

# Calculus 2 Exercises

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# Disclaimer

This document contains the solutions to the exercise sheets provided by Professor Alla during the ACSAI Calculus 2 course that was given during the Academic Year 2024/2025.

Keep in mind, however, that these solutions are **not** official and may therefore contain mistakes, so it is suggested to double check eventual computations.

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# Chapter 1

## Exercise Sheet 1: Domain and limits of functions in two variables

### 1.1 Exercise 1

Define the domain of the following functions:

- $f(x, y) = \ln(4 - 4x^2 - y^2)$

$$\Omega : 4 - 4x^2 - y^2 > 0 \Rightarrow \Omega : 4x^2 - y^2 < 4$$

**N.B.:** Observe that the domain is an ellipse with semi-axes 1 and 2.

- $f(x, y) = \sqrt{x^3 - y} + \frac{1}{y - \ln x}$

$$\Omega : \begin{cases} x^3 - y \geq 0 \\ y - \ln x \neq 0 \\ x > 0 \end{cases} \Rightarrow \Omega : \begin{cases} y \leq x^3 \\ y \neq \ln x \\ x > 0 \end{cases}$$

- $f(x, y) = \ln\left(\frac{y-x^2}{x-y}\right)$

$$\Omega : \begin{cases} \frac{y-x^2}{x-y} > 0 \\ x-y \neq 0 \end{cases} \Rightarrow \Omega : \begin{cases} y-x^2 > 0 \\ x-y > 0 \\ x-y \neq 0 \end{cases} \vee \begin{cases} y-x^2 < 0 \\ x-y < 0 \\ x-y \neq 0 \end{cases}$$

$$\Omega : \begin{cases} y > x^2 \\ y < x \\ y \neq x \end{cases} \vee \begin{cases} y < x^2 \\ y > x \\ y \neq x \end{cases}$$

- $f(x, y) = \sqrt{x^2 - y^2} + \ln(x^2 + y^2)$

$$\Omega : \begin{cases} x^2 - y^2 \geq 0 \\ x^2 + y^2 > 0 \end{cases} \Rightarrow \Omega : \begin{cases} -|x| \leq y \leq |x| \\ (x, y) \neq (0, 0) \end{cases}$$

## 1.2 Exercise 2

Show that the following limits do not exist and verify that, using polar coordinates, the result depends on the value of  $\theta$ :

- $\lim_{(x,y) \rightarrow (0,0)} \frac{2y^2}{x^2 + y^2}$

$$\lim_{(x,y) \rightarrow (0,0)} \frac{2y^2}{x^2 + y^2} = \frac{0}{0}$$

Consider the path  $y = mx$ , and recompute the limit in terms of  $x \rightarrow 0$ :

$$\lim_{x \rightarrow 0} \frac{2(mx)^2}{x^2 + (mx)^2} = \lim_{x \rightarrow 0} \frac{2m^2x^2}{x^2(1 + m^2)} = \frac{2m^2}{1 + m^2}$$

Notice that the limit does not exist because depends on the value of  $m$ . Indeed, if the limit is computed in polar coordinates, it is possible to show that:

$$\lim_{\rho \rightarrow 0} \frac{2\rho^2 \sin^2 \theta}{\rho^2 \cos^2 \theta + \rho^2 \sin^2 \theta} = \lim_{\rho \rightarrow 0} \frac{2\rho^2 \sin^2 \theta}{\rho^2} = 2 \sin^2 \theta$$

Therefore, it is possible to conclude that this limit does not exist as it depends on the value of  $\theta$ .

- $\lim_{(x,y) \rightarrow (0,0)} \frac{x^2 - 2xy + y^3}{x^2 + y^2}$

$$\lim_{(x,y) \rightarrow (0,0)} \frac{x^2 - 2xy + y^3}{x^2 + y^2} = \frac{0}{0}$$

Consider the path  $y = mx$ , and recompute the limit in terms of  $x \rightarrow 0$ :

$$\lim_{x \rightarrow 0} \frac{x^2 - 2x(mx) + (mx)^3}{x^2 + (mx)^2} = \lim_{x \rightarrow 0} \frac{x^2(1 - 2m + m^3x)}{x^2(1 + m^2)} = \frac{1 - 2m}{1 + m^2}$$

Notice that the limit does not exist because it depends on the value of  $m$ . Indeed, if the limit is computed in polar coordinates, it is possible to show that:

$$\lim_{\rho \rightarrow 0} \frac{\rho^2 \cos^2 \theta - 2\rho \cos \theta \rho \sin \theta + \rho^3 \sin^3 \theta}{\rho^2 \cos^2 \theta + \rho^2 \sin^2 \theta} = \lim_{\rho \rightarrow 0} \frac{\rho^2(\cos^2 \theta - 2 \cos \theta \sin \theta + \rho \sin^3 \theta)}{\rho^2} = \cos^2 \theta - \sin 2\theta$$

Therefore, it is possible to conclude that this limit does not exist as it depends on the value of  $\theta$ .

### 1.3 Exercise 3

Compute the following limits:

- $\lim_{(x,y) \rightarrow (0,0)} \frac{x(e^{xy}-1)}{x^2+y^2}$

Start by applying special limits for asymptotic approximation:

$$\lim_{t \rightarrow 0} \frac{e^t - 1}{t} = 1 \Rightarrow e^t - 1 \approx t, \text{ meaning that } e^{xy} - 1 \approx xy$$

Therefore, it is possible to simplify computations:

$$\lim_{(x,y) \rightarrow (0,0)} \frac{x^2 y}{x^2 + y^2} = \frac{0}{0}$$

Solve the limit by switching to polar coordinates:

$$\lim_{\rho \rightarrow 0} \frac{\rho^2 \cos^2 \theta \rho \sin \theta}{\rho^2 \cos^2 \theta + \rho^2 \sin^2 \theta} = \lim_{\rho \rightarrow 0} \frac{\rho^3 \cos^2 \theta \sin \theta}{\rho^2} = \lim_{\rho \rightarrow 0} \rho \cos^2 \theta \sin \theta = 0 \quad \forall \theta \in [0, 2\pi]$$

- $\lim_{(x,y) \rightarrow (0,0)} \frac{x(e^{x+y}-1)}{x^2+y^2}$

Start by applying special limits for asymptotic approximation:

$$\lim_{t \rightarrow 0} \frac{e^t - 1}{t} = 1 \Rightarrow e^t - 1 \approx t, \text{ meaning that } e^{x+y} - 1 \approx x + y$$

Therefore, it is possible to simplify computations:

$$\lim_{(x,y) \rightarrow (0,0)} \frac{x(x+y)}{x^2+y^2} = \frac{0}{0}$$

Solve the limit by switching to polar coordinates:

$$\lim_{\rho \rightarrow 0} \frac{\rho \cos \theta (\rho \cos \theta + \rho \sin \theta)}{\rho^2 \sin^2 \theta + \rho^2 \cos^2 \theta} = \lim_{\rho \rightarrow 0} \frac{\rho^2 \cos \theta (\cos \theta + \sin \theta)}{\rho^2} = \cos^2 \theta + \cos \theta \sin \theta$$

Notice that, in this case, the limit does not exist as its result depends on the value of  $\theta$ .

- $\lim_{(x,y) \rightarrow (0,0)} \frac{\sin(x^2 y)}{\sqrt{x^2 + y^2}}$

Start by applying special limits for asymptotic approximation:

$$\lim_{t \rightarrow 0} \frac{\sin t}{t} = 1 \Rightarrow \sin t \approx t \Rightarrow \sin(x^2 y) \approx x^2 y$$

Therefore, it is possible to simplify computations:

$$\lim_{(x,y) \rightarrow (0,0)} \frac{x^2 y}{\sqrt{x^2 + y^2}} = \frac{0}{0}$$

Solve the limit by switching to polar coordinates:

$$\lim_{\rho \rightarrow 0} \frac{\rho^2 \cos^2 \theta \rho \sin \theta}{\sqrt{\rho^2 \cos^2 \theta + \rho^2 \sin^2 \theta}} = \lim_{\rho \rightarrow 0} \frac{\rho^3 \cos^2 \theta \sin \theta}{\sqrt{\rho^2}} = \lim_{\rho \rightarrow 0} \rho^2 \cos^2 \theta \sin \theta = 0 \quad \forall \theta \in [0, 2\pi]$$

- $\lim_{(x,y) \rightarrow (1,0)} \frac{y^5}{((x-1)^2 + y^2)^2} + \frac{\ln(y+1)}{y} + \frac{\sin^2(x-1)}{x-1}$  Start by applying special limits for asymptotic approximation:

$$\lim_{t \rightarrow 0} \frac{\ln(t+1)}{t} = 1 \Rightarrow \ln(t+1) \approx t$$

$$\lim_{t \rightarrow 0} \frac{\sin t}{t} = 1 \Rightarrow \sin t \approx t \Rightarrow \sin(x-1) \approx x-1$$

Therefore, it is possible to simplify computations:

$$\lim_{(x,y) \rightarrow (0,0)} \frac{y^5}{((x-1)^2 + y^2)^2} + \frac{y}{y} + \frac{(x-1)^2}{x-1} = \lim_{(x,y) \rightarrow (0,0)} \frac{y^5}{((x-1)^2 + y^2)^2} + 1 + (x-1) = \frac{0}{0}$$

Solve the limit by switching to polar coordinates:

$$\lim_{\rho \rightarrow 0} \frac{\rho^5 \sin^5 \theta}{(\rho^2 \cos^2 \theta + \rho^2 \sin^2 \theta)^2} + 1 + \rho \cos \theta = \lim_{\rho \rightarrow 0} \frac{\rho^5 \sin^5 \theta}{(\rho^2)^2} + 1 = \lim_{\rho \rightarrow 0} \rho \sin^5 \theta + 1 = 1 \quad \forall \theta \in [0, 2\pi]$$



## Chapter 2

# Exercise Sheet 2: Continuity and partial derivatives

### 2.1 Exercise 1

Determine the continuity of the following functions in  $\mathbb{R}^2$ :

- First function:

$$f(x, y) = \begin{cases} \frac{e^{xy^2} - 1}{\sqrt{x^2 + y^2}} & \text{if } (x, y) \neq (0, 0) \\ 0 & \text{if } (x, y) = (0, 0) \end{cases}$$

The function is defined to be surely continuous in  $\mathbb{R}^2 \setminus \{(0, 0)\}$ , meaning that the goal is to check the limit of the function as  $(x, y) \rightarrow (0, 0)$ :

By asymptotic comparison,  $\lim_{(x,y) \rightarrow (0,0)} \frac{e^{xy^2} - 1}{\sqrt{x^2 + y^2}} = \lim_{(x,y) \rightarrow (0,0)} \frac{xy^2}{\sqrt{x^2 + y^2}} = \frac{0}{0}$

Solve the limit by switching to polar coordinates:

$$\lim_{\rho \rightarrow 0} \frac{\rho \cos \theta \rho^2 \sin^2 \theta}{\sqrt{\rho^2 \cos^2 \theta + \rho^2 \sin^2 \theta}} = \lim_{\rho \rightarrow 0} \frac{\rho^3 \cos \theta \sin^2 \theta}{\rho} = \lim_{\rho \rightarrow 0} \rho^2 \cos \theta \sin^2 \theta = 0 \quad \forall \theta \in [0, 2\pi]$$

Since  $\exists \lim_{(x,y) \rightarrow (0,0)} f(x, y) = f(0, 0)$ , the function is continuous in  $(0, 0)$  as well, and therefore it is continuous all over  $\mathbb{R}^2$ .

- Second function:

$$f(x, y) = \begin{cases} \frac{x^2 y^3}{(x^2 + y^2)^2} & \text{if } (x, y) \neq (0, 0) \\ 0 & \text{if } (x, y) = (0, 0) \end{cases}$$

The function is defined to be surely continuous in  $\mathbb{R}^2 \setminus \{(0,0)\}$ , meaning that the goal is to check the limit of the function as  $(x,y) \rightarrow (0,0)$ :

$$\lim_{(x,y) \rightarrow (0,0)} \frac{x^2 y^3}{(x^2 + y^2)^2} = \frac{0}{0}$$

Solve the limit by switching to polar coordinates:

$$\lim_{\rho \rightarrow 0} \frac{\rho^2 \cos^2 \theta \rho^3 \sin^3 \theta}{(\rho^2 \cos^2 \theta + \rho^2 \sin^2 \theta)^2} = \lim_{\rho \rightarrow 0} \frac{\rho^5 \cos^2 \theta \sin^3 \theta}{(\rho^2)^2} = \lim_{\rho \rightarrow 0} \rho \cos^2 \theta \sin^3 \theta = 0 \quad \forall \theta \in [0, 2\pi]$$

Since  $\exists \lim_{(x,y) \rightarrow (0,0)} f(x,y) = f(0,0)$ , the function is continuous in  $(0,0)$  as well, and therefore it is continuous all over  $\mathbb{R}^2$ .

## 2.2 Exercise 2

Compute the domain and partial derivatives of the following functions:

- $f(x,y) = (x+y)(x-y)$ .  
 $\Omega = \mathbb{R}^2$ .

$$f_x(x,y) = x - y + x + y = 2x$$

$$f_y(x,y) = x - y - (x - y) = -2y$$

**N.B.:** In this case, it is possible to simplify computations by rewriting  $f(x,y) = x^2 - y^2$ .

- $f(x,y) = \frac{x^2}{x^2+y}$ .  
 $\Omega : x^2 + y \neq 0 \Rightarrow \Omega : y \neq -x^2$ .

$$f_x(x,y) = \frac{2x(x^2+y) - x^2 \cdot 2x}{(x^2+y)^2} = \frac{2xy}{(x^2+y)^2}$$

$$f_y(x,y) = \frac{-x^2}{(x^2+y)} \quad (\text{in this case, use } \frac{d(\frac{1}{f(x)})}{dx} = -\frac{f'(x)}{f^2(x)})$$

- $f(x,y) = \sqrt{x+2y}$ .  
 $\Omega : x+2y \geq 0 \Rightarrow \Omega : y \geq -\frac{x}{2}$ .

$$f_x(x,y) = \frac{1}{2\sqrt{x+2y}}$$

$$f_y(x,y) = \frac{2}{2\sqrt{x+2y}} = \frac{1}{\sqrt{x+2y}}$$

- $f(x, y) = \ln(x^2 + y^2)$ .  
 $\Omega : x^2 + y^2 > 0 \Rightarrow \Omega : (x, y) \neq (0, 0) \Rightarrow \Omega = \{\mathbb{R}^2 \setminus (0, 0)\}$ .

$$f_x(x, y) = \frac{2x}{x^2 + y^2}$$

$$f_y(x, y) = \frac{2y}{x^2 + y^2}$$

- $f(x, y) = e^{x^2 y}$ .  
 $\Omega = \mathbb{R}^2$ .

$$f_x(x, y) = 2xye^{x^2 y}$$

$$f_y(x, y) = x^2 e^{x^2 y}$$

- $f(x, y) = \frac{e^{x^2 + y^2}}{y}$ .  
 $\Omega : y \neq 0$ .

$$f_x(x, y) = \frac{2xe^{x^2 + y^2}}{y} \text{ (in this case, treat } \frac{1}{y} \text{ as a constant)}$$

$$f_y(x, y) = \frac{2ye^{x^2 + y^2}y - e^{x^2 + y^2}}{y^2} = \frac{e^{x^2 + y^2}(2y^2 - 1)}{y^2}$$

- $f(x, y) = \ln(x + y)x^2 + y \sin x$ .  
 $\Omega : x + y > 0 \Rightarrow \Omega : y > -x$ .

$$f_x(x, y) = \frac{x^2}{x + y} + 2x \ln(x + y) + y \cos x$$

$$f_y(x, y) = \frac{x^2}{x + y} + \sin x \text{ (in this case, treat } x^2 \text{ as a constant)}$$

- $f(x, y) = \ln\left(\frac{x^2 + y^2 - 1}{e^x}\right)$ .

$$\Omega : \frac{x^2 + y^2 - 1}{e^x} > 0 \Rightarrow \Omega : \begin{cases} x^2 + y^2 - 1 > 0 \\ e^x > 0 \end{cases} \vee \begin{cases} x^2 + y^2 - 1 < 0 \\ e^x < 0 \end{cases}$$

Notice, however, that the second system of inequalities is incompatible as  $\nexists x \in \mathbb{R}$  such that  $e^x < 0$ , meaning that, knowing that  $e^x > 0 \forall x \in \mathbb{R}$ , it is possible to conclude that  $\Omega = \{(x, y) \in \mathbb{R}^2 : x^2 + y^2 > 1\}$ .

$$f_x(x, y) = \frac{e^x}{x^2 + y^2 - 1} \cdot \frac{2xe^x - (x^2 + y^2 - 1)e^x}{(e^2)^2} = \frac{2x - (x^2 + y^2 - 1)}{x^2 + y^2 - 1}$$

$$f_y(x, y) = \frac{e^x}{x^2 + y^2 - 1} \cdot \frac{2y}{e^x} = \frac{2y}{x^2 + y^2 - 1} \text{ (in this case, treat } \frac{1}{e^x} \text{ as a constant)}$$

- $f(x, y) = \ln\left(\frac{e^{x^2}}{y+1}\right) + \sqrt{\cos y}$ .

$$\Omega : \begin{cases} \frac{e^{x^2}}{y+1} > 0 \\ \cos y \geq 0 \end{cases} \Rightarrow \Omega : \begin{cases} e^{x^2} > 0 \\ y+1 > 0 \\ \cos y \geq 0 \end{cases} \vee \begin{cases} e^{x^2} < 0 \\ y+1 < 0 \\ \cos y \geq 0 \end{cases}$$

However, since the second system is incompatible, it is possible to conclude that:

$$\Omega : \begin{cases} e^{x^2} > 0 \\ y+1 > 0 \\ \cos y \geq 0 \end{cases} \Rightarrow \Omega : y \in (-1, \frac{\pi}{2}]$$

$$f_x(x, y) = \frac{y+1}{e^{x^2}} \cdot 2xe^{x^2} = 2x(y+1) \text{ (treat } \frac{1}{y+1} \text{ and } \sqrt{\cos y} \text{ as constants)}$$

$$f_y(x, y) = \frac{y+1}{e^{x^2}} \cdot \frac{-e^{x^2}}{(y+1)^2} - \frac{-\sin y}{2\sqrt{\cos y}} = -\left(\frac{1}{y+1} + \frac{\sin y}{2\sqrt{\cos y}}\right) \text{ (treat } e^{x^2} \text{ as a constant)}$$

- $f(x, y) = \ln(x^2 + y^2) - \frac{1}{\sqrt{2x+3y}} + e^{\sin(x^2+y)}$ .

$$\Omega : \begin{cases} x^2 + y^2 > 0 \\ 2x + 3y > 0 \end{cases} \Rightarrow \Omega : \begin{cases} (x, y) \neq (0, 0) \\ y > -\frac{2x}{3} \end{cases}$$

$$f_x(x, y) = \frac{2x}{x^2 + y^2} - \left(-\frac{1}{(\sqrt{2x+3y})^2} \frac{2}{2\sqrt{2x+3y}}\right) + 2xe^{\sin(x^2+y)} \cos(x^2+y)$$

$$f_y(x, y) = \frac{2y}{x^2 + y^2} - \left(-\frac{1}{(\sqrt{2x+3y})^2} \frac{3}{2\sqrt{2x+3y}}\right) + e^{\sin(x^2+y)} \cos(x^2+y)$$

## 2.3 Exercise 3

Compute the gradient of the following functions at the given point using the incremental ratio and, afterwards, verify that the result is the same by computing the partial derivatives:

- $f(x, y) = xye^{x+y}$  in  $(-1, 1)$ .

Find the partial derivatives by applying the definition of incremental ratio:

1. With respect to  $x$ :

$$f_x(-1, 1) = \lim_{h \rightarrow 0} \frac{f(-1+h, 1) - f(-1, 1)}{h} = \lim_{h \rightarrow 0} \frac{(h-1)e^{h-1+1} - (-e^{-1+1})}{h}$$

Apply special limits to conclude that:

$$f_x(-1, 1) = \lim_{h \rightarrow 0} \frac{he^h - (e^h - 1)}{h} = \lim_{h \rightarrow 0} \frac{he^h}{h} - \frac{e^h - 1}{h} = \lim_{h \rightarrow 0} e^h - 1 = 0$$

2. With respect to  $y$ :

$$f_y(-1, 1) = \lim_{h \rightarrow 0} \frac{f(-1, 1+h) - f(-1, 1)}{h} = \lim_{h \rightarrow 1} \frac{-(1+h)e^{-1+h+1} - (-e^{-1+1})}{h}$$

Apply special limits to conclude that:

$$f_y(-1, 1) = \lim_{h \rightarrow 0} \frac{-he^h - (e^h - 1)}{h} = \lim_{h \rightarrow 0} \frac{-he^h}{h} - \frac{e^h - 1}{h} = \lim_{h \rightarrow 0} -e^h - 1 = -2$$

Therefore,  $\nabla f(-1, 1) = (0, -2)$ .

Indeed, it is possible to recover the same result by directly computing the partial derivatives:

$$f_x(x, y) = ye^{x+y} + xye^{x+y} \Rightarrow f_x(-1, 1) = 0$$

$$f_y(x, y) = xe^{x+y} + xye^{x+y} \Rightarrow f_y(-1, 1) = -2$$

Therefore,  $\nabla f(-1, 1) = (0, -2)$ .

- $f(x, y) = (x - y) \sin(x^2 + y)$  in  $(0, 0)$ .

Find the partial derivatives by applying the definition of incremental ratio:

1. With respect to  $x$ :

$$f_x(x, y) = \lim_{h \rightarrow 0} \frac{f(h, 0) - f(0, 0)}{h} = \lim_{h \rightarrow 0} \frac{h \sin(h^2)}{h} = \lim_{h \rightarrow 0} \sin(h^2) = 0$$

2. With respect to  $y$ :

$$f_y(0, 0) = \lim_{h \rightarrow 0} \frac{f(0, h) - f(0, 0)}{h} = \lim_{h \rightarrow 0} \frac{-h \sin h}{h} = \lim_{h \rightarrow 0} -\sin h = 0$$

Therefore  $\nabla f(0, 0) = (0, 0)$ .

Indeed, it is possible to recover the same result by directly computing the partial derivatives:

$$f_x(x, y) = \sin(x^2 + y) + (x - y)2x \cos(x^2 + y) \Rightarrow f_x(0, 0) = 0$$

$$f_y(x, y) = -\sin(x^2 + y) + (x - y) \cos(x^2 + y) \Rightarrow f_y(0, 0) = 0$$

Therefore,  $\nabla f(0, 0) = (0, 0)$ .

- $f(x, y) = \ln(xy + 1)e^{-x}$  in  $(1, 0)$ .

Find the partial derivatives by applying the definition of incremental ratio:

1. With respect to  $x$ :

$$f_x(1, 0) = \lim_{h \rightarrow 0} \frac{f(1+h, 0) - f(1, 0)}{h} = \lim_{h \rightarrow 0} \frac{0}{h} = 0$$

2. With respect to  $y$ :

$$f_y(1, 0) = \lim_{h \rightarrow 0} \frac{f(1, h) - f(1, 0)}{h} = \lim_{h \rightarrow 0} \frac{\ln(h+1)e^{-1}}{h} = e^{-1} \text{ as } \lim_{h \rightarrow 0} \frac{\ln(h+1)}{h} = 1$$

Therefore,  $\nabla f(1, 0) = (0, e^{-1})$ .

Indeed, it is possible to recover the same result by directly computing the partial derivatives:

$$f_x(x, y) = \frac{ye^{-x}}{xy+1} + \ln(xy+1)(-e^{-x}) \Rightarrow f_x(1, 0) = 0$$

$$f_y(x, y) = \frac{xe^{-x}}{xy+1} \text{ (in this case, treat } e^{-x} \text{ as a constant)} \Rightarrow f_y(1, 0) = e^{-1}$$

Therefore,  $\nabla f(1, 0) = (0, e^{-1})$ .

## 2.4 Exercise 4

Compute the gradient and the tangent plane in the given point:

- $f(x, y) = x^3 + y^3 - 3xy$  in  $(2, 2)$ .

Start by computing the partial derivatives:

$$f_x(x, y) = 3x^2 - 3y \Rightarrow f_x(2, 2) = 6$$

$$f_y(x, y) = 3y^2 - 3x \Rightarrow f_y(2, 2) = 6$$

Therefore,  $\nabla f(2, 2) = (6, 6)$ , while the tangent plane will be given by:

$$z = \nabla f(2, 2) \cdot (x-2, y-2) + f(2, 2) = 6(x-2) + 6(y-2) + 4 = 6x - 6y - 20$$

- $f(x, y) = \frac{x-y}{x+y}$  in  $(1, 1)$ .

Start by computing the partial derivatives:

$$f_x(x, y) = \frac{(x+y) - (x-y)}{(x+y)^2} = \frac{2y}{(x+y)^2} \Rightarrow f_x(1, 1) = \frac{1}{2}$$

$$f_y(x, y) = \frac{-(x+y) - (x-y)}{(x+y)^2} = \frac{-2x}{(x+y)^2} \Rightarrow f_y(1, 1) = -\frac{1}{2}$$

Therefore,  $\nabla f(1, 1) = (\frac{1}{2}, -\frac{1}{2})$ , while the tangent plane will be given by:

$$z = \nabla f(1, 1) \cdot (x-1, y-1) + f(1, 1) = \frac{1}{2}(x-1) - \frac{1}{2}(y-1) = \frac{1}{2}x - \frac{1}{2}y$$

- $f(x, y) = e^{xy}$  in  $(1, 5)$ .

Start by computing the partial derivatives:

$$f_x(x, y) = ye^{xy} \Rightarrow f_x(1, 5) = 5e^5$$

$$f_y(x, y) = xe^{xy} \Rightarrow f_y(1, 5) = e^5$$

Therefore,  $\nabla f(1, 5) = (5e^5, e^5)$ , while the tangent plane will be given by:

$$z = \nabla f(1, 5) \cdot (x-1, y-5) + f(1, 5) = 5e^5(x-1) + e^5(y-5) + e^5 = 5e^5x + e^5y - 9e^5$$

## Chapter 3

# Exercise Sheet 3: Continuity and differentiability

### 3.1 Exercise 1

Discuss continuity and differentiability in  $\mathbb{R}^2$  for the following functions:

- First function:

$$f(x, y) = \begin{cases} \frac{e^{xy^2} - 1}{\sqrt{x^2 + y^2}} & \text{if } (x, y) \neq (0, 0) \\ 0 & \text{if } (x, y) = (0, 0) \end{cases}$$

The function is defined to be surely continuous in  $\mathbb{R}^2 \setminus \{(0, 0)\}$ , meaning that the goal is to check the limit of the function as  $(x, y) \rightarrow (0, 0)$ :

By asymptotic comparison,  $\lim_{(x,y) \rightarrow (0,0)} \frac{e^{xy^2} - 1}{\sqrt{x^2 + y^2}} = \lim_{(x,y) \rightarrow (0,0)} \frac{xy^2}{\sqrt{x^2 + y^2}} = \frac{0}{0}$

Solve the limit by switching to polar coordinates:

$$\lim_{\rho \rightarrow 0} \frac{\rho \cos \theta \rho^2 \sin^2 \theta}{\sqrt{\rho^2 \cos^2 \theta + \rho^2 \sin^2 \theta}} = \lim_{\rho \rightarrow 0} \frac{\rho^3 \cos \theta \sin^2 \theta}{\rho} = \lim_{\rho \rightarrow 0} \rho^2 \cos \theta \sin^2 \theta = 0 \quad \forall \theta \in [0, 2\pi]$$

Since  $\exists \lim_{(x,y) \rightarrow (0,0)} f(x, y) = f(0, 0)$ , the function is continuous in  $(0, 0)$  as

well, and therefore it is continuous all over  $\mathbb{R}^2$ .

Observe that the function is also differentiable in  $\mathbb{R}^2 \setminus \{(0, 0)\}$ : in order to check differentiability at  $(0, 0)$  it is possible to state that the function is differentiable in the point if and only if:

$$\lim_{(h,k) \rightarrow (0,0)} \frac{f(h,k) - f(0,0) - f_x(0,0)h - f_y(0,0)k}{\sqrt{h^2 + k^2}} = 0$$

Most particularly, apply the definition of incremental ratio to find the function's partial derivatives:

$$f_x(0,0) = \lim_{h \rightarrow 0} \frac{f(h,0) - f(0,0)}{h} = \lim_{h \rightarrow 0} \frac{1}{h} \frac{e^{h \cdot 0^2} - 1}{\sqrt{h^2}} = \lim_{h \rightarrow 0} \frac{h \cdot 0^2}{h\sqrt{h^2}} = 0$$

$$f_y(0,0) = \lim_{h \rightarrow 0} \frac{f(0,h) - f(0,0)}{h} = \lim_{h \rightarrow 0} \frac{1}{h} \frac{e^{0 \cdot h^2} - 1}{\sqrt{h^2}} = \lim_{h \rightarrow 0} \frac{0 \cdot h^2}{h\sqrt{h^2}} = 0$$

At this point, start by applying special limits for asymptotic approximation:

$$\lim_{(h,k) \rightarrow (0,0)} \frac{1}{\sqrt{h^2 + k^2}} \frac{e^{hk^2} - 1}{\sqrt{h^2 + k^2}} = \lim_{(h,k) \rightarrow (0,0)} \frac{1}{\sqrt{h^2 + k^2}} \frac{hk^2}{\sqrt{h^2 + k^2}} = \frac{0}{0}$$

Solve the limit by switching to polar coordinates:

$$\lim_{\rho \rightarrow 0} \frac{\rho \cos \theta \rho^2 \sin^2 \theta}{\rho^2 \cos^2 \theta + \rho^2 \sin^2 \theta} = \lim_{\rho \rightarrow 0} \frac{\rho^3 \cos \theta \sin^2 \theta}{\rho^2} = \lim_{\rho \rightarrow 0} \rho \cos \theta \sin^2 \theta = 0 \quad \forall \theta \in [0, 2\pi]$$

Therefore, since the condition is satisfied, the function is indeed differentiable in  $(0,0)$  as well, and therefore it is differentiable all over  $\mathbb{R}^2$ .

- Second function:

$$f(x,y) = \begin{cases} \frac{x^2 y^3}{(x^2 + y^2)^2} & \text{if } (x,y) \neq (0,0) \\ 0 & \text{if } (x,y) = (0,0) \end{cases}$$

The function is defined to be surely continuous in  $\mathbb{R}^2 \setminus \{(0,0)\}$ , meaning that the goal is to check the limit of the function as  $(x,y) \rightarrow (0,0)$ :

$$\lim_{(x,y) \rightarrow (0,0)} \frac{x^2 y^3}{(x^2 + y^2)^2} = \frac{0}{0}$$

Solve the limit by switching to polar coordinates:

$$\lim_{\rho \rightarrow 0} \frac{\rho^2 \cos^2 \theta \rho^3 \sin^3 \theta}{(\rho^2 \cos^2 \theta + \rho^2 \sin^2 \theta)^2} = \lim_{\rho \rightarrow 0} \frac{\rho^5 \cos^2 \theta \sin^3 \theta}{(\rho^2)^2} = \lim_{\rho \rightarrow 0} \rho \cos^2 \theta \sin^3 \theta = 0 \quad \forall \theta \in [0, 2\pi]$$

Since  $\exists \lim_{(x,y) \rightarrow (0,0)} f(x,y) = f(0,0)$ , the function is continuous in  $(0,0)$  as

well, and therefore it is continuous all over  $\mathbb{R}^2$ .

Observe that the function is also differentiable in  $\mathbb{R}^2 \setminus \{(0,0)\}$ : in order to check differentiability at  $(0,0)$  it is possible to state that the function is differentiable in the point if and only if:

$$\lim_{(h,k) \rightarrow (0,0)} \frac{f(h,k) - f(0,0) - f_x(0,0)h - f_y(0,0)k}{\sqrt{h^2 + k^2}} = 0$$



Most particularly, apply the definition of incremental ratio to find the function's partial derivatives:

$$f_x(0,0) = \lim_{h \rightarrow 0} \frac{f(h,0) - f(0,0)}{h} = \lim_{h \rightarrow 0} \frac{1}{h} \frac{h^2 \cdot 0^3}{(h^2)^2} = \lim_{h \rightarrow 0} \frac{0}{h^3} = 0$$

$$f_y(0,0) = \lim_{h \rightarrow 0} \frac{f(0,h) - f(0,0)}{h} = \lim_{h \rightarrow 0} \frac{1}{h} \frac{0^2 h^3}{(h^2)^2} = \lim_{h \rightarrow 0} \frac{0}{h^2} = 0$$

Therefore, it is possible to conclude that:

$$\lim_{(h,k) \rightarrow (0,0)} \frac{1}{\sqrt{h^2 + k^2}} \frac{h^2 k^3}{(h^2 + k^2)^2} = \frac{0}{0}$$

Solve the limit by switching to polar coordinates:

$$\lim_{\rho \rightarrow 0} \frac{1}{\sqrt{\rho^2 \cos^2 \theta + \rho^2 \sin^2 \theta}} \frac{\rho^2 \cos^2 \theta \rho^3 \sin^3 \theta}{(\rho^2 \cos^2 \theta + \rho^2 \sin^2 \theta)^2} = \lim_{\rho \rightarrow 0} \frac{\rho^5 \cos^2 \theta \sin^3 \theta}{\rho \cdot (\rho^2)^2} = \cos^2 \theta \sin^3 \theta$$

In this case, the limit does not exist as the result depends on the value of  $\theta$ .

Therefore, since the condition is not satisfied, the function is not differentiable at  $(0,0)$ .

## 3.2 Exercise 2

Given  $a \in \mathbb{R}$ , consider the following function:

$$f(x,y) = \begin{cases} \frac{x^3 y}{x^2 + y^2} & \text{if } (x,y) \neq (0,0) \\ a & \text{if } (x,y) = (0,0) \end{cases}$$

- Discuss continuity of  $f$  in  $(0,0)$  with respect to the parameter  $a$ .

By definition, the function will be continuous at  $(0,0)$  if and only if

$$\exists \lim_{(x,y) \rightarrow (0,0)} f(x,y) = f(0,0).$$

Therefore, start by computing the limit of the function as  $(x,y) \rightarrow (0,0)$ :

$$\lim_{(x,y) \rightarrow 0} \frac{x^3 y}{x^2 + y^2} = \frac{0}{0}$$

Solve the limit by switching to polar coordinates:

$$\lim_{\rho \rightarrow 0} \frac{\rho^3 \cos^3 \theta \rho \sin \theta}{\rho^2 \cos^2 \theta + \rho^2 \sin^2 \theta} = \lim_{\rho \rightarrow 0} \frac{\rho^4 \cos^3 \theta \sin \theta}{\rho^2} = \lim_{\rho \rightarrow 0} \rho^2 \cos^3 \theta \sin \theta = 0 \quad \forall \theta \in [0, 2\pi]$$

Therefore, the function will be continuous at  $(0,0)$  for  $f(0,0) = a = 0$ .

- Is the function differentiable in  $(0, 0)$ ?

By definition, the function is differentiable at  $(0, 0)$  if and only if:

$$\lim_{(h,k) \rightarrow (0,0)} \frac{f(h,k) - f(0,0) - f_x(0,0)h - f_y(0,0)k}{\sqrt{h^2 + k^2}} = 0$$

Most particularly, apply the definition of incremental ratio to find the function's partial derivatives:

$$f_x(0,0) = \lim_{h \rightarrow 0} \frac{f(h,0) - f(0,0)}{h} = \frac{1}{h} \frac{h^3 \cdot 0}{h^2} = \lim_{h \rightarrow 0} 0 = 0$$

$$f_y(0,0) = \lim_{h \rightarrow 0} \frac{f(0,h) - f(0,0)}{h} = \lim_{h \rightarrow 0} \frac{1}{h} \frac{0^3 \cdot h}{h^2} = \lim_{h \rightarrow 0} \frac{0}{h^2} = 0$$

Therefore, it is possible to conclude that:

$$\lim_{(h,k) \rightarrow (0,0)} \frac{1}{\sqrt{h^2 + k^2}} \frac{h^3 k}{h^2 + k^2} = \frac{0}{0}$$

Solve the limit by switching to polar coordinates:

$$\lim_{\rho \rightarrow 0} \frac{1}{\sqrt{\rho^2 \cos^2 \theta + \rho^2 \sin^2 \theta}} \frac{\rho^3 \cos^3 \theta \rho \sin \theta}{\rho^2 \cos^2 \theta + \rho^2 \sin^2 \theta} = \lim_{\rho \rightarrow 0} \frac{\rho^4 \cos^3 \theta}{\rho \cdot \rho^2} = \lim_{\rho \rightarrow 0} \rho \cos^3 \theta \sin \theta = 0 \quad \forall \theta \in [0, 2\pi]$$

Therefore, since the condition is satisfied, the function is differentiable at  $(0, 0)$ , provided that it is assumed to be continuous as well.

### 3.3 Exercise 3

Consider the following function:

$$f(x, y) = \frac{\sin^\alpha(xy)}{\sqrt{x^2 + y^2}}, \quad \alpha > 0$$

- Compute the domain of  $f$ .

$$\Omega : \begin{cases} x^2 + y^2 \geq 0 \\ x^2 + y^2 \neq 0 \end{cases} \Rightarrow \Omega : x^2 + y^2 > 0 \Rightarrow \Omega : (x, y) \neq (0, 0)$$

Therefore, it is possible to conclude that  $\Omega = \mathbb{R}^2 \setminus \{(0, 0)\}$ .

- Discuss for which value of  $\alpha$  it is possible to extend the function for continuity outside its domain.

By definition, the function will be continuous at a point  $(x_0, y_0)$  if and only if  $\exists \lim_{(x,y) \rightarrow (x_0,y_0)} f(x, y) = f(x_0, y_0)$ .

Most particularly, the function is surely continuous in  $\mathbb{R}^2 \setminus (0, 0)$ , so the goal is to check for continuity at the point  $(0, 0)$  by checking the limit of

the function as  $(x, y) \rightarrow (0, 0)$ :

By asymptotic approximation,  $\lim_{(x,y) \rightarrow (0,0)} \frac{\sin^\alpha(xy)}{\sqrt{x^2 + y^2}} = \lim_{(x,y) \rightarrow (0,0)} \frac{(xy)^\alpha}{\sqrt{x^2 + y^2}} = \frac{0}{0}$

Solve the limit by switching to polar coordinates:

$$\lim_{\rho \rightarrow 0} \frac{(\rho \cos \theta \rho \sin \theta)^\alpha}{\sqrt{\rho^2 \cos^2 \theta + \rho^2 \sin^2 \theta}} = \lim_{\rho \rightarrow 0} \frac{\rho^{2\alpha} \cos^\alpha \theta \sin^\alpha \theta}{\rho} = \begin{cases} 0 & \text{if } 2\alpha - 1 > 0 \\ \neq & \text{if } 2\alpha - 1 \leq 0 \end{cases}$$

Therefore, it is possible to extend the function for continuity by writing it as:

$$f(x, y) = \begin{cases} \frac{\sin^\alpha(xy)}{\sqrt{x^2 + y^2}} & \text{if } (x, y) \neq (0, 0) \\ 0 & \text{if } (x, y) = (0, 0) \end{cases}, \text{ provided that } \alpha > \frac{1}{2}$$

- After having extended the function  $f$  in  $\mathbb{R}^2$ , compute  $\nabla f(0, 0)$ . Assuming  $\alpha > \frac{1}{2}$  to guarantee continuity, find the function's partial derivatives by applying the definition of incremental ratio:

$$f_x(0, 0) = \lim_{h \rightarrow 0} \frac{f(h, 0) - f(0, 0)}{h} = \lim_{h \rightarrow 0} \frac{1}{h} \frac{\sin^\alpha(h \cdot 0)}{\sqrt{h^2}} = \lim_{h \rightarrow 0} \frac{0}{h^2} = 0$$

$$f_y(0, 0) = \lim_{h \rightarrow 0} \frac{f(0, h) - f(0, 0)}{h} = \lim_{h \rightarrow 0} \frac{1}{h} \frac{\sin^\alpha(0 \cdot h)}{\sqrt{h^2}} = \lim_{h \rightarrow 0} \frac{0}{h^2} = 0$$

Therefore, it is possible to conclude that  $\nabla f(0, 0) = (0, 0)$ .

- Discuss for which value of  $\alpha$   $f$  is differentiable in  $(0, 0)$ . Assuming  $\alpha > \frac{1}{2}$  to guarantee continuity and differentiability, the function is said to be differentiable at  $(0, 0)$  if and only if:

$$\lim_{(h,k) \rightarrow (0,0)} \frac{f(h, k) - f(0, 0) - f_x(0, 0)h - f_y(0, 0)k}{\sqrt{h^2 + k^2}} = 0$$

Start by applying special limits for asymptotic approximation:

$$\lim_{(h,k) \rightarrow (0,0)} \frac{1}{\sqrt{h^2 + k^2}} \frac{\sin^\alpha(hk)}{\sqrt{h^2 + k^2}} = \lim_{(h,k) \rightarrow (0,0)} \frac{(hk)^\alpha}{h^2 + k^2} = \frac{0}{0}$$

Solve the limit by switching to polar coordinates:

$$\lim_{\rho \rightarrow 0} \frac{(\rho \cos \theta \rho \sin \theta)^\alpha}{\rho^2 \cos^2 \theta + \rho^2 \sin^2 \theta} = \lim_{\rho \rightarrow 0} \frac{\rho^{2\alpha} \cos^\alpha \theta \sin^\alpha \theta}{\rho^2} = \begin{cases} 0 & \text{if } 2\alpha - 2 > 0 \\ \neq & \text{if } 2\alpha - 2 \leq 0 \end{cases}$$

Therefore, since the condition is satisfied for  $\alpha > 1$ , the function will also be differentiable at  $(0, 0)$  if and only if  $\alpha > 1$ .

### 3.4 Exercise 4

Determine if the function is differentiable at the given point:

- $f(x, y) = \sqrt{1 - xy^2}$  in  $P(1, 0)$ .

The function is said to be differentiable at  $P(1, 0)$  if and only if:

$$\lim_{(h,k) \rightarrow (0,0)} \frac{f(1+h, k) - f(1, 0) - f_x(1, 0)h - f_y(1, 0)k}{\sqrt{h^2 + k^2}} = 0$$

Most particularly, start by finding the function's partial derivatives by applying the definition of incremental ratio:

$$f_x(1, 0) = \lim_{h \rightarrow 0} \frac{f(1+h, 0) - f(1, 0)}{h} = \lim_{h \rightarrow 0} \frac{\sqrt{1 - (1+h)0^2} - \sqrt{1}}{h} = \lim_{h \rightarrow 0} \frac{0}{h} = 0$$

$$f_y(1, 0) = \lim_{h \rightarrow 0} \frac{f(1, h) - f(1, 0)}{h} = \lim_{h \rightarrow 0} \frac{\sqrt{1 - h^2} - \sqrt{1}}{h} = \lim_{h \rightarrow 0} \frac{-2h}{2\sqrt{1 - h^2}} = 0 \text{ by De L'Hopital's rule.}$$

At this point, it is possible to conclude that:

$$\lim_{(h,k) \rightarrow (0,0)} \frac{\sqrt{1 - (1+h)k^2} - \sqrt{1}}{\sqrt{h^2 + k^2}} = \frac{0}{0}$$

Solve the limit by switching to polar coordinates:

$$\lim_{\rho \rightarrow 0} \frac{\sqrt{1 - (1 + \rho \cos \theta)\rho^2 \sin^2 \theta} - \sqrt{1}}{\sqrt{\rho^2 \cos^2 \theta + \rho^2 \sin^2 \theta}} = \lim_{\rho \rightarrow 0} \frac{\sqrt{1 - \rho^2 \sin^2 \theta - \rho^3 \cos \theta \sin^2 \theta} - \sqrt{1}}{\rho} = \frac{0}{0}$$

Solve the limit by applying De L'Hopital's rule:

$$\lim_{\rho \rightarrow 0} = \frac{-2\rho \sin^2 \theta - 3\rho^2 \cos \theta \sin^2 \theta}{2\sqrt{1 - \rho^2 \sin^2 \theta} - \rho^3 \cos \theta \sin^2 \theta} = 0 \quad \forall \theta \in [0, 2\pi]$$

Therefore, since the condition is satisfied, the function is differentiable at  $(1, 0)$ .

**N.B.:** It is also possible to recover differentiability by knowing that the function is continuous and differentiable at  $(1, 0)$ .

- $f(x, y) = x^2y + e^{2xy}$  in  $P(1, 1)$ .

The function is said to be differentiable at  $P(1, 1)$  if and only if:

$$\lim_{(h,k) \rightarrow (0,0)} \frac{f(1+h, 1+k) - f(1, 1) - f_x(1, 1)h - f_y(1, 1)k}{\sqrt{h^2 + k^2}} = 0$$

Most particularly, start by finding the function's partial derivatives by applying the definition of incremental ratio:

$$f_x(1, 1) = \lim_{h \rightarrow 0} \frac{f(1+h, 1) - f(1, 1)}{h} = \lim_{h \rightarrow 0} \frac{(h+1)^2 + e^{2(h+1)} - (1 + e^2)}{h} = 2 + 2e^2$$

$$f_y(1, 1) = \lim_{h \rightarrow 0} \frac{f(1, 1+h) - f(1, 1)}{h} = \lim_{h \rightarrow 0} \frac{(h+1) + e^{2(h+1)} - (1+e^2)}{h} = 1+2e^2$$

At this point, it is possible to conclude that:

$$\lim_{(h,k) \rightarrow (0,0)} \frac{(h+1)^2(k+1) + e^{2(h+1)(k+1)} - (1+e^2) - (2+2e^2)h - (1+2e^2)k}{\sqrt{h^2+k^2}} = \frac{0}{0}$$

Start by doing some algebra and expand the following values:

$$\begin{aligned} (h+1)^2(k+1) &= (h^2+2h+1)(k+1) = h^2k+h^2+2hk+2h+k+1 \\ 2(h+1)(k+1) &= 2(hk+h+k+1) \end{aligned}$$

For this reason, it is possible to rewrite the limit in the following way:

$$\lim_{(h,k) \rightarrow (0,0)} \frac{h^2k+h^2+2hk+e^{2(hk+h+k+1)} - e^2 - 2e^2h - 2e^2k}{\sqrt{h^2+k^2}} = \frac{0}{0}$$

Solve the limit by switching to polar coordinates:

$$\lim_{\rho \rightarrow 0} \frac{\rho^2 \cos^2 \theta \rho \sin \theta + \rho^2 \cos^2 \theta + 2\rho \cos \theta \rho \sin \theta + e^{2(\rho \cos \theta \rho \sin \theta + \rho \cos \theta + \rho \sin \theta + 1)} - e^2 - 2e^2 \rho \cos \theta - 2e^2 \rho \sin \theta}{\sqrt{\rho^2 \cos^2 \theta + \rho^2 \sin^2 \theta}}$$

Focus on the exponential terms and apply special limits for asymptotic approximation:

$$\lim_{\rho \rightarrow 0} e^{2(\rho^2 \cos \theta \sin \theta + \rho \cos \theta + \rho \sin \theta + 1)} - e^2 = \lim_{\rho \rightarrow 0} e^2 (e^{2(\rho^2 \cos \theta \sin \theta + \rho \cos \theta + \rho \sin \theta)} - 1) \text{ and exploit } \lim_{t \rightarrow 0} \frac{e^t - 1}{t} = 1$$

This approximation allows to conclude that:

$$\begin{aligned} \lim_{\rho \rightarrow 0} \frac{\rho^3 \cos^2 \theta \sin \theta + \rho^2 \cos^2 \theta + 2\rho^2 \cos \theta \sin \theta + 2e^2(\rho^2 \cos \theta \sin \theta + \rho \cos \theta + \rho \sin \theta) - 2e^2 \rho \cos \theta - 2e^2 \rho \sin \theta}{\rho} \\ \lim_{\rho \rightarrow 0} \frac{\rho(\rho^2 \cos^2 \theta \sin \theta + \rho \cos^2 \theta + 2\rho \sin \theta \cos \theta + 2e^2 \rho \cos \theta \sin \theta + 2e^2 \cos \theta + 2e^2 \sin \theta - 2e^2 \cos \theta - 2e^2 \sin \theta)}{\rho} \\ \lim_{\rho \rightarrow 0} \rho^2 \cos^2 \theta \sin \theta + \rho \cos^2 \theta + 2\rho \sin \theta \cos \theta + 2e^2 \rho \cos \theta \sin \theta = 0 \quad \forall \theta \in [0, 2\pi] \end{aligned}$$

Therefore, since the condition is satisfied, the function is differentiable at  $(1, 1)$ .

**N.B.:** It is also possible to recover differentiability by knowing that the function is continuous and differentiable at  $(1, 0)$ .

### 3.5 Exercise 5

Consider the following function:

$$f(x, y) = y^2 e^{-\frac{x^2}{y^2}}$$

- Compute the domain of  $f$ .

$$\Omega : y^2 \neq 0 \Rightarrow \Omega = \{(x, y) \in \mathbb{R}^2 : y \neq 0\}$$

- Compute  $f(0, 0)$  using limits.

Since computing the actual limit of  $f$  as  $(x, y) \rightarrow (0, 0)$  can be tricky, it is possible to exploit the squeeze theorem by bounding the function.

Start by noticing that, since the function is defined as the product between a quadratic term and an exponential function, then it is for sure non-negative in  $\mathbb{R}^2$ , meaning that  $f(x, y) \geq 0$ .

In addition, since  $-\frac{x^2}{y^2} \leq 0 \forall (x, y) \in \mathbb{R}^2$ , it is possible to state that  $e^{-\frac{x^2}{y^2}} \leq 1$  in  $\mathbb{R}^2$ , meaning that  $f(x, y) \leq y^2$ .

Therefore, by applying the squeeze theorem, it is possible to conclude that:

$$0 \leq \lim_{(x,y) \rightarrow (0,0)} y^2 e^{-\frac{x^2}{y^2}} \leq \lim_{(x,y) \rightarrow (0,0)} y^2 \Rightarrow 0 \leq \lim_{(x,y) \rightarrow (0,0)} y^2 e^{-\frac{x^2}{y^2}} \leq 0 \quad \lim_{(x,y) \rightarrow (0,0)} y^2 e^{-\frac{x^2}{y^2}} = 0$$

- Compute  $f_x(0, 0)$  and  $f_y(0, 0)$  using the definition.

Find the partial derivatives by applying the definition of incremental ratio:

1. With respect to  $x$ :

$$f_x(0, 0) = \lim_{h \rightarrow 0} \frac{f(h, 0) - f(0, 0)}{h} = \lim_{h \rightarrow 0} \frac{0}{h} = 0$$

2. With respect to  $y$ :

$$f_y(0, 0) = \lim_{h \rightarrow 0} \frac{f(0, h) - f(0, 0)}{h} = \lim_{h \rightarrow 0} \frac{h^2 e^{-\frac{0}{h^2}}}{h} = \lim_{h \rightarrow 0} h = 0$$

- Is the function differentiable at  $(0, 0)$ ?

By definition, the function will be differentiable at  $(0, 0)$  if and only if the following holds true:

$$\lim_{(h,k) \rightarrow (0,0)} \frac{f(h, k) - f(0, 0) - f_x(0, 0)h - f_y(0, 0)k}{\sqrt{h^2 + k^2}} = 0$$

$$\lim_{(h,k) \rightarrow (0,0)} \frac{k^2 e^{-\frac{h^2}{k^2}}}{\sqrt{h^2 + k^2}} = \lim_{(h,k) \rightarrow (0,0)} \frac{k^2}{\sqrt{h^2 + k^2}} = \frac{0}{0} \text{ by squeeze theorem on } k^2 e^{-\frac{h^2}{k^2}} \leq k^2.$$

At this point, solve the limit by switching to polar coordinates:

$$\lim_{\rho \rightarrow 0} \frac{\rho^2 \sin^2 \theta}{\sqrt{\rho^2 \cos^2 \theta + \rho^2 \sin^2 \theta}} = \lim_{\rho \rightarrow 0} \frac{\rho^2 \sin^2 \theta}{\rho} = \lim_{\rho \rightarrow 0} \rho \sin^2 \theta = 0 \quad \forall \theta \in [0, 2\pi]$$

Therefore, since the condition is satisfied, the function is indeed differentiable at  $(0, 0)$ .

### 3.6 Exercise 6

Using the definition with the incremental ratio, compute the following directional derivatives and, afterwards, verify that the result is the same by using the formula with the gradient:

- $f(x, y) = e^x y$  along the direction  $v = (3, 4)$  at the point  $(2, 0)$ .  
Notice that  $v$  is not a unit vector, so start by normalising it:

$$\|v\| = \sqrt{3^2 + 4^2} = 5 \Rightarrow u = \frac{v}{\|v\|} = \left(\frac{3}{5}, \frac{4}{5}\right)$$

Therefore, by applying the definition of rate of change, it is possible to conclude that:

$$\frac{\partial f}{\partial u}(2, 0) = \lim_{h \rightarrow 0} \frac{f(2 + \frac{3}{5}h, \frac{4}{5}h) - f(2, 0)}{h} = \lim_{h \rightarrow 0} \frac{e^{2+\frac{3}{5}h} \frac{4}{5}h}{h} = \frac{4e^2}{5}$$

Indeed, it is possible to recover the same result by directly computing the directional derivative:

$$\begin{aligned} f_x(x, y) &= e^x y \Rightarrow f_x(2, 0) = 0 \\ f_y(x, y) &= e^x \Rightarrow f_y(2, 0) = e^2 \end{aligned}$$

Therefore, it is possible to conclude that:

$$\frac{\partial f}{\partial u}(2, 0) = \nabla f(2, 0) \cdot u = \frac{4e^2}{5}$$

- $f(x, y) = x^2 + y^2 - xy$  along the direction  $v = (1, 1)$  at the point  $(0, 0)$ .  
Notice that  $v$  is not a unit vector, so start by normalising it:

$$\|v\| = \sqrt{1^2 + 1^2} = \sqrt{2} \Rightarrow u = \frac{v}{\|v\|} = \left(\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2}\right)$$

Therefore, by applying the definition of rate of change, it is possible to conclude that:

$$\frac{\partial f}{\partial u}(0, 0) = \lim_{h \rightarrow 0} \frac{f(\frac{\sqrt{2}}{2}h, \frac{\sqrt{2}}{2}h) - f(0, 0)}{h} = \lim_{h \rightarrow 0} \frac{\frac{1}{2}h^2 + \frac{1}{2}h^2 - \frac{1}{2}h^2}{h} = \lim_{h \rightarrow 0} \frac{h^2}{2h} = 0$$

Indeed, it is possible to recover the same result by directly computing the directional derivative:

$$\begin{aligned} f_x(x, y) &= 2x - y \Rightarrow f_x(0, 0) = 0 \\ f_y(x, y) &= 2y - x \Rightarrow f_y(0, 0) = 0 \end{aligned}$$

Therefore, it is possible to conclude that:

$$\frac{\partial f}{\partial u}(0, 0) = \nabla f(0, 0) \cdot u = 0$$

### 3.7 Exercise 7

Compute the directional derivative along the direction  $v$  at the point  $P$  for the following functions:

- $f(x, y) = \ln\left(\frac{1}{x^2+y^2}\right) + 2y$  along  $v = \left(\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2}\right)$  at the point  $P(1, 1)$ .  
Start by recovering the function's gradient vector:

$$f_x(x, y) = \frac{-2x}{(x^2 + y^2)^2}(x^2 + y^2) = \frac{-2x}{x^2 + y^2} \Rightarrow f_x(1, 1) = -1$$

$$f_y(x, y) = \frac{-2y}{(x^2 + y^2)^2}(x^2 + y^2) + 2 = \frac{-2y}{x^2 + y^2} + 2 \Rightarrow f_y(1, 1) = 1$$

Therefore, given  $\nabla f(1, 1) = (-1, 1)$ , it is possible to conclude that:

$$\frac{\partial f}{\partial v}(1, 1) = \nabla f(1, 1) \cdot u = -\frac{\sqrt{2}}{2} + \frac{\sqrt{2}}{2} = 0$$

- $f(x, y) = \ln\left(\frac{x^2+y^2+1}{e^x}\right)$  along  $v = (0, 1)$  at the point  $P(0, 1)$ .  
Start by recovering the function's gradient vector:

$$f_x(x, y) = \frac{e^x}{x^2 + y^2 + 1} \cdot \frac{2xe^x - (x^2 + y^2 + 1)e^x}{(e^x)^2} = \frac{2x - (x^2 + y^2 + 1)}{x^2 + y^2 + 1} \Rightarrow f_x(0, 1) = -1$$

$$f_y(x, y) = \frac{e^x}{x^2 + y^2 + 1} \cdot \frac{2y}{e^x} = \frac{2y}{x^2 + y^2 + 1} \Rightarrow f_y(0, 1) = 1$$

Therefore, given  $\nabla f(0, 1) = (1, 1)$ , it is possible to conclude that:

$$\frac{\partial f}{\partial v}(0, 1) = \nabla f(0, 1) \cdot u = 0 + 1 = 1$$



## Chapter 4

# Exercise Sheet 4: Second derivatives and stationary points

### 4.1 Exercise 1

Compute the first and second partial derivatives of the following functions:

- $f(x, y) = \sin(2x + 3y)$ .

Start by computing the first-order partial derivatives:

$$f_x(x, y) = 2 \cos(2x + 3y)$$

$$f_y(x, y) = 3 \cos(2x + 3y)$$

Therefore, it is possible to compute the second-order partial derivatives:

$$f_{xx}(x, y) = -4 \sin(2x + 3y)$$

$$f_{xy}(x, y) = -6 \sin(2x + 3y)$$

$$f_{yx}(x, y) = -6 \sin(2x + 3y)$$

$$f_{yy}(x, y) = -9 \sin(2x + 3y)$$

- $f(x, y) = \ln(x^2 + y)$ .

Start by computing the first-order partial derivatives:

$$f_x(x, y) = \frac{2x}{x^2 + y}$$

$$f_y(x, y) = \frac{1}{x^2 + y}$$

Therefore, it is possible to compute the second-order partial derivatives:

$$\begin{aligned}f_{xx}(x, y) &= \frac{2(x^2 + y) - 2x \cdot 2x}{(x^2 + y)^2} = \frac{2y - 2x^2}{(x^2 + y)^2} \\f_{xy}(x, y) &= \frac{-2x}{(x^2 + y)^2} \\f_{yx}(x, y) &= \frac{-2x}{(x^2 + y)^2} \\f_{yy}(x, y) &= \frac{-1}{(x^2 + y)^2}\end{aligned}$$

- $f(x, y) = e^{\frac{2x}{x+3y}}$ .

Start by computing the first-order partial derivatives:

$$\begin{aligned}f_x(x, y) &= \frac{2(x + 3y) - 2x}{(x + 3y)^2} e^{\frac{2x}{x+3y}} = \frac{6y}{(x + 3y)^2} e^{\frac{2x}{x+3y}} \\f_y(x, y) &= \frac{-6x}{(x + 3y)^2} e^{\frac{2x}{x+3y}}\end{aligned}$$

Therefore, it is possible to compute the second-order partial derivatives:

$$\begin{aligned}f_{xx}(x, y) &= \frac{-12y(x + 3y)}{((x + 3y)^2)^2} e^{\frac{2x}{x+3y}} + \frac{6y}{(x + 3y)^2} \frac{6y}{(x + 3y)^2} e^{\frac{2x}{x+3y}} = \frac{-12xy}{(x + 3y)^4} e^{\frac{2x}{x+3y}} \\f_{xy}(x, y) &= \frac{6(x + 3y)^2 - 36y(x + 3y)}{((x + 3y)^2)^2} e^{\frac{2x}{x+3y}} + \frac{6y}{(x + 3y)^2} \left( \frac{-6x}{(x + 3y)^2} \right) e^{\frac{2x}{x+3y}} = \frac{(6x^2 - 90y^2)e^{\frac{2x}{x+3y}}}{(x + 3y)^4} \\f_{yx}(x, y) &= \frac{-6(x + 3y)^2 - 12x(x + 3y)}{((x + 3y)^2)^2} e^{\frac{2x}{x+3y}} + \left( \frac{-6x}{(x + 3y)^2} \right) \frac{6y}{(x + 3y)^2} e^{\frac{2x}{x+3y}} = \frac{(6x^2 - 90y^2)e^{\frac{2x}{x+3y}}}{(x + 3y)^4} \\f_{yy}(x, y) &= \frac{-36x(x + 3y)}{((x + 3y)^2)^2} e^{\frac{2x}{x+3y}} + \left( \frac{-6x}{(x + 3y)^2} \right) \left( \frac{-6x}{((x + 3y)^2)^2} \right) e^{\frac{2x}{x+3y}} = \frac{-108xy}{(x + 3y)^4} e^{\frac{2x}{x+3y}}\end{aligned}$$

- $f(x, y) = \cos(x^2 + xy + y^2)$ .

Start by computing the first-order partial derivatives:

$$\begin{aligned}f_x(x, y) &= -(2x + y) \sin(x^2 + xy + y^2) \\f_y(x, y) &= -(x + 2y) \sin(x^2 + xy + y^2)\end{aligned}$$

Therefore, it is possible to compute the second-order partial derivatives:

$$\begin{aligned}f_{xx}(x, y) &= -2 \sin(x^2 + xy + y^2) - (2x + y)^2 \cos(x^2 + xy + y^2) \\f_{xy}(x, y) &= -\sin(x^2 + xy + y^2) - (2x + y)(x + 2y) \cos(x^2 + xy + y^2) \\f_{yx}(x, y) &= -\sin(x^2 + xy + y^2) - (x + 2y)(2x + y) \cos(x^2 + xy + y^2) \\f_{yy}(x, y) &= -2 \sin(x^2 + xy + y^2) - (x + 2y)^2 \cos(x^2 + xy + y^2)\end{aligned}$$

**N.B.:** In all cases, whenever the function is continuous, Schwarz's theorem guarantees  $f_{xy}(x, y) = f_{yx}(x, y)$ .

## 4.2 Exercise 2

Discuss which kind of stationary points you obtain from the following functions:

- $f(x, y) = x^3 + y^3 + xy$ .

Start by finding the function's stationary points by solving  $\nabla f(x, y) = 0$ :

$$\begin{cases} 3x^2 + y = 0 \\ 3y^2 + x = 0 \end{cases} \quad \text{from the first equation, let } y = -3x^2.$$

$$\begin{cases} y = -3x^2 \\ 27x^4 + x = 0 \end{cases} \Rightarrow \begin{cases} y = -3x^2 \\ x(27x^3 + 1) = 0 \end{cases} \Rightarrow \begin{cases} y = -3x^2 \\ x = 0 \vee x = -\frac{1}{3} \end{cases}$$

Therefore, it is possible to conclude that  $P_1(0, 0)$  and  $P_2(-\frac{1}{3}, -\frac{1}{3})$  are the function's stationary points.

At this point, compute the Hessian matrix:

$$Hf(x, y) = \begin{bmatrix} 6x & 1 \\ 1 & 6y \end{bmatrix}$$

Consider each point separately:

1.  $P_1(0, 0)$

$$Hf(0, 0) = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \Rightarrow \det(Hf(0, 0)) = -1$$

Therefore, since  $\det(Hf(0, 0)) < 0$ ,  $P_1(0, 0)$  is a saddle point.

2.  $P_2(-\frac{1}{3}, -\frac{1}{3})$

$$Hf(-\frac{1}{3}, -\frac{1}{3}) = \begin{bmatrix} -2 & 1 \\ 1 & -2 \end{bmatrix} \Rightarrow \det(Hf(-\frac{1}{3}, -\frac{1}{3})) = 3$$

Therefore, since  $\det(Hf(-\frac{1}{3}, -\frac{1}{3})) > 0$  and  $f_{xx}(-\frac{1}{3}, -\frac{1}{3}) = -2 < 0$ ,  $P_2(-\frac{1}{3}, -\frac{1}{3})$  is a maximum point.

- $f(x, y) = x^3 - y^3 + xy$ .

Start by finding the function's stationary points by solving  $\nabla f(x, y) = 0$ :

$$\begin{cases} 3x^2 + y = 0 \\ -3y^2 + x = 0 \end{cases} \quad \text{from the second equation, let } x = 3y^2.$$

$$\begin{cases} 27y^4 + y = 0 \\ x = 3y^2 \end{cases} \Rightarrow \begin{cases} y(27y^3 + 1) = 0 \\ x = 3y^2 \end{cases} \Rightarrow \begin{cases} y = 0 \vee y = -\frac{1}{3} \\ x = 3y^2 \end{cases}$$

Therefore, it is possible to conclude that  $P_1(0, 0)$  and  $P_2(\frac{1}{3}, -\frac{1}{3})$  are the function's stationary points.

At this point, compute the Hessian matrix:

$$Hf(x, y) = \begin{bmatrix} 6x & 1 \\ 1 & -6y \end{bmatrix}$$

Consider each point separately:

1.  $P_1(0, 0)$

$$Hf(0, 0) = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \Rightarrow \det(Hf(0, 0)) = -1$$

Therefore, since  $\det(Hf(0, 0)) < 0$ ,  $P_1(0, 0)$  is a saddle point.

2.  $P_2(\frac{1}{3}, -\frac{1}{3})$

$$Hf(\frac{1}{3}, -\frac{1}{3}) = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} \Rightarrow \det(Hf(\frac{1}{3}, -\frac{1}{3})) = 3$$

Therefore, since  $\det(Hf(\frac{1}{3}, -\frac{1}{3})) > 0$  and  $f_{xx}(\frac{1}{3}, -\frac{1}{3}) = 2 > 0$ ,  $P_2(\frac{1}{3}, -\frac{1}{3})$  is a minimum point.

- $f(x, y) = x^3 + 3xy^2 - 15x - 12y$ .

Start by finding the function's stationary points by solving  $\nabla f(x, y) = 0$ :

$$\begin{cases} 3x^2 + 3y^2 - 15 = 0 \\ 6xy - 12 = 0 \end{cases} \quad \text{simplify } x = \pm\sqrt{5 - y^2} \text{ and } xy = 2.$$

Consider the solutions to the first equation separately to find the stationary points:

1.  $x = -\sqrt{5 - y^2}$

$$\begin{cases} x = -\sqrt{5 - y^2} \\ -y\sqrt{5 - y^2} = 2 \end{cases}$$

Assuming  $-y\sqrt{5 - y^2} \geq 0$ , square both sides of the second equation and solve the system via quartic equations:

$$\begin{cases} x = -\sqrt{5 - y^2} \\ y^2(5 - y^2) = 4 \end{cases} \quad \text{let } t = y^2$$

$$\begin{cases} x = -\sqrt{5 - t} \\ 5t - t^2 - 4 = 0 \end{cases} \Rightarrow t = 1 \vee t = 4$$

However, since  $t = y^2$ , the equation actually has four solutions, meaning that it is possible to find the stationary points  $P_1(-2, -1)$ ,  $P_2(-2, 1)$ ,  $P_3(-1, -2)$  and  $P_4(-1, 2)$ .

$$2. x = \sqrt{5 - y^2}$$

$$\begin{cases} x = \sqrt{5 - y^2} \\ y\sqrt{5 - y^2} = 2 \end{cases}$$

Assuming  $y\sqrt{5 - y^2} \geq 0$ , square both sides of the equation and solve the system via quadric equations:

$$\begin{cases} x = \sqrt{5 - y^2} \\ y^2(5 - y^2) = 4 \end{cases} \quad \text{let } t = y^2$$

$$\begin{cases} x = \sqrt{5 - t} \\ 5t - t^2 - 4 = 0 \end{cases} \Rightarrow t = 1 \vee t = 4$$

However, since  $t = y^2$ , the equation actually has four solutions, meaning that it is possible to find the stationary points  $P_5(2, -1)$ ,  $P_6(2, 1)$ ,  $P_7(1, -2)$  and  $P_8(1, 2)$ .

At this point, compute the Hessian matrix:

$$Hf(x, y) = \begin{bmatrix} 6x & 6y \\ 6y & 6x \end{bmatrix}$$

Consider each point separately:

$$1. P_1(-2, -1)$$

$$Hf(-2, -1) = \begin{bmatrix} -12 & -6 \\ -6 & -12 \end{bmatrix} \Rightarrow \det(Hf(-2, -1)) = 108$$

Therefore, since  $\det(Hf(-2, -1)) > 0$  and  $f_{xx}(-2, -1) = -12 < 0$ ,  $P_1(-2, -1)$  is a maximum point.

$$2. P_2(-2, 1)$$

$$Hf(-2, 1) = \begin{bmatrix} -12 & 6 \\ 6 & -12 \end{bmatrix} \Rightarrow \det(Hf(-2, 1)) = 108$$

Therefore, since  $\det(Hf(-2, 1)) > 0$  and  $f_{xx}(-2, 1) = -12 < 0$ ,  $P_2(-2, 1)$  is a maximum point.

$$3. P_3(-1, -2)$$

$$Hf(-1, -2) = \begin{bmatrix} -6 & -12 \\ -12 & -6 \end{bmatrix} \Rightarrow \det(Hf(-1, -2)) = -108$$

Therefore, since  $\det(Hf(-1, -2)) < 0$ ,  $P_3(-1, -2)$  is a saddle point.

$$4. P_4(-1, 2)$$

$$Hf(-1, 2) = \begin{bmatrix} -6 & 12 \\ 12 & -6 \end{bmatrix} \Rightarrow \det(Hf(-1, 2)) = -108$$

Therefore, since  $\det(Hf(-1, 2)) < 0$ ,  $P_4(-1, 2)$  is a saddle point.

5.  $P_5(2, -1)$

$$Hf(2, -1) = \begin{bmatrix} 12 & -6 \\ -6 & 12 \end{bmatrix} \Rightarrow \det(Hf(2, -1)) = 108$$

Therefore, since  $\det(Hf(2, -1)) > 0$  and  $f_{xx}(2, -1) = 12 > 0$ ,  $P_5(2, -1)$  is a minimum point.

6.  $P_6(2, 1)$

$$Hf(2, 1) = \begin{bmatrix} 12 & 6 \\ 6 & 12 \end{bmatrix} \Rightarrow \det(Hf(2, 1)) = 108$$

Therefore, since  $\det(Hf(2, 1)) > 0$  and  $f_{xx}(2, 1) = 12 > 0$ ,  $P_6(2, 1)$  is a minimum point.

7.  $P_7(1, -2)$

$$Hf(1, -2) = \begin{bmatrix} 6 & -12 \\ -12 & 6 \end{bmatrix} \Rightarrow \det(Hf(1, -2)) = -108$$

Therefore, since  $\det(Hf(1, -2)) < 0$ ,  $P_7(1, -2)$  is a saddle point.

8.  $P_8(1, 2)$

$$Hf(1, 2) = \begin{bmatrix} 6 & 12 \\ 12 & 6 \end{bmatrix} \Rightarrow \det(Hf(1, 2)) = -108$$

Therefore, since  $\det(Hf(1, 2)) < 0$ ,  $P_8(1, 2)$  is a saddle point.

- $f(x, y) = 2(x^2 + y^2 + 1) - (x^4 + y^4)$ .

Start by finding the function's stationary points by solving  $\nabla f(x, y) = 0$ :

$$\begin{cases} 4x - 4x^3 = 0 \\ 4y - 4y^3 = 0 \end{cases} \quad \text{from the first equation, let } 4x - 4x^3 = 0 \Leftrightarrow x = 0 \vee x = -1 \vee x = 1.$$

Consider each solution separately to find the stationary points:

1.  $x = 0$

$$\begin{cases} x = 0 \\ 4y(1 - y^2) = 0 \end{cases} \Rightarrow \begin{cases} x = 0 \\ y = 0 \vee y = \pm 1 \end{cases}$$

Therefore, it is possible to find the stationary points  $P_1(0, 0)$ ,  $P_2(0, -1)$  and  $P_3(0, 1)$ .

2.  $x = -1$

$$\begin{cases} x = -1 \\ 4y(1 - y^2) = 0 \end{cases} \Rightarrow \begin{cases} x = -1 \\ y = 0 \vee y = \pm 1 \end{cases}$$

Therefore, it is possible to find the stationary points  $P_4(-1, 0)$ ,  $P_5(-1, -1)$  and  $P_6(-1, 1)$ .

3.  $x = 1$

$$\begin{cases} x = 1 \\ 4y(1 - y^2) = 0 \end{cases} \Rightarrow \begin{cases} x = 1 \\ y = 0 \vee y = \pm 1 \end{cases}$$

Therefore, it is possible to find the stationary points  $P_7(1, 0)$ ,  $P_8(1, -1)$  and  $P_9(1, 1)$ .

At this point, compute the Hessian matrix:

$$Hf(x, y) = \begin{bmatrix} 4 - 12x^2 & 0 \\ 0 & 4 - 12y^2 \end{bmatrix}$$

Consider each point separately:

1.  $P_1(0, 0)$

$$Hf(0, 0) = \begin{bmatrix} 4 & 0 \\ 0 & 4 \end{bmatrix} \Rightarrow \det(Hf(0, 0)) = 16$$

Therefore, since  $\det(Hf(0, 0)) > 0$  and  $f_{xx}(0, 0) = 4 > 0$ ,  $P_1(0, 0)$  is a minimum point.

2.  $P_2(0, -1)$

$$Hf(0, -1) = \begin{bmatrix} 4 & 0 \\ 0 & -8 \end{bmatrix} \Rightarrow \det(Hf(0, -1)) = -32$$

Therefore, since  $\det(Hf(0, -1)) < 0$ ,  $P_2(0, -1)$  is a saddle point.

3.  $P_3(0, 1)$

$$Hf(0, 1) = \begin{bmatrix} 4 & 0 \\ 0 & -8 \end{bmatrix} \Rightarrow \det(Hf(0, 1)) = -32$$

Therefore, since  $\det(Hf(0, 1)) < 0$ ,  $P_3(0, 1)$  is a saddle point.

4.  $P_4(-1, 0)$

$$Hf(-1, 0) = \begin{bmatrix} -8 & 0 \\ 0 & 4 \end{bmatrix} \Rightarrow \det(Hf(-1, 0)) = -32$$

Therefore, since  $\det(Hf(-1, 0)) < 0$ ,  $P_4(-1, 0)$  is a saddle point.

5.  $P_5(-1, -1)$

$$Hf(-1, -1) = \begin{bmatrix} -8 & 0 \\ 0 & -8 \end{bmatrix} \Rightarrow \det(Hf(-1, -1)) = 64$$

Therefore, since  $\det(Hf(-1, -1)) > 0$  and  $f_{xx}(-1, -1) = -8 < 0$ ,  $P_5(-1, -1)$  is a maximum point.

6.  $P_6(-1, 1)$

$$Hf(-1, 1) = \begin{bmatrix} -8 & 0 \\ 0 & -8 \end{bmatrix} \Rightarrow \det(Hf(-1, 1)) = 64$$

Therefore, since  $\det(Hf(-1, 1)) > 0$  and  $f_{xx}(-1, 1) = -8 < 0$ ,  $P_6(-1, 1)$  is a maximum point.

7.  $P_7(1, 0)$

$$Hf(1, 0) = \begin{bmatrix} -8 & 0 \\ 0 & 4 \end{bmatrix} \Rightarrow \det(Hf(1, 0)) = -32$$

Therefore, since  $\det(Hf(1, 0)) < 0$ ,  $P_7(1, 0)$  is a saddle point.

8.  $P_8(1, -1)$

$$Hf(1, -1) = \begin{bmatrix} -8 & 0 \\ 0 & -8 \end{bmatrix} \Rightarrow \det(Hf(1, -1)) = 64$$

Therefore, since  $\det(Hf(1, -1)) > 0$  and  $f_{xx}(1, -1) = -8 < 0$ ,  $P_8(1, -1)$  is a maximum point.

9.  $P_9(1, 1)$

$$Hf(1, 1) = \begin{bmatrix} -8 & 0 \\ 0 & -8 \end{bmatrix} \Rightarrow \det(Hf(1, 1)) = 64$$

Therefore, since  $\det(Hf(1, 1)) > 0$  and  $f_{xx}(1, 1) = -8 < 0$ ,  $P_9(1, 1)$  is a maximum point.

- $f(x, y) = 2x^4 - 16x^2y^2 + x$ .

Start by finding the function's stationary points by solving  $\nabla f(x, y) = 0$ :

$$\begin{cases} 8x^3 - 32xy^2 + 1 = 0 \\ -32x^2y = 0 \end{cases} \quad \text{from the second equation, let } 32x^2y = 0 \Leftrightarrow x = 0 \vee y = 0$$

Consider two separate systems:

$$\begin{cases} x = 0 \\ 1 = 0 \end{cases} \quad \vee \quad \begin{cases} y = 0 \\ 8x^3 + 1 = 0 \end{cases}$$

Therefore, since the first system has no solutions, it is possible to conclude that  $P_1(-\frac{1}{2}, 0)$  is the function's sole stationary point.

At this point, compute the Hessian matrix:

$$Hf(x, y) = \begin{bmatrix} 24x^2 - 32y^2 & -64xy \\ -64xy & -32x^2 \end{bmatrix}$$

Consider the matrix for  $P_1(-\frac{1}{2}, 0)$ :

$$Hf(-\frac{1}{2}, 0) = \begin{bmatrix} 6 & 0 \\ 0 & -8 \end{bmatrix} \Rightarrow \det(Hf(-\frac{1}{2}, 0)) = -48$$

Therefore, since  $\det(Hf(-\frac{1}{2}, 0)) < 0$ ,  $P_1(-\frac{1}{2}, 0)$  is a saddle point.



- $f(x, y, z) = (x^3 - x)(y^2 + z^2 - 1)$ .

Start by finding the function's stationary points by solving  $\nabla f(x, y, z) = 0$ :

$$\begin{cases} (3x^2 - 1)(y^2 + z^2 - 1) = 0 \\ 2y(x^3 - x) = 0 \\ 2z(x^3 - x) = 0 \end{cases} \quad \text{choose } 2y(x^3 - x) = 0 \Leftrightarrow y = 0 \vee x = 0 \vee x = \pm 1$$

Consider each solution separately to find the stationary points:

1.  $y = 0$

$$\begin{cases} y = 0 \\ (3x^2 - 1)(z^2 - 1) = 0 \\ 2z(x^3 - x) = 0 \end{cases} \quad \text{choose } 2z(x^3 - x) = 0 \Leftrightarrow z = 0 \vee x = 0 \vee x = \pm 1$$

Again, consider each solution separately:

- (a)  $z = 0$

$$\begin{cases} y = 0 \\ z = 0 \\ -(3x^2 - 1) = 0 \end{cases} \Rightarrow \begin{cases} y = 0 \\ z = 0 \\ x = \pm \frac{\sqrt{3}}{3} \end{cases}$$

Therefore, it is possible to find the stationary points  $P_1(-\frac{\sqrt{3}}{3}, 0, 0)$  and  $P_2(\frac{\sqrt{3}}{3}, 0, 0)$ .

- (b)  $x = 0$

$$\begin{cases} y = 0 \\ x = 0 \\ -(z^2 - 1) = 0 \end{cases} \Rightarrow \begin{cases} y = 0 \\ x = 0 \\ z = \pm 1 \end{cases}$$

Therefore, it is possible to find the stationary points  $P_3(0, 0, -1)$  and  $P_4(0, 0, 1)$ .

- (c)  $x = -1$

$$\begin{cases} y = 0 \\ x = -1 \\ 2(z^2 - 1) = 0 \end{cases} \Rightarrow \begin{cases} y = 0 \\ x = -1 \\ z = \pm 1 \end{cases}$$

Therefore, it is possible to find the stationary points  $P_5(-1, 0, -1)$  and  $P_6(-1, 0, 1)$ .

- (d)  $x = 1$

$$\begin{cases} y = 0 \\ x = 1 \\ 2(z^2 - 1) = 0 \end{cases} \Rightarrow \begin{cases} y = 0 \\ x = 1 \\ z = \pm 1 \end{cases}$$

Therefore, it is possible to find the stationary points  $P_7(1, 0, -1)$  and  $P_8(1, 0, 1)$ .

2.  $x = 0$

$$\begin{cases} x = 0 \\ -(y^2 + z^2 - 1) = 0 \\ 0 = 0 \end{cases}$$

Since this system has infinite solutions, parametrize  $y^2 + z^2 = 1$  as a unit circle and consider  $P_9(0, \cos \theta, \sin \theta)$ , with  $\theta \in [0, 2\pi]$  to be a stationary point for the function.

3.  $x = -1$

$$\begin{cases} x = -1 \\ 2(y^2 + z^2 - 1) = 0 \\ 0 = 0 \end{cases}$$

Since this system has infinite solutions, parametrize  $y^2 + z^2 = 1$  as a unit circle and consider  $P_{10}(-1, \cos \theta, \sin \theta)$ , with  $\theta \in [0, 2\pi]$  to be a stationary point for the function.

4.  $x = 1$

$$\begin{cases} x = 1 \\ 2(y^2 + z^2 - 1) = 0 \\ 0 = 0 \end{cases}$$

Since this system has infinite solutions, parametrize  $y^2 + z^2 = 1$  as a unit circle and consider  $P_{11}(1, \cos \theta, \sin \theta)$ , with  $\theta \in [0, 2\pi]$  to be a stationary point for the function.

At this point, compute the Hessian matrix:

$$Hf(x, y, z) = \begin{bmatrix} 6x(y^2 + z^2 - 1) & 2y(3x^2 - 1) & 2z(3x^2 - 1) \\ 2y(3x^2 - 1) & 2(x^3 - x) & 0 \\ 2z(3x^2 - 1) & 0 & 2(x^3 - x) \end{bmatrix}$$

Consider each point separately:

1.  $P_1(-\frac{\sqrt{3}}{3}, 0, 0)$

$$Hf(-\frac{\sqrt{3}}{3}, 0, 0) = \begin{bmatrix} 2\sqrt{3} & 0 & 0 \\ 0 & \frac{4\sqrt{3}}{9} & 0 \\ 0 & 0 & \frac{4\sqrt{3}}{9} \end{bmatrix} \Rightarrow \lambda_1 = 2\sqrt{3}, \lambda_{2,3} = \frac{4\sqrt{3}}{9}$$

Therefore, since the Hessian matrix is positive-definite,  $P_1(-\frac{\sqrt{3}}{3}, 0, 0)$  is a minimum point.

2.  $P_2(\frac{\sqrt{3}}{3}, 0, 0)$

$$Hf(\frac{\sqrt{3}}{3}, 0, 0) = \begin{bmatrix} -2\sqrt{3} & 0 & 0 \\ 0 & -\frac{4\sqrt{3}}{9} & 0 \\ 0 & 0 & -\frac{4\sqrt{3}}{9} \end{bmatrix} \Rightarrow \lambda_1 = -2\sqrt{3}, \lambda_{2,3} = -\frac{4\sqrt{3}}{9}$$

Therefore, since the Hessian matrix is negative-definite,  $P_2(\frac{\sqrt{3}}{3}, 0, 0)$  is a maximum point.

3.  $P_3(0, 0, -1)$

$$Hf(0, 0, -1) = \begin{bmatrix} 0 & 0 & 2 \\ 0 & 0 & 0 \\ 2 & 0 & 0 \end{bmatrix}$$

In this case, the eigenvalues must be found by solving the characteristic polynomial:

$$\lambda I - Hf = \begin{bmatrix} \lambda & 0 & -2 \\ 0 & \lambda & 0 \\ -2 & 0 & \lambda \end{bmatrix} \Rightarrow \det(\lambda I - Hf) = \lambda^3 - 4\lambda = 0 \Rightarrow \lambda_1 = 0, \lambda_2 = -2, \lambda_3 = 2$$

Therefore, since the matrix is semi-definite, the test is inconclusive for  $P_3(0, 0, -1)$ .

4.  $P_4(0, 0, 1)$

$$Hf(0, 0, 1) = \begin{bmatrix} 0 & 0 & -2 \\ 0 & 0 & 0 \\ -2 & 0 & 0 \end{bmatrix}$$

In this case, the eigenvalues must be found by solving the characteristic polynomial:

$$\lambda I - Hf = \begin{bmatrix} \lambda & 0 & 2 \\ 0 & \lambda & 0 \\ 2 & 0 & \lambda \end{bmatrix} \Rightarrow \det(\lambda I - Hf) = \lambda^3 - 4\lambda = 0 \Rightarrow \lambda_1 = 0, \lambda_2 = -2, \lambda_3 = 2$$

Therefore, since the matrix is semi-definite, the test is inconclusive for  $P_4(0, 0, 1)$ .

5.  $P_5(-1, 0, -1)$

$$Hf(-1, 0, -1) = \begin{bmatrix} 0 & 0 & -4 \\ 0 & 0 & 0 \\ -4 & 0 & 0 \end{bmatrix}$$

In this case, the eigenvalues must be found by solving the characteristic polynomial:

$$\lambda I - Hf = \begin{bmatrix} \lambda & 0 & 4 \\ 0 & \lambda & 0 \\ 4 & 0 & \lambda \end{bmatrix} \Rightarrow \det(\lambda I - Hf) = \lambda^3 - 16\lambda = 0 \Rightarrow \lambda_1 = 0, \lambda_2 = -4, \lambda_3 = 4$$

Therefore, since the matrix is semi-definite, the test is inconclusive for  $P_5(-1, 0, -1)$ .

6.  $P_6(-1, 0, 1)$

$$Hf(-1, 0, 1) = \begin{bmatrix} 0 & 0 & 4 \\ 0 & 0 & 0 \\ 4 & 0 & 0 \end{bmatrix}$$

In this case, the eigenvalues must be found by solving the characteristic polynomial:

$$\lambda I - Hf = \begin{bmatrix} \lambda & 0 & -4 \\ 0 & \lambda & 0 \\ -4 & 0 & \lambda \end{bmatrix} \Rightarrow \det(\lambda I - Hf) = \lambda^3 - 16\lambda = 0 \Rightarrow \lambda_1 = 0, \lambda_2 = -4, \lambda_3 = 4$$

Therefore, since the matrix is semi-definite, the test is inconclusive for  $P_6(-1, 0, 1)$ .

7.  $P_7(1, 0, -1)$

$$Hf(1, 0, -1) = \begin{bmatrix} 0 & 0 & -4 \\ 0 & 0 & 0 \\ -4 & 0 & 0 \end{bmatrix}$$

In this case, the eigenvalues must be found by solving the characteristic polynomial:

$$\lambda I - Hf = \begin{bmatrix} \lambda & 0 & 4 \\ 0 & \lambda & 0 \\ 4 & 0 & \lambda \end{bmatrix} \Rightarrow \det(\lambda I - Hf) = \lambda^3 - 16\lambda = 0 \Rightarrow \lambda_1 = 0, \lambda_2 = -4, \lambda_3 = 4$$

Therefore, since the matrix is semi-definite, the test is inconclusive for  $P_7(1, 0, -1)$ .

8.  $P_8(1, 0, 1)$

$$Hf(1, 0, 1) = \begin{bmatrix} 0 & 0 & 4 \\ 0 & 0 & 0 \\ 4 & 0 & 0 \end{bmatrix}$$

In this case, the eigenvalues must be found by solving the characteristic polynomial:

$$\lambda I - Hf = \begin{bmatrix} \lambda & 0 & -4 \\ 0 & \lambda & 0 \\ -4 & 0 & \lambda \end{bmatrix} \Rightarrow \det(\lambda I - Hf) = \lambda^3 - 16\lambda = 0 \Rightarrow \lambda_1 = 0, \lambda_2 = -4, \lambda_3 = 4$$

Therefore, since the matrix is semi-definite, the test is inconclusive for  $P_8(1, 0, 1)$ .

9.  $P_9(0, \cos \theta, \sin \theta)$

$$Hf(0, \cos \theta, \sin \theta) = \begin{bmatrix} 0 & -2 \cos \theta & -2 \sin \theta \\ -2 \cos \theta & 0 & 0 \\ -2 \sin \theta & 0 & 0 \end{bmatrix}$$

In this case, the eigenvalues must be found by solving the characteristic polynomial:

$$\lambda I - Hf = \begin{bmatrix} \lambda & 2 \cos \theta & 2 \sin \theta \\ 2 \cos \theta & \lambda & 0 \\ 2 \sin \theta & 0 & \lambda \end{bmatrix} \Rightarrow \det(\lambda I - Hf) = \lambda^3 - 4\lambda = 0 \Rightarrow \lambda_1 = 0, \lambda_{2,3} = \pm 2$$

Therefore, since the matrix is semi-definite, the test is inconclusive for  $P_9(0, \cos \theta, \sin \theta)$ .

10.  $P_{10}(-1, \cos \theta, \sin \theta)$

$$Hf(-1, \cos \theta, \sin \theta) = \begin{bmatrix} 0 & 4 \cos \theta & 4 \sin \theta \\ 4 \cos \theta & 0 & 0 \\ 4 \sin \theta & 0 & 0 \end{bmatrix}$$

In this case, eigenvalues must be found by solving the characteristic polynomial:

$$\lambda I - Hf = \begin{bmatrix} \lambda & -4 \cos \theta & -4 \sin \theta \\ -4 \cos \theta & \lambda & 0 \\ -4 \sin \theta & 0 & \lambda \end{bmatrix} \Rightarrow \det(\lambda I - Hf) = \lambda^3 - 16\lambda = 0 \Rightarrow \lambda_1 = 0, \lambda_{2,3} = \pm 4$$

Therefore, since the matrix is semi-definite, the test is inconclusive for  $P_{10}(-1, \cos \theta, \sin \theta)$ .

11.  $P_{11}(1, \cos \theta, \sin \theta)$

$$Hf(1, \cos \theta, \sin \theta) = \begin{bmatrix} 0 & 4 \cos \theta & 4 \sin \theta \\ 4 \cos \theta & 0 & 0 \\ 4 \sin \theta & 0 & 0 \end{bmatrix}$$

In this case, eigenvalues must be found by solving the characteristic polynomial:

$$\lambda I - Hf = \begin{bmatrix} \lambda & -4 \cos \theta & -4 \sin \theta \\ -4 \cos \theta & \lambda & 0 \\ -4 \sin \theta & 0 & \lambda \end{bmatrix} \Rightarrow \det(\lambda I - Hf) = \lambda^3 - 16\lambda = 0 \Rightarrow \lambda_1 = 0, \lambda_{2,3} = \pm 4$$

Therefore, since the matrix is semi-definite, the test is inconclusive for  $P_{11}(1, \cos \theta, \sin \theta)$ .

- $f(x, y, z) = x^2 + y^2 + (z^2 - 1)^2 + 12$ .

Start by finding the function's stationary points by solving  $\nabla f(x, y, z) = 0$ :

$$\begin{cases} 2x = 0 \\ 2y = 0 \\ 4z(z^2 - 1) = 0 \end{cases} \Rightarrow \begin{cases} x = 0 \\ y = 0 \\ z = 0 \vee z = \pm 1 \end{cases}$$

Therefore, it is possible to conclude that the function's stationary points are  $P_1(0, 0, 0)$ ,  $P_2(0, 0, -1)$  and  $P_3(0, 0, 1)$ .

At this point, compute the Hessian matrix:

$$Hf(x, y, z) = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 12z^2 - 4 \end{bmatrix}$$

Consider each point separately:

1.  $P_1(0, 0, 0)$

$$Hf(0, 0, 0) = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & -4 \end{bmatrix} \Rightarrow \lambda_{1,2} = 2, \lambda_3 = -4$$

Therefore, since the Hessian matrix is indefinite,  $P_1(0, 0, 0)$  is a saddle point.

2.  $P_2(0, 0, -1)$

$$Hf(0, 0, 0) = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 8 \end{bmatrix} \Rightarrow \lambda_{1,2} = 2, \lambda_3 = 8$$

Therefore, since the Hessian matrix is positive-definite,  $P_2(0, 0, -1)$  is a minimum point.

3.  $P_3(0, 0, 1)$

$$Hf(0, 0, 0) = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 8 \end{bmatrix} \Rightarrow \lambda_{1,2} = 2, \lambda_3 = 8$$

Therefore, since the Hessian matrix is positive-definite,  $P_3(0, 0, 1)$  is a minimum point.

## Chapter 5

# Exercise Sheet 5: Curves

### 5.1 Exercise 1

Consider the following parametric equations:

$$\gamma_1 : \begin{cases} x(t) = 2 - t \\ y(t) = 4t - t^2 \end{cases}, t \in [0, 4]$$

$$\gamma_2 : \begin{cases} x(t) = t - 6 \\ y(t) = 4 - t \end{cases}, t \in [4, 6]$$

$$\gamma_3 : \begin{cases} x(t) = 3 \cos t \\ y(t) = 5 \sin t \end{cases}, t \in [\pi, 2\pi]$$

- Write the Cartesian equations of the curves.

1. First curve:

Start by writing  $t$  in terms of one of the two parameters:

$$x(t) = 2 - t \Rightarrow t = 2 - x$$

At this point, substitute the value of  $t$  into the parametric equation of  $y$  to recover the corresponding Cartesian equation:

$$y(t) = 4(2 - x) - (2 - x)^2 = 8 - 4x - 4 + 4x - x^2 = 4 - x^2 \Rightarrow y = 4 - x^2$$

2. Second curve:

Start by writing  $t$  in terms of one of the two parameters:

$$x(t) = t - 6 \Rightarrow t = x + 6$$

At this point, substitute the value of  $t$  into the parametric equation of  $y$  in order to recover the corresponding Cartesian equation:

$$y(t) = 4 - (x + 6) = 4 - x - 6 = -x - 2 \Rightarrow y = -x - 2$$

3. Third curve:

Observe that this is actually the parametrization of an ellipse, meaning that the corresponding Cartesian equation will be given by:

$$\frac{x^2}{9} + \frac{y^2}{25} = 1$$

- Determine if the curves are closed and/or simple.

1. First curve:

By definition, the curve is said to be closed in  $[0, 4]$  if and only if  $\gamma_1(0) = \gamma_1(4)$ :

$$\gamma_1(0) = (2, 0) \neq (-2, 0) = \gamma_1(4)$$

Therefore, the curve is not closed in the interval  $[0, 4]$ .

In addition, the curve is said to be simple in  $(0, 4)$  if and only if, by picking  $a, b \in (0, 4)$ , it holds that  $\gamma_1(a) = \gamma_1(b)$ :

$$\begin{cases} 2 - a = 2 - b \\ 4a - a^2 = 4b - b^2 \end{cases} \Rightarrow \begin{cases} a = b \\ 4b - b^2 = 4b - b^2 \end{cases}$$

Therefore, since the condition is satisfied, the curve is indeed simple in  $(0, 4)$ .

**N.B.:** Alternatively, it is possible to directly confirm that the curve is simple by noticing that the first component is an injective function.

2. Second curve:

By definition, the curve is said to be closed in  $[4, 6]$  if and only if  $\gamma_2(4) = \gamma_2(6)$ :

$$\gamma_2(4) = (-2, 0) \neq (0, -2) = \gamma_2(6)$$

Therefore, the curve is not closed in the interval  $[4, 6]$ .

In addition, the curve is said to be simple in  $(4, 6)$  if and only if, by picking  $a, b \in (4, 6)$ , it holds that  $\gamma_2(a) = \gamma_2(b) \Leftrightarrow a = b$ :

$$\begin{cases} a - 6 = b - 6 \\ 4 - a = 4 - b \end{cases} \Rightarrow \begin{cases} a = b \\ a = b \end{cases}$$

Therefore, since the condition is satisfied, the curve is indeed simple in  $(4, 6)$ .

**N.B.:** Alternatively, it is possible to directly confirm that the curve is simple by noticing that both its components are injective functions.

3. Third curve:

By definition, the curve is said to be closed in  $[\pi, 2\pi]$  if and only if  $\gamma_3(\pi) = \gamma_3(2\pi)$ :

$$\gamma_3(\pi) = (-3, 0) \neq \gamma_3(2\pi) = (3, 0)$$



Therefore, the curve is not closed in the interval  $[\pi, 2\pi]$ .

In addition, the curve is said to be simple in  $(\pi, 2\pi)$  if and only if, by picking  $a, b \in (\pi, 2\pi)$ , it holds that  $\gamma_3(a) = \gamma_3(b) \Leftrightarrow a = b$ :

$$\begin{cases} 3 \cos a = 3 \cos b \\ 5 \sin a = 5 \sin b \end{cases} \Rightarrow \begin{cases} a = -b \\ -\sin b = \sin b \end{cases} \vee \begin{cases} a = b \\ \sin b = \sin b \end{cases}$$

Therefore, since the condition is satisfied, the curve is indeed simple in  $(\pi, 2\pi)$ .

- Find the tangent vector and the unit tangent vector to  $\gamma_1$  at the point  $P(1, 3)$ .

Start by finding the point  $t_0 \in [0, 4]$  such that  $\gamma_1(t_0) = P$ :

$$\begin{cases} 2 - t_0 = 1 \\ 4t_0 - t_0^2 = 3 \end{cases} \Rightarrow \begin{cases} t_0 = 1 \\ 4 - 1 = 3 \end{cases} \Rightarrow t_0 = 1 \in [0, 4]$$

At this point, find the generic parametric equation of the tangent vector of  $\gamma_1$ :

$$\gamma_1' : \begin{cases} x'(t) = -1 \\ y'(t) = 4 - 2t \end{cases}, t \in [0, 4]$$

Therefore, by plugging into the equation  $t_0 = x$ , it is possible to find the tangent vector at the point  $P$  as:

$$\gamma_1'(1) = (-1, 2)$$

Lastly, it is possible to recover the unit tangent vector at the point  $P$  by normalizing the tangent vector:

$$\|\gamma_1'(1)\| = \sqrt{1 + 4} = \sqrt{5} \Rightarrow \gamma_{1_u}'(1) = \left(-\frac{\sqrt{5}}{5}, \frac{2\sqrt{5}}{5}\right)$$

- Find the tangent vector and the unit tangent vector to  $\gamma_3$  at the point  $P(-\frac{3\sqrt{3}}{2}, -\frac{5}{2})$ .

Start by finding the point  $t_0 \in [\pi, 2\pi]$  such that  $\gamma_3(t_0) = P$ :

$$\begin{cases} 3 \cos t_0 = -\frac{3\sqrt{3}}{2} \\ 5 \sin t_0 = -\frac{5}{2} \end{cases} \Rightarrow \begin{cases} \cos t_0 = -\frac{\sqrt{3}}{2} \\ \sin t_0 = -\frac{1}{2} \end{cases} \Rightarrow t_0 = \frac{7\pi}{6} \in [\pi, 2\pi]$$

At this point, find the generic parametric equation of the tangent vector of  $\gamma_3$ :

$$\gamma_3' : \begin{cases} x'(t) = -3 \sin t \\ y'(t) = 5 \cos t \end{cases}$$

Therefore, by plugging into the equation  $t_0 = \frac{7\pi}{6}$ , it is possible to find the tangent vector at the point  $P$  as:

$$\gamma'_3\left(\frac{7\pi}{6}\right) = \left(\frac{3}{2}, -\frac{5\sqrt{3}}{2}\right)$$

Lastly, it is possible to recover the unit tangent vector at the point  $P$  by normalizing the tangent vector:

$$\|\gamma'_3\left(\frac{7\pi}{6}\right)\| = \sqrt{\frac{9}{4} + \frac{75}{4}} = \sqrt{21} \Rightarrow \gamma'_{3_u}\left(\frac{7\pi}{6}\right) = \left(\frac{\sqrt{21}}{14}, -\frac{5\sqrt{7}}{14}\right)$$

## 5.2 Exercise 2

Consider the curve  $\gamma(t) = (e^t, \sqrt{2}t)$ , for  $t \in [-1, 1]$ .

- Determine if the curve is closed.  
By definition, the curve is said to be closed in  $[-1, 1]$  if and only if  $\gamma(-1) = \gamma(1)$ :

$$\gamma(-1) = (e^{-1}, -\sqrt{2}) \neq (e, \sqrt{2}) = \gamma(1)$$

Therefore, the curve is not closed in  $[-1, 1]$ .

- Determine if the curve is simple.  
By definition, the curve is said to be simple in  $(-1, 1)$  if and only if, by picking  $a, b \in (-1, 1)$ , it holds that  $\gamma(a) = \gamma(b) \Leftrightarrow a = b$ :

$$\begin{cases} e^a = e^b \\ \sqrt{2}a = \sqrt{2}b \end{cases} \Rightarrow \begin{cases} a = b \\ a = b \end{cases}$$

Therefore, since the condition is satisfied, the curve is indeed simple in  $(-1, 1)$ .

**N.B.:** Alternatively, it is possible to directly confirm that the curve is simple by noticing that both components are injective functions.

- Determine if the curve is regular.  
By definition, the curve is said to be regular in  $(-1, 1)$  if and only if the tangent vector  $\gamma'(t)$  is component-wise continuous and  $\gamma'(t) \neq 0 \forall t \in (-1, 1)$ . Start by computing  $\gamma'(t) = (e^t, \sqrt{2})$  and study  $\gamma'(t) = 0$ :

$$\begin{cases} e^t = 0 \\ \sqrt{2} = 0 \end{cases}, \text{ which is an incompatible system.}$$

Therefore, since the condition is satisfied, the curve is indeed regular in  $(-1, 1)$ .

- Determine the tangent vector at the point  $P(1, 0)$ .  
Start by finding the point  $t_0 \in [-1, 1]$  such that  $\gamma(t_0) = P$ :

$$\begin{cases} e^{t_0} = 1 \\ \sqrt{2}t_0 = 0 \end{cases} \Rightarrow t_0 = 0 \in [-1, 1]$$

Therefore, given the generic equation of the tangent vector  $\gamma'(t) = (e^t, \sqrt{2})$ , it is possible to conclude that  $\gamma'(0) = (1, \sqrt{2})$ .

- Determine the Cartesian equation of the curve.  
Start by writing  $t$  in terms of one of the two parameters:

$$x(t) = e^t \Rightarrow t = \ln x$$

At this point, substitute the value of  $t$  into the parametric equation of  $y$  to recover the corresponding Cartesian equation:

$$y(t) = \sqrt{2} \ln x \Rightarrow y = \sqrt{2} \ln x$$

### 5.3 Exercise 3

Compute the length of the following curves:

- First curve:

$$\gamma : \begin{cases} x(t) = t^2 \\ y(t) = \frac{t^3}{3} - t \end{cases}, t \in [0, 1]$$

Start by computing the curve's tangent vector and show that it is regular in  $(0, 1)$ :

$$\gamma'(t) : \begin{cases} x'(t) = 2t \\ y'(t) = t^2 - 1 \end{cases} \Rightarrow \begin{cases} 2t = 0 \\ t^2 - 1 = 0 \end{cases}, \text{ which is an incompatible system.}$$

At this point, find the norm of the tangent vector:

$$\|\gamma'(t)\| = \sqrt{4t^2 + t^4 - 2t^2 + 1} = \sqrt{t^4 + 2t^2 + 1} = \sqrt{(t^2 + 1)^2} = t^2 + 1$$

Therefore, it is possible to conclude that:

$$L(\gamma) = \int_0^1 t^2 + 1 \, dt = \left[ \frac{t^3}{3} + t \right]_0^1 = \frac{4}{3}$$

- Second curve:

$$\gamma : \begin{cases} x(t) = 4t^3 - 3t \\ y(t) = 6t^2 \end{cases}, t \in [0, 1]$$

Start by computing the curve's tangent vector and show that it is regular in  $(0, 1)$ :

$$\gamma' : \begin{cases} x'(t) = 12t^2 - 3 \\ y'(t) = 12t \end{cases} \Rightarrow \begin{cases} 12t^2 - 3 = 0 \\ 12t = 0 \end{cases}, \text{ which is an incompatible system.}$$

At this point, find the norm of the tangent vector:

$$\|\gamma'(t)\| = \sqrt{144t^4 - 72t^2 + 9 + 144t^2} = \sqrt{144t^4 + 72t^2 + 9} = \sqrt{(12t^2 + 3)^2} = 12t^2 + 3$$

Therefore, it is possible to conclude that:

$$L(\gamma) = \int_0^1 12t^2 + 3 \, dt = [4t^3 + 3t]_0^1 = 7$$

## 5.4 Exercise 4

Consider the curve  $r : \mathbb{R} \rightarrow \mathbb{R}^2$  with parametric equations:

$$r(t) = (t^2, t^3)$$

- Determine if the curve is closed.

Observe that the curve cannot be closed in  $\mathbb{R}$  because, by taking the limits for  $t \rightarrow -\infty$  and  $t \rightarrow +\infty$ , it is possible to notice that:

$$\lim_{t \rightarrow -\infty} r(t) = (+\infty, -\infty) \neq (+\infty, +\infty) = \lim_{t \rightarrow +\infty} r(t)$$

- Determine if the curve is simple.

By definition, the curve is said to be simple in  $\mathbb{R}$  if and only if, by picking  $a, b \in \mathbb{R}$ , it holds that  $r(a) = r(b) \Leftrightarrow a = b$ :

$$\begin{cases} a^2 = b^2 \\ a^3 = b^3 \end{cases} \Rightarrow \begin{cases} a = -b \\ -b^3 = b^3 \end{cases} \vee \begin{cases} a = b \\ b^3 = b^3 \end{cases}$$

Therefore, since the condition is satisfied, the curve is indeed simple in  $\mathbb{R}$ .

**N.B.:** Alternatively, it is possible to directly confirm that the curve is simple by noticing that the second component is an injective function.

- Determine if the curve is regular.

By definition, the curve is said to be regular in  $\mathbb{R}$  if and only if the tangent vector  $r'(t)$  is component-wise continuous and  $r'(t) \neq 0 \, \forall \, t \in \mathbb{R}$ .

Start by computing  $r'(t) = (2t, 3t^2)$  and study  $r'(t) = 0$ :

$$\begin{cases} 2t = 0 \\ 3t^2 = 0 \end{cases} \Leftrightarrow t = 0 \in \mathbb{R}$$

Therefore, since the condition is not satisfied, the curve cannot be regular in  $\mathbb{R}$ .

- Compute the length of the curve starting from the point  $P_1(0, 0)$  to the point  $P_2(1, 1)$ .

Start by finding the points  $a, b \in \mathbb{R}^3$  such that  $r(a) = P_1$  and  $r(b) = P_2$ :

$$\begin{cases} a^2 = 0 \\ a^3 = 0 \end{cases} \Leftrightarrow a = 0$$

$$\begin{cases} b^2 = 1 \\ b^3 = 1 \end{cases} \Leftrightarrow b = 1$$

Show that the curve is regular at least in  $(0, 1)$ :

$$r'(t) = (2t, 3t^2) \Rightarrow \begin{cases} 2t = 0 \\ 3t^2 = 0 \end{cases} \Leftrightarrow t = 0 \notin (0, 1)$$

At this point, compute the norm of the tangent vector:

$$\|r'(t)\| = \sqrt{4t^2 + 9t^4} = \sqrt{t^2(4 + 9t^2)} = t\sqrt{4 + 9t^2}$$

Therefore, it is possible to conclude that:

$$L(r) = \int_0^1 t\sqrt{4 + 9t^2} dt$$

Apply a change of variable: let  $u = 4 + 9t^2$ , for  $u \in [4, 13]$ , and consider  $\frac{du}{dt} = 18t$ , resulting in:

$$L(r) = \frac{1}{18} \int_4^{13} \sqrt{u} du = \frac{1}{18} \frac{2}{3} [u^{\frac{3}{2}}]_4^{13} = \frac{1}{27} (\sqrt{13^3} - \sqrt{4^3}) = \frac{(\sqrt{13^3} - 8)}{27}$$

## 5.5 Exercise 5

Compute the length of the curve  $y = \frac{2}{3}\sqrt{(x-1)^3}$ , for  $x \in [1, 4]$ .

Start by parametrizing the Cartesian equation of the curve by setting  $x(t) = t$  and plug in this value into the equation of  $y(t)$ , resulting in:

$$\gamma : \begin{cases} x(t) = t \\ y(t) = \frac{2}{3}\sqrt{(t-1)^3} \end{cases}, t \in [1, 4]$$

Compute the equation of the tangent vector and show that it is regular in  $(1, 4)$ :

$$\gamma' : \begin{cases} x'(t) = 1 \\ y'(t) = \sqrt{t-1} \end{cases} \Rightarrow \begin{cases} 1 = 0 \\ \sqrt{t-1} = 0 \end{cases}, \text{ which is an incompatible system.}$$

At this point, compute the norm of the tangent vector:

$$\|\gamma'(t)\| = \sqrt{1 + t - 1} = \sqrt{t}$$

Therefore, it is possible to conclude that:

$$L(\gamma) = \int_1^4 \sqrt{t} \, dt = \left[ \frac{t^{\frac{3}{2}}}{\frac{3}{2}} \right]_1^4 = \frac{2}{3}(\sqrt{64} - 1) = \frac{2}{3}(8 - 1) = \frac{14}{3}$$

## 5.6 Exercise 6

Let  $r : [-1, 0] \rightarrow \mathbb{R}^3$  be the curve in space with parametric equation:

$$r(t) = (3t^2, 1 + 3t, 2t^3)$$

- Determine if the curve is closed.  
By definition, the curve is said to be closed in  $[-1, 0]$  if and only if  $r(-1) = r(0)$ :

$$r(-1) = (3, -2, -2) \neq (0, 1, 0) = r(0)$$

Therefore, the curve is not closed in the interval  $[-1, 0]$ .

- Determine if the curve is simple.  
By definition, the curve is said to be simple in  $(-1, 0)$  if and only if, by picking  $a, b \in (-1, 0)$ , it holds that  $r(a) = r(b) \Leftrightarrow a = b$ :

$$\begin{cases} 3a^2 = 3b^2 \\ 1 + 3a = 1 + 3b \\ 2a^3 = 2b^3 \end{cases} \Rightarrow \begin{cases} b^2 = b^2 \\ a = b \\ b^3 = b^3 \end{cases}$$

Therefore, since the condition is satisfied, the curve is indeed simple in  $(-1, 0)$ .

**N.B.:** Alternatively, it is possible to directly confirm that the curve is simple by noticing that the second and third components are injective functions and that the first component, while not injective in  $\mathbb{R}$ , is injective at least in  $(-1, 0)$ .

- Determine if the curve is regular.  
By definition, the curve is said to be regular in  $(-1, 0)$  if and only if the tangent vector  $r'(t)$  is component-wise continuous and  $r'(t) \neq 0 \, \forall \, t \in (-1, 0)$ . Start by computing  $r'(t) = (6t, 3, 6t^2)$  and study  $r'(t) = 0$ :

$$\begin{cases} 6t = 0 \\ 3 = 0 \\ 6t^2 = 0 \end{cases}, \text{ which is an incompatible system.}$$

Therefore, since the condition is satisfied, the curve is indeed regular in  $(-1, 0)$ .

- Compute the length of the curve.  
Knowing that the curve is regular in  $(-1, 0)$ , start by computing the norm of the tangent vector:

$$\|r'(t)\| = \sqrt{36t^2 + 9 + 36t^4} = \sqrt{(6t^2 + 3)^2} = 6t^2 + 3$$

Therefore, it is possible to conclude that:

$$L(r) = \int_{-1}^0 6t^2 + 3 \, dt = [2t^3 + 3t]_{-1}^0 = 5$$

- Compute the tangent vector to  $r(t)$  at the point  $P(0, 1, 0)$ .  
Start by finding the point  $t_0 \in [-1, 0]$  such that  $r(t_0) = P$ :

$$\begin{cases} 3t_0^2 = 0 \\ 1 + 3t_0 = 1 \\ 2t_0^3 = 0 \end{cases} \Rightarrow t_0 = 0 \in [-1, 0]$$

Therefore, given the tangent vector  $r'(t) = (6t, 3, 6t^2)$ , it is possible to conclude that  $r'(0) = (0, 3, 0)$ .

## 5.7 Exercise 7

Compute the length of the segment of  $\mathbb{R}^3$  that links  $P_1(1, 2, 3)$  to  $P_2(0, 4, 1)$ .  
Start by considering the generic parametric equation of a segment in  $\mathbb{R}^3$ :

$$\gamma : \begin{cases} x = x_0 + at \\ y = y_0 + bt \\ z = z_0 + ct \end{cases}, \text{ with } a, b, c \in \mathbb{R}.$$

Assume that the segment is defined in  $[0, 1]$ , and, by picking  $(x_0, y_0, z_0) = P_1$ , rewrite this equation in the following way:

$$\gamma : \begin{cases} x = 1 + at \\ y = 2 + bt \\ z = 3 + ct \end{cases} \text{ with } t \in [0, 1]$$

However, the segment must also pass through  $P_2$ , meaning that it is possible to find  $a, b, c$  by solving the following system:

$$\begin{cases} 0 = 1 + at \\ 4 = 2 + bt \\ 1 = 3 + ct \end{cases} \text{ with } t = 1 \Rightarrow \begin{cases} a = -1 \\ b = 2 \\ c = -2 \end{cases}$$

Therefore, the parametric equation of the segment will be given by:

$$\gamma : \begin{cases} x = 1 - t \\ y = 2 + 2t \\ z = 3 - 2t \end{cases}$$

At this point, compute the tangent vector and find its norm:

$$\gamma' : \begin{cases} x' = -1 \\ y' = 2 \\ z' = -2 \end{cases} \Rightarrow \|\gamma'(t)\| = \sqrt{1 + 4 + 4} = \sqrt{9} = 3$$

Therefore, it is possible to conclude that:

$$L(\gamma) = \int_0^1 3 \, dt = [3t]_0^1 = 3$$



## Chapter 6

# Exercise Sheet 6: Curves and line integrals

### 6.1 Exercise 1

Let  $\gamma$  be the curve with Cartesian equation  $y = x^3$ , with  $x \in [0, 1]$ :

- Write the parametric equation for  $\gamma$ .  
Start by parametrizing  $x(t) = t$ , for  $t \in [0, 1]$ , allowing to conclude that:

$$\gamma : \begin{cases} x(t) = t \\ y(t) = t^3 \end{cases}, t \in [0, 1]$$

- Determine if the curve is simple or regular.  
By definition, the curve is said to be simple in  $(0, 1)$  if and only if, by picking  $a, b \in (0, 1)$ , it holds that  $\gamma(a) = \gamma(b) \Leftrightarrow a = b$ :

$$\begin{cases} a = b \\ a^3 = b^3 \end{cases} \Leftrightarrow a = b$$

Therefore, since the condition is satisfied, the curve is indeed simple in  $(0, 1)$ .

**N.B.:** Alternatively, it is possible to directly confirm that the curve is simple by noticing that both components are injective functions in the interval  $(0, 1)$ .

On the other hand, the curve is defined to be regular in the interval  $(0, 1)$  if and only if the tangent vector  $\gamma'(t)$  is component-wise continuous and  $\gamma'(t) \neq 0 \forall t \in (0, 1)$ .

Start by computing  $\gamma'(t) = (1, 3t^2)$  and study  $\gamma'(t) = 0$ :

$$\begin{cases} 1 = 0 \\ 3t^2 = 0 \end{cases}, \text{ which is an incompatible system.}$$

Therefore, since the condition is satisfied, the curve is indeed regular in  $(0, 1)$ .

- Compute the line integral of  $f(x, y) = x^3 + y$  with respect to  $\gamma$ .  
Knowing that  $\gamma'(t) = (1, 3t^2)$ , let  $\|\gamma'(t)\| = \sqrt{1 + 9t^4}$  and compute the following integral:

$$\int_{\gamma} x^3 + y \, dt = \int_0^1 (t^3 + t^3) \sqrt{1 + 9t^4} \, dt = \int_0^1 2t^3 \sqrt{1 + 9t^4} \, dt$$

Apply a change of variable and let  $u = 1 + 9t^4$ , for  $u = [1, 10]$ , and recover  $\frac{du}{dt} = 36t^3$ , allowing to conclude that:

$$\frac{2}{36} \int_1^{10} \sqrt{u} \, du = \frac{1}{18} \left[ \frac{u^{\frac{3}{2}}}{\frac{3}{2}} \right]_1^{10} = \frac{1}{27} ((10)^{\frac{3}{2}} - 1) = \frac{\sqrt{1000} - 1}{27}$$

## 6.2 Exercise 2

Let  $\gamma$  be the arc of a hyperbola  $y = \frac{1}{x}$ , with  $x \in [\frac{1}{2}, 2]$ :

- Write the parametric equation for  $\gamma$ .  
Start by parametrizing  $x(t) = t$ , for  $t \in [\frac{1}{2}, 2]$ , allowing to conclude that:

$$\gamma : \begin{cases} x(t) = t \\ y(t) = \frac{1}{t} \end{cases}, \quad t \in [\frac{1}{2}, 2]$$

- Determine if the curve is regular.  
By definition, the curve is said to be regular in the interval  $(\frac{1}{2}, 2)$  if and only if the tangent vector  $\gamma'(t)$  is component-wise continuous and  $\gamma'(t) \neq 0 \, \forall \, t \in [\frac{1}{2}, 2]$ .  
Start by computing  $\gamma'(t) = (1, -\frac{1}{t^2})$  and study  $\gamma'(t) = 0$ :

$$\begin{cases} 1 = 0 \\ -\frac{1}{t^2} = 0 \end{cases}, \text{ which is an incompatible system.}$$

Therefore, since the condition is satisfied, the curve is indeed regular in  $(\frac{1}{2}, 2)$ .

- Compute the line integral of  $f(x, y) = x^5$  with respect to  $\gamma$ .  
Knowing that  $\gamma'(t) = (1, -\frac{1}{t^2})$ , let  $\|\gamma'(t)\| = \frac{\sqrt{t^4 + 1}}{t^2}$  and compute the following integral:

$$\int_{\gamma} x^5 \, dt = \int_{\frac{1}{2}}^2 t^5 \frac{\sqrt{t^4 + 1}}{t^2} \, dt = \int_{\frac{1}{2}}^2 t^3 \sqrt{t^4 + 1} \, dt$$

Apply a change of variable and let  $u = t^4 + 1$ , for  $t \in [\frac{1}{2}, 2]$ , and recover  $\frac{du}{dt} = 4t^3$ , allowing to conclude that:

$$\frac{1}{4} \int_{\frac{17}{16}}^{17} \sqrt{u} \, du = \frac{1}{4} \left[ \frac{u^{\frac{3}{2}}}{\frac{3}{2}} \right]_{\frac{17}{16}}^{17} = \frac{1}{6} \left( (17)^{\frac{3}{2}} - \left( \frac{17}{16} \right)^{\frac{3}{2}} \right) = \frac{\sqrt{17^3} - \sqrt{\left( \frac{17}{16} \right)^3}}{6}$$

### 6.3 Exercise 3

Compute the following line integrals:

- $f(x, y) = x^5$ , with respect to the curve  $\gamma$  given by  $y = \frac{1}{x}$ , for  $x \in [\frac{1}{2}, 2]$ .  
Start by parametrizing  $\gamma$  from the Cartesian equation:

$$\gamma : \begin{cases} x(t) = t \\ y(t) = \frac{1}{t} \end{cases}, \quad t \in [\frac{1}{2}, 2]$$

Compute the norm of the tangent vector:

$$\gamma'(t) = (1, -\frac{1}{t^2}) \Rightarrow \|\gamma'(t)\| = \sqrt{1 + \frac{1}{t^4}} = \sqrt{\frac{t^4 + 1}{t^4}} = \frac{\sqrt{t^4 + 1}}{t^2}$$

Therefore, it is possible to compute the line integral in the following way:

$$\int_{\gamma} x^5 \, dt = \int_{\frac{1}{2}}^2 t^5 \frac{\sqrt{t^4 + 1}}{t^2} \, dt = \int_{\frac{1}{2}}^2 t^3 \sqrt{t^4 + 1} \, dt$$

Apply a change of variable: let  $u = t^4 + 1$ , for  $u \in [\frac{17}{16}, 17]$ , and consider  $\frac{du}{dt} = 4t^3$ , allowing to conclude that:

$$\frac{1}{4} \int_{\frac{17}{16}}^{17} \sqrt{u} \, du = \frac{1}{4} \frac{2}{3} \left[ u^{\frac{3}{2}} \right]_{\frac{17}{16}}^{17} = \frac{\sqrt{17^3} - \sqrt{\left( \frac{17}{16} \right)^3}}{6}$$

- $f(x, y) = \sin(xy)$ , with respect to the square with vertices  $(0, 0)$ ,  $(1, 0)$ ,  $(1, 1)$ ,  $(0, 1)$ .  
By plotting the square, let  $\gamma = \gamma_1 \cup \gamma_2 \cup \gamma_3 \cup \gamma_4$  and consider each curve separately:

1. Let  $\gamma_1(t) = (t, 0)$ , for  $t \in [0, 1]$ .

Compute the norm of the tangent vector:

$$\gamma_1'(t) = (1, 0) \Rightarrow \|\gamma_1'(t)\| = \sqrt{1 + 0} = 1$$

Therefore, it is possible to compute the line integral in the following way:

$$\int_{\gamma_1} \sin(xy) \, dt = \int_0^1 \sin(0t) \, dt = \int_0^1 0 \, dt = 0$$

2. Let  $\gamma_2(t) = (1, t)$ , for  $t \in [0, 1]$ .

Compute the norm of the tangent vector:

$$\gamma_2'(t) = (0, 1) \Rightarrow \|\gamma_2'(t)\| = \sqrt{0+1} = 1$$

Therefore, it is possible to compute the line integral in the following way:

$$\int_{\gamma_2} \sin(xy) \, dt = \int_0^1 \sin t \, dt = [-\cos t]_0^1 = 1 - \cos 1$$

3. Let  $\gamma_3(t) = (t, 1)$ , for  $t \in [1, 0]$  (in this case, the direction of traversal is inverted).

Compute the norm of the tangent vector:

$$\gamma_3'(t) = (1, 0) \Rightarrow \|\gamma_3'(t)\| = \sqrt{1+0} = 1$$

Therefore, it is possible to compute the line integral in the following way:

$$\int_{\gamma_3} \sin(xy) \, dt = \int_1^0 \sin t \, dt = - \int_0^1 \sin t \, dt = -[-\cos t]_0^1 = \cos 1 - 1$$

4. Let  $\gamma_4(t) = (0, t)$ , for  $t \in [1, 0]$  (in this case, the direction of traversal is inverted).

Compute the norm of the tangent vector:

$$\gamma_4'(t) = (0, 1) \Rightarrow \|\gamma_4'(t)\| = \sqrt{0+1} = 1$$

Therefore, it is possible to compute the line integral in the following way:

$$\int_{\gamma_4} \sin(xy) \, dt = \int_1^0 \sin(0t) \, dt = - \int_0^1 0 \, dt = 0$$

Therefore, by applying integral additivity, it is possible to conclude that:

$$\int_{\gamma} \sin(xy) \, dt = 0 + (1 - \cos 1) + (\cos 1 - 1) + 0 = 0$$

- $f(x, y) = \sqrt{x^2 + y^2}$ , with respect to  $\gamma = (2(\cos t + t \sin t), 2(\sin t - t \cos t))$  for  $t \in [0, 2\pi]$ .

Start by computing the norm of the tangent vector:

$$\gamma'(t) = (2t \cos t, 2t \sin t) \Rightarrow \|\gamma'(t)\| = \sqrt{4t^2 \cos^2 t + 4t^2 \sin^2 t} = 2t$$

Therefore, it is possible to compute the line integral in the following way:

$$\int_{\gamma} \sqrt{x^2 + y^2} \, dt = \int_0^{2\pi} \sqrt{(2(\cos t + t \sin t))^2 + (2(\sin t - t \cos t))^2} \cdot 2t \, dt = \int_0^{2\pi} 2\sqrt{t^2 + 1} \cdot 2t \, dt$$

Apply a change of variable: let  $u = t^2 + 1$ , for  $u \in [1, 4\pi^2 + 1]$ , and consider  $\frac{du}{dt} = 2t$ , allowing to conclude that:

$$2 \int_1^{4\pi^2+1} \sqrt{u} \, du = 2 \frac{2}{3} [u^{\frac{3}{2}}]_1^{4\pi^2+1} = \frac{4(\sqrt{(4\pi^2+1)^3} - 1)}{3}$$

## 6.4 Exercise 4

Given the curve  $\gamma$  with parametric equation:

$$\gamma : \begin{cases} x = t^2 \\ y = \frac{t^3}{3} - 1 \end{cases}, t \in [0, 1]$$

- Determine if the curve is closed, simple or regular.  
By definition, the curve will be closed in  $[0, 1]$  if and only if  $\gamma(0) = \gamma(1)$ :

$$\gamma(0) = (0, -1) \neq (1, -\frac{2}{3}) = \gamma(1)$$

Therefore, the curve is not closed in the interval  $[0, 1]$ .

In addition, the curve is said to be simple in  $(0, 1)$  if and only if, by picking  $a, b \in (0, 1)$  it holds that  $\gamma(a) = \gamma(b) \Leftrightarrow a = b$ :

$$\begin{cases} a^2 = b^2 \\ \frac{a^3}{3} - 1 = \frac{b^3}{3} - 1 \end{cases} \Rightarrow \begin{cases} a = -b \\ -\frac{b^3}{3} = \frac{b^3}{3} \end{cases} \vee \begin{cases} a = b \\ \frac{b^3}{3} = \frac{b^3}{3} \end{cases}$$

Therefore, since the condition is satisfied, the curve is indeed simple in  $(0, 1)$ .

**N.B.:** Alternatively, it is possible to directly confirm that the curve is simple by noticing that the second component is an injective function and, similarly, the first component, while not injective in  $\mathbb{R}$ , is injective at least in  $(0, 1)$ .

Lastly, the curve is said to be regular in  $(0, 1)$  if and only if the tangent vector  $\gamma'(t)$  is component-wise continuous and  $\gamma'(t) \neq 0 \, \forall t \in (0, 1)$ .

Start by computing  $\gamma'(t) = (2t, t^2)$  and study  $\gamma'(t) = 0$ :

$$\begin{cases} 2t = 0 \\ t^2 = 0 \end{cases} \Leftrightarrow t = 0 \notin (0, 1)$$

Therefore, since the condition is satisfied, the curve is indeed regular in  $(0, 1)$ .

- Compute  $L(\gamma)$ .  
Knowing that the curve is regular in its domain, it is possible to compute its length through its norm:

$$\|\gamma'(t)\| = \sqrt{(2t)^2 + (t^2)^2} = t\sqrt{4 + t^2}$$

Therefore, it is possible to conclude that:

$$L(\gamma) = \int_0^1 \|\gamma'(t)\| dt = \int_0^1 t\sqrt{4+t^2} dt$$

Apply a change of variable and let  $u = 4 + t^2$ , for  $u \in [4, 5]$ , and recover  $\frac{du}{dt} = 2t$ , resulting in:

$$L(\gamma) = \frac{1}{2} \int_4^5 \sqrt{u} du = \frac{1}{2} \left[ \frac{u^{\frac{3}{2}}}{\frac{3}{2}} \right]_4^5 = \frac{1}{3} (5^{\frac{3}{2}} - 4^{\frac{3}{2}}) = \frac{\sqrt{125} - 8}{3}$$

- Compute the following line integral:

$$\int_{\gamma} \frac{e^{x^{\frac{3}{2}} - 3y}}{x + 4} dt$$

By using the information recovered about the tangent vector, it is possible to compute the integral in the following way:

$$\int_{\gamma} \frac{e^{x^{\frac{3}{2}} - 3y}}{x + 4} dt = \int_0^1 \frac{e^{t^2 \cdot \frac{3}{2} - 3(\frac{t^3}{3} - 1)}}{t^2 + 4} \cdot t\sqrt{t^2 + 4} dt = \int_0^1 \frac{e^3 t}{\sqrt{t^2 + 4}} dt$$

Apply a change of variable and let  $u = t^2 + 4$ , for  $u \in [0, 5]$ , and recover  $\frac{du}{dt} = 2t$ , allowing to conclude that:

$$\frac{e^3}{2} \int_4^5 \frac{1}{\sqrt{u}} du = \frac{e^3}{2} [2\sqrt{u}]_4^5 = e^3(\sqrt{5} - \sqrt{4})$$

## 6.5 Exercise 5

Compute the following line integrals:

- $f(x, y) = x$  with respect to  $\gamma = (t, t^2)$ , for  $t \in [0, 2]$ .  
Start by finding the norm of the tangent vector:

$$\gamma'(t) = (1, 2t) \Rightarrow \|\gamma'(t)\| = \sqrt{1 + 4t^2}$$

Therefore, it is possible to compute the line integral in the following way:

$$\int_{\gamma} x dt = \int_0^2 t\sqrt{1 + 4t^2} dt$$

Apply a change of variable: let  $u = 1 + 4t^2$ , for  $u \in [1, 17]$ , and consider  $\frac{du}{dt} = 8t$ , resulting in:

$$\frac{1}{8} \int_1^{17} \sqrt{u} du = \frac{1}{8} \frac{2}{3} [u^{\frac{3}{2}}]_1^{17} = \frac{\sqrt{17^3} - 1}{12}$$

- $f(x, y) = \sqrt{1 - y^2}$  with respect to  $\gamma = (\sin t, \cos t)$ , for  $t \in [0, \pi]$ .  
Start by finding the norm of the tangent vector:

$$\gamma'(t) = (\cos t, -\sin t) \Rightarrow \|\gamma'(t)\| = \sqrt{\cos^2 t + \sin^2 t} = 1$$

Therefore, it is possible to compute the line integral in the following way:

$$\int_{\gamma} \sqrt{1 - y^2} dt = \int_0^{\pi} \sqrt{1 - \cos^2 t} dt = \int_0^{\pi} \sin t dt = [-\cos t]_0^{\pi} = 2$$

- $f(x, y) = \frac{x}{1+y^2}$  with respect to  $\gamma = (\cos t, \sin t)$ , for  $t \in [0, \frac{\pi}{2}]$ .  
Start by finding the norm of the tangent vector:

$$\gamma'(t) = (-\sin t, \cos t) \Rightarrow \|\gamma'(t)\| = \sqrt{\sin^2 t + \cos^2 t} = 1$$

Therefore, it is possible to compute the line integral in the following way:

$$\int_{\gamma} \frac{x}{1+y^2} dt = \int_0^{\frac{\pi}{2}} \frac{\cos t}{1+\sin^2 t} dt$$

Apply a change of variable: let  $u = \sin t$ , for  $u \in [0, 1]$ , and consider  $\frac{du}{dt} = \cos t$ , resulting in:

$$\int_0^1 \frac{1}{1+u^2} du = [\arctan u]_0^1 = \frac{\pi}{4}$$

- $f(x, y) = y^2$  with respect to  $\gamma = (t, e^t)$ , for  $t \in [0, \ln 2]$ .  
Start by finding the norm of the tangent vector:

$$\gamma'(t) = (1, e^t) \Rightarrow \|\gamma'(t)\| = \sqrt{1 + (e^t)^2} = \sqrt{1 + e^{2t}}$$

Therefore, it is possible to compute the line integral in the following way:

$$\int_{\gamma} y^2 dt = \int_0^{\ln 2} e^{2t} \sqrt{1 + e^{2t}} dt$$

Apply a change of variable: let  $u = 1 + e^{2t}$ , for  $u \in [2, 5]$ , and consider  $\frac{du}{dt} = 2e^{2t}$ , resulting in:

$$\frac{1}{2} \int_2^5 \sqrt{u} du = \frac{1}{2} \frac{2}{3} [u^{\frac{3}{2}}]_2^5 = \frac{\sqrt{125} - \sqrt{8}}{3}$$

- $f(x, y, z) = x + z$  with respect to  $\gamma = (t, \frac{3\sqrt{2}}{2}t^2, t^3)$ , for  $t \in [0, 1]$ .  
Start by finding the norm of the tangent vector:

$$\gamma'(t) = (1, 3\sqrt{2}t, 3t^2) \Rightarrow \|\gamma'(t)\| = \sqrt{1 + 18t^2 + 9t^4}$$

Therefore, it is possible to compute the line integral in the following way:

$$\int_{\gamma} x + z dt = \int_0^1 (t + t^3) \sqrt{1 + 18t^2 + 9t^4} dt$$

Apply a change of variable: let  $u = 1 + 18t^2 + 9t^4$ , for  $u \in [1, 28]$ , and consider  $\frac{du}{dt} = 36t + 36t^3 = 36(t + t^3)$ , resulting in:

$$\frac{1}{36} \int_1^{28} \sqrt{u} \, du = \frac{1}{36} \frac{2}{3} [u^{\frac{3}{2}}]_1^{28} = \frac{\sqrt{28^3} - 1}{54}$$

- $f(x, y, z) = \sqrt{z}$  with respect to  $\gamma = (\cos t, \sin t, t^2)$ , for  $t \in [0, \pi]$ .  
Start by finding the norm of the tangent vector:

$$\gamma'(t) = (-\sin t, \cos t, 2t) \Rightarrow \|\gamma'(t)\| = \sqrt{\sin^2 t + \cos^2 t + 4t^2} = \sqrt{1 + 4t^2}$$

Therefore, it is possible to compute the line integral in the following way:

$$\int_{\gamma} \sqrt{z} \, dt = \int_0^{\pi} \sqrt{t^2} \sqrt{1 + 4t^2} \, dt = \int_0^{\pi} t \sqrt{1 + 4t^2} \, dt$$

Apply a change of variable: let  $u = 1 + 4t^2$ , for  $u \in [1, 1 + 4\pi^2]$ , and consider  $\frac{du}{dt} = 8t$ , resulting in:

$$\frac{1}{8} \int_1^{1+4\pi^2} \sqrt{u} \, du = \frac{1}{8} \frac{2}{3} [u^{\frac{3}{2}}]_1^{1+4\pi^2} = \frac{\sqrt{(1 + 4\pi^2)^3} - 1}{12}$$

## 6.6 Exercise 6

Compute the following line integrals:

- $f(x, y) = x + y$  with respect to the triangle with vertices  $(0, 0)$ ,  $(0, 1)$ ,  $(1, 0)$ .  
By plotting the triangle, let  $\gamma = \gamma_1 \cup \gamma_2 \cup \gamma_3$  and consider each curve separately:

1. Let  $\gamma_1(t) = (0, t)$ , for  $t \in [0, 1]$ .

Compute the norm of the tangent vector:

$$\gamma'_1(t) = (0, 1) \Rightarrow \|\gamma'_1(t)\| = \sqrt{0 + 1} = 1$$

Therefore, it is possible to compute the line integral in the following way:

$$\int_{\gamma_1} x + y \, dt = \int_0^1 t \, dt = [\frac{t^2}{2}]_0^1 = \frac{1}{2}$$

2. Let  $\gamma_2(t) = (t, 1 - t)$ , for  $t \in [0, 1]$ .

Compute the norm of the tangent vector:

$$\gamma'_2(t) = (1, -1) \Rightarrow \|\gamma'_2(t)\| = \sqrt{1 + 1} = \sqrt{2}$$

Therefore, it is possible to compute the line integral in the following way:

$$\int_{\gamma_2} x + y \, dt = \int_0^1 (t + (1 - t)) \sqrt{2} \, dt = \sqrt{2} \int_0^1 dt = \sqrt{2} [t]_0^1 = \sqrt{2}$$



3. Let  $\gamma_3(t) = (t, 0)$ , for  $t \in [1, 0]$  (in this case, the direction of traversal is inverted).

Compute the norm of the tangent vector:

$$\gamma'_3(t) = (1, 0) \Rightarrow \|\gamma'_3(t)\| = \sqrt{1+0} = 1$$

Therefore, it is possible to compute the line integral in the following way:

$$\int_{\gamma_3} x + y \, dt = \int_1^0 t \, dt = -\int_0^1 t \, dt = -\left[\frac{t^2}{2}\right]_0^1 = -\frac{1}{2}$$

Therefore, by applying integral additivity, it is possible to conclude that:

$$\int_{\gamma} x + y \, dt = \frac{1}{2} + \sqrt{2} - \frac{1}{2} = \sqrt{2}$$

**N.B.:** The result of this integral may change according to the direction of traversal considered for the curve.

- $f(x, y) = xy$  with respect to the quarter of ellipse of equation  $\frac{x^2}{4} + \frac{y^2}{9} = 1$  that is contained in the first quadrant.

Start by parametrizing the Cartesian equation of the curve:

$$\gamma : \begin{cases} x = 2 \cos t \\ y = 3 \sin t \end{cases}, \quad t \in [0, \frac{\pi}{2}]$$

At this point, compute the norm of the tangent vector:

$$\gamma'(t) = (-2 \sin t, 3 \cos t) \Rightarrow \|\gamma'(t)\| = \sqrt{4 \sin^2 t + 9 \cos^2 t} = \sqrt{4 + 5 \cos^2 t}$$

Therefore, it is possible to compute the line integral in the following way:

$$\int_{\gamma} xy \, dt = \int_0^{\frac{\pi}{2}} 6 \cos t \sin t \sqrt{4 + 5 \cos^2 t} \, dt$$

Apply a change of variable: let  $u = 4 + 5 \cos^2 t$ , for  $u \in [9, 4]$ , and consider  $\frac{du}{dt} = -10 \cos t \sin t$ , resulting in:

$$-\frac{6}{10} \int_9^4 \sqrt{u} \, du = \frac{3}{5} \int_4^9 \sqrt{u} \, du = \frac{3}{5} \frac{2}{3} [u^{\frac{3}{2}}]_4^9 = \frac{2}{5} (27 - 8) = \frac{38}{5}$$

## 6.7 Exercise 7

The cycloid is the curve described by a point on the circumference of a circle of radius  $R$  as the circle rolls along the  $x$ -axis without slipping. This curve has parametric equation given by:

$$\gamma(t) = (R(t - \sin t), R(1 - \cos t)), \quad t \in [0, 2\pi]$$

- Determine if the curve is closed and regular.

By definition, the curve will be closed in  $[0, 2\pi]$  if and only if  $\gamma(0) = \gamma(2\pi)$ :

$$\gamma(0) = (0, 0) \neq (2\pi R, 0) = \gamma(2\pi)$$

Therefore, the curve is not closed in the interval  $[0, 2\pi]$  unless  $R = 0$ .

On the other hand, the curve is defined to be regular in the interval  $(0, 2\pi)$  if and only if the tangent vector  $\gamma'(t)$  is component-wise continuous and  $\gamma'(t) \neq 0 \forall t \in (0, 2\pi)$ .

Start by computing  $\gamma'(t) = (R(1 - \cos t), R \sin t)$  and study  $\gamma'(t) = 0$ :

$$\begin{cases} R(1 - \cos t) = 0 \\ R \sin t = 0 \end{cases} \Leftrightarrow t = 0 \notin (0, 2\pi) \vee t = 2\pi \notin (0, 2\pi)$$

Therefore, since the condition is satisfied, the curve is indeed regular in  $(0, 2\pi)$ .

- Compute the length of the curve.

Knowing that the curve is regular in its domain, it is possible to compute its length through its norm:

$$\|\gamma'(t)\| = \sqrt{(R(1 - \cos t))^2 + (R \sin t)^2} = \sqrt{2R^2(1 - \cos t)}$$

Most particularly, by exploiting the identity  $1 - \cos t = 2 \sin^2(\frac{t}{2})$ , it is possible to simplify the previous result to:

$$\|\gamma'(t)\| = \sqrt{2R^2 \cdot 2 \sin^2(\frac{t}{2})} = 2R \sin(\frac{t}{2})$$

Therefore, it is possible to conclude that:

$$L(\gamma) = \int_0^{2\pi} \|\gamma'(t)\| dt = \int_0^{2\pi} 2R \sin(\frac{t}{2}) dt$$

Apply a change of variable and let  $u = \frac{t}{2}$ , for  $u \in [0, \pi]$ , and let  $\frac{du}{dt} = \frac{1}{2}$ , resulting in:

$$L(\gamma) = \int_0^\pi 2R \sin u \cdot 2 du = 4R[-\cos u]_0^\pi = 4R[1 - (-1)] = 8R$$

## Chapter 7

# Exercise Sheet 7: Local extrema

### 7.1 Exercise 1

Compute the absolute maximum and minimum of the following functions constrained to the indicated region.

- $f(x, y) = x^2y + xy^2 - xy$ ,  $D = \{(x, y) \in \mathbb{R}^2 : y \geq x - 1, y \leq 1, x \geq 0\}$ .  
Start by finding the stationary points  $(x, y)$  such that  $\nabla f(x, y) = 0$ :

$$\begin{cases} 2xy + y^2 - y = 0 \\ x^2 + 2xy - x = 0 \end{cases} \Rightarrow \begin{cases} y(2x + y - 1) = 0 \\ x(x + 2y - 1) = 0 \end{cases}$$

Consider each solution to the first equation separately:

1.  $y = 0$ :

$$\begin{cases} y = 0 \\ x(x - 1) = 0 \end{cases} \Rightarrow \begin{cases} y = 0 \\ x = 0 \vee x = 1 \end{cases}$$

In this case, it is possible to find the stationary points  $P_1(0, 0) \in D$  and  $P_2(1, 0) \in D$ .

2.  $2x + y - 1 = 0$ :

$$\begin{cases} y = 1 - 2x \\ x(x + 2 - 4x - 1) = 0 \end{cases} \Rightarrow \begin{cases} y = 1 - 2x \\ x(1 - 3x) = 0 \end{cases} \Rightarrow \begin{cases} x = 0 \\ y = 1 \end{cases} \vee \begin{cases} x = \frac{1}{3} \\ y = \frac{1}{3} \end{cases}$$

In this case, it is possible to find the stationary points  $P_3(0, 1) \in D$ , which also happens to be one of the corners of the region, and  $P_4(\frac{1}{3}, \frac{1}{3}) \in D$ .

At this point, study the boundaries (and eventual corners) of the region by parametrizing it as a curve  $\gamma = \gamma_1 \cup \gamma_2 \cup \gamma_3$ :

1. Let  $\gamma_1(t) = (t, t-1)$ , for  $t \in [0, 2]$ .  
Restrict the function to the curve by letting  $f_{\gamma_1}(t) = 2t^3 - 4t^2 + 2t$  and find the corresponding stationary points:

$$f'_{\gamma_1}(t) = 6t^2 - 8t + 2 = 0 \Rightarrow t = \frac{1}{3} \vee t = 1$$

Therefore, is possible to find the stationary points  $P_5(\frac{1}{3}, -\frac{2}{3}) \in D$  and  $P_2(1, 0)$ , which was already found via  $\nabla f(x, y) = 0$ .

Furthermore, by studying the extremes of the interval, it is possible to recover the corners  $P_6(0, -1) \in D$  and  $P_7(2, 1) \in D$ .

2. Let  $\gamma_2(t) = (t, 1)$ , for  $t \in [2, 0]$  (in this case, the direction of traversal is inverted).

Restrict the function to the curve by letting  $f_{\gamma_2}(t) = t^2$  and find the corresponding stationary points:

$$f'_{\gamma_2}(t) = 2t = 0 \Rightarrow t = 0$$

Therefore, it is possible to find again the point  $P_3(0, 1)$ , which was already found via  $\nabla f(x, y) = 0$ .

Furthermore, by studying the extremes of the interval, it is possible to recover again the corners  $P_7(2, 1)$ , which was already found via  $\gamma_1$  and  $P_3(0, 1)$ .

3. Let  $\gamma_3(t) = (0, t)$ , for  $t \in [1, -1]$  (in this case, the direction of traversal is inverted).

Restrict the function to the curve and let  $f_{\gamma_3}(t) = 0$ , which means that there is no stationary point to study as the function is 0 in this component.

On the other hand, by studying the extremes of the interval, it is possible to find again the corners  $P_3(0, 1)$  and  $P_6(0, -1) \in D$ , which were already found via  $\nabla f(x, y) = 0$  and  $\gamma_1$  respectively.

Lastly, compare the values the function takes at the found points:

1.  $P_1(0, 0) \Rightarrow f(0, 0) = 0$ .
2.  $P_2(1, 0) \Rightarrow f(1, 0) = 0$ .
3.  $P_3(0, 1) \Rightarrow f(0, 1) = 0$ .
4.  $P_4(\frac{1}{3}, \frac{1}{3}) \Rightarrow f(\frac{1}{3}, \frac{1}{3}) = -\frac{1}{27}$ .
5.  $P_5(\frac{1}{3}, -\frac{2}{3}) \Rightarrow f(\frac{1}{3}, -\frac{2}{3}) = \frac{8}{27}$ .
6.  $P_6(0, -1) = 0$ .
7.  $P_7(2, 1) = 4$ .

Therefore, it is possible to conclude that  $P_7(2, 1)$  is a local maximum, whereas  $P_4(\frac{1}{3}, \frac{1}{3})$  is a local minimum.

- $f(x, y) = x^3 - xy + y^3$  within the triangle with vertices  $(0, 0), (0, 1), (1, 0)$ .  
Start by finding the stationary points  $(x, y)$  such that  $\nabla f(x, y) = 0$ :

$$\begin{cases} 3x^2 - y = 0 \\ -x + 3y^2 = 0 \end{cases} \Rightarrow \begin{cases} y = 3x^2 \\ 27x^4 - x = 0 \end{cases} \Rightarrow \begin{cases} y = 3x^2 \\ x(27x^3 - 1) = 0 \end{cases} \Rightarrow \begin{cases} x = 0 \\ y = 0 \end{cases} \vee \begin{cases} x = \frac{1}{3} \\ y = \frac{1}{3} \end{cases}$$

Therefore, it is possible to find the stationary points  $P_1(0, 0) \in D$ , which also happens to be one of the corners of the region, and  $P_2(\frac{1}{3}, \frac{1}{3}) \in D$ .

**N.B.:** Without loss of generality, the same conclusion is reached by setting  $x = 3y^2$  instead.

At this point, study the boundaries (and eventual corners) of the region by parametrizing it as a curve  $\gamma = \gamma_1 \cup \gamma_2 \cup \gamma_3$ :

1. Let  $\gamma_1(t) = (t, t)$ , for  $t \in [0, 1]$ .  
Restrict the function to the curve by letting  $f_{\gamma_1}(t) = t^3$  and find the corresponding stationary points:

$$f'_{\gamma_1}(t) = 3t^2 = 0 \Rightarrow t = 0$$

Therefore, it is possible to find again the corner  $P_1(0, 0)$ , which was already found via  $\nabla f(x, y) = 0$ .

Furthermore, by studying the extremes of the interval, it is possible to recover the corners  $P_1(0, 0)$  and  $P_3(0, 1) \in D$ .

2. Let  $\gamma_2(t) = (t, 1 - t)$ , for  $t \in [0, 1]$ .  
Restrict the function to the curve by letting  $f_{\gamma_2}(t) = 4t^2 - 4t + 1$  and find the corresponding stationary points:

$$f'_{\gamma_2}(t) = 8t - 4 = 0 \Rightarrow t = \frac{1}{2}$$

Therefore, it is possible to find the stationary point  $P_4(\frac{1}{2}, \frac{1}{2}) \in D$ .

Furthermore, by studying the extremes of the interval, it is possible to recover the corners  $P_3(0, 1)$ , which was already found via  $\gamma_1$ , and  $P_5(1, 0) \in D$ .

3. Let  $\gamma_3(t) = (t, 0)$ , for  $t \in [1, 0]$  (in this case, the direction of traversal is inverted).  
Restrict the function to the curve and let  $f_{\gamma_3}(t) = t^3$  and find the corresponding stationary points:

$$f'_{\gamma_3}(t) = 3t^2 = 0 \Rightarrow t = 0$$

Therefore, it is possible to find again the corner  $P_1(0, 0)$ , which was already found via  $\nabla f(x, y) = 0$  and then through  $\gamma_1$ .

Furthermore, by studying the extremes of the interval, it is possible to recover again the corners  $P_5(1, 0)$  and  $P_1(0, 0)$ , which were found via  $\gamma_2$  and  $\nabla f(x, y) = 0$  and  $\gamma_1$  respectively.

Lastly, compare the values the function takes at the found points:

1.  $P_1(0,0) \Rightarrow f(0,0) = 0$ .
2.  $P_2(\frac{1}{3}, \frac{1}{3}) \Rightarrow f(\frac{1}{3}, \frac{1}{3}) = -\frac{1}{27}$ .
3.  $P_3(0,1) \Rightarrow f(0,1) = 1$ .
4.  $P_4(\frac{1}{2}, \frac{1}{2}) \Rightarrow f(\frac{1}{2}, \frac{1}{2}) = 0$ .
5.  $P_5(1,0) \Rightarrow f(1,0) = 1$ .

Therefore, it is possible to conclude that  $P_3(0,1)$  and  $P_5(1,0)$  are local maxima, whereas  $P_2(\frac{1}{3}, \frac{1}{3})$  is a local minimum.

- $f(x,y) = x^3 - xy^2$ ,  $D = \{(x,y) \in \mathbb{R}^2 : 0 \leq x \leq 1, 0 \leq y \leq 1\}$ .  
Start by finding the stationary points  $(x,y)$  such that  $\nabla f(x,y) = 0$ :

$$\begin{cases} 3x^2 - y^2 = 0 \\ -2xy = 0 \end{cases} \Rightarrow \begin{cases} x = 0 \\ y = 0 \end{cases}$$

Therefore, it is possible to find a first candidate  $P_1(0,0) \in D$ , which also happens to be one of the corners of the region.

At this point, study the boundaries (and eventual corners) of the region by parametrizing it as a curve  $\gamma = \gamma_1 \cup \gamma_2 \cup \gamma_3 \cup \gamma_4$ :

1. Let  $\gamma_1(t) = (t,0)$ , for  $t \in [0,1]$ .  
Restrict the function to the curve by letting  $f_{\gamma_1}(t) = t^3$  and find the corresponding stationary points:

$$f'_{\gamma_1}(t) = 3t^2 = 0 \Rightarrow t = 0$$

Therefore, it is possible to recover again the corner  $P_1(0,0)$ , which was already found via  $\nabla f(x,y) = 0$ .

Furthermore, by studying the extremes of the interval, it is possible to find the corners  $P_1(0,0)$  and  $P_2(1,0) \in D$ .

2. Let  $\gamma_2(t) = (1,t)$ , for  $t \in [0,1]$ .  
Restrict the function to the curve by letting  $f_{\gamma_2}(t) = 1 - t^2$  and find the corresponding stationary points:

$$f'_{\gamma_2}(t) = -2t = 0 \Rightarrow t = 0$$

Therefore, it is possible to recover again the corner  $P_2(1,0)$ , which was already found as a corner via  $\gamma_1$ .

Furthermore, by studying the extremes of the interval, it is possible to find the corners  $P_2(1,0)$  and  $P_3(1,1) \in D$ .

3. Let  $\gamma_3(t) = (t,1)$ , for  $t \in [1,0]$  (in this case, the direction of traversal is inverted).  
Restrict the function to the curve by letting  $f_{\gamma_3}(t) = t^3 - t$  and find the corresponding stationary points:

$$f'_{\gamma_3}(t) = 3t^2 - 1 = 0 \Rightarrow t = \pm \frac{\sqrt{3}}{3}$$

Therefore, discard  $P(-\frac{\sqrt{3}}{3}, 1) \notin D$  and focus on the stationary point  $P_4(\frac{\sqrt{3}}{3}, 1) \in D$ .

Furthermore, by studying the extremes of the interval, it is possible to recover again the corners  $P_3(1, 1)$ , which was already found via  $\gamma_2$ , and  $P_5(0, 1) \in D$ .

4. Let  $\gamma_4(t) = (0, t)$ , for  $t \in [1, 0]$  (in this case, the direction of traversal is inverted).

Restrict the function to the curve and let  $f_{\gamma_4}(t) = 0$ , which means that there is no stationary point to study as the function is 0 in this component.

On the other hand, by studying the extremes of the interval, it is possible to find again the corners  $P_5(0, 1)$  and  $P_1(0, 0)$ , which were already found via  $\gamma_3$  and  $\gamma_1$  respectively.

Lastly, compare the values the function takes at the found points:

1.  $P_1(0, 0) \Rightarrow f(0, 0) = 0$ .
2.  $P_2(1, 0) \Rightarrow f(1, 0) = 1$ .
3.  $P_3(1, 1) \Rightarrow f(1, 1) = 0$ .
4.  $P_4(\frac{\sqrt{3}}{3}, 1) \Rightarrow f(\frac{\sqrt{3}}{3}, 1) = -\frac{2\sqrt{3}}{9}$ .
5.  $P_5(0, 1) \Rightarrow f(0, 1) = 0$ .

Therefore, it is possible to conclude that  $P_2(1, 0)$  is a local maximum, whereas  $P_4(\frac{\sqrt{3}}{3}, 1)$  is a local minimum.

- $f(x, y) = x^2 + 3y^2 - x$ ,  $D = \{(x, y) \in \mathbb{R}^2 : x \geq 0, y \leq -x + 1, y \geq x - 1\}$ . Start by finding the stationary points  $(x, y)$  such that  $\nabla f(x, y) = 0$ :

$$\begin{cases} 2x - 1 = 0 \\ 6y = 0 \end{cases} \Rightarrow \begin{cases} x = \frac{1}{2} \\ y = 0 \end{cases}$$

Therefore, it is possible to find a first candidate  $P_1(\frac{1}{2}, 0) \in D$ .

At this point, study the boundaries (and eventual corners) of the region by parametrizing it as a curve  $\gamma = \gamma_1 \cup \gamma_2 \cup \gamma_3$ :

1. Let  $\gamma(t) = (t, t - 1)$ , for  $t \in [0, 1]$ .

Restrict the function to the curve by letting  $f_{\gamma_1}(t) = 4t^2 - 7t + 3$  and find the corresponding stationary points:

$$f'_{\gamma_1}(t) = 8t - 7 = 0 \Rightarrow t = \frac{7}{8}$$

Therefore, it is possible to find the stationary point  $P_2(\frac{7}{8}, -\frac{1}{8}) \in D$ . Furthermore, by studying the extremes of the interval, it is possible to recover the corners  $P_3(0, -1) \in D$  and  $P_4(1, 0) \in D$ .

2. Let  $\gamma_2(t) = (t, 1 - t)$ , for  $t \in [1, 0]$  (in this case, the direction of traversal is inverted).

Restrict the function to the curve by letting  $f_{\gamma_2}(t) = 4t^2 - 7t + 3$  and find the corresponding stationary points:

$$f'_{\gamma_2}(t) = 8t - 7 = 0 \Rightarrow t = \frac{7}{8}$$

Therefore, it is possible to find the stationary point  $P_5(\frac{7}{8}, \frac{1}{8}) \in D$ . Furthermore, by studying the extremes of the interval, it is possible to recover the corners  $P_4(1, 0)$ , which was already found via  $\gamma_1$ , and  $P_6(0, 1) \in D$ .

3. Let  $\gamma_3(t) = (0, t)$ , for  $t \in [1, -1]$  (in this case, the direction of traversal is inverted).

Restrict the function to the curve by letting  $f_{\gamma_3}(t) = 3t^2$  and find the corresponding stationary points:

$$f'_{\gamma_3}(t) = 6t = 0 \Rightarrow t = 0$$

Therefore, it is possible to find the stationary point  $P_7(0, 0) \in D$ . Furthermore, by studying the extremes of the interval, it is possible to recover again the corners  $P_6(0, 1)$  and  $P_3(0, -1)$ , which were already found via  $\gamma_1$  and  $\gamma_2$  respectively.

Lastly, compare the values the function takes at the found points:

1.  $P_1(\frac{1}{2}, 0) \Rightarrow f(\frac{1}{2}, 0) = -\frac{1}{4}$ .
2.  $P_2(\frac{7}{8}, -\frac{1}{8}) \Rightarrow f(\frac{7}{8}, -\frac{1}{8}) = -\frac{1}{16}$ .
3.  $P_3(0, -1) \Rightarrow f(0, -1) = 3$ .
4.  $P_4(1, 0) \Rightarrow f(1, 0) = 0$ .
5.  $P_5(\frac{7}{8}, \frac{1}{8}) \Rightarrow f(\frac{7}{8}, \frac{1}{8}) = -\frac{1}{16}$ .
6.  $P_6(0, 1) \Rightarrow f(0, 1) = 3$ .
7.  $P_7(0, 0) \Rightarrow f(0, 0) = 0$ .

Therefore, it is possible to conclude that  $P_3(0, -1)$  and  $P_6(0, 1)$  are local maxima, whereas  $P_1(\frac{1}{2}, 0)$  is a local minimum.

- $f(x, y) = 2x^2 + y^2 - x$ ,  $D = \{(x, y) \in \mathbb{R}^2 : x^2 + y^2 \leq 1\}$ .  
Start by finding the stationary points  $(x, y)$  such that  $\nabla f(x, y) = 0$ :

$$\begin{cases} 4x - 1 = 0 \\ 2y = 0 \end{cases} \Rightarrow \begin{cases} x = \frac{1}{4} \\ y = 0 \end{cases}$$

Therefore, it is possible to recover a first candidate as  $P_1(\frac{1}{4}, 0) \in D$ . At this point, study the boundaries (and eventual corners) of the region by parametrizing it as a curve  $\gamma(t) = (\cos t, \sin t)$ , for  $t \in [0, 2\pi]$ . Restrict the function to the curve by letting  $f_{\gamma}(t) = \cos^2 t - \cos t + 1$  and



find the corresponding stationary points:

$$f'_\gamma(t) = -2 \sin t \cos t + \sin t = \sin t(1 - 2 \cos t) = 0 \Rightarrow t = 0 \vee t = \pi \vee t = 2\pi \vee t = \frac{\pi}{3} \vee t = \frac{5\pi}{3}$$

Therefore, it is possible to find stationary points  $P_2(1, 0) \in D$ ,  $P_3(-1, 0) \in D$ ,  $P_4(\frac{1}{2}, \frac{\sqrt{3}}{2}) \in D$  and  $P_5(\frac{1}{2}, -\frac{\sqrt{3}}{2}) \in D$ .

Most particularly, observe that there are no corners to study.

Lastly, compare the values the function takes at the found points:

1.  $P_1(\frac{1}{4}, 0) \Rightarrow f(\frac{1}{4}, 0) = -\frac{1}{8}$ .
2.  $P_2(1, 0) \Rightarrow f(1, 0) = 1$ .
3.  $P_3(-1, 0) \Rightarrow f(-1, 0) = 3$ .
4.  $P_4(\frac{1}{2}, \frac{\sqrt{3}}{2}) \Rightarrow f(\frac{1}{2}, \frac{\sqrt{3}}{2}) = \frac{3}{4}$ .
5.  $P_5(\frac{1}{2}, -\frac{\sqrt{3}}{2}) \Rightarrow f(\frac{1}{2}, -\frac{\sqrt{3}}{2}) = \frac{3}{4}$ .

Therefore, it is possible to conclude that  $P_3(-1, 0)$  is a local maximum, whereas  $P_1(\frac{1}{4}, 0)$  is a local minimum.

- $f(x, y) = x^2 - y^2 + x + 1$ ,  $D = \{(x, y) \in \mathbb{R}^2 : 4x^2 + y^2 \leq 1\}$ .  
Start by finding the stationary points  $(x, y)$  such that  $\nabla f(x, y) = 0$ :

$$\begin{cases} 2x + 1 = 0 \\ -2y = 0 \end{cases} \Rightarrow \begin{cases} x = -\frac{1}{2} \\ y = 0 \end{cases}$$

Therefore, it is possible to recover a first candidate as  $P_1(-\frac{1}{2}, 0) \in D$ .

At this point, study the boundaries (and eventual corners) of the region by parametrizing it as a curve  $\gamma(t) = (\frac{\cos t}{2}, \sin t)$ , for  $t \in [0, 2\pi]$ .

Restrict the function to the curve by letting  $f_\gamma(t) = \frac{5 \cos^2 t}{4} + \frac{\cos t}{2}$  and find the corresponding stationary points:

$$f'_\gamma(t) = -\frac{5 \sin t \cos t}{2} - \frac{\sin t}{2} = -\frac{\sin t}{2}(5 \cos t + 1) = 0 \Rightarrow t = 0 \vee t = \pi \vee t = 2\pi \vee \arccos(-\frac{1}{5}) \vee 2\pi - \arccos(-\frac{1}{5})$$

Therefore, it is possible to find the stationary points  $P_2(\frac{1}{2}, 0) \in D$ ,  $P_1(-\frac{1}{2}, 0)$ ,

which was already found via  $\nabla f(x, y) = 0$ ,  $P_3(-\frac{1}{10}, \sqrt{\frac{24}{25}}) \in D$  and

$P_4(-\frac{1}{10}, -\sqrt{\frac{24}{25}}) \in D$ .

Most particularly, observe that there are not corners to study.

Lastly, compare the values the function takes at the found points:

1.  $P_1(-\frac{1}{2}, 0) \Rightarrow f(-\frac{1}{2}, 0) = \frac{3}{4}$ .
2.  $P_2(\frac{1}{2}, 0) \Rightarrow f(\frac{1}{2}, 0) = \frac{7}{4}$ .
3.  $P_3(-\frac{1}{10}, \sqrt{\frac{24}{25}}) \Rightarrow f(-\frac{1}{10}, \sqrt{\frac{24}{25}}) = -\frac{1}{20}$ .
4.  $P_4(-\frac{1}{10}, -\sqrt{\frac{24}{25}}) \Rightarrow f(-\frac{1}{10}, -\sqrt{\frac{24}{25}}) = -\frac{1}{20}$ .

Therefore, it is possible to conclude that  $P_2(\frac{1}{2}, 0)$  is a local maximum, whereas  $P_3(-\frac{1}{10}, \sqrt{\frac{24}{25}})$  and  $P_4(-\frac{1}{10}, -\sqrt{\frac{24}{25}})$  are local minima.

- $f(x, y) = \sin(x+y) \cos(x-y)$ ,  $D = \{(x, y) \in \mathbb{R}^2 : 0 \leq x \leq \pi, 0 \leq y \leq \pi\}$ . Start by finding the stationary points  $(x, y)$  such that  $\nabla f(x, y) = 0$ :

$$\begin{aligned} \begin{cases} \cos(x+y) \cos(x-y) - \sin(x+y) \cos(x-y) = 0 \\ \cos(x+y) \cos(x-y) + \sin(x+y) \sin(x-y) = 0 \end{cases} &\Rightarrow \begin{cases} \cos((x+y) + (x-y)) = 0 \\ \cos((x+y) - (x-y)) = 0 \end{cases} \\ \begin{cases} \cos 2x = 0 \\ \cos 2y = 0 \end{cases} &\Rightarrow \begin{cases} x = \frac{\pi}{4} + \frac{k\pi}{2} \\ y = \frac{\pi}{4} + \frac{k\pi}{2} \end{cases} \quad \text{for } k \in \{0, 1\}. \end{aligned}$$

By combining the various values, it is possible to find the stationary points  $P_1(\frac{\pi}{4}, \frac{\pi}{4}) \in D$ ,  $P_2(\frac{\pi}{4}, \frac{3\pi}{4}) \in D$ ,  $P_3(\frac{3\pi}{4}, \frac{\pi}{4}) \in D$  and  $P_4(\frac{3\pi}{4}, \frac{3\pi}{4}) \in D$ .

At this point, study the boundaries (and eventual corners) of the region by parametrizing it as a curve  $\gamma = \gamma_1 \cup \gamma_2 \cup \gamma_3 \cup \gamma_4$ :

1. Let  $\gamma_1(t) = (t, 0)$ , for  $t \in [0, \pi]$ .

Restrict the function to the curve by letting  $f_{\gamma_1}(t) = \sin t \cos t$  and find the corresponding stationary points:

$$f'_{\gamma_1}(t) = \cos^2 t - \sin^2 t = \cos 2t = 0 \Rightarrow t = \frac{\pi}{4} \vee t = \frac{3\pi}{4}$$

Therefore, it is possible to find the stationary points  $P_5(\frac{\pi}{4}, 0) \in D$  and  $P_6(\frac{3\pi}{4}, 0) \in D$ .

Furthermore, by studying the extremes of the interval, it is possible to find the corners  $P_7(0, 0) \in D$  and  $P_8(\pi, 0) \in D$ .

2. Let  $\gamma_2(t) = (\pi, t)$ , for  $t \in [0, \pi]$ .

Restrict the function to the curve by letting  $f_{\gamma_2}(t) = \sin t \cos t$  and find the corresponding stationary points:

$$f'_{\gamma_2}(t) = \cos^2 t - \sin^2 t = \cos 2t = 0 \Rightarrow t = \frac{\pi}{4} \vee t = \frac{3\pi}{4}$$

Therefore, it is possible to find the stationary points  $P_9(\pi, \frac{\pi}{4}) \in D$  and  $P_{10}(\pi, \frac{3\pi}{4}) \in D$ .

Furthermore, by studying the extremes of the interval, it is possible to find the corners  $P_8(\pi, 0)$ , which was already found as a corner via  $\gamma_1$ , and  $P_{11}(\pi, \pi) \in D$ .

3. Let  $\gamma_3(t) = (t, \pi)$ , for  $t \in [\pi, 0]$  (in this case, the direction of traversal is inverted).

Restrict the function to the curve by letting  $f_{\gamma_3}(t) = \sin t \cos t$  and find the corresponding stationary points:

$$f'_{\gamma_3}(t) = \cos^2 t - \sin^2 t = \cos 2t = 0 \Rightarrow t = \frac{\pi}{4} \vee t = \frac{3\pi}{4}$$

Therefore, it is possible to find the stationary points  $P_{12}(\frac{\pi}{4}, \pi) \in D$  and  $P_{13}(\frac{3\pi}{4}, \pi) \in D$ .

Furthermore, by studying the extremes of the interval, it is possible to find the corners  $P_{11}(\pi, \pi)$ , which was already found as a corner via  $\gamma_2$ , and  $P_{14}(0, \pi) \in D$ .

4. Let  $\gamma_4(t) = (0, t)$ , for  $t \in [\pi, 0]$  (in this case, the direction of traversal is inverted).

Restrict the function to the curve by letting  $f_{\gamma_4}(t) = \sin t \cos t$  and find the corresponding stationary points:

$$f'_{\gamma_4}(t) = \cos^2 t - \sin^2 t = \cos 2t = 0 \Rightarrow t = \frac{\pi}{4} \vee t = \frac{3\pi}{4}$$

Therefore, it is possible to find the stationary points  $P_{15}(0, \frac{\pi}{4}) \in D$  and  $P_{16}(0, \frac{3\pi}{4}) \in D$ .

Furthermore, by studying the extremes of the interval it is possible to find the corners  $P_{17}(0, \pi) \in D$  and  $P_7(0, 0)$ , which was already found as a corner via  $\gamma_1$ .

Lastly, compare the values the function takes at the found points:

1.  $P_1(\frac{\pi}{4}, \frac{\pi}{4}) \Rightarrow f(\frac{\pi}{4}, \frac{\pi}{4}) = 1.$
2.  $P_2(\frac{\pi}{4}, \frac{3\pi}{4}) \Rightarrow f(\frac{\pi}{4}, \frac{3\pi}{4}) = 0.$
3.  $P_3(\frac{3\pi}{4}, \frac{\pi}{4}) \Rightarrow f(\frac{3\pi}{4}, \frac{\pi}{4}) = 0.$
4.  $P_4(\frac{3\pi}{4}, \frac{3\pi}{4}) \Rightarrow f(\frac{3\pi}{4}, \frac{3\pi}{4}) = -1.$
5.  $P_5(\frac{\pi}{4}, 0) \Rightarrow f(\frac{\pi}{4}, 0) = \frac{1}{2}.$
6.  $P_6(\frac{3\pi}{4}, 0) \Rightarrow f(\frac{3\pi}{4}, 0) = -\frac{1}{2}.$
7.  $P_7(0, 0) \Rightarrow f(0, 0) = 0.$
8.  $P_8(\pi, 0) \Rightarrow f(\pi, 0) = 0.$
9.  $P_9(\pi, \frac{\pi}{4}) \Rightarrow f(\pi, \frac{\pi}{4}) = \frac{1}{2}.$
10.  $P_{10}(\pi, \frac{3\pi}{4}) \Rightarrow f(\pi, \frac{3\pi}{4}) = -\frac{1}{2}.$
11.  $P_{11}(\pi, \pi) \Rightarrow f(\pi, \pi) = 0.$
12.  $P_{12}(\frac{\pi}{4}, \pi) \Rightarrow f(\frac{\pi}{4}, \pi) = \frac{1}{2}.$
13.  $P_{13}(\frac{3\pi}{4}, \pi) \Rightarrow f(\frac{3\pi}{4}, \pi) = -\frac{1}{2}.$
14.  $P_{14}(0, \pi) \Rightarrow f(0, \pi) = 0.$
15.  $P_{15}(0, \frac{\pi}{4}) \Rightarrow f(0, \frac{\pi}{4}) = \frac{1}{2}.$
16.  $P_{16}(0, \frac{3\pi}{4}) \Rightarrow f(0, \frac{3\pi}{4}) = -\frac{1}{2}.$
17.  $P_{17}(0, \pi) \Rightarrow f(0, \pi) = 0.$

Therefore, it is possible to conclude that  $P_1(\frac{\pi}{4}, \frac{\pi}{4})$  is a local maximum, whereas  $P_4(\frac{3\pi}{4}, \frac{3\pi}{4})$  is a local minimum.

## Chapter 8

# Exercise Sheet 8: Double integrals

### 8.1 Exercise 1

Compute the following double integrals:

- $f(x, y) = x + y$  over  $Q = [0, 1] \times [0, 2]$ .  
Apply Fubini's theorem for double integrals:

$$\int_0^2 \int_0^1 x + y \, dx dy = \int_0^2 \left[ \frac{x^2}{2} + xy \right]_0^1 dy = \int_0^2 \frac{1}{2} + y \, dy = \left[ \frac{y}{2} + \frac{y^2}{2} \right]_0^2 = 3$$

- $f(x, y) = x(1 - y)$  over the square of vertices  $(1, 0), (2, 0), (1, 1), (2, 1)$ .  
By plotting the square on a graph, observe that the region can be written as  $Q = [1, 2] \times [0, 1]$ .  
Therefore, it is possible to apply Fubini's theorem for double integrals:

$$\int_0^1 \int_1^2 x(1-y) \, dx dy = \int_0^1 (1-y) \left[ \frac{x^2}{2} \right]_1^2 dy = \int_0^1 \frac{3(1-y)}{2} \, dy = \frac{3}{2} \left[ y - \frac{y^2}{2} \right]_0^1 = \frac{3}{4}$$

- $f(x, y) = \frac{1}{x+y}$  over  $Q = [0, 1] \times [0, 1]$ .  
Observe that the function is not continuous at  $(0, 0) \in Q$ , meaning that, technically, the function cannot be integrated over  $Q$ .  
However, if Fubini's theorem is applied, it is possible to discover the following:

$$\int_0^1 \int_0^1 \frac{1}{x+y} \, dx dy = \int_0^1 [\ln |x+y|]_0^1 dy = \int_0^1 \ln(1+y) - \ln y \, dy$$

At this point, apply integral linearity and solve each integral separately:

1. First integral:

$$\int_0^1 \ln(1+y) dy = [(1+y) \ln(1+y) - (1+y)]_0^1 = 2 \ln 2 - 1$$

2. Second integral:

$$\int_0^1 \ln y dy = \lim_{a \rightarrow 0^+} \int_a^1 \ln y dy = \lim_{a \rightarrow 0^+} [a \ln a - a]_a^1 = \lim_{a \rightarrow 0^+} -1 - a \ln a - a = 0 \cdot \infty$$

The problem lies in  $a \ln a$ , so, let  $a = \frac{1}{a}$  and apply De L'Hopital's rule:

$$\lim_{a \rightarrow 0^+} \frac{\ln a}{\frac{1}{a}} = \lim_{a \rightarrow 0^+} \frac{\frac{1}{a}}{-\frac{1}{a^2}} = \lim_{a \rightarrow 0^+} \frac{1}{a} \cdot (-a^2) = \lim_{a \rightarrow 0^+} -a = 0$$

For this reason, it is possible to conclude that the function is integrable and:

$$\int_0^1 \ln y dy = -1$$

It is thus possible to conclude that:

$$\int_0^1 \int_0^1 \frac{1}{x+y} dx dy = 2 \ln 2 - 1 - (-1) = 2 \ln 2$$

Therefore, the function is actually integrable in an improper way in  $Q$ .

- $f(x, y) = \frac{1}{(x+2y)^2}$  over  $Q = [3, 4] \times [1, 2]$ .

Apply Fubini's theorem for double integrals:

$$\int_1^2 \int_3^4 \frac{1}{(x+2y)^2} dx dy = \int_1^2 \left[ -\frac{1}{x+2y} \right]_3^4 dy = \int_1^2 \frac{1}{3+2y} - \frac{1}{4+2y} dy = \left[ \frac{\ln | \frac{3+2y}{4+2y} |}{2} \right]_1^2 = \frac{\ln(\frac{21}{20})}{2}$$

- $f(x, y) = \frac{x}{1+y}$  over  $Q = [0, 1] \times [2, 3]$ .

Apply Fubini's theorem for double integrals:

$$\int_0^1 \int_2^3 \frac{x}{1+y} dy dx = \int_0^1 x [\ln |1+y|]_2^3 dx = (\ln 4 - \ln 3) \int_0^1 x dx = \ln\left(\frac{4}{3}\right) \left[ \frac{x^2}{2} \right]_0^1 = \frac{\ln(\frac{4}{3})}{2}$$

- $f(x, y) = \frac{x}{1+xy}$  over  $Q = [0, 1] \times [0, 2]$ .

Apply Fubini's theorem for double integrals:

$$\int_0^1 \int_0^2 \frac{x}{1+xy} dy dx$$

Apply a change of variable: let  $u = 1+xy$ , for  $u \in [1, 1+2x]$ , and consider  $\frac{du}{dy} = x$ , resulting in:

$$\int_0^1 \int_1^{1+2x} \frac{1}{u} du dx = \int_0^1 [\ln |u|]_1^{1+2x} dx = \int_0^1 \ln(1+2x) dx$$

Apply another change of variable: let  $t = 1 + 2x$ , for  $t \in [1, 3]$ , and consider  $\frac{dt}{dx} = 2$ , resulting in:

$$\frac{1}{2} \int_1^3 \ln t \, dt = \frac{1}{2} [t \ln t - t]_1^3 = \frac{3 \ln 3 - 2}{2}$$

- $f(x, y) = xye^{x^2+y^2}$  over the rectangle of vertices  $(0, 0), (2, 0), (0, 3), (2, 3)$ . By plotting the rectangle on a graph, observe that the region can be written as  $Q = [0, 2] \times [0, 3]$ .

Most particularly, by the properties of exponentials, let  $xye^{x^2+y^2} = xe^{x^2}ye^{y^2}$  and solve the integral by applying decoupling:

$$\int_0^3 \int_0^2 xye^{x^2+y^2} \, dx dy = \int_0^2 xe^{x^2} \, dx \int_0^3 ye^{y^2} \, dy$$

Consider each integral separately:

1. Integral with respect to  $x$ :

$$\int_0^2 xe^{x^2} \, dx$$

Apply a change of variable: let  $u = x^2$ , for  $u \in [0, 4]$ , and consider  $\frac{du}{dx} = 2x$ , resulting in:

$$\frac{1}{2} \int_0^4 e^u \, du = \frac{1}{2} [e^u]_0^4 = \frac{e^4 - 1}{2}$$

2. Integral with respect to  $y$ :

$$\int_0^3 ye^{y^2} \, dy$$

Apply a change of variable: let  $t = y^2$ , for  $t \in [0, 9]$ , and consider  $\frac{dt}{dy} = 2y$ , resulting in:

$$\frac{1}{2} \int_0^9 e^t \, dt = \frac{1}{2} [e^t]_0^9 = \frac{e^9 - 1}{2}$$

Therefore, it is possible to conclude that:

$$\int_0^3 \int_0^2 xye^{x^2+y^2} \, dx dy = \frac{e^4 - 1}{2} \cdot \frac{e^9 - 1}{2} = \frac{e^{13} - e^9 - e^4 + 1}{4}$$

- $f(x, y) = x \sin(xy)$  over  $Q = [1, 2] \times [2, 3]$ . Apply Fubini's theorem for double integrals:

$$\int_1^2 \int_2^3 x \sin(xy) \, dy dx$$

Apply a change of variable: let  $u = xy$ , for  $u \in [2x, 3x]$ , and consider  $\frac{du}{dy} = x$ , resulting in:

$$\int_1^2 \int_{2x}^{3x} \sin u \, du \, dx = \int_1^2 [-\cos u]_{2x}^{3x} \, dx = \int_1^2 \cos 2x - \cos 3x \, dx = \left[ \frac{\sin 2x}{2} - \frac{\sin 3x}{3} \right]_1^2$$

## 8.2 Exercise 2

Write the following domains as a normal domain with respect to  $x$  and as a normal domain with respect to  $y$ :

- The triangle with vertices  $(1, 0), (2, 0), (2, 1)$ .

1. With respect to  $x$ :

$$D = \{(x, y) \in \mathbb{R}^2 : 1 \leq x \leq 2, 0 \leq y \leq x - 1\}$$

2. With respect to  $y$ :

$$D = \{(x, y) \in \mathbb{R}^2 : 0 \leq y \leq 1, y + 1 \leq x \leq 2\}$$

- The triangle with vertices  $(0, 0), (1, 0), (\frac{1}{2}, 1)$ .

1. With respect to  $x$ :

$$D = \{(x, y) \in \mathbb{R}^2 : 0 \leq x \leq \frac{1}{2}, 0 \leq y \leq 2x\} \cup \{(x, y) \in \mathbb{R}^2 : \frac{1}{2} \leq x \leq 1, 0 \leq y \leq 2 - 2x\}$$

2. With respect to  $y$ :

$$D = \{(x, y) \in \mathbb{R}^2 : 0 \leq y \leq 1, \frac{y}{2} \leq x \leq 1 - \frac{y}{2}\}$$

- The region bounded by the lines  $y = 2x$ ,  $y = x$  and  $y = -x + 1$ .

1. With respect to  $x$ :

$$D = \{(x, y) \in \mathbb{R}^2 : 0 \leq x \leq \frac{1}{3}, x \leq y \leq 2x\} \cup \{(x, y) \in \mathbb{R}^2 : \frac{1}{3} \leq x \leq \frac{1}{2}, x \leq y \leq 1 - x\}$$

2. With respect to  $y$ :

$$D = \{(x, y) \in \mathbb{R}^2 : 0 \leq y \leq \frac{1}{2}, \frac{y}{2} \leq x \leq y\} \cup \{(x, y) \in \mathbb{R}^2 : \frac{1}{2} \leq y \leq \frac{2}{3}, \frac{y}{2} \leq x \leq 1 - y\}$$

- $D = \{(x, y) \in \mathbb{R}^2 : x \geq 0, y \leq 0, y \geq x - 3\}$ .

1. With respect to  $x$ :

$$D = \{(x, y) \in \mathbb{R}^2 : 0 \leq x \leq 3, x - 3 \leq y \leq 0\}$$

2. With respect to  $y$ :

$$D = \{(x, y) \in \mathbb{R}^2 : -3 \leq y \leq 0, 0 \leq x \leq 3 - y\}$$

- The region bounded by  $y = x^2$  and  $y = 1$ .

1. With respect to  $x$ :

$$D = \{(x, y) \in \mathbb{R}^2 : 0 \leq x \leq 1, x^2 \leq y \leq 1\}$$

2. With respect to  $y$ :

$$D = \{(x, y) \in \mathbb{R}^2 : 0 \leq y \leq 1, 0 \leq x \leq \sqrt{y}\}$$

- The region bounded by  $y = \sqrt{x}$ ,  $y = 1 - x$  and the  $x$ -axis.

1. With respect to  $x$ :

$$D = \{(x, y) \in \mathbb{R}^2 : 0 \leq x \leq \frac{3 - \sqrt{5}}{2}, 0 \leq y \leq \sqrt{x}\} \cup \{(x, y) \in \mathbb{R}^2 : \frac{3 - \sqrt{5}}{2} \leq x \leq 1, 0 \leq y \leq 1 - x\}$$

2. With respect to  $y$ :

$$D = \{(x, y) \in \mathbb{R}^2 : 0 \leq y \leq \frac{-1 + \sqrt{5}}{2}, y^2 \leq x \leq 1 - y\}$$

- The quarter of the unit circle contained in the second quadrant.

1. With respect to  $x$ :

$$D = \{(x, y) \in \mathbb{R}^2 : -1 \leq x \leq 0, 0 \leq y \leq \sqrt{1 - x^2}\}$$

2. With respect to  $y$ :

$$D = \{(x, y) \in \mathbb{R}^2 : 0 \leq y \leq 1, -\sqrt{1 - y^2} \leq x \leq 0\}$$

### 8.3 Exercise 3

Compute the area of the following regions:

- The triangle with vertices  $(0, 0)$ ,  $(2, 0)$ ,  $(1, 1)$ .  
By plotting the triangle on a graph, write the corresponding region as a normal domain with respect to  $y$ :

$$D = \{(x, y) \in \mathbb{R}^2 : 0 \leq y \leq 1, y \leq x \leq 2 - y\}$$

Therefore, apply Fubini's theorem for double integrals and rewrite the integral in the following way:

$$A(D) = \int \int_D dx dy = \int_0^1 \int_y^{2-y} dx dy = \int_0^1 2 - 2y dy = [2y - y^2]_0^1 = 1$$



- $D = \{(x, y) \in \mathbb{R}^2 : x \leq 0, y \geq 0, y \leq x + 2\}$ .

By plotting the corresponding region on a graph, rewrite  $D$  as a normal domain with respect to  $x$ :

$$D = \{(x, y) \in \mathbb{R}^2 : -2 \leq x \leq 0, 0 \leq y \leq x + 2\}$$

Therefore, apply Fubini's theorem for double integrals and rewrite the integral in the following way:

$$A(D) = \int \int_D dx dy = \int_{-2}^0 \int_0^{x+2} dy dx = \int_{-2}^0 x + 2 dx = \left[\frac{x^2}{2} + 2x\right]_{-2}^0 = 2$$

- The region bounded between  $y = -x^2 + 1$  and  $y = 0$ .

By plotting the corresponding region on a graph, rewrite  $D$  as a normal domain with respect to  $x$ :

$$D = \{(x, y) \in \mathbb{R}^2 : -1 \leq x \leq 1, 0 \leq y \leq 1 - x^2\}$$

Therefore, apply Fubini's theorem for double integrals and rewrite the integral in the following way:

$$A(D) = \int \int_D dx dy = \int_{-1}^1 \int_0^{1-x^2} dy dx = \int_{-1}^1 1 - x^2 dx = \left[x - \frac{x^3}{3}\right]_{-1}^1 = \frac{4}{3}$$

- The region bounded by  $y = \sqrt{x}$ ,  $y = 0$  and  $x = 2$ .

By plotting the region on a graph, rewrite it as a normal domain with respect to  $x$ :

$$D = \{(x, y) \in \mathbb{R}^2 : 0 \leq x \leq 2, 0 \leq y \leq \sqrt{x}\}$$

Therefore, apply Fubini's theorem for double integrals and rewrite the integral in the following way:

$$A(D) = \int \int_D dx dy = \int_0^2 \int_0^{\sqrt{x}} dy dx = \int_0^2 \sqrt{x} dx = \left[\frac{x^{\frac{3}{2}}}{\frac{3}{2}}\right]_0^2 = \frac{4\sqrt{2}}{3}$$

- $D = \{(x, y) \in \mathbb{R}^2 : y \geq x^2 - 1, y \leq -x^2 + 1\}$ .

By plotting the corresponding region on a graph, rewrite  $D$  as a normal domain with respect to  $x$ :

$$D = \{(x, y) \in \mathbb{R}^2 : -1 \leq x \leq 1, x^2 - 1 \leq y \leq 1 - x^2\}$$

Therefore, apply Fubini's theorem for double integrals and rewrite the integral in the following way:

$$A(D) = \int \int_D dx dy = \int_{-1}^1 \int_{x^2-1}^{1-x^2} dy dx = \int_{-1}^1 2 - 2x^2 dx = \left[2x - \frac{2x^3}{3}\right]_{-1}^1 = \frac{8}{3}$$

## 8.4 Exercise 4

Compute the integral of  $f(x, y) = xe^y$  over the triangle with vertices  $(0, 0)$ ,  $(-1, 0)$ ,  $(0, -1)$ . By plotting the triangle on a graph, rewrite  $D$  as a normal domain with respect to  $x$ :

$$D = \{(x, y) \in \mathbb{R}^2 : -1 \leq x \leq 0, -1-x \leq y \leq 0\}$$

Therefore, apply Fubini's theorem for double integrals and rewrite the integral in the following way:

$$\int_{-1}^0 \int_{-1-x}^0 xe^y dy dx = \int_{-1}^0 x[e^y]_{-1-x}^0 dx = \int_{-1}^0 x(1-e^{-1-x}) dx = \int_{-1}^0 x-xe^{-1-x} dx$$

At this point, apply integral linearity and solve each integral separately:

1. First integral:

$$\int_{-1}^0 x dx = \left[\frac{x^2}{2}\right]_{-1}^0 = -\frac{1}{2}$$

2. Second integral:

$$\int_{-1}^0 xe^{-1-x} dx = \int_{-1}^0 \frac{xe^{-x}}{e} dx$$

Apply integration by parts and let  $f'(x) = e^{-x}$  and  $g(x) = x$ :

$$\int_{-1}^0 xe^{-1-x} dx = \frac{1}{e}([-xe^{-x}]_{-1}^0 - \int_{-1}^0 -e^{-x} dx) = \frac{1}{e}[-xe^{-x} - e^{-x}]_{-1}^0 = -\frac{1}{e}$$

Therefore, it is possible to conclude that:

$$\int \int_D xe^y dx dy = -\frac{1}{2} - \left(-\frac{1}{e}\right) = \frac{2-e}{2e}$$

## 8.5 Exercise 5

Compute the following integrals:

- $f(x, y) = x$  over  $D = \{(x, y) \in \mathbb{R}^2 : -1 \leq x \leq 1, 0 \leq y \leq 1-x^2\}$ .

Since  $D$  is expressed as a normal domain with respect to  $x$ , apply Fubini's theorem for double integrals and solve the integral in the following way:

$$\int_{-1}^1 \int_0^{1-x^2} x dy dx = \int_{-1}^1 x[y]_0^{1-x^2} dx = \int_{-1}^1 x(1-x^2) dx = \left[\frac{x^2}{2} - \frac{x^4}{4}\right]_{-1}^1 = 0$$

**N.B.:** It is possible to directly conclude that the integral is equal to 0 by observing the symmetry of  $x(1-x^2)$ , which is an odd function in the interval  $[-1, 1]$ .

- $f(x, y) = x^2 + y$  over  $D = \{(x, y) \in \mathbb{R}^2 : 0 \leq x \leq 2, 0 \leq y \leq \frac{x}{2}\}$ .  
Since  $D$  is expressed as a normal domain with respect to  $x$ , apply Fubini's theorem for double integrals and solve the integral in the following way:

$$\int_0^2 \int_0^{\frac{x}{2}} x^2 + y \, dy \, dx = \int_0^2 [x^2 y + \frac{y^2}{2}]_0^{\frac{x}{2}} \, dx = \int_0^2 \frac{x^3}{2} + \frac{x^2}{8} \, dx = [\frac{x^4}{8} + \frac{x^3}{24}]_0^2 = \frac{7}{3}$$

- $f(x, y) = xy$  over the triangle of vertices  $(0, 0), (0, 1), (1, 1)$ .  
By plotting the triangle on a graph, write the corresponding region as a normal domain with respect to  $x$ :

$$D = \{(x, y) \in \mathbb{R}^2 : 0 \leq x \leq 1, 0 \leq y \leq x\}$$

Therefore, apply Fubini's theorem for double integrals and solve the integral in the following way:

$$\int_0^1 \int_0^x xy \, dy \, dx = \int_0^1 x [\frac{y^2}{2}]_0^x \, dx = \int_0^1 \frac{x^3}{2} \, dx = [\frac{x^4}{8}]_0^1 = \frac{1}{8}$$

- $f(x, y) = y^3$  over the triangle of vertices  $(0, 2), (1, 1), (3, 2)$ .  
By plotting the triangle on a graph, write the corresponding region as a normal domain with respect to  $y$ :

$$D = \{(x, y) \in \mathbb{R}^2 : 1 \leq y \leq 2, 2 - y \leq x \leq 2y - 1\}$$

Therefore, apply Fubini's theorem for double integrals and solve the integral in the following way:

$$\int_1^2 \int_{2-y}^{2y-1} y^3 \, dx \, dy = \int_1^2 y^3 [x]_{2-y}^{2y-1} \, dy = \int_1^2 3y^4 - 3y^3 \, dy = [\frac{3y^5}{5} - \frac{3y^4}{4}]_1^2 = \frac{93}{5} - \frac{45}{4}$$

- $f(x, y) = ye^{-x^2}$  over  $D = \{(x, y) \in \mathbb{R}^2 : 0 \leq x \leq 1, 0 \leq y \leq \sqrt{x}\}$ .  
Since  $D$  is expressed as a normal domain with respect to  $x$ , apply Fubini's theorem for double integrals and solve the integral in the following way:

$$\int_0^1 \int_0^{\sqrt{x}} ye^{-x^2} \, dy \, dx = \int_0^1 e^{-x^2} [\frac{y^2}{2}]_0^{\sqrt{x}} \, dx = \int_0^1 \frac{x}{2} e^{-x^2} \, dx$$

Apply a change of variable: let  $u = -x^2$ , for  $u \in [0, -1]$ , and consider  $\frac{du}{dx} = -2x$ , resulting in:

$$-\frac{1}{4} \int_0^{-1} e^u \, du = \frac{1}{4} \int_{-1}^0 e^u \, du = \frac{1}{4} [e^u]_{-1}^0 = \frac{1 - e^{-1}}{4}$$

## Chapter 9

# Exercise Sheet 9: Double and triple integrals

### 9.1 Exercise 1

Compute the following double integrals:

- $f(x, y) = x^2$  over  $D = \{(x, y) \in \mathbb{R}^2 : 4 \leq x^2 + y^2 \leq 9\}$ . Solve the integral by switching to polar coordinates:

$$\begin{cases} x = \rho \cos \theta \\ y = \rho \sin \theta \end{cases}, \text{ for } \rho \in [2, 3] \text{ and } \theta \in [0, 2\pi] \Rightarrow |\det(J)| = \rho$$

Therefore, it is possible to rewrite the integral in the following way:

$$\int \int_D x^2 \, dx dy = \int_2^3 \int_0^{2\pi} \rho^2 \cos^2 \theta \cdot \rho \, d\rho d\theta = \int_2^3 \int_0^{2\pi} \rho^3 \cos^2 \theta \, d\rho d\theta$$

Solve the integral by applying decoupling:

$$\int_2^3 \rho^3 \, d\rho \int_0^{2\pi} \cos^2 \theta \, d\theta = \left[\frac{\rho^4}{4}\right]_2^3 \left[\frac{\theta}{2} + \frac{\sin 2\theta}{4}\right]_0^{2\pi} = \frac{65\pi}{4}$$

- $f(x, y) = x^2 + y^2$  over  $D = \{(x, y) \in \mathbb{R}^2 : 1 \leq x^2 + y^2 \leq 4, x \geq 0, y \geq 0\}$ . Solve the integral by switching to polar coordinates:

$$\begin{cases} x = \rho \cos \theta \\ y = \rho \sin \theta \end{cases}, \text{ for } \rho \in [1, 2] \text{ and } \theta \in [0, \frac{\pi}{2}] \Rightarrow |\det(J)| = \rho$$

Therefore, it is possible to rewrite the integral in the following way:

$$\int \int_D x^2 + y^2 \, dx dy = \int_1^2 \int_0^{\frac{\pi}{2}} (\rho^2 \cos^2 \theta + \rho^2 \sin^2 \theta) \cdot \rho \, d\rho d\theta = \int_1^2 \int_0^{\frac{\pi}{2}} \rho^3 \, d\rho d\theta$$

Solve the integral by applying decoupling:

$$\int_1^2 \rho^3 d\rho \int_0^{\frac{\pi}{2}} d\theta = [\frac{\rho^4}{4}]_1^2 [\theta]_0^{\frac{\pi}{2}} = \frac{15}{4} \frac{\pi}{2} = \frac{15\pi}{8}$$

- $f(x, y) = y^3$  over  $D = \{(x, y) \in \mathbb{R}^2 : x^2 + y^2 \leq 1, x \geq |y|\}$ .  
Solve the integral by switching to polar coordinates:

$$\begin{cases} x = \rho \cos \theta \\ y = \rho \sin \theta \end{cases}, \text{ for } \rho \in [0, 1] \text{ and } \theta \in [-\frac{\pi}{4}, \frac{\pi}{4}] \Rightarrow |det(J)| = \rho$$

Therefore, it is possible to rewrite the integral in the following way:

$$\int \int_D y^3 dx dy = \int_0^1 \int_{-\frac{\pi}{4}}^{\frac{\pi}{4}} \rho^3 \sin^3 \theta \cdot \rho d\rho d\theta = \int_0^1 \int_{-\frac{\pi}{4}}^{\frac{\pi}{4}} \rho^4 \sin^3 \theta d\rho d\theta$$

Notice that this integral is actually equal to 0 by symmetry of  $\sin^3 \theta$ , which is an odd function in the interval  $[-\frac{\pi}{4}, \frac{\pi}{4}]$ .

- $f(x, y) = xy^2$  over  $D = \{x^2 + y^2 \leq 1, y \geq 0, x \geq 0, y \geq -x + 1\}$ .  
Apply integral additivity and let  $D = D_1 \setminus (D_2 \cup D_3)$  and consider each region separately:

1. Let  $D_1 = \{x^2 + y^2 \leq 1, y \geq 0, x \geq 0\}$  and solve the integral by switching to polar coordinates:

$$\begin{cases} x = \rho \cos \theta \\ y = \rho \sin \theta \end{cases} \text{ for } \rho \in [0, 1] \text{ and } \theta \in [0, \frac{\pi}{2}] \Rightarrow |det(J)| = \rho$$

Therefore, it is possible to rewrite the integral in the following way:

$$\int_0^1 \int_0^{\frac{\pi}{2}} \rho \cos \theta \rho^2 \sin^2 \theta \cdot \rho d\rho d\theta = \int_0^1 \int_0^{\frac{\pi}{2}} \rho^4 \cos \theta \sin^2 \theta d\rho d\theta$$

Solve the integral by applying decoupling:

$$\int_0^1 \rho^4 d\rho \int_0^{\frac{\pi}{2}} \cos \theta \sin^2 \theta d\theta = [\frac{\rho^5}{5}]_0^1 [\frac{\sin^3 \theta}{3}]_0^{\frac{\pi}{2}} = \frac{1}{5} \cdot \frac{1}{3} = \frac{1}{15}$$

2. By plotting, let  $D_2 = \{0 \leq x \leq \frac{1}{2}, x \leq y \leq 1 - x\}$  and apply Fubini's theorem for double integrals:

$$\int_0^{\frac{1}{2}} \int_x^{1-x} xy^2 dy dx = \int_0^{\frac{1}{2}} x [\frac{y^3}{3}]_x^{1-x} dx = \int_0^{\frac{1}{2}} \frac{x(1-x)^3}{3} - \frac{x \cdot x^3}{3} dx$$

Rewrite the integral in the following way:

$$\int_0^{\frac{1}{2}} \frac{x - 3x^2 + 3x^3 - 2x^4}{3} dx = [\frac{x^2}{6} - \frac{x^3}{3} + \frac{x^4}{4} - \frac{2x^5}{15}]_0^{\frac{1}{2}} = \frac{11}{960}$$

3. Let  $D_3 = \{x^2 + y^2 \leq 1, x \geq 0, 0 \leq y \leq x\}$  and solve the integral by switching to polar coordinates:

$$\begin{cases} x = \rho \cos \theta \\ y = \rho \sin \theta \end{cases} \quad \text{for } \rho \in [0, 1] \text{ and } \theta \in [0, \frac{\pi}{4}] \Rightarrow |\det(J)| = \rho$$

Therefore, it is possible to rewrite the integral in the following way:

$$\int_0^1 \int_0^{\frac{\pi}{4}} \rho \cos \theta \rho^2 \sin^2 \theta \cdot \rho \, d\rho d\theta = \int_0^1 \int_0^{\frac{\pi}{4}} \rho^4 \cos \theta \sin^2 \theta \, d\rho d\theta$$

Solve the integral by applying decoupling:

$$\int_0^1 \rho^4 \, d\rho \int_0^{\frac{\pi}{4}} \cos \theta \sin^2 \theta \, d\theta = [\frac{\rho^5}{5}]_0^1 [\frac{\sin^3 \theta}{3}]_0^{\frac{\pi}{4}} = \frac{1}{5} \cdot \frac{2\sqrt{2}}{24} = \frac{\sqrt{2}}{60}$$

Therefore, it is possible to conclude that:

$$\iint_D xy^2 \, dx dy = \frac{1}{15} - (\frac{11}{960} + \frac{\sqrt{2}}{60}) = \frac{53 - 16\sqrt{2}}{960}$$

- $f(x, y) = x + y$  over  $D = \{(x, y) \in \mathbb{R}^2 : x^2 + y^2 \leq 2, y \leq x^2, x \geq 0\}$ .  
Apply integral additivity and let  $D = D_1 \cup D_2$  and consider each region separately:

1. Let  $D_1 = \{0 \leq x \leq 1, -\sqrt{2-x^2} \leq y \leq x^2\}$  and apply Fubini's theorem for double integrals:

$$\int_0^1 \int_{-\sqrt{2-x^2}}^{x^2} x+y \, dy dx = \int_0^1 [xy + \frac{y^2}{2}]_{-\sqrt{2-x^2}}^{x^2} dx = \int_0^1 x^3 + \frac{x^4}{2} + x\sqrt{2-x^2} - \frac{2-x^2}{2} \, dx$$

For simplicity, apply integral linearity and solve each integral separately:

- (a) First integral:

$$\int_0^1 x^3 \, dx = [\frac{x^4}{4}]_0^1 = \frac{1}{4}$$

- (b) Second integral:

$$\int_0^1 \frac{x^4}{2} \, dx = [\frac{x^5}{10}]_0^1 = \frac{1}{10}$$

- (c) Third integral:

$$\int_0^1 x\sqrt{2-x^2} \, dx$$

Apply a change of variable: let  $u = 2 - x^2$ , for  $u \in [2, 1]$ , and consider  $\frac{du}{dx} = -2x$ , resulting in:

$$-\frac{1}{2} \int_2^1 \sqrt{u} \, du = \frac{1}{2} \int_1^2 \sqrt{u} \, du = \frac{1}{2} \left[ \frac{u^{\frac{3}{2}}}{\frac{3}{2}} \right]_1^2 = \frac{2\sqrt{2}-1}{3}$$

(d) Fourth integral:

$$\int_0^1 \frac{2-x^2}{2} \, dx = \int_0^1 1 - \frac{x^2}{2} \, dx = \left[ x - \frac{x^3}{6} \right]_0^1 = \frac{5}{6}$$

Therefore, it is possible to conclude that:

$$\int \int_{D_1} x + y \, dx dy = \frac{1}{4} + \frac{1}{10} + \frac{2\sqrt{2}-1}{3} - \frac{5}{6} = \frac{40\sqrt{2}-49}{60}$$

2. Let  $D_2 = \{1 \leq x \leq \sqrt{2}, -\sqrt{2-x^2} \leq y \leq \sqrt{2-x^2}\}$  and apply Fubini's theorem for double integrals:

$$\int_1^{\sqrt{2}} \int_{-\sqrt{2-x^2}}^{\sqrt{2-x^2}} x+y \, dy dx = \int_1^{\sqrt{2}} \left[ xy + \frac{y^2}{2} \right]_{-\sqrt{2-x^2}}^{\sqrt{2-x^2}} dx = \int_1^{\sqrt{2}} 2x\sqrt{2-x^2} \, dx$$

Apply a change of variable: let  $u = 2 - x^2$ , for  $u \in [1, 0]$ , and consider  $\frac{du}{dx} = -2x$ , resulting in:

$$-\int_1^0 \sqrt{u} \, du = \int_0^1 \sqrt{u} \, du = \left[ \frac{u^{\frac{3}{2}}}{\frac{3}{2}} \right]_0^1 = \frac{2}{3}$$

Therefore, it is possible to conclude that:

$$\int \int_D x + y \, dx dy = \frac{40\sqrt{2}-49}{60} + \frac{2}{3} = \frac{40\sqrt{2}-9}{60}$$

- $f(x, y) = y \cos x$  over  $D = \{(x, y) \in \mathbb{R}^2 : x^2 + y^2 \leq 1, y \geq 1 - x\}$ .  
By plotting the corresponding region on a graph, rewrite  $D$  as a normal domain with respect to  $x$ :

$$D = \{(x, y) \in \mathbb{R}^2 : 0 \leq x \leq 1, 1-x \leq y \leq \sqrt{1-x^2}\}$$

Therefore, apply Fubini's theorem for double integrals and rewrite the integral in the following way:

$$\int_0^1 \int_{1-x}^{\sqrt{1-x^2}} y \cos x \, dy dx = \int_0^1 \cos x \left[ \frac{y^2}{2} \right]_{1-x}^{\sqrt{1-x^2}} dx = \int_0^1 (x-x^2) \cos x \, dx$$

At this point, apply integral linearity and solve each integral separately:

1. First integral:

$$\int_0^1 x \cos x \, dx$$

Apply integration by parts and let  $f'(x) = \cos x$  and  $g(x) = x$ :

$$\int_0^1 x \cos x \, dx = [x \sin x]_0^1 - \int_0^1 \sin x \, dx = [x \sin x + \cos x]_0^1 = \sin 1 + \cos 1 - 1$$

2. Second integral:

$$\int_0^1 x^2 \cos x \, dx$$

Apply integration by parts and let  $f'(x) = \cos x$  and  $g(x) = x^2$ :

$$\int_0^1 x^2 \cos x = [x^2 \sin x]_0^1 - \int_0^1 2x \sin x \, dx$$

Again, apply integration by parts and let  $r'(x) = \sin x$  and  $s(t) = 2x$ :

$$\int_0^1 2x \sin x \, dx = [-2x \cos x]_0^1 - \int_0^1 -2 \cos x \, dx = [-2x \cos x + 2 \sin x]_0^1$$

This allows to conclude that:

$$\int_0^1 x^2 \cos x \, dx = [x^2 \sin x + 2x \cos x - 2 \sin x]_0^1 = 2 \cos 1 - \sin 1$$

Therefore, it is possible to conclude that:

$$\int \int_D y \cos x \, dx dy = \sin 1 + \cos 1 - 1 - (2 \cos 1 - \sin 1) = 2 \sin 1 - \cos 1 - 1$$

- $f(x, y) = e^{x-y}$ , where  $D$  is the region bounded by  $x + y = 4$ ,  $3x + y = 4$  and  $x + 3y = 4$ .

Apply integral additivity and let  $D = D_1 \cup D_2$  and consider each region separately:

1. Let  $D_1 = \{0 \leq x \leq 1, 4 - 3x \leq y \leq 4 - x\}$  and apply Fubini's theorem for double integrals:

$$\int_0^1 \int_{4-3x}^{4-x} e^x e^{-y} \, dy dx = \int_0^1 e^x [-e^{-y}]_{4-3x}^{4-x} \, dx = \int_0^1 \frac{e^{4x} - e^{2x}}{e^4} \, dx = \frac{1}{e^4} \left[ \frac{e^{4x}}{4} - \frac{e^{2x}}{2} \right]_0^1 = \frac{e^4 - 2e^2 + 1}{4e^4}$$

2. Let  $D_2 = \{1 \leq x \leq 4, \frac{4-x}{3} \leq y \leq 4-x\}$  and apply Fubini's theorem for double integrals:

$$\int_1^4 \int_{\frac{4-x}{3}}^{4-x} e^x e^{-y} \, dy dx = \int_1^4 e^x [-e^{-y}]_{\frac{4-x}{3}}^{4-x} \, dx = \int_1^4 \frac{e^{\frac{4x}{3}}}{e^{\frac{4}{3}}} - \frac{e^{2x}}{e^4} \, dx = \left[ \frac{3e^{\frac{4x}{3}}}{4e^{\frac{4}{3}}} - \frac{e^{2x}}{2e^4} \right]_1^4 = \frac{e^6 - 3e^2 + 2}{4e^4}$$



Therefore, it is possible to conclude that:

$$\int \int_D e^{x-y} dx dy = \frac{e^4 - 2e^2 + 1}{4e^4} + \frac{e^6 - 3e^2 + 2}{4e^4} = \frac{e^6 + e^4 - 5e^2 + 3}{4e^4}$$

## 9.2 Exercise 2

Compute the volume of the following regions:

- $\Omega = \{(x, y, z) \in \mathbb{R}^3 : 0 \leq x \leq 1, 1 \leq y \leq 2, z \geq 0, z \leq 4 - x - y\}$ .  
Start by extracting  $Q = [0, 1] \times [1, 2]$  and  $z \in [0, 4 - x - y]$  from the definition of  $\Omega$ , resulting in:

$$V(\Omega) \int \int \int_{\Omega} dx dy dz = \int \int_Q \int_0^{4-x-y} dz dx dy = \int \int_Q 4 - x - y dx dy$$

At this point, apply Fubini's theorem for double integrals:

$$V(\Omega) = \int_1^2 \int_0^1 4 - x - y dx dy = \int_1^2 [4x - \frac{x^2}{2} - yx]_0^1 dy = \int_1^2 \frac{7}{2} - y dy = [\frac{7y}{2} - \frac{y^2}{2}]_1^2 = 2$$

- $\Omega = \{(x, y, z) \in \mathbb{R}^3 : x^2 + y^2 \leq z \leq 2\}$ .  
Due to the definition of  $\Omega$ , it is useful to switch to cylindrical coordinates:

$$\begin{cases} x = \rho \cos \theta \\ y = \rho \sin \theta \\ z = z \end{cases} \quad \text{for } \rho \in [0, \sqrt{2}], \theta \in [0, 2\pi] \text{ and } z \in [\rho^2, 2].$$

Knowing that, in cylindrical coordinates,  $|\det(J)| = \rho$ , it is possible to conclude that:

$$\begin{aligned} V(\Omega) &= \int \int \int_{\Omega} dx dy dz = \int_0^{\sqrt{2}} \int_0^{2\pi} \int_{\rho^2}^2 \rho d\rho d\theta dz \\ V(\Omega) &= 2\pi \int_0^{\sqrt{2}} \rho [z]_{\rho^2}^2 d\rho = 2\pi \int_0^{\sqrt{2}} 2\rho - \rho^3 d\rho = 2\pi [\rho^2 - \frac{\rho^4}{4}]_0^{\sqrt{2}} = 2\pi \end{aligned}$$

## 9.3 Exercise 3

Compute the following integral:

$$\int \int \int_{\Omega} x + y + z dx dy dz, \Omega = \{0 \leq x \leq 1, 2x \leq y \leq x, 0 \leq z \leq x + y\}$$

From the definition of  $\Omega$ , let  $D = \{0 \leq x \leq 1, 2x \leq y \leq x\}$  and  $z \in [0, x + y]$ , resulting in:

$$\int_0^1 \int_{2x}^x \int_0^{x+y} x + y + z dz dy dx = \int_0^1 \int_{2x}^x x(x + y) + y(x + y) + \frac{(x + y)^2}{2} dy dx$$

Most particularly, by doing some algebra, it is possible to rewrite the integral in the following way:

$$\int_0^1 \int_{2x}^x (x+y) \left( \frac{3x+3y}{2} \right) dy dx = \int_0^1 \int_{2x}^x \frac{3(x+y)^2}{2} dy dx$$

At this point, apply Fubini's theorem for double integrals:

$$\int_0^1 \int_{2x}^x \frac{3(x+y)^2}{2} dy dx = \int_0^1 \frac{3}{2} \left[ \frac{(x+y)^3}{3} \right]_{2x}^x dx = \int_0^1 -\frac{19x^3}{2} dx = \left[ -\frac{x^4}{8} \right]_0^1 = -\frac{19}{8}$$

## 9.4 Exercise 4

Compute the following integral:

$$\iiint_{\Omega} y \, dx dy dz, \Omega = \{x^2 + y^2 \leq 1, z \geq 0, z \leq x\}$$

Solve the integral by switching to cylindrical coordinates:

$$\begin{cases} x = \rho \cos \theta \\ y = \rho \sin \theta \\ z = z \end{cases} \quad \text{for } \rho \in [0, 1], \theta \in [0, 2\pi], z \in [0, \rho \cos \theta] \Rightarrow |\det(J)| = \rho$$

Therefore, it is possible to rewrite the integral in the following way:

$$\int_0^1 \int_0^{2\pi} \left( \int_0^{\rho \cos \theta} \rho \sin \theta \cdot \rho \, dz \right) d\rho d\theta = \int_0^1 \int_0^{2\pi} \rho^2 \sin \theta \cdot \rho \cos \theta \, d\rho d\theta$$

Solve the integral by applying decoupling:

$$\int_0^1 \rho^3 \, d\rho \int_0^{2\pi} \sin \theta \cos \theta \, d\theta = \left[ \frac{\rho^4}{4} \right]_0^1 \left[ \frac{\sin^2 \theta}{2} \right]_0^{2\pi} = 0$$

**N.B.:** It is possible to directly notice that the integral is 0 either by observing the periodicity of  $\sin \theta$  or by applying substitution and letting  $u = \sin \theta$ , with  $u \in [0, 0]$ .

## 9.5 Exercise 5

Compute the following integral:

$$\iiint_{\Omega} e^y z \, dx dy dz, \Omega = \{0 \leq x \leq 1, 0 \leq y \leq x^3, 0 \leq z \leq x\}$$

From the definition of  $\Omega$ , let  $D = \{0 \leq x \leq 1, 0 \leq y \leq x^3\}$  and  $z \in [0, x]$ , resulting in:

$$\int_0^1 \int_0^{x^3} \left( \int_0^x e^y z \, dz \right) dy dx = \int_0^1 \int_0^{x^3} e^y \frac{x^2}{2} \, dy dx$$

At this point, apply Fubini's theorem for double integrals:

$$\int_0^1 \int_0^{x^3} e^y \frac{x^2}{2} dy dx = \int_0^1 \frac{x^2}{2} [e^y]_0^{x^3} dx = \int_0^1 \frac{x^2}{2} (e^{x^3} - 1) dx$$

Apply integral linearity and solve each integral separately:

1. First integral:

$$\int_0^1 \frac{x^2 e^{x^3}}{2} dx$$

Apply a change of variable: let  $u = x^3$ , for  $u \in [0, 1]$ , and consider  $\frac{du}{dx} = 3x^2$ , resulting in:

$$\frac{1}{6} \int_0^1 e^u du = \frac{1}{6} [e^u]_0^1 = \frac{e-1}{6}$$

2. Second integral:

$$\int_0^1 \frac{x^2}{2} dx = [\frac{x^3}{6}]_0^1 = \frac{1}{6}$$

Therefore, it is possible to conclude that:

$$\int \int \int_{\Omega} e^y z dx dy dz = \frac{e-1}{6} - \frac{1}{6} = \frac{e-2}{6}$$

## 9.6 Exercise 6

Compute the following integral:

$$\int \int \int_{\Omega} yz dx dy dz, \Omega = \{x^2 + y^2 \leq 4, y - z + 1 \geq 0, z \geq -4\}$$

Solve the integral by switching to cylindrical coordinates:

$$\begin{cases} x = \rho \cos \theta \\ y = \rho \sin \theta \\ z = z \end{cases} \quad \text{for } \rho \in [0, 2], \theta \in [0, 2\pi], z \in [-4, \rho \sin \theta + 1] \Rightarrow |\det(J)| = \rho$$

Therefore, it is possible to rewrite the integral in the following way:

$$\int_0^2 \int_0^{2\pi} \left( \int_{-4}^{\rho \sin \theta + 1} \rho \sin \theta z \cdot \rho dz \right) d\rho d\theta = \int_0^2 \int_0^{2\pi} \rho^2 \sin \theta \left( \frac{\rho^2 \sin^2 \theta + 2\rho \sin \theta - 15}{2} \right) d\rho d\theta$$

At this point, apply integral linearity and solve each integral separately:

1. First integral:

Solve the integral by applying decoupling:

$$\int_0^2 \frac{\rho^4}{2} d\rho \int_0^{2\pi} \sin^3 \theta d\theta = 0 \text{ by periodicity of } \sin^3 \theta.$$

2. Second integral:

Given  $\sin^2 \theta = \frac{1 - \cos 2\theta}{2}$ , solve the integral by applying decoupling:

$$\int_0^2 \rho^3 d\rho \int_0^{2\pi} \frac{1 - \cos 2\theta}{2} d\theta = \left[\frac{\rho^4}{4}\right]_0^2 \left[\frac{\theta}{2} - \frac{\sin 2\theta}{4}\right]_0^{2\pi} = 4\pi$$

3. Third integral:

Solve the integral by applying decoupling:

$$\int_0^2 \frac{15\rho^2}{2} d\rho \int_0^{2\pi} \sin \theta d\theta = 0 \text{ by periodicity of } \sin \theta.$$

Therefore, it is possible to conclude that:

$$\int \int \int_{\Omega} yz \, dx dy dz = 0 + 4\pi - 0 = 4\pi$$