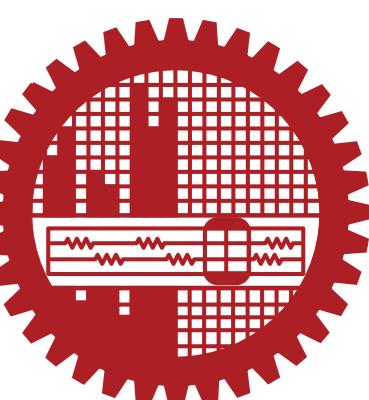


# Satellite Fusion Based Historical Inundation Estimates in Bangladesh

Jonathan Giezendanner<sup>1</sup>, Rohit Mukherjee<sup>1</sup>, Matthew Purri<sup>1</sup>, Mitchell Thomas<sup>2</sup>,  
Max Mauerman<sup>2</sup>, Upmanu Lall<sup>3</sup>, Arifuzzaman Bhuyan<sup>4</sup>, A.K.M. Saiful Islam<sup>5</sup>, Beth Tellman<sup>1</sup>

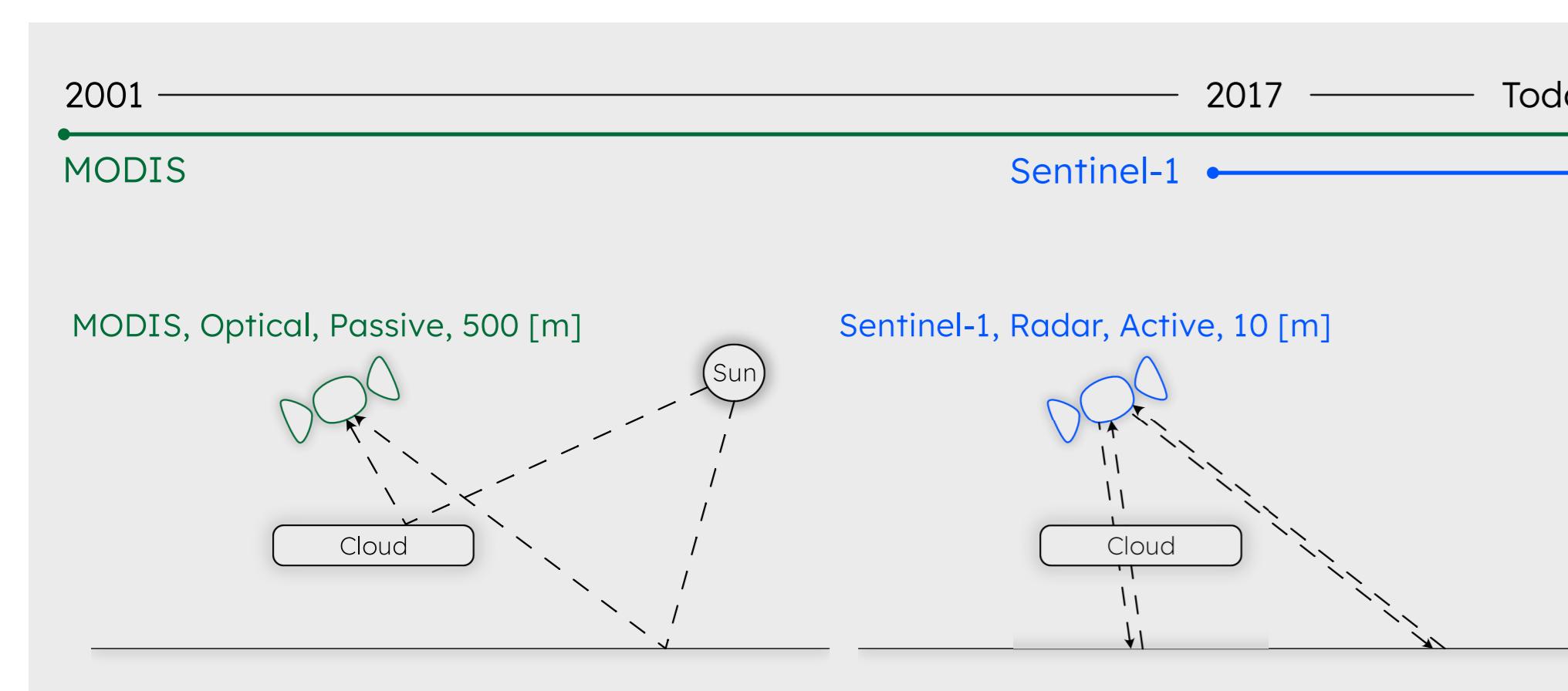


## Why Historical Inundation Estimates?

- In Asia: 68 billion in losses in agricultural production, 60% due to floods (FAO 2015)
- Insurance can support farmers' sustainable development (Benami et al 2021)
- Payout based on **measurable proxy** for losses
- Payout issued when **pre-defined threshold** is reached
- For Floods:** based on **Return Period vs Fractional Flooded Area** estimates
- Requires accurate historical estimate of **yearly maximum flood extent** (capture peaks)
- Requires long time series (**at least 20 years**)

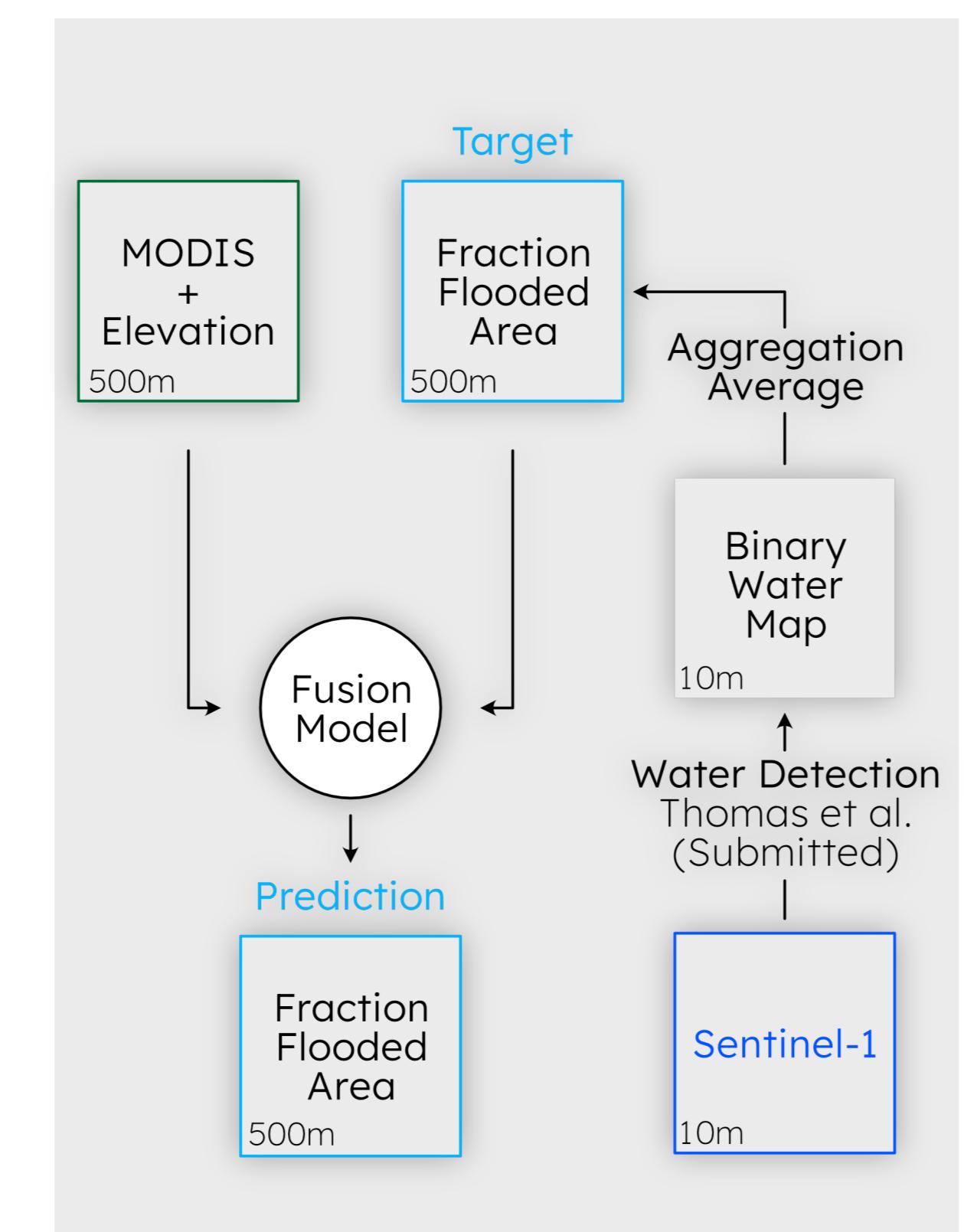
## Mapping Floods over 20 Years

- Best Satellites for Flood detection (Radar, Sentinel-1, 10 m resolution) only available recently
- MODIS provides long time-series but only Optical, 500 m resolution



**Goal** Create historical (20+ years) time series of flooded areas over Bangladesh for return period estimates  
→ Reproduce Sentinel-1 observed fraction of flooded area with MODIS data  
→ Fusion algorithm

## A Fusion Framework to Combine Data Sources

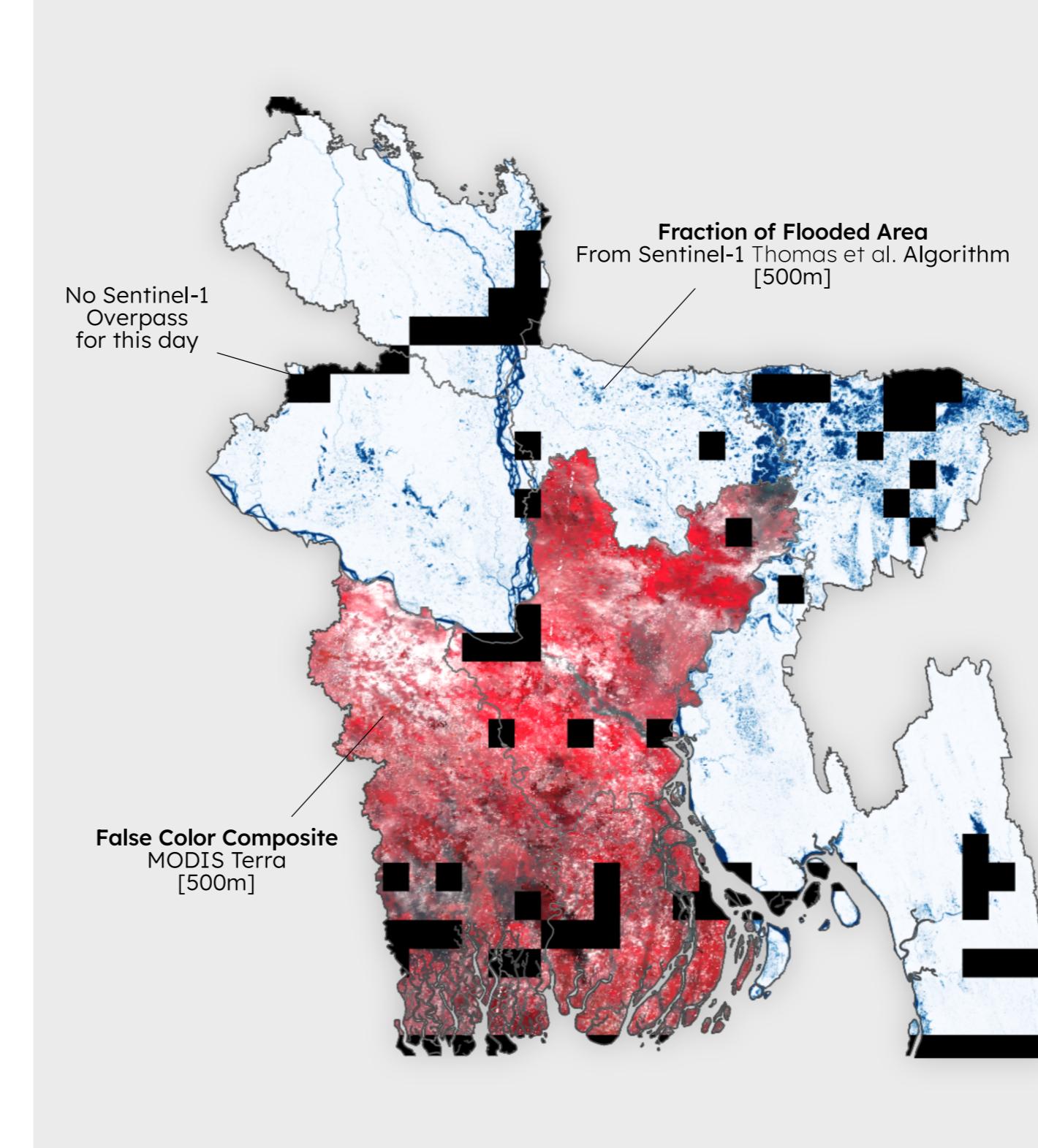


**Target:** Fraction Flooded Area at 500 meter resolution

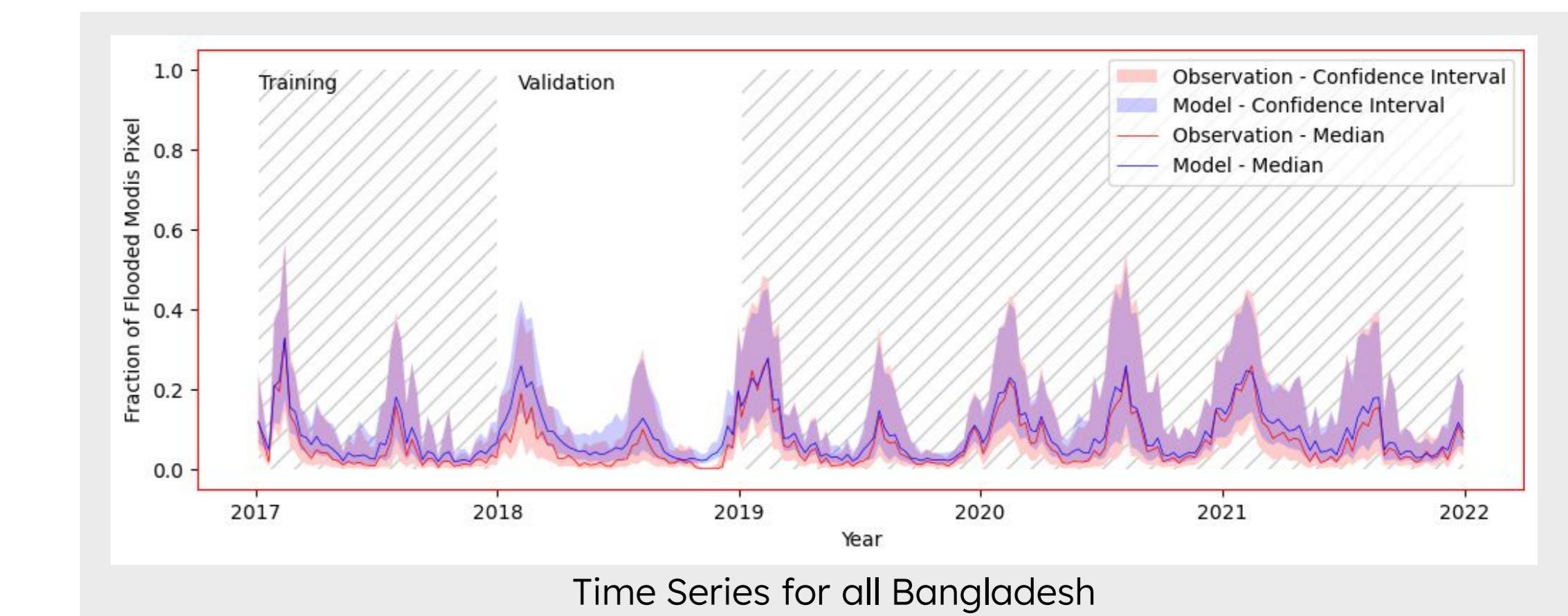
- Based on Sentinel-1
- Dynamic thresholding binary map at 10 [m] resolution Thomas et al., submitted
- Fraction inundated area ( $\in [0,1]$ ) for each MODIS pixel at 500 [m] resolution

### Features:

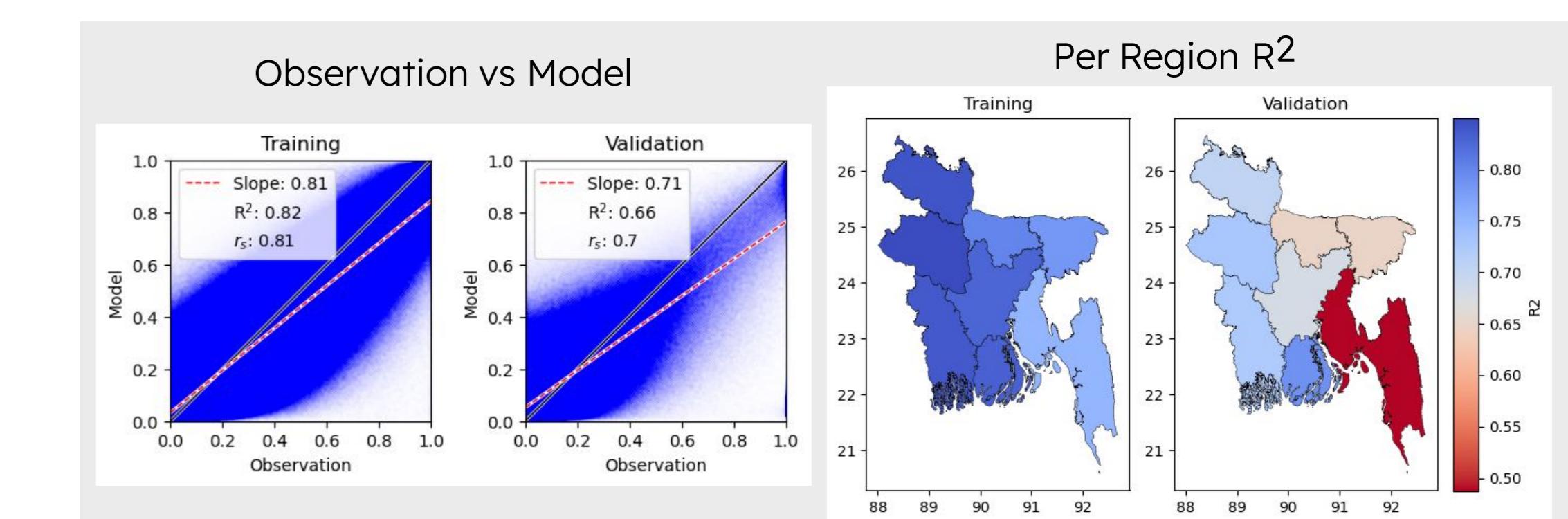
- 8-Days MODIS Terra composite image at 500 [m] resolution
- Elevation (FABDEM)



## Trained Model



Overall R2 of .66 for the validation

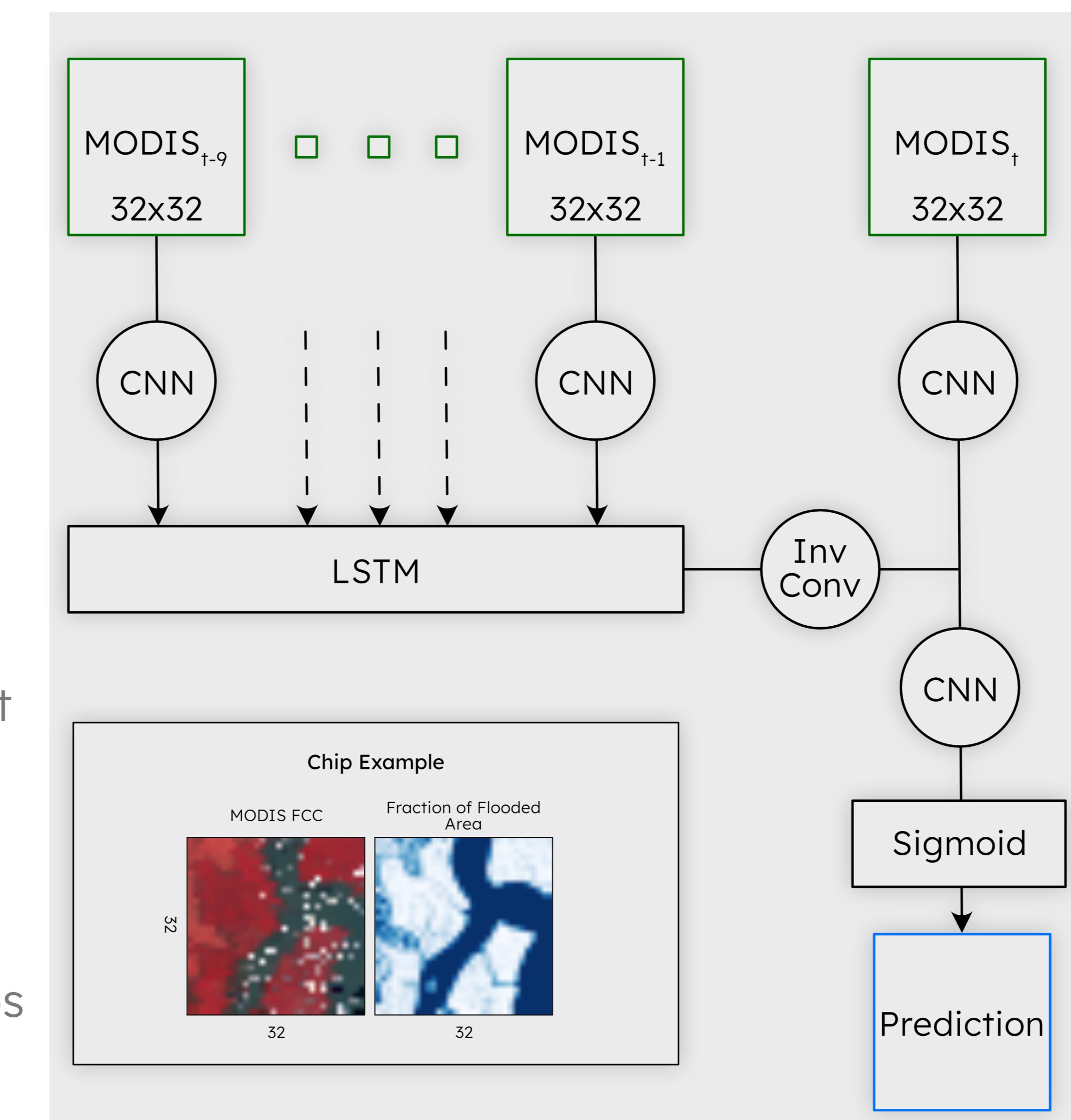


## Combine CNNs and LSTM for Spatial and Temporal Context

### Long-Short-Term-Memory (LSTM) coupled with Convolutional Neural Networks (CNNs):

For each day:

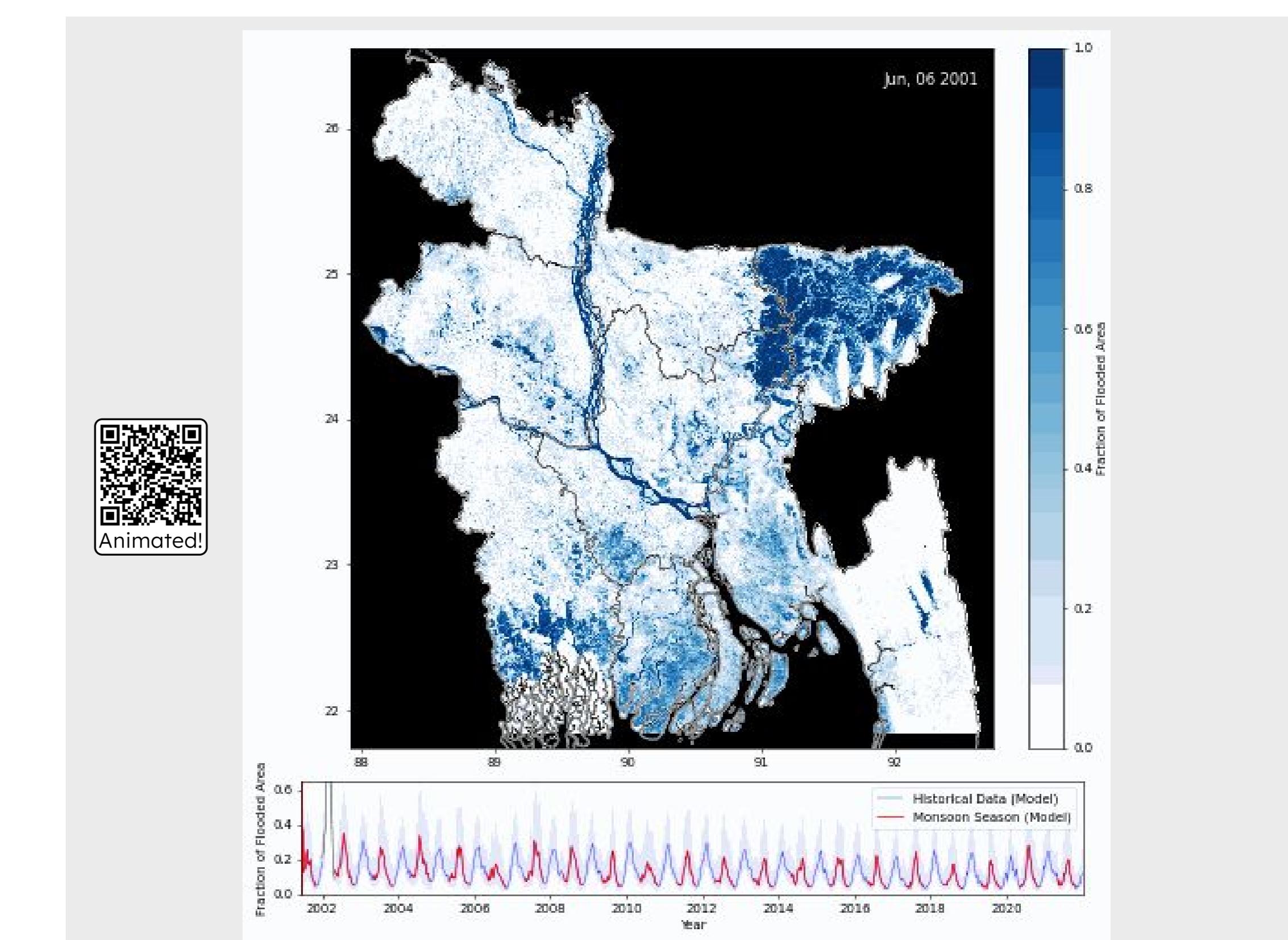
- The 10 MODIS images up to the event are run through a CNN (one network, same parameters)  
→ This provides the spatial context
- The 9 previous CNN outputs are run through an LSTM  
→ This provides the temporal context
- The LSTM output is combined with the CNN at time t and run through the last CNN to provide a prediction



### Training and Testing:

- Each Chip is 32x32 pixels at 500 [m]
- The total dataset contains 150'946 chips
- Year 2018 is removed from the dataset for testing (21'487 chips)

## Inferred Time Series



### Future work:

- Per-year cross-validation
- Improve Mountain regions
- Longer LSTM to capture annual trends

### Acknowledgements

This work is undertaken as part of the NASA New (Early Career) Investigators (NIP) Program (80NSSC21K1044)

Jonathan Giezendanner  
Postdoctoral Researcher  
University of Arizona  
Social [Pixel] Lab  
<https://beth-tellman.github.io>

[jonathan.giezendanner@gmail.com](mailto:jonathan.giezendanner@gmail.com)  
[@JoGiezi](https://twitter.com/JoGiezi)  
[jgiezendanner.com](http://jgiezendanner.com)  
[GieziJo](https://github.com/GieziJo)

