

**TITLE**

by

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## SUMMARY

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### TITLE

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## **LIST OF ABBREVIATIONS**

FDD	Fault Detection and Diagnosis
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# CHAPTER 1 INTRODUCTION

## 1.1 PROBLEM STATEMENT

### 1.1.1 Context of the problem

The modern industrial complex has a large number of automated processes. The automation of processes enables sustainable and predictable production. Control loops are one of the key building blocks that make automation possible.

Each sub section of a process consists of multiple control loops that together form a complex system. Continuous maintenance and fast response to disturbances is required to ensure that the overall goals of the automated process is sustained.

However, the complexities in analyzing the various number of control loops that form part of industrial control systems causes a time delay between the onset of a fault and the detection of that fault. Furthermore, once a fault is detected it can be very difficult to discern the source of a disturbance without time consuming interventions that add risk to process stability.[1]

A data driven approach is mostly applied in solving these kind of problems and a lot of focus is given in developing methods and tools that support this approach. In industry, the exact process model is rarely known or available when performing fault finding tasks using time series data.[2] Tools that only use routine operating data like the method developed by [3] provide an exciting new perspective on how to solve these complex problem using data driven methods. An approach that provides the user with an intuitive and interactive tool to analyze process behavior can add value to the fault detection and diagnosis process. By highlighting fundamental interaction paths using operating data it can translate into quicker response times to address process instabilities.

A key element of any tool that assists in process fault finding is the visualization and interaction with the data. Every decision made in a industrial process involves reacting to process data. In modern industrial processes most short term decisions are made using the process data as visualized on the process control system. This same data is used to monitor and detect deviations in the process. When deviations are detected a fault finding process needs to be followed to determine what caused the deviation and how to correct it.

The fault finding process often requires a lot of data analysis using a certain frame of reference to determine what is normal behavior. With any process there needs to be some kind of visual interaction with the data in order for the human brain to process it. This visual interface can range from the simplest form of simply looking at how a point value on the control system changes over a period to constructing graphs of complex time series transformations of multiple data sets.

### **1.1.2 Research gap**

The intent of this study is to explore approaches to the fault detection and diagnosis process with specific focus on the human interaction with data to analyze and solve a problem. The core element of this process is the visual context in which the data is viewed and transformed in order to generate understanding and knowledge.

In the modern industrial era a lot of fault detection problems are solved using computer based tools that are very efficient at processing large amounts of data and performing complex data transformations in a relatively short period of time.

A time series fault detection and diagnosis problem is often solved by creating a specialized tool that would transform data into knowledge which would most likely have a visual representation as the end result. The problem and solution are then presented as the end result of the study. If the audience then want to re-produce the results or test the method on a different data set they have to reproduce the tool that was used to generate the knowledge as well. This is a time consuming process and a barrier to further development of the proposed method.

A researcher might also make the specialized tool available to the audience but if the tool was developed on a platform that uses proprietary code then it also presents a barrier to further development. There are a lot of tools available for visualization of data but very few of them are built on open source

platforms. Recent development in the computer science industry has made available a large number of open source tools and platforms, but there are very few examples in literature of them being applied in the visual analytics realm.

New developments in the fault detection and diagnosis problem have presented many new views of how to identify that a fault has occurred or how to identify the root cause of a fault. These new methods display the results in static graphs that highlight the most important elements of the transformed data set. One key element of the user experience that has not been developed yet is the ability to interact with the data. Interaction allows for faster knowledge transfer and easier understanding of how the parameters used in the transformation effect the final result. If the audience could be able to interact with the presented data at every step of the transformation then a much faster and deeper understanding could be achieved of the communicated method.

## **1.2 RESEARCH OBJECTIVE AND QUESTIONS**

The focus of this dissertation will be to explore the ways in which visual analytic systems can be used to aid in the fault finding process.

FDD will be discussed in general and with regards to new methods that have been developed that attempt to solve the problem. Questions that will be explored in this study will include:

- What methods have been developed for fault detection and diagnosis?
- How does visual analytics play a role in the fault detection and diagnosis process?
- What tools are currently available for visualization?
- How can the FDD process be facilitated by using open source software?

## **1.3 HYPOTHESIS AND APPROACH**

It is assumed that there is a logical thought process that is applied when doing FDD. This logical thought process combined with proven analytical methods can provide accurate and actionable results to the FDD process. Visual analytics plays a key role in this process and the different ways that data is collected, processed and transformed into knowledge about the existence of a fault and where the fault is located.

The approach taken in this study will be to outline how the FFD process can be completed using time series data and graphical knowledge of the plant topology to formulate a method for detecting and



diagnosis process faults. Visual analytics will be used to facilitate this process and the interaction with data in a way that guides the user in the process of completing the FDD process.

#### **1.4 RESEARCH GOALS**

The goal of the study will be to highlight key aspects of the FDD process and the visual analytics systems available to use in this process. Different ways in which to develop these visual systems will be explored with a strong focus on developing computer aided tools that will be easily usable by a large audience that can also contribute the tool.

#### **1.5 RESEARCH CONTRIBUTION**

One particular fault finding technique that involves complex transformations of data to determine the root cause of disturbances will be discussed and demonstrated. A visual analytic system will be developed based on best practices to attempt improving the user experience when analyzing a complex control problem.

#### **1.6 OVERVIEW OF STUDY**

Chapter 2 will provide an overview of work completed in utilizing network theory and graphical methods to identify process faults. This chapter will also explore how visualization is used in the fault finding process and how visual methods support and facilitate the FDD process.

Chapter 3 will contain the results of work done to create a open source visualization tool that incorporates the insight obtained from Chapter 2.

Chapter 4 will demonstrate the results from applying this tool the results obtained from applying the analytical methods described in Chapter 2. This chapter will also discuss these results and how they improve the FDD process.

Chapter 5 will summarize the literature review and contribution made.

## **CHAPTER 2    LITERATURE STUDY**

### **2.1    CHAPTER OBJECTIVES**

This chapter explores literature in the field of fault detection and diagnosis of process control in industrial processes. It then elaborates on visualization techniques and how they could be used to aid in the fault detection and diagnosis process.

### **2.2    FAULT DETECTION AND DIAGNOSIS**

The automated control of industrial processes has developed significantly in recent decades. Advances in computing power had allowed the distributed control system to become common place in most industrial processes. This together with advanced control techniques like model predictive control has allowed for automated real time optimization of the key economic variables. Despite these advances one of the most important tasks in managing a process is still being done manually by operational teams; responding to abnormal events. It can be described as the timely identification, diagnosis of the root cause and the appropriate supervisory action to address an abnormality and bring the process back to stability. [4] defined this task as abnormal event management (AEM) which is critical to the stability of a process. [4] refers to statistics that indicate that 70 % of industrial accidents are caused by human errors. This indicates that methods to improve this task can significantly improve the economic, safety and environmental impact of these industries.

A fault can be described as a deviation of an observable variable or calculated parameter from its acceptable operating range [4]. This can be a process deviation like low steam outlet temperatures from a boiler. A possible cause for this could be a failure on a attemperator valve which can be referred to as the basic event or root cause. The diagnosis task can be seen as a classification problem wherein a root cause or fault must be placed in a certain group of faults which will have a pe-determined method to solve them.

Disturbances in single control loops are fairly straight forward to solve but disturbances that propagate through a complex system on a plant wide scale are much harder to present a much bigger challenge. One of the goals of process control is to shift process variability to places like buffer tanks and plant utilities. In modern industrial processes these options have become limited as inventory is usually kept to a minimum and the use of recycle streams for heat integration has introduced extra sources complex interaction [1].

When considering which type of disturbances to analyze, the time frame of the disturbance can be used to distinguish between different types of disturbances. [1] classified the types of disturbances in a plant wide setting into three main categories with regards to timescales:

1. slowly-developing, i.e. fouling of a heat exchanger
2. persistent and dynamic
3. abrupt, i.e. a compressor trip

The second item, persistent and dynamic disturbances that propagate through an entire system on a continuous basis is of interest for this study.

### **2.2.1 FDD AS ANALYTICAL REDUNDANCY**

Fault diagnosis is normally used to improve the reliability of a system [5]. There are two methods that can be used to accomplish fault diagnosis: the first is hardware redundancy and the second is software or analytical redundancy. Hardware redundancy requires the use of identical components that use the same input signals to generate duplicate output signals. If the output signal then differs between the two redundant controllers it is easy to detect a fault and take action, examples of this method is limit checking and majority voting. Hardware redundancy can be very expensive and is often times not present due to cost considerations or only present on the most critical sensor elements. This creates the opportunity for faults to occur on any of the other non-redundant elements and then propagate through to even these redundant elements. For this reason analytical redundancy has become the main method for doing fault diagnosis.

In this context of analytical redundancy, fault diagnosis includes three components; fault detection, fault isolation and fault identification [5]. Fault diagnosis starts with detecting that a fault has occurred, after detection the fault needs to be isolated by providing information as to where in the system the

fault is located. Finally the fault identification step provides information on the types, shapes and size of the fault which basically provides degree/ level of malfunction.

### 2.2.2 CLASSIFYING FDD METHODS

[5] completed a comprehensive overview of fault diagnosis techniques that have been developed over the last 30 years with specific focus on highlighting new developments over the last 10 years. According to this study by [5], fault detection and diagnosis techniques can be divided into three methods; model-based methods, signal-based methods and knowledge-based methods.

Model based methods use a model of the system derived from physical principles or system identification techniques. The system outputs are then compared to model predicted outputs to identify faults.

Signal based methods do not rely on input- output relationships but rather extract features from the signals measured in the system. Diagnostic decisions are then taken by comparing these key features to prior healthy versions of the same features. These methods can be time-domain based like computing the mean or standard deviation. They can also be frequency-domain based by looking at the spectrum of signals such as the discrete Fourier transform.

[6] discussed the knowledge based methods in detail in the second part of the overview paper. Knowledge based methods are also referred to as data driven methods. These methods can be either qualitative or quantitative in nature. They require large amounts of historical process data and computing power to extract process knowledge.

Qualitative knowledge based fault diagnosis is expert-system methods that rely on sets of rules to evaluate data and detect faults. The rules have to be developed specifically for the system in question but integrating this method with a object-orientated paradigm provided more flexibility by developing more general rules. Another method used with this description is qualitative trend analysis (QTA) which identifies process trends from noisy data and compares them to a database that contains fault trends. The QTA method has been advanced by combining it with integrated signed directed graphs (SDG) to compensate for some of the disadvantages of this method.

Quantitative knowledge based methods are based on solving the pattern recognition problem. This

can be done using statistical analysis techniques like principal component analysis (PCA), partial least squares (PLS), independent component analysis (ICA) or support vector machine (SVM). This can also be done using Non statistical analysis based methods which are better suited for non-linear applications, an example of this is a neural network.

A lot of new research is being done in quantitative knowledge based methods due to the vast amount of data that is now available in modern industrial complexes. [7] defines these methods as multivariate statistical process monitoring (MSPM). For linear Gaussian process methods such as PCA, PLS and canonical correlation analysis CCA are used. To cater for non-Gaussian, non-linear and dynamic characteristics numerous extensions have been developed for the above mentioned methods.

### **2.2.3 EVALUATING FFD METHODS AND STRUCTURE**

Two very important concepts to understand when evaluating fault FFD methods is completeness and resolution [4]. Completeness describes how well a method is at detecting all the possible faults exhibited by the system. Resolution then relates to how well the method is at classifying the fault into a small subset of the available faults. A diagnostic system has the following desirable characteristics according to [4].

1. Quick detection and diagnosis - creates a trade-off between robustness and performance
2. Isolability - ability to distinguish between different failures
3. Robustness - robust to various noise and uncertainties
4. Novelty identifiability - can detect a new/novel fault in the process
5. Classification error estimate - error measures to project confidence levels
6. Adaptability - be able to develop new scope as new problems/faults arises and more information becomes available
7. Explanation facility - provide explanation of how fault originated and propagated. Ability to reason cause and effect relationships in the process.
8. Modeling requirements - modeling effort required should be minimal
9. Storage and computational requirements - achieve balance between computational complexity and storage requirements
10. Multiple fault identifiability

In any diagnostic system the measurements and data goes through a transformation process. Two important components to take note of when considering transformations are the a priori process knowledge and the search technique used [4]. In general the transformation of data will go through four steps:

1. Measurement space
2. Feature space
3. Decision space
4. Class space

[4] explains these spaces as follows: The measurement space contains the raw input signals to the diagnostic system. The feature space contains a set of variables that are derived from the measurement space using a priori problem knowledge. Useful features are extracted, in this transformation there is often a significant dimension reduction. This is normally done by using feature selection or feature extraction. Its assumed that features cluster better than measurements which will facilitate improved classification or better discrimination. By extracting discriminant features it takes the burden of the next transformation so that it can easily find the features distinguish between features that match certain decisions. The mapping from feature to decision space is usually done via some sort of objective function or using simple threshold functions. The class space consist of the list of possible faults and the decision space maps to it via threshold functions, template matching or symbolic reasoning. This could be summarized as using some sort of search or learning algorithm to complete these mappings. It is also the final interpretation of the diagnostic system delivered to the user. The decision space and the class space usually have the same dimensions. This could provide the option of combining these two spaces but the advantage of still keeping them separate is that a certain diagnostic method might not be able to give a crisp solution as to what fault is being detected.

A priori knowledge plays a crucial role through this entire transformation process, it can greatly simplify the problem in every step of the process. Sets of failures and relationships between observations and failures is crucial to the success of any method. This relationship can be inferred, the most basic example begin a lookup table or it can be based on domain knowledge. First principle knowledge is referred to as deep, casual and model-based knowledge whereas knowledge gained from past experience with the process can be referred to as shallow, compiled, evidential or process history-based knowledge [4].

### 2.2.4 NEW APPROACHES TO DATA DRIVEN METHODS

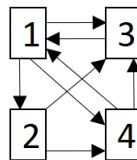
In the following sections of this exploration more focus will be given to knowledge/ data driven methods. Improvements in computing power and better access to tools used for analyzing data make it possible to significantly improve the contribution of data driven methods to the FDD process.

New data driven methods that apply concepts from other fields have started to show some promising results. One of these methods is the use of the PageRank algorithm [8] employed by google on the ranking of control loops based on the degree of interaction.[3] has developed a methodology called LoopRank with the aim of prioritizing control loop maintenance by highlighting loops that have a higher correlation with other loops.

### 2.2.5 PAGERANK DERIVATION

The ranking algorithm developed by [8] started with the idea of ranking web sites depending on how many times they are referenced by other websites.

Consider a group of 4 websites that contain references to each other in the manner indicated in Figure 2.1. References are indicated by arrows.



**Figure 2.1.** web pages with references

An initial idea would be that a page that has more references or back links is more important. Let  $x_k$  be the importance of page  $k$ . If this method is followed then  $x_3 = 3$  would be the most important web page because it has the most references.

This initial ranking method indicates that  $x_3$  is important, but it doesn't take into account the importance that  $x_3$  passes on to  $x_1$  because it is the only page referenced by  $x_3$ .

Another approach would be to let back links from important pages count more than back links from less important pages. If a page  $k$  has a back link from page  $j$ , then the score given to this back link can be calculated as  $x_k = \frac{x_j}{n_j}$  where  $n_j$  is the total number of references made by page  $j$ . The total score for page  $x_k$  is then calculated by the sum of all back links to it adjusted for the number of references made. Applying this new method the importance score for each node is calculated:

$$x_1 = \frac{x_3}{1} + \frac{x_4}{2}$$

$$x_2 = \frac{x_1}{3}$$

$$x_3 = \frac{x_1}{3} + \frac{x_2}{2} + \frac{x_4}{2}$$

$$x_4 = \frac{x_1}{3} + \frac{x_2}{2}$$

These equations can be written in a matrix form, which will be defined as the link matrix  $A$ :

$$A = \begin{bmatrix} 0 & 0 & 1 & \frac{1}{2} \\ \frac{1}{3} & 0 & 0 & 0 \\ \frac{1}{3} & \frac{1}{2} & 0 & \frac{1}{2} \\ \frac{1}{3} & \frac{1}{2} & 0 & 0 \end{bmatrix}$$

Each row in the matrix  $A$  represents a page or node while each column represents the importance score from another node. For example row one represents node 1 and it has a back link from node 3 with an importance score of 1 and a back link from node 4 with a importance score of  $\frac{1}{2}$ .

if  $x = \begin{bmatrix} x_1 & x_2 & x_3 & x_4 \end{bmatrix}^T$  then the problem can be defined as the eigenvector problem:

$$Ax = x\lambda$$

with  $x$  being an eigenvector for  $A$  with an eigenvalue of 1

if  $A$  is a  $n \times n$  matrix, then a nonzero vector  $x$  is an eigenvector if  $Ax = \lambda x$  for some scalar  $\lambda$ . The eigenvector  $x$  that solves this equation is then calculated to be:

$x \approx \begin{bmatrix} 0.387 & 0.129 & 0.290 & 0.194 \end{bmatrix}^T$  which shows that node one is in fact more important than node three.

### 2.2.6 LOOPRANK ADAPTION

[3] developed a method called LoopRank which is based on the PageRank algorithm to prioritize control loop maintenance. Modern industrial sites have a large number of control loops which becomes challenging to maintain effectively given limited technical resources.

The LoopRank method can be summarized in five steps:



1. Collect time series data of control loop parameters
2. Calculate the partial correlation between all the variables in the data set. This information is used to build a relative weight matrix  $A$  or link matrix as referred to in the PageRank algorithm
3. Compute the LoopRank based on the relative weight matrix  $A$  using the eigenvector centrality theorem
4. Multiply the result for each loop with a pre-defined weight that is based on the criticality of the loop. This weight is assigned heuristically depending on loop type and profitability
5. Normalize the results to express the score for each loop as a percentage

[3] demonstrated the efficacy of LoopRank by testing it on an industrial case study in which it successfully flagged the most critical control loops.

### 2.2.7 LOOPRANK DEVELOPMENT

[2] compared LoopRank with a more traditional data driven method that utilizes the integral of absolute or squared error to determine loop interaction. Canonical correlation was used to calculate the relative weight matrix in the LoopRank methodology. It was found that both methods delivered similar results.

The LoopRank methodology was further expanded on by [9] with the goal of improving the relative weight matrix used in step 2 of the procedure as outlined by [3].

[9] demonstrated how transfer entropy provides a more robust estimation of the casual links between nodes in a relative weight matrix. This method was tested using data from the well known Tennessee Eastman case study and was able to successfully highlight the disturbance variables as the top ranking nodes in the matrix.

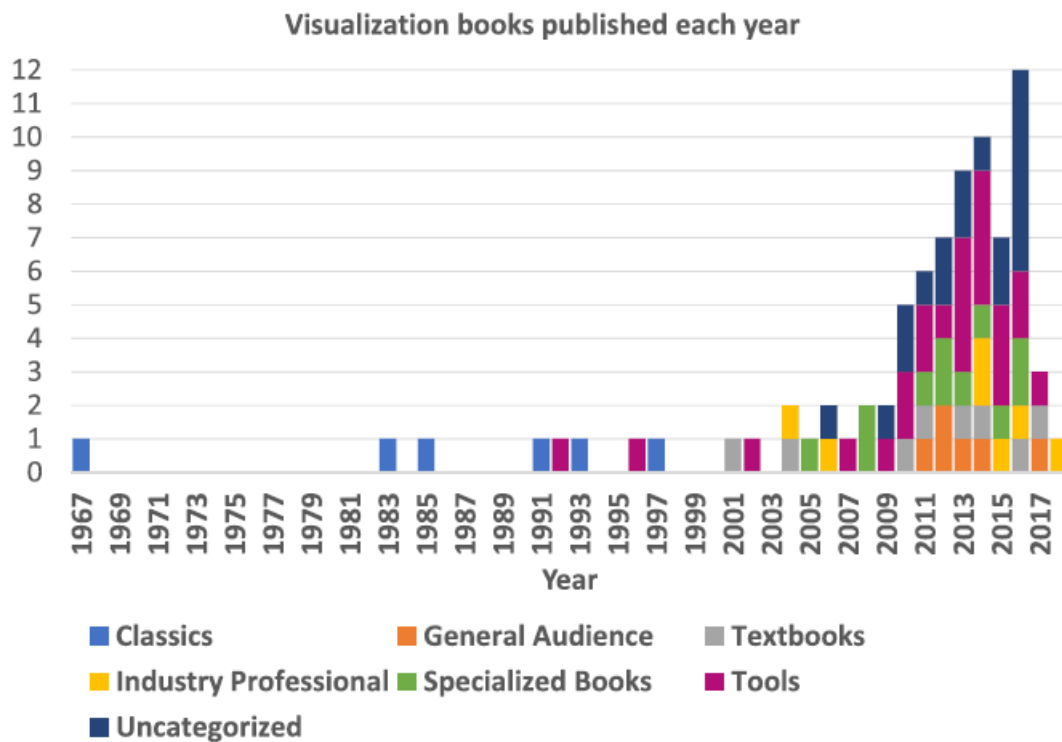
[10] further developed the LoopRank methodology to calculate importance scores for multiple overlapping time regions. Studying how the importance scores change over time then provided a very useful method for performing incipient fault detection.

### 2.3 VISUALIZATION

The methodologies involved in fault detection and diagnosis of industrial processes rely heavily on the visual analysis of time series data. Data is continuously generated by industrial processes, this data in its simplest form can be floating point or boolean values on a control system interface screen. This data is used by plant personnel as feedback on the current status of automated processes.

This study will focus on methods and approaches taken to visualize temporal or time series data.

Some of the first books to discuss information visualization date back to 1967 with the publication of Jacques Bertin's *Semiologie Graphique* [11]. A survey by [11] highlighted the number of visualization books have been published each year, displayed in 2.2.



**Figure 2.2.** Visualization books published each year

The IEEE Visualization conference series aimed at sharing developments in this field started in 1990 and has contributed a large amount of data on how visualization assists other fields to better understand their data. [12] compiled a database of these publications to assist researchers in this field to understand the history of visualization in a field and make the researcher aware of new developments trends. The

papers presented through these conferences serve as valuable source to describe previous work related to visualization for the use of fault detection and diagnosis.

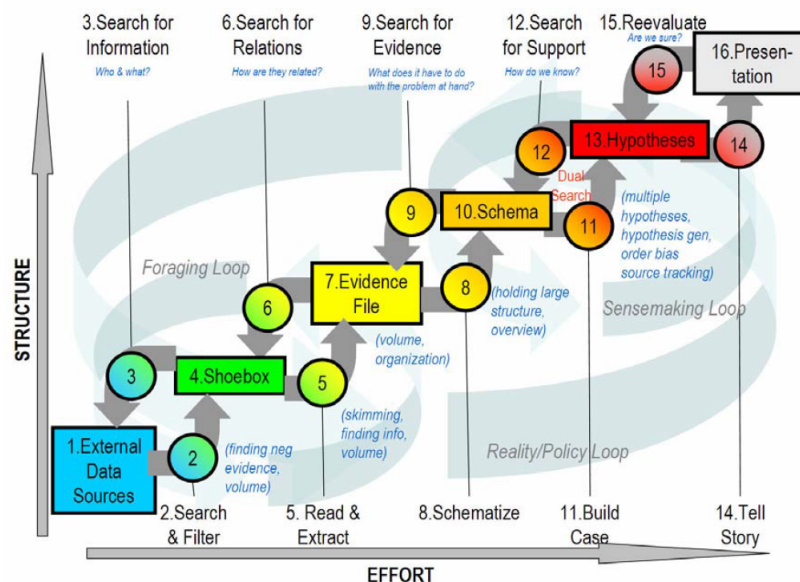
### 2.3.1 VISUAL ANALYTICS

Before designing it is important to understand the mental processes behind data analytics that are used by people to understand and gain insight into data. The work discussed in this section first attempts to describe the human aspect of the process and then attempts to integrate the role of the machine or computer into the process.

One of the earliest models for that describe the process of 'sensemaking' was developed by [13]. In this model intelligence analysis or sensemaking consists of:

1. Information gathering
2. Representation of the information in the form of an outline or model that aids the analysis
3. Development of insight through manipulation of the outline or model
4. Creation of a knowledge product or direct action based on the analysis

The process is visually described by Figure 2.3.



**Figure 2.3.** [13] sensemaking model

The rectangles represent the flow of data and the circles represent the process flow. What is very clear from this model is that there are a lot of back loops and sets of activities that cycle around finding information and making sense of the information. The end result of the process is the generation of novel information by the analyst.

The External data sources are filtered into a smaller data set called a shoebox. Snippets are then extracted from the shoe box based on observed relationships and placed in the Evidence File. A Schema or model is then developed and verified using the Evidence file. A Hypotheses is then form based on this model with a feedback loop that search for additional support of this hypotheses. Finally there is a presentation that is first reevaluated before becoming the product of this work. This model can be used in a top-down (theory to data) or bottom-up (data to theory) approach.

Another approach that represents a more non-linear model that might be a closer representation to how humans actually process information. [14] present a model that starts of with the assumption that people always start making sense of something with some perspective, viewpoint or framework. The frame basically functions as hypothesis of how the data fits together.

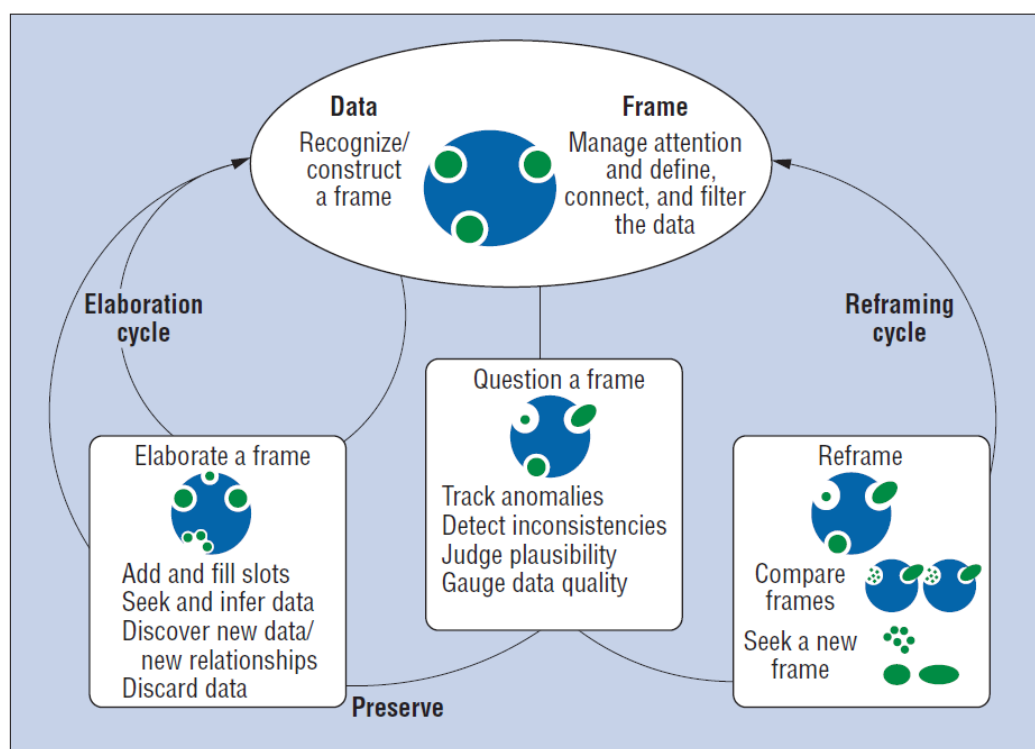
These frameworks or frames actually define what counts as data and shape the data. Frames also change as we acquire data making it a two way path between a frame and data.

The first cycle that starts from the frame/ data idea is the elaboration cycle. In this cycle the frame is expanded and questioned - there could be doubt about the explanation it provides. If the doubt, possibly caused by troublesome data is explained away then the frame is preserved.

The second cycle involves a re framing process. If questioning the frame leads to its rejection, it might lead to its replacement with a better one. We could compare frames to see which one fits the data best.

This model is displayed in Figure2.4.

This is a continuous process in which a frame is strengthened or improvement at each iteration.

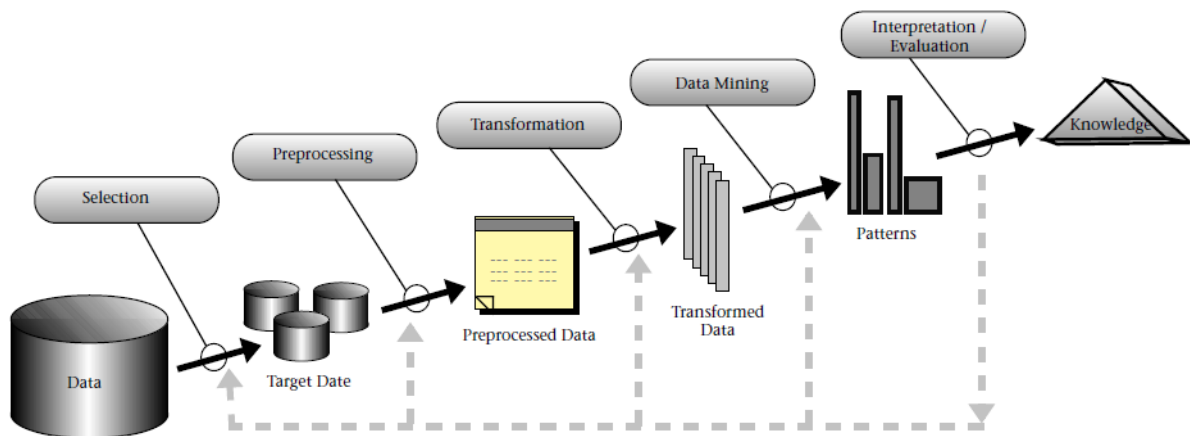


**Figure 2.4.** [14] frame-data sensemaking model

Any method for turning data into knowledge requires the manipulation of the data. The analysis would start with an analysis of the data. This analysis has traditionally been done manually but with the exponential growth in the amount of data that can form part of an analysis other methods are being developed to make this step more efficient. [15] analyzed this challenge in the emerging field of knowledge discovery in databases (KDD). In simple terms this field is concerned with development of methods and techniques for making sense of data.

One of the most noteworthy fields where these methods are applied is in the areas of astronomy. These fields contain terabytes of data contained in images. Although industrial application of data analysis contain a lot less data than this it could still be worth while studying these techniques to see if they can assist with effectively utilizing large amounts of time series data.

The goal of KDD is extracting high-level knowledge from low-level data in the context of large data sets [15]. The KDD process is visually described by Figure 2.5. The process is described by the following steps:



**Figure 2.5.** [15] steps in the knowledge discovery in databases model

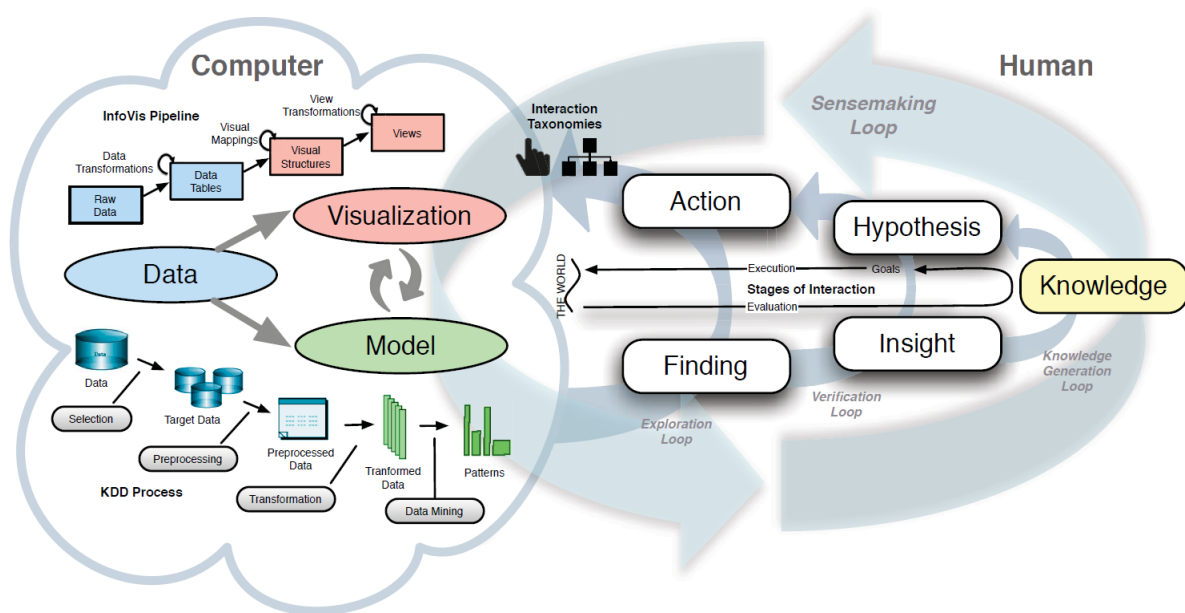
1. Develop understanding of application domain and use prior knowledge to determine the goal of the KDD
2. Create a data set or subset of the available data that will be used to discover useful information
3. Data cleaning, in this step invalid data like noise or questionable data is removed in order to prevent false deductions
4. Data reduction and projection - finding useful features to represent the data, in this step dimensional reduction can be done to simplify the analysis
5. Match the goals of KDD to a specific data mining method
6. Exploratory analysis of the model and hypothesis selection, in this step the data mining method is chosen as well as the methods that will be used to search for patterns
7. Data mining - searching for patterns in the data that would confirm the hypothesis
8. Interpreting the mined patterns
9. Acting on the discovered knowledge, using it to solve the problem

These steps describe a linear process but there can be movement back and forth between the steps to refine the process.

[16] goes a step further to describe the process in which knowledge is generated from data by developing a model that defines how the human and computer interact. This model is split into two parts:

1. computer system which involves the data, visualization and analytic models
2. human component that describes the cognitive process associated with an analytical session

What makes visual analytics so effective is the integration of these two parts; the human side provides the perceptive skills, cognitive reasoning and domain knowledge while the computer side provides the computing data storage capability [16]. This visual analytic model also attempts to incorporate some of the other models described earlier like the Sensemaking model [13] and the Knowledge Discovery Process in Databases (KDD) [15]. The complete knowledge generation model with the reference to other models is displayed in Figure 2.6.



**Figure 2.6.** [16] computer-human interaction in knowledge generating process

The computer part of the model has three main elements:

1. Data - this includes all the data that describes the analytical problem and includes facts in any structured, semi-structured or unstructured manner. Another element to this is a term called meta data, which could be data that describes the structure of other data or data that summarizes other data.
2. Model - This can be any descriptive measure of the data ranging from statistical properties of the data to complex data mining algorithms. This process can deliver a single number to describe the strength of an hypothesis or a complex pattern.

3. Visualization - In this process the data is transformed into some kind of visual artifact that enables the analyst to detect relationships.

, The human element is also described in three main loops: The computer part of the model has three main elements:

1. Exploration loop - Findings are made based on observations of the visual analytics system, Actions or individual tasks are then performed that result in tangible and unique responses from the visual analytics system.
2. Verification loop - Insight is gained from interpreting Findings, often with previous domain knowledge to generate units of information. A Hypothesis is then formed based on these Insights and tested in the visual analytics system through Actions.
3. Knowledge - The final part is to build up confidence in the Insights from the data and Hypotheses tested on the data. If patterns or stories told by the data makes sense and can be used to answer the questions from the visual analytic process then Knowledge is generated. This Knowledge is added to the domain knowledge of the analyst to ask more questions and generate more Knowledge.

This model proposed by [16] again highlights the iterative process of visual analytics and how feedback loops are used in every element of the model.

### **2.3.2 VALUE OF RECORD KEEPING IN VISUALIZATION**

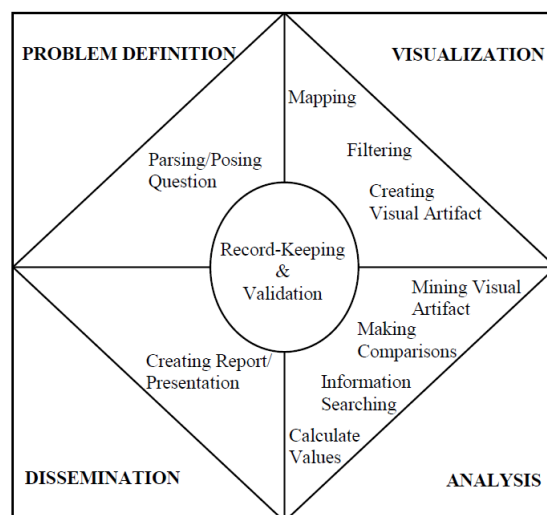
[17] conducted a experiment to study the visual analytics process and the role of record keeping in this process. This study also elaborated on key elements for the design of a collaborative visual analysis tool. The study required groups to complete tasks given a certain data set using computer aided visual analytics. Actions taken during visual analytics were grouped into four phases:

1. Problem definition - understanding what needs to be solved
2. Visualization - generating visual artifacts
3. Analysis - most complex phase that requires examining of charts and making sense of them combined with other data
4. Dissemination - compiling findings in a report



The findings from the study conducted by [17] confirmed observations by other researchers about the non-linear temporal order of activities. While completing the tasks users would move through the phases in a variety of orders. The visualization and analysis phases were strongly interrelated, the users moved back and forth between these two phases much more than the other phases.

[17] generated a very visual model of these four phases with key elements noted in each phase:



**Figure 2.7.** Visualization books published each year

Record keeping involves the saving of visual artifacts and notes. In most cases a visual artifact can convey a complex idea more effectively than notes. Visual artifacts were saved for two main reasons; using them in reporting and using them to enhance the analysis process.[17] recommends that visual analytic systems provide functionality to save visual artifacts like charts for later use and comparison. Note taking also plays a critical role in all phases of the process. The notes high level content could be divided into two categories; findings and cues. Findings are a results of mathematical calculations, statistical operations or decisions and outcomes of the analysis process, they could also take to form of saved charts. Cues can be anything that is not directly extracted from the visualizations that could assist the user to framing or understanding the task at hand. A larger proportion of findings were recorded in the analysis phase while the cues were largely taken during the visualization phase. The study concluded that record keeping is used intensively by data analysts.

[18] completed a longitudinal study of a bioinformatics data set analysis to gain understanding of the entire analysis process from raw data to insights. Visual analytics can be described as a process wherein

user gain insight into complex data. The study highlighted how analysts gather and build insights over long periods of time and connecting the data to extensive domain knowledge and expertise. It is emphasized that analyst spend a significant amount of time on manual manipulation of data and this creates a very important need for the visualization tool to be interactive. Inferior visualizations with interaction were preferred over superior static visualizations.

### **2.3.3 VISUALIZATION TOOLS**

[19] performed a comparison of visualization tools in the development of a tool that can be used for data analysis at CERN. The goal of this tool was to enable scientist to observe a data set as a whole in order to make better decisions of what variable pairs and time frames to analyze during test campaigns.

JavaScript and Python Libraries were investigated and evaluated. D3 and Dygraphs were both discussed as JavaScript libraries that can be used for plotting. Matplotlib was discussed as a Python library that is based on the plotting functionalities of MATLAB. Two other Python libraries, Bokeh and Mpld3 were discussed with specific attention to their capabilities to generate HTML which enables them to easily present graphs on a web browser. Furthermore Mpld3 can integrate Matplotlib plots using D3 to render them to a web page.

[19] did a detailed comparison of Bokeh and Mpld3 which identified Bokeh as their preferred choice. Comparing key aspects like loading time, rendering time and features Bokeh was faster and had more actively developed libraries.

[20] did a comparison of data visualization systems with the specific focus on big data applications. Tools were categorized into coding and zero coding tools with graphical user interfaces.

Within the coding category two languages were discussed; Python and R. Within Python multiple libraries were analyzed for visualization, including Bokeh, Altair, Seaborn, ggplot and Pygal. The zero coding category included Tableau, Infogram, Charblocks, Datawrapper, Plotly, RAW and Visual. It's important to note that of these zero coding tools Plotly is also a Python library used by the data science community.

[21] also completed an overview of tools used for big data visualization and the challenges faced

with attempting to visualization large amounts of data. The tools were compared using the following criteria:

1. Open Source
2. Integration with popular data sources like Hadoop Hive or Google Analytics
3. Interactive visualization
4. MOOCS; tutorials available for online learning of the tool
5. API; can the services of the tool be embedded

Five tools were analyzed using this criteria:

1. Tableau
2. Power BI
3. Plotly
4. Gephi
5. Excel 2016

A summary of the results is displayed in Table 2.1 shows an example of a table.

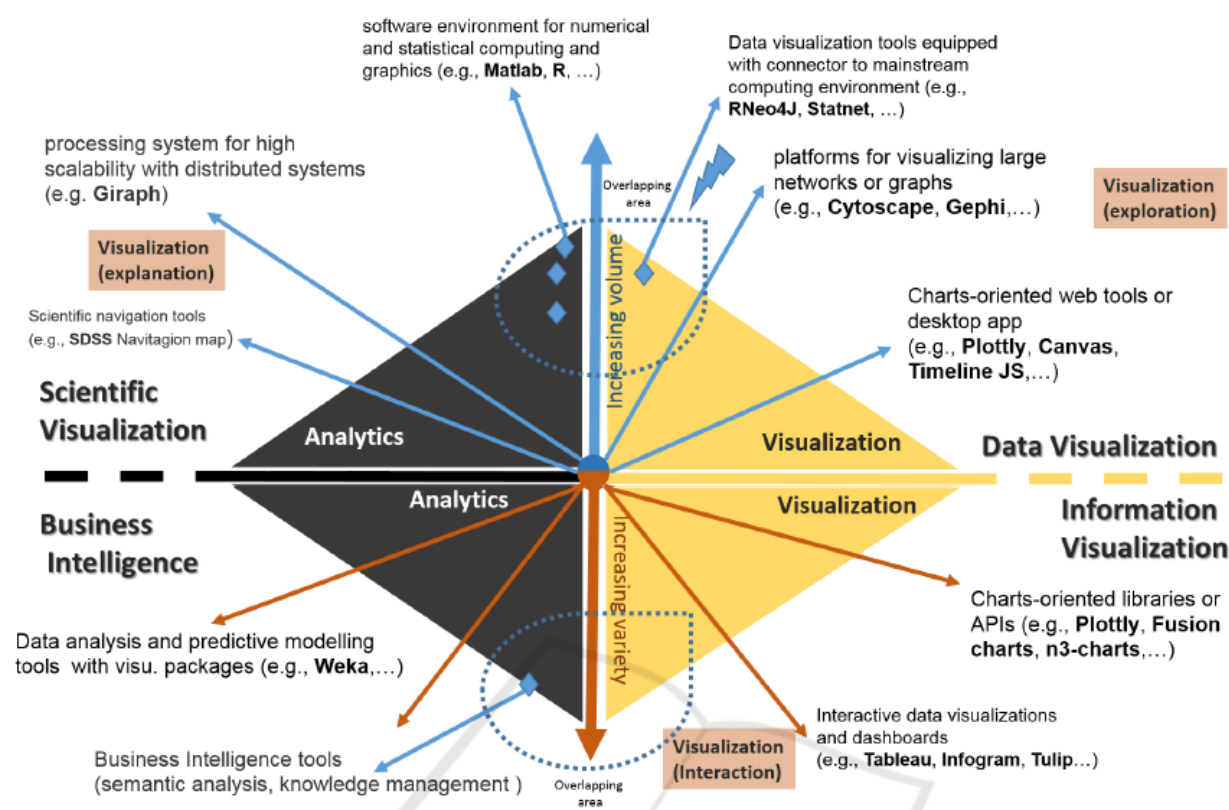
**Table 2.1.** This is a table caption

	Open source	Integration	Interactive	MOOCS	API
Tableau	N	Y	Y	Y	Y
Power BI	N	Y	Y	Y	Y
Plotly	Y	N	Y	Y	Y
Gephi	Y	N	Y	Y	Y
Tableau	N	Y	Y	Y	Y

One of the biggest challenges with modern visualization tools is the latency created by processing large data sets [21]. This can be addressed by using pre-computed data, paralyzing data processing and rendering and using predictive middleware.

[22] completed a comprehensive survey of tools used in Big Data applications. The concept of Big Data has different dimensions, one model that attempts to described these dimensions is widely known as 3Vs. The 3Vs stand for Volume, Velocity and Variety. Each of these dimensions pose its own unique challenges in the data management process.

The analysis and visualization of data was represented in a diagram that distinguishes between four different types of software solutions [22]. The diagram displayed in Figure 2.8 depicts the different types according to the Volume and Variety challenges in the 3Vs model.



**Figure 2.8.** Big data visualization solutions

Differentiation is also done according to four main categories that describe the goals of visualization. The first goal would be the clear and effective communication of information to the user with the

creation and study of the visual representation of data. The Information Visualization category is created to describe this goal. The second goal diverges from the first one in terms of spatial representation. If spatial representation is given to the visualization because of the intrinsic spatial layout of data like a flow simulation in a 3D space, then this can be seen as Scientific Visualization. These two categories can be further divided according to the dimension of volume and variety of data. In the end these four categories chosen by [22] to divide software are:

1. business intelligent tools for data mining of heterogeneous data
2. scientific visualization tools focused that focus on specific spatial representations using larger data sets
3. data visualization tools used for visual exploration
4. information visualization tools used for interactive visual exploration of data

[22] analyses 35 different software solutions in these four categories. What is interesting to note is that Plotly is well described in both the data and information visualization categories which implies that does well at handling big data challenges with variety and volume.

## **2.4 VISUALIZATION AND FDD**

[1] described the exiting potential of combining data driven methods with process information to enhance the diagnosis step. The process information required is a qualitative model of the process topology which captures the logical pathways that information can flow. A standard called Computer Aided Engineering Exchange (CAEX) specifies an XML schema that can to capture the process topology and feed it into a data driven tool.

[23] demonstrated a tool that combined plant topology information written in XML with results form a signal analysis tool called Plant-Wide Disturbance Analysis (PDA) to deliver enhanced isolation and diagnosis of root causes. The connectivity information provided by the plant topology allows the tool to verify or reject hypothesis about the propagation path of a fault. The tool described here was built in C# and contains a reasoning engine that can searches for physical paths and determines root causes for measured plant-wide disturbances.

Another useful model to visualize process connections is the signed directed graph (SDG) model. This model provides a useful way to visual cause-effect relations in continuous systems [24]. The process variables are denoted as nodes and the casual relations as directed arcs. The sign of the arc indicates the casual flow of the process. [10] used SDG models to aid in the logical reasoning process and display the results obtained from data driven methods like the LoopRank algorithm that was expanded on in earlier sections.

SDG models can be obtained by flow sheets, empirical knowledge and mathematical models but in general they are more often derived from qualitative process knowledge and experience [24]. These models are of particular importance in plant-wide fault detection because they can help explain the fault propagation through a complex system.

Process monitoring and fault detection of batch processes has received attention in recent years. The extensive use of batch processing in the production of high value products makes it a important to ensure that batch runs are completed with a high level of success. [25] developed a novel approach to process monitoring and fault detection in batch processes by utilizing a technique they termed time-explicit Kiviat diagrams. The core idea behind this technique is based on Multi-way Principle Component Analysis that facilitates batch-wise unfolding of the three dimensional (Time\*Variables\*Batches) batch data matrix into a two dimensional matrix that captures the variation across batches. The type of data required to warrant the use of this technique is very similar to the data generated by multiple time region analysis in the LoopRank analysis done by [10]. Each batch can be seen as a time region in the LoopRank analysis and the analysis can be seen as the completion of multiple batch runs.

# CHAPTER 3 METHODS (FOR ILLUSTRATION THIS HEADING CONTINUES ONTO THE NEXT LINE)

## 3.1 CHAPTER OVERVIEW

Chapter overview chapter overview chapter overview chapter overview chapter overview chapter overview chapter overview chapter overview chapter overview.

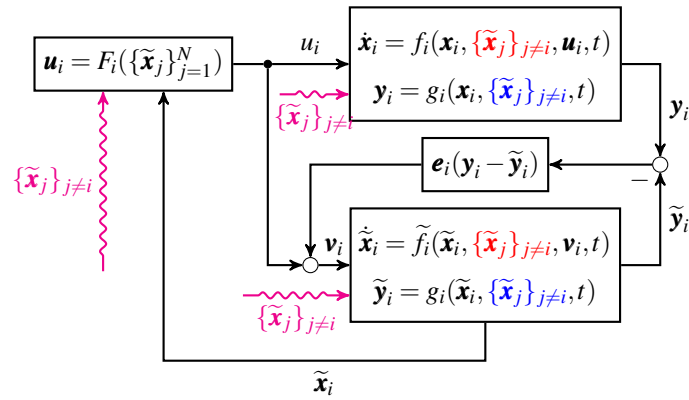


Figure 3.1. Another example of a figure

## CHAPTER 4 RESULTS

### 4.1 CHAPTER OVERVIEW

Chapter overview chapter overview chapter overview chapter overview chapter overview chapter overview chapter overview chapter overview chapter overview.

Table 4.1 shows a more complex example of a table.

**Table 4.1.** A comparison of the total thermal conductance of the VO<sub>x</sub> devices at atmospheric pressure.

Device	Theoretical <sup>(a)</sup> [μWK <sup>-1</sup> ]	Theoretical <sup>(b)</sup> [μWK <sup>-1</sup> ]	Simulated [μWK <sup>-1</sup> ]	Experimental [μWK <sup>-1</sup> ]
VOX4	14.28	11.02	9.55	8.30
VOX6	22.55	18.03	15.71	11.91
VOX7	22.89	18.11	15.91	13.27
VOX8	23.45	18.54	17.69	11.77
VOX13	18.16	14.96	14.39	13.45
VOX15	22.55	18.03	15.65	12.74
VOX23	21.54	17.62	15.62	9.27
VOX24	22.21	17.95	15.44	10.88
VOX32	16.97	13.75	11.41	9.31
VOX33	16.97	13.72	11.67	12.26
VOX36	21.48	17.56	16.51	15.42
VOX39	12.39	10.20	9.55	10.49

<sup>(a)</sup> Theoretical calculation using the standard approach.

<sup>(b)</sup> Theoretical calculation using the compensated method by including the thermal constriction resistance.



## **CHAPTER 5   DISCUSSION**

### **5.1   CHAPTER OVERVIEW**

# **CHAPTER 6   CONCLUSION**

## **6.1   EXAMPLE HEADING**

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# **ADDENDUM A    DERIVATION OF HIGHER ORDER MODELS**

## **A.1    EXAMPLE HEADING**

### **A.1.1    Subheading example**

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