

Estimation of Tire Forces and Torques via Nonlinear Suspension Models and Optimal Control

Motivation

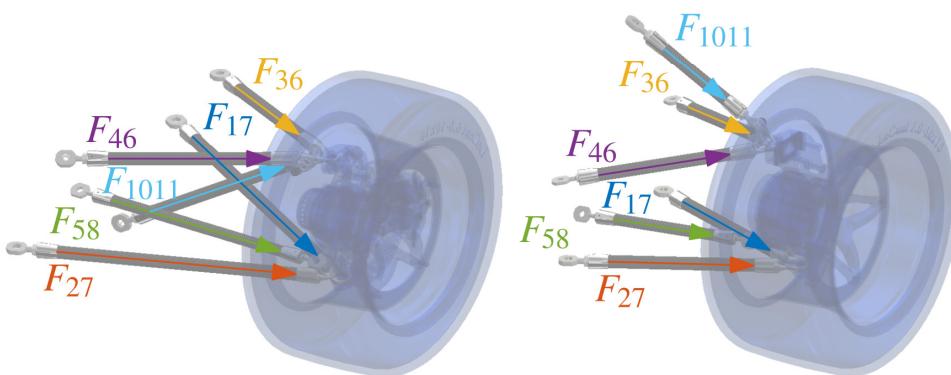
Scaling tire loads to real operating conditions



Image courtesy of E-Agle Trento Racing Team

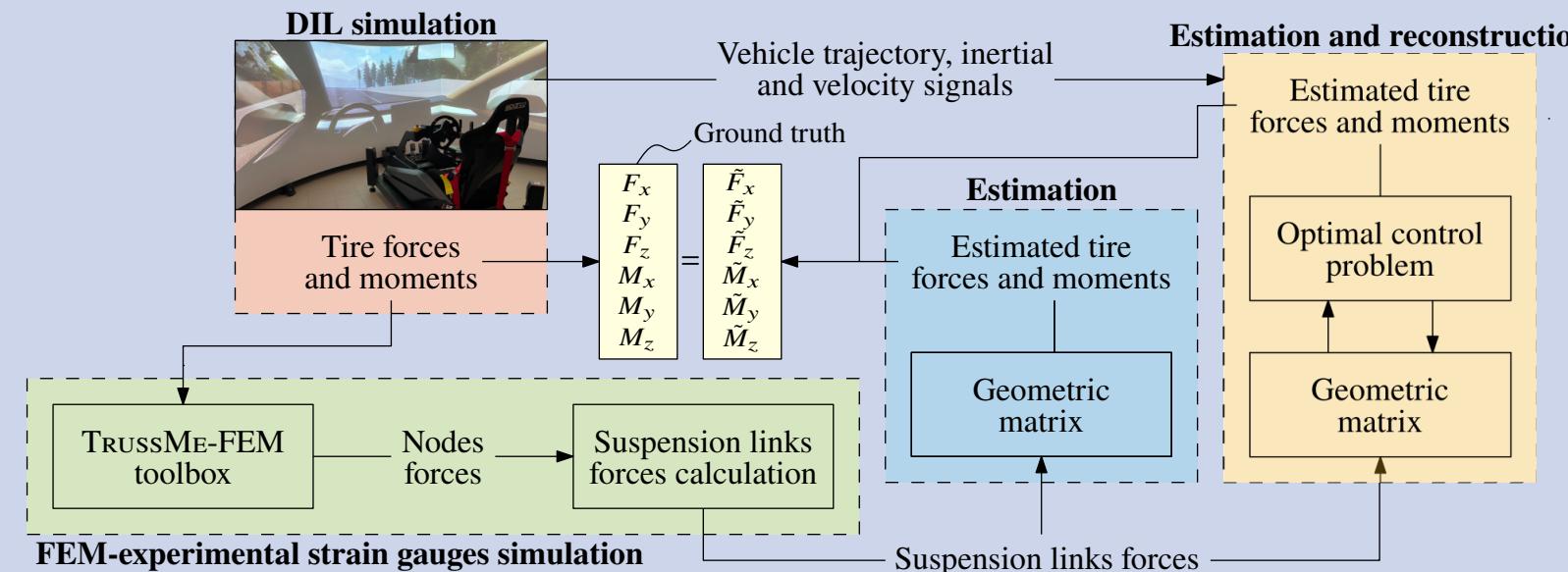
Accurate tire loads estimation require expensive sensors and thorough testing

Tire Forces and Moments



Can we estimate tire *forces* and *torques* using only strain gauges data? Can we estimate tire loads even with *missing* or *corrupted* sensors signals?

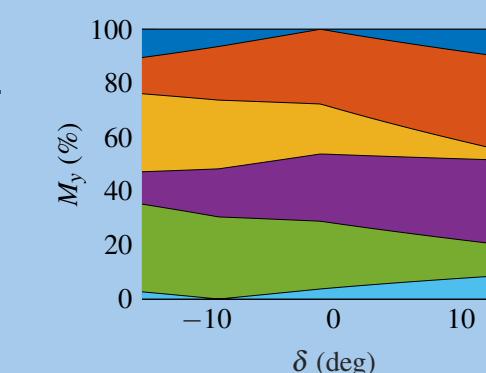
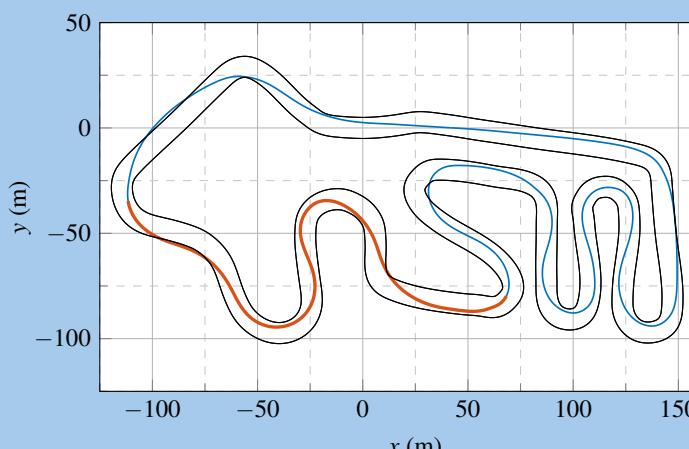
Proposed Methodology



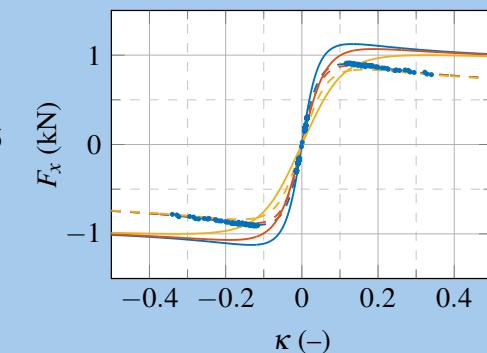
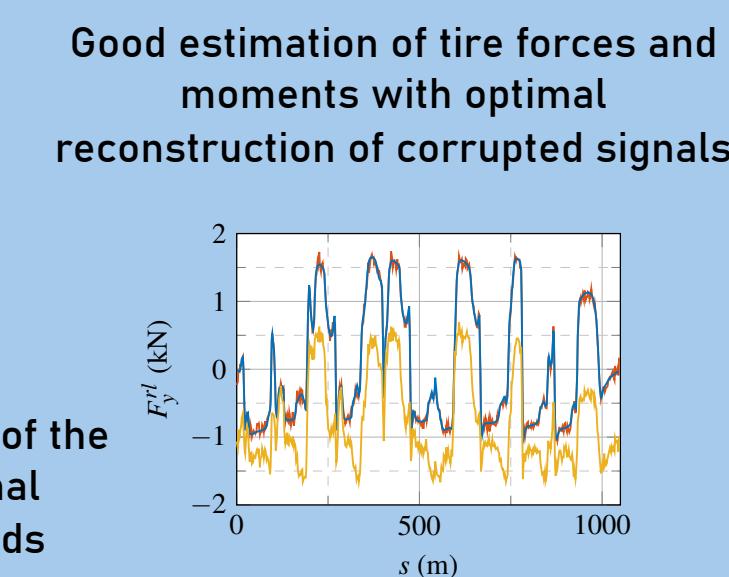
- ✓ *Symbolic modeling ensures efficiency and code consistency*
- ✓ *Nonlinear suspension model with asymmetric tension-compression behavior*
- ✓ *Geometric matrix with steering angle and suspension travel influences*
- ✓ *Optimal control compensates for sensor faults or corrupted data*

Results

Validation on a DIL simulator with a high-fidelity multi-body vehicle model



Insights into contributions of the suspension links internal reactions to the tire loads



Tire forces and moments scaling factors