

Programming Project #2: Image Quilting

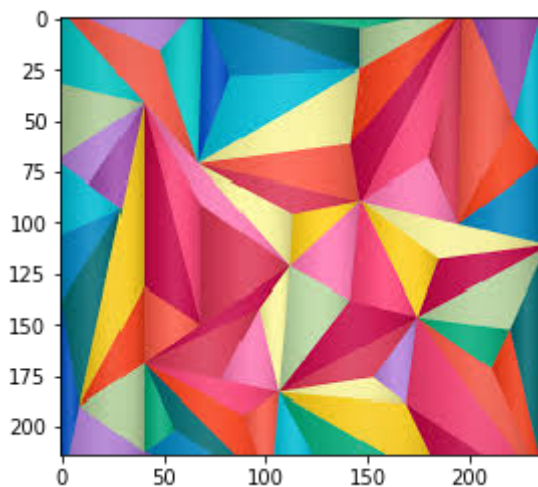
CS445: Computational Photography - Fall 2019

```
In [1]: import random
import cv2
import numpy as np
import matplotlib.pyplot as plt
%matplotlib notebook
import utils
import os
```

```
In [2]: from utils import cut # default cut function for seam finding section
```

Part I: Randomly Sampled Texture (10 pts)

```
In [3]: sample_img_dir = 'image/texture1.jpg' # feel free to change
sample_img = None
if os.path.exists(sample_img_dir):
    sample_img = cv2.imread(sample_img_dir)
    sample_img = sample_img.astype(np.float32)/255.0
    plt.imshow(sample_img[...,-1::-1])
```



```
In [4]: sample_img.shape
```

```
Out[4]: (214, 236, 3)
```

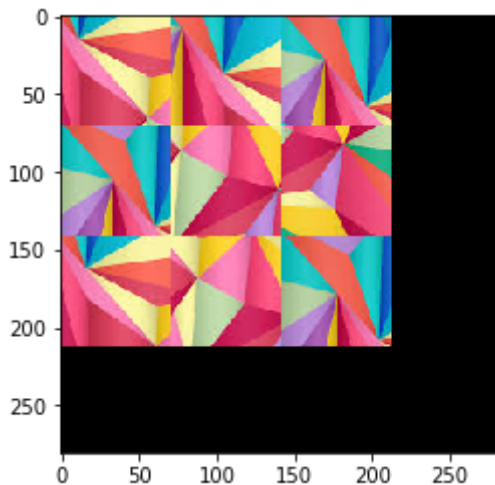
```
In [5]: def quilt_random(sample, out_size, patch_size):
        """
        Randomly samples square patches of size patchsize from sample in order to

        :param sample: numpy.ndarray    The image you read from sample directory
        :param out_size: int             The width of the square output image
        :param patch_size: int           The width of the square sample patch
        :return: numpy.ndarray
        """

        output = np.zeros((out_size,out_size,3), dtype=np.float32)
        number = out_size // patch_size
        # plt.imshow(patch_selected)
        for i in range (number):
            for j in range (number):
                a = random.randint(0,sample.shape[0]-patch_size)
                patch_selected = sample[a:a+patch_size,a:a+patch_size]
                output[i*patch_size:(i+1)*patch_size,j*patch_size:(j+1)*patch_size] = patch_selected
        # ball = img[20:30,30:30]
        # img[30:40,30:30] = ball
        return output
        ssd = (np.sum((mask*template)**2)) - 2 * cv2.filter2D(sample, cv2.CV_64F, mask)
```

```
In [6]: out_size = 281 # feel free to change to debug
        patch_size = 71 # feel free to change to debug
        res = quilt_random(sample_img, out_size, patch_size)
        plt.imshow(res[...,-1:-1])
```

Out[6]: <matplotlib.image.AxesImage at 0x11d41ca20>



Part II: Overlapping Patches (30 pts)

```

In [67]: import math
# Suppose I have a template T, a mask M, and an image I: then,
#  $ssd = ((M*T)**2).sum() - 2 * cv2.filter2D(I, ddepth=-1, kernel = M*T) + cv2.filter2D(I, ddepth=-1, kernel = M*T)$ 
def ssd_patch(sample, patch_size, template, mask):
    """
    ssd_patch performs template matching with the overlapping region, compute
    each patch, based on the sum of squared differences (SSD) of the overlap
    and sampled patch.
    """
    start_index = (patch_size-1) // 2
    end_index = (sample.shape[0]-1) - start_index # end index is 191-9=182,
    # print("template")
    # plt.imshow(template)
    # plt.show()
    # print("mask")
    # plt.imshow(mask)
    # plt.show()
    # print("sample")
    # plt.imshow(sample)
    # plt.show()
    ssd = ((mask*template)**2).sum() - 2 * cv2.filter2D(sample, ddepth=-1, kernel=template)
    # plt.imshow(ssd.mean(2)) !!!!!!!!!!!!!
    # plt.show()
    sample_size = sample.shape[0]
    cost_image = np.zeros((sample_size,sample_size), dtype=np.float32)
    for i in range(start_index,end_index+1):
        for j in range(start_index,end_index+1):
            cost_image[i,j] = ssd[i,j].sum()
    # print("cost image")
    # print(cost_image)
    # plt.imshow(cost_image)
    # plt.show()
    return cost_image

```

```

In [77]: def choose_sample(sample, patch_size, cost_image, tol):
# for sample.shape = (192,192,3) and patch_size = 19 and overlap = 5
start_index = (patch_size-1) // 2 # start index is (19-1)/2=9
end_index = (sample.shape[0]-1) - start_index # end index is 191-9=182,
minc = float("inf")
# first to find the min cost
for i in range (start_index,end_index+1):
    for j in range (start_index,end_index+1):
        if cost_image[i,j] < minc:
            minc = cost_image[i,j]
compare_cost = minc*(1+tol)
for i in range (start_index,end_index+1):
    for j in range (start_index,end_index+1):
        if cost_image[i,j] < compare_cost:
            return i,j

```

```

In [78]: def quilt_simple(sample, out_size, patch_size, overlap, tol):
        """
        Randomly samples square patches of size patchsize from sample in order to
        Feel free to add function parameters
        :param sample: numpy.ndarray
        :param out_size: int
        :param patch_size: int
        :param overlap: int
        :param tol: int
        :return: numpy.ndarray
        """

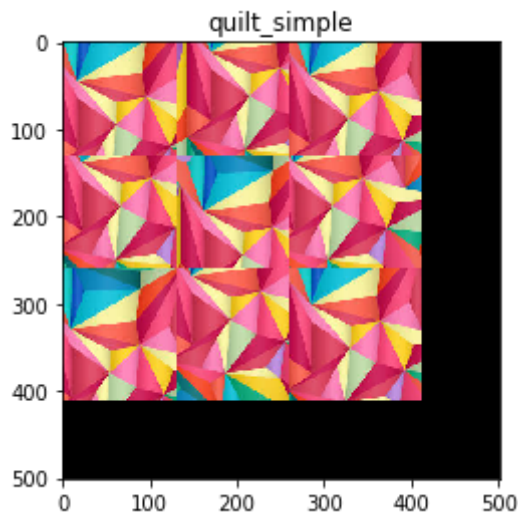
        output = np.zeros((out_size,out_size,3), dtype=np.float32)
        patch_size_remaining = patch_size - overlap
        number = (out_size - patch_size) // patch_size_remaining + 1 # the number of patches
        # Start by sampling a random patch for the upper-left corner.
        k = (patch_size-1) // 2
        a = random.randint(0,sample.shape[0]-patch_size)
        b = random.randint(0,sample.shape[0]-patch_size)
        #
        #     a = 0
        #     b = 0
        output[0:patch_size,0:patch_size] = sample[a:a+patch_size,b:b+patch_size]
        print(a,b)
        # the second patch along the top row will overlap by patch_size
        # pixels in the vertical direction and overlap pixels in the horizontal
        for h_left_index in range (0,number):
            for w_left_index in range (0,number):
                # The mask has the same size as the patch template and
                # has values of 1 in the overlapping region and values of 0 elsewhere
                mask = np.zeros((patch_size,patch_size,3), dtype=np.float32)
                # the coordinate of the left_top point is (x_left_top*patch_size, y_left_top*patch_size)
                if (w_left_index == 0) and (h_left_index == 0):
                    mask[:,0:overlap] = 1.0
                    mask[0:overlap,:] = 1.0
                    continue
                elif (h_left_index == 0):
                    mask[:,0:overlap] = 1.0
                elif (w_left_index == 0):
                    mask[0:overlap,:] = 1.0
                else:
                    mask[:,0:overlap] = 1.0
                    mask[0:overlap,:] = 1.0
                h_left = h_left_index * patch_size_remaining
                w_left = w_left_index * patch_size_remaining
                # The template is the patch in the current output image that is used to calculate the cost
                # (many pixel values will be 0 because they are not filled in yet)
                template = output[h_left:h_left+patch_size,w_left:w_left+patch_size]
                #
                plt.imshow(mask)
                #
                plt.show()
                #
                print(mask)
                cost_image = ssd_patch(sample, patch_size, template, mask)
                i ,j = choose_sample(sample, patch_size, cost_image, tol)
                output[h_left:h_left+patch_size,w_left:w_left+patch_size] = sample[i:i+patch_size,j:j+patch_size]
                # the same as the patch_size
        return output

```

```
In [79]: res = quilt_simple(sample_img, 501, 151, 21, 0.0000001) #feel free to change
plt.imshow(res[...,-1::-1]) # overlap 0.005 is not enough while 0.0005 is en
plt.title('quilt_simple')
```

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```
Out[79]: Text(0.5, 1.0, 'quilt_simple')
```



```
In [80]: # plt.figure()
# plt.imshow(iml_lowpass, cmap='gray')
# plt.axis('off')
# plt.savefig('./image/dog_filter_low.jpg')
```

Part III: Seam Finding (20 pts)

```
In [12]: # optional or use cut(err_patch) directly
def customized_cut(bndcost):
    pass
```

```
In [13]: def calculate_err(overlap_origin, overlap_sample):
    h = overlap_origin.shape[0]
    w = overlap_origin.shape[1]
    overlap_diff = overlap_origin - overlap_sample
    overlap_diff = np.square(overlap_diff)
    err_patch = np.zeros((h,w), dtype=np.float32)
    for i in range(h):
        for j in range(w):
            err_patch[i,j] = overlap_diff[i][j].sum()
    return err_patch
```

```

In [14]: def quilt_cut(sample, out_size, patch_size, overlap, tol):
    """
    Samples square patches of size patchsize from sample using seam finding
    Feel free to add function parameters
    :param sample: numpy.ndarray
    :param out_size: int
    :param patch_size: int
    :param overlap: int
    :param tol: int
    :return: numpy.ndarray
    """

    output = np.zeros((out_size,out_size,3), dtype=np.float32)
    patch_size_remaining = patch_size - overlap
    number = (out_size - patch_size) // patch_size_remaining + 1 # the number
    # Start by sampling a random patch for the upper-left corner.
    k = (patch_size-1) // 2
    a = random.randint(0,sample.shape[0]-patch_size)
    b = random.randint(0,sample.shape[0]-patch_size)
    #
    #     a = 0
    #     b = 0
    output[0:patch_size,0:patch_size] = sample[a:a+patch_size,b:b+patch_size]
    print(a,b)
    # the second patch along the top row will overlap by patch_size
    # pixels in the vertical direction and overlap pixels in the horizontal
    for h_left_index in range (0,number):
        for w_left_index in range (0,number):
            # The mask has the same size as the patch template and
            # has values of 1 in the overlapping region and values of 0 else
            mask = np.zeros((patch_size,patch_size,3), dtype=np.float32)
            # the coordinate of the left_top point is (x_left_top*patch_size
            if (w_left_index == 0) and (h_left_index == 0):
                mask[:,0:overlap] = 1.0
                mask[0:overlap,:] = 1.0
                continue
            elif (h_left_index == 0):
                mask[:,0:overlap] = 1.0
            elif (w_left_index == 0):
                mask[0:overlap,:] = 1.0
            else:
                mask[:,0:overlap] = 1.0
                mask[0:overlap,:] = 1.0
            h_left = h_left_index * patch_size_remaining
            w_left = w_left_index * patch_size_remaining
            # The template is the patch in the current output image that is
            # (many pixel values will be 0 because they are not filled in yet)
            template = output[h_left:h_left+patch_size,w_left:w_left+patch_size]
            cost_image = ssd_patch(sample, patch_size, template, mask)
            i ,j = choose_sample(sample, patch_size, cost_image, tol)
            # output[h_left:h_left+patch_size,w_left:w_left+patch_size] = sample[i:i+patch_size,j:j+patch_size]
            # the same as the patch_size
            # added code for quilt_cost -----
            # the situation of left overlaps
            if (h_left_index == 0):
                overlap_origin = output[h_left:h_left+patch_size,w_left:w_left+patch_size]
                overlap_sample = sample[i-k:i-k+patch_size, j-k:j-k+overlap]

```

```

err_patch = calculate_err(overlap_origin, overlap_sample)
mask = cut(err_patch.T)
mask = mask.T
h,w = mask.shape
mask_handle = np.zeros((h,w,3), dtype = np.float32)
# convert int to float, can't find easier way
for a in range(h):
    for b in range(w):
        if mask[a,b] == 1:
            for c in range(3):
                mask_handle[a,b,c] = 1.0
        else:
            for c in range(3):
                mask_handle[a,b,c] = 0.0
overlap_mix = overlap_origin*(1-mask_handle) + overlap_sample
output[h_left:h_left+patch_size,w_left:w_left+patch_size] = overlap_mix
output[h_left:h_left+patch_size,w_left:w_left+overlap] = overlap_sample
# the situation of top overlaps
elif (w_left_index == 0):
    overlap_origin = output[h_left:h_left+overlap,w_left:w_left+patch_size]
    plt.imshow(overlap_origin[...,-1:-1])
    plt.show()
    overlap_sample = sample[i-k:i-k+overlap, j-k:j-k+patch_size]
    plt.imshow(overlap_sample[...,-1:-1])
    plt.show()
    err_patch = calculate_err(overlap_origin, overlap_sample)
    print("cost")
    plt.imshow(err_patch[...,-1:-1])
    plt.show()

mask = cut(err_patch)
h,w = mask.shape
mask_handle = np.zeros((h,w,3), dtype = np.float32)
# convert int to float, cannot find easier way
for a in range(h):
    for b in range(w):
        if mask[a,b] == 1:
            for c in range(3):
                mask_handle[a,b,c] = 1.0
        else:
            for c in range(3):
                mask_handle[a,b,c] = 0.0
    templ = overlap_origin*(1-mask_handle)
    plt.imshow(templ[...,-1:-1])
    plt.show()
    temp2 = overlap_sample*mask_handle
    plt.imshow(temp2[...,-1:-1])
    plt.show()
    overlap_mix = overlap_origin*(1-mask_handle) + overlap_sample
    plt.imshow(overlap_mix[...,-1:-1])
    plt.show()
    output[h_left:h_left+patch_size,w_left:w_left+patch_size] = overlap_mix
    output[h_left:h_left+overlap,w_left:w_left+patch_size] = overlap_sample
# if a patch has top and left overlaps, you will need to compute the overlap
# and the mask can be defined as the intersection of the masks
else:

```

```

# left overlaps part
overlap_origin = output[h_left:h_left+patch_size,w_left:w_left+patch_size]
overlap_sample = sample[i-k:i-k+patch_size, j-k:j-k+patch_size]

err_patch = calculate_err(overlap_origin,overlap_sample)
mask3 = cut(err_patch.T)
mask3 = mask3.T

h,w = mask3.shape
mask3_extend = np.ones((patch_size,patch_size), dtype = "int")
for a in range(h):
    for b in range(w):
        if mask3[a,b] == 1:
            mask3_extend[a,b] = 1
        else:
            mask3_extend[a,b] = 0

# top overlaps part
overlap_origin = output[h_left:h_left+overlap,w_left:w_left+overlap]
overlap_sample = sample[i-k:i-k+overlap, j-k:j-k+patch_size]
err_patch = calculate_err(overlap_origin,overlap_sample)
mask4 = cut(err_patch)

h,w = mask4.shape
mask4_extend = np.ones((patch_size,patch_size), dtype = "int")
# convert int to float, cannot find easier way
for a in range(h):
    for b in range(w):
        if mask4[a,b] == 1:
            mask4_extend[a,b] = 1
        else:
            mask4_extend[a,b] = 0
mask_combined = mask3_extend & mask4_extend
# convert int to float, cannot find easier way, and convert
mask_combined_handle = np.zeros((patch_size,patch_size,3), dtype = "float")
for a in range(patch_size):
    for b in range(patch_size):
        if mask_combined[a,b] == 1:
            for c in range(3):
                mask_combined_handle[a,b,c] = 1.0
        else:
            for c in range(3):
                mask_combined_handle[a,b,c] = 0.0
# plt.imshow(mask_combined_handle)
# plt.show()
overlap_mix_extend = (1.0-mask_combined_handle) * template \
+ mask_combined_handle * sample[i-k:i-k+patch_size, j-k:j-k+patch_size]
output[h_left:h_left+patch_size,w_left:w_left+patch_size] = overlap_mix_extend

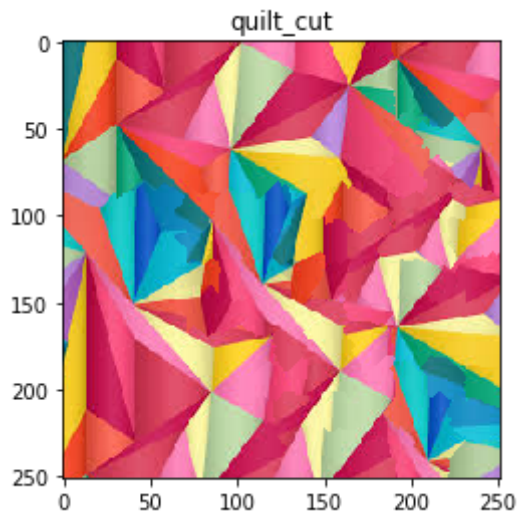
return output

```



```
In [22]: res = quilt_cut(sample_img, 251, 31, 11, 0.00005)
plt.imshow(res[...,-1::-1]) # overlap 0.005 is not enough while 0.0005 is en
plt.title('quilt_cut')
plt.show()
```

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part IV: Texture Transfer (30 pts)

```

In [128]: import math
# Suppose I have a template T, a mask M, and an image I: then,
# ssd = ((M*T)**2).sum() - 2 * cv2.filter2D(I, ddepth=-1, kernel = M*T) + cv2.filter2D(I, ddepth=-1, kernel = M*T)
def ssd_overlap(sample, patch_size, template, mask):
    """
    ssd_patch performs template matching with the overlapping region, compute
    each patch, based on the sum of squared differences (SSD) of the overlap
    and sampled patch.
    """
    sample_size = min(sample.shape[0], sample.shape[1])
    start_index = (patch_size-1) // 2
    end_index = (sample_size-1) - start_index # end index is 191-9=182, take
    ssd = ((mask*template)**2).sum() - 2 * cv2.filter2D(sample, ddepth=-1, kernel = mask*template)
    # plt.imshow(ssd.mean(2)) !!!!!!!!!!!!!
    # plt.show()
    cost_image = np.zeros((sample_size, sample_size), dtype=np.float32)
    for i in range(start_index, end_index+1):
        for j in range(start_index, end_index+1):
            cost_image[i, j] = ssd[i, j].sum()
    # print("cost image")
    # print(cost_image)
    # plt.imshow(cost_image)
    # plt.show()
    return cost_image

```

```

In [96]: def ssd_transfer(sample, patch_size, target_patch):
    sample_size = min(sample.shape[0], sample.shape[1])
    k = (patch_size-1) // 2
    start_index = (patch_size-1) // 2
    end_index = (sample_size-1) - start_index # end index is 191-9=182, take
    cost_image = np.zeros((sample_size, sample_size), dtype=np.float32)
    for i in range(start_index, end_index+1):
        for j in range(start_index, end_index+1):
            cost_image[i, j] = 0
            for m in range (-k, k+1):
                for n in range (-k, k+1):
                    cost_image[i, j] += abs(sample[i+m, j+n]-target_patch[k+m, k+n])
    return cost_image

```

```

In [105]: def choose_sample(sample, patch_size, cost_image, tol):
    sample_size = min(sample.shape[0], sample.shape[1])
    # for sample.shape = (192,192,3) and patch_size = 19 and overlap = 5
    start_index = (patch_size-1) // 2 # start index is (19-1)/2=9
    end_index = (sample_size-1) - start_index # end index is 191-9=182, take
    minc = float("inf")
    # first to find the min cost
    for i in range (start_index, end_index+1):
        for j in range (start_index, end_index+1):
            if cost_image[i, j] < minc:
                minc = cost_image[i, j]
    compare_cost = minc*(1+tol)
    for i in range (start_index, end_index+1):
        for j in range (start_index, end_index+1):
            if cost_image[i, j] < compare_cost:
                return i, j

```

```

In [121]: def texture_transfer(sample, target, patch_size, overlap, tol):
    """
    Samples square patches of size patchsize from sample using seam finding
    Feel free to add function parameters
    :param sample: numpy.ndarray
    :param out_size: int
    :param patch_size: int
    :param overlap: int
    :param tol: int
    :return: numpy.ndarray
    """

    target_size = target.shape
    out_size1 = target.shape[0]
    out_size2 = target.shape[1]
    output = np.zeros((out_size1,out_size2), dtype=np.float32)
    patch_size_remaining = patch_size - overlap
    number1 = (out_size1 - patch_size) // patch_size_remaining + 1 # the number of patches in the vertical direction
    number2 = (out_size2 - patch_size) // patch_size_remaining + 1 # the number of patches in the horizontal direction
    # Start by sampling a random patch for the upper-left corner.
    k = (patch_size-1) // 2
    target_patch_ini = target[0:0+patch_size,0:0+patch_size]
    cost_image_ini = ssd_transfer(sample, patch_size, target_patch_ini)
    a, b = choose_sample(sample, patch_size, cost_image_ini, tol)

    output[0:patch_size,0:patch_size] = sample[a:a+patch_size,b:b+patch_size]
    print(a,b)
    # the second patch along the top row will overlap by patch_size
    # pixels in the vertical direction and overlap pixels in the horizontal
    for h_left_index in range (0,number1):
        for w_left_index in range (0,number2):
            # The mask has the same size as the patch template and
            # has values of 1 in the overlapping region and values of 0 elsewhere
            mask = np.zeros((patch_size,patch_size), dtype=np.float32)
            # the coordinate of the left_top point is (x_left_top*patch_size, y_left_top*patch_size)
            if (w_left_index == 0) and (h_left_index == 0):
                mask[:,0:overlap] = 1.0
                mask[0:overlap,:] = 1.0
                continue
            elif (h_left_index == 0):
                mask[:,0:overlap] = 1.0
            elif (w_left_index == 0):
                mask[0:overlap,:] = 1.0
            else:
                mask[:,0:overlap] = 1.0
                mask[0:overlap,:] = 1.0
            h_left = h_left_index * patch_size_remaining
            w_left = w_left_index * patch_size_remaining
            # The template is the patch in the current output image that is
            # (many pixel values will be 0 because they are not filled in yet)
            template = output[h_left:h_left+patch_size,w_left:w_left+patch_size]
            target_patch = target[h_left:h_left+patch_size,w_left:w_left+patch_size]
            cost_image1 = ssd_overlap(sample, patch_size, template, mask)
            cost_image2 = ssd_transfer(sample, patch_size, target_patch)
            cost_image = cost_image1*0.5 + cost_image2*0.5
            i, j = choose_sample(sample, patch_size, cost_image, tol)
            # output[h_left:h_left+patch_size,w_left:w_left+patch_size] = sample[i:i+patch_size,j:j+patch_size]

```

```

# the same as the patch_size
# added code for quilt_cost -----
# the situation of left overlaps
if (h_left_index == 0):
    overlap_origin = output[h_left:h_left+patch_size,w_left:w_left+patch_size]
    overlap_sample = sample[i-k:i-k+patch_size, j-k:j-k+patch_size]

    err_patch = calculate_err(overlap_origin,overlap_sample)
    mask = cut(err_patch.T)
    mask = mask.T
    h,w = mask.shape
    mask_handle = np.zeros((h,w), dtype = np.float32)
    # convert int to float, can't find easier way
    for a in range(h):
        for b in range(w):
            if mask[a,b] == 1:
                mask_handle[a,b] = 1.0
            else:
                mask_handle[a,b] = 1.0
    overlap_mix = overlap_origin*(1-mask_handle) + overlap_sample*mask_handle
    output[h_left:h_left+patch_size,w_left:w_left+patch_size] = overlap_mix
    output[h_left:h_left+patch_size,w_left:w_left+overlap] = overlap_sample
# the situation of top overlaps
elif (w_left_index == 0):
    overlap_origin = output[h_left:h_left+overlap,w_left:w_left+patch_size]
    plt.imshow(overlap_origin[...,-1:-1])
    plt.show()
    overlap_sample = sample[i-k:i-k+overlap, j-k:j-k+patch_size]
    plt.imshow(overlap_sample[...,-1:-1])
    plt.show()
    err_patch = calculate_err(overlap_origin,overlap_sample)
    print("cost")
    plt.imshow(err_patch[...,-1:-1])
    plt.show()

    mask = cut(err_patch)
    h,w = mask.shape
    mask_handle = np.zeros((h,w), dtype = np.float32)
    # convert int to float, cannot find easier way
    for a in range(h):
        for b in range(w):
            if mask[a,b] == 1:
                mask_handle[a,b] = 1.0
            else:
                mask_handle[a,b] = 1.0
    temp1 = overlap_origin*(1-mask_handle)
    plt.imshow(temp1[...,-1:-1])
    plt.show()
    temp2 = overlap_sample*mask_handle
    plt.imshow(temp2[...,-1:-1])
    plt.show()
    overlap_mix = overlap_origin*(1-mask_handle) + overlap_sample*mask_handle
    plt.imshow(overlap_mix[...,-1:-1])
    plt.show()
    output[h_left:h_left+patch_size,w_left:w_left+patch_size] = overlap_mix
    output[h_left:h_left+overlap,w_left:w_left+patch_size] = overlap_sample
# if a patch has top and left overlaps, you will need to compute

```

```

# and the mask can be defined as the intersection of the masks
else:
    # left overlaps part
    overlap_origin = output[h_left:h_left+patch_size,w_left:w_left+patch_size]
    overlap_sample = sample[i-k:i-k+patch_size, j-k:j-k+patch_size]

    err_patch = calculate_err(overlap_origin,overlap_sample)
    mask3 = cut(err_patch.T)
    mask3 = mask3.T

    h,w = mask3.shape
    mask3_extend = np.ones((patch_size,patch_size), dtype = "int")
    for a in range(h):
        for b in range(w):
            if mask3[a,b] == 1:
                mask3_extend[a,b] = 1
            else:
                mask3_extend[a,b] = 0

    # top overlaps part
    overlap_origin = output[h_left:h_left+overlap,w_left:w_left+overlap]
    overlap_sample = sample[i-k:i-k+overlap, j-k:j-k+patch_size]
    err_patch = calculate_err(overlap_origin,overlap_sample)
    mask4 = cut(err_patch)

    h,w = mask4.shape
    mask4_extend = np.ones((patch_size,patch_size), dtype = "int")
    # convert int to float, cannot find easier way
    for a in range(h):
        for b in range(w):
            if mask4[a,b] == 1:
                mask4_extend[a,b] = 1
            else:
                mask4_extend[a,b] = 0
    mask_combined = mask3_extend & mask4_extend
    # convert int to float, cannot find easier way, and convert
    mask_combined_handle = np.zeros((patch_size,patch_size), dtype = "float")
    for a in range(patch_size):
        for b in range(patch_size):
            if mask_combined[a,b] == 1:
                mask_combined_handle[a,b] = 1.0
            else:
                mask_combined_handle[a,b] = 1.0
    # plt.imshow(mask_combined_handle)
    # plt.show()
    overlap_mix_extend = (1.0-mask_combined_handle) * template \
    + mask_combined_handle * sample[i-k:i-k+patch_size, j-k:j-k+patch_size]
    output[h_left:h_left+patch_size,w_left:w_left+patch_size] = overlap_mix_extend

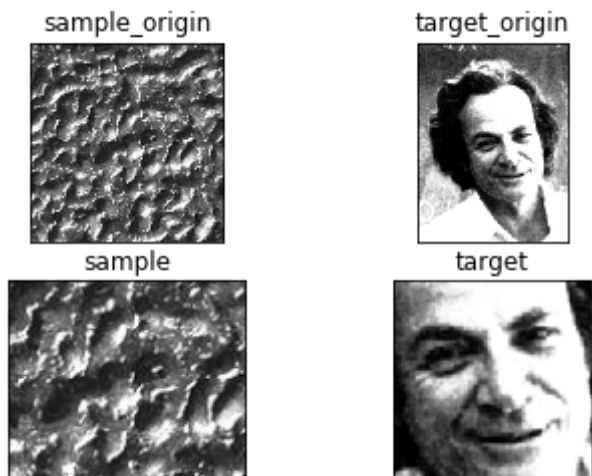
return output

```

```
In [153]: def read_image(image_path):
            intensity_image = cv2.imread(image_path, cv2.IMREAD_GRAYSCALE)
            return intensity_image.astype(np.float32) / 255
sample_file = "./samples/sample1.jpg"
target_file = "./samples/feynman.tiff"
sample = read_image(sample_file)
target = read_image(target_file)
fig, axes = plt.subplots(2, 2)
axes[0,0].imshow(sample,cmap='gray')
axes[0,0].set_title('sample_origin'), axes[0,0].set_xticks([]), axes[0,0].set_yticks([])
axes[0,1].imshow(target,cmap='gray')
axes[0,1].set_title('target_origin'), axes[0,1].set_xticks([]), axes[0,1].set_yticks([])
print(sample.shape)
print(target.shape)
sample = sample[sample.shape[0]//2-50:sample.shape[0]//2+50, sample.shape[1]//2-50:sample.shape[1]//2+50]
target = target[target.shape[0]//2-50:target.shape[0]//2+90, target.shape[1]//2-50:target.shape[1]//2+90]
print(sample.shape)
print(target.shape)

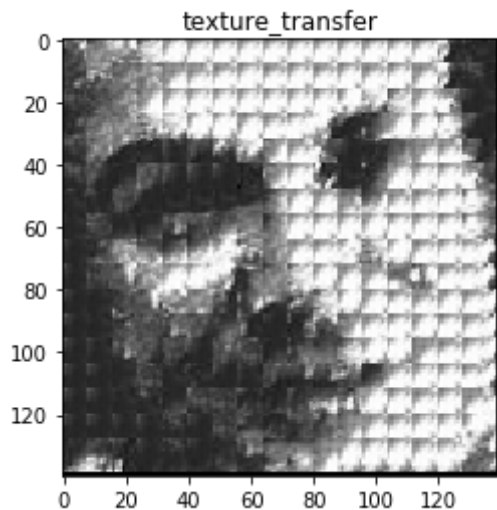
axes[1,0].imshow(sample,cmap='gray')
axes[1,0].set_title('sample'), axes[1,0].set_xticks([]), axes[1,0].set_yticks([])
axes[1,1].imshow(target,cmap='gray')
axes[1,1].set_title('target'), axes[1,1].set_xticks([]), axes[1,1].set_yticks([])
```

(200, 196)
(355, 271)
(100, 120)
(140, 140)



```
In [154]: res = texture_transfer(sample, target, 11, 3, 0.0005)
plt.imshow(res, cmap='gray')
plt.title('texture_transfer')
plt.show()
```

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Bells & Whistles

(10 pts) Create and use your own version of `cut.m`. To get these points, you should create your own implementation without basing it directly on the provided function (you're on the honor code for this one).

You can simply copy your customized `_cut(bndcost)` into the box below so that it is easier for us to grade

In []:

(15 pts) Implement the iterative texture transfer method described in the paper. Compare to the non-iterative method for two examples.

In []:

(up to 20 pts) Use a combination of texture transfer and blending to create a face-in-toast image like the one on top. To get full points, you must use some type of blending, such as feathering or Laplacian pyramid blending.

In []:

(up to 40 pts) Extend your method to fill holes of arbitrary shape for image completion. In this case, patches are drawn from other parts of the target image. For the full 40 pts, you should implement a smart priority function (e.g., similar to Criminisi et al.).

In []:

In []:

In []:

In []:

In []: