# University of Nottingham Malaysia

## SCHOOL OF COMPUTER SCIENCE A LEVEL 2 MODULE, SUMMER SEMESTER 2022-2023 RESIT

## **INTRODUCTION TO IMAGE PROCESSING (COMP 2032)**

Time allowed: **ONE** Hour

Candidates may complete the front cover of their answer book and sign their desk card but must NOT write anything else until the start of the examination period is announced.

### Answer ALL Questions

Marks available for sections of questions are shown in brackets in the right-hand margin.

No calculators are permitted in this examination.

Dictionaries are not allowed with one exception. Those whose first language is not English may use a standard translation dictionary to translate between that language and English provided that neither language is the subject of this examination. Subject specific translation dictionaries are not permitted.

No electronic devices capable of storing and retrieving text, including electronic dictionaries, may be used.

DO NOT turn your examination paper over until instructed to do so.

#### **ADDITIONAL MATERIAL:**

None

#### INFORMATION FOR INVIGILATORS:

Questions papers should be collected in at the end of the exam – do not allow candidates to take copies from the exam room.

## 1. Linear and Non-linear Filtering [30%]

a) Why do we perform spatial filtering?

[6 marks]

b) Based on your understanding, explain in your own words, what does the following terms imply:

i.	Image Noise	[2 marks]
ii.	Gaussian Noise	[2 marks]
iii.	Salt and Pepper Noise	[2 marks]

c) Detail the process of **convolution** using examples to support your explanation.

[5 marks]

d) What is the **difference** between linear and non-linear filtering?

[3 marks]

e) Given the intensity of a local region, as shown in Figure 1 below:

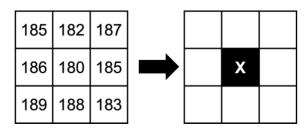


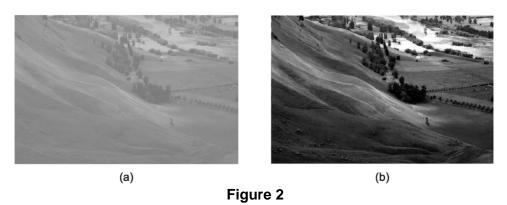
Figure 1

By <u>showing your workings</u>, compute the value of **X** when using the following approach:

i. Mean filteringii. Median filtering[4 marks][4 marks]

f) Gaussian filter is said to be **separable**. How can we apply a 2D Gaussian into two 1D Gaussian? [2 marks]

## 2. Whole Image Methods and Segmentation [40%]



a) Figure 2(b) is obtained by performing histogram equalisation onto Figure 2(a).
 Detail how the algorithm works, practically.

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COMP2032 Page 2|4

b) Based on your answer in 2(a), apply histogram equalisation to a 3-bit per pixel image as listed in Table 1.

Table 1

Pixel Value	Normalised Frequency	
0	0.05	
1	0.2	
2	0	
3	0.1	
4	0.5	
5	0	
6	0.05	
7	0.1	

Show your workings and compute the:

- i. Mapping from input pixel values to output pixel values.
- ii. Normalised histogram of the output image.

[14 marks]

- c) Colour histograms are commonly used for image matching. Detail how this can be done, **step-by-step**. [5 marks]
- d) Please list all the steps involved in the application of the basic concept of Watershed to image segmentation.
  [5 marks]

4	4	2	2
2	3	1	3
1	2	3	2
1	1	3	2

Figure 3

e) Consider the image fragment in Figure 3 (*in which the numbers represent intensity values*). Using letters of the alphabet to label regions, show how this image fragment would be segmented by the **Watershed** algorithm. [10 marks]

## 3. Interactive Methods and Compositing [30%]



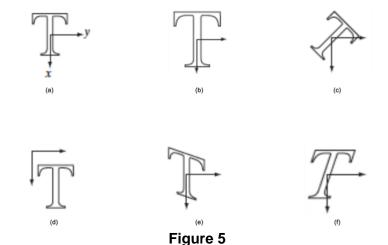
Figure 4

a) Figure 4 is a result obtained after performing the livewire algorithm. Detail each step of the algorithm.
 [8 marks]

P.T.O

COMP2032 Page 3|4

b) What is meant of the term **cooling** in the context of the livewire algorithm. [2 marks]



- c) Figure 5 shows different types of **affine transformations**. Please list down transformations (a) to (f). **[6 marks]**
- d) Applying transformation can be done via **two types of mapping** approaches. Please name them and explain how they are performed. [8 marks]
- e) Based on your understanding, explain in your own words, how does the following approaches work:

i. Nearest neighbour interpolation
 ii. Bilinear interpolation
 iii. Bicubic interpolation
 iii. Bicubic interpolation