### Parallel & Distibuted Computing: Lecture 6

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October 11, 2018

## Concepts and Terminology

Some General Parallel Terminology

2 Limits and Costs of Parallel Programming

# Some General Parallel Terminology

Synchronization The coordination of parallel tasks in real time, very often associated with communications.

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- Coarse: relatively large amounts of computational work are done between communication events
- Fine: relatively small amounts of computational work are done between communication events

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wall-clock time of serial execution wall-clock time of parallel execution

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Parallel Overhead The amount of time required to coordinate parallel tasks, as opposed to doing useful work. Parallel overhead can include factors such as:

Task start-up time

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Scalability Refers to a parallel system's (hardware and/or software) ability to demonstrate a proportionate increase in parallel speedup with the addition of more resources. Factors that contribute to scalability include:

> Hardware - particularly memory-cpu bandwidths and network communication properties

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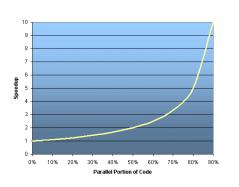
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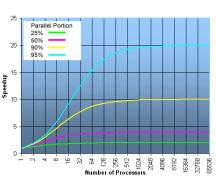
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- Characteristics of your specific application

Limits and Costs of Parallel Programming

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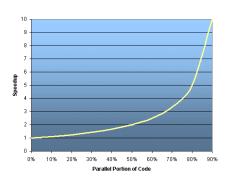


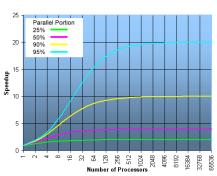


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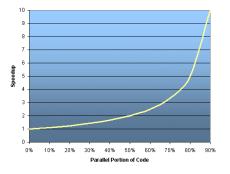


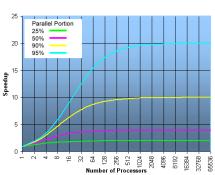
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- If no code can be parallelized, P = 0 and speedup = 1 (no speedup).
- If all code is parallelized, P=1 and the speedup  $=\infty$  (in theory).
- If 50% of code can be parallelized, max(speedup) = 2, meaning the code may run twice as fast

# Amdahl's Law 2/4

Introducing the number N of processors performing the parallel fraction of work, the relationship can be modeled by:

speedup = 
$$\frac{1}{\frac{P}{N} + S}$$

where P = parallel fraction, N = number of processors and S = serialfraction.

## Amdahl's Law 3/4

It soon becomes obvious that there are limits to the scalability of parallelism For example:

N	speedup		
	P = .50	P = .90	P = .99
10	1.82	5.26	9.17
100	1.98	9.17	50.25
1,000	1.99	9.91	90.99
10,000	1.99	9.91	99.02
100,000	1.99	9.99	99.90

Figure 1: Speedup table

## Amdahl's Law 4/4

However, certain problems demonstrate increased performance by increasing the problem size. For example:

```
2D Grid Calculations
                        85 seconds
                                     85%
Serial fraction
                        15 seconds
                                     15%
```

We can increase the problem size by doubling the grid dimensions and halving the time step. This results in four times the number of grid points and twice the number of time steps. The timings then look like:

```
680 seconds 97.84%
2D Grid Calculations
Serial fraction
                        15 seconds
                                      2.16%
```

Problems that increase the percentage of parallel time with their size are more scalable than problems with a fixed percentage of parallel time.

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- Adhering to "good" software development practices is essential when working with parallel applications - especially if somebody besides you will have to work with the software.

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- Hardware architectures are characteristically highly variable and can affect portability.

#### Resource Requirements

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- For short running parallel programs, there can actually be a decrease in performance compared to a similar serial implementation. The overhead costs associated with setting up the parallel environment, task creation, communications and task termination can comprise a significant portion of the total execution time for short runs.

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  - Strong scaling: The total problem size stays fixed as more processors are added.
  - Weak scaling: The problem size per processor stays fixed as more processors are added.
- The ability of a parallel program's performance to scale is a result of a number of interrelated factors. Simply adding more processors is rarely the answer.

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- Parallel support libraries and subsystems software can limit scalability independent of your application.