

Taurus: An Intelligent Data Plane

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ABSTRACT

Emerging trends such as cloud computing, the internet of things, and augmented and virtual reality demand highly responsive, available, secure, and scalable networks to meet users’ quality of experience expectations. Operators currently manage these networks and protocols using a variety of ad-hoc tools and scripts; however, the unpredictable and complex interactions between network conditions and workloads make such manual tuning difficult.

Machine learning (ML) can help approximate and automate these complex interactions that govern today’s hyper-scale datacenter networks [5]. Recent proposals generate ML models for networks to produce recommendations for policies like routing and congestion control [14]. At present, these models run on a logically-centralized control plane for inferring learned policies, hence, causing delays of tens of millisecond when updating network devices [3, 7]. Modern reconfigurable switching devices (*e.g.*, RMT [1]), on the other hand, lack the necessary operations (*e.g.*, loops and multiplication) needed to run these ML models in the data plane itself. Therefore, for policies like anomaly detection where inputs to the ML model may vary over time (*e.g.*, payload size or time-windowed features [13]), most packets—even of a single flow—need to traverse the control plane, thus, significantly increasing load on the controller and inflating flow latencies [9].

In this paper, we present *Taurus*, an intelligent data-plane architecture for ML inference at line rate. Taurus extends the Protocol Independent Switch Architecture (PISA) [1, 6] and adds an ML-capable block with a map-reduce abstraction to its match-action table pipeline (Figure 1a). The map-reduce block receives pre-processed network and packet features from the preceding match-action tables and the parser, and feeds results to the following match-action tables for post processing (*e.g.*, drop, route, or encapsulate a packet based on the prediction). The design of the map-reduce block follows a spatial SIMD architecture that can support a variety of ML models. It is composed of Compute Units (CU) and Memory Units (MU) interspersed in a grid-like fashion (Figure 1b) [11]. Each CU is organized into stages and lanes (Figure 1c); a stage consists of a Functional Unit (FU) and pipeline register (PR), and lanes is the number of such stages running in parallel. A CU can perform either a map, reduction, or both; while an MU is a block of on-chip SRAM memory.

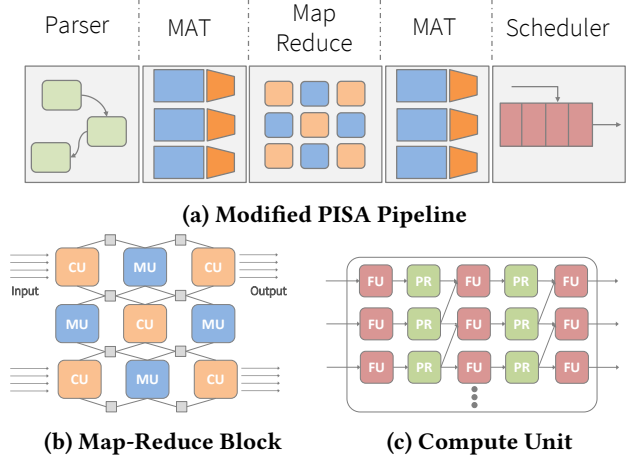


Figure 1: Taurus Data Plane Architecture

		Perf.		Area		Power	
App	Model	GPkt/s	ns	mm ²	+	mW	+
Anomaly	SVM	1.00	68	4.59	6.1	263	1.1
Anomaly	DNN	1.00	362	8.80	11.7	506	2.0
Indigo	LSTM	0.08	380	17.73	23.6	1018	4.1

Table 1: Performance, area, and power overheads for three different application models. Overheads are calculated relative to a 300 mm² chip with 4 reconfigurable pipelines [4], each drawing an estimated 25 W.

Table 1 shows that that cost of adding ML models to a network data plane is small. Taurus can run simple models such as SVM-based anomaly detection [8] with as little as 6.1% area and 1.1% power overhead. The deep learning (DL) network [12] consumes more resources but the area and power utilization is still under 12% and 2%, respectively. Both models meet the high-end switch line rates of a billion packets per second (*i.e.*, 1 GPkt/s). The third application, Indigo [14] is an endpoint application for congestion control that could be deployed on Taurus-based network interface cards (NICs). The Indigo’s DL network is unrolled to meet 40 Gbps line rate for minimum-sized packets (*i.e.*, 0.08 GPkt/s). While the original DL network ran once every 10ms, a Taurus-based NIC runs it in 10ns intervals. With Taurus, we demonstrate that data-plane devices can run ML models and do inference at line rate with several orders of magnitude lower latencies than traditional control-plane approaches [2, 3, 10].

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