

view_frames Result
Recorded at time: 3521.091

robot1/odom

Broadcaster: /gazebo
Average rate: 50.202 Hz
Most recent transform: 3521.073 (0.018 sec old)
Buffer length: 4.940 sec

robot1/base_link

Broadcaster: /robot1/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (3521.091 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot1/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (3521.091 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot1/scan_tf
Average rate: 10.196 Hz
Most recent transform: 3521.159 (-0.068 sec old)
Buffer length: 4.904 sec

robot1/chassis

Broadcaster: /robot1/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (3521.091 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot1/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (3521.091 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot1/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (3521.091 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot1/robot_state_publisher
Average rate: 8.571 Hz
Most recent transform: 3521.034 (0.057 sec old)
Buffer length: 4.900 sec

Broadcaster: /robot1/robot_state_publisher
Average rate: 8.571 Hz
Most recent transform: 3521.034 (0.057 sec old)
Buffer length: 4.900 sec

Broadcaster: /robot1/robot_state_publisher
Average rate: 5.102 Hz
Most recent transform: 3521.034 (0.057 sec old)
Buffer length: 4.900 sec

robot1/battery0

robot1/sonar

robot1/top

robot1/left_hub

robot1/right_hub

robot1/swivel

robot1/camera_depth_frame

robot1/camera_link

robot1/camera_rgb_optical_frame

robot1/left_wheel

robot1/right_wheel

robot1/center_wheel

robot1/camera_depth_optical_frame

robot1/center_hubcap

robot2/odom

Broadcaster: /gazebo
Average rate: 50.202 Hz
Most recent transform: 3521.075 (0.016 sec old)
Buffer length: 4.940 sec

robot2/base_link

Broadcaster: /robot2/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (3521.091 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot2/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (3521.091 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot2/scan_tf
Average rate: 10.206 Hz
Most recent transform: 3521.107 (-0.016 sec old)
Buffer length: 4.801 sec

robot2/chassis

Broadcaster: /robot2/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (3521.091 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot2/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (3521.091 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot2/robot_state_publisher
Average rate: 8.619 Hz
Most recent transform: 0.000 (3521.091 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot2/robot_state_publisher
Average rate: 8.619 Hz
Most recent transform: 3521.036 (0.055 sec old)
Buffer length: 4.873 sec

Broadcaster: /robot2/robot_state_publisher
Average rate: 8.619 Hz
Most recent transform: 3521.036 (0.055 sec old)
Buffer length: 4.873 sec

Broadcaster: /robot2/robot_state_publisher
Average rate: 5.130 Hz
Most recent transform: 3521.036 (0.055 sec old)
Buffer length: 4.873 sec

Broadcaster: /robot2/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (3521.091 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot2/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (3521.091 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot2/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (3521.091 sec old)
Buffer length: 0.000 sec

robot2/battery0

robot2/sonar

robot2/top

robot2/left_hub

robot2/right_hub

robot2/swivel

robot2/camera_depth_frame

robot2/camera_link

robot2/camera_rgb_optical_frame

robot2/left_wheel

robot2/right_wheel

robot2/center_wheel

robot2/camera_depth_optical_frame

robot2/center_hubcap