

# Contiki OS

Giacomo Tanganelli  
PhD student @ University of Pisa  
[g.tanganelli@iet.unipi.it](mailto:g.tanganelli@iet.unipi.it)



# WSN Operating Systems

- The OS hides many HW details
  - Simplify the programmer life
- Contains drivers to radio and sensors, scheduling, network stacks, process & power management
- TinyOS, **Contiki**, FreeRTOS, Mantis OS

# Contiki overview



- Contiki is a dynamic operating system for constrained devices
- Event driven kernel
  - Protothreads on top of it
- Support for many platform
  - Tmote Sky, Zolertia Z1, MicaZ ...
- Support for many CPU

# Contiki core



- Is based on an enhanced event handler:
  - Loop that just takes the next event and processes it
  - Nothing to do->goes to sleep (MCU low power mode)
- Set of services
  - Networking, storage, timers ...



# Event vs Thread

- Event driven kernel only use events
  - Difficult to program
  - No sequential flow of control
  - Low overhead
- Threads
  - Easy to program
  - Sequential flow of control
  - High overhead (more stacks)

# Protothreads



- Single stack
- Sequential flow of control
- Do not save local variable state across blocking calls
  - Overcome by use static variables

# Protothreads



```
int a_protothread(struct pt *pt) {  
    PT_BEGIN(pt);
```

```
    PT_WAIT_UNTIL(pt, condition1);
```

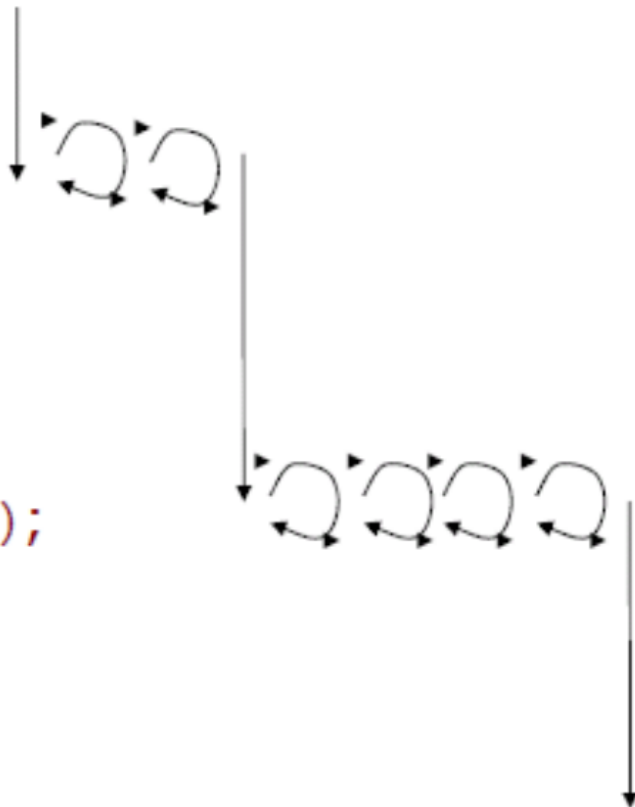
```
    if(something) {
```

```
        PT_WAIT_UNTIL(pt, condition2);
```

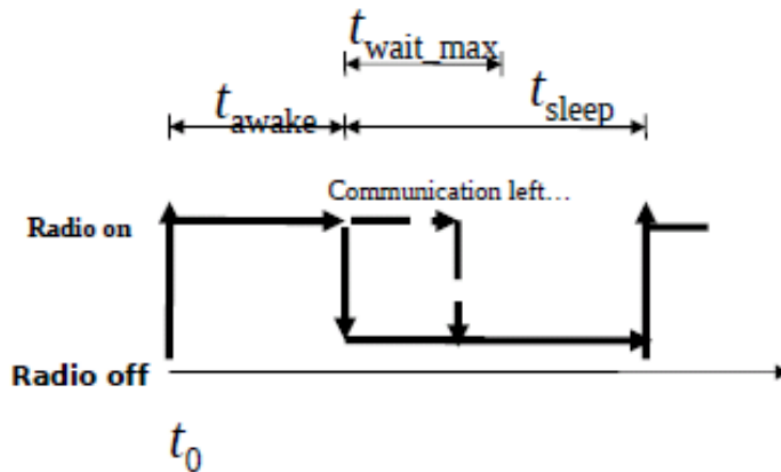
```
    }
```

```
    PT_END(pt);
```

```
}
```



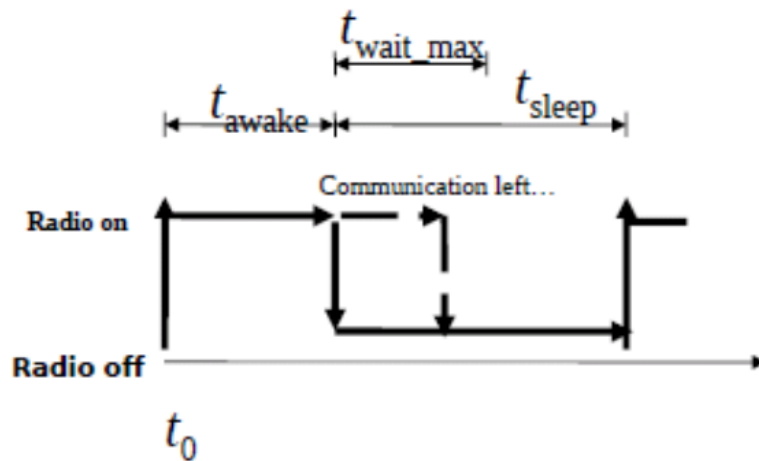
# Protothreads



1. Turn radio on.
2. Wait until  $t = t_0 + t_{\text{awake}}$ .
3. If communication has not completed, wait until it has completed or  $t = t_0 + t_{\text{awake}} + t_{\text{wait\_max}}$ .
4. Turn the radio off. Wait until  $t = t_0 + t_{\text{awake}} + t_{\text{sleep}}$ .
5. Repeat from step 1.



# Protothreads



```
int protothread(struct pt *pt) {
    PT_BEGIN(pt);
    while(1) {
        radio_on();
        timer = t_await;
        PT_WAIT_UNTIL(pt, expired(timer));
        timer = t_sleep;
        if(!comm_complete()) {
            wait_timer = t_wait_max;
            PT_WAIT_UNTIL(pt, comm_complete()
                          || expired(wait_timer));
        }
        radio_off();
        PT_WAIT_UNTIL(pt, expired(timer));
    }
    PT_END(pt);
}
```

# Processes



- Processes are protothreads
- `PROCESS_THREAD` defines a new process
- Must start with `PROCESS_BEGIN()`
- Must end with `PROCESS_END()`
- Wait for new event:
  - `PROCESS_WAIT_EVENT()`
  - `PROCESS_WAIT_EVENT_UNTIL(condition c)`

# Contiki directories



- core
  - System source code
- apps
  - System apps
- platform
  - Platform-specific code
    - Default mote configuration
- cpu
  - CPU-specific code
- example
  - Lots of examples. **USE** it as a starting point.
- tools
  - Cooja and other useful stuff

# Hello World



```
#include "contiki.h"
#include <stdio.h>
/* Declare the process */
PROCESS(hello_world_process, "Hello world");
/* Make the process start when the module is loaded */
AUTOSTART_PROCESSES(&hello_world_process);

/* Define the process code */
PROCESS_THREAD(hello_world_process, ev, data) {
    PROCESS_BEGIN(); /* Must always come first */
    printf("Hello, world!\n"); /* code goes here. All printf must end
with \n */
    PROCESS_END(); /* Must always come last */
}
```

# Makefile



```
CONTIKI_PROJECT = hello-world
```

```
all: $(CONTIKI_PROJECT)
```

```
CONTIKI = /home/user/contiki
```

```
include $(CONTIKI)/Makefile.include
```

# project-conf.h



- Used to override default configurations
- Add to Makefile

```
CFLAGS += -DPROJECT_CONF_H=\"project-conf.h\"
```
- Example: change RDC protocol

```
#define NETSTACK_CONF_RDC nullrdc_driver
```
- See `platform/z1/contiki-conf.h`



# Run a program on a mote

- Compile
  - make TARGET=z1 hello-world
- Upload to the mote
  - make TARGET=z1 hello-world.upload
- Useful stuff
  - make TARGET=z1 savetarget
    - Save a default target for the project
  - make motelist
    - Display the motes connected to the PC
  - make login
    - View the program output

# Timers



- struct timer
    - Passive timer, only keeps track of its expiration time
  - struct etimer
    - Active timer, sends an event when it expires
  - struct ctimer
    - Active timer, calls a function when it expires
  - struct rtimer
    - Real-time timer, calls a function at an exact time.
- Reserved for OS internals





# POST and WAIT

- `PROCESS_WAIT_EVENT();`
  - Waits for an event to be posted to the process
- `PROCESS_WAIT_EVENT_UNTIL(condition c);`
  - Waits for an event to be posted to the process, with an extra condition. Often used: wait until timer has expired
  - `PROCESS_WAIT_EVENT_UNTIL(etime_expired(&timer));`
- `PROCESS_POST(...)` and `PROCESS_POST_SYNCH(..)`
  - Post (a)synchronous event to a process.
  - The other process usually waits with `PROCESS_WAIT_EVENT_UNTIL(ev == EVENTNAME);`

# Sensors



```
#include "dev/button-sensor.h"
```

```
#include "dev/leds.h"
```

```
SENSORS_ACTIVATE(button_sensor);
```

```
PROCESS_WAIT_EVENT_UNTIL(ev==sensors_event &&  
data==&button_sensor);
```

```
leds_toggle(LED_ALL);
```

See [example/sky/test-button.c](#)

# Exercise 1



- Write a program that loops indefinitely, check if a button has been pressed, and if so, toggles LEDs and prints out a message.



# Timer functions

```
static struct etimer et;  
etimer_set(&et, CLOCK_SECOND*4);  
  
PROCESS_WAIT_EVENT();  
If(etimer_expired(&et)){  
    etimer_reset(&et);  
}
```

# Exercise 2 & 3



- Write a program that loops indefinitely, check if the timer has expired, and if so, toggles LEDs and prints out a message.
- Write a program that loops indefinitely, waits for an event, check if a button has been pressed, toggles LEDs and prints out “Button Press!”. If, instead, the timer has expired toggles LEDs and prints out “Timer!”