view frames Result Recorded at time: 1750385653.171 robotiq_85_left_knuckle_link world robotiq_85_right_knuckle_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: $1\overline{0}000.\overline{00}0$ Hz Most recent transform: 0.000 (1750385653.171 sec old) Most recent transform: 0.000 (1750385653.171 sec old) Most recent transform: 0.000 (1750385653.171 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec robotiq_85_left_finger_link base link robotiq_85_right_finger_link Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Broadcaster: /robot_state_publisher Average rate: 10.204 Hz
\Most recent transform: 1750385653.126 (0.045 sec old) Most recent transform: 0.000 (1750385653.171 sec old) Buffer length: 0.000 sec Buffer length: 4.900 sec shoulder link base Broadcaster: /robot state publisher Average rate: 10.204 Hz Most recent transform: 1750385653.126 (0.045 sec old) Buffer length: 4.900 sec upper_arm_link Broadcaster: /robot_state_publisher Average rate: 10.204 Hz
Most recent transform: 1750385653.126 (0.045 sec old) Buffer length: 4.900 sec forearm_link Broadcaster: /robot_state_publisher Average rate: $10.20\overline{4}$ Hz Most recent transform: 1750385653.126 (0.045 sec old) Buffer length: 4.900 sec wrist_1_link Broadcaster: /robot_state_publisher Average rate: $10.20\overline{4}$ Hz Most recent transform: 1750385653.126 (0.045 sec old) Buffer length: 4.900 sec wrist_2_link Broadcaster: /robot_state_publisher Average rate: 10.204 Hz
Most recent transform: 1750385653.126 (0.045 sec old) Buffer length: 4.900 sec wrist_3_link Broadcaster: /robot state publisher Broadcaster: /robot_state_publisher Average rate: $1\overline{0}000.\overline{0}0$ Hz Average rate: $1\overline{0}000.\overline{00}0$ Hz Most recent transform: 0.000 (1750385653.171 sec old) Most recent transform: 0.000 (1750385653.171 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec tool0 ee_link Broadcaster: /robot state publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Most recent transform: 0.000 (1750385653.171 sec old) Buffer length: 0.000 sec $robotiq_coupler$ Broadcaster: /robot state publisher Average rate: $1\overline{0}000.\overline{0}0$ Hz Most recent transform: 0.000 (1750385653.171 sec old) Buffer length: 0.000 sec robotiq_85_base_link