

A Formal Verification of Reversible Primitive Permutations

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Introduction

Conventions

1. The definition

1.1 The original definition

Formalizing definitions can be quite a challenge on its own. Here is the original definition of Reversible Primitive Permutations (ORPP for short):

Definition 1.1.1 (Original Reversible Primitive Permutations).

By definition, $\text{ORPP} = \bigcup_{k \in \mathbb{N}} \text{ORPP}^k$ is the smallest class of functions $\mathbb{N}^k \rightarrow \mathbb{N}$ such that

- The *identity* Id ,

$$x \quad \text{Id} \quad x$$
- The *sign-change* Ne ,

$$x \quad \text{Ne} \quad -x$$
- The *successor* Su ,

$$x \quad \text{Su} \quad x + 1$$
- The *predecessor* Pr ,

$$x \quad \text{Pr} \quad x - 1$$
- $$\begin{array}{c} x \\ y \end{array} \quad \text{Sw} \quad \begin{array}{c} y \\ x \end{array}$$
- $$\begin{array}{c} x_1 \\ \vdots \\ x_n \end{array} \quad \begin{array}{c} f \circ g \\ \vdots \end{array} \quad \begin{array}{c} y_1 \\ \vdots \\ y_n \end{array} = \begin{array}{c} x_1 \\ \vdots \\ x_n \end{array} \quad \begin{array}{c} f \\ \vdots \end{array} \quad \begin{array}{c} g \\ \vdots \end{array} \quad \begin{array}{c} y_1 \\ \vdots \\ y_n \end{array}$$
- $$\begin{array}{c} x_1 \\ \vdots \\ x_n \\ y_1 \\ \vdots \\ y_m \end{array} \quad \begin{array}{c} f \parallel g \\ \vdots \end{array} \quad \begin{array}{c} w_1 \\ \vdots \\ w_n \\ z_1 \\ \vdots \\ z_m \end{array} = \begin{array}{c} x_1 \\ \vdots \\ x_n \\ y_1 \\ \vdots \\ y_m \end{array} \quad \begin{array}{c} f \\ \vdots \\ g \end{array} \quad \begin{array}{c} w_1 \\ \vdots \\ w_n \\ z_1 \\ \vdots \\ z_m \end{array}$$

$$\begin{aligned}
 & \bullet \begin{array}{c} x_1 \\ \vdots \\ x_n \\ x \end{array} \begin{array}{c} \boxed{\text{It}[f]} \\ y_1 \\ \vdots \\ y_n \\ x \end{array} = \begin{array}{c} \overbrace{\begin{array}{c} x_1 \\ \vdots \\ x_n \\ x \end{array} \begin{array}{c} \boxed{f} \quad \dots \quad \boxed{f} \end{array}}^{|x| \text{ times}} \begin{array}{c} y_1 \\ \vdots \\ y_n \\ x \end{array} \\
 & \bullet \begin{array}{c} x_1 \\ \vdots \\ x_n \\ x \end{array} \begin{array}{c} \boxed{\text{If}[f, g, h]} \\ y_1 \\ \vdots \\ y_n \\ x \end{array} \left. \vphantom{\begin{array}{c} x_1 \\ \vdots \\ x_n \\ x \end{array}} \right\} = \begin{cases} f[x_1, \dots, x_n] & \text{if } x > 0 \\ g[x_1, \dots, x_n] & \text{if } x = 0 \\ h[x_1, \dots, x_n] & \text{if } x < 0 \end{cases}
 \end{aligned}$$