

# COMP2054 ADE

## Shortest Paths:

### Floyd-Warshall (FW)

# All-Pairs Shortest Paths

- Suppose that wanted to find the SP between **all** pairs of start and end nodes
  - Dijkstra's algorithm finds all shortest path costs from one given starting node
  - [Not assessed] The complexity of Dijkstra is  $O(|V| * (|V| * \log(|V|) + |E|))$
  - We could run Dijkstra from every node
  - Would then be a factor of  $O(|V|)$  worse than Dijkstra, e.g.  $O(|V| * (|V| * \log(|V|) + |E|))$
- But may be better to run a specific algorithm
  - We will do the "Floyd-Warshall" (FW) algorithm

# FW All-Pairs SPs

- The basic method has similarities to the methods for “change giving” in an earlier lecture
  - “Build best answers for a set of coins, and then add the effects of coins one at a time”
- “Build the optimal answers using a subset of the nodes. Then add the effects of other nodes one at a time”

# FW All-Pairs SPs: data structure

Main data structure definition:

$d(i,j,k) =$

shortest distance between nodes  $i$  and  $j$ ,  
but using only the nodes  $\{1, \dots, k\}$  as potential allowed  
intermediary points

- E.g.  $d(2,5,3) =$   
"shortest distance from  $n_2$  to  $n_5$  using only  $\{n_1, n_2, n_3\}$   
as potential intermediate points'."
- Usage of all or any of these intermediate points is not forced,  
but other points, such as  $n_4 \dots$ , cannot be used

# FW: Initialisation of data structure

Initialisation:

$d(i,j,0)$  = best distance between nodes  $i$  and  $j$ , but not using any intermediate nodes,

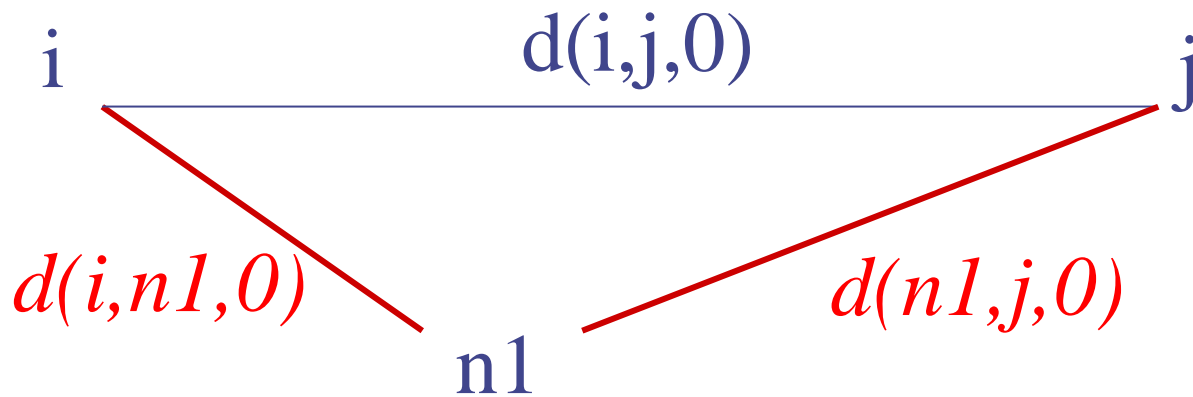
so only using a single edge, Hence

$$\begin{aligned} d(i,j,0) &= w(i,j) \quad \text{if there is an edge } i \text{ to } j \\ &= \text{Inf} \quad \text{otherwise} \end{aligned}$$

where Inf is 'infinity', and could be implemented as a special value, or a number large enough to act as infinity (bigger than all other numbers encountered), etc.

# FW All-Pairs SPs

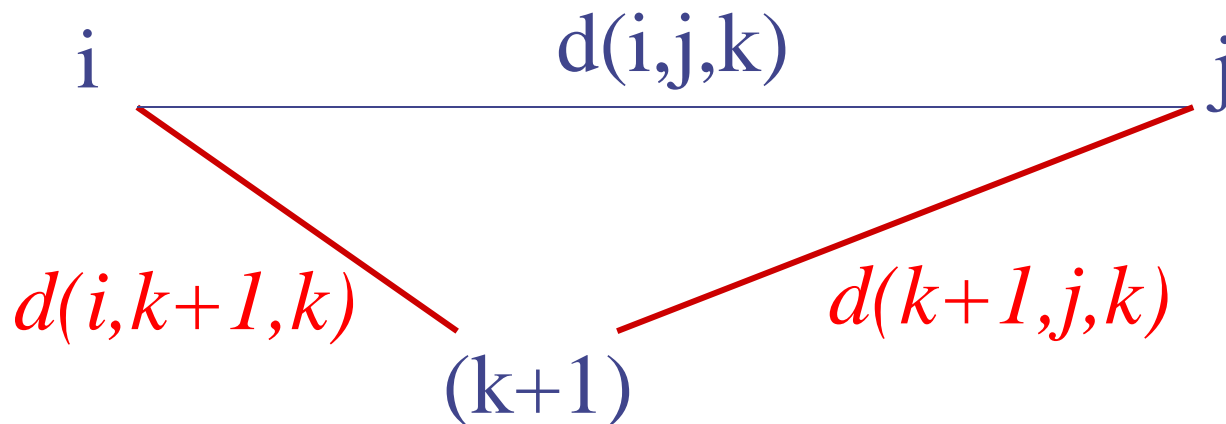
- Now suppose that we add the node 'n1' to the set of nodes that can be intermediates, i.e. consider  $k = 1$
- Best path is now the best of "either direct, or via n1."
- $d(i,j,1) = \min ( d(i,j,0), w(i,n1) + w(n1,j) )$   
 $= \min ( d(i,j,0), d(i,n1,0) + d(n1,j,0) )$



# FW All-Pairs SPs

- Now suppose that we add the new node “(k+1)” to the set of “via nodes” that can be intermediates, but have already considered k of them
- Best path is now either direct using only the k ‘via nodes’ already accounted for, or else also via node ‘k+1’ (and using the previous k via’s)

$$d(i,j,k+1) = \min ( d(i,j,k), \quad d(i,k+1,k) + d(k+1,j,k) )$$



# FW equations

$$\begin{aligned} d(i,j,0) &= w(i,j) && \text{if there is an edge } i \text{ to } j \\ &= \text{Inf} && \text{otherwise} \end{aligned}$$

$$d(i,j,k+1) = \min \left( d(i,j,k), \right. \\ \left. d(i,k+1,k) + d(k+1,j,k) \right)$$

Note:

- The rhs depends only on  $d(-,-,k)$
- The lhs gives  $d(-,-,k+1)$
- So solve by “start at  $k=0$  and iteratively increase  $k$ ”

(These are an example of “Bellmann Equations” and can be solved using DP.)



# FW equations – Comment

k is a dummy variable, and so we could equally well write

$$d(i,j,k) = \min ( \ d(i,j,k-1), \\ d(i,k,k-1) + d(k,j,k-1) \ )$$

Of course, in practice, when implementing, then have to be more careful about the range of k. So that it correctly captures the idea of

- Start with no “via nodes” allowed
- Add “via nodes” one at a time

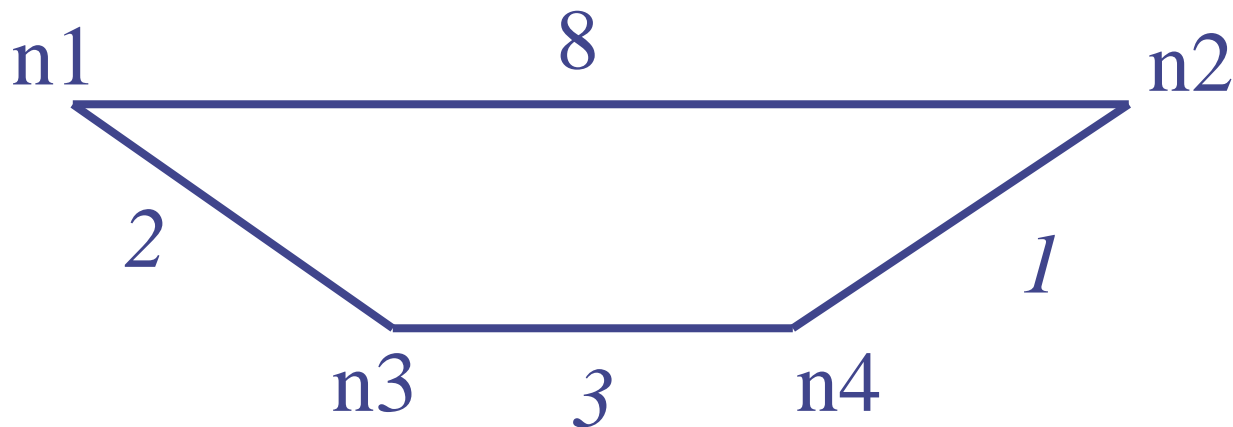
# Self-edges?

- The FW format does not in itself make any assumptions about  $d(i,i)$ 
  - i.e. whether “self-edges” are always assumed to exist.
- However, we will assume that

$$d(i, i) = 0 \quad \text{for all } i$$

- that is, travelling from a node A to itself is possible at cost 0.
- This is for simplicity, and also makes it compatible with Dijkstra which (typically) has the same assumption

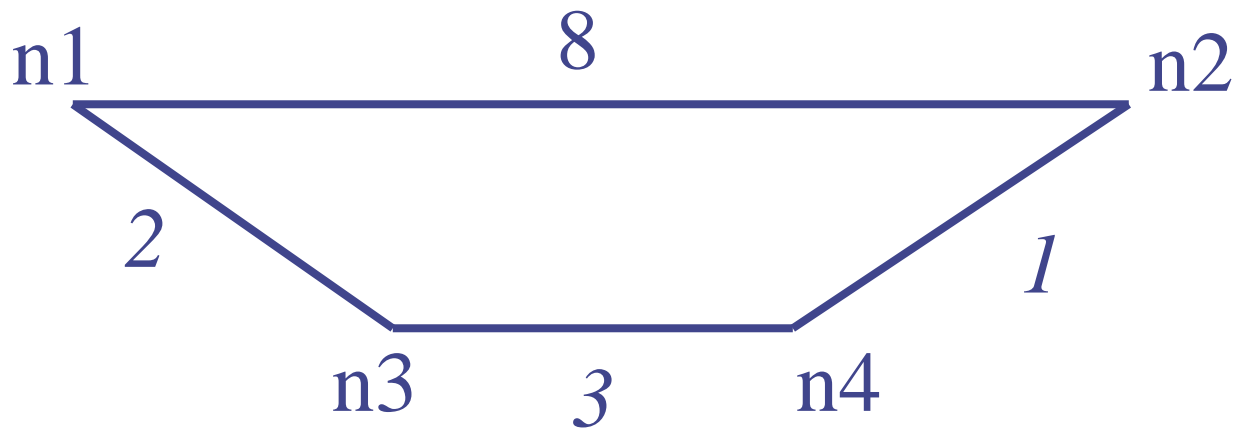
# FW example : $d(i,j,0)$



- Initial  $d(i,j,0)$ 
  - direct edges only
- Edges are undirected, hence matrix is symmetric

$d(i,j,0)$	n1	n2	n3	n4
n1	0	8	2	Inf
n2	8	0	Inf	1
n3	2	Inf	0	3
n4	Inf	1	3	0

# FW example : $d(i,j,1)$ , partial



Set of intermediates = { n1 }

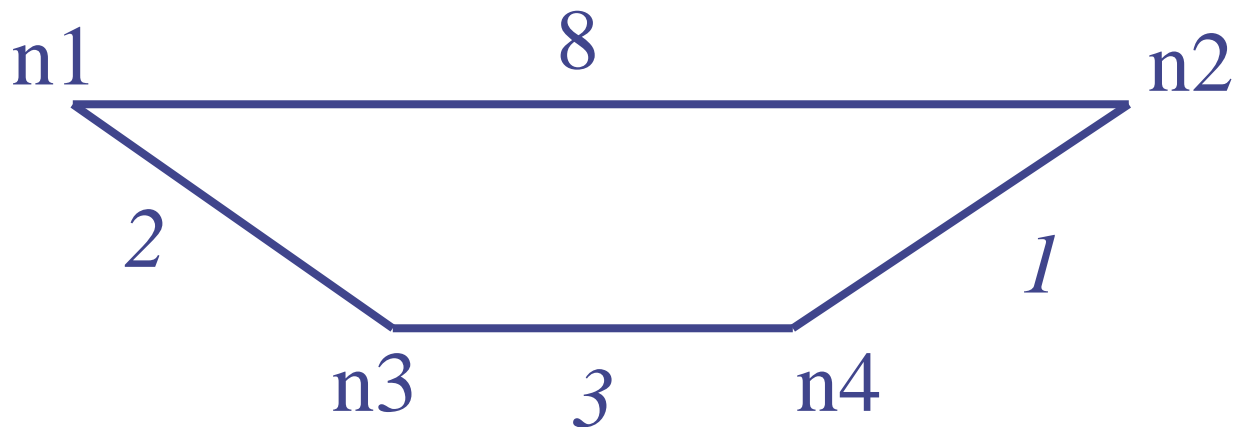
Example:

$$\begin{aligned} & d(n3, n2, 1) \\ &= \min( \text{Inf}, d(n3, n1, 0) + d(n1, n2, 0) ) \\ &= \min( \text{Inf}, 2 + 8 ) = 10 \end{aligned}$$

(We can “see” the optimal will be  $3+1$  via  $n4$ , but we have not considered  $n4$  yet)

$d(i,j,1)$	n1	n2	n3	n4
n1	0	8	2	Inf
n2	8	0	<b>Inf</b> <b>10</b>	1
n3	2	<b>Inf</b> <b>10</b>	0	3
n4	Inf	1	3	0

# FW example : $d(i,j,1)$



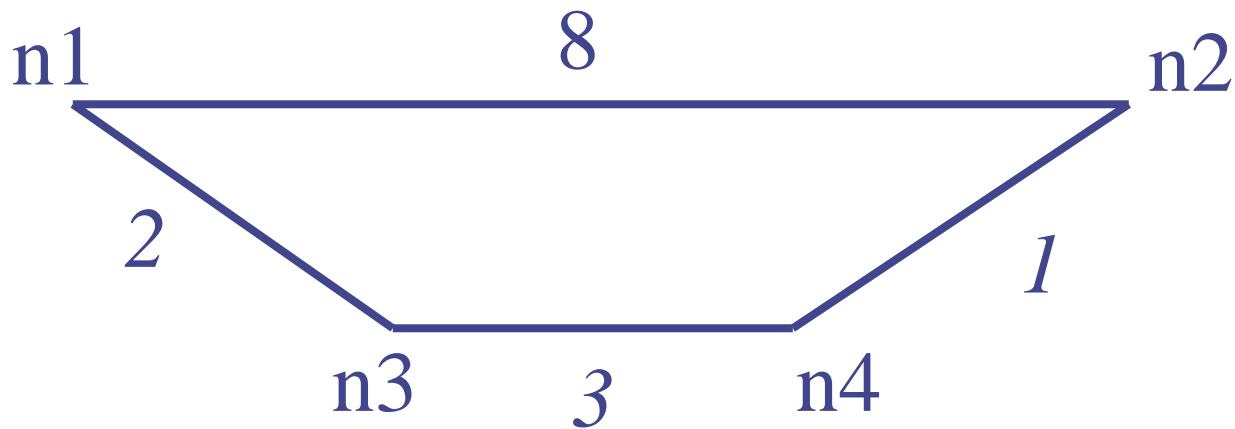
Set of intermediates =  $\{ n1 \}$

Filling in the other entries – check that no other entries change

The matrix is symmetric so will now just give the lower-triangle.

$d(i,j,1)$	n1	n2	n3	n4
n1	0			
n2	8	0		
n3	2	10	0	
n4	Inf	1	3	0

# FW example : $d(i,j,2)$



Set of intermediates = { n1, n2 }

Node n2 is new, so e.g.

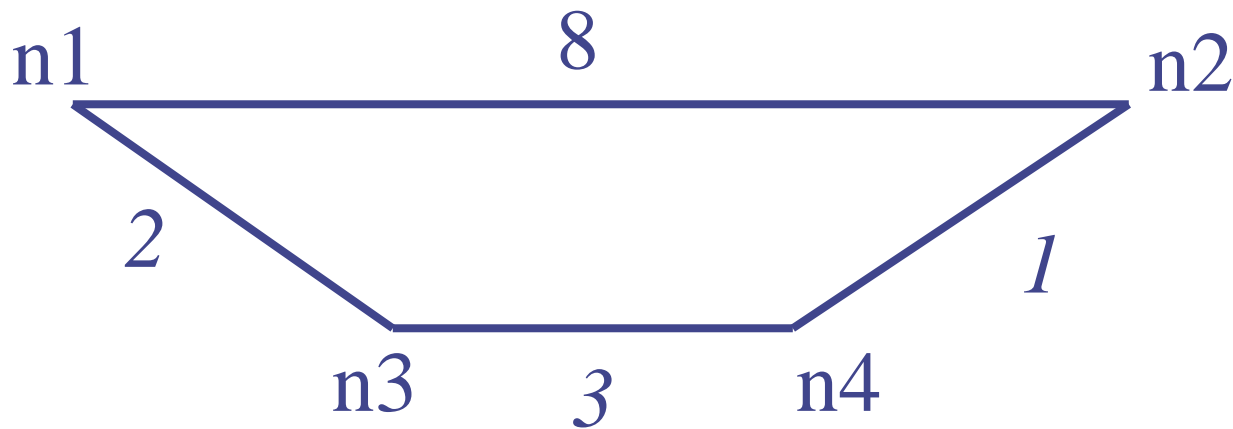
$d(n4, n1, 2)$

$= \min( \text{Inf}, d(n4, n2, 1) + d(n2, n1, 1) )$

$= \min( \text{Inf}, 1+8 ) = 9$

$d(i,j,2)$	n1	n2	n3	n4
n1	0			
n2	8	0		
n3	2	10	0	
n4	Inf 9	1	3	0

# FW example : $d(i,j,3)$



Set of intermediates =  $\{ n1, n2, n3 \}$

Node n3 is new, so e.g.

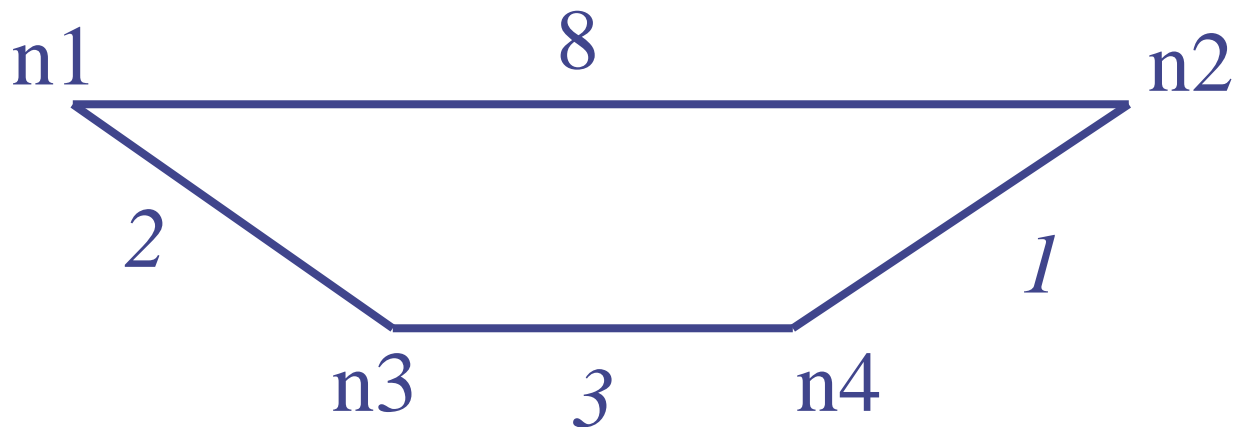
$d(n4, n1, 3)$

$= \min( 9, d(n4, n3, 2) + d(n3, n1, 2) )$

$= \min( 9, 3+2 ) = 5$

$d(i,j,3)$	n1	n2	n3	n4
n1	0			
n2	8	0		
n3	2	10	0	
n4	9 5	1	3	0

# FW example : $d(i,j,4)$



Set of intermediates =  $\{n1, n2, n3, n4\}$

Node n4 is new, so e.g.

$d(n1, n2, 4)$

$= \min( 8, d(n1, n4, 3) + d(n4, n2, 3) )$

$= \min( 8, 5+1 ) = 6$

$d(i,j,4)$	n1	n2	n3	n4
n1	0			
n2	8	0		
n3	2	4	0	
n4	5	1	3	0

Finished as all intermediates are now accounted for



# FW code & complexity

The main loop after initialisation is:

```
foreach k = 1, ...    (so "foreach  $n_k \in V$ ")  
  foreach i  $\in V$   
    foreach j  $\in V$   
       $d(i,j,k+1) = \min( d(i,j,k), d(i,k+1,k) + d(k+1,j,k) )$ 
```

Note that it is vital that 'k' is the outer loop.

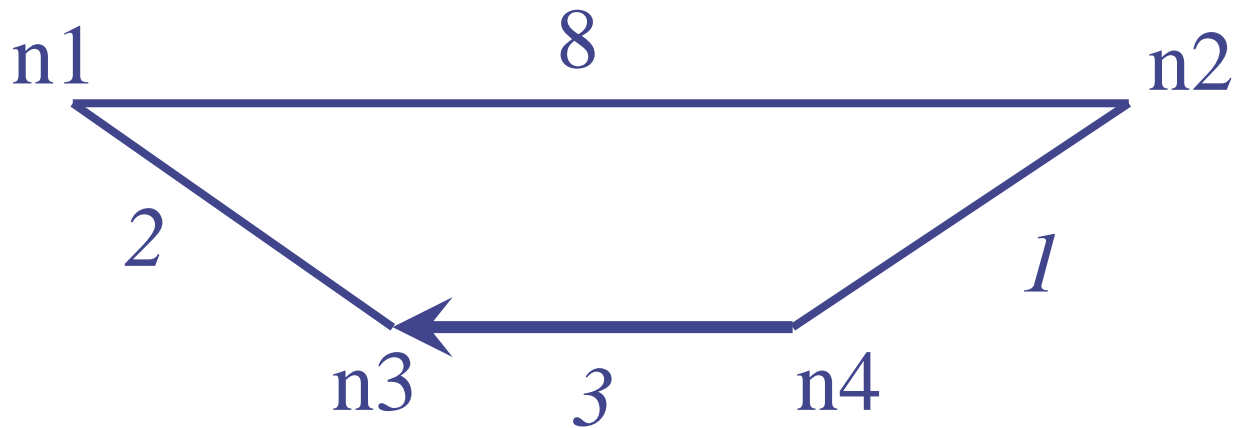
Have 3 nested loops, of ranges  $|V|$ . **Hence is  $O(|V|^3)$**

(If the graph is sparse, then  $|E| \ll |V|^2$ , so then "all-starts Dijkstra" may be better. "<<" means "much less than".)

# FW on digraphs

- FW also works the same on directed graphs
  - The initial matrix  $d(i,j,0)$  need not be symmetric, but then the remaining calculations use exactly the same formulas

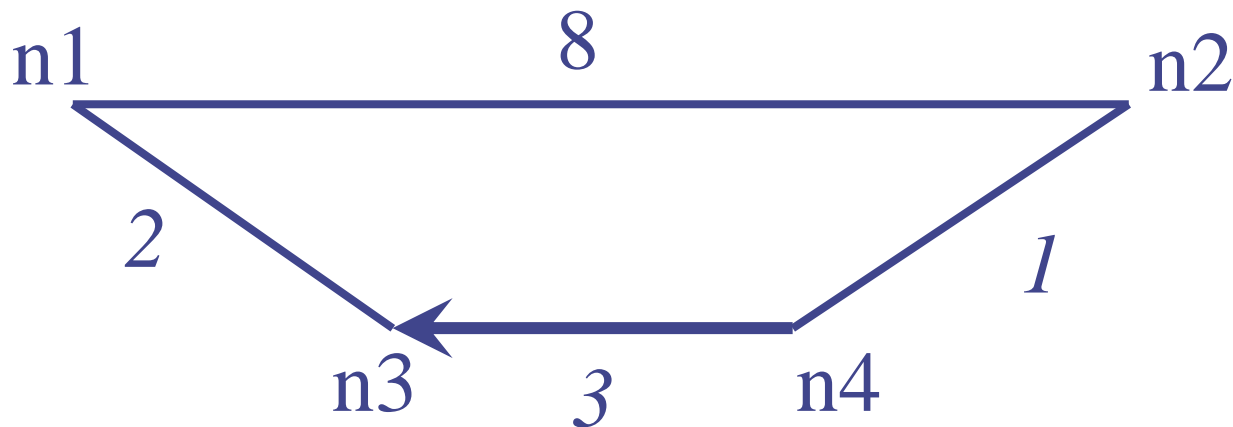
# FW digraph example : $d(i,j,0)$



- Initial  $d(i,j,0)$ 
  - direct edges only
  - edges with no arrows are bidirectional
- Matrix is no longer symmetric

$d(i,j,0)$	n1	n2	n3	n4
n1	0	8	2	Inf
n2	8	0	Inf	1
n3	2	Inf	0	<b>Inf</b>
n4	Inf	1	3	0

# FW example : $d(i,j,1)$ , partial



Set of intermediates = { n1 }

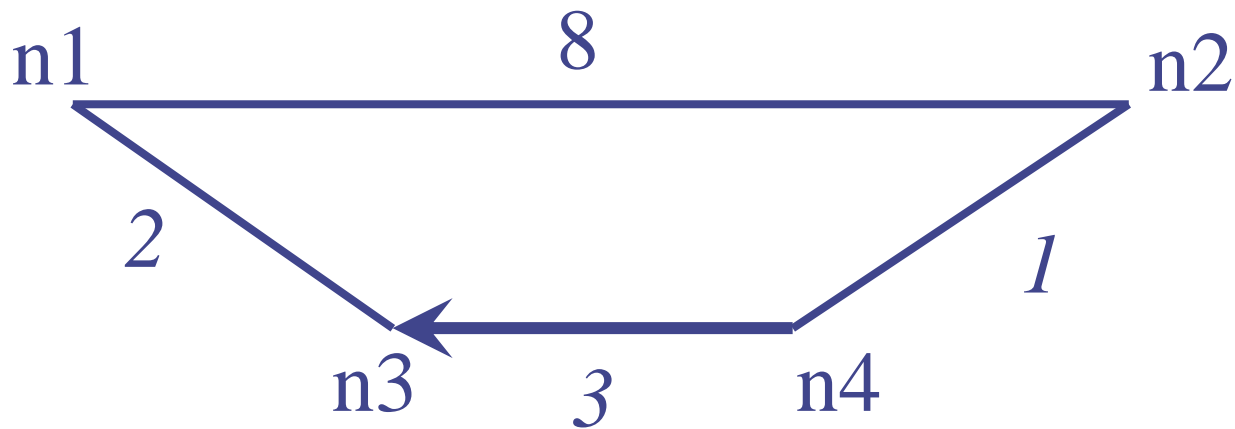
Example:

$$\begin{aligned}
 &d(n2, n3, 1) \\
 &= \min( \text{Inf}, d(n2, n1, 0) + d(n1, n3, 0) ) \\
 &= \min( \text{Inf}, 8 + 2 ) = 10
 \end{aligned}$$

(We can “see” the optimal will be  $3+1$  via  $n4$ , but we have not considered  $n4$  yet)

$d(i,j,1)$	n1	n2	n3	n4
n1	0	8	2	Inf
n2	8	0	<b>Inf</b> <b>10</b>	1
n3	2	<b>Inf</b> <b>10</b>	0	Inf
n4	Inf	1	3	0

# FW example : $d(i,j,1)$

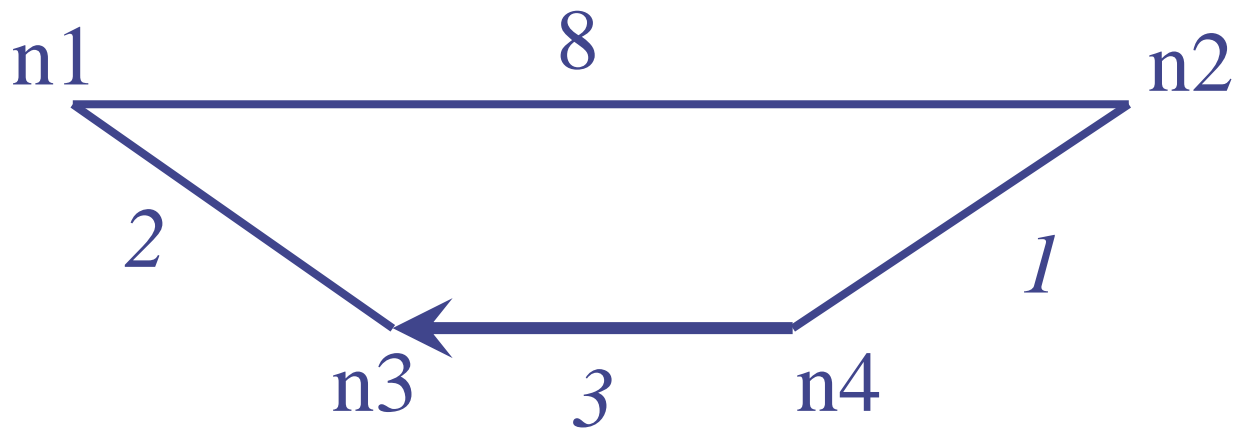


Set of intermediates =  $\{ n1 \}$

Filling in the other entries – check that no other entries change

$d(i,j,1)$	n1	n2	n3	n4
n1	0	8	2	Inf
n2	8	0	10	1
n3	2	10	0	Inf
n4	Inf	1	3	0

# FW example : $d(i,j,2)$



Set of intermediates =  $\{ n1, n2 \}$

Node n2 is new, so e.g.

$d(n4, n1, 2)$

$= \min(\text{Inf}, d(n4, n2, 1) + d(n2, n1, 1))$

$= \min(\text{Inf}, 1 + 8) = 9$  etc

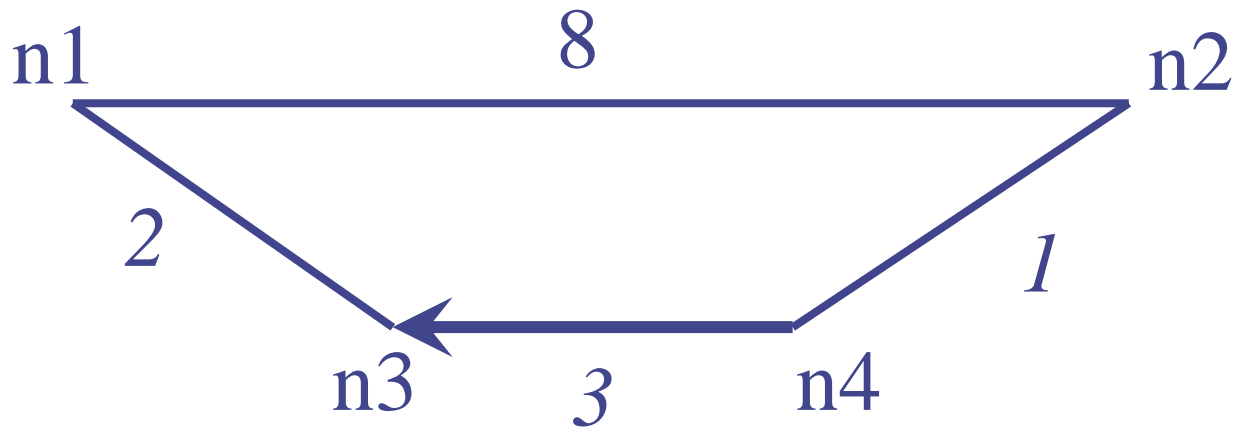
$d(n3, n4, 2)$

$= \min(\text{Inf}, d(n3, n2, 1) + d(n2, n4, 1))$

$= \min(\text{Inf}, 10 + 1) = 11$

$d(i,j,2)$	n1	n2	n3	n4
n1	0	8	2	Inf 9
n2	8	0	10	1
n3	2	10	0	Inf 11
n4	Inf 9	1	3	0

# FW example : $d(i,j,3)$



Set of intermediates =  $\{ n1, n2, n3 \}$

Node n3 is new, so e.g.

$d(n4, n1, 3)$

$= \min( 9, d(n4, n3, 2) + d(n3, n1, 2) )$

$= \min( 9, 3+2 ) = 5$

but

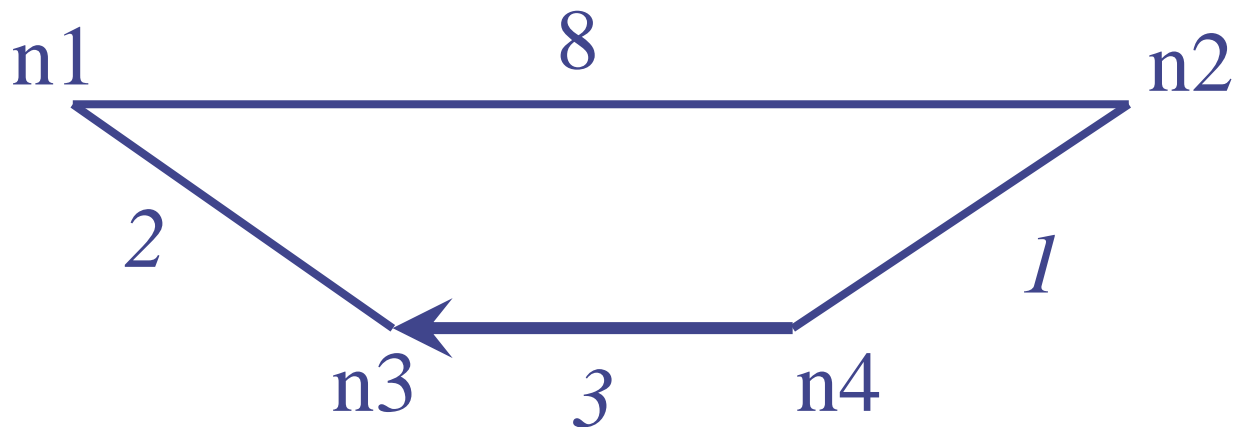
$d(n1, n4, 3)$

$= \min( 9, d(n1, n3, 2) + d(n3, n4, 2) )$

$= \min( 9, 2+\text{Inf} ) = 9$

$d(i,j,3)$	n1	n2	n3	n4
n1	0	8	2	<b>9</b>
n2	8	0	10	1
n3	2	10	0	11
n4	<b>9 5</b>	1	3	0

# FW example : $d(i,j,4)$



Set of intermediates =  $\{n1, n2, n3, n4\}$

Node n4 is new, so e.g.

$d(n2, n1, 4)$

$= \min( 8, d(n2, n4, 3) + d(n4, n1, 3) )$

$= \min( 8, 1 + 5 ) = 6$

$d(i,j,4)$	n1	n2	n3	n4
n1	0	8	2	9
n2	<b>8 6</b>	0	<del>10</del> <b>4</b>	1
n3	2	10	0	11
n4	5	1	3	0

Finished as all intermediates are now accounted for



# FW with negative edges

- FW even works if some (directed) edge weights are negative
  - BUT it is essential that there are no cycles of total negative weight
  - Otherwise simply repeatedly following around the negative cycle may reduce lengths to be as negative as desired, so there is no shortest path
- Offline Exercise: repeat the previous example with  $d(n_4, n_3) = -1$  (instead of  $+3$ )
  - The cycle  $n_4-n_3-n_1-n_2-n_4$  has weight  $-1+2+8+1=10$  which is allowed

# FW: Recall - key idea

Uses that SP does satisfy a nice decomposition of

- If  $P(A,B)$  is a shortest path, and goes via  $M$  then  $P(A,M)$  is optimal for  $A$  to  $M$  and  $P(M,B)$  is optimal for  $M$  to  $B$
- Hence uses a version of “dynamic programming”

# Exercise

- You are **highly** recommended to
  - create some small to medium graphs (directed and undirected) and work through both (Dijkstra and FW) algorithms
  - repeat working examples until you **understand** them fully and can do it 'by hand' quickly and easily
    - Both algorithms are classics, and similar ideas appear in many other algorithms

# Minimum Expectations

- Know and understand definition of all-pairs shortest path, and Floyd-Warshall algorithm
- Be able to apply FW, by hand, to small graphs