Reinforcement Learning (RL)

Chapter 2:

Multi-Armed Bandit

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- ✓ ε-greedy algorithm
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- ✓ Thompson Sampling algorithm

Aim of this chapter:

✓ Understand concepts of Multi-Armed Bandit problem as basic problem for Reinforcement Learning (RL) and discuss multiple approaches to deal with the problem.

Exploitation vs Exploration:

Exploration: Try new things all the time

Take some risk to collect information about unknown options

Exploitation: Use previous experience

Take advantage of the best option we know

Explore
High uncertainty

Search

Scale

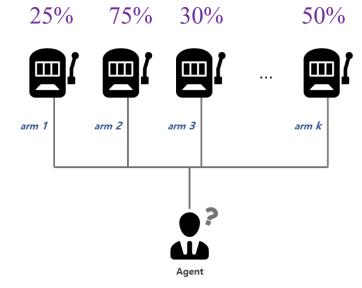
Low uncertainty

The best long-term strategy may involve short-term sacrifices

✓ In a casino facing multiple slot machines and each is configured with an unknown probability of how likely you can win or lose at one play

What is the best strategy to achieve highest long-term rewards

✓ Considering infinite number of trials (to understand concept)



Definition:

- ✓ A classic problem that demonstrates the exploration vs exploitation and basic concept of RL
- ✓ It is a **one state problem: (why?)**
 - ➤ Because rewards has no effect on the future rewards and reward distributions are stationary
- ✓ The goal is to **maximize the cumulative reward** by doing actions (arms do the actins)

arm 1 arm 2 arm 3 arm k

we do not

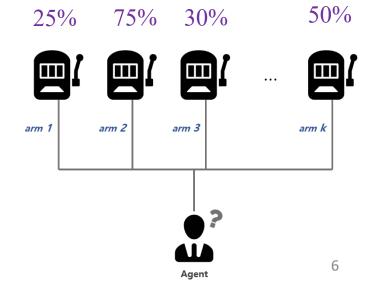
Slot Machines

Note: It is a simple version of Markov Decision Process (MDP) since we do not have states (only one state) **we will see multi state in next chapter**

The most basic Approach

- ✓ Playing with **one machine for many rounds** to get reward is simplest approach
- **✓** This does not guarantees the best long-term reward

✓ Also based on limited set of knowledge and resources we need to have **smart approach!**



Definition:

- \checkmark Considered as a tuple of (a, r)
- \checkmark Take an action a and receive reward r (on one slot machine).
- ✓ *K* machines with reward probabilities of $\{P_1, P_2, ..., P_K\}$
- ✓ The value of action a is the expected reward $V(a) = \mathbb{E}[r|a] = P$
- \checkmark At the time step t the reward function $r_t = R(a_t)$ based on the probability

Example:

✓ The goal is to maximize the cumulative reward:

$$\max \sum_{t=1}^{T} r_t$$

✓ If we know the optimal action and best reward the goal can be minimizing

the loss function:

$$\mathcal{L}_T = \mathbb{E}\sum_{t=1}^T (P^* - Q(a_t))$$

$$P^* = Q(a^*) = \max_{1toK}(P_i)$$

The regret we might have by not selecting the optimal action up to the time step T

Value of taking action a in time t

Multi-Armed Bandit Strategies

- 1) Playing with one machine for many rounds
 - The most bad and naive approach (no exploration)
- 2) Exploration randomly
 - Not reliable
- 3) Exploration preference to uncertainty (wise exploration)



ε-greedy policy concept:

 \checkmark The ε-greedy algorithm takes the **best action** or choose a **random action** exploration occasionally.

How?

- a) Generate a random number ($rand \in [0, 1]$)
- b) If $rand < \varepsilon$ choose a greedy action (exploitation)
- c) Otherwise choose a random action (exploration)



To avoid inefficient exploration, we can decrease the parameter ε in time (we call it epsilon decay)

Multi-Armed Bandit by ε-greedy policy:

- ✓ Action value is estimated using the past experience:
 - By averaging the rewards of action that we have observed up to the current time step t:

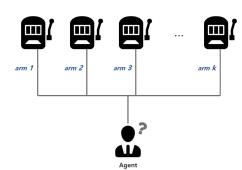
$$\hat{Q}_t(a) = 1/N_t(a) \sum_{t=1}^T r_t \, \mathbb{1}[a = a_t]$$

* How many times the action a has been selected before time t

Now we pick the best action that we have learnt by choosing an action:

$$\hat{a}_t^* = argmax_{a \in A} \hat{Q}_t(a)$$

Best estimated action in time t



Challenge of ε -greedy policy:

- ✓ If we can tune ε parameter well we will have good result.
- \checkmark Defining proper value of the ε sometimes is challenging!

Solution

✓ Having an approach that relies on number times that we applied an action.

Upper Confidence Bounds (UCB)

Upper Confidence Bounds (UCB) algorithm

- ✓ Favor exploration of actions with a strong potential to have a optimal value!
- ✓ We have a **bound per each action** that indicates **how confident** we are about the **Q-value of that action**.
 - ✓ Less confident = Bound will be **big**
 - ✓ More confident = Bound will be small

Total number of choosing actions (t)

square root
$$U_t(a) = \sqrt{\frac{2 \log t}{N_t(a)}}, a \in A$$

✓ Larger $N_t(a_i)$ gives us smaller $U_t(a_i)$

Total number of times that specific action (a_i) has been selected

Upper Confidence Bounds (UCB) algorithm

- ✓ In fact, we prefer actions that we haven't had a confident value estimation for it yet.
- ✓ UCB algorithm measures this potential by an **Upper Confidence Bound** of the reward value then add to Q-value
- ✓ So, it **select the greediest action** to maximize the upper confidence bound as follows:

$$a_t^{UCB} = argmax_{a \in A} Q_t(a) + U_t(a)$$

Upper Confidence Bounds (UCB) algorithm

Example

$a_t^{UCB} = argmax_{a \in A} Q_t(a) + U_t(a)$

Assumptions:

$$Q_{1000}(a_1) = 1$$
 $N_{1000}(a_1) = 200$
 $Q_{1000}(a_2) = 1$ $N_{1000}(a_2) = 150$
 $Q_{1000}(a_3) = 1$ $N_{1000}(a_3) = 750$

$$U_{1000}(a_1) = \sqrt{\frac{2\log 1000}{N_t(a_1)}} = \sqrt{\frac{63.25}{200}} = 0.51$$

$$U_{1000}(a_2) = \sqrt{\frac{2\log 1000}{N_t(a_1)}} = \sqrt{\frac{63.25}{150}} = \mathbf{0.64}$$

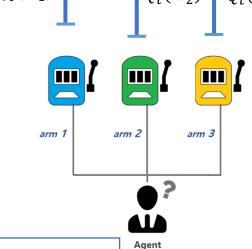
$$U_{1000}(a_2) = \sqrt{\frac{2\log 1000}{N_t(a_1)}} = \sqrt{\frac{63.25}{750}} = 0.29$$

$$U_t(a) = \sqrt{\frac{2 \log t}{N_t(a)}}, a \in A \qquad Q_t(a_1) = 0.51$$

$$Q_t(a_2) = 0.64$$

$$Q_t(a_2) = 0.29$$

$$Q_t(a_3) = 0.64$$



In machine two we have higher hope (not very sure about its Q-value)

Thompson Sampling algorithm

- ✓ At each time step, we want to select action a according to the probability that a is **optimal**
- ✓ Beta distribution can be considered as Q(a), which is essentially the success probability θ
- \checkmark The α and β correspond to the counts when we **succeeded** or **failed** to get a reward respectively.

Thompson Sampling algorithm

- ✓ It samples an expected reward $\hat{Q}(a)$ from the prior distribution $Beta(\alpha_i, \beta_i)$ for every action at each time t.
- ✓ Then the best action is selected among samples.

Beta Distribution

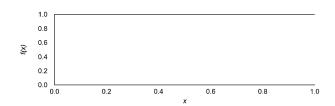
$$P(\theta) = \frac{1}{B(\alpha, \beta)} x^{\alpha - 1} (1 - x)^{\beta - 1}, \qquad \theta \in [0, 1], \alpha, \beta > 0$$

$$B(\alpha,\beta) = \int_0^1 u^{\alpha-1} (1-u)^{\beta-1} du$$

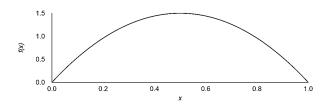
Beta Distribution

$$P(\theta) = \frac{1}{B(\alpha, \beta)} x^{\alpha - 1} (1 - x)^{\beta - 1}$$

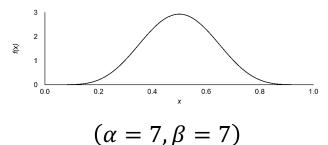
f(x)

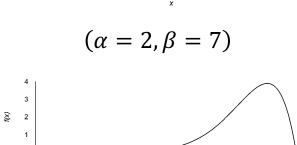


$$(\alpha = 1, \beta = 1)$$



$$(\alpha = 2, \beta = 2)$$

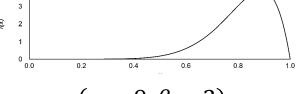




 $(\alpha = 1, \beta = 6)$

0.6

1.0



$$(\alpha = 9, \beta = 2)$$

You can try online:

https://homepage.divms.uiowa.edu/~mbognar/a pplets/beta.html

Thompson Sampling algorithm

$$P(\theta) = \frac{1}{B(\alpha, \beta)} x^{\alpha - 1} (1 - x)^{\beta - 1}$$

Idea

- ✓ Idea is to *estimating* α , β values by change them continuously.
- ✓ It changes the shape of the distributions related to possible actions.
- ✓ If we **repeat it many times** the sampling the distribution and getting Q-value we will form our desired (true) estimation

https://homepage.divms.uiowa.edu/~mbognar/applets/beta.html

Thompson Sampling algorithm

Iteration 1

✓ Assume initial distribution of $(\alpha = 2, \beta = 2)$ for each bandit

 $P(Q_1)$ 1.5

1.0

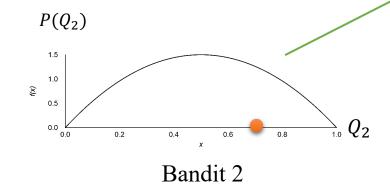
0.5

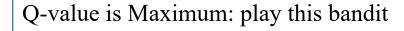
0.0

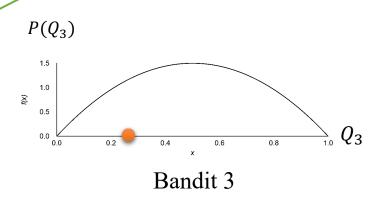
0.2

0.4

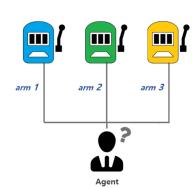
Bandit 1







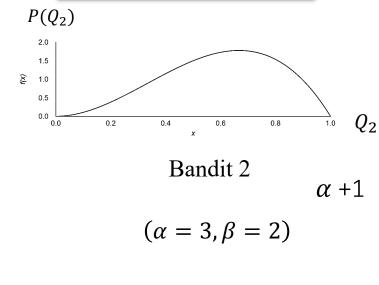
- ✓ Sample Q-value from each of the distributions (Random based on distribution probability)
- ✓ Update the α and β values for the winner $(\alpha + 1)$ or loser $(\beta + 1)$ bandit (here Bandit 2)

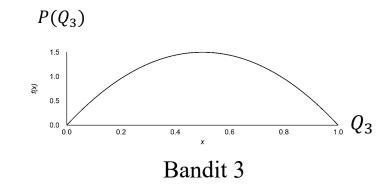


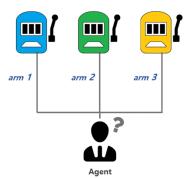
Thompson Sampling algorithm

$P(Q_1)$ 1.5 1.0 0.5 0.0 0.0 0.2 0.4 x 0.6 0.8 1.0 Q_1 Bandit 1

If machine 2 wins



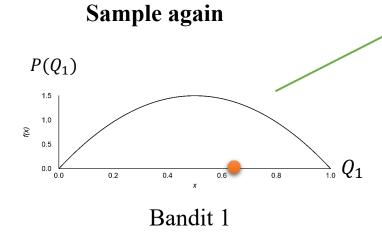


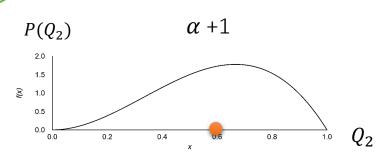


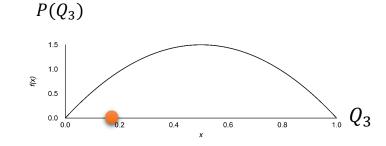
Thompson Sampling algorithm



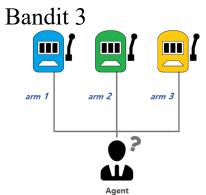
Q-value is Maximum: play this bandit







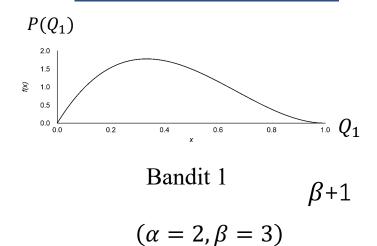
 $(\alpha = 3, \beta = 2)$ Bandit 2

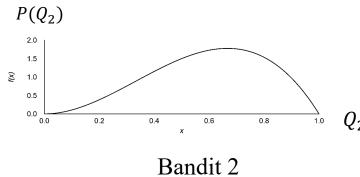


Thompson Sampling algorithm

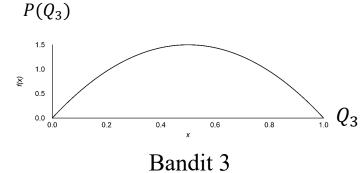
Iteration 2

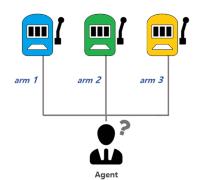
If machine 1 loses







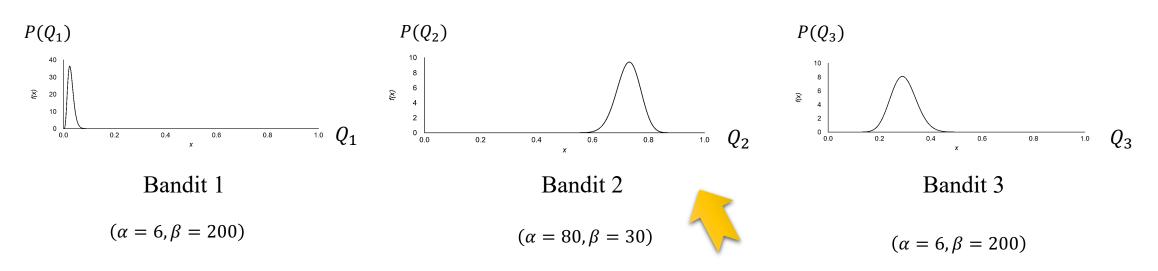




 $(\alpha = 3, \beta = 2)$

Thompson Sampling algorithm

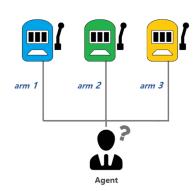
✓ After **continuing enough iterations** our probability estimations will be close to real machines winning probability



Now with sampling we get higher Q-value from second bandit. So play most of the time in **Bandit 2**.

Thompson Sampling algorithm

✓ We discuss a python solution.



Assignment

✓ Compare MAB problem with three algorithms (Thompson Sampling, UCB, and ε-greedy)

Note: plot and compare mean total reward and time for three algorithms, 1000 iterations (as shown in the example)

Summery

- ✓ We discussed introduction to Multi-Armed Bandit (MAB) problem
- ✓ We learnt ε-greedy algorithm
- ✓ Discussed importance of UCB algorithm
- ✓ Finly used Thompson Sampling algorithm to Solve MAB problem