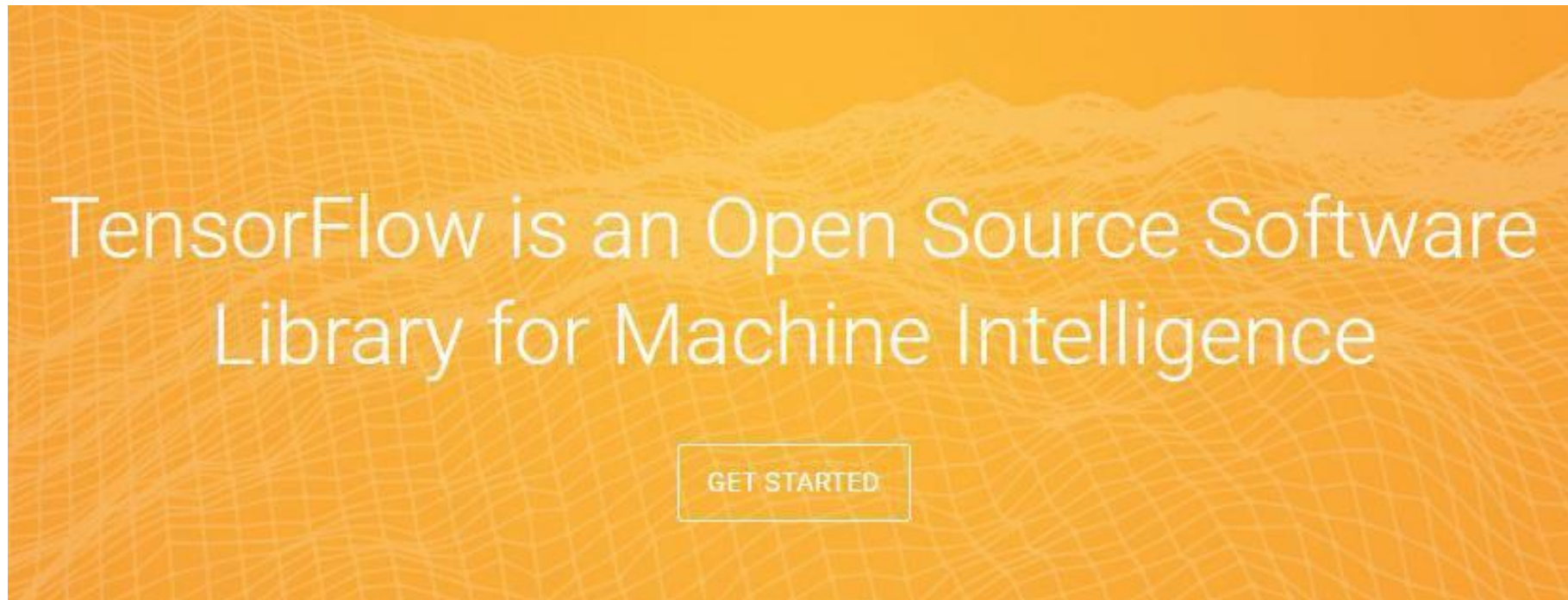
Caffe is a deep learning framework made with expression, speed, and modularity in mind. It is developed by the Berkeley Vision and Learning Center ([BVLC](#)) and by community contributors. [Yangqing Jia](#) created the project during his PhD at UC Berkeley. Caffe is released under the [BSD 2-Clause license](#).

Check out our web image classification [demo](#)!

LeNet in Caffe

```
layer {  
  name: "conv1"  
  type: "Convolution"  
  bottom: "data"  
  top: "conv1"  
  param {  
    lr_mult: 1  
  }  
  param {  
    lr_mult: 2  
  }  
  convolution_param {  
    num_output: 20  
    kernel_size: 5  
    stride: 1  
    weight_filler {  
      type: "xavier"  
    }  
    bias_filler {  
      type: "constant"  
    }  
  }  
}
```

Platform: Tensorflow (tensorflow.org)



Platform: Tensorflow (tensorflow.org)

```
conv = tf.nn.conv2d(data,
                    convl_weights,
                    strides=[1, 1, 1, 1],
                    padding='SAME')
# Bias and rectified linear non-linearity.
relu = tf.nn.relu(tf.nn.bias_add(conv, convl_biases))
# Max pooling. The kernel size spec {ksize} also follows the layout of
# the data. Here we have a pooling window of 2, and a stride of 2.
pool = tf.nn.max_pool(relu,
                      ksize=[1, 2, 2, 1],
                      strides=[1, 2, 2, 1],
                      padding='SAME')
```

Platform: Tensorflow (tensorflow.org)

```
# Fully connected layer. Note that the '+' operation automatically
# broadcasts the biases.
hidden = tf.nn.relu(tf.matmul(reshape, fcl_weights) + fcl_biases)
# Add a 50% dropout during training only. Dropout also scales
# activations such that no rescaling is needed at evaluation time.
if train:
    hidden = tf.nn.dropout(hidden, 0.5, seed=SEED)
```

Others

- [Theano](#) – CPU/GPU symbolic expression compiler in python (from MILA lab at University of Montreal)
- [Torch](#) – provides a Matlab-like environment for state-of-the-art machine learning algorithms in lua
- [Lasagne](#) - Lasagne is a lightweight library to build and train neural networks in Theano
- See: [http://deeplearning.net/software links/](http://deeplearning.net/software_links/)

Optimization: momentum

Basic algorithms

- Minimize the (regularized) empirical loss

$$\hat{L}_R(\theta) = \frac{1}{n} \sum_{t=1}^n l(\theta, x_t, y_t) + R(\theta)$$

where the hypothesis is parametrized by θ

- Gradient descent

$$\theta_{t+1} = \theta_t - \eta_t \nabla \hat{L}_R(\theta_t)$$

Mini-batch stochastic gradient descent

- Instead of one data point, work with a small batch of b points

$$(x_{tb+1}, y_{tb+1}), \dots, (x_{tb+b}, y_{tb+b})$$

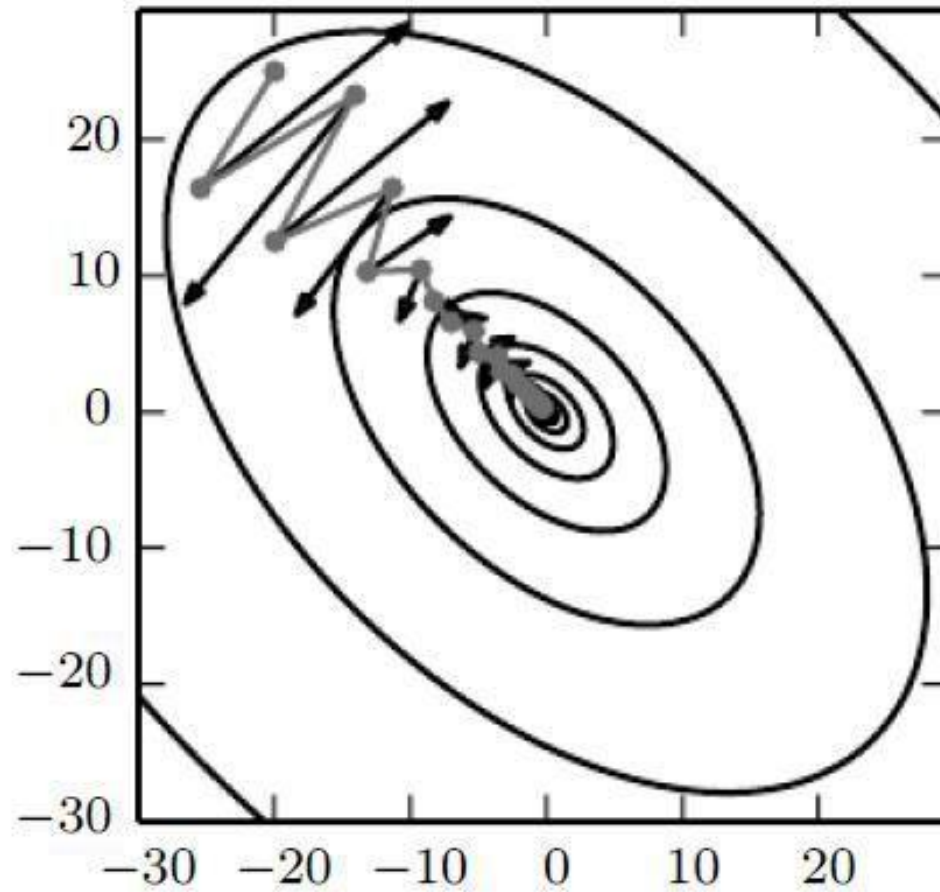
- Update rule

$$\theta_{t+1} = \theta_t - \eta_t \left(\frac{1}{b} \sum_{i=1}^b \nabla l(\theta_t, x_{tb+i}, y_{tb+i}) + R(\theta_t) \right)$$

Momentum

- Drawback of SGD: can be slow when gradient is small
- Observation: when the gradient is consistent across consecutive steps, can take larger steps
- Metaphor: rolling marble ball on gentle slope

Momentum



Contour: loss function
Path: SGD with momentum
Arrow: stochastic gradient

Momentum

- work with a small batch of b points

$$(x_{tb+1}, y_{tb+1}), \dots, (x_{tb+b}, y_{tb+b})$$

- Keep a momentum variable v_t , and set a decay rate α
- Update rule

$$v_t = \alpha v_{t-1} - \eta_t \left(\frac{1}{b} \sum_{i=1}^b l(\theta_t, x_{tb+i}, y_{tb+i}) + R(\theta_t) \right)$$

$$\theta_{t+1} = \theta_t + v_t$$

Momentum

- Keep a momentum variable v_t , and set a decay rate α
- Update rule

$$v_t = \alpha v_{t-1} - \eta_t \left(\frac{1}{b} \sum_{i=1}^b l(\theta_t, x_{tb+i}, y_{tb+i}) + R(\theta_t) \right)$$
$$\theta_{t+1} = \theta_t + v_t$$

- Practical guide: α is set to 0.5 until the initial learning stabilizes and then is increased to 0.9 or higher.