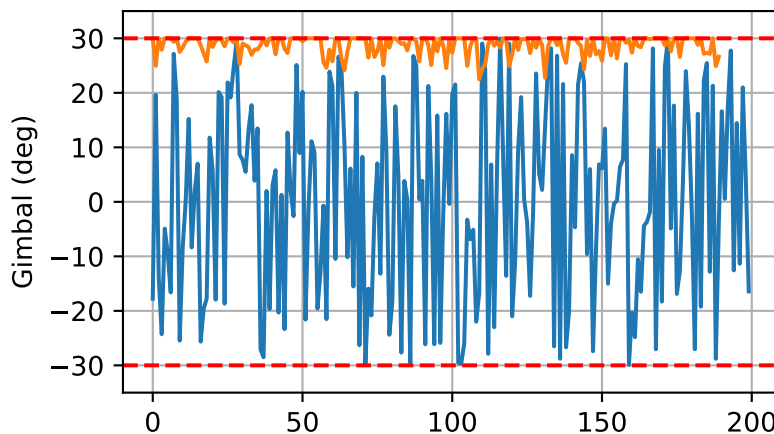


- Example Random Run
- Example Policy Run
- Min thrust
- Max thrust



- Example Random Run
- Example Policy Run
- Min gimbal
- Max gimbal