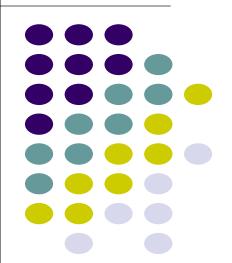
#### IT/PC/B/T/411

#### **Machine Learning**

Deep Learning Basics Lecture 07: Factor Analysis



#### Dr. Pawan Kumar Singh

**Department of Information Technology** Jadavpur University

pawankrsingh.cse@gmail.com

+91-6291555693

Supervised v.s. Unsupervised

# Math formulation for supervised learning

- Given training data  $\{(x_i, y): 1 \le i \le n\}$  i.i.d. from distribution D
- Find  $y = f(x) \in \mathcal{H}$  that minimizes  $\mathbb{P}(f) = \frac{1}{n} \sigma_i^n$   $l(f, x_i, y)$
- s.t. the expected loss is small

$$L(f) = \mathbb{E}_{(x,y) \sim D}[l(f,x,y)]$$

### Unsupervised learning

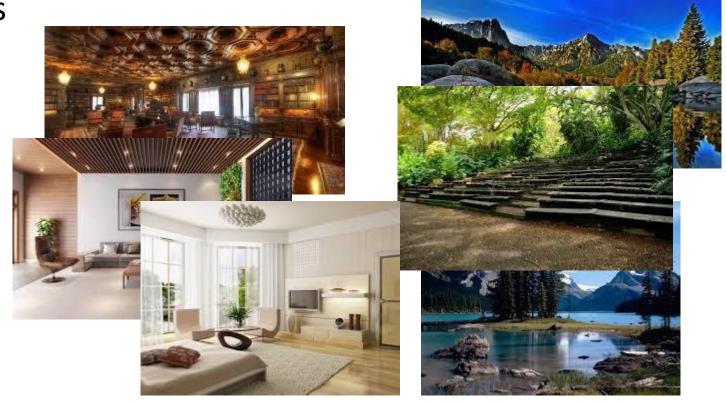
- Given training data  $\{x_i: 1 \le i \le n\}$  i.i.d. from distribution D
- Extract some "structure" from the data

- Do not have a general framework
- Typical unsupervised tasks:
  - Summarization: clustering, dimension reduction
  - Learning probabilistic models: latent variable model, density estimation

Lun 1

# High dimensional data

• Example 1: images



Dimension: 300x300 = 90,000

## High dimensional data

- Example 2: documents
- Features:
  - Unigram (count of each word): thousands
  - Bigram (co-occurrence contextual information): millions
- Netflix survey: 480189 users x 17770 movies

	Movie 1	Movie 2	Movie 3	Movie 4	Movie 5	Movie 6	
User 1	5	3	3	1	3	3	
User 2	?	3	3	1	2	5	
User 3	4	3	1	?	5	1	

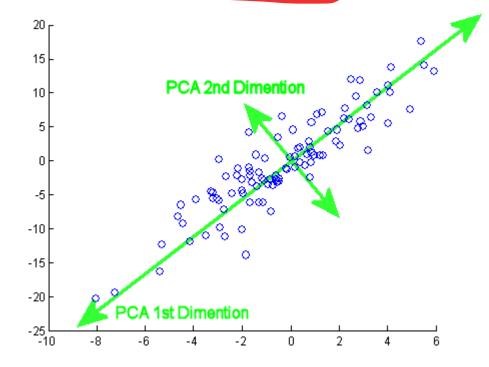
• Data analysis point of view: dimension reduction technique on a given set of high dimensional data  $\{x_i: 1 \le i \le n\}$ 

 Math point of view: eigen-decomposition of the covariance (or singular value decomposition of the data)

Classic, commonly used tool

- Extract hidden lower dimensional structure of the data
  - my to capture the variance structure as much as possible
- Computation: solved by singular value decomposition (SVD)

**Definition:** an orthogonal projection or transformation of the data into a (typically lower dimensional) subspace so that the variance of the projected data is maximized.



- illustration of the projection to 1 dim
- Pay attention to the variance of the projected points

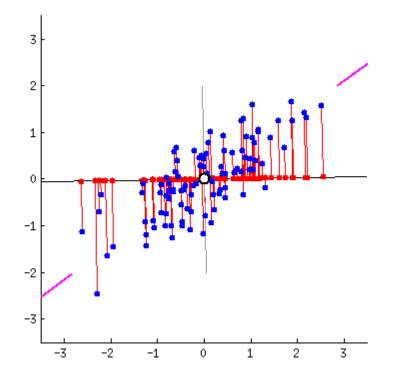


Figure from amoeba@stackexchange

#### U. V. L.P.

# Principal Component Analysis (PCA)

- Principal Components (PC) are directions that capture most of the variance in the data
  - First PC: direction of greatest variability in data
    - Data points are most spread out when projected on the first PC compared to any other direction
  - Second PC: next direction of greatest variability, orthogonal to first PC
  - Third PC: next direction of greatest variability, orthogonal to first and second PC's

•

#### Wath formulation

- Suppose the data are centered:  $\sigma_{i=1}^n x_i =$
- Then their projections on any direction v are centered:  $\sigma_{i=1}^n v^T x_i = 0$
- First PC: maximize the variance of the projections

$$\max_{v} [v^T x_i]^2$$
,  $s.t. v^T v = 1$ 

equivalent to

$$\max_{v} v^T X X^T v, \qquad s.t. \quad v^T v = 1$$

where the columns of X are the data points

#### Math formulation

• First PC:

$$\max_{v} v^T X X^T v, \qquad s.t. \quad v^T v = 1$$

where the columns of X are the data points

• Solved by Lagrangian: exists  $\lambda$ , so that

$$\max_{v} v^{T} X X^{T} v - \lambda v^{T} v$$

$$\frac{\partial}{\partial v} = 0 \rightarrow (X X^{T} - \lambda I) v = 0 \rightarrow X X^{T} v = \lambda v$$

#### Computation: Eigen-decomposition

• First PC:  $XX^Tv = \lambda v$ 

- $XX^T$ : covariance matrix
- v: eigen-vector of the covariance matrix
- First PC: first eigen-vector of the covariance matrix

• Top k PC's: similar argument shows they are the top k eigen-vectors

#### Computation: Eigen-decomposition

- Top k PC's: the top k eigen-vectors  $XX^TU = \Lambda U$  where  $\Lambda$  is a diagonal matrix
- *U* are the left singular vectors of *X*

- Recall SVD decomposition theorem:
- An  $m \times n$  real matrix M has factorization  $M = U \Sigma V^T$  where U is an  $m \times m$  orthogonal matrix,  $\Sigma$  is a  $m \times n$  rectangular diagonal matrix with non-negative real numbers on the diagonal, and V is an  $n \times n$  orthogonal matrix.

### Equivalent view: low rank approximation

First PC maximizes variance:

$$\max_{v} v^T X X^T v, \qquad s.t. \quad v^T v = 1$$

• Alternative viewpoint: find vector  $\boldsymbol{v}$  such that the projection yields minimum MSE reconstruction

$$\min_{v} \frac{1}{n} ||x_i - vv^T x_i||^2, \quad s.t. \quad v^T v = 1$$

$$= 1$$

#### Equivalent view: low rank approximation

• Alternative viewpoint: find vector  $\boldsymbol{v}$  such that the projection yields minimum MSE reconstruction

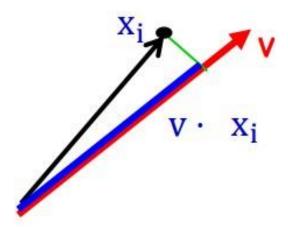
$$\min_{v} \frac{1}{n} ||x_i - vv^T x_i||^2, \quad s.t. \quad v^T v = 1$$

$$= 1$$

blue<sup>2</sup> + green<sup>2</sup> = black<sup>2</sup>

black2 is fixed (it's just the data)

So, maximizing blue<sup>2</sup> is equivalent to minimizing green<sup>2</sup>



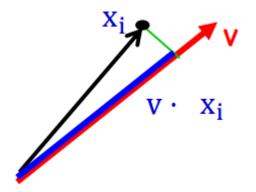
#### Summary

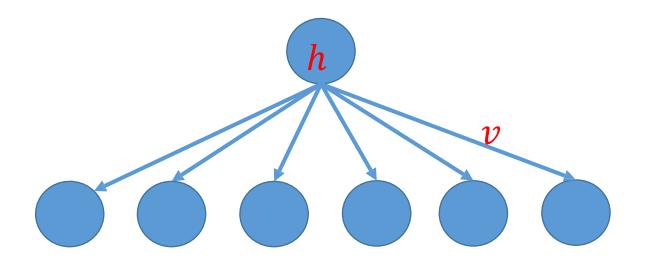
- A: orthogonal projection that maximizes variance
  - Low rank approximation: orthogonal projection that minimizes error
  - Eigen-decomposition/SVD

All equivalent for centered data

#### A latent variable view of PCA

- Let  $h_i = v^T x_i$
- Data point viewed as  $x_i = vh_i + noise$

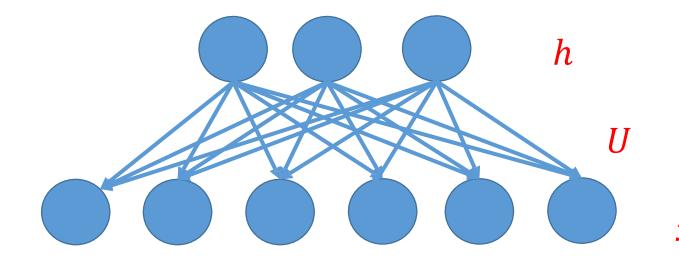




 $\chi_{i}$ 

#### A latent variable view of PCA

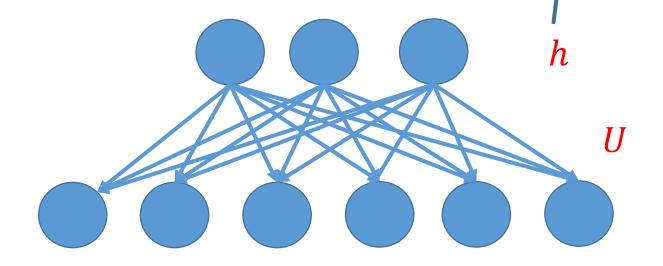
- Consider top k PC's U
- Let  $h_i = U^T x_i$
- Data point viewed as  $x_i = Uh_i + noise$



#### A latent variable view of PCA

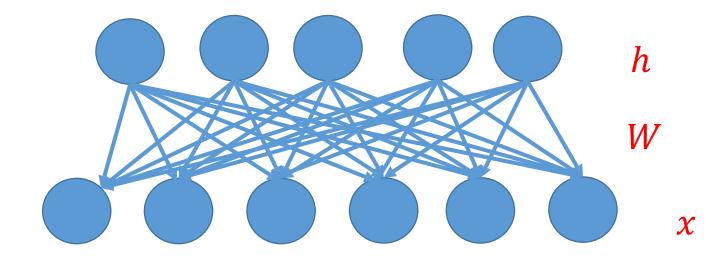
- Consider top k PC's U
- Let  $h_i = U^T x_i$
- Data point viewed as  $x_i = Uh_i + noise$

PCA structure assumption: *h* low dimension. What about other assumptions?



X

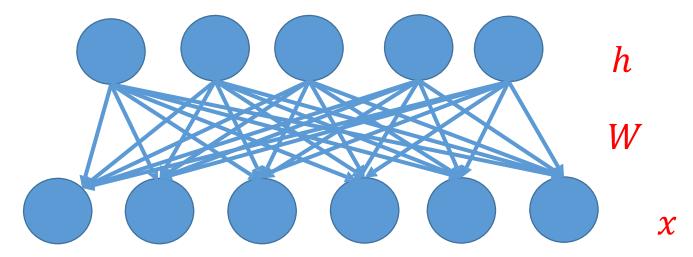
- Structure assumption: h is sparse, i.e.,  $|h|_0$  is small
- Dimension of *h* can be large



Latent variable probabilistic model view:

$$p(x|h) = Wh + N\left(0, \frac{1}{\beta}I\right)$$
, h is sparse.

 $p(x|h) = Wh + N\left(0, \frac{1}{\beta}I\right), h \text{ is sparse,}$ • E.g., from Laplacian prior:  $p(h) = \frac{\lambda}{2} \exp(-\frac{\lambda}{2}|h|_1)$ 



• Suppose W is known. MLE on h is

$$h^* = \arg \max_{h} \log p(h|x)$$

$$h^* = \arg \min_{h} \lambda ||h||_1 + \beta ||x - Wh||_2^2$$

- Suppose both W, h unknown.
  - Typically alternate between updating W, h

• Historical note: study on visual system

• Bruno A Olshausen, and David Field. "Emergence of simple-cell receptive field properties by learning a sparse code for natural images." *Nature* 381.6583 (1996): 607-609.

# Project paper list

#### Supervised learning

 AlexNet: <u>ImageNet Classification with Deep Convolutional Neural</u> <u>Networks</u>

GoogLeNet: Going Deeper with Convolutions

• Residue Network: <u>Deep Residual Learning for Image Recognition</u>

#### Unsupervised learning

• Deep belief networks: A fast learning algorithm for deep belief nets

Reducing the Dimensionality of Data with Neural Networks

Variational autoencoder: <u>Auto-Encoding Variational Bayes</u>

Generative Adversarial Nets

#### Recurrent neural networks

Long-short term memory

Memory networks

Sequence to Sequence Learning with Neural Networks

### You choose the paper that interests you!

- Need to consult with TA
  - Heavier responsibility on the student side if customize the project

- Check recent papers in the conferences <u>ICML</u>, <u>NIPS</u>, <u>ICLR</u>
- Check papers by leading researchers: Hinton, Lecun, Bengio, etc.
- Explore whether deep learning can be applied to your application

Not recommend arXiv: too many deep learning papers