

# Parallel & Distributed Computing: Lecture 16

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# Julia Parallel programming in Julia 2 — Summary

From [Julia Manual](#)

- 1 Built-in support for clusters
- 2 Data Movement
- 3 Shared arrays
- 4 Parallel Map and Loops

# Built-in support for clusters

# Process identifiers

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- The process providing the **interactive Julia prompt** always has an **id=1**
- The processes used by default for **parallel operations** are referred to as **“workers”**
- When there is **only one process**, process 1 is considered a **worker**.
- **Otherwise**, workers are considered to be **all processes other than process 1**

# Code Availability

```
$ ./julia -p 4
```

Most commonly you will be **loading code** from **files** or **packages**, and you have a considerable amount of **flexibility** in controlling which processes load code.

# Code Availability

Consider a file, `largrid.jl` we want to execute

Look at the Repo <https://github.com/cvdlab/larlib-literate>

and suppose to work with the local copy

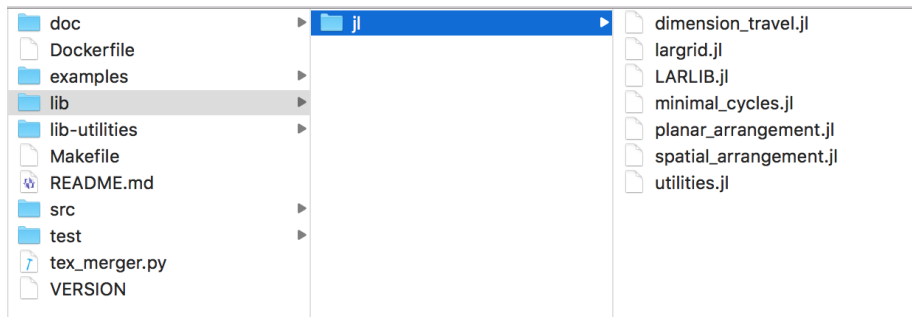


Figure 1: [Local repository of larlib-literate](https://github.com/cvdlab/larlib-literate)

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- `include("lib/jl/largrid.jl")` loads the file on just a single process (whichever one executes the statement)

```
@everywhere include("./lib/jl/largrid.jl")
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- `using LARGRID` causes the module to be loaded on all processes; however, the module is brought into scope only on the one executing the statement.

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- `include("lib/jl/largrid.jl")` loads the file on **just a single process** (whichever one executes the statement)
- `using LARGRID` causes the module to be **loaded on all processes**; however, the module is **brought into scope only** on the one executing the statement.
- You can force a command to **run on all processes** using the `@everywhere` macro

```
@everywhere include("./lib/jl/largrid.jl")
```

# Preloading at start-up

A file can also be **preloaded on multiple processes** at startup, and a **driver script** can be used **to drive** the computation:

```
julia -p <n> -L file1.jl -L file2.jl driver.jl
```

The **Julia process** running the **driver script** in the example above has an **id=1**, just like a process providing an interactive prompt.

# Built-in support for two types of clusters

The [base Julia](#) installation has in-built support for two types of clusters:

- A [local cluster](#) specified with the `-p` option as shown above.

This uses a [passwordless ssh login](#) to start Julia worker processes (from the same path as the current host) on the specified machines.



# Built-in support for two types of clusters

The [base Julia](#) installation has in-built support for two types of clusters:

- A [local cluster](#) specified with the `-p` option as shown above.
- A [cluster](#) spanning machines using the `‘-machinefile’` option.

This uses a [passwordless ssh login](#) to start Julia worker processes (from the same path as the current host) on the specified machines.

# Cluster computing: `_addprocs()`, `rmprocs()`, `workers()`

## Functions

- `addprocs()`,

are available as a programmatic means of **adding**, **removing** and **querying** the processes in a **cluster**.

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# Cluster computing: `_addprocs()`, `rmprocs()`, `workers()`

## Functions

- `addprocs()`,
- `rmprocs()`,
- `workers()`,
- and others

are available as a programmatic means of **adding**, **removing** and **querying** the processes in a **cluster**.

# Cluster computing

Note that **workers do not run a .juliarc.jl startup script**, nor do they **synchronize their global state** (such as global variables, new method definitions, and loaded modules) with any of the other running processes.

Other types of clusters can be supported by writing your own custom ClusterManager, as described in the **ClusterManagers** section of the manual.

# Data Movement

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- Sending messages and moving data constitute most of the overhead in a parallel program.
- Reducing the number of messages and the amount of data sent \*\*is critical\* to achieving performance and scalability.
- It is important to understand the data movement performed by Julia's various parallel programming constructs.

# Explicit and implicit data movement

- `fetch()` can be considered an explicit data movement operation,

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# Explicit and implicit data movement

- `fetch()` can be considered an explicit data movement operation,

since it directly asks that an object be moved to the local machine.

- `@spawn` (and a few related constructs) also moves data,

but this is not as obvious, hence it can be called an implicit data movement operation.

# Explicit and implicit data movement: Example

## Method 1:

```
julia> A = rand(1000,1000);  
julia> Bref = @spawn A^2;  
julia> fetch(Bref);
```

# Explicit and implicit data movement: Example

## Method 1:

```
julia> A = rand(1000,1000);  
julia> Bref = @spawn A^2;  
julia> fetch(Bref);
```

## Method 2:

```
julia> Bref = @spawn rand(1000,1000)^2;  
julia> fetch(Bref);
```

# Conclusion

In this **toy example**, the two methods are easy to distinguish and choose from.

However, in a **real program** **designing data movement** might require more thought and likely **some measurement**

# Global variables

```
A = rand(10,10)
remotecall_fetch(()->foo(A), 2)
```

Note that A is a global variable defined in the local workspace.

Worker 2 **does not have** a variable called A under Main.

The **act of shipping the** closure `()->foo(A)` to worker 2 results in `Main.A` being defined on 2.

`Main.A` continues to exist on worker 2 even after the call `remotecall_fetch` returns.



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- New global bindings are created on destination workers if they are referenced as part of a remote call.
- Global constants are declared as constants on remote nodes too.
- Globals are re-sent to a destination worker only in the context of a remote call, and then only if its value has changed. Also, the cluster does not synchronize global bindings across nodes.

# Global variables

For example:

```
A = rand(10,10)
remotecall_fetch(()->foo(A), 2) # worker 2
A = rand(10,10)
remotecall_fetch(()->foo(A), 3) # worker 3
A = nothing
```

Executing the above snippet results in `Main.A` on worker 2 having a different value from `Main.A` on worker 3, while the value of `Main.A` on node 1 is set to `nothing`.

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As you may have realized:

- while memory associated with globals may be collected when they are reassigned on the master,

This will release any memory associated with them as part of a regular garbage collection cycle.

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# Global variables

As you may have realized:

- while memory associated with globals may be collected when they are reassigned on the master,
- no such action is taken on the workers as the bindings continue to be valid.
- `clear!` can be used to manually `reassign specific globals` on remote nodes to nothing once they are no longer required.

This will release any memory associated with them as part of a regular garbage collection cycle.

## Global variables: example

comportamento differente per Julia 5.x and Julia 6.x

```
A = rand(10,10);
```

```
remotecall_fetch(()->A, 2);
```

```
B = rand(10,10);
```

```
let B = B  
    remotecall_fetch(()->B, 2)  
end;
```

```
@spawnat 2 whos();
```



## The constructs introducing scope blocks are:

Scope name	block/construct introducing this kind of scope
Global Scope	module, <u>baremodule</u> , at interactive prompt (REPL)
Local Scope	<b>Soft Local Scope</b> : for, while, comprehensions, try-catch-finally, let
Local Scope	<b>Hard Local Scope</b> : functions (either syntax, anonymous & do-blocks), struct, macro

Figure 2: Kind of scope

# Scope of Variables

The **scope of a variable** is the region of code within which a variable is visible. Variable scoping helps avoid variable naming conflicts.

## Global Scope

Each **module** introduces a **new global scope**, separate from the global scope of all other modules; there is no all-encompassing global scope.

## Local Scope

A **new local scope** is introduced by **most code-blocks**,

A **local scope** usually **inherits all the variables from its parent scope**, both for **reading** and **writing**.

There are two subtypes of local scopes, **hard** and **soft**, with slightly different rules concerning what variables are inherited.

# Shared arrays

# Shared arrays

Shared Arrays use system shared memory to map the same array across many processes.

While there are some similarities to a DArray, the behavior of a SharedArray is quite different.

In a DArray, **each process** has local access to **just a chunk** of the data, and no two processes share the same chunk;

in contrast, in a SharedArray each “participating” process has access to the entire array.

A SharedArray is a good choice when you want to have a **large amount of data jointly accessible** to two or more processes on the same machine.

# Shared arrays

The `constructor` for a shared array is of the form:

```
SharedArray{T,N}(dims::NTuple; init=false, pids=Int[])
```

which creates an `N-dimensional shared array` of a bits type `T` and size `dims` across the processes specified by `pids`.

Unlike distributed arrays, a shared array is `accessible only` from those participating workers specified by the `pids` `named argument` (and the `creating process too`, if it is on the same host).

# Shared arrays

## EXAMPLE

# Shared arrays

# Parallel Map and Loops



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