

PMC Lecture 04

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Chapter 1

Parallel computing

1.1 Writing parallel programs

Generally speaking, it is possible to write parallel programs by using some dedicated APIs provided by the C programming language.

	Shared Memory	Distributed Memory
SIMD	CUDA	
MIMD	Pthreads/ OpenMP/ CUDA	MPI

1.1.1 Implementing memory structures

Regarding memory structures, a parallel system can implement a shared memory structure, where cores can access a common memory space, or a distributed memory structure, which provides a private memory for each core and thus coordinates activity by message passing over a dedicated network.

1.1.2 Implementing control units

Regarding control units, a parallel system can opt for a multiple-instruction multiple-data approach, where each core has its own control unit and can work independently of the other cores, or a single-instruction multiple-data approach, where cores share the same control unit and can either execute the same instructions on different data or stay idle.

1.2 Classifying multicore systems

Generally speaking, multicore systems tend to experience performance benefits compared to single-core system.

In particular, it is possible to classify a multicore system in one of the following groups:

- **Concurrent systems:** the system allows multiple tasks to run at any time, although said tasks can still be independent.
- **Parallel systems:** the tasks cooperate closely, typically by means of a shared memory or a communication network, in order to solve a common problem.
- **Distributed systems:** the tasks can cooperate to solve a common problem, but, compared to parallel systems, they work together less frequently.

1.3 The von Neumann architecture

When implementing a (parallel) system, it can come in handy to know its high-level architecture in order to simplify the optimization procedure.

Nowadays, most systems are based on the von Neumann architecture, which contains the following components:

- **Main memory:** this structure collects data and instructions, which are accessed by referring to the address of their location within the memory space.
- **Processor:** this component acts as a control unit as it executes a program with the help of registers, which typically store variables or information about the status of the program, and a program counter, which contains the memory address of the next instruction to execute.
- **Interconnect:** this component, typically implemented as a bus, allows to connect the main memory with the processor, meaning that it will also need to deal with the "von Neumann bottleneck", which represents a limitation concerning the communication capability of the system.

