```
the arm beat all other arms with probability of 0.5 — Condorcet winner
                                                                                                            a Condorcet winner may not exist — motivation
                                                the arm beat the most other arms — Copeland winner
                                                       solve the N dimensional parametric decision problem with high confidence — motivation
                                                                                                                                                                                                                                                                                                           solve the problem where absolute rewards
                                                          find the optimal arm choice
                                                                                                                                                                                                                                                                                         motivation
                                                                                                                                                                                                                                                                                                            have no natural scale or are difficult to measure
                                                                                          parametric decision problem
                                                    with minimum amount of samples
                                                                                                                                                                                                                                                                                                           ordered arms
                                                                                                                            problem definition
                                                                     epsilon-approximation (error rate)
                                                                                                                                                                                                                                                                                                           strong stochastic transitivity (SST)
                                                       probability of at least 1-delta (confidence bound)
                                                                                                                                                                                                                                                                                         Assumption
                                                                                                                                                                                                                                                                                                            stochastic triangle inequality (STI)
                                                                              terminate with T samples
                                                                                                                                                                                                                                                                                                                       - logisitic (Bradley-Terry model)
                                                  there is a unique arm that is superior to the others
                                                                                                                                                                                                                                                                                                                         Gaussian model
                                                                                                       Condorcet assumption — Assumption
                                                    does not require the arms to be totally ordered
                                                                                                                                                                                                                                                                                                                                  Condorcet winner
                            work by reducing progressively a box-shaped confidence set H until a
                                                                                                                                                                                                                                                                                                                                 - SST
                                                                                                                                                                                                                                                                                                                   property
                            single decision remains in f(H).
                                                                                                                                                                                                                                                                                                                                  finite horizon
                            eliminate the arms loss with high probability to another arm until leave with
                            Condorcet winner
                                                                                                                                                                                                                                                                                                                              combine estimate \hat{P} with confidence interval, update the optimality
                                          Only one arm (Condorcet) left in feasible set
                                                                                                                                                                                                                                                                                          Algorithm
                                                                                                                                                                                                                                                                                                                                  Condorcet winner
                                                                                          Condition of "Accept"
                                           other replacement, e.g. bound of sub of r.v.
                                        bound of confidence interval ([a,b])
                                                                                                                     SAVAGE — Algorithm
                                                                                                                                                                                                                                                                                                         IF2
                                                                                                                                                                                                                                                                                                                                  finite horizon
                                                                                                                                                   SAVAGE
                                                                                IndepTest: choose the preference
                                                    exist copeland winner )-
                                                                                                                                                                                                                                                                                                                   core: IF1 + pruning
                                                                             Parameters Elimination by Sampling
                                                                                                                                                                                                                                                                                                       logarithmic round
                                        outperforms IF and BTM for moderate K — O(K^2 log T)
                                                                                                                                                                                                                                                                                         Regret
                                                                                                                                                                                                                                                                                                                           confidence intervals
                                                                                    finite horizon
                                                                                                                                                                                                                                                                                                       regret analysis
                                                                                                                                                                                                                                                                                                                           regret per match
                                                                                                        Regret
                                                                                   infinite horizon
                                                                                                                                                                                                                                                                                                                           random walk
                                                                         regret analysis: Theorm 1
                                                                                                                                                                                                                                                                                        Lower Bound: regret of dueling bandit algorithm has d lower bound
                                                               Copeland winner
                                                                                                                                                                                                                                                                                       Reference: The K-armed Dueling bandits problem, 2009
                                                                                      Coperland score — Copeland bandit
                                                  number of one-to-one winning
                                                                                                                                                                                                                                                                                                              extend the Dueling Bandits Problem to a relaxed
                                                                                                                                                                                                                                                                                                              setting where preference magnitudes can violate transitivity
                                                                          mean performance against others
                                                                                                                                   Application
                                                                                                                                                                                                                                                                                                              relaxed stochastic transitivity (RST)
                                                              stability (the utility is linear)
                                                                                                                                                                                                                                                                                            Assumption
                                                                                               Advantage
                                                                                                                                                                                                                                                                                                              stochasitic triangle inequality (STI)
                                reduces the dimension of the problem to only K parameters
                                                                                                               Borda bandit
                                                                                                                                                                                                                                                                                                                                     PAC: confident near-optimal bandit
                                         Borda winner may not be the Condorcet winner — Disadvantage
                                    SAVAGE Sampling/Borda: a Borda relaxation of the COndorcet feasible set
                                                                                                                                                                                                                                                                                                                                      Condorcet winner
                                                                                Reference: Generic Exploration and K-armed Voting Bandits, 2013
                                                                                                                                                                    Copeland Bandit
                                                                                                                                                                                                                                                                                                                                      ordered arms
                                                                                                          Upper confidence bound — idea
                                                                                                                                                                                                                                                                                                                                            — drawback — require explicit value of \gamma
                                                          design for small number of arms Copeland winner problem )——( motivation )
                                                                                                                                                                                                                                                                                                                        property
           have confidence to beat other arms — optimistic copeland winner
                                                                                   optimism followed by pessimism — principle
            have confidence to beat potential winner — pessimistic opponent
                                                                                                                                        CCB
                                                                                                                                                                                                                                                                                            Algorithm — BTM
                                                                                                                                                                                                                                                                                                                                       mistake-free
                                                                                     Remove non-Copeland winners
                                                                                                                        Algorithm
                                                                                                                                                                                                                                                                                BTM
                                                                                                                                                                                                                                                                                                                                   compare the fewest recored comparison bandit with the mean bandit
                                                                                            Add Copeland winners
                                                                                                                                                   CCB, RCB
                                                                                                                                                                                                                                                                                                                                    (random sample)
                                                                                                                           Regret
                                                                                                                                                                                                                                                                                                                                                             different parameters
                                                                                                                                                                                                                                                                                                                        confidence interval
                                                               design for large-scale arms Coepland winner problem — motivation —
                                                                                      Approximate Copeland Solver
                                                                                                                                                                                                                                                                                                                                                                                   First, the Borda score of the Condorcet winner is always
                                                                              KL-best arm-elimination indetification
                                                                                                                                                                                                                                                                                                                                                                                   greater than or equal to 0.5
                                                                                                                                                                                                                                                                                                                                                                   theorem
                                                                                                                                                                                                                                                                                                                                                                                  the Condorcet winner remains optimal after removing other bandits
                                                                                                                           Regret
                                                                                                                                                                                                                                                                                                                        Another perspective — Borda score
                                                                                              Copeland Dueling Bandits, 2015 — Reference
                                                                                                                                                                                                                                                                                                                                                                              — Keep eliminating Borda losers, eventually the Condorcet winner
                                                                                                                                                                                                                                                                                                        logarithmic round
                                                                                                       Minimum Empirical Divergence — idea
                                    defines the minimum number of comparisons to prove i is inferior to j
                                                                                                                                                                                                                                                                                            Regret
                                                                                                                                                                                                                                                                                                                             mistake-free
                                                                                                           empirical divergence I(t) — theory
                                                        likehood function of condorcet winner: exp(-l(t))
                                                                                                                                                                                                                                                                                                                         number of removed comparisons
                                                                                                                                                                                                                                                                                                          regret analysis
                                                                                                                                                                                                                                                                                                                             incurred regret of comparison — RST
                                                                     set the exploration phase as 1 — RMED1
                                                                                                                                                                                                                                                                                            Reference: Beat the Mean Bandit, 2011
                                                                    set the exploration phase as 1
                                                                                                                     subroutine — Algorithm
                                                                                                                                                     RMED
                         Unlike RMED1, RMED2 keeps drawing pairs of arms i, j at least \alpha log log t
                                                                                                                                                                                                                                                                                                              reducing the Dueling Bandits problem to the conventional (stochastic)
                                                                                                       RMED2
                                                                                                                                                                                                                                                                                             motivation
                         times (Line 10 in Algorithm 1
                                                                                                                                                                                                                                                                                                               Multi-Armed Bandits problem
                            conducts an "\alpha log log T" exploration in the initial phase \rightarrow RMED2FH
                                                                                                                                                                                                                                                                                                                                             average utility
                                                                                                                                                                                                                                                                                                                  reward (not observed)
                                                                                                                                          regret
                                                                                                                                                                                                                                                                                                                                              choice-based utility
                                                                                Regret Lower Bound and Optimal Algorithm, 2015 — Reference
                                                                                                                                                                                                                                                                                                                                                                left alternative
                                                                                                                                                                                                                                                                                                                  linear link function — observed choice
                                                                                                                                                                                                         dueling bandit
                                                                                                                                                                                                                                                 Condorcet winner
                                                           Extends the Thompson Sampling in relative setting to apply dueling bandit
                                                                                                                                                                                                                                                                                             UBDB problem
                                                                                                                                                                                                                                                                                                                                                                 right alternative
                                                                                                                                       motivation
                                                           TS achieves lower regret in practive and more robust than other algorithms
                                                                                                                                                                                                                                                                                                                  regret — accumlative gap with optimlity
                                                                                                               Copeland winner — Assumption
                                                                                                                                                                                                                                                                                                                                                   objective: choose at each round an action from some
                                                                                                                                                                                                                                                                                                                                                  finite set of actions, and receive a reward based on some
                                                                                                                                                                                                                                                                                                                   partial monitoring games —
                                              selects both the first and the second candidates according to Thompson
                                                                                                                                                                                                                                                                                                                                                   unknown function chosen by an oblivious process
                                              Sampling
                                         sample from the parameters representing the number of winning: B_{ij} \rightarrow idea
                                                                                                                           D-TS
                                                                                                                                                                                                                                                                                                        advance — choose the arm with some strategy, observe
                   choose the first arm based on upper confidence bound ——(RUCB-based elimination)
                                                                                                                                                                                                                                                                                                        feedback — update based on feedback
                                                                                                                                                        DTS
choose the second arm only from the uncertain pair (with high lower
                                                                         RLCB-based elimination
                                                                                                           elimination
confidence bound)
                                                                                                                                                                                                                                                                                                               linear link function
                                                                                                                                        Algorithm
                                               avoid falling in suboptimal comparisons — objective
                                                                                                                                                                                                                                                                                                                procedure is based on SBM
                                                                                                                                                                                                                                                                                             Assumption
                                                         change the selection of the first arms
                                                                                                                                                                                                                                                                                                               Large of Structured — Large or possibly infinite set of arms X
                                                                                                  compare with D-TS — D-TS+ —
                                                           minimize the regret of comparison
                                                                                                                                                                                                                                                                                                             - Unstructured — the elements of X typically have no structure
                                                                                                           O(K \log T + K^2 \log \log T) regret
                                                                                                                                                                                                                                                                                                         view the dueling bandit as the dueling of two arms with different strategy
                                                                                                                                                                                                                                                                                UBDB
                                                                                                                                                                                                                                                                                                         (left and right)
                                                                         double-thompson-sampling-for-dueling-bandits-Paper, 2016 — Reference
                                                                                                                                                                                                                                                                                                                                            left: random choice
                                                                                                                                                                                                                                                                                                                         — Doubler
                                                                                                                                                                                                                                                                                                              Structured
                                                                                                                                                                                                                                                                                                                                            right: SBM
                                                                                   solve the problem of dueling bandit arm with dependent arms — motivation
                                                                                                                                                                                                                                                                                                                                                 left: arm of last round
                                                                                  use covariance between arms to model the dependency
                                                                                                                                                                                                                                                                                                             Unstructured — MultiSBM
                                                                                                                                                                                                                                                                                             Algorithm
                                                                                                                                             Gaussian process
                                                               posterior inference updates the mean reward estimates for all arms and
                                                               update the dependency
                                                            reduces the multi-dueling bandits problem to a conventional MAB bandit
                                                        simultaneously dueling multiple arms as well as modeling dependencies
                                                                                                                                                                                                                                                                                                          Doubler — when SBM is UCB
                                                        between arms using a kernel
                                                                                                                                                                                                                                                                                                          MultiSBM
                                using linear function to estimate the preference based on utility u —— approximate linearity —— Assumpation
                                                                                                                                                                                                                                                                                                          Sparring — a constant times the regret of the two SBMs
                                                                                   independent case
                                                                                                                                                                                                                                                                                             Regret
                                                                                                          Ind-Self-Sparring
                                                                                                                                                                                                                                                                                                          Lower Bound — UBDB problem has the same lower boudn of the classic MAB problem
                                                                                                                                                                     Dependent arm
                                                                                           SBM: TS
                                                                                                                                                                                                                                                                                                                                           constant utility of arms
                                                                                                                                 Algorithm
                                                                                  dependent case
                                                                                                                                                                                                                                                                                                                        UBDB setting
                                                                                                                                                 Self-Sparring
                                                                                                                                                                                                                                                                                                                                           UBDB has a lower bound of √KT matching with MAB
                         use Gaussian processes GP(\mu(b), k(b, b')). to model the preference function
                                                                                                       Kernel-Self-Sparring
                                                                                                                                                                                                                                                                                                                                             arbitrary utilities of arms
                                                                                                                                                                                                                                                                                                                                           Sparring can obtain the same regret bound of SBM with adversial setting
                                                       apply Bayesian update using (i_j (t), r_{jk}) to
                                                      obtain (\mu_t, \sigma_t)
                                                                                                                                                                                                                                                                                             Reference: Reducing Dueling Bandits to Cardinal Bandits, 2014
                                                                                                                 O(K \log T / \Delta) Regret
                                                                                                                                                                                                                                                                                                              Extends the Upper Confidence Bound algorithm in relative setting to apply
                                                                                                                                                                                                                                                                                             motivation
                                                                                                                                                                                                                                                                                                               dueling bandit
                                                                           Multi-dueling Bandits with Dependent Arms, 2017 — Reference
                                                                                                                                                                                                                                                                                                                                            fixed number of iteration
                                                                                                   the user can suggest improvements in the form
                                                                                                                                                                                                                                                                                                                   finite-horizon setting
                                                                                                   of coactive feedback
                                                                                                                                                                                                                                                                                                                                             goal: maxmize the accuracy of returning the best arm in T
                                                                 Preference-Based Learning for Exoskeleton Gait Optimization, 2020 — Reference
                                                                                                                                                                                                                                                                                                                                           unfixed T or infinite
                                                                                                                                                                                                                                                                                             standard setting
                                                                                                                                                                                                                                                                                                                   horizonless setting
                                                                                                                                                                                                                                                                                                                                           goal: minimize the cunulative regret over time
                                                                                                                                                                                                                                                                                                                                   horizonless to finite — stop at T
                                                                                                                                                                                                                                                                                                                                   finite to horizonless — doubling trick
                                                                                                                                                                                                                                                                                                               Condorcet winner
                                                                                                                                                                                                                                                                                             Assumption
                                                                                                                                                                                                                                                                                                              horizonless or finite
                                                                                                                                                                                                                                                                                                                         idea — Apply UCB in relative setting: upper bound
                                                                                                                                                                                                                                                                                                                                                       optimistically: u_{cj}
                                                                                                                                                                                                                                                                                RUCB
                                                                                                                                                                                                                                                                                                                                                       pessimistically: u_{jc}
                                                                                                                                                                                                                                                                                                                         two kinds of comparison
                                                                                                                                                                                                                                                                                                             RUCB
                                                                                                                                                                                                                                                                                                                                                       objective: avoid auto-comparisons until is great certainty of optimality
                                                                                                                                                                                                                                                                                                                                                    achieves high-probability regret bounds while making minimal assumptions
                                                                                                                                                                                                                                                                                                                                                    other than assuming a Condorcet winner.
                                                                                                                                                                                                                                                                                             Algorithm
                                                                                                                                                                                                                                                                                                                          Major Improvement
                                                                                                                                                                                                                                                                                                                                                   Causes — avoids arm elimination
                                                                                                                                                                                                                                                                                                                                            partition the K arms into small batches and compares arms within each
                                                                                                                                                                                                                                                                                                          RUCB \longrightarrow O(K<sup>2</sup> + K log T)
                                                                                                                                                                                                                                                                                                                                                  MergeRUCB does not require global pairwise comparisons between all
```

pairs of arms than RUCB

Reference: Relative Upper Confidence Bound for the K-Armed Dueling

Bandit Problem, 2014