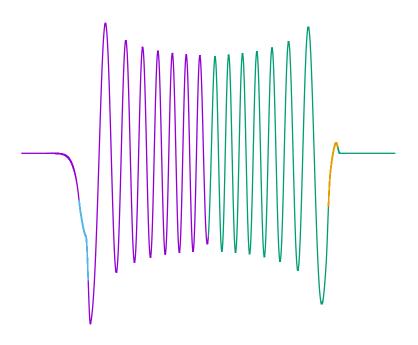
Approximating Solutions of the Time Independent Schrödinger Equation

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Vorwort

Der Rest der Arbeit wird in Englisch sein aber ich habe mich entschieden eine kleine Zusammenfassung zu schreiben, so dass jeder zumindest die Grundlagen meiner Arbeit versteht. Zu begin des 20. Jahrhunderts gab es einen Umschwung in der Physik, Quantenmechanik wurde entdeckt. Diese neue Theorie kann nicht mehr präzise voraussagen machen wie es zuvor der Fall war. Man kann nur noch sagen mit welcher Wahrscheinlichkeit etwas passiert und ein Partikel kann an zwei Orten gleichzeitig sein.

Vielleicht haben Sie schon einmal von Schrödingers Katze gehört. Dies war ein Gedankenexperiment von Schrödinger um auf zu zeigen wie absurd seine Theorie wirklich ist und dass sie nicht stimmen könne. Stell dir vor du schliesst deine Katze in eine Box ein. In dieser Box ist ein Atom das entweder zerfallen kann oder nicht. Dazu gibt es einen Detektor der misst ob das Atom zerfallen ist, in diesem Fall wird ein Gift frei gelassen und die Katze stirbt. Das Problem ist jetzt aber, dass dieses Atom den Regeln der Quanten Mechanik folgt und deshalb gleichzeitig bereits zerfallen ist und nicht zerfallen ist, die einzig logische Schlussfolgerung ist deshalb, dass die Katze gleichzeitig Tod und am leben ist (Schrödinger, 1935).

In der Realität funktioniert es wahrscheinlich jedoch nicht so. Heisst das Universum "entscheidet" ob die Katze gestorben ist oder nicht, jedoch weiss man bis Heute nicht wann das Universum "entscheidet".

Damit die Katze gleichzeitig Tod und Lebendig sein kann brauchen wir die Wellenfunktion. Sie beschreibt alles was in unserem Universum gerade passiert und "speichert" wie wahrscheinlich es ist, dass die Katze tot ist.

In meiner Maturaarbeit habe ich ein Programm geschrieben das genau diese Wellenfunktion ausrechnet in einem sehr vereinfachten Universum. Weil ich schon lange mal wissen möchte wie genau dieses bizarre Objekt aussieht. Auf der Titel Seite ist eine dieser Wellenfunktionen abgebildet.

1. Introduction

Richard Feynmann one of the core people behind our modern theory of quantum mechanics repeatedly said: "I think I can safely say that nobody understands quantum mechanics.". Nothing behaves like in our every day lives. Everything is just a probability and nothing certain. Even Schrödinger the inventor of the equation that governs all of those weird phenomena rejected the idea that there are just probabilities.

In this paper we will try to understand this world a little bit better by looking at wave functions in a simplified universe. This universe only has 1 dimension and there will not be any sense of time. This means we will be able to actually see how the wave function looks like in a graph.

1.1. Goals

The goal of this Maturaarbeit is to write a program, schroeding-approx that calculates solutions to the time independent Schrödinger equation in 1 dimension for a large verity of potentials. We assume that the wave function, $\Psi(x)$ will converge to 0 as x goes to $\pm\infty$. The program should be reasonably fast, meaning that for simple potentials and low energies it should be done in under 1 minute. The architecture should be able to support improvements.

Making the program user friendly is not a main focus. Meaning that a clear and simple API that can be extended in the future is enough. Even dough the user will have to edit the code to for example change between energies.

The program should also follow the UNIX philosophy, "do one thing and one thing well". As a consequence the program will only do the calculations and not the plotting. But it provides a simple and clear interface for a plotting program such as GNU Plot.

The main focus will be to balance performance and accuracy. Accuracy manly meaning that the visualizations should be visually accurate and give some insight into quantum mechanics. The user should also be able to tune the balance between performance and accuracy to some degree.

2. Preliminary

2.1. Schrödinger Equation

In 1926 Erwin Schrödinger changed our understanding of quantum physics with the Schrödinger equation. Based on the observations of de Broglie that particles behave like waves he developed a wave equation which describes how the waves move and change in a given potential V(x) or Hamiltonian \hat{H} .

$$i\hbar \frac{\partial}{\partial t} \Psi(x,t) = \left[-\frac{\hbar^2}{2m} \frac{\partial^2}{\partial x^2} + V(x,t) \right] \Psi(x,t)$$

Or more general

$$\mathrm{i}\hbar\frac{\partial}{\partial t}\Psi(x,t) = \hat{H}\Psi(x,t)$$

The time independent version that is going to be used later, ignores the change over time and is much simpler to solve since it is *only* an ordinary differential equation instead of a partial differential equation.

$$E\psi(x) = \hat{H}\psi(x)$$

or

$$-\frac{\hbar^2}{2m}\frac{d^2\psi}{dx^2}(x) + V(x)\psi(x) = E\psi(x)$$

Even with the time independent equation it is very difficult to get analytical solutions, because of this there are mainly three approaches to approximate solutions of $\psi(x)$, perturbation theory, density functional field theory and WKB approximation. Perturbation theory's goal is to give an analytical approximation which means it is extremely difficult to implement for a computer. WKB on the other hand is much better since it is to some degree a step by step manual.

2.2. Rust

Rust is one of the newer programming languages and attempts to replace C/C++ which are notoriously difficult to work with. It supports both functional and object-oriented paradigms. It is much safer in terms of memory and promises the same performance as C. One of the goals of Rust is fearless concurrency which means everybody should be able to write concurrent

code without deadlocks and data races. This means calculations can utilize the full potential of the CPU without countless hours of debugging.

Functional programming languages are especially useful for mathematical problems, because they are based on the same mathematics as the problem.

Rust as of the time of writing this document is not yet standardized meaning the code provided might no longer be correct with one of the newer Rust versions.

In case you aren't familiar with Rust, it has excellent documentation on https://doc.rust-lang.org/book/.

2.3. Interpretation of Quantum Mechanics

The author believes in the many worlds interpretation of Hugh Everett. "The wave interpretation. This is the position proposed in the present thesis, in which the wave function itself is held to be the fundamental entity, obeying at all times a deterministic wave equation." (DeWitt und Graham, 2015, p. 115). This means that the observer is also quantum mechanical and gets entangled with one particular state of the system that is being measured (DeWitt und Graham, 2015, p. 116). This is some what different to the popular explanation of many worlds but has the same results and is, at least to the author more reasonable.

An important point for the author also was that the theory accepts quantum mechanics as it is and doesn't make unreasonable assumption such as that the observer plays an important role.

On top of that this interpretation also discards the need for an "observation" in the program which would also be mathematically impossible (DeWitt und Graham, 2015, p. 111).

2.4. Complex Numbers

In quantum mechanics it's customary to work with complex numbers. Complex numbers are an extension to the real numbers, since Rust will do most of the heavy lifting here are the most important things that you should know

$$i^{2} = -1$$

$$z = a + bi$$

$$Re(z) = a$$

$$Im(z) = b$$

$$\overline{z} = a - bi$$

$$||z||^{2} = a^{2} + b^{2}$$

$$e^{\theta i} = \cos(\theta) + i\sin(\theta)$$

i is the imaginary unit, z is the general form of a complex number where $\{a,b\} \in \mathbb{R}$, \overline{z} is the complex conjugate and $||z||^2$ is the norm square of z. The last equation is the Euler's formula, it rotates a number in the complex plane by θ radians.

The complex plane is similar to the real number line, every complex number can be represented on this plane where Re(z) is the x-coordinate and Im(z) is the y-coordinate.

2.5. Gnuplot

Gnuplot is a cross platform plotting program that is very simple to use. schroedingerapprox will output a file data.txt, you can plot the function by typing gnuplot and then typing

1 call "plot.gnuplot"

to plot the real part of the wave function, or

1 call "plot 3d.gnuplot"

to see the full complex wave function.

If you'd like to learn more about Gnuplot you can read there user manual on http://www.gnuplot.info/

2.6. Planck Units

By using Planck units the equations get a little bit easier. Working in Planck units means that all fundamental constants are equal to 1.

$$c = k_B = G = \hbar = 1.$$

This means that the constants will usually cancel out.

To convert to SI units we can just multiply powers of the constants such that there unit results in one of the base units.

$$l_{\rm Planck} = l_{\rm SI} \sqrt{\frac{G\hbar}{c^3}} \qquad 1 \text{ m}_{\rm Planck} \approx 1.616255(18) \cdot 10^{-35} \text{ m} \qquad \text{(CODATA, 2022a)}$$

$$m_{\rm Planck} = m_{\rm SI} \sqrt{\frac{c\hbar}{G}} \qquad 1 \text{ kg}_{\rm Planck} \approx 2.176434(24) \cdot 10^{-8} \text{ kg} \qquad \text{(CODATA, 2022b)}$$

$$t_{\rm Planck} = t_{\rm SI} \sqrt{\frac{G\hbar}{c^5}} \qquad 1 \text{ s}_{\rm Planck} \approx 5.391247(60) \cdot 10^{-44} \text{ s} \qquad \text{(CODATA, 2022c)}$$

(Gaarder Haug, 2016, Table 1)

The program will take all of its in- and outputs in Planck units.

3. Methods

3.1. Program Architecture

The program has multiple interfaces or traits as they are called in Rust that give the program some abstraction. In C is a UML diagram of the architecture. Since current version of Rust does not support manual implementations of std::ops::Fn we have to define our own trait for functions Func<A, R> where A is the type of the argument and R is the return type. Later we will use this trait to implement functions for integration, evaluation and more useful utilities.

WaveFunction is at the heart of the program, it contains all the functionality to build wave functions. It is composed of WaveFunctionPart which represent either a Joint, PureWkb or an ApproxPart. With the range function we can check when they are valid.

3.2. Newtons Method

Newton's method, also called the Newton-Raphson method, is a root-finding algorithm that uses the first few terms of the Taylor series of a function f(x) in the vicinity of a suspected root (Weisstein, 2022). It makes a sequence of approximations of a root x_n that in certain cases converges to the exact value where

$$\lim_{n\to\infty}f(x_n)=0$$

The sequence is defined as

$$x_0 = a$$

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$$

Visually this looks like figure 3.1 f(x) = (x-2)(x-1)(x+1).

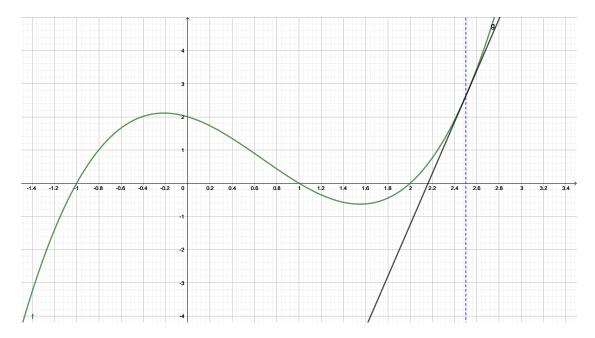


Figure 3.1.: Illustration of Newtons method, f(x) = (x-1)(x-2)(x+1).

The blue line indicates the initial guess which in this case is 2.5 the black line (g(x)) is a tangent to f(x) at (guess, f(guess)) the next guess will be where the tangent intersects the x-Axis (solution of g(x) = 0). This will converge rather quickly compared to other methods such as Regula falsi.

```
1
    pub fn newtons method<F>(f: &F, mut guess: f64, precision: f64) -> f64
 2
 3
             F: Fn(f64) -> f64,
 4
 5
        loop {
 6
             let step = f(guess) / derivative(f, guess);
 7
             if step.abs() < precision {</pre>
 8
                 return guess;
 9
             } else {
                 guess -= step;
10
11
             }
12
        }
13
    }
```

In Rust the sequence is implemented with a function that takes a closure f, the initial guess guess and a stop condition precision the function will return if $||cfracf(x_n)f'(x_n)||$ is less than precision.

From the structure of the algorithm it is very tempting to implement it recursively, but by using a loop it is much faster since there are no unnecessary jumps and the precision can (at least in theory) be 0 without causing a stack overflow.

3.3. Regula Falsi with Bisection

Newtons method fails if the first guess is at a maximum, since the step would go to infinity. For this case we can first use a bisection search to detect a sign change. We need to do a bisection search since Regula falsi requires two guesses.

The algorithm itself is quite simple. To start we need

$$f(x): \mathbb{R} \to \mathbb{R} \tag{3.1}$$

$$\{a \in \mathbb{R} \mid f(a) \le 0\} \tag{3.2}$$

$$\{b \in \mathbb{R} \mid f(b) \ge 0\}. \tag{3.3}$$

Then we can draw a line between the two points (a, f(a)) and (b, f(b)). Then a becomes the x-value where the line intersects the x-axis becomes the new b, when we do the process again with the new b we will get our new value for a. We can repeat this process until we cross a fresh hold for the accuracy and the result will be the last intersection of the line with the x-axis.

3.4. Derivatives

Derivatives can be calculated numerically as in the C++ library Boost (John Maddock, 2022). The author implemented a analytical system for derivatives in Go. From that experience the benefit is negligible compared to the increase in performance and in development time since every function is a special object.

```
1
    pub fn derivative<F, R>(func: &F, x: f64) -> R
 2
 3
        F: Fn(f64) \rightarrow R + ?Sized,
 4
        R: Sub<R, Output = R> + Div<f64, Output = R> + Mul<f64, Output = R> + Add<R,
             Output = R>,
 5
    {
 6
        let dx = f64::epsilon().sqrt();
 7
        let dx1 = dx;
 8
        let dx2 = dx1 * 2.0;
 9
        let dx3 = dx1 * 3.0;
10
        let m1 = (func(x + dx1) - func(x - dx1)) / 2.0;
11
12
        let m2 = (func(x + dx2) - func(x - dx2)) / 4.0;
13
        let m3 = (func(x + dx3) - func(x - dx3)) / 6.0;
14
15
        let fifteen m1 = m1 * 15.0;
16
        let six m2 = m2 * 6.0;
17
        let ten dx1 = dx1 * 10.0;
18
19
        return ((fifteen m1 - six m2) + m3) / ten dx1;
20
```

f64::epsilon().sqrt() is approximately 0.000000014901161. f64::epsilon() is the smallest double precision floating point number where $1 + \epsilon \neq 1$. this has been chosen for dx because it should be fairly precise.

3.5. Integration

The same principles apply to integrals as to derivative it would not be a great benefit to implement an analytic integration system. Integrals would also be much more difficult to implement than derivatives since integrals can not be broken down in to many smaller integrals that can be computed easily instead it needs to be solved as is.

One approach would be to use the same method as with the derivative, take the definition with the limit and use a small value but this method can be improved in this case, since integrals calculate areas under curves a trapeze is more efficient and accurate then the rectangle that results from the definition.

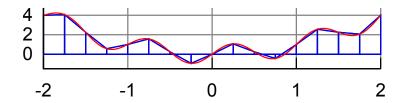


Figure 3.2.: Illustration of integration with trapeze from Wkipedia (2022).

Figure 3.2 shows visually how the methods work, each blue trapeze from start (*a*) to end (*b*) has an area of

$$\int_{a}^{b} f(x) dx \approx (b-a) f\left(\frac{a+b}{2}\right).$$

One trapeze would be fairly inaccurate to calculate the area under the function but as the area from *a* to *b* is subdivided further the result become better and better.

The general structure of the algorithm can very easily be run in parallel since it doesn't matter in which order the segments are added together and the segments also don't dependent on one another. In Rust this is implemented using rayon. Rayon is an implementation for parallel iterators meaning that normal data structures that implement std::iter can be run in parallel <code>just</code> by changing ::iter() to ::par_iter(). This might not work in all cases because of memory safety but in this case the borrow checker will throw an error and the code wont compile.

```
pub trait Func<A, R>: Sync + Send {
    fn eval(&self, x: A) -> R;
}

pub struct Point {
    pub x: f64,
    pub y: Complex64,
}
```

Such that functions with states, like wave functions that store parameters, can be integrated there is a trait Func<A, R>.

Point stores both the input, x and the output, y of a function.

```
pub fn evaluate function between<X, Y>(f: &dyn Func<X, Y>, a: X, b: X, n: usize) ->
        Vec<Point<X, Y>>
 2
    where
 3
        X: Copy
 4
            + Send
 5
            + Sync
 6
            + std::cmp::PartialEq
 7
            + From<f64>
 8
            + std::ops::Add<Output = X>
 9
            + std::ops::Sub<Output = X>
10
            + std::ops::Mul<Output = X>
11
            + std::ops::Div<Output = X>,
12
        Y: Send + Sync,
13
        if a == b {
14
15
             return vec![];
16
        }
17
18
        (0..n)
19
             .into_par_iter()
20
             .map(|i| {
```

```
21
                index_to_range(
22
                    X::from(i as f64),
23
                    X::from(0.0_f64),
24
                    X::from((n - 1) as f64),
25
                    a,
26
                    b,
27
                )
28
            })
29
            .map(|x: X| Point { x, y: f.eval(x) })
30
            .collect()
31
    }
```

Func<X, Y> can be passed to evaluate_function_between it calculates n points between an interval from a to b and returns a vector of Point. X and Y are general data types such that it supports as many types of numbers as possible.

```
1
    pub fn integrate<</pre>
 2
        X: Sync + std::ops::Add<Output = X> + std::ops::Sub<Output = X> + Copy,
 3
        Y: Default
 4
            + Sync
 5
            + std::ops::AddAssign
 6
            + std::ops::Div<f64, Output = Y>
 7
            + std::ops::Mul<Output = Y>
 8
            + std::ops::Add<Output = Y>
 9
            + Send
10
            + std::iter::Sum<Y>
11
            + Copy
12
            + From<X>,
13
    >(
14
        points: Vec<Point<X, Y>>,
15
        batch size: usize,
16
    ) -> Y {
17
        if points.len() < 2 {</pre>
18
             return Y::default();
19
        }
20
21
        let batches: Vec<&[Point<X, Y>]> = points.chunks(batch size).collect();
22
23
        let parallel: Y = batches
24
            .par iter()
25
             .map(|batch| {
26
                 let mut sum = Y::default();
27
                 for i in 0..(batch.len() - 1) {
28
                     sum += trapezoidal_approx(&batch[i], &batch[i + 1]);
29
                }
30
                 return sum;
31
            })
32
             .sum();
33
34
        let mut rest = Y::default();
35
36
        for i in 0..batches.len() - 1 {
37
             rest += trapezoidal approx(&batches[i][batches[i].len() - 1], &batches[i +
                 1][0]);
38
        }
39
40
        return parallel + rest;
41 }
```

The actual integration happens in integrate, it calculates the areas of the trapezes between the points passed to it. For optimization 1000 trapezes are calculated per thread because it would take more time to create a new thread then to actually do the calculation, this has to be further investigated and 1000 might not be optimal. The calculations performed per thread are called a batch, after all batches have been calculated the boundaries between batches also has to be considered therefor they are added in the end with rest.

3.6. Transition Regions

The approximation that will be used splits $\Psi(x)$ into multiple parts that do not match perfectly together.

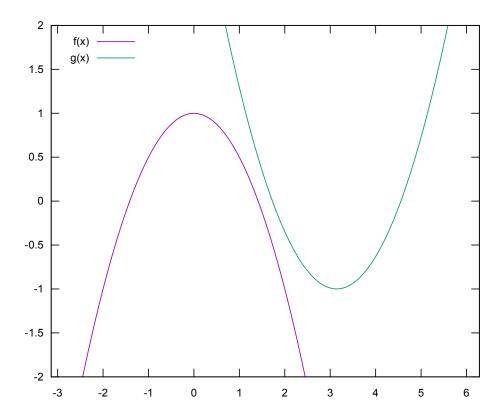


Figure 3.3.: Example for joining functions

Lets consider an example, in figure 3.6 we can see two Taylor series of cosine. Now we have to join the two functions at $x = \pi/2$ such that its a mathematically smooth transition.

$$f(x) = 1 - \frac{x^2}{2} \tag{3.4}$$

$$f(x) = 1 - \frac{x^2}{2}$$

$$g(x) = \frac{(x - \pi)^2}{2} - 1$$
(3.4)

As a first guess lets join f(x) and g(x) with a step function, this means that the joint function h(x) will be

$$h(x) = \begin{cases} f(x) & x < \frac{\pi}{2} \\ g(x) & x > \frac{\pi}{2} \end{cases}.$$

This gives us 3.6 which is obviously not smooth.

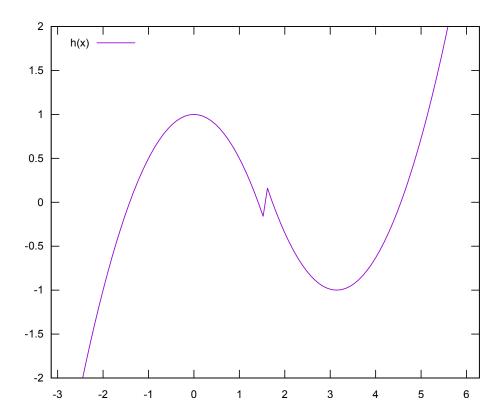


Figure 3.4.: Plot of h(x) with step joint

If we use the formula from (Hall, 2013, p. 325, section 15.6.4) with

$$\delta = 0.5$$

$$\alpha = \frac{\pi}{2} - \frac{\delta}{2}$$

$$\chi(x) = \sin^2\left(x\frac{\pi}{2}\right)$$

this results in

$$h(x) = \begin{cases} f(x) & x < \alpha \\ g(x) & x > \alpha + \delta \end{cases}$$
$$f(x) + (g(x) - f(x))\chi(\frac{x - \alpha}{\delta}) \quad else$$

which is mathematically smooth as we can see in figure 3.6 (proof in Appendix A.1.1).

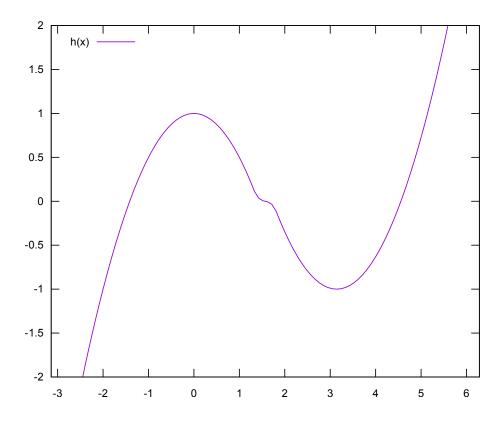


Figure 3.5.: Plot of h(x) with Hall joint

3.6.1. Implementation in Rust

In the program we can define a struct Joint that implements Func<f64, Complex64>. As in the example we need two functions f(x) and g(x) which we will rename to left and right. We will also need a variable α and δ which will be named cut and delta.

```
#[derive(Clone)]
 1
 2
    pub struct Joint {
 3
        pub left: Arc<dyn Func<f64, Complex64>>,
        pub right: Arc<dyn Func<f64, Complex64>>,
 4
 5
        pub cut: f64,
 6
        pub delta: f64,
 7
 8
 9
    impl Func<f64, Complex64> for Joint {
10
        fn eval(&self, x: f64) -> Complex64 {
            let chi = |x: f64| f64::sin(x * f64::consts::PI / 2.0).powi(2);
11
12
            let left_val = left.eval(x);
13
            return left_val + (right.eval(x) - left_val) * chi((x - self.cut) / self.
                delta)
14
```

In the proof we assume that f(x) and g(x) are continuous of first order in the interval $(\alpha, \alpha + \delta)$. In the code we will not check this requirement since it would have a major impact on performance to check the derivative on every point.

4. Calculation

4.1. Energy Levels

Solving the Schrödinger equation is an eigenvalue problem. This means that only certain energies will result in physically correct results. For an energy to be valid it has to satisfy the Maslov-corrected Bhor-Sommerfeld condition which states that

$$n \in \mathbb{N}_0 \tag{4.1}$$

$$C = \{ x \in \mathbb{R} \mid V(x) < E \} \tag{4.2}$$

$$C = \{x \in \mathbb{R} \mid V(x) < E\}$$

$$\int_{C} \sqrt{2m(E - V(x))} dx = 2\pi(n + 1/2)$$
(4.2)

this condition does not (in most cases) give the exact energy levels (Hall, 2013). It can be interpreted such that the oscillating part of the wave function has to complete all half oscillation.

To solve this problem for an arbitrary potential in a computer the set C and the fact that n has to be a non negative integer is not really helpful, but the condition can be rewritten to

$$p(x) = \begin{cases} \sqrt{2m(E - V(x))} & V(x) < E \\ 0 & else \end{cases}$$
 (4.4)

$$\frac{1}{2\pi} \int_{-\infty}^{\infty} p(x)dx - \frac{1}{2} \mod 1 = 0 \tag{4.5}$$

Unfortunately 4.5 is not continuous which means that Newtons method can't be applied. Further on the bounds of integration have to be finite, this means the user of the program will have to specify a value for the constant APPROX INF where any value for x out side of that range should satisfy V(x) > E. But it shouldn't be to big since the integrate function can only evaluate a relatively small number (default 64000) of trapezes before the performance will suffer enormously. The default value for APPROX INF is (-200.0, 200.0).

The implementation is quite strait forward we evaluate 4.5 for a number of energies and then check for discontinuities.

```
pub fn nth energy<F: Fn(f64) -> f64 + Sync>(n: usize, mass: f64, pot: &F, view: (f64,
        f64)) -> f64 {
2
       const ENERGY STEP: f64 = 10.0;
3
       const CHECKS PER ENERGY STEP: usize = INTEG STEPS;
       let sommerfeld cond = SommerfeldCond { mass, pot, view };
4
5
6
       let mut energy = 0.0;
       let mut i = 0;
```

```
8
 9
        loop {
10
            let vals = evaluate function between(
11
                &sommerfeld cond,
12
                energy,
13
                energy + ENERGY STEP,
14
                CHECKS PER ENERGY STEP,
15
            );
16
            let mut int_solutions = vals
                 .iter()
17
18
                 .zip(vals.iter().skip(1))
                 .collect::<Vec<(&Point<f64, f64>, &Point<f64, f64>)>>()
19
20
                 .par_iter()
                 .filter(|(p1, p2)| (p1.y - p2.y).abs() > 0.5 || p1.y.signum() != p2.y.
21
                     signum())
22
                 .map(|ps| ps.1)
23
                 .collect::<Vec<&Point<f64, f64>>>();
24
            int solutions.sort by(|p1, p2| cmp f64(\&p1.x, \&p2.x));
25
            if i + int_solutions.len() > n {
26
                 return int solutions[n - i].x;
27
28
            energy += ENERGY_STEP - (ENERGY_STEP / (CHECKS_PER_ENERGY_STEP as f64 + 1.0))
29
            i += int solutions.len();
30
        }
31
    }
```

First we check over the interval $(0.0, ENERGY_STEP)$ if there are not enough zeros we check the next interval of energies and so on until we found n zeros. It's also possible that 4.5 is negative before the 0th energy there for we also have to check for normal zeros by comparing the signs of the values.

The struct SommerfeldCond is a Func<f64, f64> that evaluates 4.5.

4.1.1. Accuracy

For a benchmark we will use

$$m = 1$$

$$V(x) = x^{2}$$

$$(-\infty, \infty) \approx (-200, 200).$$

To get the actual values we will use Wolfram Language with WolframScript a programing language similar to Wolframalpha that can calculate the integral analytically. In Rust we can rewrite main to

```
1 fn main() {
2   let output_dir = Path::new("output");
3
```

```
4
        let values = (0..=50)
 5
            .into iter()
 6
            .map(|n: usize| Point::<usize, f64> {
 7
                y: energy::nth energy(n, 1.0, &potentials::square, APPROX INF),
 8
 9
            })
10
            .collect::<Vec<Point<usize, f64>>>();
11
12
        std::env::set_current_dir(&output_dir).unwrap();
13
        File::create("energy.txt")
14
            .unwrap()
            .write_all(plot::to_gnuplot_string(values).as_bytes())
15
16
17 }
```

This will output all energy levels from n = 0 to n = 50. We can implement the same thing WolframScript

```
m = 1
 1
 2
   V[x_{-}] = x^2
 3
 4
    nthEnergy[n ] = Module[{energys, energy},
 5
        sommerfeldIntegral[en] = Integrate[Sqrt[2*m*(en - V[x])],
 6
                                                 {x, -Sqrt[en], Sqrt[en]}]
        energys = Solve[sommerfeldIntegral[en] == 2*Pi*(n + 1/2), en] // N;
 7
 8
        energy = en /. energys[[1]];
 9
        energy
10
        ]
11
12
    energys = Table[\{n, N@nthEnergy[n]\}, \{n, 0, 50\}]
13
14 csv = ExportString[energys, "CSV"]
    csv = StringReplace[csv, "," -> " "]
16 Export["output/energies_exact.dat", csv]
```

These programs will output two files energy.txt (Appendix B.1) for our implementation in Rust and energies_exact.dat (Appendix B.1) for WolframScript. As a ruff estimate we would expect an error of $\pm \frac{10}{64000} \approx \pm 1.56 * 10^{-4}$, because the program checks for energies with that step size.

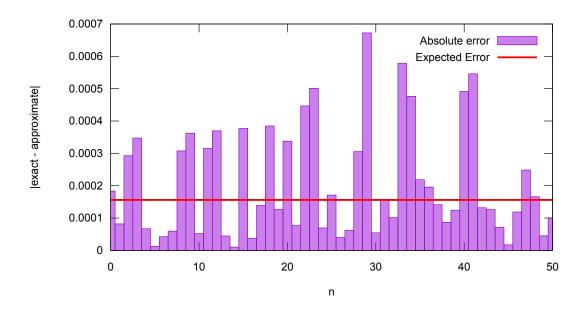


Figure 4.1.: Absolute error of energy levels in square potential

When we plot the absolute error we get figure 4.1.1. The error is a little higher than expected which is probably due to errors in the integral. Still the algorithm should be precise enough. If you'd like you could pick a lower value for ENERGY_STEP in src/energy.rs:49, but this will impact the performance for calculating energies with higher numbers for n.

4.2. Approximation Scheme

There are mainly three approximation methods used to solve for the actual wave function itself. There is perturbation theory which breaks the problem down in to ever smaller subproblems that then can be solved exactly. This can be achieved by adding something to the Hamiltonian operator \hat{H} which can then be solved exactly. But perturbation theory is inefficient compared to other approximation methods when calculated on a computer (Van Mourik et al., 2014, Introduction).

The second is Density functional field theory, it has evolved over the years and is used heavily in chemistry to calculate properties of molecules and is also applicable for the time dependent Schrödinger equation. It is something that might be interesting to add to the program in the future.

The program uses the third method WKB approximation, it is applicable to a wide verity of linear differential equations and works very well in the case of the Schrödinger equation. Originally it was developed by Wentzel, Kramers and Brillouin in 1926. It gives an approximation to the eigenfunctions of the Hamiltonian \hat{H} in one dimension. The approximation is best understood as applying to a fixed range of energies as \hbar tends to zero (Hall, 2013,

p. 305).

WKB splits $\Psi(x)$ into tree parts that can be connected to form the full solution. The tree parts are described as

$$p(x) = \sqrt{2m(|E - V(x)|)}$$
 (4.6)

$$V(t) - E = 0 \tag{4.7}$$

$$\psi_{exp}^{WKB}(x) = \frac{c_1}{2\sqrt{p(x)}} \exp\left(-\left|\int_x^t p(y)dy\right|\right) \tag{4.8}$$

$$\psi_{osz}^{WKB}(x) = \frac{c_1}{\sqrt{p(x)}} \cos\left(\int_x^t p(y)dy - \delta\right)$$
 (4.9)

$$u_1 = -2m\frac{dV}{dx}(t) \tag{4.10}$$

$$\psi^{Airy}(x) = \frac{c_1 \sqrt{\pi}}{\sqrt[6]{u_1}} \operatorname{Ai}\left(\sqrt[3]{u_1}(t-x)\right). \tag{4.11}$$

Since equation 4.7 might have more than one solution for turning points t, we have to consider each one of them individually and in the end join them into one function.

The factor of 1/2 in equation 4.8 is analogous to (Littlejohn, 2020, eq. 92). This means that it's only valid if the turning points aren't "too close together" (Littlejohn, 2020). This will be a problem later when we look at some solutions. Littlejohn (2020) also mansions that there are extensions to WKB that can handle these cases. It would be interesting to add those to the program in the future.

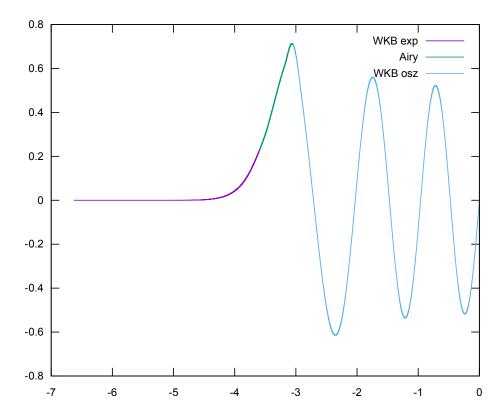


Figure 4.2.: Left half of wave function with $N_{Energy} = 5 \Rightarrow E = 11.0$, m = 2, $V(x) = x^2$

In figure 4.2 the three parts are visualized. The purple section on the left is the exponential decaying part $\psi^{WKB}_{exp}(x)$, equation 4.8 is a modified version of the original version as described in (Hall, 2013, p. 317, eq. 15.25) where b and a are different solutions for t of equation 4.7. The absolute symbol makes it possible to not differentiate between the case where x < t and x > t. Further on a factor of $e^{\delta i}$ was added such that the imaginary part of $\psi^{WKB}_{exp}(x)$ is the same as in $\psi^{WKB}_{osz}(x)$.

The blue part on the right is $\psi_{osz}^{WKB}(x)$. Again equation 4.9 was expanded to result in the more general complex solution and it also works for both ψ_1 and ψ_2 in (Hall, 2013, p. 316-317, Claim 15.7). Hall (2013) assumes that $\delta = \pi/4$ which doesn't work in the simple case of $V(x) = x^2$, in figure 4.2 $\delta = 0$ was used. This will be further discussed in section ??.

4.2.1. Validity

When we look at the derivation of WKB we will see that equations 4.8 and 4.9 can only be valid if

$$p(x) = \sqrt{V(x) - E}$$
$$\left| \frac{dp}{dx}(x) \right| \ll p^2(x)$$

as Zwiebach (2018) showed in his lecture. But this would mean that WKB is only valid iff V(x) > E because $p^2(x)$ would be negative otherwise. If this is the case this would imply that 4.8 can't be valid.

We will assume that this contradiction is wrong and assume that WKB is valid if

$$\left| \frac{d}{dx} (\sqrt{|V(x) - E|}) \right| < |V(x) - E|$$

4.2.2. Implementation

4.3. Turning Points

A point x where V(x) = E is called a turning point. We assume that the WKB function is a good approximation in the region where

$$-\frac{1}{2m}\frac{dV}{dx}(x) \ll (V(x) - E)^2. \tag{4.12}$$

In order to do the actual calculation we need a range were the Airy function is valid. From equation 4.12 we can infer that the Airy function is valid where

$$-\frac{a}{2m}\frac{dV}{dx}(x) - (V(x) - E)^2 > 0 {(4.13)}$$

We can assume that the Airy function is only valid in a closed interval, this means that there must be at least two roots of equation 4.13. These roots will be called turning point boundaries from now on. The factor of a is used to emulate the behavior of \ll .

The left boundary point must have a positive and the right a negative derivative. This means we can solve for roots and group them together by there derivatives.

In order to find all roots we will use a modification of Newtons method. When we find a solution, x_0 we can divide the original function by $(x-x_0)$ this means that Newtons method wont be able to find x_0 again.

Further on since we check for roots inside the interval of APPROX_INF we don't have a good first guess where the turning point might be. Because of this we will make 1000 guesses evenly distributed over the interval and invent a system that can rate how good of a guess this point could be. Newtons method works well if the value of f(x) is small and f'(x) is neither to small nor to big. We will assume that f'(x) = 1 is optimal. As a rating we will use

$$\sigma(x) = \frac{|f(x)|}{-\exp\left(\left(\frac{df}{dx}(x)\right)^2 + 1\right)}$$

where lower is better. This function is just an educated guess, but it has to have some properties, as the derivative of f tends to 0, $\sigma(x)$ should diverge to infinity.

$$\lim_{\frac{df}{dx}\to 0} \sigma(x) = \infty$$

If f(x) = 0 we found an actual root in the first guess meaning that $\sigma(x)$ should be 0. Formula 4.3 doesn't satisfy this property since it's undefined if f'(x) = 0 and f(x) = 0, but we can extend it's definition such that

$$\sigma(x) = \begin{cases} \frac{|f(x)|}{-\exp(\left(\frac{df}{dx}(x)\right)^2 + 1)} & f(x) \neq 0 \text{ and } \frac{df}{dx} \neq 0\\ 0 & \text{else} \end{cases}$$

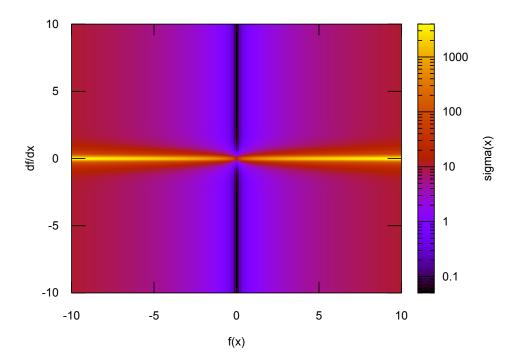


Figure 4.3.: Logarithmic heat diagram of $\sigma(x)$, darker/bluer is better

As we can see in figure 4.3 where darker/bluer values are better than yellow/red areas that $\sigma(x)$ indeed has all of the desired properties.

After we rated all of the 1000 guesses we can pick the best one as a first guess and use the modified Newtons method with it. We do this process 256 times by default. In theory we could therefor use the WKB approximation for potentials with up to 256 turning points.

```
1 fn find_zeros(phase: &Phase, view: (f64, f64)) -> Vec<f64> {
2    let phase_clone = phase.clone();
3    let validity_func = Arc::new(move |x: f64| {
```

```
4
            1.0 / (2.0 * phase clone.mass).sqrt() * derivative(&|t| (phase clone.
                 potential)(t), x).abs()
 5
                 - ((phase clone.potential)(x) - phase clone.energy).pow(2)
 6
        });
 7
        let mut zeros = NewtonsMethodFindNewZero::new(validity func, ACCURACY, 1e4 as
            usize);
 8
 9
        (0..MAX_TURNING_POINTS).into_iter().for_each(|_| {
10
            let modified_func = |x| zeros.modified_func(x);
11
12
            let guess = make_guess(&modified_func, view, 1000);
13
            guess.map(|g| zeros.next_zero(g));
14
        });
15
        let view = if view.0 < view.1 {</pre>
16
17
            view
18
        } else {
19
            (view.1, view.0)
20
        let unique_zeros = zeros
21
22
             .get previous zeros()
23
             .iter()
24
             .filter(|x| **x > view.0 \&\& **x < view.1)
25
             .map(|x| *x)
26
             .collect::<Vec<f64>>();
27
        return unique_zeros;
28
    }
```

Here make_guess uses $\sigma(x)$ and returns the best guess. NewtonsMethodFindNewZero is the modified version of Newtons method where all the roots are stored and its implementation of Func<f64, f64> is just defined as

$$\frac{f(x)}{\prod\limits_{r\in Z}(x-r)}\tag{4.14}$$

Where the set Z is the set of all the zeros that have been found previously. After the 256 iterations we filter out all the zeros that aren't in the view. Equation 4.14 is implemented in NewtonsMethodFindNewZero. Unfortunately this procedure can't be implement asynchronously since you have to know all previous zeros before you can find a new one.

Once we found the zeros we need to group them as previously mentioned the derivative of the validity function (4.13) must be positive if the boundary point is on the left and negative when its on the right side of the turning point. It could be the case that if the turning point is in the view that one of the boundary points is actually outside the view. For this we can use Regula falsi combined with bisection. We will do this for both the left and right most turning point if there was only one boundary found.

4.4. Wave Function Parts

All the equations of

4.5. Wave Function

To combine all the WaveFunctionPart structs, we will define the WaveFunction struct. Under the hood it will also calculate all the variables and construct all the WaveFunctionPart structs.

First we need to calculate the energy for the given parameters that are passed to the constructor. Note the this energy will also be printed to the terminal.

```
let energy = energy::nth_energy(n_energy, mass, &potential, approx_inf);
println!("{}_Energy:_{{:.9}}", Ordinal(n_energy).to_string(), energy);
```

Using the energy we can calculate the view. For this we need to find the two outermost turning points. This can be done by applying Newtons method to

$$V(x)-E$$

with initial guesses approx_inf.0 for lower_bound and approx_inf.1 for upper_bound. The view will then be

```
1 (
2    lower_bound * (upper_bound - lower_bound) * view_factor,
3    upper_bound * (upper_bound - lower_bound) * view_factor,
4 )
```

If Newtons method fails we will define the view to be approx inf.

Once we've got the view, we can calculate all the turning points and there Airy functions along with them, using AiryWaveFunction::new. In the case that there are turning points we can then take go through each turning point and also copy it's neighbors. For the outer most turning points we will take approx inf.

With these groups of 3 we can construct a WkbWaveFunction for each of the turning points. However there were issues when dividing the oscillating part of the wave function was split into two parts with different turning points. According to Hall (2013) it should be mathematically indistinguishable when using either of the turning points, but there arise discontinuities at the transition region. Because of that it has been decided that only the left turning point will be used.

Unfortunately in this method even though the function is continuous it will not be symmetric about the mid point of the oscillating region. This has the effect that the probabilities will be lower on the right none the less they should have the same probability. Because of the architecture of the program the oscillating part will still be split into two distinct regions.

While iterating over the turning points we can also calculate the ranges in which the functions are valid.

Once we have all the WkbWaveFunction instances we need to group them with the AiryWaveFunction instances. Using those pairs we can finally construct all the ApproxPart instances.

Finally we need to apply the scaling which may be one of the following options (where $a \in \mathbb{C}$):

None The solution wont be multiplied by anything.

Mul(a) The solution will be multiplied by a.

Renormalize(a) $\Psi(x)$ will be renormalized such that $\int_{-\infty}^{\infty} |a\Psi(x)|^2 dx = 1$. This can be useful to add a phase to the wave function.

In the case that no turning points are found WKB will be inaccurate. But for completeness we will assume that approx_inf is a turning point. Then we can insert two WkbWaveFunction instances without the Airy functions. This behavior is implemented in PureWkb. Afterwards we apply the same scaling procedure (4.5) as if there were turning points.

In this case you'll also get a warning in the terminal that no turning points were found. Because the results can be inaccurate.

4.5.1. Super Position

Because the super position principal is also applicable to energies it is possible that $\Psi(x)$ is a sum of wave functions with different energies.

On the implementation side this means that we can create a struct SuperPosition that is constructed with a list of energy levels and ScalingType that can be used to construct the previously discussed WaveFunction. Its implementation of Func<f64, Complex64> will then sum over all the results of the individual WaveFunction structs.

5. Program Manual

In the src directory you will find the main.rs file. After the imports (lines with use) you can find all the constants that can be configured. In the description below, (E) stands for "expert" and means that you should use the default unless you really know what you're doing.

Concurrency Configurations Tune accuracy and performance

INTEG_STEPS The number of steps that will be used to integrate over an interval

TRAPEZE_PER_THREAD (E) The number of trapezes that are calculated on a thread in sequence. This number must be smaller then INTEG_STEPS.

NUMBER_OF_POINTS The number of points that will be written to the output file.

APPROX_INF This are the values for " $\pm \infty$ ". Where the first number is $-\infty$ and the second number is ∞ . Most importantly outside of this interval V(x) > E.

Joint configuration Adjust the width of joints

AIRY_TRANSITION_FRACTION (E) When a joint between an Airy and a WKB function has to be added, we have to know how wide the joint should be. The width is calculated by taking the distance between the turning point boundaries and multiplying it by this number.

ENABLE_WKB_JOINTS If set to true joints will be added between Airy and WKB wave function parts. If set to false no joints will be added at this boundary.

VALIDITY_LL_FACTOR (E) This factor gets used as *a* in 4.13. Higher values will create larger ranges for Airy functions.

5.1. Wave Function

When you only have one energy level you should use WaveFunction::new.

The example above has to placed right after the fn main() line. You have to replace all the commentaries (/*...*/) with the values you want. For the first you can choose a potential from section 5.4 for this you can type potentials::/*potential*/.

For the Mass you can just use a normal float.

"nth energy " must be a positive integer (including 0) and is the nth energy level of the potential.

And as for the scaling type, choose one of the options described at the end of section ??.

5.2. SuperPosition

To construct a super position you can add this to your main function

```
let wave function = wave function builder::SuperPosition::new(
 1
 2
        &/*potential*/,
 3
        /*mass*/,
 4
        []&
 5
            (/*nth energy*/, /*phase*/),
 6
            (/*nth energy*/, /*phase*/),
 7
 8
 9
        APPROX INF,
10
        1.5, // view factor
11
        ScalingType::/*scaling*/),
12);
```

Just like in section 5.1 you have to replace all the commentaries (/*...*/) with the values you want.

"potential" you have to choose a potential from section 5.4.

"nth energy " must be a positive integer (including 0) and is the nth energy level of the potential.

"phase" a complex number that the wave function with the corresponding energy will be multiplied by. To make a complex number you can use complex(/*Re*/, /*Im*/).

"// ..." you can add as many energies as your computer can handle.

And as for the scaling type, choose one of the options described at the end of section ??.

5.3. Plotting

For all the plotting methods mentioned below you'll need an output directory in which the files will be placed.

```
1 let output_dir = Path::new("output");
```

The default is *output*, you can choose any directory name that you'd like. The folder will be located where you ran the program. The data calculated by the program will be stored as space separated values like in the example below (the first line will not be in the output file).

[&]quot;mass" your mass as a float.

x Re Im1.0 2.718 3.1412.0 1.414 1.465

Every line is a data point where the first number is the x-coordinate, the second the real part of $\Psi(x)$ and the third the imaginary part of $\Psi(x)$

5.3.1. WaveFunction

For a WaveFunction as we've seen in section 5.1 you have three options.

plot_wavefunction

With plot::plot wavefunction the result will be plotted as one function in gnuplot.

1 plot::plot_wavefunction(&wave_function, output_dir, "data.txt");

You can replace data.txt with another file name.

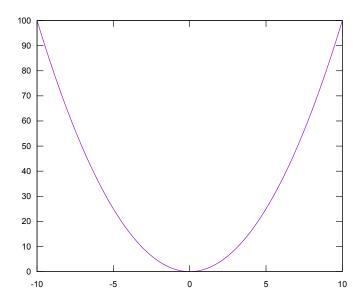
plot_wavefunction_parts

plot probability

5.4. Potentials

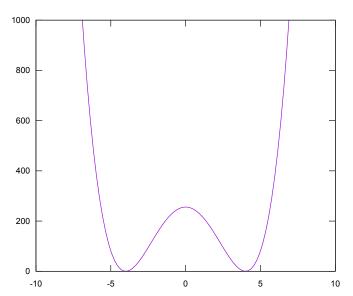
square Normal square potential as used in Hall (2013).

 x^2



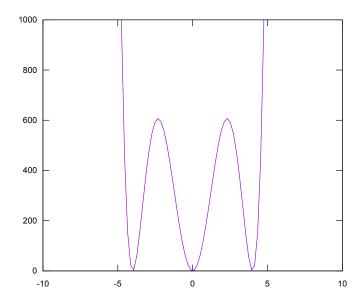
mexican_hat 4th degree polynomial that looks like a mexican hat, with 2 minima.

$$(x-4)^2(x+4)^2$$



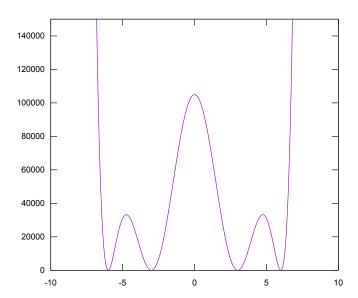
double _mexican _hat 6th degree polynomial that has 3 minima.

$$(x-4)^2x^2(x+4)^2$$



triple _mexican _hat 8th degree polynomial that has 4 minima.

$$(x-6)^2(x-3)^2(x+3)^2(x+6)^2$$



smooth_step Step function that goes to ENERGY_INF outside the interval (-5,5). Joints were added at ± 5 to make the function differentiable.

5.4.1. Custom Potentials

To create a custom potential you'll have to define a function like shown below.

```
1 fn my_potential(x: f64) -> f64 {
2    return /*some calculation*/;
3 }
```

my_potential is the name that you can choose and have to use later when you're passing it to WaveFunction::new. /*some calculation*/ can be any Rust code that results in a f64.

Examples

Negative bell curve $(-e^{-x^2} + 1)$

```
1 fn neg_bell(x: f64) -> f64 {
2    return -(-x.powi(2)).exp();
3 }
```

General polynomial (might not work for all configurations)

```
1 const COEFFICIENTS: [f64;4] = [a, b, c, d]
2 fn polynom(x: f64) -> f64 {
```

You need to set values for a, b, etc. and they need to be floating point numbers or you'll get error E0308. For example 1 would cause an error but 1.0 or 3.141 are correct. You can add even more coefficients if you'd like. The 4 in the square brackets is the degree of the polynomial plus 1. The potential above would mathematically be $a + bx + cx^2 + dx^3$.

A. Detailed Calculations

A.1. Proofs

A.1.1. Smoothness of Transitionfunction

Given that

$$f: \mathbb{R} \to \mathbb{C} \tag{A.1}$$

$$g: \mathbb{R} \to \mathbb{C}$$
 (A.2)

$$\{f,g\} \in C^1 \tag{A.3}$$

$$\{\alpha, \delta\} \in \mathbb{C}$$
 (A.4)

define (Hall, 2013)

$$\chi(x) = \sin^2\left(\frac{\pi(x-\alpha)}{2\delta}\right) \tag{A.5}$$

$$(f \sqcup g)(x) = f(x) + (g(x) - f(x))\chi(x)$$
(A.6)

and proof that

$$\frac{d(f \sqcup g)}{dx}(\alpha) = \frac{df}{dx}(\alpha) \tag{A.7}$$

$$\frac{d(f \sqcup g)}{dx}(\alpha + \delta) = \frac{dg}{dx}(\alpha + \delta). \tag{A.8}$$

Calculate derivatives

$$\frac{d\chi}{dx}(x) = \frac{\pi}{2\delta} \sin\left(\frac{\pi(x-\alpha)}{\delta}\right) \tag{A.9}$$

$$\frac{d(f \sqcup g)}{dx}(x) = \frac{df}{dx}(x) + \left(\frac{dg}{dx}(x) - \frac{df}{dx}(x)\right)\chi(x) + (g(x) - f(x))\frac{d\chi}{dx}(x). \tag{A.10}$$

Note that

$$\frac{d\chi}{dx}(\alpha) = 0 \tag{A.11}$$

$$\chi(\alpha) = 0 \tag{A.12}$$

$$\frac{d\chi}{dx}(\alpha+\delta) = 0 \tag{A.13}$$

$$\chi(\alpha + \delta) = 1 \tag{A.14}$$

therefor

$$\frac{d(f \sqcup g)}{dx}(\alpha) = \frac{df}{dx}(\alpha) + 0\left(\frac{dg}{dx}(\alpha) - \frac{df}{dx}(\alpha)\right) + 0(g(x) - f(x)) = \frac{df}{dx}(\alpha) \tag{A.15}$$

and

$$\frac{d(f \sqcup g)}{dx}(\alpha + \delta) = \frac{df}{dx}(\alpha + \delta) + 1\left(\frac{dg}{dx}(\alpha + \delta) - \frac{df}{dx}(\alpha + \delta)\right) + 0(g(x) - f(x)) \quad (A.16)$$

$$\frac{d(f \sqcup g)}{dx}(\alpha + \delta) = \frac{df}{dx}(\alpha + \delta) + \frac{dg}{dx}(\alpha + \delta) - \frac{df}{dx}(\alpha + \delta) = \frac{dg}{dx}(\alpha + \delta) \blacksquare. \quad (A.17)$$

B. Data Files

B.1. Energies

	energy.txt		energies_exact.dat
1	0 1.4143970999546869	1	0 1.4142135623730951
2	1 4.2427225425397275	2	1 4.242640687119286
3	2 7.071360490007656	3	2 7.0710678118654755
4	3 9.89984218503414	4	3 9.899494936611665
5	4 12.727855127619105	5	4 12.727922061357857
6	5 15.55633682264559	6	5 15.556349186104047
7	6 18.384818517672073	7	6 18.38477631085024
8	7 21.213143965139928	8	7 21.213203435596427
9	8 24.041938165049302	9	8 24.041630560342618
10	9 26.870419860075785	10	9 26.870057685088806
11	10 29.69843279777794	11	10 29.698484809834998
12	11 32.52722700257012	12	11 32.526911934581186
13	12 35.35570869759661	13	12 35.35533905932738
14	13 38.18372163529877	14	13 38.18376618407357
15	14 41.012203335208056	15	14 41.01219330881976
16	15 43.84099753511743	16	15 43.84062043356595
17	16 46.66901047281958	17	16 46.66904755831214
18	17 49.49733591540462	18	17 49.49747468305833
19	18 52.32628637263825	19	18 52.32590180780452
20	19 55.15445556278185	20	19 55.15432893255071
21	20 57.98309351024977	21	20 57.9827560572969
22	21 60.811106452834736	22	21 60.81118318204309
23	22 63.64005690518555	23	22 63.63961030678928
24	23 66.46853860021204	24	23 66.46803743153548
25	24 69.29639528547274	25	24 69.29646455628166
26	25 72.1247207329406	26	25 72.12489168102785
27	26 74.95335868040853	27	26 74.95331880577405
28	27 77.78168412299357	28	27 77.78174593052023
29	28 80.61047832778574	29	28 80.61017305526643
30	29 83.43927252769512	30	29 83.43860018001261
31	30 86.26697296051438	31	30 86.2670273047588
32	31 89.09561090798232	32	31 89.095454429505
33	32 91.92378010300872	33	32 91.92388155425118
34	33 94.75288680780098	34	33 94.75230867899738
35	34 97.58121225038602	35	34 97.58073580374356
36	35 100.40938144541242	36	35 100.40916292848975
37	36 103.23739438311458	37	36 103.23759005323595
38	37 106.06587607814106	38	37 106.06601717798213

39	38 108.89435777316754	39 38 108.89444430272833
40	39 111.72299572551829	40 39 111.72287142747452
41	40 114.55178992542766	41 40 114.5512985522207
42	41 117.38027162045414	42 41 117.3797256769669
43	42 120.2082845630391	43 42 120.20815280171308
44	43 123.0364537531827	44 43 123.03657992645928
45	44 125.86493544820918	45 44 125.86500705120547
46	45 128.69341714323565	46 45 128.69343417595167
47	46 131.52174259070352	47 46 131.52186130069785
48	47 134.35053679061292	48 47 134.35028842544403
49	48 137.17854972831506	49 48 137.17871555019022
50	49 140.0071876806658	50 49 140.00714267493643
51	50 142.83566937569228	51 50 142.83556979968262

C. Source Code

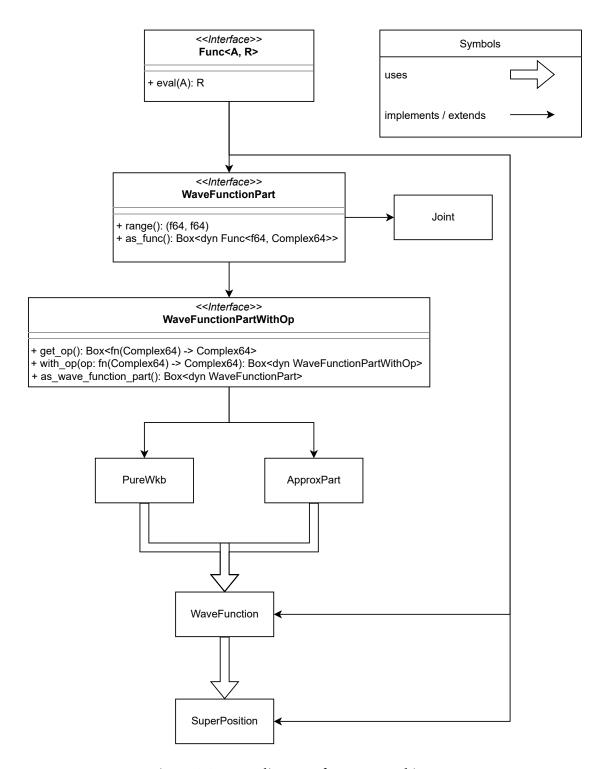


Figure C.1.: UML diagram of program architecture

The source code is also available on the authors GitHub https://github.com/Gian-Laager/Schroedinger-Approximation

src/main.rs

```
1 #![allow(dead code)]
 2
 3 mod airy;
 4 mod airy wave func;
 5 mod check;
 6 mod energy;
 7 mod integrals;
 8 mod newtons method;
 9 mod plot;
10 mod potentials;
11 mod tui;
12 mod turning_points;
13 mod utils;
14 mod wave_function_builder;
15 mod wkb_wave_func;
16
17 use crate::airy::airy_ai;
18 use crate::airy_wave_func::AiryWaveFunction;
19 use crate::integrals::*;
20 use crate::newtons method::derivative;
21 use crate::utils::Func;
22 use crate::utils::*;
23 use crate::wave function builder::*;
24 use crate::wkb wave func::WkbWaveFunction;
25 use num::complex::Complex64;
26 use num::pow::Pow;
27 use rayon::iter::*;
28 use std::f64;
29 use std::fs::File;
30 use std::io::Write;
31 use std::path::Path;
32 use std::sync::Arc;
33
34 const INTEG_STEPS: usize = 64000;
35 const TRAPEZE_PER_THREAD: usize = 1000;
36 const NUMBER_OF_POINTS: usize = 100000;
37
38 const AIRY TRANSITION FRACTION: f64 = 0.5;
39 const ENABLE AIRY JOINTS: bool = true;
40
41 const VALIDITY_LL_FACTOR: f64 = 3.5;
42
43 const APPROX INF: (f64, f64) = (-200.0, 200.0);
```

```
44
45
    fn main() {
46
        // let wave function = wave function builder::WaveFunction::new(
47
               &potentials::square,
48
        //
               1.0,
               17,
49
        //
50
               APPROX INF,
        //
51
               0.15,
        //
52
        //
               ScalingType::Renormalize(1.0.into()),
53
        // );
54
        let wave_function = wave_function_builder::SuperPosition::new(
55
56
            &potentials::mexican hat,
57
            1.0,
58
            3.
59
                (15, 1.0.into()),
60
                (16, complex(0.0, 1.0 * f64::consts::PI / 8.0).exp()),
61
                (17, complex(0.0, 2.0 * f64::consts::PI / 8.0).exp()),
                (18, complex(0.0, 3.0 * f64::consts::PI / 8.0).exp()),
62
63
                // (15, complex(0.0, 2.0 * f64::consts::PI / 3.0).exp()),
64
            ],
65
            APPROX INF,
66
            0.15,
67
            ScalingType::Renormalize(complex(1.0, 0.0)),
68
        );
69
70
        let output_dir = Path::new("output");
71
72
        // For WaveFunction
73
        // plot::plot_wavefunction(&wave_function, output_dir, "data.txt");
74
        // plot::plot_wavefunction_parts(&wave_function, output_dir, "data.txt");
75
        // plot::plot_probability(&wave_function, output_dir, "data.txt");
76
77
        // For SuperPosition
78
        plot::plot superposition(&wave function, output dir, "data.txt");
79
        // plot::plot probability super pos(&wave function, output dir, "data.txt");
80 }
```

src/airy.rs

```
/* automatically generated by rust-bindgen 0.59.2 */
#![allow(non_snake_case)]
#![allow(deref_nullptr)]
#![allow(non_camel_case_types)]

#![derive(PartialEq, Copy, Clone, Hash, Debug, Default)]
#[repr(C)]
pub struct __BindgenComplex<T> {
    pub re: T,
```

```
10
        pub im: T,
11 }
12 pub type size t = ::std::os::raw::c ulong;
13 pub type wchar t = ::std::os::raw::c int;
14 #[repr(C)]
15 #[repr(align(16))]
16 #[derive(Debug, Copy, Clone)]
17  pub struct max_align_t {
18
        pub __clang_max_align_nonce1: ::std::os::raw::c_longlong,
19
        pub __bindgen_padding_0: u64,
        pub __clang_max_align_nonce2: u128,
20
21
22
    #[test]
23
    fn bindgen_test_layout_max_align_t() {
24
        assert eq!(
25
            ::std::mem::size of::<max align t>(),
26
27
            concat!("Size_of:_", stringify!(max_align_t))
28
        );
29
        assert eq!(
30
            ::std::mem::align of::<max align t>(),
31
            16usize,
32
            concat!("Alignment_of_", stringify!(max_align_t))
33
        );
34
        assert eq!(
35
            unsafe {
                &(*(::std::ptr::null::<max_align_t>())).__clang_max_align_nonce1 as *
36
                    const _ as usize
37
            },
38
            Ousize,
39
            concat!(
40
                "Offset_of_field:_",
41
                stringify!(max_align_t),
42
                "::",
43
                stringify!( clang max align nonce1)
44
            )
45
        );
46
        assert eq!(
47
            unsafe {
48
                &(*(::std::ptr::null::<max align t>())). clang max align nonce2 as *
                    const _ as usize
49
            },
            16usize,
50
51
            concat!(
52
                "Offset_of_field:_",
53
                stringify!(max_align_t),
54
                "::",
55
                stringify!(__clang_max_align_nonce2)
56
```

```
57
    );
58 }
59 #[repr(C)]
60 #[derive(Debug, Copy, Clone)]
61
     pub struct _GoString_ {
62
         pub p: *const ::std::os::raw::c_char,
63
         pub n: isize,
64 }
65
    #[test]
66
    fn bindgen_test_layout__GoString_() {
67
         assert_eq!(
68
             ::std::mem::size_of::<_GoString_>(),
69
             16usize,
70
             concat!("Size_of:_", stringify!(_GoString_))
71
         );
72
         assert eq!(
73
             ::std::mem::align of::< GoString >(),
74
             8usize,
75
             concat!("Alignment_of_", stringify!(_GoString_))
76
         );
77
         assert eq!(
78
             unsafe { &(*(::std::ptr::null::<_GoString_>())).p as *const _ as usize },
79
             Ousize,
80
             concat!(
81
                 "Offset, of, field: ",
82
                 stringify!(_GoString_),
                 "::",
83
84
                 stringify!(p)
85
             )
86
         );
87
         assert_eq!(
88
             unsafe { &(*(::std::ptr::null::<_GoString_>())).n as *const _ as usize },
89
             8usize,
90
             concat!(
91
                 "Offset_of_field:_",
92
                 stringify!( GoString ),
93
                 "::",
94
                 stringify!(n)
95
             )
96
         );
97 }
98
    pub type GoInt8 = ::std::os::raw::c_schar;
99
     pub type GoUint8 = ::std::os::raw::c_uchar;
pub type GoInt16 = ::std::os::raw::c_short;
pub type GoUint16 = ::std::os::raw::c_ushort;
102    pub type GoInt32 = ::std::os::raw::c_int;
103 pub type GoUint32 = ::std::os::raw::c uint;
104  pub type GoInt64 = ::std::os::raw::c longlong;
pub type GoUint64 = ::std::os::raw::c_ulonglong;
```

```
106  pub type GoInt = GoInt64;
107  pub type GoUint = GoUint64;
108  pub type GoUintptr = ::std::os::raw::c_ulong;
109
    pub type GoFloat32 = f32;
110 pub type GoFloat64 = f64;
pub type GoComplex64 = __BindgenComplex<f32>;
pub type GoComplex128 = __BindgenComplex<f64>;
113 pub type _check_for_64_bit_pointer_matching_GoInt = [::std::os::raw::c_char; lusize];
114 pub type GoString = GoString ;
pub type GoMap = *mut ::std::os::raw::c_void;
pub type GoChan = *mut ::std::os::raw::c_void;
117
    #[repr(C)]
118 #[derive(Debug, Copy, Clone)]
119  pub struct GoInterface {
120
         pub t: *mut ::std::os::raw::c void,
121
         pub v: *mut ::std::os::raw::c void,
122 }
123
    #[test]
124
     fn bindgen_test_layout_GoInterface() {
125
         assert eq!(
126
             ::std::mem::size of::<GoInterface>(),
127
             16usize,
128
             concat!("Size_of:_", stringify!(GoInterface))
129
         );
130
         assert eq!(
131
             ::std::mem::align_of::<GoInterface>(),
132
133
             concat!("Alignment, of, ", stringify!(GoInterface))
134
         );
135
         assert_eq!(
             unsafe { &(*(::std::ptr::null::<GoInterface>())).t as *const _ as usize },
136
137
             Ousize,
138
             concat!(
139
                 "Offset_of_field:_",
140
                 stringify!(GoInterface),
                 "::",
141
142
                 stringify!(t)
143
             )
144
         );
145
         assert eq!(
146
             unsafe { &(*(::std::ptr::null::<GoInterface>())).v as *const _ as usize },
147
             8usize,
148
             concat!(
149
                 "Offset_of_field:_",
150
                 stringify!(GoInterface),
                 "::",
151
152
                 stringify!(v)
153
             )
154
         );
```

```
155 }
156 #[repr(C)]
157 #[derive(Debug, Copy, Clone)]
158
     pub struct GoSlice {
159
         pub data: *mut ::std::os::raw::c void,
160
         pub len: GoInt,
161
         pub cap: GoInt,
162 }
163
    #[test]
164
     fn bindgen_test_layout_GoSlice() {
165
         assert_eq!(
166
             ::std::mem::size_of::<GoSlice>(),
167
             24usize,
168
             concat!("Size_of:_", stringify!(GoSlice))
169
         );
170
         assert_eq!(
171
             ::std::mem::align of::<GoSlice>(),
172
             8usize,
173
             concat!("Alignment_of_", stringify!(GoSlice))
174
         );
175
         assert eq!(
176
             unsafe { &(*(::std::ptr::null::<GoSlice>())).data as *const _ as usize },
177
             Ousize,
178
             concat!(
179
                 "Offset_of_field:_",
180
                 stringify!(GoSlice),
                 "::",
181
182
                 stringify!(data)
183
             )
184
         );
185
         assert_eq!(
186
             unsafe { &(*(::std::ptr::null::<GoSlice>())).len as *const _ as usize },
187
             8usize,
188
             concat!(
189
                 "Offset_of_field:_",
190
                 stringify!(GoSlice),
191
                 "::",
192
                 stringify!(len)
193
             )
194
         );
195
         assert_eq!(
196
             unsafe { &(*(::std::ptr::null::<GoSlice>())).cap as *const _ as usize },
197
             16usize,
198
             concat!(
199
                 "Offset_of_field:_",
200
                 stringify!(GoSlice),
                 "::",
201
202
                 stringify!(cap)
203
```

```
204
     );
205 }
206 #[repr(C)]
207
     #[derive(Debug, Copy, Clone)]
208
     pub struct airy_ai_return {
209
         pub r0: GoFloat64,
210
         pub r1: GoFloat64,
211 }
212 #[test]
213
     fn bindgen_test_layout_airy_ai_return() {
214
         assert_eq!(
215
             ::std::mem::size_of::<airy_ai_return>(),
216
             16usize,
217
             concat!("Size_of:_", stringify!(airy_ai_return))
218
         );
219
         assert_eq!(
220
             ::std::mem::align of::<airy ai return>(),
221
222
             concat!("Alignment_of_", stringify!(airy_ai_return))
223
         );
224
         assert eq!(
225
             unsafe { &(*(::std::ptr::null::<airy_ai_return>())).r0 as *const _ as usize
                 },
226
             Ousize,
227
             concat!(
228
                 "Offset_of_field:_",
229
                 stringify!(airy_ai_return),
230
                 "::",
231
                 stringify!(r0)
232
             )
233
         );
234
         assert eq!(
235
             unsafe { &(*(::std::ptr::null::<airy ai return>())).r1 as *const as usize
                 },
236
             8usize,
237
             concat!(
238
                 "Offset_of_field:_",
239
                 stringify!(airy_ai_return),
240
                 "::",
241
                 stringify!(r1)
242
             )
243
         );
244
     }
245
     extern "C" {
246
         pub fn airy_ai(zr: GoFloat64, zi: GoFloat64) -> airy_ai_return;
247
```

src/airy_wave_func.rs

```
1 use crate::newtons method::newtons method;
 2 use crate::newtons method::*;
 3 use crate::turning points::*;
 4 use crate::wkb_wave_func::Phase;
 5 use crate::*;
 6 use num::signum;
 7 use std::sync::Arc;
 8
 9 #[allow(non snake case)]
fn Ai(x: Complex64) -> Complex64 {
        let go_return;
11
12
        unsafe {
13
            go_return = airy_ai(x.re, x.im);
14
15
        return complex(go_return.r0, go_return.r1);
16 }
17
18 #[allow(non_snake_case)]
19
    fn Bi(x: Complex64) -> Complex64 {
20
        return -complex(0.0, 1.0) * Ai(x)
21
            + 2.0 * Ai(x * complex(-0.5, 3.0_f64.sqrt() / 2.0)) * complex(3_f64.sqrt() /
                2.0, 0.5);
22 }
23
24 #[derive(Clone)]
25  pub struct AiryWaveFunction {
26
        c: Complex64,
27
        u 1: f64,
28
        pub turning_point: f64,
29
        phase: Arc<Phase>,
30
        pub ts: (f64, f64),
31
        op: fn(Complex64) -> Complex64,
32
        phase_off: f64,
33 }
34
35
    impl AiryWaveFunction {
36
        pub fn get_op(&self) -> Box<fn(Complex64) -> Complex64> {
37
            Box::new(self.op)
38
39
40
        fn get_u_1_cube_root(u_1: f64) -> f64 {
41
            signum(u_1) * u_1.abs().pow(1.0 / 3.0)
42
43
44
        pub fn new<'a>(phase: Arc<Phase>, view: (f64, f64)) -> (Vec<AiryWaveFunction>,
            TGroup) {
45
            let phase = phase;
46
            let turning_point_boundaries = turning_points::calc_ts(phase.as_ref(), view);
47
```

```
48
            let funcs: Vec<AiryWaveFunction> = turning point boundaries
49
50
                 .iter()
51
                 .map(|((t1, t2), )| {
52
                    let x 1 = newtons method(
                         &|x| (phase.potential)(x) - phase.energy,
53
54
                         (*t1 + *t2) / 2.0,
55
                         1e-7,
56
                    );
57
                    let u_1 = 2.0 * phase.mass * -derivative(phase.potential.as_ref(),
                    // let u_1 = |x| -2.0 * phase.mass * ((phase.potential)(&x) - phase.
58
                         energy) / (H BAR * H BAR * (x - x 1));
59
60
                    AiryWaveFunction {
61
                         u 1,
62
                         turning point: x 1,
63
                         phase: phase.clone(),
64
                         ts: (*t1, *t2),
65
                         op: identity,
66
                         c: 1.0.into(),
67
                         phase_off: 0.0,
68
                    }
69
                })
70
                 .collect::<Vec<AiryWaveFunction>>();
71
            return (funcs, turning_point_boundaries);
72
        }
73
74
        pub fn with_op(&self, op: fn(Complex64) -> Complex64) -> AiryWaveFunction {
75
            AiryWaveFunction {
76
                u_1: self.u_1,
77
                turning_point: self.turning_point,
78
                phase: self.phase.clone(),
79
                ts: self.ts,
80
                op,
81
                c: self.c,
82
                phase_off: self.phase_off,
83
            }
84
        }
85
86
        pub fn with_c(&self, c: Complex64) -> AiryWaveFunction {
87
            AiryWaveFunction {
88
                u_1: self.u_1,
89
                turning_point: self.turning_point,
90
                phase: self.phase.clone(),
91
                ts: self.ts,
92
                op: self.op,
93
                С,
94
                phase_off: self.phase_off,
```

```
95
             }
96
         }
97
98
         pub fn with phase off(&self, phase off: f64) -> AiryWaveFunction {
99
             AiryWaveFunction {
100
                 u 1: self.u 1,
101
                 turning_point: self.turning_point,
102
                 phase: self.phase.clone(),
103
                 ts: self.ts,
104
                 op: self.op,
105
                 c: self.c,
106
                 phase_off,
107
             }
108
         }
109
     }
110
111
     impl Func<f64, Complex64> for AiryWaveFunction {
112
         fn eval(&self, x: f64) -> Complex64 {
113
             let u_1_cube_root = Self::get_u_1_cube_root(self.u_1);
114
115
             if self.u 1 < 0.0 {</pre>
116
                  return self.c
117
                     * ((std::f64::consts::PI.sqrt() / (self.u_1).abs().pow(1.0 / 6.0))
118
                          * Ai(complex(u 1 cube root * (self.turning point - x), 0.0)))
119
                          as Complex64;
120
             } else {
121
                  return self.c
122
                     * ((std::f64::consts::PI.sqrt() / (self.u_1).abs().pow(1.0 / 6.0))
123
                          * Ai(complex(u_1_cube_root * (self.turning_point - x), 0.0)))
124
                          as Complex64;
125
             }
126
         }
127
     }
128
129
     #[cfg(test)]
130
     mod test {
131
         use super::*;
132
133
         #[test]
134
         fn airy func plot() {
135
             let output_dir = Path::new("output");
136
             std::env::set_current_dir(&output_dir).unwrap();
137
138
             let airy_ai = Function::new(|x| Ai(complex(x, 0.0)));
139
             let airy_bi = Function::new(|x| Bi(complex(x, 0.0)));
140
             let values = evaluate_function_between(&airy_ai, -10.0, 5.0, NUMBER_OF_POINTS
                 );
141
142
             let mut data_file = File::create("airy.txt").unwrap();
```

```
143
144
              let data str ai: String = values
145
                   .par iter()
146
                   .map(|p| \rightarrow String \{ format!("{}_{\sqcup}{}_{\sqcup}{}_{\parallel}n", p.x, p.y.re, p.y.im) \})
147
                   .reduce(|| String::new(), |s: String, current: String| s + &*current);
148
149
              let values_bi = evaluate_function_between(&airy_bi, -5.0, 2.0,
                   NUMBER_OF_POINTS);
150
151
              let data_str_bi: String = values_bi
152
                   .par_iter()
153
                   .map(|p| \rightarrow String \{ format!("{}_{u}{}_{u}{}_{n}, p.x, p.y.re, p.y.im) \})
154
                   .reduce(|| String::new(), |s: String, current: String| s + &*current);
155
156
              data file
157
                   .write all((data str ai + "\n\n" + &*data str bi).as ref())
158
                   .unwrap()
159
          }
160 }
```

src/check.rs

```
1
   use crate::*;
 2
 3
    pub struct SchroedingerError<'a> {
 4
        pub wave_func: &'a WaveFunction,
 5 }
 6
 7
    impl Func<f64, Complex64> for SchroedingerError<'_> {
 8
        fn eval(&self, x: f64) -> Complex64 {
            complex(-1.0 / (2.0 * self.wave_func.get_phase().mass), 0.0)
 9
10
                * Derivative {
11
                    f: &Derivative { f: self.wave func },
12
                }
                .eval(x)
13
                + ((self.wave_func.get_phase().potential)(x) - self.wave_func.get_phase()
14
                    .energy)
                    * self.wave_func.eval(x)
15
16
        }
17
```

src/energy.rs

```
1 use crate::*;
2
3 struct Integrand<'a, F: Fn(f64) -> f64 + Sync> {
4   mass: f64,
5   pot: &'a F,
6   energy: f64,
```

```
7
    }
 8
9
    impl<F: Fn(f64) -> f64 + Sync> Func<f64, f64> for Integrand<' , F> {
10
        fn eval(&self, x: f64) -> f64 {
11
            let pot = (self.pot)(x);
12
13
            if !pot.is_finite() {
14
                 return 0.0;
15
            }
16
17
            if pot < self.energy {</pre>
18
                 return (2.0 * self.mass * (self.energy - pot)).sqrt();
19
            } else {
20
                return 0.0;
21
            }
22
        }
23
    }
24
25
    struct SommerfeldCond<'a, F: Fn(f64) -> f64 + Sync> {
26
        mass: f64,
27
        pot: &'a F,
28
        view: (f64, f64),
29
    }
30
31
    impl<F: Fn(f64) -> f64 + Sync> Func<f64, f64> for SommerfeldCond<' , F> {
32
        fn eval(&self, energy: f64) -> f64 {
33
            let integrand = Integrand {
34
                mass: self.mass,
35
                pot: self.pot,
36
                energy,
37
            };
38
            let integral = integrate(
39
                evaluate function between(&integrand, self.view.0, self.view.1,
                    INTEG_STEPS),
40
                TRAPEZE PER THREAD,
41
            );
42
            return ((integral - f64::consts::PI) / f64::consts::PI) % 1.0;
43
        }
44
    }
45
46
    pub fn nth_energy<F: Fn(f64) -> f64 + Sync>(n: usize, mass: f64, pot: &F, view: (f64,
         f64)) -> f64 {
47
        const ENERGY_STEP: f64 = 10.0;
48
        const CHECKS_PER_ENERGY_STEP: usize = INTEG_STEPS;
49
        let sommerfeld_cond = SommerfeldCond { mass, pot, view };
50
51
        let mut energy = 0.0; // newtons method non smooth(\&|e| sommerfeld cond.eval(e),
            1e-7, 1e-7);
52
        let mut i = 0;
```

```
53
54
        loop {
55
            let vals = evaluate function between(
56
                &sommerfeld cond,
57
                energy,
58
                energy + ENERGY_STEP,
59
                CHECKS_PER_ENERGY_STEP,
60
            );
61
            let mut int_solutions = vals
62
                 .iter()
63
                 .zip(vals.iter().skip(1))
                 .collect::<Vec<(&Point<f64, f64>, &Point<f64, f64>)>>()
64
65
                 .par iter()
66
                 .filter(|(p1, p2)| (p1.y - p2.y).abs() > 0.5 || p1.y.signum() != p2.y.
                    signum())
67
                 .map(|ps| ps.1)
68
                 .collect::<Vec<&Point<f64, f64>>>();
69
            int_solutions.sort_by(|p1, p2| cmp_f64(&p1.x, &p2.x));
70
            if i + int_solutions.len() > n {
71
                 return int solutions[n - i].x;
72
            }
73
            energy += ENERGY_STEP - (ENERGY_STEP / (CHECKS_PER_ENERGY_STEP as f64 + 1.0))
74
            i += int solutions.len();
75
        }
76 }
```

src/integrals.rs

```
1
   use crate::*;
 2 use rayon::prelude::*;
 3
 4 #[allow(non_camel_case_types)]
 5 #[derive(Clone)]
 6 pub struct Point<T_X, T_Y> {
 7
        pub x: T_X,
 8
        pub y: T_Y,
 9
    }
10
11
    pub fn trapezoidal_approx<X, Y>(start: &Point<X, Y>, end: &Point<X, Y>) -> Y
12
13
        X: std::ops::Sub<Output = X> + Copy,
14
        Y: std::ops::Add<Output = Y>
15
            + std::ops::Mul<Output = Y>
16
            + std::ops::Div<f64, Output = Y>
17
            + Copy
18
            + From<X>,
19
20
        return Y::from(end.x - start.x) * (start.y + end.y) / 2.0_f64;
```

```
21
    }
22
23
    pub fn index to range<T>(x: T, in min: T, in max: T, out min: T, out max: T) -> T
24
    where
        T: Copy
25
26
            + std::ops::Sub<Output = T>
27
            + std::ops::Mul<Output = T>
28
            + std::ops::Div<Output = T>
29
            + std::ops::Add<Output = T>,
30
   {
31
        return (x - in_min) * (out_max - out_min) / (in_max - in_min) + out_min;
32
    }
33
34
    pub fn integrate<</pre>
35
        X: Sync + std::ops::Add<Output = X> + std::ops::Sub<Output = X> + Copy,
36
        Y: Default
37
            + Sync
38
            + std::ops::AddAssign
39
            + std::ops::Div<f64, Output = Y>
40
            + std::ops::Mul<Output = Y>
41
            + std::ops::Add<Output = Y>
42
            + Send
43
            + std::iter::Sum<Y>
44
            + Copy
45
            + From<X>,
46
    >(
47
        points: Vec<Point<X, Y>>,
48
        batch_size: usize,
49
    ) -> Y {
50
        if points.len() < 2 {</pre>
51
             return Y::default();
52
53
54
        let batches: Vec<&[Point<X, Y>]> = points.chunks(batch_size).collect();
55
56
        let parallel: Y = batches
57
            .par_iter()
58
             .map(|batch| {
59
                let mut sum = Y::default();
60
                for i in 0..(batch.len() - 1) {
61
                    sum += trapezoidal_approx(&batch[i], &batch[i + 1]);
62
                }
63
                 return sum;
64
            })
65
            .sum();
66
67
        let mut rest = Y::default();
68
69
        for i in 0..batches.len() - 1 {
```

```
70
             rest += trapezoidal_approx(&batches[i][batches[i].len() - 1], &batches[i +
                 1][0]);
71
         }
72
73
         return parallel + rest;
74
75
76
     pub fn evaluate_function_between<X, Y>(f: &dyn Func<X, Y>, a: X, b: X, n: usize) ->
         Vec<Point<X, Y>>
77
     where
78
         X: Copy
79
             + Send
80
             + Sync
81
             + std::cmp::PartialEq
82
             + From<f64>
83
             + std::ops::Add<Output = X>
84
             + std::ops::Sub<Output = X>
85
             + std::ops::Mul<Output = X>
86
             + std::ops::Div<Output = X>,
87
         Y: Send + Sync,
88
         if a == b {
89
90
             return vec![];
91
92
93
         (0..n)
94
             .into_par_iter()
95
             .map(|i| {
96
                 index_to_range(
97
                     X::from(i as f64),
98
                     X::from(0.0_f64),
99
                     X::from((n - 1) as f64),
100
                     a,
101
                     b,
102
                 )
103
             })
104
             .map(|x: X| Point { x, y: f.eval(x) })
105
             .collect()
106
107
108
     #[cfg(test)]
109
     mod test {
110
         use super::*;
111
112
         fn square(x: f64) -> Complex64 {
113
             return complex(x * x, 0.0);
114
115
116
         fn square_integral(a: f64, b: f64) -> Complex64 {
```

```
117
             return complex(b * b * b / 3.0 - a * a * a / 3.0, 0.0);
118
         }
119
120
         #[tokio::test(flavor = "multi thread")]
121
         async fn integral_of_square() {
122
             let square_func: Function<f64, Complex64> = Function::new(square);
123
             for i in 0..100 {
124
                 for j in 0..10 {
125
                     let a = f64::from(i - 50) / 12.3;
126
                     let b = f64::from(j - 50) / 12.3;
127
128
                     if i == j {
129
                         assert eq!(
130
                             integrate(
131
                                  evaluate function between(&square func, a, b, INTEG STEPS
132
                                  TRAPEZE PER THREAD,
133
                             ),
134
                              complex(0.0, 0.0)
135
                         );
136
                         continue;
137
                     }
138
139
                     let epsilon = 0.00001;
140
                     assert!(complex compare(
141
                         integrate(
142
                             evaluate_function_between(&square_func, a, b, INTEG_STEPS),
143
                              TRAPEZE PER THREAD,
144
145
                         square_integral(a, b),
146
                         epsilon,
147
                     ));
148
                 }
149
             }
150
         }
151
152
         #[test]
153
         fn evaluate square func between() {
154
             let square func: Function<f64, Complex64> = Function::new(square);
155
             let actual = evaluate function between(&square func, -2.0, 2.0, 5);
156
             let expected = vec![
                 Point {
157
                     x: -2.0,
158
159
                     y: complex(4.0, 0.0),
160
                 },
161
                 Point {
162
                     x: -1.0,
163
                     y: complex(1.0, 0.0),
164
```

```
165
                 Point {
166
                     x: 0.0,
167
                     y: complex(0.0, 0.0),
168
                 },
169
                 Point {
170
                     x: 1.0,
171
                     y: complex(1.0, 0.0),
172
                 },
173
                 Point {
174
                     x: 2.0,
175
                     y: complex(4.0, 0.0),
176
                 },
177
             ];
178
179
             for (a, e) in actual.iter().zip(expected) {
180
                 assert eq!(a.x, e.x);
181
                 assert_eq!(a.y, e.y);
182
             }
183
         }
184
185
         fn sinusoidal_exp_complex(x: f64) -> Complex64 {
186
             return complex(x, x).exp();
187
188
189
         fn sinusoidal exp complex integral(a: f64, b: f64) -> Complex64 {
190
             // (-1/2 + i/2) (e^((1 + i) a) - e^((1 + i) b))
191
             return complex(-0.5, 0.5) * (complex(a, a).exp() - complex(b, b).exp());
192
193
194
         #[tokio::test(flavor = "multi_thread")]
195
         async fn integral_of_sinusoidal_exp() {
196
             let sinusoidal exp complex: Function<f64, Complex64> =
197
                 Function::new(sinusoidal_exp_complex);
198
             for i in 0..10 {
199
                 for j in 0..10 {
200
                     let a = f64::from(i - 50) / 12.3;
                     let b = f64::from(j - 50) / 12.3;
201
202
203
                     if i == j {
204
                         assert eq!(
205
                             integrate(
206
                                  evaluate_function_between(&sinusoidal_exp_complex, a, b,
                                      INTEG_STEPS),
207
                                  TRAPEZE_PER_THREAD,
208
                              ),
209
                              complex(0.0, 0.0)
210
                          );
211
                          continue;
212
```

```
213
                      let epsilon = 0.0001;
                     assert!(complex_compare(
214
215
                          integrate(
216
                              evaluate function between(&sinusoidal exp complex, a, b,
                                  INTEG STEPS),
217
                              TRAPEZE PER THREAD,
218
                          ),
219
                          sinusoidal_exp_complex_integral(a, b),
220
221
                     ));
222
                 }
223
             }
224
         }
225
     }
```

src/main.rs

```
1 #![allow(dead_code)]
 2
 3 mod airy;
 4 mod airy_wave_func;
 5 mod check;
 6 mod energy;
 7 mod integrals;
 8 mod newtons_method;
 9 mod plot;
10 mod potentials;
11 mod tui;
12 mod turning_points;
13 mod utils;
14 mod wave_function_builder;
15 mod wkb_wave_func;
16
17 use crate::airy::airy_ai;
18 use crate::airy_wave_func::AiryWaveFunction;
19 use crate::integrals::*;
20 use crate::newtons_method::derivative;
21 use crate::utils::Func;
22 use crate::utils::*;
23 use crate::wave_function_builder::*;
24 use crate::wkb wave func::WkbWaveFunction;
use num::complex::Complex64;
26 use num::pow::Pow;
27 use rayon::iter::*;
28 use std::f64;
29 use std::fs::File;
30 use std::io::Write;
31 use std::path::Path;
32 use std::sync::Arc;
```

```
33
34 const INTEG STEPS: usize = 64000;
35
    const TRAPEZE PER THREAD: usize = 1000;
36
    const NUMBER OF POINTS: usize = 100000;
37
38
    const AIRY TRANSITION FRACTION: f64 = 0.5;
39
    const ENABLE_AIRY_JOINTS: bool = true;
40
41
    const VALIDITY_LL_FACTOR: f64 = 3.5;
42
    const APPROX_INF: (f64, f64) = (-200.0, 200.0);
43
44
45
    fn main() {
46
        // let wave_function = wave_function_builder::WaveFunction::new(
47
               &potentials::square,
48
               1.0,
        //
49
        //
               17,
               APPROX_INF,
50
        //
        //
51
               0.15,
52
        //
               ScalingType::Renormalize(1.0.into()),
53
        // );
54
55
        let wave_function = wave_function_builder::SuperPosition::new(
56
            &potentials::mexican hat,
57
            1.0,
58
            1&
59
                (15, 1.0.into()),
                (16, complex(0.0, 1.0 * f64::consts::PI / 8.0).exp()),
60
61
                (17, complex(0.0, 2.0 * f64::consts::PI / 8.0).exp()),
62
                (18, complex(0.0, 3.0 * f64::consts::PI / 8.0).exp()),
63
                // (15, complex(0.0, 2.0 * f64::consts::PI / 3.0).exp()),
64
            ],
            APPROX_INF,
65
66
            0.15,
67
            ScalingType::Renormalize(complex(1.0, 0.0)),
68
        );
69
70
        let output dir = Path::new("output");
71
72
        // For WaveFunction
73
        // plot::plot_wavefunction(&wave_function, output_dir, "data.txt");
74
        // plot::plot_wavefunction_parts(&wave_function, output_dir, "data.txt");
75
        // plot::plot_probability(&wave_function, output_dir, "data.txt");
76
        // For SuperPosition
77
78
        plot::plot superposition(&wave function, output dir, "data.txt");
79
        // plot::plot probability super pos(&wave function, output dir, "data.txt");
80 }
```

src/newtons_method.rs

```
1 use crate::integrals::*;
 2 use crate::utils::cmp_f64;
 3 use num::Float;
 4 use rayon::prelude::*;
 5 use std::cmp::Ordering;
 6 use std::fmt::Debug;
 7 use std::ops::*;
 8
   use std::sync::Arc;
 9
10 #[derive(Default, Debug)]
11
    pub struct Vec2 {
12
        x: f64,
        y: f64,
13
14
    }
15
16
    impl Vec2 {
17
        pub fn dot(&self, other: &Vec2) -> f64 {
18
            return self.x * other.x + self.y + other.y;
19
20
21
        pub fn mag(&self) -> f64 {
22
            return (self.x.powi(2) * self.y.powi(2)).sqrt();
23
24
25
        pub fn pseudo inverse(&self) -> CoVec2 {
26
            CoVec2(self.x, self.y) * (1.0 / (self.x.powi(2) + self.y.powi(2)))
27
28
    }
29
30
    impl Add for Vec2 {
31
        type Output = Vec2;
32
33
        fn add(self, other: Self) -> Self::Output {
34
            Vec2 {
35
                x: self.x + other.x,
36
                y: self.y + other.y,
37
38
        }
39
    }
40
41
    impl Sub for Vec2 {
42
        type Output = Vec2;
43
44
        fn sub(self, other: Self) -> Self::Output {
45
            Vec2 {
46
                x: self.x - other.x,
```

```
47
                y: self.x - other.y,
48
            }
49
        }
50
51
52
    impl Mul<f64> for Vec2 {
53
        type Output = Vec2;
54
55
        fn mul(self, s: f64) -> Self::Output {
56
            Vec2 {
57
                x: self.x * s,
58
                y: self.y * s,
59
            }
60
        }
61
    }
62
63
    #[derive(Debug)]
64
   pub struct CoVec2(f64, f64);
65
    impl Add for CoVec2 {
66
67
        type Output = CoVec2;
68
69
        fn add(self, other: Self) -> Self::Output {
70
            CoVec2(self.0 + other.0, self.1 + other.1)
71
72
    }
73
74
    impl Sub for CoVec2 {
        type Output = CoVec2;
75
76
77
        fn sub(self, other: Self) -> Self::Output {
78
            CoVec2(self.0 - other.0, self.1 - other.1)
79
        }
80
81
82
    impl Mul<Vec2> for CoVec2 {
83
        type Output = f64;
84
85
        fn mul(self, vec: Vec2) -> Self::Output {
86
            return self.0 * vec.x + self.1 * vec.y;
87
88
    }
89
90
    impl Mul<f64> for CoVec2 {
91
        type Output = CoVec2;
92
93
        fn mul(self, s: f64) -> Self::Output {
94
            CoVec2(self.0 * s, self.1 * s)
95
```

```
96 }
97
98 fn gradient<F>(f: F, x: f64) -> Vec2
99
     where
100
         F: Fn(f64) -> Vec2,
101
102
         let x_{component} = |x| f(x).x;
103
         let y_component = |x| f(x).y;
104
         return Vec2 {
105
             x: derivative(&x_component, x),
106
             y: derivative(&y_component, x),
107
         };
108
     }
109
110 // pub fn derivative<F, R>(f: &F, x: f64) -> R
111
    // where
112 // F: Fn(f64) \rightarrow R + ?Sized,
113
     //
          R: Sub<R, Output = R> + Div<f64, Output = R>,
114
     // {
115
     //
            let epsilon = f64::epsilon().sqrt();
116
            (f(x + epsilon / 2.0) - f(x - epsilon / 2.0)) / epsilon
     //
117
    // }
118
119
     pub fn derivative<F, R>(func: &F, x: f64) -> R
120
     where
121
         F: Fn(f64) \rightarrow R + ?Sized,
         R: Sub<R, Output = R> + Div<f64, Output = R> + Mul<f64, Output = R> + Add<R,
122
             Output = R>,
123
     {
124
         let dx = f64::epsilon().sqrt();
125
         let dx1 = dx;
126
         let dx2 = dx1 * 2.0;
127
         let dx3 = dx1 * 3.0;
128
129
         let m1 = (func(x + dx1) - func(x - dx1)) / 2.0;
130
         let m2 = (func(x + dx2) - func(x - dx2)) / 4.0;
131
         let m3 = (func(x + dx3) - func(x - dx3)) / 6.0;
132
133
         let fifteen m1 = m1 * 15.0;
134
         let six m2 = m2 * 6.0;
135
         let ten_dx1 = dx1 * 10.0;
136
137
         return ((fifteen_m1 - six_m2) + m3) / ten_dx1;
138
     }
139
140 pub fn newtons_method<F>(f: &F, mut guess: f64, precision: f64) -> f64
141
         F: Fn(f64) -> f64,
142
143 {
```

```
144
145
             let step = f(guess) / derivative(f, guess);
146
             if step.abs() < precision {</pre>
147
                  return guess;
148
             } else {
149
                 guess -= step;
150
             }
151
         }
152
     }
153
     pub fn newtons_method_2d<F>(f: &F, mut guess: f64, precision: f64) -> f64
154
155
     where
156
         F: Fn(f64) -> Vec2,
157
         F::Output: Debug,
158
     {
159
         loop {
160
             let jacobian = gradient(f, guess);
161
             let step: f64 = jacobian.pseudo_inverse() * f(guess);
162
             if step.abs() < precision {</pre>
163
                  return guess;
164
             } else {
165
                 guess -= step;
166
             }
167
         }
168
169
170
     pub fn newtons_method_max_iters<F>(
171
         f: &F,
172
         mut guess: f64,
173
         precision: f64,
174
         max_iters: usize,
175
    ) -> Option<f64>
176
     where
177
         F: Fn(f64) -> f64,
178
179
         for _ in 0..max_iters {
180
             let step = f(guess) / derivative(f, guess);
181
             if step.abs() < precision {</pre>
182
                  return Some(guess);
183
             } else {
184
                 guess -= step;
185
             }
186
187
         None
188
189
     fn sigmoid(x: f64) -> f64 {
190
191
         1.0 / (1.0 + (-x).exp())
192 }
```

```
193
194
     fn check sign(initial: f64, new: f64) -> bool {
195
         if initial == new {
196
              return false;
197
198
         return (initial <= -0.0 && new >= 0.0) || (initial >= 0.0 && new <= 0.0);
199
200
201
     pub fn bisection_search_sign_change<F>(f: &F, initial_guess: f64, step: f64) -> (f64,
          f64)
202
     where
203
         F: Fn(f64) -> f64 + ?Sized,
204
     {
205
         let mut result = initial guess;
206
         while !check sign(f(initial guess), f(result)) {
207
             result += step
208
209
         return (result - step, result);
210
211
     fn regula_falsi_c<F>(f: &F, a: f64, b: f64) -> f64
212
     where
213
214
         F: Fn(f64) \rightarrow f64 + ?Sized,
215
     {
216
         return (a * f(b) - b * f(a)) / (f(b) - f(a));
217
     }
218
219
     pub fn regula falsi method<F>(f: &F, mut a: f64, mut b: f64, precision: f64) -> f64
220
     where
221
         F: Fn(f64) -> f64 + ?Sized,
222
     {
223
         if a > b {
224
             let temp = a;
225
             a = b;
226
             b = temp;
227
228
229
         let mut c = regula_falsi_c(f, a, b);
230
         while f64::abs(f(c)) > precision {
231
             b = regula falsi c(f, a, b);
232
             a = regula_falsi_c(f, a, b);
233
             c = regula_falsi_c(f, a, b);
234
235
         return c;
236
237
238
     pub fn regula falsi bisection<F>(f: &F, guess: f64, bisection step: f64, precision:
         f64) -> f64
239
     where
```

```
240
         F: Fn(f64) -> f64 + ?Sized,
241
     {
242
         let (a, b) = bisection search sign change(f, guess, bisection step);
243
         return regula falsi method(f, a, b, precision);
244
245
246
     #[derive(Clone)]
247
     pub struct NewtonsMethodFindNewZero<F>
248
         F: Fn(f64) -> f64 + ?Sized + Clone,
249
250 {
251
         f: Arc<F>,
252
         precision: f64,
253
         max iters: usize,
254
         previous zeros: Vec<(i32, f64)>,
255
     }
256
257
     impl<F: Fn(f64) -> f64 + ?Sized + Clone> NewtonsMethodFindNewZero<F> {
258
         pub(crate) fn new(f: Arc<F>, precision: f64, max_iters: usize) ->
             NewtonsMethodFindNewZero<F> {
259
             NewtonsMethodFindNewZero {
260
                 f,
261
                 precision,
262
                 max iters,
263
                 previous_zeros: vec![],
264
             }
265
         }
266
267
         pub(crate) fn modified_func(&self, x: f64) -> f64 {
268
             let divisor = self
269
                  .previous_zeros
270
                  .iter()
271
                  .fold(1.0, |acc, (n, z)| acc * (x - z).powi(*n));
272
             let divisor = if divisor == 0.0 {
273
                 divisor + self.precision
274
             } else {
275
                 divisor
276
             };
277
             (self.f)(x) / divisor
278
279
280
         pub(crate) fn next_zero(&mut self, guess: f64) -> Option<f64> {
281
             let zero = newtons_method_max_iters(
282
                 &|x| self.modified_func(x),
283
                 guess,
284
                 self.precision,
285
                 self.max iters,
286
             );
287
```

```
288
             if let Some(z) = zero {
289
                 // to avoid hitting maxima and minima twice
290
                 if derivative(\&|x| self.modified func(x), z).abs() < self.precision {
291
                      self.previous zeros.push((2, z));
292
                 } else {
293
                      self.previous_zeros.push((1, z));
294
                 }
295
             }
296
297
             return zero;
298
         }
299
300
         pub(crate) fn get previous zeros(&self) -> Vec<f64> {
301
             self.previous zeros
302
                  .iter()
303
                  .map(|( , z)| *z)
304
                  .collect::<Vec<f64>>()
305
         }
306
307
308
     pub fn make guess<F>(f: &F, (start, end): (f64, f64), n: usize) -> Option<f64>
309
     where
310
         F: Fn(f64) \rightarrow f64 + Sync,
311
     {
312
         let sort_func = |(_, y1): &(f64, f64), (_, y2): &(f64, f64)| -> Ordering {
             cmp_f64(&y1, &y2) };
313
         let mut points: Vec<(f64, f64)>=(0..n)
314
              .into par iter()
315
              .map(|i| index_to_range(i as f64, 0.0, n as f64, start, end))
316
              .map(move |x| {
317
                 let der = derivative(f, x);
318
                  (x, f(x) / (-(-der * der).exp() + 1.0))
319
             })
320
             .map(|(x, y)| (x, y.abs()))
321
             .collect();
322
         points.sort by(sort func);
323
         points.get(0).map(|point| point.0)
324
325
326
     pub fn newtons method find new zero<F>(
327
         f: &F,
328
         guess: f64,
329
         precision: f64,
330
         max_iters: usize,
331
         known_zeros: &Vec<f64>,
332 ) -> Option<f64>
333
     where
334
         F: Fn(f64) -> f64,
335
```

```
336
         let f modified = |x| f(x) / known zeros.iter().fold(0.0, |acc, &z| acc * (x - z))
337
         newtons method max iters(&f modified, guess, precision, max iters)
338
339
340
     #[cfg(test)]
341
     mod test {
342
         use super::*;
343
         use crate::utils::cmp_f64;
344
345
         fn float_compare(expect: f64, actual: f64, epsilon: f64) -> bool {
346
             let average = (expect.abs() + actual.abs()) / 2.0;
347
             if average != 0.0 {
348
                  (expect - actual).abs() / average < epsilon</pre>
349
             } else {
350
                  (expect - actual).abs() < epsilon</pre>
351
             }
352
         }
353
354
         #[test]
355
         fn derivative_square_test() {
356
             let square = |x| x * x;
357
             let actual = |x| 2.0 * x;
358
359
             for i in 0..100 {
360
                 let x = index_to_range(i as f64, 0.0, 100.0, -20.0, 20.0);
361
                 assert!(float_compare(derivative(&square, x), actual(x), 1e-4));
362
             }
363
         }
364
365
         #[test]
366
         fn derivative_exp_test() {
367
             let exp = |x: f64| x.exp();
368
369
             for i in 0..100 {
370
                  let x = index to range(i as f64, 0.0, 100.0, -20.0, 20.0);
371
                 assert!(float_compare(derivative(&exp, x), exp(x), 1e-4));
372
             }
373
         }
374
375
         #[test]
376
         fn newtons_method_square() {
377
             for i in 0..100 {
378
                 let zero = index_to_range(i as f64, 0.0, 100.0, 0.1, 10.0);
379
                 let func = |x| x * x - zero * zero;
380
                 assert!(float_compare(
381
                      newtons method(&func, 100.0, 1e-7),
382
                      zero,
383
                      1e-4,
```

```
384
                 ));
385
                 assert!(float compare(
386
                     newtons method(&func, -100.0, 1e-7),
387
                     -zero,
388
                     1e-4,
389
                 ));
390
             }
391
         }
392
393
         #[test]
394
         fn newtons_method_cube() {
395
             for i in 0..100 {
396
                 let zero = index to range(i as f64, 0.0, 100.0, 0.1, 10.0);
397
                 let func = |x| (x - zero) * (x + zero) * (x - zero / 2.0);
398
                 assert!(float compare(
399
                     newtons method(&func, 100.0, 1e-7),
400
                     zero,
401
                     1e-4,
402
                 ));
403
                 assert!(float compare(
404
                     newtons method(&func, -100.0, 1e-7),
405
                     -zero,
406
                     1e-4,
407
                 ));
408
                 assert!(float compare(
409
                     newtons_method(&func, 0.0, 1e-7),
410
                     zero / 2.0,
411
                     1e-4,
412
                 ));
413
             }
414
         }
415
416
         #[test]
417
         fn newtons_method_find_next_polynomial() {
             for i in 0..10 {
418
419
                  for j in 0..10 {
420
                      for k in 0..10 {
421
                          let a = index_to_range(i as f64, 0.0, 10.0, -10.0, 10.0);
422
                          let b = index to range(j as f64, 0.0, 10.0, -100.0, 0.0);
423
                          let c = index to range(k as f64, 0.0, 10.0, -1.0, 20.0);
424
                          let test_func = |x: f64| (x - a) * (x - b) * (x - c);
425
426
                          for _guess in [a, b, c] {
427
                              let mut finder =
428
                                  NewtonsMethodFindNewZero::new(Arc::new(test_func), 1e-15,
                                       10000000);
429
430
                              finder.next zero(1.0);
431
                              finder.next_zero(1.0);
```

```
432
                                                                             finder.next zero(1.0);
433
434
                                                                             let mut zeros expected = [a, b, c];
435
                                                                             let mut zeros actual = finder.get previous zeros().clone();
436
437
                                                                             zeros_expected.sort_by(cmp_f64);
438
                                                                             zeros_actual.sort_by(cmp_f64);
439
440
                                                                            assert_eq!(zeros_actual.len(), 3);
441
442
                                                                             for (expected, actual) in zeros_expected.iter().zip(
                                                                                        zeros_actual.iter()) {
443
                                                                                        assert!((*expected - *actual).abs() < 1e-10);</pre>
444
                                                                            }
445
                                                                  }
446
                                                       }
447
                                           }
448
                                  }
449
                        }
450
451
                        #[test]
452
                        fn newtons_method_find_next_test() {
453
                                  let interval = (-10.0, 10.0);
454
455
                                  let test func = |x: f64| 5.0 * (3.0 * x + 1.0).abs() - (1.5 * x.powi(2) + x - 1.0).abs() - (1.5 * x.
                                                50.0).powi(2);
456
457
                                   let mut finder = NewtonsMethodFindNewZero::new(Arc::new(test func), 1e-11,
                                             100000000);
458
459
                                   for _i in 0..4 {
460
                                             let guess = make_guess(&|x| finder.modified_func(x), interval, 1000);
461
                                             finder.next_zero(guess.unwrap());
462
                                  }
463
464
                                   let mut zeros = finder.get previous zeros().clone();
465
                                   zeros.sort by(cmp f64);
466
                                   let expected = [-6.65276132415, -5.58024707627, 4.91358040961,
                                             5.98609465748];
467
468
                                   println!("zeros: [:#?]", zeros);
469
470
                                   assert_eq!(zeros.len(), expected.len());
471
472
                                   for (expected, actual) in expected.iter().zip(zeros.iter()) {
473
                                             assert!((*expected - *actual).abs() < 1e-10);</pre>
474
                                  }
475
                        }
476
```

```
477
         #[test]
478
         fn regula falsi bisection test() {
479
             let func = |x: f64| x * (x - 2.0) * (x + 2.0);
480
481
             let actual = regula falsi bisection(&func, -1e-3, -1e-3, 1e-5);
482
             let expected = -2.0;
483
484
             println!("expected:_{{}},_actual__{{}}", expected, actual);
485
             assert!(float_compare(expected, actual, 1e-3));
486
         }
487
     }
```

src/plot.rs

```
use crate::*;
 1
 2
   use std::fmt;
 3
 4
    pub fn to_gnuplot_string_complex<X>(values: Vec<Point<X, Complex64>>) -> String
 5
    where
 6
        X: fmt::Display + Send + Sync,
 7
    {
 8
         values
 9
             .par iter()
10
             .map(|p| \rightarrow String \{ format!("{}_{|}^{}_{|}^{} n", p.x, p.y.re, p.y.im) \})
11
             .reduce(|| String::new(), |s: String, current: String| s + &*current)
12
13
14
    pub fn to_gnuplot_string<X, Y>(values: Vec<Point<X, Y>>) -> String
15
16
        X: fmt::Display + Send + Sync,
17
        Y: fmt::Display + Send + Sync,
18
19
        values
20
             .par_iter()
21
             .map(|p| \rightarrow String \{ format!("{}_{\downarrow}{}_{\downarrow}n", p.x, p.y) \})
22
             .reduce(|| String::new(), |s: String, current: String| s + &*current)
23
    }
24
25
    pub fn plot_wavefunction_parts(wave_function: &WaveFunction, output_dir: &Path,
         output_file: &str) {
26
         std::env::set current dir(&output dir).unwrap();
27
28
         let wkb values = wave function
29
             .get wkb ranges in view()
30
             .iter()
             .map(|range| evaluate_function_between(wave_function, range.0, range.1,
31
                 NUMBER OF POINTS))
32
             .collect::<Vec<Vec<Point<f64, Complex64>>>>();
33
```

```
34
        let airy values = wave function
35
            .get airy ranges()
36
            .iter()
37
            .map(|range| {
38
                evaluate function between(
39
                    wave function,
40
                    f64::max(wave_function.get_view().0, range.0),
41
                    f64::min(wave_function.get_view().1, range.1),
42
                    NUMBER OF POINTS,
43
                )
44
            })
45
            .collect::<Vec<Vec<Point<f64, Complex64>>>>();
46
47
        let wkb values str = wkb values
48
            .par iter()
49
            .map(|values| to gnuplot string complex(values.to vec()))
50
51
                 || String::new(),
52
                 |s: String, current: String| s + "\n\n" + &*current,
53
            );
54
55
        let airy_values_str = airy_values
56
            .par iter()
57
            .map(|values| to gnuplot string complex(values.to vec()))
58
            .reduce(
59
                 || String::new(),
60
                 |s: String, current: String| s + "\n\n" + &*current,
61
            );
62
63
        let mut data_full = File::create(output_file).unwrap();
64
        data_full.write_all(wkb_values_str.as_ref()).unwrap();
65
        data_full.write_all("\n\n".as_bytes()).unwrap();
66
        data_full.write_all(airy_values_str.as_ref()).unwrap();
67
68
        let mut plot 3d file = File::create("plot 3d.gnuplot").unwrap();
69
70
        let wkb_3d_cmd = (1..=wkb_values.len())
71
            .into iter()
72
            .map(|n| {
73
                 format!(
74
                     "\"{}\"_u_1:2:3_i_{}_t_\"WKB_{}\"_w_l",
75
                    output_file,
76
                    n - 1,
77
                    n
78
                )
79
            })
            .collect::<Vec<String>>()
80
81
            .join(",");
82
```

```
83
          let airy 3d cmd = (1..=airy values.len())
84
              .into iter()
85
              .map(|n| {
86
                  format!(
87
                       "\"{}\"_u_1:2:3_i_{}_t_\"Airy_{}\"_w_l",
88
                      output file,
89
                      n + wkb_values.len() - 1,
90
91
                  )
92
              })
93
              .collect::<Vec<String>>()
              .join(",<sub>"</sub>);
94
95
          let plot 3d cmd: String = "splot,".to string() + &wkb 3d cmd + ",,," + &
              airy 3d cmd;
96
          plot 3d file.write all(plot 3d cmd.as ref()).unwrap();
97
98
          let mut plot file = File::create("plot.gnuplot").unwrap();
99
          let wkb_cmd = (1..=wkb_values.len())
100
              .into iter()
101
              .map(|n| {
102
                  format!(
103
                       \label{eq:continuity} $$ "\"\{}\"u_1:2_i_{}_t_\"Re(WKB_{},)\"_w_l",
104
                      output_file,
105
                      n - 1,
106
                      n
107
                  )
108
              })
109
              .collect::<Vec<String>>()
110
              .join(",<sub>"</sub>);
111
112
          let airy_cmd = (1..=airy_values.len())
113
              .into iter()
114
              .map(|n| {
115
                  format!(
116
                       "\"{}\"_u_1:2_i_{}_t_\"Re(Airy_{})\"_w_l",
117
                      output file,
118
                      n + wkb values.len() - 1,
119
                      n
120
                  )
121
              })
122
              .collect::<Vec<String>>()
123
              .join(",<sub>"</sub>);
          let plot_cmd: String = "plot_".to_string() + &wkb_cmd + ",_" + &airy_cmd;
124
125
126
          plot_file.write_all(plot_cmd.as_ref()).unwrap();
127
128
          let mut plot imag file = File::create("plot im.gnuplot").unwrap();
129
130
          let wkb_im_cmd = (1..=wkb_values.len())
```

```
131
             .into iter()
132
             .map(|n| {
133
                 format!(
134
                      "\"{}\"_u_1:3_i_{}_t_\"Im(WKB_{})\"_w_l",
135
                     output_file,
136
                     n - 1,
137
                     n
138
                 )
139
             })
140
             .collect::<Vec<String>>()
141
             .join(",");
142
143
         let airy im cmd = (1..=airy values.len())
144
             .into iter()
145
             .map(|n| {
146
                 format!(
147
                     "\"{}\"_u_1:3_i_{}_t_\"Im(Airy_{})\"_w_l",
148
                     output_file,
149
                     n + wkb values.len() - 1,
150
                     n
151
                 )
152
             })
153
             .collect::<Vec<String>>()
154
             .join(",");
155
         let plot_imag_cmd: String = "plot_".to_string() + &wkb_im_cmd + ",_" + &
             airy_im_cmd;
156
157
         plot imag file.write all(plot imag cmd.as ref()).unwrap();
158
     }
159
160
     pub fn plot_complex_function(
161
         func: &dyn Func<f64, Complex64>,
162
         view: (f64, f64),
163
         title: &str,
164
         output dir: &Path,
165
         output file: &str,
166
     ) {
167
         std::env::set current dir(&output dir).unwrap();
168
         let values = evaluate function between(func, view.0, view.1, NUMBER OF POINTS);
169
170
         let values_str = to_gnuplot_string_complex(values);
171
172
         let mut data_file = File::create(output_file).unwrap();
173
174
         data_file.write_all(values_str.as_bytes()).unwrap();
175
         let mut plot 3d file = File::create("plot 3d.gnuplot").unwrap();
176
177
         plot_3d_file
178
              .write_all(format!("splot_\"{}\"_uu_1:2:3_t_\"{}\"_uw_l", output_file, title).
```

```
as bytes())
179
              .unwrap();
180
181
         let mut plot file = File::create("plot.gnuplot").unwrap();
182
         plot file
183
              .write\_all(format!("plot\_\"{}\"\_u\_1:2\_t\_\"Re({})\"\_w\_l", output\_file, title).
                  as_bytes())
184
              .unwrap();
185
186
         let mut plot_im_file = File::create("plot_im.gnuplot").unwrap();
187
         plot_im_file
188
              .write\_all(format!("plot\_\"{}\"\_u\_1:3\_t\_\"Im({})\"\_w\_l", \ output\_file, \ title).
                  as bytes())
189
              .unwrap();
190
     }
191
192
     pub fn plot wavefunction(wave function: &WaveFunction, output dir: &Path, output file
         : &str) {
193
         plot_complex_function(
194
             wave function,
             wave function.get_view(),
195
196
             "Psi",
197
             output_dir,
198
              output file,
199
         );
200
     }
201
202
     pub fn plot superposition(wave function: &SuperPosition, output dir: &Path,
         output_file: &str) {
203
         plot_complex_function(
204
             wave_function,
205
             wave_function.get_view(),
206
              "Psi",
207
             output_dir,
208
              output file,
209
         );
210
     }
211
212
     pub fn plot probability(wave function: &WaveFunction, output dir: &Path, output file:
          &str) {
213
         std::env::set_current_dir(&output_dir).unwrap();
214
         let values = evaluate_function_between(
215
             wave_function,
216
             wave_function.get_view().0,
217
             wave_function.get_view().1,
218
             NUMBER OF POINTS,
219
220
         .par iter()
221
         .map(|p| Point {
```

```
222
             x: p.x,
223
             y: p.y.norm_sqr(),
224
         })
225
         .collect();
226
227
         let values_str = to_gnuplot_string(values);
228
229
         let mut data_file = File::create(output_file).unwrap();
230
231
         data_file.write_all(values_str.as_bytes()).unwrap();
232
233
         let mut plot_file = File::create("plot.gnuplot").unwrap();
234
         plot file
235
              .write\_all(format!("plot_\""{}\"_\uu_\1:2_\ut_\\"|Psi|^2\\"_\uw_\ull", output_file).\\
                  as bytes())
236
              .unwrap();
237
     }
238
239
     pub fn plot_probability_super_pos(
240
         wave function: &SuperPosition,
241
         output dir: &Path,
242
         output_file: &str,
243
     ) {
244
         std::env::set current dir(&output dir).unwrap();
245
         let values = evaluate function between(
246
             wave_function,
247
             wave_function.get_view().0,
248
             wave function.get view().1,
249
             NUMBER OF POINTS,
250
251
         .par_iter()
252
         .map(|p| Point {
253
             x: p.x,
254
             y: p.y.norm_sqr(),
255
         })
256
         .collect();
257
258
         let values str = to gnuplot string(values);
259
260
         let mut data file = File::create(output file).unwrap();
261
262
         data_file.write_all(values_str.as_bytes()).unwrap();
263
264
         let mut plot_file = File::create("plot.gnuplot").unwrap();
265
         plot_file
266
              .write\_all(format!("plot\_\"{}\"\_u\_1:2\_t\_\"|Psi|^2\"\_w\_l", output\_file).
                  as bytes())
267
              .unwrap();
268
```

src/potentials.rs

```
1
    use crate::*;
 2
 3
   const ENERGY INF: f64 = 1e6;
 4
 5 #[allow(unused)]
 6
    pub fn smooth_step(x: f64) -> f64 {
 7
        const TRANSITION: f64 = 0.5;
 8
        let step = Arc::new(Function::new(|x: f64| -> Complex64 {
 9
            if x.abs() < 2.0 {
10
                complex(10.0, 0.0)
11
            } else {
12
                complex(0.0, 0.0)
13
            }
14
        }));
        let zero = Arc::new(Function::new(|_: f64| -> Complex64 { complex(0.0, 0.0) }));
15
16
        let inf = Arc::new(Function::new(|x: f64| -> Complex64 {
17
            if x.abs() > 5.0 {
18
                complex(ENERGY_INF, 0.0)
19
            } else {
20
                complex(0.0, 0.0)
21
22
        }));
23
24
        let joint_inf_zero_l = wave_function_builder::Joint {
25
            left: inf.clone(),
26
            right: zero.clone(),
27
            cut: -5.0 + TRANSITION / 2.0,
28
            delta: TRANSITION,
29
        };
30
31
        let joint_zero_step_l = wave_function_builder::Joint {
32
            left: zero.clone(),
33
            right: step.clone(),
34
            cut: -2.0 + TRANSITION / 2.0,
35
            delta: TRANSITION,
36
        };
37
38
        let joint_zero_inf_r = wave_function_builder::Joint {
39
            left: zero.clone(),
40
            right: inf.clone(),
41
            cut: 5.0 - TRANSITION / 2.0,
42
            delta: TRANSITION,
43
        };
44
45
        let joint_step_zero_r = wave_function_builder::Joint {
46
            left: step.clone(),
```

```
47
            right: zero.clone(),
48
            cut: 2.0 - TRANSITION / 2.0,
49
            delta: TRANSITION,
50
        };
51
52
        if wave_function_builder::is_in_range(joint_zero_inf_r.range(), x) {
53
            return joint_zero_inf_r.eval(x).re;
54
        }
55
56
        if wave_function_builder::is_in_range(joint_inf_zero_l.range(), x) {
57
            return joint_inf_zero_l.eval(x).re;
58
59
60
        if wave function builder::is in range(joint step zero r.range(), x) {
61
            return joint_step_zero_r.eval(x).re;
62
        }
63
64
        if wave_function_builder::is_in_range(joint_zero_step_l.range(), x) {
65
            return joint_zero_step_l.eval(x).re;
66
67
68
        return zero.eval(x).re.max(inf.eval(x).re.max(step.eval(x).re));
69
    }
70
71
   #[allow(unused)]
72
    pub fn mexican_hat(x: f64) -> f64 {
73
        (x - 4.0).powi(2) * (x + 4.0).powi(2)
74
75
76 #[allow(unused)]
77
    pub fn double_mexican_hat(x: f64) -> f64 {
78
        (x - 4.0).powi(2) * x.powi(2) * (x + 4.0).powi(2)
79
   }
80
81
   #[allow(unused)]
82
    pub fn triple mexican hat(x: f64) -> f64 {
83
        (x - 6.0).powi(2) * (x - 3.0).powi(2) * (x + 3.0).powi(2) * (x + 6.0).powi(2)
84
85
86 pub fn square(x: f64) -> f64 {
87
        x * x
88
```

src/tui.rs

```
1 use std::io;
2
3 fn get_float_from_user(message: &str) -> f64 {
    loop {
```

```
5
            println!("{}", message);
 6
            let mut input = String::new();
 7
 8
            // io::stdout().lock().write(message.as ref()).unwrap();
 9
            io::stdin()
10
                 .read line(&mut input)
11
                 .expect("Not_a_valid_string");
12
            println!("");
13
            let num = input.trim().parse();
            if num.is_ok() {
14
15
                 return num.unwrap();
16
            }
17
        }
18
    }
19
20
    fn get user bounds() -> (f64, f64) {
21
        let user bound lower: f64 = get float from user("Lower_Bound:_");
22
23
        let user_bound_upper: f64 = get_float_from_user("Upper_bound:");
24
        return (user bound lower, user bound upper);
25
26
    fn ask_user_for_view(lower_bound: Option<f64>, upper_bound: Option<f64>) -> (f64, f64
27
        println!("Failed, to, determine, boundary, of, the, graph, automatically.");
28
        println!("Pleas_enter_values_manually.");
29
        lower_bound.map(|b| println!("(Suggestion_for_lower_bound:_{{}})", b));
30
        upper_bound.map(|b| println!("(Suggestion_for_upper_bound:_{{}})", b));
31
32
        return get_user_bounds();
33
```

src/turning_points.rs

```
1 use crate::cmp f64;
 2 use crate::newtons_method::*;
 3 use crate::wkb_wave_func::*;
 4 use crate::*;
 5 use num::signum;
 6
 7
   const MAX TURNING POINTS: usize = 256;
 8 const ACCURACY: f64 = 1e-9;
 9
10
   pub struct TGroup {
        pub ts: Vec<((f64, f64), f64)>,
11
12
        // pub tn: Option<f64>,
13
14
15 impl TGroup {
      pub fn new() -> TGroup {
```

```
17
            TGroup { ts: vec![] }
18
        }
19
20
        pub fn add ts(&mut self, new t: ((f64, f64), f64)) {
21
            self.ts.push(new t);
22
23
    }
24
25
    fn validity_func(phase: Phase) -> Arc<dyn Fn(f64) -> f64> {
26
        Arc::new(move |x: f64| {
            1.0 / (2.0 * phase.mass).sqrt() * derivative(\&|t| (phase.potential)(t), x).
27
                abs() * VALIDITY_LL_FACTOR
28
                 - ((phase.potential)(x) - phase.energy).pow(2)
29
        })
30
    }
31
32
    fn group ts(zeros: &Vec<f64>, phase: &Phase) -> TGroup {
33
        let mut zeros = zeros.clone();
34
        let valid = validity_func(phase.clone());
35
36
        zeros.sort by(cmp f64);
37
        let mut derivatives = zeros
38
            .iter()
39
            .map(|x| derivative(valid.as ref(), *x))
40
            .map(signum)
            .zip(zeros.clone())
41
42
            .collect::<Vec<(f64, f64)>>();
43
44
        let mut groups = TGroup { ts: vec![] };
45
46
        if let Some((deriv, z)) = derivatives.first() {
47
            if *deriv < 0.0 {</pre>
48
                let mut guess = z - ACCURACY.sqrt();
49
                let mut new_deriv = *deriv;
50
                let mut missing_t = *z;
51
52
                while new deriv < 0.0 {</pre>
53
                    missing t =
54
                         regula falsi bisection(valid.as ref(), guess, -ACCURACY.sqrt(),
                             ACCURACY);
55
                    new_deriv = signum(derivative(valid.as_ref(), missing_t));
56
                    guess -= ACCURACY.sqrt();
57
                }
58
59
                derivatives.insert(
60
61
                     (signum(derivative(valid.as ref(), missing t)), missing t),
62
                );
63
```

```
64
65
66
         if let Some((deriv, z)) = derivatives.last() {
67
             if *deriv > 0.0 {
68
                 let mut guess = z + ACCURACY.sqrt();
69
                 let mut new deriv = *deriv;
70
                 let mut missing_t = *z;
71
72
                 while new_deriv > 0.0 {
73
                     missing_t =
74
                          regula_falsi_bisection(valid.as_ref(), guess, ACCURACY.sqrt(),
                              ACCURACY);
75
                     new deriv = signum(derivative(valid.as ref(), missing t));
76
                     guess += ACCURACY.sqrt();
77
                 }
78
79
                 derivatives.push((signum(derivative(valid.as ref(), missing t)),
                     missing t));
80
             }
81
82
83
         assert_eq!(derivatives.len() % 2, 0);
84
85
         for i in (0..derivatives.len()).step by(2) {
86
             let (t1 deriv, t1) = derivatives[i];
87
             let (t2_deriv, t2) = derivatives[i + 1];
88
             assert!(t1_deriv > 0.0);
89
             assert!(t2_deriv < 0.0);</pre>
90
91
             let turning_point = newtons_method(
92
                 &|x| phase.energy - (phase.potential)(x),
                 (t1 + t2) / 2.0,
93
94
                 1e-7,
95
             );
96
             groups.add ts(((t1, t2), turning point));
97
         }
98
99
         return groups;
100
101
102
     pub fn calc_ts(phase: &Phase, view: (f64, f64)) -> TGroup {
103
         let zeros = find_zeros(phase, view);
104
         let groups = group_ts(&zeros, phase);
105
         println!(
106
             "Turning_Points:__{:.7?}",
107
             groups.ts.iter().map(|(_, t)| *t).collect::<Vec<f64>>()
108
109
         return groups;
110 }
```

```
111
112
     fn find zeros(phase: &Phase, view: (f64, f64)) -> Vec<f64> {
113
         let phase clone = phase.clone();
114
         let validity func = Arc::new(move |x: f64| {
115
             1.0 / (2.0 * phase clone.mass).sqrt()
                  * derivative(&|t| (phase_clone.potential)(t), x).abs()
116
117
                 * VALIDITY_LL_FACTOR
118
                 - ((phase_clone.potential)(x) - phase_clone.energy).pow(2)
119
         });
120
         let mut zeros = NewtonsMethodFindNewZero::new(validity_func, ACCURACY, 1e4 as
             usize);
121
122
         (0..MAX TURNING POINTS).into iter().for each(| | {
123
             let modified_func = |x| zeros.modified_func(x);
124
125
             let guess = make guess(&modified func, view, 1000);
126
             guess.map(|g| zeros.next zero(g));
127
         });
128
129
         let view = if view.0 < view.1 {</pre>
130
             view
         } else {
131
132
             (view.1, view.0)
133
134
         let unique zeros = zeros
135
             .get_previous_zeros()
136
             .iter()
137
             .filter(|x| **x > view.0 \&\& **x < view.1)
138
             .map(|x| *x)
139
             .collect::<Vec<f64>>();
140
         return unique_zeros;
141
```

src/utils.rs

```
1 use crate::newtons_method::derivative;
    use crate::Complex64;
 3
    use std::cmp::Ordering;
 4
 5
    pub fn cmp_f64(a: &f64, b: &f64) -> Ordering {
 6
        if a < b {
 7
            return Ordering::Less;
 8
        } else if a > b {
 9
            return Ordering::Greater;
10
11
        return Ordering::Equal;
12
13
    pub fn complex(re: f64, im: f64) -> Complex64 {
```

```
15
        return Complex64 { re, im };
16 }
17
18
    pub fn sigmoid(x: f64) -> f64 {
19
        1.0 / (1.0 + (-x).exp())
20
21
22
    pub fn identity(c: Complex64) -> Complex64 {
23
24 }
25
    pub fn conjugate(c: Complex64) -> Complex64 {
26
27
        c.conj()
28
   }
29
30
    pub fn negative(c: Complex64) -> Complex64 {
31
       - C
32
    }
33
34
    pub fn negative conj(c: Complex64) -> Complex64 {
35
        -c.conj()
36
    }
37
38
    pub fn complex compare(expect: Complex64, actual: Complex64, epsilon: f64) -> bool {
39
        let average = (expect.norm() + actual.norm()) / 2.0;
40
        return (expect - actual).norm() / average < epsilon;</pre>
41
    }
42
43
    pub fn float_compare(expect: f64, actual: f64, epsilon: f64) -> bool {
44
        let average = (expect + actual) / 2.0;
45
46
        if average < epsilon {</pre>
47
            return expect == actual;
48
49
50
        return (expect - actual) / average < epsilon;</pre>
51
    }
52
53
    pub trait Func<A, R>: Sync + Send {
54
        fn eval(&self, x: A) -> R;
55
56
57
    pub trait ReToC: Sync + Func<f64, Complex64> {}
58
59
    pub trait ReToRe: Sync + Func<f64, f64> {}
60
61
   pub struct Function<A, R> {
62
        pub(crate) f: fn(A) -> R,
63 }
```

```
64
65
    impl<A, R> Function<A, R> {
66
        pub const fn new(f: fn(A) -> R) -> Function<A, R> {
67
            return Function { f };
68
69
70
71
    impl<A, R> Func<A, R> for Function<A, R> {
72
        fn eval(\&self, x: A) -> R {
73
            (self.f)(x)
74
75
76
    pub struct Derivative<'a> {
77
        pub f: &'a dyn Func<f64, Complex64>,
78
   }
79
80
    impl Func<f64, Complex64> for Derivative<' > {
81
        fn eval(&self, x: f64) -> Complex64 {
82
            derivative(\&|x| self.f.eval(x), x)
83
84
    }
85
86
    fn get_wavefunc_exp_sign(x: f64) -> f64 {
87
        if -0.5 \le x \&\& x \le 0.5 {
88
            return 1.0;
89
        } else {
90
            return -1.0;
91
        }
92
   }
```

src/wave_function_builder.rs

```
use crate::wkb_wave_func::Phase;
 2 use crate::*;
 3 use ordinal::Ordinal;
 4
   use std::sync::*;
 5
 6
    pub enum ScalingType {
 7
        Mul(Complex64),
 8
        Renormalize(Complex64),
 9
        None,
10
    }
11
    pub trait WaveFunctionPart: Func<f64, Complex64> + Sync + Send {
12
13
        fn range(&self) -> (f64, f64);
14
        fn as_func(&self) -> Box<dyn Func<f64, Complex64>>;
15
16
    pub trait WaveFunctionPartWithOp: WaveFunctionPart {
```

```
18
        fn get op(&self) -> Box<fn(Complex64) -> Complex64>;
19
        fn with op(&self, op: fn(Complex64) -> Complex64) -> Box<dyn</pre>
            WaveFunctionPartWithOp>;
20
        fn as wave function part(&self) -> Box<dyn WaveFunctionPart>;
21
22
23
    pub fn is_in_range(range: (f64, f64), x: f64) -> bool {
24
        return range.0 <= x \&\& range.1 > x;
25
   }
26
27
   #[derive(Clone)]
28
    pub struct Joint {
29
        pub left: Arc<dyn Func<f64, Complex64>>,
30
        pub right: Arc<dyn Func<f64, Complex64>>,
31
        pub cut: f64,
32
        pub delta: f64,
33
    }
34
35
    impl WaveFunctionPart for Joint {
36
        fn range(&self) -> (f64, f64) {
37
            if self.delta > 0.0 {
38
                (self.cut, self.cut + self.delta)
39
            } else {
40
                (self.cut + self.delta, self.cut)
41
42
        }
43
        fn as_func(&self) -> Box<dyn Func<f64, Complex64>> {
44
            return Box::new(self.clone());
45
        }
46
    }
47
48
    impl Func<f64, Complex64> for Joint {
49
        fn eval(&self, x: f64) -> Complex64 {
50
            let (left, right) = if self.delta > 0.0 {
51
                (&self.left, &self.right)
52
            } else {
53
                (&self.right, &self.left)
54
            };
55
56
            let delta = self.delta.abs();
57
58
            let chi = |x: f64| f64::sin(x * f64::consts::PI / 2.0).powi(2);
59
            let left_val = left.eval(x);
60
            return left_val + (right.eval(x) - left_val) * chi((x - self.cut) / delta);
61
        }
62 }
63
64 #[derive(Clone)]
65 struct PureWkb {
```

```
66
         wkb: Arc<WkbWaveFunction>,
67
         range: (f64, f64),
68
     }
69
     impl WaveFunctionPart for PureWkb {
70
71
         fn range(&self) -> (f64, f64) {
72
             self.range
73
74
         fn as_func(&self) -> Box<dyn Func<f64, Complex64>> {
75
             Box::new(self.clone())
76
         }
77
     }
78
79
     impl WaveFunctionPartWithOp for PureWkb {
80
         fn as wave function part(&self) -> Box<dyn WaveFunctionPart> {
81
             Box::new(self.clone())
82
         }
83
84
         fn get_op(&self) -> Box<fn(Complex64) -> Complex64> {
85
             self.wkb.get op()
86
87
88
         fn with_op(&self, op: fn(Complex64) -> Complex64) -> Box<dyn</pre>
             WaveFunctionPartWithOp> {
89
             Box::new(PureWkb {
90
                 wkb: Arc::new(self.wkb.with_op(op)),
91
                  range: self.range,
92
             })
93
         }
94
     }
95
96
     impl Func<f64, Complex64> for PureWkb {
97
         fn eval(&self, x: f64) -> Complex64 {
98
             self.wkb.eval(x)
99
         }
100
101
102
     #[derive(Clone)]
103
     struct ApproxPart {
104
         airy: Arc<AiryWaveFunction>,
105
         wkb: Arc<WkbWaveFunction>,
106
         airy_join_l: Joint,
107
         airy_join_r: Joint,
108
         range: (f64, f64),
109
110
111
     impl WaveFunctionPart for ApproxPart {
112
         fn range(&self) -> (f64, f64) {
113
             self.range
```

```
114
115
         fn as func(&self) -> Box<dyn Func<f64, Complex64>> {
116
             Box::new(self.clone())
117
         }
118
119
120
     impl WaveFunctionPartWithOp for ApproxPart {
121
         fn as_wave_function_part(&self) -> Box<dyn WaveFunctionPart> {
122
             Box::new(self.clone())
123
         }
124
125
         fn get_op(&self) -> Box<fn(Complex64) -> Complex64> {
126
             self.wkb.get op()
127
         }
128
129
         fn with op(&self, op: fn(Complex64) -> Complex64) -> Box<dyn</pre>
             WaveFunctionPartWithOp> {
130
             Box::new(ApproxPart::new(
131
                 self.airy.with_op(op),
132
                 self.wkb.with op(op),
133
                 self.range,
134
             ))
135
         }
136
     }
137
138
     impl ApproxPart {
139
         fn new(airy: AiryWaveFunction, wkb: WkbWaveFunction, range: (f64, f64)) ->
             ApproxPart {
140
             let airy_rc = Arc::new(airy);
141
             let wkb_rc = Arc::new(wkb);
             let delta = (airy_rc.ts.1 - airy_rc.ts.0) * AIRY_TRANSITION_FRACTION;
142
143
             ApproxPart {
144
                 airy: airy_rc.clone(),
145
                 wkb: wkb_rc.clone(),
146
                 airy join l: Joint {
147
                      left: wkb rc.clone(),
148
                      right: airy_rc.clone(),
149
                     cut: airy_rc.ts.0 + delta / 2.0,
150
                     delta: -delta,
151
                 },
152
                 airy_join_r: Joint {
153
                      left: airy_rc.clone(),
154
                      right: wkb_rc.clone(),
155
                      cut: airy_rc.ts.1 - delta / 2.0,
156
                     delta,
157
                 },
158
                  range,
159
             }
160
```

```
161
     }
162
163
     impl Func<f64, Complex64> for ApproxPart {
164
         fn eval(&self, x: f64) -> Complex64 {
165
             if is_in_range(self.airy_join_l.range(), x) && ENABLE_AIRY_JOINTS {
166
                  return self.airy_join_l.eval(x);
167
             } else if is_in_range(self.airy_join_r.range(), x) && ENABLE_AIRY_JOINTS {
168
                  return self.airy_join_r.eval(x);
169
             } else if is_in_range(self.airy.ts, x) {
170
                  return self.airy.eval(x);
171
             } else {
172
                  return self.wkb.eval(x);
173
             }
174
         }
175
     }
176
177
     #[derive(Clone)]
178
     pub struct WaveFunction {
179
         phase: Arc<Phase>,
180
         view: (f64, f64),
181
         parts: Vec<Arc<dyn WaveFunctionPart>>,
182
         airy_ranges: Vec<(f64, f64)>,
183
         wkb_ranges: Vec<(f64, f64)>,
184
         scaling: Complex64,
185
     }
186
187
     fn sign_match(f1: f64, f2: f64) -> bool {
188
         return f1.signum() == f2.signum();
189
     }
190
191
     fn sign_match_complex(mut c1: Complex64, mut c2: Complex64) -> bool {
192
         if c1.re.abs() < c1.im.abs() {</pre>
193
             c1.re = 0.0;
194
         }
195
196
         if c1.im.abs() < c1.re.abs() {</pre>
197
             c1.im = 0.0;
198
199
200
         if c2.re.abs() < c2.im.abs() {</pre>
201
             c2.re = 0.0;
202
203
204
         if c2.im.abs() < c2.re.abs() {</pre>
205
             c2.im = 0.0;
206
         }
207
208
         return sign_match(c1.re, c2.re) && sign_match(c1.im, c2.im);
209
```

```
210
211
     impl WaveFunction {
212
         pub fn get energy(&self) -> f64 {
213
             self.phase.energy
214
215
216
         pub fn new<F: Fn(f64) -> f64 + Sync + Send>(
217
             potential: &'static F,
218
             mass: f64,
219
             n_energy: usize,
220
             approx_inf: (f64, f64),
221
             view_factor: f64,
222
             scaling: ScalingType,
223
         ) -> WaveFunction {
224
             let energy = energy::nth energy(n energy, mass, &potential, approx inf);
225
             println!("{}_Energy:_{{:.9}}", Ordinal(n energy).to string(), energy);
226
227
             let lower bound = newtons method::newtons method max iters(
228
                 \&|x| potential(x) - energy,
229
                 approx inf.0,
230
                 1e-7,
231
                 100000,
232
             );
233
             let upper bound = newtons method::newtons method max iters(
234
                 &|x| potential(x) - energy,
235
                 approx_inf.1,
236
                 1e-7,
237
                 100000,
238
             );
239
240
             let view = if lower_bound.is_some() && upper_bound.is_some() {
241
242
                     lower_bound.unwrap() * (upper_bound.unwrap() - lower_bound.unwrap())
                          * view factor,
243
                     upper bound.unwrap() * (upper bound.unwrap() - lower bound.unwrap())
                          * view factor,
244
                  )
245
             } else {
246
                 println!("Failed_to_determine_view_automatically,_using_APPROX INF_as_
                     view");
247
248
                     approx_inf.0 - f64::EPSILON.sqrt(),
249
                     approx_inf.1 + f64::EPSILON.sqrt(),
250
                 )
251
             };
252
253
             let phase = Arc::new(Phase::new(energy, mass, potential));
254
255
             let (airy_wave_funcs, boundaries) = AiryWaveFunction::new(phase.clone(), (
```

```
view.0, view.1));
             let (parts, airy_ranges, wkb_ranges): (
256
257
                 Vec<Arc<dyn WaveFunctionPart>>,
258
                 Vec<(f64, f64)>,
259
                 Vec<(f64, f64)>,
260
             ) = if boundaries.ts.len() == 0 {
261
                 println!("No_turning_points_found_in_view!_Results_might_be_in_accurate")
262
                 let wkb1 = WkbWaveFunction::new(
263
                     phase.clone(),
264
                     1.0.into(),
265
                     INTEG_STEPS,
266
                     approx inf.0,
267
                     approx inf.0,
268
                     f64::consts::PI / 4.0,
269
                 );
270
                 let wkb2 = WkbWaveFunction::new(
271
                     phase.clone(),
272
                     1.0.into(),
273
                     INTEG STEPS,
274
                     approx inf.0,
275
                     approx_inf.1,
276
                     f64::consts::PI / 4.0,
277
                 );
278
279
                 let center = (view.0 + view.1) / 2.0;
280
                 let wkb1 = Box::new(PureWkb {
281
                     wkb: Arc::new(wkb1),
282
                      range: (approx_inf.0, center),
283
                 });
284
285
                 let wkb2 = Box::new(PureWkb {
286
                     wkb: Arc::new(wkb2),
287
                     range: (center, approx_inf.1),
288
                 });
289
290
                 let wkb1 range = wkb1.range();
291
292
                     vec![
293
                         Arc::from(wkb1.as wave function part()),
294
                          Arc::from(wkb2.as_wave_function_part()),
295
                     ],
                     vec![],
296
297
                     vec![wkb1_range, wkb2.range()],
298
                 )
299
             } else {
300
                 let turning points: Vec<f64> = [
                     vec![2.0 * approx_inf.0 - boundaries.ts.first().unwrap().1],
301
302
                     boundaries.ts.iter().map(|p| p.1).collect(),
```

```
303
                      vec![2.0 * approx inf.1 - boundaries.ts.last().unwrap().1],
304
                  ]
305
                  .concat();
306
307
                  let wave funcs = turning points
308
                      .iter()
309
                      .zip(turning_points.iter().skip(1))
310
                      .zip(turning_points.iter().skip(2))
311
                          |((previous, boundary), next)| -> (WkbWaveFunction, (f64, f64)) {
312
313
314
                                  if derivative(phase.potential.as_ref(), *boundary) > 0.0
                                      WkbWaveFunction::new(
315
316
                                           phase.clone(),
317
                                           1.0.into(),
318
                                           INTEG STEPS,
319
                                           *boundary,
320
                                           *previous,
321
                                           f64::consts::PI / 4.0,
322
                                      )
323
                                  } else {
324
                                      WkbWaveFunction::new(
325
                                           phase.clone(),
326
                                           1.0.into(),
327
                                           INTEG_STEPS,
328
                                           *boundary,
329
                                           *boundary,
                                           f64::consts::PI / 4.0,
330
331
                                      )
332
333
                                  ((boundary + previous) / 2.0, (next + boundary) / 2.0),
334
                              )
335
                          },
336
                      )
337
                      .collect::<Vec<(WkbWaveFunction, (f64, f64))>>();
338
339
                  let wkb airy pair: Vec<(&(WkbWaveFunction, (f64, f64)), AiryWaveFunction)</pre>
                      > = wave funcs
340
                      .iter()
341
                      .zip(airy_wave_funcs.iter())
342
                      .map(|(w, a)| {
343
                          (
344
345
                              a.with_phase_off(w.0.phase_off)
346
                                  .with_c(w.0.get_exp_sign().into()),
347
348
                      })
349
                      .collect();
```

```
350
351
                 let wkb ranges = wkb airy pair
352
                      .iter()
353
                      .map(|(( , wkb range), )| *wkb range)
354
                      .collect();
355
                 let airy_ranges = wkb_airy_pair.iter().map(|(_, airy)| airy.ts).collect()
356
357
                 let approx_parts: Vec<Arc<dyn WaveFunctionPartWithOp>> = wkb_airy_pair
358
359
                      .map(|((wkb, range), airy)| -> Arc<dyn WaveFunctionPartWithOp> {
360
                          Arc::new(ApproxPart::new(airy.clone(), wkb.clone(), *range))
361
                     })
362
                      .collect();
363
364
365
                     approx parts
366
                          .iter()
367
                          .map(|p| Arc::from(p.as_wave_function_part()))
368
                          .collect(),
369
                     airy_ranges,
370
                     wkb_ranges,
371
                 )
372
             };
373
374
             match scaling {
375
                 ScalingType::Mul(s) => WaveFunction {
376
                      phase,
377
                      view,
378
                     parts,
379
                     airy_ranges,
                     wkb_ranges,
380
381
                     scaling: s,
382
383
                 ScalingType::None => WaveFunction {
384
                     phase,
385
                     view,
386
                     parts,
387
                     airy ranges,
388
                     wkb ranges,
389
                     scaling: complex(1.0, 0.0),
390
391
                 ScalingType::Renormalize(s) => {
392
                      let unscaled = WaveFunction {
393
                          phase: phase.clone(),
394
                          view,
395
                          parts: parts.clone(),
                          airy_ranges: airy_ranges.clone(),
396
397
                          wkb_ranges: wkb_ranges.clone(),
```

```
398
                           scaling: s,
399
                      };
400
                       let factor = renormalize factor(&unscaled, approx inf);
401
                       WaveFunction {
402
                           phase,
403
                           view,
404
                           parts,
405
                           airy_ranges,
406
                           wkb_ranges,
                           scaling: s * factor,
407
408
                      }
409
                  }
410
              }
411
          }
412
413
          pub fn calc psi(&self, x: f64) -> Complex64 {
414
              for part in self.parts.as slice() {
415
                  if is_in_range(part.range(), x) {
416
                       return part.eval(x);
417
                  }
418
              }
419
              panic!(
420
                  "[WkbWaveFunction::calc_psi]_{\bot}x_{\bot}out_{\bot}of_{\bot}range_{\bot}(x_{\bot}=_{\bot}\{\},_{\bot}ranges:_{\bot}\{:\#?\})",
421
422
                  self.parts
423
                       .iter()
424
                       .map(|p| p.range())
425
                       .collect::<Vec<(f64, f64)>>()
426
              );
427
         }
428
429
          pub fn get_airy_ranges(&self) -> &[(f64, f64)] {
430
              self.airy_ranges.as_slice()
431
          }
432
433
          pub fn get wkb ranges(&self) -> &[(f64, f64)] {
434
              self.wkb_ranges.as_slice()
435
          }
436
437
          pub fn get wkb ranges in view(&self) -> Vec<(f64, f64)> {
438
              self.wkb_ranges
439
                   .iter()
440
                   .map(|range| {
441
                       (
442
                           f64::max(self.get_view().0, range.0),
443
                           f64::min(self.get_view().1, range.1),
444
445
                  })
446
                   .collect::<Vec<(f64, f64)>>()
```

```
447
448
449
         pub fn is wkb(&self, x: f64) -> bool {
450
             self.wkb ranges
451
                  .iter()
452
                  .map(|r| is_in_range(*r, x))
453
                  .collect::<Vec<bool>>()
454
                  .contains(&true)
455
         }
456
457
         pub fn is_airy(&self, x: f64) -> bool {
458
             self.airy_ranges
459
                  .iter()
460
                  .map(|r| is in range(*r, x))
461
                  .collect::<Vec<bool>>()
462
                  .contains(&true)
463
         }
464
465
         pub fn get_view(&self) -> (f64, f64) {
466
             self.view
467
468
469
         pub fn set_view(&mut self, view: (f64, f64)) {
470
             self.view = view
471
472
473
         pub fn get_phase(&self) -> Arc<Phase> {
474
             self.phase.clone()
475
         }
476
     }
477
478
     impl Func<f64, Complex64> for WaveFunction {
479
         fn eval(&self, x: f64) -> Complex64 {
480
             self.scaling * self.calc_psi(x)
481
         }
482
     }
483
484
     pub struct SuperPosition {
485
         wave funcs: Vec<WaveFunction>,
486
         scaling: Complex64,
487
     }
488
489
     impl SuperPosition {
490
         pub fn new<F: Fn(f64) \rightarrow f64 + Send + Sync>(
491
             potential: &'static F,
492
             mass: f64,
             n_energies_scaling: &[(usize, Complex64)],
493
494
             approx_inf: (f64, f64),
             view_factor: f64,
495
```

```
496
             scaling: ScalingType,
497
         ) -> SuperPosition {
498
             let wave funcs = n energies scaling
499
                  .iter()
                  .map(|(e, scale)| {
500
501
                      let wave = WaveFunction::new(
502
                          potential,
503
                          mass,
504
                          *е,
505
                          approx_inf,
506
                          view_factor,
507
                          ScalingType::Mul(*scale),
508
                      );
509
                      println!("Calculated_{{}_Energy\n", Ordinal(*e).to_string());
510
                      return wave;
511
                 })
512
                  .collect();
513
514
             match scaling {
515
                 ScalingType::Mul(s) => SuperPosition {
516
                      wave funcs,
517
                      scaling: s,
518
                 },
519
                 ScalingType::None => SuperPosition {
520
                      wave funcs,
521
                      scaling: 1.0.into(),
522
                 ScalingType::Renormalize(s) => {
523
524
                      let unscaled = SuperPosition {
525
                          wave_funcs: wave_funcs.clone(),
526
                          scaling: s,
527
                      };
528
                      let factor = renormalize_factor(&unscaled, approx_inf);
529
                      println!("factor: [] {} ", factor);
530
                      SuperPosition {
531
                          wave funcs,
532
                          scaling: s * factor,
533
                     }
534
                 }
535
             }
536
         }
537
538
         pub fn get_view(&self) -> (f64, f64) {
539
             let view_a = self
540
                  .wave_funcs
541
                  .iter()
542
                  .map(|w| w.get_view().0)
543
                  .min_by(cmp_f64)
544
                  .unwrap();
```

```
545
             let view b = self
546
                  .wave funcs
547
                  .iter()
548
                  .map(|w| w.get view().1)
549
                  .max_by(cmp_f64)
550
                  .unwrap();
551
             (view_a, view_b)
552
         }
553
     }
554
555
     impl Func<f64, Complex64> for SuperPosition {
556
         fn eval(&self, x: f64) -> Complex64 {
557
             self.scaling * self.wave_funcs.iter().map(|w| w.eval(x)).sum::<Complex64>()
558
         }
559
     }
560
561
    struct Scaled<A, R>
     where
562
563
         R: std::ops::Mul<R, Output = R> + Sync + Send + Clone,
564
565
         scale: R,
566
         func: Box<dyn Func<A, R>>,
567
568
569
     impl<A, R> Func<A, R> for Scaled<A, R>
570
     where
571
         R: std::ops::Mul<R, Output = R> + Sync + Send + Clone,
572
     {
573
         fn eval(\&self, x: A) -> R {
574
             self.func.eval(x) * self.scale.clone()
575
         }
576
     }
577
578
     fn renormalize_factor(wave_func: &dyn Func<f64, Complex64>, approx_inf: (f64, f64))
         -> f64 {
579
         1.0 / integrate(
580
             evaluate_function_between(
581
                 wave func,
582
                 approx inf.0 * (1.0 - f64::EPSILON),
583
                 approx inf.1 * (1.0 - f64::EPSILON),
584
                 INTEG_STEPS,
585
             )
586
             .par_iter()
587
             .map(|p| Point {
588
                 x: p.x,
589
                 y: p.y.norm_sqr(),
590
591
             .collect(),
592
             TRAPEZE_PER_THREAD,
```

```
593
594
     }
595
596
     pub fn renormalize(
597
         wave func: Box<dyn Func<f64, Complex64>>,
598
         approx_inf: (f64, f64),
599
     ) -> Box<dyn Func<f64, Complex64>> {
600
         let area = renormalize_factor(wave_func.as_ref(), approx_inf);
601
         return Box::new(Scaled::<f64, Complex64> {
602
             scale: area.into(),
603
             func: wave_func,
604
         });
605
     }
606
607
     #[cfg(test)]
608
     mod test {
609
         use super::*;
610
611
         #[test]
612
         fn sign check complex test() {
613
             let range = (-50.0, 50.0);
614
             let n = 100000;
615
             for ri1 in 0..n {
616
                  for iil in 0..n {
617
                      for ri2 in 0..n {
618
                          for ii2 in 0..n {
619
                              let re1 = index_to_range(ri1 as f64, 0.0, n as f64, range.0,
                                  range.1);
620
                              let im1 = index_to_range(ii1 as f64, 0.0, n as f64, range.0,
                                  range.1);
621
                              let re2 = index_to_range(ri2 as f64, 0.0, n as f64, range.0,
622
                              let im2 = index_to_range(ii2 as f64, 0.0, n as f64, range.0,
                                  range.1);
623
624
                              assert eq!(
625
                                  sign_match_complex(complex(re1, im1), complex(re2, im2)),
626
                                  sign_match_complex(complex(re2, im2), complex(re1, im1))
627
                              );
628
                         }
629
                     }
630
                 }
631
             }
632
         }
633
```

src/wkb wave func.rs

```
1 use crate::*;
```

```
2 use std::fmt::Display;
    use std::sync::Arc;
 4
 5
   #[derive(Clone)]
 6
    pub struct Phase {
        pub energy: f64,
 7
 8
        pub mass: f64,
 9
        pub potential: Arc<dyn Fn(f64) -> f64 + Send + Sync>,
10
    }
11
12
    impl Display for Phase {
13
        fn fmt(&self, f: &mut std::fmt::Formatter<'_>) -> std::fmt::Result {
14
            write!(
15
                f,
16
                "Phase_{{energy:_{},_mass:_{},_potential:_[func]}}",
17
                self.energy, self.mass
18
19
        }
20
21
22
    impl Phase {
23
        fn default() -> Phase {
24
            Phase {
25
                energy: 0.0,
26
                mass: 0.0,
27
                potential: Arc::new(|_x| 0.0),
28
            }
29
        }
30
31
        pub fn new<F: Fn(f64) -> f64 + Sync + Send>(
32
            energy: f64,
33
            mass: f64,
34
            potential: &'static F,
35
        ) -> Phase {
36
            return Phase {
37
                energy,
38
                mass,
39
                potential: Arc::new(potential),
40
            };
41
        }
42
        fn sqrt_momentum(&self, x: f64) -> f64 {
43
44
            self.eval(x).abs().sqrt()
45
        }
46
    }
47
48
    impl Func<f64, f64> for Phase {
49
        fn eval(&self, x: f64) -> f64 {
50
            (2.0 * self.mass * ((self.potential)(x) - self.energy))
```

```
51
                 .abs()
52
                 .sqrt()
53
        }
54
55
56
    #[derive(Clone)]
57
    pub struct WkbWaveFunction {
58
        pub c: Complex64,
59
        pub turning_point_exp: f64,
60
        pub turning_point_osz: f64,
61
        pub phase: Arc<Phase>,
62
        integration_steps: usize,
63
        op: fn(Complex64) -> Complex64,
64
        pub phase off: f64,
65
    }
66
67
    impl WkbWaveFunction {
        pub fn get_c(&self) -> Complex64 {
68
69
            self.c
70
71
72
        pub fn with_c(&self, c: Complex64) -> WkbWaveFunction {
73
            WkbWaveFunction {
74
                С,
75
                turning_point_exp: self.turning_point_exp,
76
                turning_point_osz: self.turning_point_osz,
77
                phase: self.phase.clone(),
78
                integration_steps: self.integration_steps,
79
                op: self.op,
80
                phase_off: self.phase_off,
81
            }
82
        }
83
84
        pub fn new(
85
            phase: Arc<Phase>,
86
            c: Complex64,
87
            integration steps: usize,
88
            turning_point_exp: f64,
89
            turning point osz: f64,
90
            phase off: f64,
91
        ) -> WkbWaveFunction {
92
            return WkbWaveFunction {
93
94
                turning_point_exp,
95
                turning_point_osz,
96
                phase: phase.clone(),
97
                integration steps,
98
                op: identity,
99
                phase_off,
```

```
100
             };
101
         }
102
103
         pub fn with op(&self, op: fn(Complex64) -> Complex64) -> WkbWaveFunction {
104
             return WkbWaveFunction {
105
                 c: self.c,
106
                 turning_point_exp: self.turning_point_exp,
107
                 turning_point_osz: self.turning_point_osz,
108
                 phase: self.phase.clone(),
109
                 integration_steps: self.integration_steps,
110
111
                 phase_off: self.phase_off,
112
             };
113
         }
114
115
         pub fn get op(&self) -> Box<fn(Complex64) -> Complex64> {
116
             Box::new(self.op)
117
         }
118
119
         pub fn get exp sign(&self) -> f64 {
120
             let limit_sign = if self.turning_point_exp == self.turning_point_osz {
121
                 1.0
122
             } else {
123
                 -1.0
124
             };
125
126
             self.psi_osz(self.turning_point_exp + limit_sign * f64::EPSILON.sqrt())
127
128
                 .signum()
129
         }
130
131
         fn psi osz(&self, x: f64) -> Complex64 {
132
             let integral = integrate(
133
                 evaluate_function_between(
134
                     self.phase.as ref(),
135
                     Χ,
136
                     self.turning_point_osz,
137
                     self.integration steps,
138
139
                 TRAPEZE PER THREAD,
140
             );
141
             -self.c * complex((integral - self.phase_off).cos(), 0.0) / self.phase.
                 sqrt_momentum(x)
142
         }
143
144
         fn psi_exp(&self, x: f64) -> Complex64 {
145
             let integral = integrate(
146
                 evaluate function between(
147
                     self.phase.as_ref(),
```

```
148
149
                      self.turning_point_exp,
150
                      self.integration steps,
151
152
                 TRAPEZE PER THREAD,
153
             );
154
             let exp_sign = self.get_exp_sign();
155
156
             exp_sign * (self.c * 0.5 * (-integral.abs()).exp())
157
         }
158
     }
159
160
     impl Func<f64, Complex64> for WkbWaveFunction {
161
         fn eval(&self, x: f64) -> Complex64 {
162
             let val = if self.phase.energy < (self.phase.potential)(x) {</pre>
163
                  self.psi exp(x)
             } else {
164
165
                 self.psi_osz(x)
166
             };
167
168
             return (self.op)(val);
169
         }
170
171
172
     #[cfg(test)]
173
     mod test {
174
         use super::*;
175
         use std::cmp::Ordering;
176
         fn pot(x: f64) -> f64 {
177
178
             1.0 / (x * x)
179
         }
180
181
         fn pot_in(x: f64) -> f64 {
182
             1.0 / x.sqrt()
183
184
185
         #[test]
186
         fn phase off() {
187
             let energy cond = |e: f64| \rightarrow f64 \{ (0.5 * (e - 0.5)) % 1.0 \};
188
189
             let integ = Function::<f64, f64>::new(energy_cond);
             let mut values = evaluate_function_between(&integ, 0.0, 5.0, NUMBER_OF_POINTS
190
                  );
191
             let sort_func =
192
                  |p1: &Point<f64, f64>, p2: &Point<f64, f64>| -> Ordering { cmp_f64(&p1.x,
                       &p2.x) };
193
             values.sort_by(sort_func);
194
```

```
195
             let mut data_file = File::create("energy.txt").unwrap();
196
197
             let data str: String = values
198
                  .par iter()
199
                  .map(|p| \rightarrow String \{ format!("{}_{u}{}_{n}, p.x, p.y) \})
200
                  .reduce(|| String::new(), |s: String, current: String| s + &*current);
201
202
              data_file.write_all((data_str).as_ref()).unwrap()
203
         }
204 }
```

lib/build.sh

```
1 #! /bin/bash
2
3 go get main
4 go build -o libairy.a -buildmode=c-archive main.go
```

lib/go.mod

```
1 module main
2
3 go 1.18
4
5 require gonum.org/v1/gonum v0.11.0
```

lib/main.go

```
1 package main
 2
 3 import "C"
 4 import "gonum.org/v1/gonum/mathext"
 5
 6 //export airy_ai
 7
   func airy ai(zr float64, zi float64) (float64, float64) {
 8
        z := mathext.AiryAi(complex(zr, zi))
 9
        return real(z), imag(z)
10 }
11
12
    func main() {
13
14
```

build.rs

```
1 use std::env;
2 use std::path::PathBuf;
3 use std::process::Command;
```

```
4
 5
    fn main() {
 6
        Command::new("sh")
 7
            .arg("build.sh")
 8
            .current_dir("./lib/")
 9
            .status()
10
            .unwrap();
11
12
        let path = "./lib";
13
        let lib = "airy";
14
15
        println!("cargo:rustc-link-search=native={}", path);
16
        println!("cargo:rustc-link-lib=static={}", lib);
17
18
        // The bindgen::Builder is the main entry point
19
        // to bindgen, and lets you build up options for
20
        // the resulting bindings.
21
        let bindings = bindgen::Builder::default()
22
            // The input header we would like to generate
23
            // bindings for.
24
            .header("lib/libairy.h")
25
            // Tell cargo to invalidate the built crate whenever any of the
26
            // included header files changed.
27
            .parse callbacks(Box::new(bindgen::CargoCallbacks))
28
            // Finish the builder and generate the bindings.
29
            .generate()
30
            // Unwrap the Result and panic on failure.
31
            .expect("Unable_to_generate_bindings");
32
33
        // Write the bindings to the $OUT_DIR/bindings.rs file.
        let out_path = PathBuf::from(env::var("OUT_DIR").unwrap());
34
35
36
            .write to file(out path.join("bindings.rs"))
37
            .expect("Couldn't_write_bindings!");
38
```

Cargo.toml

```
11 rayon = "1.5.3"
12 scilib = "0.5.0"
13 ordinal = "0.3.1"
14
15 [build-dependencies]
16 bindgen = "0.60.1"
```

energy.wsl

```
1 \quad \mathsf{m} = 1
 2 V[x] = x^2
 3
 4
    nthEnergy[n_] = Module[{energys, energy},
 5
        energys = Solve[Integrate[Sqrt[2*m*(en - V[x])], {x, -Sqrt[en], Sqrt[en]}] == 2*
            Pi*(n + 1/2), en] // N;
 6
        energy = en /. energys[[1]];
 7
        energy
 8
        ]
 9
10 energys = Table[\{n, N@nthEnergy[n]\}, \{n, 0, 50\}]
11
12 csv = ExportString[energys, "CSV"]
13 csv = StringReplace[csv, "," -> " "]
14 Export["output/energys_exact.dat", csv]
```

exact.wsl

```
1 c1 = -5.0
 2 c2 = 1.0
 3 \quad numberOfPoints = 1000
 4 m = 2
 5
 6 viewFactor = 1.5
 7
 8 \ V[x_] := x^2
 9
10 energys = Solve[Integrate[Sqrt[2*m*(en - V[x])], {x, -Sqrt[en], Sqrt[en]}] == 2*Pi*(n
        + 1/2), en] // N
11
    energy = en /. energys[[1]]
12
13 view = Solve[energy == V[x], x]
14 view = Function[l, x /. l] /@ view
15 view = Function[x, x*viewFactor] /@ view
16
17
18 Print["Energy = ", energy]
19 Print["view = ", view]
20
21
```

```
22 solution := DSolve[\{V[x] psi[x] - psi''[x]/(2 m) == energy psi[x]\}, psi[x], x]
23 psi[x] = psi[x] /. solution[[1]] /. C[1] -> c1 /. C[2] -> c2
24
25 Print["psi[x] = ", psi[x]]
26
27
    (*psi[x_] = c2*ParabolicCylinderD[(-1 - 50*Sqrt[m])/2, *)
              (*I*2^{(3/4)*m^{(1/4)*x}} + c1*ParabolicCylinderD[(-1 + 50*Sqrt[m])/2, *)
28
29
              (*2^{(3/4)}*m^{(1/4)}*x]*)
30
31
32
33
    step = (Abs[view[[1]]] + Abs[view[[2]]]) / numberOfPoints
34
35
36 vals = Table[\{x, N@psi[x]\}, \{x, view[[1]], view[[2]], step\}]
37 vals = Function[p, \{p[[1]], Re[p[[2]]\}, Im[p[[2]]]\}\}] /@ vals
38 Print["psi[0] = ", psi[0]]
39
40 total = N@Integrate[Re[psi[x]]^2 + Im[psi[x]]^2, {x, -Sqrt[energy], Sqrt[energy]}]
41
42 Print["area under solution = ", total]
43 total = N@Integrate[Abs[psi[x]], {x, -Sqrt[energy], Sqrt[energy]}]
44 Print["area under solution after renormalization = ", N@Integrate[Re[psi[x]]^2 + Im[
        psi[x]]^2, {x, -Sqrt[energy], Sqrt[energy]}]]
45
46
    vals = Function[p, {p[[1]], p[[2]] / total, p[[3]] / total}] /@ vals
47
48 csv = ExportString[vals, "CSV"]
49 csv = StringReplace[csv, "," -> " "]
50 Export["output/exact.dat", csv]
```

Bildquellen

Wo nicht anders angegeben, sind die Bilder aus dieser Arbeit selbst erstellt worden.

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Selbständigkeitserklärung

Hiermit bestätige ich, Gian Laager, meine Maturaarbeit selbständig verfasst und alle Quellen angegeben zu haben.

Ich nehme zur Kenntnis, dass meine Arbeit zur Überprüfung der korrekten und vollständigen Angabe der Quellen mit Hilfe einer Software (Plagiaterkennungstool) geprüft wird. Zu meinem eigenen Schutz wird die Software auch dazu verwendet, später eingereichte Arbeiten mit meiner Arbeit elektronisch zu vergleichen und damit Abschriften und eine Verletzung meines Urheberrechts zu verhindern. Falls Verdacht besteht, dass mein Urheberrecht verletzt wurde, erkläre ich mich damit einverstanden, dass die Schulleitung meine Arbeit zu Prüfzwecken herausgibt.

Ort	Datum	Unterschrift
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