

Artificial Intelligence, Blockchain, e Criptovalute nello Sviluppo Software

Lezioni 10, 11 e 12: Fondamenti di Data Science per
l'analisi dello sviluppo software

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Content

- Linear Regression
- Correlation and Covariance
- Toward Inference



Part 1

Linear Regression



Linear Regression – Problem 1

- Suppose that:
 - I want to relate two random scalar phenomena, X and Y , to identify the relationships existing between them,
 - I can measure their values several times i , so I can have a set of pairs (x_i, y_i) with i spanning the interval of observation, say $i \in [0 \dots n - 1]$

i	\mathbf{X}	\mathbf{Y}
0	1	3
1	2	4
2	5	4
3	6	-1
4	7	5
5	9	8



Linear Regression – Problem 2

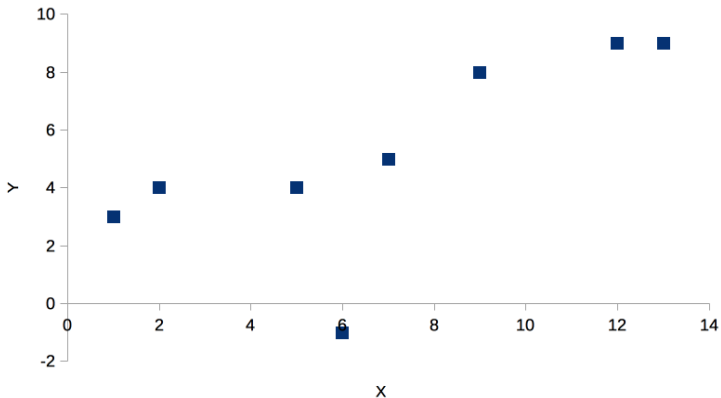
Using a simple and common approach, I may try to build a relationship between the two phenomena. However:

- What kind of relationships I am going to look for?
- How do I build it?



Linear Regression – Problem 3

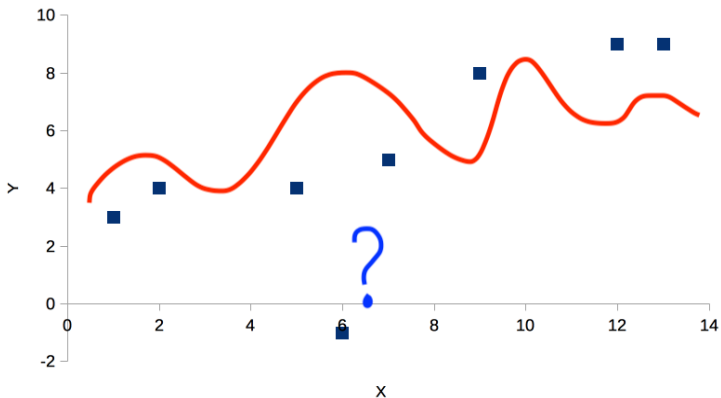
In other words, I have this set of points:





Linear Regression – Problem 4

How can I build a line that represent the relationships between these two sets?





Linear Regression – Definition

We need to define:

- A **mean function** that represents the relationship that I hypothesize between the phenomena X and Y
- A **cost-minimization function** to define the parameters of the mean function

We will use initially:

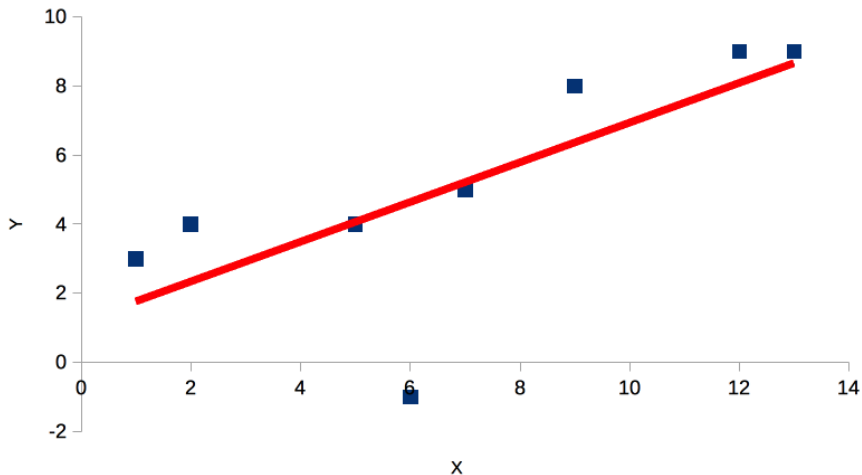
- As **mean function** the simple line
- As **cost function** the square of the errors between the modeled values and the real values

We define **Ordinary Least Squares (OLS) Linear Regression** as a simple line that minimizes a square error between modelled values and real values.



Linear Regression – Goal

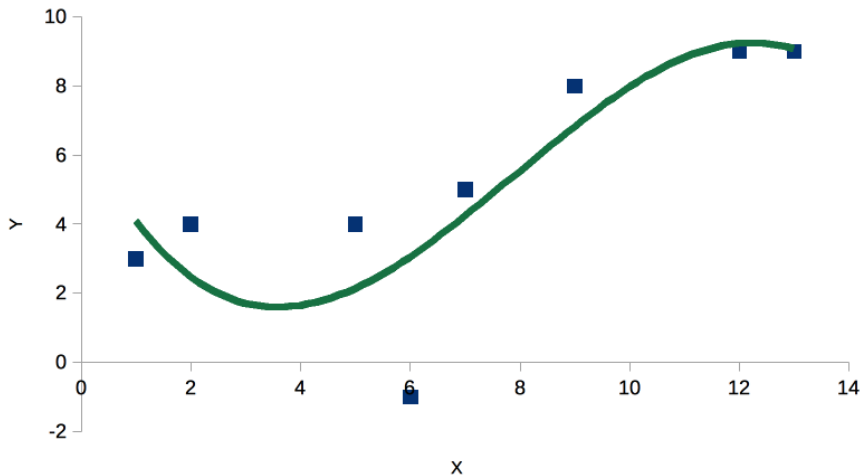
This is what we would like to build:





Linear Regression – Alternative Goal 1

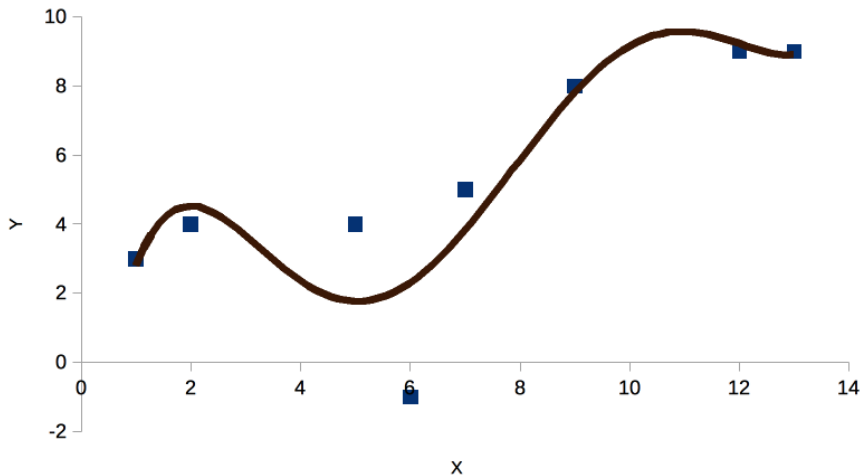
But we could have used as a mean function a cubic function:





Linear Regression – Alternative Goal 2

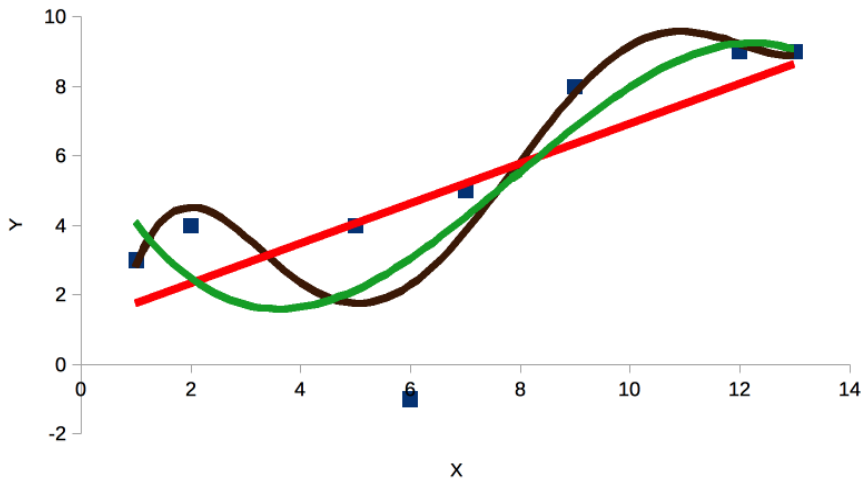
But we could have used as a mean function a fifth order function:





Linear Regression – All Goals

What are the differences between all these 3?





Linear Regression – Formula (1/3)

I want to build a model of the kind:

$$Y = \theta_0 + \theta_1 X$$

Where X and Y are the phenomena that we are measuring.

Note:

- we know that there is no line passing for n arbitrary points with $n \leq 3$
- we need to introduce an approximation

$$\hat{Y} = \theta_0 + \theta_1 \hat{X} + \epsilon$$

- in our case ϵ is the error that is introduced by the approximation
- as we said, our cost function, our distance from the model, will be the square of the error ϵ^2
- θ_0 and θ_1 are called the **regression coefficients**



Linear Regression – Formula (2/3)

Altogether:

- we have a set of pairs (x_i, y_i) with $i \in [0 \dots n - 1]$
- we want to build n linear equations of the kind (the mean function):

$$y_i = \theta_0 + \theta_1 x_i + \epsilon_i$$

- and we start with an approximation of the kind:

$$\hat{y}_i = \theta_0 + \theta_1 x_i$$



Linear Regression – Formula (3/3)

Altogether:

- our goal is to compute θ_0 and θ_1 that minimize the quadratic error (the cost function)

$$\sum_{i=0}^{n-1} \epsilon_i^2$$

- notice that:
 - we will denote as (x_i, y_i) the original data
 - we will denote as (\hat{x}_i, \hat{y}_i) the approximation that we obtain in the linear regression
 - x_i and \hat{x}_i are the same
 - there could be errors in the slides and you get extra credits by finding them



Linear Regression – Computation

- Since

$$y_i = \theta_0 + \theta_1 x_i + \epsilon_i$$

- therefore

$$\epsilon_i = y_i - \theta_0 - \theta_1 x_i$$

- we need to minimize:

$$\sum_{i=0}^{n-1} \epsilon_i^2 = \sum_{i=0}^{n-1} (y_i - \theta_0 - \theta_1 x_i)^2$$

- we need to zero the two partial derivatives:

$$\frac{\partial \sum_{i=0}^{n-1} (y_i - \theta_0 - \theta_1 x_i)^2}{\partial \theta_i}$$

- so we have to solve two simple equations and then to check the Hessian



Linear Regression – Computation for θ_0

$$\frac{\partial \sum_{i=0}^{n-1} (y_i - \theta_0 - \theta_1 x_i)^2}{\partial \theta_0} = 0 \Rightarrow$$

$$2 \sum_{i=0}^{n-1} (y_i - \theta_0 - \theta_1 x_i) = 0 \Rightarrow$$

$$\sum_{i=0}^{n-1} (y_i - \theta_0 - \theta_1 x_i) = 0$$



Linear Regression – Computation for θ_1

$$\frac{\partial \sum_{i=0}^{n-1} (y_i - \theta_0 - \theta_1 x_i)^2}{\partial \theta_1} = 0 \Rightarrow$$

$$2 \sum_{i=0}^{n-1} x_i (y_i - \theta_0 - \theta_1 x_i) = 0 \Rightarrow$$

$$\sum_{i=0}^{n-1} x_i (y_i - \theta_0 - \theta_1 x_i) = 0$$



Linear Regression – From the first equation

From the first equation:

$$\sum_{i=0}^{n-1}(\theta_0) = \sum_{i=0}^{n-1}(y_i - \theta_1 x_i) \Rightarrow$$

$$\sum_{i=0}^{n-1}(\theta_0) = \sum_{i=0}^{n-1}(y_i) - \theta_1 \sum_{i=0}^{n-1}(x_i) \Rightarrow$$

$$n\theta_0 = n\bar{y} - n\theta_1\bar{x} \Rightarrow$$

$$\theta_0 = \bar{y} - \theta_1\bar{x}$$



Linear Regression – In the second equation

$$\sum_{i=0}^{n-1} x_i(y_i - \theta_0 - \theta_1 x_i) = 0 \Rightarrow$$

$$\sum_{i=0}^{n-1} x_i y_i - \theta_0 \sum_{i=0}^{n-1} x_i - \theta_1 \sum_{i=0}^{n-1} x_i^2 = 0 \Rightarrow$$

$$\sum_{i=0}^{n-1} x_i y_i - n\theta_0 \bar{x} - n\theta_1 \bar{x}^2 = 0 \Rightarrow$$



Linear Regression – Combining the result

Substituting $\theta_0 = \bar{y} - \theta_1 \bar{x}$:

$$\sum_{i=0}^{n-1} x_i y_i - n(\bar{y} - \theta_1 \bar{x}) \bar{x} - n\theta_1 \bar{x}^2 = 0 \Rightarrow$$

$$\sum_{i=0}^{n-1} x_i y_i - n\bar{y}\bar{x} + n\theta_1 \bar{x}^2 - n\theta_1 \bar{x}^2 = 0$$

$$n\theta_1(\bar{x}^2 - \bar{x}^2) = \sum_{i=0}^{n-1} x_i y_i - n\bar{y}\bar{x}$$



Linear Regression – Final step

$$\theta_1 = \frac{\sum_{i=0}^{n-1} x_i y_i - n \bar{y} \bar{x}}{n(\bar{x}^2 - \bar{x}^2)}$$

$$\theta_1 = \frac{\frac{\sum_{i=0}^{n-1} x_i y_i}{n} - \bar{y} \bar{x}}{(\bar{x}^2 - \bar{x}^2)}$$

$$\theta_1 = \frac{Cov(x, y)}{Var(x)}$$

Which we can also write as:

$$\theta_1 = \frac{\sum_{i=0}^{n-1} (x_i - \bar{x})(y_i - \bar{y})}{\sum_{i=0}^{n-1} (x_i - \bar{x})^2}$$



Going back to our exercise...

Using the formula above we obtain that for the following dataset:

i	\mathbf{X}	\mathbf{Y}
0	1	3
1	2	4
2	5	4
3	6	-1
4	7	5
5	9	8
6	12	9
7	13	9

We have an equation:

$$\hat{Y} = \theta_0 + \theta_1 \hat{X}$$

with:

- $\theta_0 = 1.179$
- $\theta_1 = 0.574$



Our model

i	\mathbf{X}	\mathbf{Y}	\hat{Y}	ϵ
0	1	3	1.753	1.247
1	2	4	2.327	1.673
2	5	4	4.049	-0.049
3	6	-1	4.623	-5.623
4	7	5	5.197	-0.197
5	9	8	6.345	1.655
6	12	9	8.067	0.933
7	13	9	8.641	0.359



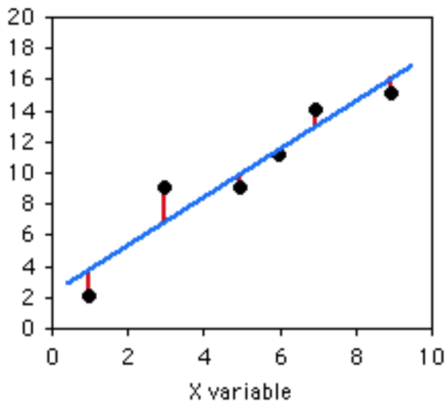
Linear Regression – Exercise

Build a linear regression for the following dataset:

X	Y
1	2
3	9
5	9
6	11
7	14
9	15



Linear Regression – Exercise





Linear Regression – Exercise

The regression equation for these numbers is $\hat{y} = 2.0286 + 1.5429x$. Now, fill the blanks using such equation and calculate the sum of squared deviations (last column).

x	y	Predicted y (\hat{y})	Deviate from predicted (abs.)	Squared deviate
1	2			
3	9			
5	9			
6	11			
7	14			
9	15			



Linear Regression – Exercise

Results. The sum of squared deviations: 10.8

x	y	Predicted y (\hat{y})	Deviate from predicted (abs.)	Squared deviate
1	2	3.57	1.57	2.46
3	9	6.66	2.34	5.48
5	9	9.74	0.74	0.55
6	11	11.29	0.29	0.08
7	14	12.83	1.17	1.37
9	15	15.91	0.91	0.83



Linear Regression – Modeling

In fact, we might think to use linear regression to model phenomena, assuming a linear dependence between input (the collected parameters) and output.

Here are some “real world” examples (w.r.t. certain assumptions):

- - Impact of SAT Score (or GPA) on College Admissions;
- - Impact of product price on number of sales;
- - Impact of rainfall amount on the number of fruits yielded;
- - Impact of blood alcohol content on coordination.



Linear Regression – Evaluation

We can evaluate the quality of linear regression, i.e. assess how good the model for the data that we have:

- - by the sum of squares of residuals;
- - by the coefficient of determination.



The sum of squared errors

The sum of squares of residuals, also called the residual sum of squares:

$$SS_{res} = \sum_i (y_i - \hat{y}_i)^2$$

In the case above SS_{res} is equal to 39.751672.



The coefficient of determination (R^2)

The coefficient of determination describes the proportion of variance of the dependent variable explained by the regression model. If the regression model is “perfect”, SS_{res} is zero, and R^2 is 1.

$$R^2 = 1 - \frac{SS_{res}}{SS_{tot}}$$

The total sum of squares:

$$SS_{tot} = \sum_i (y_i - \bar{y})^2$$

where

$$\bar{y} = \frac{1}{n} \sum_{i=1}^n y_i$$



In the example above

$$SS_{tot} = \sum_i (y_i - \bar{y})^2 = 82.875$$

Remember that:

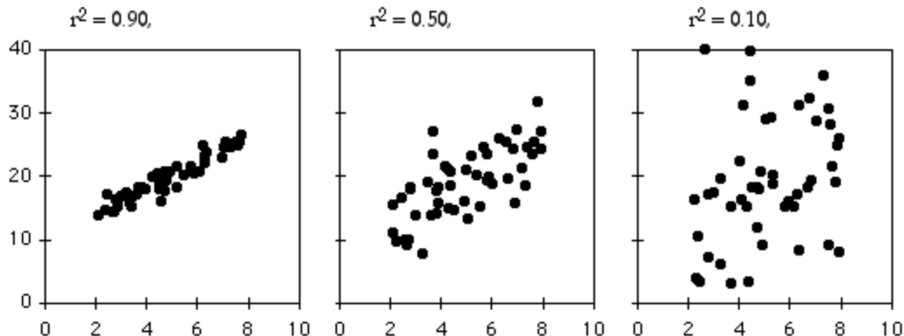
$$SS_{res} = \sum_i (y_i - \hat{y}_i)^2 = 39.751672$$

Therefore:

$$R^2 = 1 - \frac{SS_{res}}{SS_{tot}} = 1 - \frac{39.751672}{82.875} = 0.5203$$



Coefficient of determination (R^2)





Multivariate Linear Regression

- The “X” variable is often called “feature” in machine learning.
- Indeed, we could have multiple features, say, n .
- If we also have m observations, we could build a system of m equations of the kind:

$$y_i = \boldsymbol{\theta}^T \cdot \mathbf{x}_i + \epsilon_i, i = 1 \dots m$$

- and then we will build our linear regression (approximation) as:

$$\hat{y}_i = \boldsymbol{\theta}^T \cdot \hat{\mathbf{x}}_i, i = 1 \dots m$$

- where \mathbf{x}_i and $\hat{\mathbf{x}}_i$ are vectors of $n + 1$ features for the i -th observation

Question: Why here we use $n + 1$?



A closed-form solution of Linear Regression

To find the value of θ , there is a closed-form solution, a mathematical equation that gives the result directly.

This is called the **Normal Equation**:

$$\theta = (\mathbf{X} \cdot \mathbf{X}^T)^{-1} \cdot \mathbf{X}^T \cdot \mathbf{y}$$



Derivation of the closed-form solution (1/4)

- We start considering a set of m equations of the form:

$$\hat{y}_i = \boldsymbol{\theta}^T \mathbf{x}_i, i = 1 \dots m$$

- where \mathbf{x}_i has dimension $n + 1$
- We move all the model in matrix format:

$$\hat{\mathbf{y}} = \mathbf{X} \cdot \boldsymbol{\theta}$$

- Notice that $\hat{\mathbf{y}}$ and \mathbf{y} have dimension $(m,1)$, \mathbf{X} $(m,n+1)$, and $\boldsymbol{\theta}$ $(n+1,1)$. $\mathbf{X} \cdot \boldsymbol{\theta}$ has therefore dimension $(m,1)$ as it should be.
- The error vector $\boldsymbol{\epsilon}$ is defined for each pair as:

$$\boldsymbol{\epsilon} = \hat{\mathbf{y}} - \mathbf{y} = \mathbf{X} \cdot \boldsymbol{\theta} - \mathbf{y}$$

- And the square of the error is:



Derivation of the closed-form solution (2/4)

- To determine the values of the parameters we take the partial derivatives and we null them:

$$\frac{\partial(\mathbf{X} \cdot \boldsymbol{\theta} - \mathbf{y})^T(\mathbf{X} \cdot \boldsymbol{\theta} - \mathbf{y})}{\partial \boldsymbol{\theta}} = 0$$

- Now we evaluate:

$$\begin{aligned} & \frac{\partial(\mathbf{X} \cdot \boldsymbol{\theta} - \mathbf{y})^T(\mathbf{X} \cdot \boldsymbol{\theta} - \mathbf{y})}{\partial \boldsymbol{\theta}} = \\ &= \frac{\partial((\mathbf{X} \cdot \boldsymbol{\theta})^T(\mathbf{X} \cdot \boldsymbol{\theta}) - (\mathbf{X} \cdot \boldsymbol{\theta})^T \mathbf{y} - \mathbf{y}^T \mathbf{X} \cdot \boldsymbol{\theta} + \mathbf{y}^T \mathbf{y})}{\partial \boldsymbol{\theta}} = \\ &= \frac{\partial((\mathbf{X} \cdot \boldsymbol{\theta})^T(\mathbf{X} \cdot \boldsymbol{\theta}) - 2(\mathbf{X} \cdot \boldsymbol{\theta})^T \mathbf{y} + \mathbf{y}^T \mathbf{y})}{\partial \boldsymbol{\theta}} \end{aligned}$$



Derivation of the closed-form solution (3/4)

- Now we can consider that:

$$\frac{\partial(\mathbf{y}^T \mathbf{y})}{\partial \boldsymbol{\theta}} = 0$$

- that:

$$\frac{\partial((\mathbf{X} \cdot \boldsymbol{\theta})^T \mathbf{y})}{\partial \boldsymbol{\theta}} = \mathbf{X}^T \mathbf{y}$$

- Notice that $\mathbf{X}^T \mathbf{y}$ has dimension $(n+1, m) \cdot (m, 1)$, that is, $(n+1, 1)$.
- and finally that:

$$\frac{\partial((\mathbf{X} \cdot \boldsymbol{\theta})^T (\mathbf{X} \cdot \boldsymbol{\theta}))}{\partial \boldsymbol{\theta}} = 2\mathbf{X}^T \mathbf{X} \boldsymbol{\theta}$$

- Notice that $\mathbf{X}^T \mathbf{X} \boldsymbol{\theta}$ has dimension $(n+1, m) \cdot (m, n+1) \cdot (n+1, 1)$, that is, $(n+1, 1)$ as it should be.



Derivation of the closed-form solution (4/4)

- Substituting the results in the original formula:

$$2\mathbf{X}^T \mathbf{X} \boldsymbol{\theta} - 2\mathbf{X}^T \mathbf{y} = 0 \Rightarrow$$

$$\mathbf{X}^T \mathbf{X} \boldsymbol{\theta} = \mathbf{X}^T \mathbf{y} \Rightarrow$$

- Notice that $\mathbf{X}^T \mathbf{X}$ has dimension $(n+1, m) \cdot (m, n+1)$, that is, $(n+1, n+1)$. Notice that $m \gg n$, so we *hope* that $\mathbf{X}^T \mathbf{X}$ is invertible.

$$\boldsymbol{\theta} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$

- QED.



Computational complexity

The Normal Equation computes the inverse of $X^T \cdot X$, which is an $n \times n$ matrix (where n is the number of features).

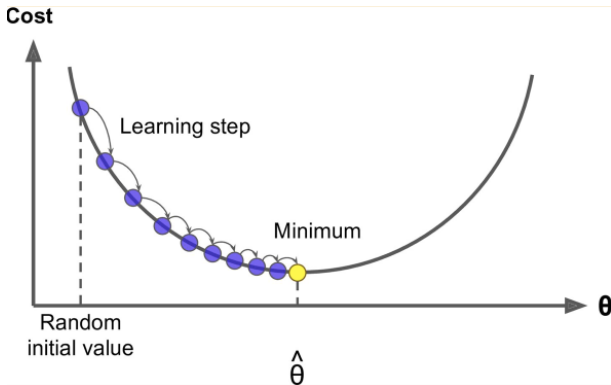
The computational complexity of inverting such a matrix is typically about $O(n^{2.4})$ to $O(n^3)$ (depending on the implementation).

In other words, if you double the number of features, you multiply the computation time by roughly $2^{2.4} = 5.3$ to $2^3 = 8$.



Linear Regression – Approximation

Gradient Descent is a very generic optimization algorithm capable of finding optimal solutions to a wide range of problems. The general idea of Gradient Descent is to tweak parameters iteratively in order to minimize a cost function.





Gradient Descent - Computation

To implement Gradient Descent, you need to compute the gradient of the MSE cost function with regards to each model parameter θ_j .
Mean squared error (MSE) cost function for a Linear Regression model:

$$MSE(\theta) = \frac{1}{m} \sum_{k=1}^m (\boldsymbol{\theta}^T \cdot \mathbf{x}^{(k)} - \mathbf{y}^{(k)})^2$$

$\mathbf{x}^{(k)}$ - k-th observation vector ($\mathbf{x}^{(k)}$ is an n-dimensional vector)



Gradient Descent - Computation

To implement Gradient Descent, you need to compute the gradient of the MSE cost function with regards to each model parameter θ_j .

$$\frac{\partial}{\partial \theta_j} MSE(\theta) = \frac{2}{m} \sum_{i=1}^m (\theta^T \cdot \mathbf{x}^{(i)} - \mathbf{y}^{(i)}) x_j^{(i)}$$



Gradient Descent - Computation

In vector form:

$$\nabla_{\theta} MSE(\theta) = \frac{2}{m} \mathbf{X}^T (\mathbf{X} \cdot \boldsymbol{\theta} - \mathbf{y})$$

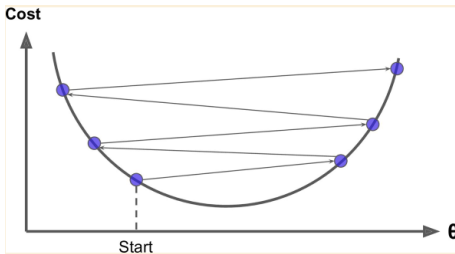
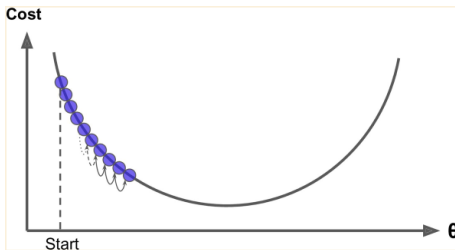
We update vector $\boldsymbol{\theta}$ step by step:

$$\boldsymbol{\theta}^{next} = \boldsymbol{\theta} - \eta \nabla_{\theta} MSE(\theta)$$

η – learning rate

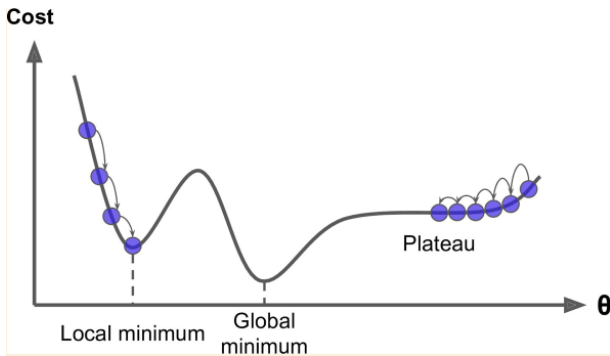


Learning rate





Pitfalls of Gradient Descent





Linear Regression and Machine Learning

Linear Regression is a statistical model developed in the field of Regression Analysis.

Later it was borrowed for the use of Machine Learning field.

Terminology difference

Regression analysis	Machine Learning
estimation, fitting	training, learning
regressors	features
response	target



References

- 1) <http://www.cs.umd.edu/~djacobs/CMSC426/Convolution.pdf>
- 2) https://www.researchgate.net/post/Difference_between_convolution_and_correlation
- 3) https://www.tutorialspoint.com/signals_and_systems/convolution_and_correlation.htm



Part 2

Correlation and Covariance



Content

- Covariance
- Correlation (aka Pearson product-moment correlation coefficient)
- Relationship between Pearson correlation and linear regression



Covariance

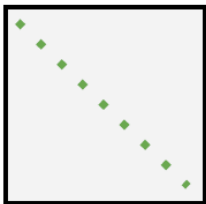
- To proceed further with our analysis we will use the concept of **covariance**, which we have already seen
- It expresses the degree in which the variation of a random variable is connected to the variation of another random variable
- It is defined as follows:
 - Given two random variables X and Y

$$\text{Cov}(X, Y) = E[(X - E(X))(Y - E(Y))]$$



Covariance – graphically

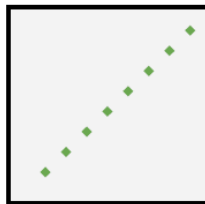
COVARIANCE



Large Negative
Covariance



Nearly Zero
Covariance



Large Positive
Covariance

Source : *https:*

//www.geeksforgeeks.org/mathematics-covariance-and-correlation



About the covariance - 1

• We notice that:

- The covariance of a random variable with itself is the variance:

$$\text{Cov}(X, X) = \text{Var}(X)$$

- There is a similar property as for the variance

$$\text{Cov}(X, Y) = E(XY) - E(X)E(Y)$$

since:

$$\begin{aligned}\text{Cov}(X, Y) &= E[(X - E(X))(Y - E(Y))] = \\ &= E(XY) - E(XE(Y)) - E(E(X)Y) + E(E(X)E(Y)) = \\ &= E(XY) - E(X)E(Y) - E(X)E(Y) + E(X)E(Y) = \\ &= E(XY) - E(X)E(Y)\end{aligned}$$

QED.



About the covariance - 2

- The covariance is symmetric:

$$\text{Cov}(X, Y) = \text{Cov}(Y, X)$$

- The covariance is linear with respect to multiplications by constants:

$$(\forall a, b \in \mathbb{R}) \quad \text{Cov}(aX, bY) = ab\text{Cov}(X, Y)$$

- If $e \sim N(0, \sigma)$, $\text{Cov}(X, e) = 0$

$$\text{Cov}(X, e) = E(Xe) - E(X)E(e)$$

Since X and e are independent

$$E(Xe) = E(X)E(e)$$

Moreover, $e \sim N(0, \sigma)$

$$E(e) = 0$$



Pearson Correlation Coefficient

- AKA Pearson product-moment correlation coefficient or just correlation coefficient
- It expresses the linear correlation between two random variables
- It is defined as follows:
 - Given two random variables X and Y

$$r_{X,Y} = \frac{Cov(X, Y)}{\sigma_X \sigma_Y}$$

- Where:

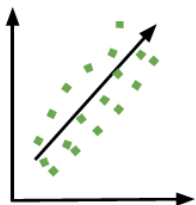
$$\sigma_Z = \sqrt{Var(Z)}$$

For the time being we intentionally ignore the difference between sample and population.

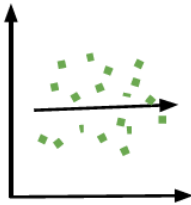


Pearson Correlation Coefficient – graphically

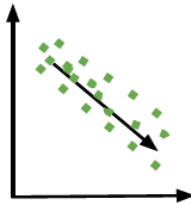
CORRELATION



Positive
Correlation



Zero
Correlation



Negative
Correlation

Source : [https:](https://www.geeksforgeeks.org/mathematics-covariance-and-correlation)

[//www.geeksforgeeks.org/mathematics-covariance-and-correlation](https://www.geeksforgeeks.org/mathematics-covariance-and-correlation)



About the Pearson Correlation Coefficient

- The Pearson correlation coefficient is also often expressed as:

$$r_{X,Y} = \frac{\sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})}{\sqrt{\sum_{i=1}^n (x_i - \bar{x})^2 \sum_{i=1}^n (y_i - \bar{y})^2}}$$

- It is symmetric: $r_{X,Y} = r_{Y,X}$
- It is invariant with respect to multiplications by, and additions of constants:
 $(\forall a, b, c, d \in \mathbb{R}, b \neq 0, d \neq 0) \quad r_{X,Y} = r_{(a+bX), (c+dY)}$
- It ranges from -1 to 1: $-1 \leq r_{X,Y} \leq 1$
 $r_{X,Y} = 1$ means perfect linear relationship (all points lie on a monotonically increasing line)
 $r_{X,Y} = -1$ means perfect opposite linear relationship (all points lie on a monotonically decreasing line)
 $r_{X,Y} = 0$ means no linear relationship between X and Y



Back to Linear Regression (1/2)

- We now focus our attention to the case of the linear regression
- Suppose we have two phenomena that we want to measure, X and Y
- Let us assume
 - that there is a linear relationship between them
 - that I can express the data I collect as:

$$y = \theta_0 + X\theta_1 + \epsilon$$

- where ϵ is a stationary gaussian process $N(0, \sigma^2)$
- We know the solution that minimizes the square error



Back to Linear Regression (2/2)

- From this solution we have extracted the coefficient of determination

$$R^2 = 1 - \frac{SS_{res}}{SS_{tot}}$$

- Where:

- $SS_{res} = \sum_i (y_i - \hat{y}_i)^2$
- SS_{res} is the distance between the reality and the 1-degree best approximation, that is, the OLS model

- and

- $SS_{tot} = \sum_i (y_i - \bar{y})^2$
- SS_{tot} is the distance between the reality and the 0-degree best approximation, that is, the mean

- I want to know the relationship between R^2 and the correlation coefficient between X and Y , $r_{X,Y}$



Our goal – understanding R and r

- We focus on 1D
- We are now going to prove a fundamental point.
- Under the assumption that the noise is gaussian and centered in 0, in a linear regression:

$$R^2 = r_{X,Y}^2$$



$$R^2 = r_{X,Y}^2 (1/4)$$

- Since

$$\hat{y} = \theta_0 + \theta_1 x$$

- we have from above (see page 56) that:

$$r_{X,Y} = r_{\hat{Y},Y}$$

- We define now the explained sum of squares (ESS)
 - $ESS = \sum_i (\hat{y}_i - \bar{y})^2$
 - ESS is the additional knowledge we get on the random variable using a polynomial of degree 1 vs. using a polynomial of degree 0
- We will now prove that **under our hypotheses**:

$$ESS + SS_{res} = SS_{tot}$$



$$[R^2 = r_{X,Y}^2] - ESS + SS_{res} = SS_{tot} \quad (1/6)$$

- We start from:

$$(y_i - \bar{y}) = (y_i - \hat{y}_i) + (\hat{y}_i - \bar{y})$$

- which we square:

$$(y_i - \bar{y})^2 = (y_i - \hat{y}_i)^2 + 2(y_i - \hat{y}_i)(\hat{y}_i - \bar{y}) + (\hat{y}_i - \bar{y})^2$$

- and then we sum:

$$\sum_i (y_i - \bar{y})^2 = \sum_i (y_i - \hat{y}_i)^2 + \sum_i 2(y_i - \hat{y}_i)(\hat{y}_i - \bar{y}) + \sum_i (\hat{y}_i - \bar{y})^2$$

Source with modifications:

https://en.wikipedia.org/wiki/Explained_sum_of_squares



$$[R^2 = r_{X,Y}^2] - ESS + SS_{res} = SS_{tot} \quad (2/6)$$

- Now we focus on:

$$\sum_i 2(y_i - \hat{y}_i)(\hat{y}_i - \bar{y}) = 2 \sum_i (y_i - \hat{y}_i)(\hat{y}_i - \bar{y})$$

- and we want to prove that it is 0, that is $\sum_i (y_i - \hat{y}_i)(\hat{y}_i - \bar{y}) = 0$; considering:

$$y_i = \hat{y}_i + \epsilon_i$$

$$E(y_i) = E(\hat{y}_i + \epsilon_i) = E(\hat{y}_i) + E(\epsilon_i) = E(\hat{y}_i)$$

because ϵ is a stationary gaussian process $N(0, \sigma^2)$

Source with modifications:

https://en.wikipedia.org/wiki/Explained_sum_of_squares



$$[R^2 = r_{X,Y}^2] - ESS + SS_{res} = SS_{tot} \quad (3/6)$$

- We can build a system:

$$\begin{cases} \hat{y}_i = \theta_0 + \theta_1 x_i \\ \bar{y} = \theta_0 + \theta_1 \bar{x} \end{cases}$$

- from which we deduce by subtraction:

$$\hat{y}_i - \bar{y} = \theta_1(x_i - \bar{x})$$

- remembering that:

$$\theta_1 = \frac{Cov(x, y)}{Var(x)} = \frac{\sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})}{\sum_{i=1}^n (x_i - \bar{x})^2}$$

Source with modifications: https://en.wikipedia.org/wiki/Explained_sum_of_squares



$$[R^2 = r_{X,Y}^2] - ESS + SS_{res} = SS_{tot} \quad (4/6)$$

• So:

$$\begin{aligned} \sum_i (y_i - \hat{y}_i)(\hat{y}_i - \bar{y}) &= \sum_i (y_i - \hat{y}_i)(\theta_1(x_i - \bar{x})) = \\ &= \theta_1 \sum_i (y_i - \hat{y}_i)(x_i - \bar{x}) \end{aligned}$$

• Now, let's consider that:

$$\begin{aligned} (y_i - \hat{y}_i) &= y_i - \hat{y}_i + \bar{y} - \bar{y} = (y_i - \bar{y}) - (\hat{y}_i - \bar{y}) = \\ &= (y_i - \bar{y}) - \theta_1(x_i - \bar{x}) \end{aligned}$$

• Substituting $(y_i - \hat{y}_i)$ above we get:

$$\theta_1 \sum_i (y_i - \hat{y}_i)(x_i - \bar{x}) = \theta_1 \sum_i [(y_i - \bar{y}) - \theta_1(x_i - \bar{x})](x_i - \bar{x})$$

Source with modifications:

https://en.wikipedia.org/wiki/Explained_sum_of_squares



$$[R^2 = r_{X,Y}^2] - ESS + SS_{res} = SS_{tot} \quad (5/6)$$

- We can conclude:

$$\begin{aligned} & \theta_1 \sum_i [(y_i - \bar{y}) - \theta_1(x_i - \bar{x})](x_i - \bar{x}) = \\ &= \theta_1 \left[\sum_i (y_i - \bar{y})(x_i - \bar{x}) - \sum_i \theta_1(x_i - \bar{x})(x_i - \bar{x}) \right] = \\ &= \theta_1 \left[\sum_i (y_i - \bar{y})(x_i - \bar{x}) - \sum_i \frac{\sum_j (x_j - \bar{x})(y_j - \bar{y})}{\sum_j (x_j - \bar{x})^2} (x_i - \bar{x})^2 \right] = \end{aligned}$$

Source with modifications:

https://en.wikipedia.org/wiki/Explained_sum_of_squares



$$[R^2 = r_{X,Y}^2] - ESS + SS_{res} = SS_{tot} \quad (6/6)$$

• And simplifying what is in [•]:

$$\begin{aligned} & \sum_i (y_i - \bar{y})(x_i - \bar{x}) - \sum_i \frac{\sum_j (x_j - \bar{x})(y_j - \bar{y})}{\sum_j (x_j - \bar{x})^2} (x_i - \bar{x})^2 = \\ &= \sum_i (y_i - \bar{y})(x_i - \bar{x}) - \sum_j (x_j - \bar{x})(y_j - \bar{y}) \sum_i \frac{(x_i - \bar{x})^2}{\sum_j (x_j - \bar{x})^2} = \\ &= \sum_i (x_i - \bar{x})(y_i - \bar{y}) - \sum_j (x_j - \bar{x})(y_j - \bar{y}) \frac{\sum_i (x_i - \bar{x})^2}{\sum_j (x_j - \bar{x})^2} = \\ &= \sum_i (x_i - \bar{x})(y_i - \bar{y}) - \sum_j (x_j - \bar{x})(y_j - \bar{y}) = 0 \end{aligned}$$

QED.

Source with modifications:

https://en.wikipedia.org/wiki/Explained_sum_of_squares



$$R^2 = r_{X,Y}^2 \quad (2/4)$$

- Now we know that, under the assumption to deal with a Gaussian noise centered in 0 we have:

$$ESS + SS_{res} = SS_{tot}$$

- Under this hypothesis we have:

$$R^2 = 1 - \frac{SS_{res}}{SS_{tot}} = \frac{SS_{tot} - SS_{res}}{SS_{tot}} = \frac{ESS}{SS_{tot}}$$



$$R^2 = r_{X,Y}^2 \quad (3/4)$$

- We now consider the square of $r_{X,Y} = r_{\hat{Y},Y}$

$$\begin{aligned} r_{\hat{Y},Y}^2 &= \left(\frac{\text{Cov}(\hat{Y}, Y)}{\sqrt{\text{Var}(Y)\text{Var}(\hat{Y})}} \right)^2 = \frac{\text{Cov}(\hat{Y}, Y)\text{Cov}(\hat{Y}, Y)}{\text{Var}(Y)\text{Var}(\hat{Y})} = \\ &= \frac{\text{Cov}(\hat{Y}, \hat{Y} + \epsilon)\text{Cov}(\hat{Y}, \hat{Y} + \epsilon)}{\text{Var}(Y)\text{Var}(\hat{Y})} = \\ &= \frac{(\text{Cov}(\hat{Y}, \hat{Y}) + \text{Cov}(\hat{Y}, \epsilon))(\text{Cov}(\hat{Y}, \hat{Y}) + \text{Cov}(\hat{Y}, \epsilon))}{\text{Var}(Y)\text{Var}(\hat{Y})} = \\ &= \frac{\text{Cov}(\hat{Y}, \hat{Y})\text{Cov}(\hat{Y}, \hat{Y})}{\text{Var}(Y)\text{Var}(\hat{Y})} \end{aligned}$$

Source with modifications:

<https://economicstheoryblog.com/2014/11/05/proof/>



$$R^2 = r_{X,Y}^2 \quad (4/4)$$

- But we know that $Cov(\hat{Y}, \hat{Y}) = Var(\hat{Y})$, therefore we get that

$$\begin{aligned} r_{X,Y}^2 &= \frac{Var(\hat{Y})Var(\hat{Y})}{Var(Y)Var(\hat{Y})} = \frac{Var(\hat{Y})}{Var(Y)} = \\ &= \frac{\frac{\sum_i (\hat{y}_i - \bar{\hat{y}})^2}{n}}{\frac{\sum_i (y_i - \bar{y})^2}{n}} = \frac{\sum_i (\hat{y}_i - \bar{\hat{y}})^2}{\sum_i (y_i - \bar{y})^2} = \frac{ESS}{SS_{tot}} \end{aligned}$$

since we have already proven that $\bar{y} = \bar{\hat{y}}$

QED

Source with modifications:

<https://economictheoryblog.com/2014/11/05/proof/>



Comment on $R^2 = r_{X,Y}^2$

- This is a major result
- It is the center of our subsequent investigation, in the case of normality of error we can model, interconnect, and understand relationships in an easy way
- The next question is on how the slope of the regression line (θ_1) relates to the correlation coefficient $r_{X,Y}$



$r_{X,Y}$ and θ_1

- We know that:

$$\theta_1 = \frac{Cov(X, Y)}{Var(X)}$$

- And that:

$$r_{X,Y} = \frac{Cov(X, Y)}{\sigma_X \sigma_Y}$$

- Therefore:

$$\theta_1 Var(X) = r_{X,Y} \sigma_X \sigma_Y$$

- We can then conclude that:

$$\theta_1 = \frac{\sigma_X \sigma_Y}{Var(X)} r_{X,Y}$$

$$r_{X,Y} = \frac{Var(X)}{\sigma_X \sigma_Y} \theta_1$$



Comment on $r_{X,Y} \sim \theta_1$

- $r_{X,Y}$ and θ_1 are therefore directly and monotonically proportional
- It means that a positive relationship implies a positive slope and viceversa



General remark

- Right now we work with samples of larger populations of data
- We measure properties of samples, like mean, standard deviation, covariance, correlation coefficient
- All these properties are also random variable and have a distribution
- Our question is therefore, what kind of distribution is the one of the correlation coefficient
- Knowing its distribution allows us to understand the relationships existing between the variables it connect



Part 3

Toward Inference



Content

- Premises of the Law of Large Numbers
- Markov's inequality
- Chebyshev's inequality
- Proof of the Law of Large Numbers



Last words...

- Right now we work with samples of larger populations of data
- We measure properties of samples, like mean, standard deviation, covariance, correlation coefficient
- All these properties are also random variable and have a distribution
- Our question is therefore, what kind of distribution is the one of the correlation coefficient
- Knowing its distribution allows us to understand the relationships existing between the variables it connect



Knowing the sample ...

- What can we infer of populations now that I know the properties of the sample?
- Now we know the mean, the standard deviation, the distribution of the sample, what would be the mean, the standard deviation, and the distribution of the population?
- Moreover, from two samples we can build a regression, what would be the regression of the population?



We start from the mean

- Now we start from the mean
- We suppose that we have an unknown population \mathfrak{P} of entities on a ratio scale from which we extract n samples \mathfrak{S}_i with $i \in [1 \dots n]$
- Each sample i is composed by n_i elements $e_{i,j}$ with $j \in [1 \dots n_i]$
- We can compute the set of the means of each sample $\mathfrak{S}_i, \overline{m}_i$ with $i \in [1 \dots n]$
- \overline{m}_i is a random variable, so we would like to know what is its structure
- There are two fundamental theorems in statistics that provide the distributions of such \overline{m}_i , the Law of Large Numbers (LLN) and the Central Limit Theorem (CLT)
- Since we are not making **any** assumption on the population Π , we can just ignore it and consider simply a sequence of random variables, which we will call x_i assuming that there is



LLN – Premises

- From now on, we will use the notation “iid” to denote the property of a set of random variables to be independent and identically distributed
- Let $\{\mathfrak{X}n_1, \mathfrak{X}n_2, \dots, \mathfrak{X}n_n\}$ a set of n iid random variables drawn from a population with mean μ**
- Each $\mathfrak{X}n_i$ could be considered the average of a sample \mathfrak{S}_i of size 1, that is $\mathfrak{S}_i = \{\mathfrak{X}n_i\}$
- Let us consider $\overline{\mathfrak{X}n}$, the average for this sample of size n**
- $\overline{\mathfrak{X}n}$ is like the average of the n averages of each sample \mathfrak{S}_i

Source with modifications:

https://en.wikipedia.org/wiki/Law_of_large_numbers



LLN – Weak formulation

- Let $\{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n\}$ a set of n iid random variables drawn from a population with mean μ
- Let us consider $\overline{\mathbf{x}_n}$, the average for this sample of size n
- the Law of Large Number in its weak formulation states that:

$$(\forall \epsilon \in \mathbb{R}^+) \quad \lim_{n \rightarrow \infty} \mathbb{P}(|\overline{\mathbf{x}_n} - \mu| > \epsilon) = 0$$

- This means that $\overline{\mathbf{x}_n}$ tends to get the value of μ probabilistically

Source with modifications:

https://en.wikipedia.org/wiki/Law_of_large_numbers



LLN – Proof (1/4)

- We are now going to prove LLN
- To do so, we need to prove two other interesting theorems:
 - The Markov's inequality
 - The Chebyshev's inequality

Source with modifications:

https://en.wikipedia.org/wiki/Law_of_large_numbers



[LLN – Proof] Markov's inequality (1/3)

- The Markov's inequality put a first boundary on the distribution of a random variable
- Let $X \geq 0$ be a random variable with mean $\mu \in \mathbb{R}$
- Then:

$$(\forall k \in \mathbb{R}^+) \quad \mathbb{P}(X \geq k) \leq \frac{\mu}{k}$$

- Proof:

$$\mu = \int_{-\infty}^{+\infty} x f_x(x) dx$$

Source with modifications:

https://en.wikipedia.org/wiki/Markov%27s_inequality



[LLN – Proof] Markov's inequality (2/3)

- Since $X \geq 0$

$$\int_{-\infty}^{+\infty} x f_x(x) dx = \int_0^{+\infty} x f_x(x) dx =$$

And given $k \in \mathbb{R}^+$

$$= \int_0^k x f_x(x) dx + \int_k^{+\infty} x f_x(x) dx$$

Since $\int_0^k x f_x(x) dx \geq 0$

$$\mu \geq \int_k^{+\infty} x f_x(x) dx \geq k \int_k^{+\infty} f_x(x) dx = \mathbb{P}(X \geq k)$$

Source with modifications:

https://en.wikipedia.org/wiki/Markov%27s_inequality



[LLN – Proof] Markov's inequality (3/3)

- Therefore we have

$$\mu \geq k\mathbb{P}(X \geq k)$$

- And from this we conclude:

$$\mathbb{P}(X \geq k) \leq \frac{\mu}{k}$$

Source with modifications:

https://en.wikipedia.org/wiki/Markov%27s_inequality



[LLN – Proof] Chebyshev's inequality (1/3)

- The Chebyshev's inequality put a further limit on the distribution of a random variable
- Let X be a random variable with mean $\mu \in \mathbb{R}$ and variance $\sigma^2 > 0$
- Then:

$$(\forall k \in \mathbb{R}^+) \quad \mathbb{P}(|X - \mu| \geq k\sigma) \leq \frac{1}{k^2}$$

- Proof:

Let us define a new random variable

$$Y = (X - \mu)^2 \geq 0$$

Let us define

$$h = (k\sigma)^2$$

Source with modifications:

https://en.wikipedia.org/wiki/Chebyshev%27s_inequality



[LLN – Proof] Chebyshev's inequality (2/3)

- By the Markov inequality we have for the nonnegative random variable Y and for the positive real h :

$$\mathbb{P}(Y \geq h) \leq \frac{\overline{Y}}{h}$$

- And this means:

$$\mathbb{P}((X - \mu)^2 \geq (k\sigma)^2) \leq \frac{\overline{(X - \mu)^2}}{(k\sigma)^2} = \frac{\sigma^2}{k^2\sigma^2} = \frac{1}{k^2}$$

Source with modifications:

https://en.wikipedia.org/wiki/Chebyshev%27s_inequality



[LLN – Proof] Chebyshev's inequality (3/3)

- This can be rewritten into:

$$\mathbb{P}(|X - \mu| \geq |k\sigma|) \leq \frac{1}{k^2}$$

- Since we know that both k and σ are strictly positive:

$$\mathbb{P}(|X - \mu| \geq k\sigma) \leq \frac{1}{k^2}$$

QED

Source with modifications:

https://en.wikipedia.org/wiki/Chebyshev%27s_inequality



LLN – Proof (2/4)

- We want to prove that:

$$(\forall \epsilon \in \mathbb{R}^+) \quad \lim_{n \rightarrow \infty} \mathbb{P}(|\overline{\mathfrak{X}}_n - \mu| > \epsilon) = 0$$

- we add the additional hypothesis that $\sigma_i > 0$
- Let us consider σ_i ;
 - since the variables \mathfrak{X}_{n_i} are iid

$$(\forall i, j) \quad (\sigma_i = \sigma_j = \sigma)$$

- we also assume that $\sigma > 0$
- finally, since the variables \mathfrak{X}_{n_i} are independent of one another:

$$\text{Var}(\overline{\mathfrak{X}}_n) = \frac{\sigma^2}{n} = \mathfrak{s}_n^2$$

Source with modifications:

https://en.wikipedia.org/wiki/Chebyshev%27s_inequality



LLN – Proof (3/4)

- Let us define:

$$k = \frac{\epsilon}{s_n}$$

k exists, since s_n is strictly positive; therefore:

$$\epsilon = k s_n$$

- By Chebyshev's inequality we have:

$$\mathbb{P}(|\overline{\mathfrak{X}}_n - \mu| \geq k s_n) \leq \frac{1}{k^2}$$

- That is:

$$\mathbb{P}(|\overline{\mathfrak{X}}_n - \mu| \geq \epsilon) \leq \frac{s_n^2}{\epsilon^2}$$

Source with modifications:

https://en.wikipedia.org/wiki/Chebyshev%27s_inequality



LLN – Proof (4/4)

- Since:

$$\mathfrak{s}_n^2 = \frac{\sigma^2}{n}$$

- We have that

$$\lim_{n \rightarrow \infty} \frac{\mathfrak{s}_n^2}{\epsilon^2} = \lim_{n \rightarrow \infty} \frac{\sigma^2}{n\epsilon^2} = \frac{\sigma^2}{\epsilon^2} \lim_{n \rightarrow \infty} \frac{1}{n} = 0$$

- Therefore:

$$\lim_{n \rightarrow \infty} (\mathbb{P}(|\overline{\mathfrak{X}}_n - \mu| \geq \epsilon)) \leq \lim_{n \rightarrow \infty} \frac{\mathfrak{s}_n^2}{\epsilon^2} = 0 \Rightarrow \lim_{n \rightarrow \infty} (\mathbb{P}(|\overline{\mathfrak{X}}_n - \mu| \geq \epsilon)) = 0$$

QED

Source with modifications:

https://en.wikipedia.org/wiki/Chebyshev%27s_inequality



Lecture 14

Content:

- Central Limit Theorem in the Linderberg-Lévy formulation
- Moment
- Moment generating function
- Proof of the Central Limit Theorem in the Linderberg-Lévy formulation
- Final comment



CLT – Lindeberg–Lévy formulation

- Let $\{\mathbf{X}_1, \mathbf{X}_2, \dots, \mathbf{X}_n\}$ a set of n iid random variables drawn from a population with mean μ and standard deviation σ
- Let us consider for this sample of size n :
 - the mean, $\overline{\mathbf{X}}$
 - the variance, σ^2
 - the modulated difference, \mathfrak{D}_n , defined as:

$$\mathfrak{D}_n = \sqrt{n}(\overline{\mathbf{X}} - \mu)$$

- Central Limit Theorem (Lindeberg–Lévy formulation):

$$\mathfrak{D}_n \rightarrow N(0, \sigma^2)$$

- This means that \mathfrak{D}_n tends to be normal.

Source with modifications:

https://en.wikipedia.org/wiki/Central_limit_theorem



[CLT – LLf] Moment (1/2)

- To prove the CLT – LLf we need to introduce a few additional statistical concepts that could be useful also in the continuation of this course series
- We define the r^{th} **moment** of a random variable X as the expected value of the r^{th} power of X ; formally:

$$\mu_X(r) = E(X^r)$$

clearly: $\mu_X(1) = \mu_X = E(X)$

- Example:
 - If $P(X = 0) = 0.25$ and $P(X = 4) = 0.75$:
 $\mu_X(1) = 3$
 $\mu_X(2) = 12$
 $\mu_X(3) = 48$
 $\mu_X(4) = 192$

Source with modifications:

<https://www.statlect.com/fundamentals-of-probability/moments>



[CLT – LLf] Moment (2/2)

- We define the **central** r^{th} **moment** of a random variable X as the expected value of the r^{th} deviation of X ; formally:

$$\overline{\mu_X(r)} = E((X - \mu_X)^r)$$

clearly: $\overline{\mu_X(2)} = \sigma_X^2 = E((X - \mu_X)^2)$

- Example:
 - If $P(X = 0) = 0.25$ and $P(X = 4) = 0.75$:
$$\begin{aligned}\overline{\mu_X(1)} &= 0 \\ \overline{\mu_X(2)} &= 3 \\ \overline{\mu_X(3)} &= -6 \\ \overline{\mu_X(4)} &= 21\end{aligned}$$

Source with modifications:

<https://www.statlect.com/fundamentals-of-probability/moments>



[CLT – LLf] Mfg (1/10)

- Let X be a random variable defined over a set S and let f_X be its probability density function
- We define the **moment generating function (mgf)** M_X over X as:

$$M_X(t) = E(e^{tX}) = \int_S e^{tx} f_X(x) dx$$

if there exists $h \in \mathbb{R}^+$ so that $E(e^{tX})$ is defined in $(-h, +h)$

- Note that:
 - The mgf may not exist
 - The mgf has interesting properties

Source with modifications:

<https://onlinecourses.science.psu.edu/stat414/node/72/>



[CLT – LLf] Mgf (2/10)

- Mgf and first moment:

$$\left[\frac{dM_X(t)}{dt} \right] (t=0) = \mu_X(1) = \mu_X = E(X)$$

Since:

$$\begin{aligned} \left[\frac{dM_X(t)}{dt} \right] (t=0) &= \left[\frac{d \int_S e^{tx} f_X(x) dx}{dt} \right] (t=0) = \\ &= \left[\int_S x e^{tx} f_X(x) dx \right] (t=0) = \int_S x e^{0x} f_X(x) dx = \int_S x f_X(x) dx = \end{aligned}$$

Source with modifications:

<https://onlinecourses.science.psu.edu/stat414/node/73/>



[CLT – LLf] Mgf (3/10)

- In general:

$$\left[\frac{d^n M_X(t)}{dt^n} \right] (t=0) = \mu_X(n) = E(X^n)$$

- This comes from:

$$\frac{d^n M_X(t)}{dt^n} = \int_S x^n e^{tx} f_X(x) dx$$

- Proof. By induction, $n=1$, see above
- Let us assume that the proposition holds for $n-1$:

$$\frac{d^{n-1} M_X(t)}{dt^{n-1}} = \int_S x^{n-1} e^{tx} f_X(x) dx$$

Source with modifications:

<https://onlinecourses.science.psu.edu/stat414/node/73/>



[CLT – LLf] Mgf (4/10)

- We check it holds for n :

$$\begin{aligned}\frac{d^n M_X(t)}{dt^n} &= \frac{d \left[\frac{d^{n-1} M_X(t)}{dt^{n-1}} \right]}{dt} = \\ &= \frac{d \left[\int_S x^{n-1} e^{tx} f_X(x) dx \right]}{dt} = \int_S x^n e^{tx} f_X(x) dx\end{aligned}$$

QED

- This confirms:

$$\left[\frac{d^n M_X(t)}{dt^n} \right] (t = 0) = \mu_X(n) = E(X^n)$$

Source with modifications:

<https://onlinecourses.science.psu.edu/stat414/node/73/>



[CLT – LLf] Mgf (5/10)

- Mgf and second moment:

$$\sigma_X^2 = E(X^2) - (E(X))^2 = \left[\frac{d^2 M_X(t)}{dt^2} \right] (t=0) - \left\{ \left[\frac{dM_X(t)}{dt} \right] (t=0) \right\}^2$$

And if the mean is 0:

$$\sigma_X^2 = \left[\frac{d^2 M_X(t)}{dt^2} \right] (t=0)$$

Source with modifications:

<https://onlinecourses.science.psu.edu/stat414/node/73/>



[CLT – LLf] Mgf (6/10)

- Fundamental fact:

If the mgf for a random variable exists, it characterizes fully such random variable.

Proof: omitted.

- It means that mgf and pdf are interchangeable
- We need now to determine the mgf for a normally distributed random variable $N(0, \sigma^2)$
- We will then use this to prove the CLT – LLf
- Let Z be a random variable, $Z \sim N(0, 1)$ then, the mgf for Z is:

$$M_Z(t) = e^{\frac{1}{2}t^2}$$



[CLT – LLf] Mgf (7/10)

• Proof

$$\begin{aligned}M_Z(t) &= \int_{-\infty}^{+\infty} e^{zt} \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}z^2} dz = \int_{-\infty}^{+\infty} \frac{1}{\sqrt{2\pi}} e^{zt - \frac{1}{2}z^2} dz = \\&= \int_{-\infty}^{+\infty} \frac{1}{\sqrt{2\pi}} e^{\frac{1}{2}(2zt - z^2)} dz = \int_{-\infty}^{+\infty} \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}(z^2 - 2zt + t^2 - t^2)} dz = \\&= \int_{-\infty}^{+\infty} \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}(z^2 - 2zt + t^2)} e^{\frac{1}{2}t^2} dz = \int_{-\infty}^{+\infty} \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}(z-t)^2} e^{\frac{1}{2}t^2} dz \\&= e^{\frac{1}{2}t^2} \int_{-\infty}^{+\infty} \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}(z-t)^2} dz = e^{\frac{1}{2}t^2}\end{aligned}$$

QED

Source with modifications:

<https://www.le.ac.uk/users/dsgp1/COURSES/MATHSTAT/6normgf.pdf>



[CLT – LLf] Mgf (8/10)

Extending to the case of general Gaussian variables:

- Let X be a random variable, $X \sim N(\mu, \sigma_X^2)$, then the mgf for X is:

$$M_X(t) = e^{t\mu + \frac{1}{2}t^2\sigma_X^2}$$

- We can first define $Z = \frac{X-\mu}{\sigma_X}$ and $Z \sim N(0, 1)$

$$\begin{aligned} M_X(t) &= E(e^{tX}) = E(e^{t(\mu + \sigma_X Z)}) = E(e^{t\mu} e^{t\sigma_X Z}) = e^{t\mu} E(e^{t\sigma_X Z}) = \\ &= e^{t\mu} M_X(t\sigma_X) = e^{t\mu} e^{\frac{1}{2}t^2\sigma_X^2} = e^{t\mu + \frac{1}{2}t^2\sigma_X^2} \end{aligned}$$

QED

Source with modifications:

<https://www.quora.com/What-is-the-MGF-of-normal-distribution>



[CLT – LLf] Mgf (9/10)

The last piece of information that we miss are the following two properties:

- **Property 1: Moment of the Sum** Let $Y = \sum_{i=1}^{i=n} X_i$ where X_i are iid random variables then:

$$M_Y(t) = \prod_{i=1}^{i=n} M_{X_i}(t)$$

Proof:

$$\begin{aligned} M_Y(t) &= E(e^{tY}) = E(e^{t \sum_{i=1}^{i=n} X_i}) = E\left(\prod_{i=1}^{i=n} e^{tX_i}\right) = \\ &= \prod_{i=1}^{i=n} E(e^{tX_i}) = \prod_{i=1}^{i=n} M_{X_i}(t) \end{aligned}$$

QED



[CLT – LLf] Mgf (10/10)

- **Property 2: Moment of the LC** Let $Y = a + bX$ where X is a random variable and $a, b \in \mathbb{R}, b \neq 0$ then:

$$M_Y(t) = e^{at} M_X(bt)$$

Proof:

$$\begin{aligned} M_Y(t) &= E(e^{(a+bX)t}) = E(e^{at+bXt}) = E(e^{at}e^{bXt}) = e^{at}E(e^{bXt}) \\ &= e^{at}E(e^{btX}) = e^{at}M_X(bt) \end{aligned}$$

QED

- **Corollary:** the sum of randomly iid Gaussian r.v. is still Gaussian.

Source with modifications: <https://onlinecourses.science.psu.edu/stat414/node/170/> and <https://www.stat.berkeley.edu/~mlugo/stat134-f11/clt-proof.pdf>



CLT – LLf – Proof (1/7)

- Remember that we want to prove that:

$$\mathfrak{D}n dN(0, \sigma^2)$$

- This is like proving that:

$$\frac{\mathfrak{D}n}{\sigma} dN(0, 1)$$

- We can rewrite $\mathfrak{D}n/\sigma$:

$$\begin{aligned} \frac{\mathfrak{D}n}{\sigma} &= \frac{\sqrt{n}}{\sigma} (\overline{\mathfrak{X}n} - \mu) = \frac{\sqrt{n}}{\sigma} \left[\frac{\sum_{i=1}^{i=n} \mathfrak{X}n_i}{n} - \mu \right] = \frac{\sqrt{n}}{\sigma} \frac{\sum_{i=1}^{i=n} \mathfrak{X}n_i - n\mu}{n} \\ &= \frac{\sum_{i=1}^{i=n} \mathfrak{X}n_i - n\mu}{\sigma \sqrt{n}} \end{aligned}$$

Source with modifications: <https://www.stat.berkeley.edu/~mlugo/stat134-f11/clt-proof.pdf> and https://en.wikipedia.org/wiki/Central_limit_theorem



CLT – LLf – Proof (2/7)

- Note: We can assume that $\mu = 0$. If it is not, we could define a new set of variables $\mathfrak{Y}_i = \mathfrak{X}_i - \mu$ and we would have that:

$$\sum_{i=1}^{i=n} \mathfrak{X}_{n_i} - n\mu = \sum_{i=1}^{i=n} \mathfrak{Y}_i$$

Preserving the same proof.

- Let now define $\mathfrak{W}_n = \mathfrak{D}n/\sigma$

$$\mathfrak{W}_n = \frac{\sum_{i=1}^{i=n} \mathfrak{X}_{n_i}}{\sigma\sqrt{n}}$$

- We want to prove that $\mathfrak{W}_n \sim N(0, 1)$ demonstrating that its moment is the same as the one of $N(0, 1)$

Source with modifications: <https://www.stat.berkeley.edu/~mlugo/stat134-f11/clt-proof.pdf> and https://en.wikipedia.org/wiki/Central_limit_theorem



CLT – LLf – Proof (3/7)

- Note: We recall Property 1 (Slide ??) and 2 (Slide ??) about the momentum of combining random variables and we have:

$$M_{\mathfrak{D}_n}(t) = \left[M_{\mathfrak{x}_i} \left(\frac{t}{\sqrt{n}} \right) \right]^n$$

and likewise:

$$M_{\mathfrak{W}_n}(t) = M_{\mathfrak{D}_n} \left(\frac{t}{\sigma} \right) = \left[M_{\mathfrak{x}_i} \left(\frac{t}{\sigma\sqrt{n}} \right) \right]^n$$

- In essence we need to evaluate the limit for n going to infinite of $\left[M_{\mathfrak{x}_i} \left(\frac{t}{\sigma\sqrt{n}} \right) \right]^n$
- We want to prove that such limit is equal to the momentum of the standard normal distribution:

$$M_{N(0,1)}(t) = e^{\frac{1}{2}t^2}$$



CLT – LLf – Proof (4/7)

- For simplicity we take the natural logarithm:

$$\ln \left[M_{\mathbf{x}_i} \left(\frac{t}{\sigma\sqrt{n}} \right) \right]^n = n \ln \left[M_{\mathbf{x}_i} \left(\frac{t}{\sigma\sqrt{n}} \right) \right]$$

- Now we define

$$q = \frac{1}{\sqrt{n}}$$

Therefore n is $1/p^2$ and $n \rightarrow \infty \Rightarrow p \rightarrow 0$. This means that we want to compute:

$$\lim_{p \rightarrow 0} \frac{\ln M_{\mathbf{x}_i} \left(\frac{tp}{\sigma} \right)}{p^2} =$$

- This is an indeterminate form, so we can take the derivative of both side by the theorem of de l'Hôpital

Source with modifications: <https://www.stat.berkeley.edu/~mlugo/stat134-f11/clt-proof.pdf> and https://en.wikipedia.org/wiki/Central_limit_theorem



CLT – LLf – Proof (5/7)

- This results to:

$$= \lim_{p \rightarrow 0} \frac{\frac{1}{M_{\mathfrak{X}_i}(\frac{tp}{\sigma})} \frac{dM_{\mathfrak{X}_i}(\frac{tp}{\sigma})}{dp} \frac{t}{\sigma}}{2p} = \frac{t}{2\sigma} \lim_{p \rightarrow 0} \frac{\frac{dM_{\mathfrak{X}_i}(\frac{tp}{\sigma})}{dp}}{pM_{\mathfrak{X}_i}(\frac{tp}{\sigma})} =$$

- This is again an indeterminate form, so we can take the derivative of both side by the theorem of de l'Hôpital

$$= \frac{t}{2\sigma} \lim_{p \rightarrow 0} \frac{\frac{d^2 M_{\mathfrak{X}_i}(\frac{tp}{\sigma})}{dp^2} \frac{t}{\sigma}}{M_{\mathfrak{X}_i}(\frac{tp}{\sigma}) + p \frac{dM_{\mathfrak{X}_i}(\frac{tp}{\sigma})}{dp} \frac{t}{\sigma}} = \frac{t^2}{2\sigma^2} \lim_{p \rightarrow 0} \frac{\frac{d^2 M_{\mathfrak{X}_i}(\frac{tp}{\sigma})}{dp^2}}{M_{\mathfrak{X}_i}(\frac{tp}{\sigma}) + p \frac{dM_{\mathfrak{X}_i}(\frac{tp}{\sigma})}{dp} \frac{t}{\sigma}}$$

- We now take the limits at numerator and denominator and we are done.

Source with modifications: <https://www.stat.berkeley.edu/~mlugo/stat134-f11/clt-proof.pdf> and https://en.wikipedia.org/wiki/Central_limit_theorem



CLT – LLf – Proof (6/7)

- Numerator:

$$\begin{aligned}\lim_{p \rightarrow 0} \frac{d^2 M_{\mathfrak{X}_i}(\frac{tp}{\sigma})}{dp^2} &= \left[\frac{d^2 M_{\mathfrak{X}_i}(\frac{tp}{\sigma})}{dp^2} \right] (0) = E(\mathfrak{X}_i^2) = \\ &= E(\mathfrak{X}_i)^2 + Var(\mathfrak{X}_i) = 0 + \sigma^2 = \sigma^2\end{aligned}$$

- Denominator:

$$\begin{aligned}\lim_{p \rightarrow 0} \left[M_{\mathfrak{X}_i}(\frac{tp}{\sigma}) + p \frac{dM_{\mathfrak{X}_i}(\frac{tp}{\sigma})}{dp} \frac{t}{\sigma} \right] &= M_{\mathfrak{X}_i}(0) + 0 \left[\frac{dM_{\mathfrak{X}_i}(\frac{tp}{\sigma})}{dp} \frac{t}{\sigma} \right] (0) = \\ &= M_{\mathfrak{X}_i}(0) = 1\end{aligned}$$

Source with modifications: <https://www.stat.berkeley.edu/~mlugo/stat134-f11/clt-proof.pdf> and https://en.wikipedia.org/wiki/Central_limit_theorem



CLT – LLf – Proof (7/7)

- And now we pull everything together and we obtain:

$$\lim_{p \rightarrow 0} \frac{\ln M_{\mathfrak{X}_i}(\frac{tp}{\sigma})}{p^2} = \frac{t^2}{2\sigma^2} \frac{\sigma^2}{1} = \frac{t^2}{2}$$

- And, therefore

$$\lim_{n \rightarrow +\infty} M_{\mathfrak{W}_n}(t) = e^{\frac{1}{2}t^2}$$

QED

Source with modifications: <https://www.stat.berkeley.edu/~mlugo/stat134-f11/clt-proof.pdf> and https://en.wikipedia.org/wiki/Central_limit_theorem



Status

- Now we know that the means of samples of a population tend to be distributed normally.
- This is an essential assumption to perform several numeric operations, like Montecarlo simulations, Bootstrap, etc.
- We can now understand the distribution of the Pearson momentum correlation coefficient of the sample
- Moreover, we have an open infinite issue on what to do if the data is NOT on a ratio scale
- This is an open issue for followup courses