

# Generative Adversarial Networks (GANs)

Fiseha B. Tesema, PhD

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- Majority of the slide is complied from
  1. Deep Learning for computer vision: University of Michigan,  
<https://web.eecs.umich.edu/~justincj/teaching/eecs498/WI2022/>
  2. CS231n: Deep Learning for Computer Vision, Stanford university,  
<https://cs231n.stanford.edu/>

# Generative Models

- Given training data, generate new samples from same distribution



Training data  $\sim p_{\text{data}}(x)$



Generated samples  $\sim p_{\text{model}}(x)$

Want to learn  $p_{\text{model}}(x)$  similar to  $p_{\text{data}}(x)$

# What is a Generative Adversarial Network?



The GAN architecture was first described in the 2014 paper **by Ian Goodfellow**, et al. titled “Generative Adversarial Networks.”

The screenshot shows the arXiv page for the paper "Generative Adversarial Networks" by Ian J. Goodfellow et al. The page is from the "stat" category, specifically "stat.ML". It includes the Cornell University logo, a search bar, and various links to access the paper (PDF, TeX Source, etc.). The abstract is visible, describing the proposed framework for estimating generative models via an adversarial process. The page also lists subjects, citation information, and references.

Cornell University

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arXiv > stat > arXiv:1406.2661

Search... All fields Search

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Statistics > Machine Learning

[Submitted on 10 Jun 2014]

## Generative Adversarial Networks

Ian J. Goodfellow, Jean Pouget-Abadie, Mehdi Mirza, Bing Xu, David Warde-Farley, Sherjil Ozair, Aaron Courville, Yoshua Bengio

We propose a new framework for estimating generative models via an adversarial process, in which we simultaneously train two models: a generative model  $G$  that captures the data distribution, and a discriminative model  $D$  that estimates the probability that a sample came from the training data rather than  $G$ . The training procedure for  $G$  is to maximize the probability of  $D$  making a mistake. This framework corresponds to a minimax two-player game. In the space of arbitrary functions  $G$  and  $D$ , a unique solution exists, with  $G$  recovering the training data distribution and  $D$  equal to  $1/2$  everywhere. In the case where  $G$  and  $D$  are defined by multilayer perceptrons, the entire system can be trained with backpropagation. There is no need for any Markov chains or unrolled approximate inference networks during either training or generation of samples. Experiments demonstrate the potential of the framework through qualitative and quantitative evaluation of the generated samples.

Subjects: **Machine Learning (stat.ML)**; Machine Learning (cs.LG)

Cite as: arXiv:1406.2661 [stat.ML]  
(or arXiv:1406.2661v1 [stat.ML] for this version)  
<https://doi.org/10.48550/arXiv.1406.2661>

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- cs
- cs.LG
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### References & Citations

- NASA ADS
- Google Scholar
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59 blog links ([what is this?](#))

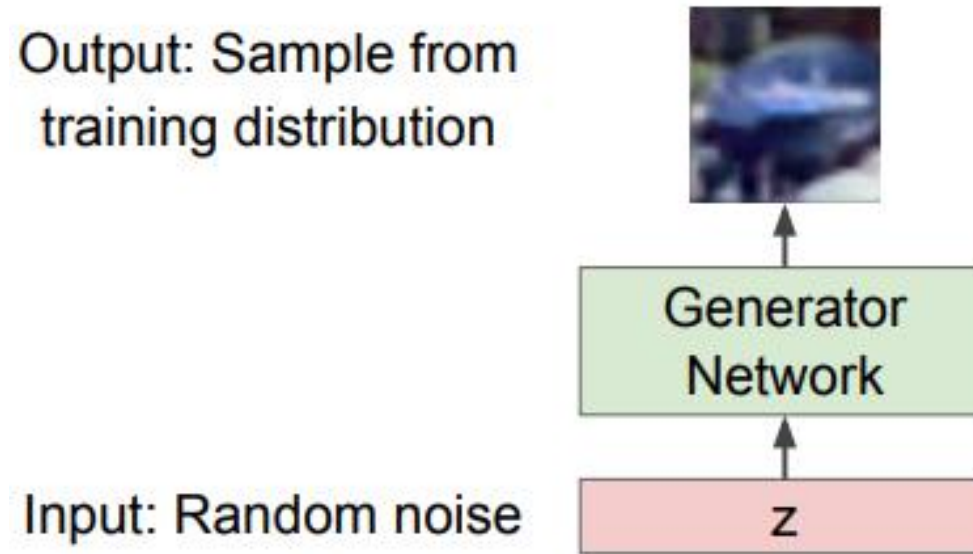


“the most interesting idea in the last 10 years in machine learning”,  
Yann LeCun, Chief AI Scientist at Facebook

# What is a Generative Adversarial Network?

- GAN for short
  - “Generative” = it generates/produces things
  - “Adversarial” = element of competition
  - “Network” = well, it’s a network

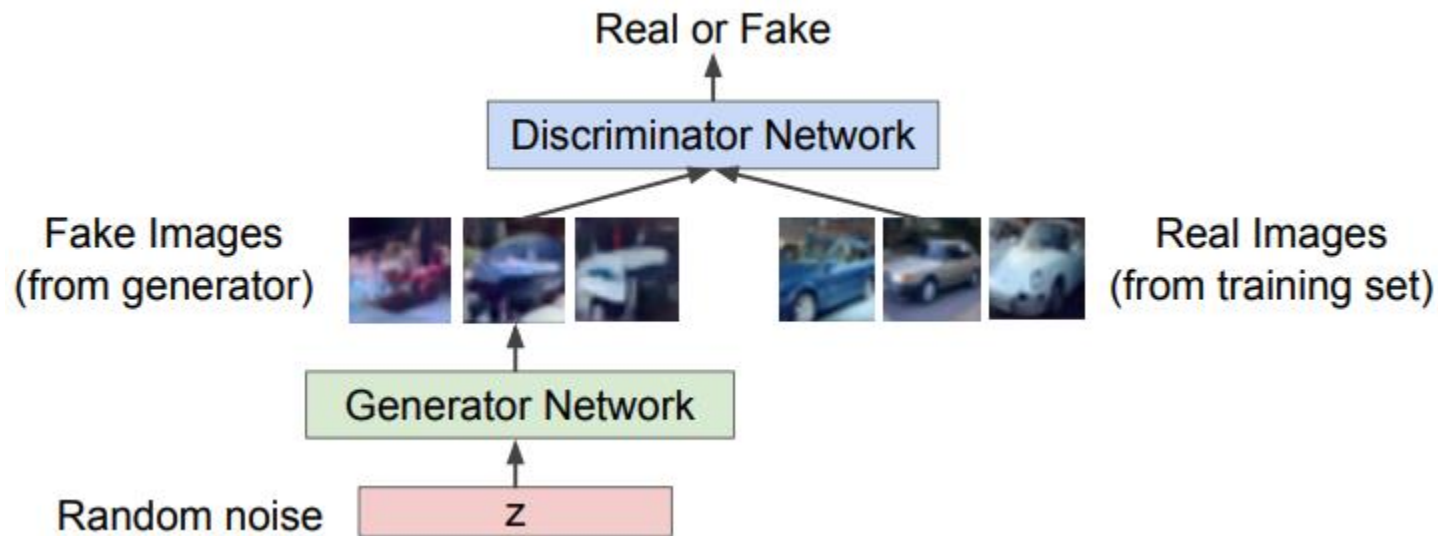
# Generative Adversarial Network



From Goodfellow et al, 2014, Generative Adversarial Networks

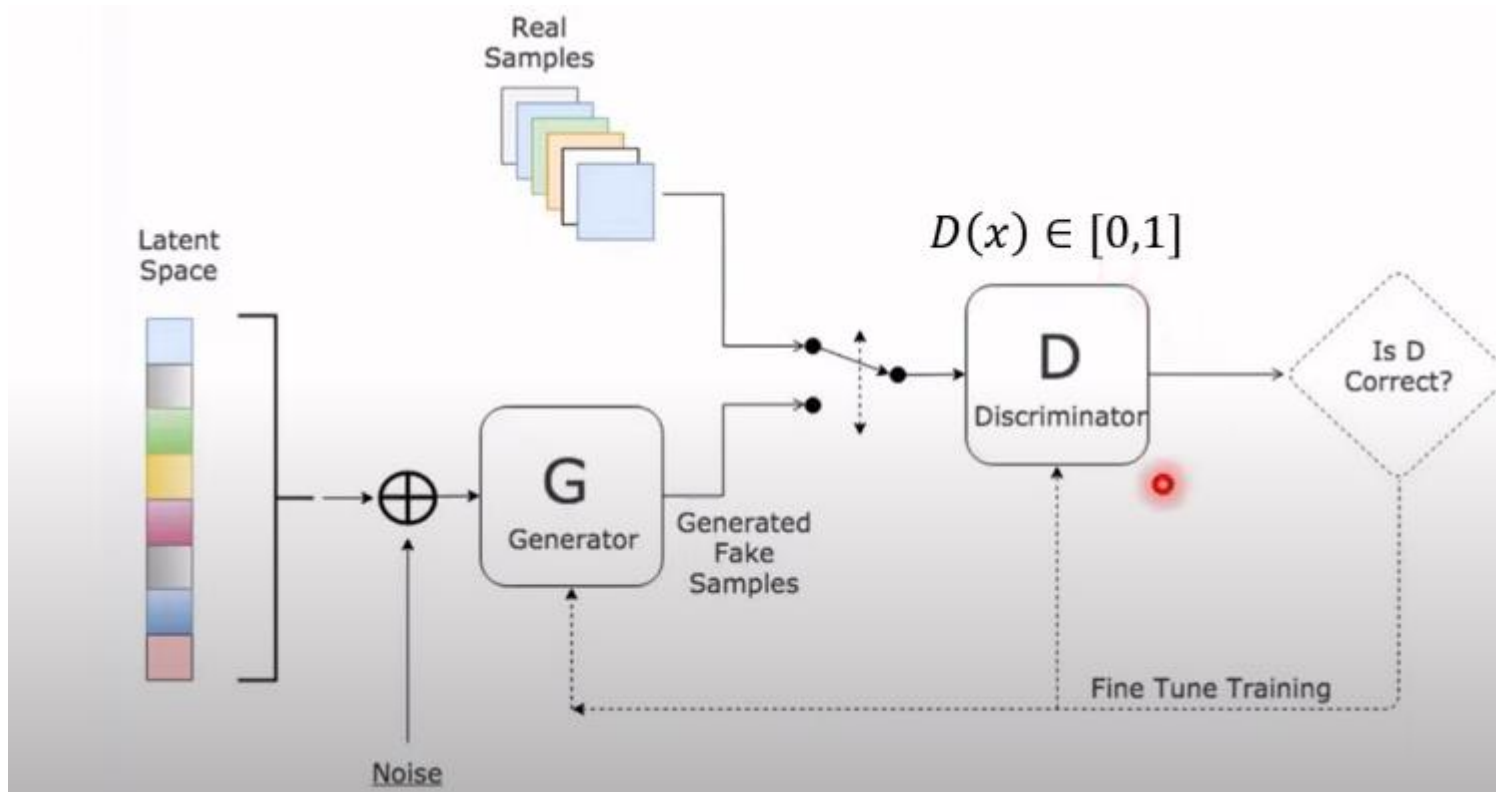
# Training GANs: Two –player game

- **Generator network:** try to fool the discriminator by generating real-looking images
- **Discriminator network:** try to distinguish between real and fake images





# Training GANs: Two –player game

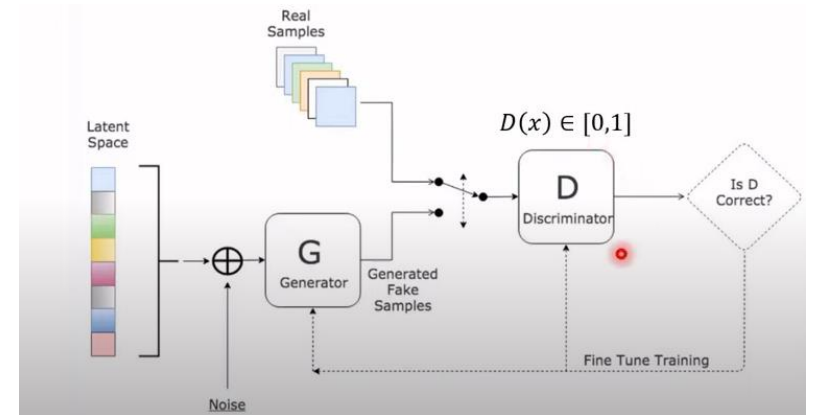


# Training GANs: Two –player game

- **Generator network:** try to fool the discriminator by generating real-looking images
- **Discriminator network:** try to distinguish between real and fake images
- Train Jointly in **minimax game:**
  - Minimax objective function:

$$\min_{\theta_g} \max_{\theta_d} \left[ \mathbb{E}_{x \sim p_{data}} \log \underbrace{D_{\theta_d}(x)}_{\substack{\text{Discriminator output} \\ \text{for real data } x}} + \mathbb{E}_{z \sim p(z)} \log(1 - \underbrace{D_{\theta_d}(G_{\theta_g}(z))}_{\substack{\text{Discriminator output for} \\ \text{generated fake data } G(z)}}) \right]$$

Discriminator outputs likelihood in (0,1) of real image



- Where,
  - $D(x)$  is the discriminator's estimate of the probability that real data instance  $x$  is real.
  - $\mathbb{E}_x$  is the expected value over all real data instances.
  - $G(z)$  is the generator's output when given noise  $z$ .
  - $D(G(z))$  is the discriminator's estimate of the probability that a fake instance is real.
  - $\mathbb{E}_z$  is the expected value over all random inputs to the generator (in effect, the expected value over all generated fake instances  $G(z)$ ).

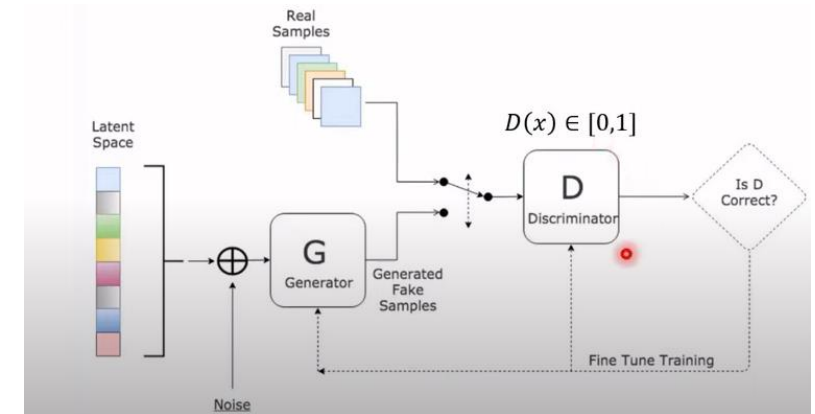
# Training GANs: Two –player game

- Minimax objective function:

$$\min_{\theta_g} \max_{\theta_d} \left[ \mathbb{E}_{x \sim p_{data}} \log D_{\theta_d}(x) + \mathbb{E}_{z \sim p(z)} \log(1 - D_{\theta_d}(G_{\theta_g}(z))) \right]$$

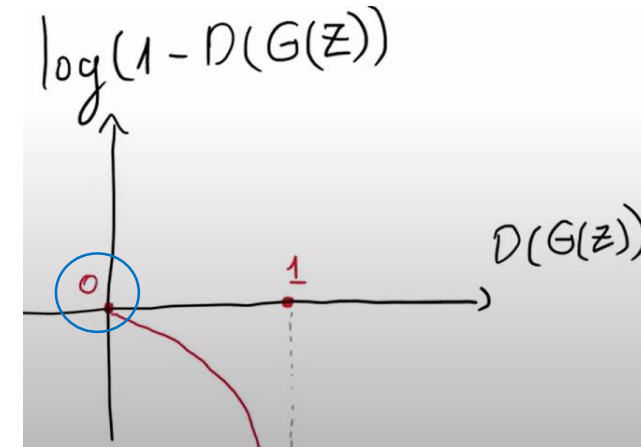
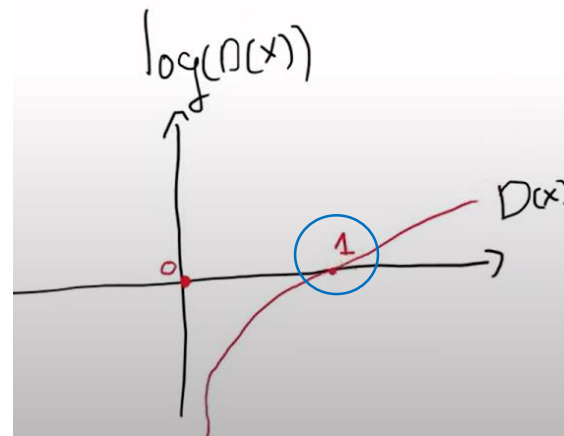
- Alternate between:

- 1. **Gradient ascent** on discriminator



$$\max_{\theta_d} \left[ \mathbb{E}_{x \sim p_{data}} \log D_{\theta_d}(x) + \mathbb{E}_{z \sim p(z)} \log(1 - D_{\theta_d}(G_{\theta_g}(z))) \right]$$

- The objective is to predict the real image is 1.
- The max value is when  $D(x)$  is 1.
- Thus the objective function needs to be maximized



- The objective is to predict the fake image is 0.
- The max value is when  $D(G(z))$  is zero.
- Thus the objective function needs to be maximized to get 0.

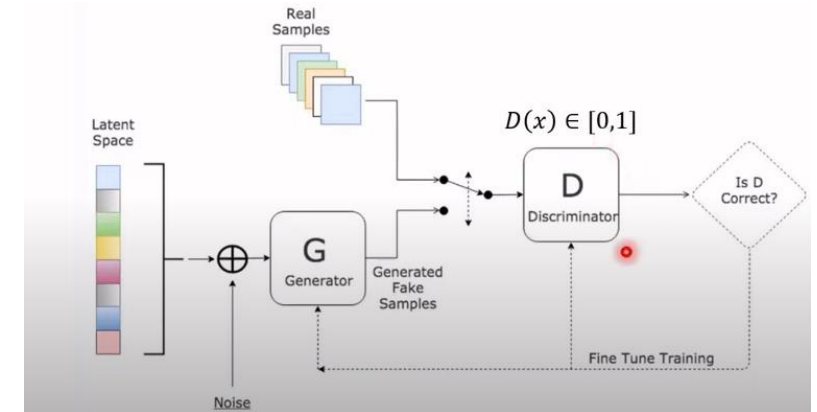
# Training GANs: Two –player game

- Minimax objective function:

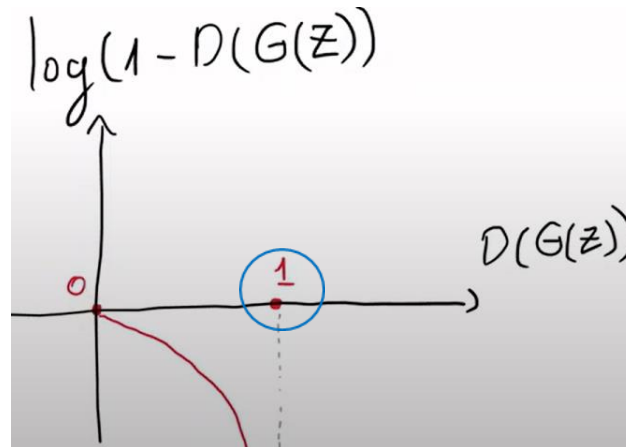
$$\min_{\theta_g} \max_{\theta_d} \left[ \mathbb{E}_{x \sim p_{data}} \log D_{\theta_d}(x) + \mathbb{E}_{z \sim p(z)} \log(1 - D_{\theta_d}(G_{\theta_g}(z))) \right]$$

- Alternate between:

- 1. Gradient descent on generator



$$\min_{\theta_g} \mathbb{E}_{z \sim p(z)} \log(1 - D_{\theta_d}(G_{\theta_g}(z)))$$



- The objective is to predict the fake image is 1.
- The  $D(G(z))$  is become 1 when the objective function is minimized.
- Thus the objective function needs to be minimized.

# Training GANs: Two –player game

- Minimax objective function:

$$\min_{\theta_g} \max_{\theta_d} \left[ \mathbb{E}_{x \sim p_{data}} \log D_{\theta_d}(x) + \mathbb{E}_{z \sim p(z)} \log(1 - D_{\theta_d}(G_{\theta_g}(z))) \right]$$

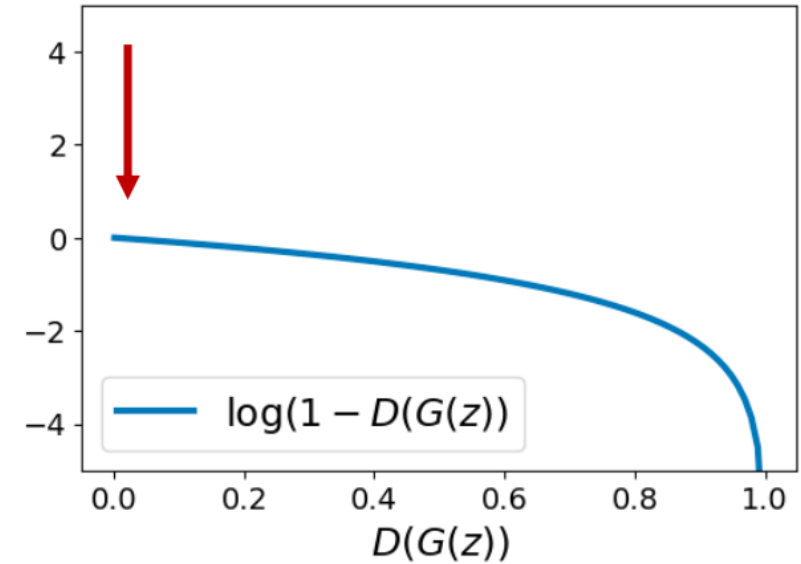
- Alternate between:

- 1. **Gradient ascent** on discriminator

$$\max_{\theta_d} \left[ \mathbb{E}_{x \sim p_{data}} \log D_{\theta_d}(x) + \mathbb{E}_{z \sim p(z)} \log(1 - D_{\theta_d}(G_{\theta_g}(z))) \right]$$

- 2. **Gradient descent** on generator

$$\min_{\theta_g} \mathbb{E}_{z \sim p(z)} \log(1 - D_{\theta_d}(G_{\theta_g}(z)))$$



At start of training, generator is very bad and discriminator can easily tell apart real/fake, so  $D(G(z))$  close to 0

Problem: Vanishing gradients for G

# Training GANs: Two –player game

- Minimax objective function:

$$\min_{\theta_g} \max_{\theta_d} \left[ \mathbb{E}_{x \sim p_{data}} \log D_{\theta_d}(x) + \mathbb{E}_{z \sim p(z)} \log(1 - D_{\theta_d}(G_{\theta_g}(z))) \right]$$

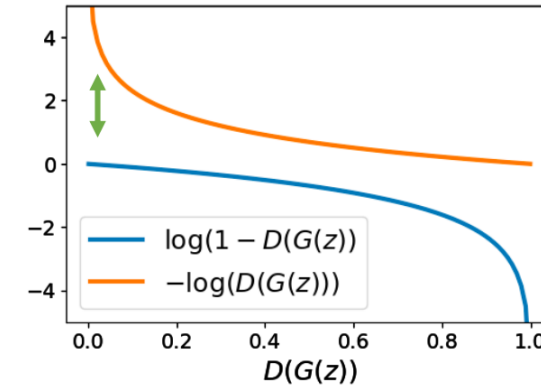
- Alternate between:

- 1. **Gradient ascent** on discriminator

$$\max_{\theta_d} \left[ \mathbb{E}_{x \sim p_{data}} \log D_{\theta_d}(x) + \mathbb{E}_{z \sim p(z)} \log(1 - D_{\theta_d}(G_{\theta_g}(z))) \right]$$

- 2. **Gradient ascent** on generator, **different objective**

$$\max_{\theta_g} \mathbb{E}_{z \sim p(z)} -\log(D_{\theta_d}(G_{\theta_g}(z)))$$



At start of training, generator is very bad and discriminator can easily tell apart real/fake, so  $D(G(z))$  close to 0

**Problem: Vanishing gradients for G**

**Solution:** Right now G is trained to minimize  $\log(1-D(G(z)))$ . Instead, train G to maximize  $-\log(D(G(z)))$ .

Then G gets strong gradients at start of training!

# Training GANs: Two –player game

- Minimax objective function:

$$\min_{\theta_g} \max_{\theta_d} \left[ \mathbb{E}_{x \sim p_{data}} \log D_{\theta_d}(x) + \mathbb{E}_{z \sim p(z)} \log(1 - D_{\theta_d}(G_{\theta_g}(z))) \right]$$

- Alternate between:

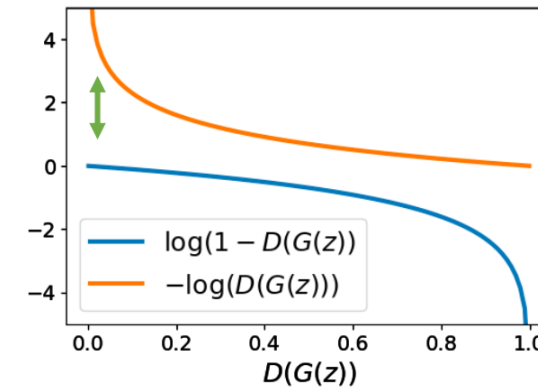
- 1. **Gradient ascent** on discriminator

$$\max_{\theta_d} \left[ \mathbb{E}_{x \sim p_{data}} \log D_{\theta_d}(x) + \mathbb{E}_{z \sim p(z)} \log(1 - D_{\theta_d}(G_{\theta_g}(z))) \right]$$

- 2. Gradient **ascent** on generator, **different objective**

$$\max_{\theta_g} \mathbb{E}_{z \sim p(z)} -\log(D_{\theta_d}(G_{\theta_g}(z)))$$

Aside: Jointly training two networks is challenging, can be unstable. Choosing objectives with better loss landscapes helps training, **is an active area of research.**



At start of training, generator is very bad and discriminator can easily tell apart real/fake, so  $D(G(z))$  close to 0

**Problem: Vanishing gradients for G**

**Solution:** Right now G is trained to minimize  $\log(1 - D(G(z)))$ . Instead, train G to maximize  $-\log(D(G(z)))$ .

Then G gets strong gradients at start of training!

From Goodfellow et al, 2014, Generative Adversarial Networks

# Training GANs: Two-player game

- Putting it together: GAN training algorithm

**for** number of training iterations **do**

**for**  $k$  steps **do**

- Sample minibatch of  $m$  noise samples  $\{\mathbf{z}^{(1)}, \dots, \mathbf{z}^{(m)}\}$  from noise prior  $p_g(\mathbf{z})$ .
- Sample minibatch of  $m$  examples  $\{\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(m)}\}$  from data generating distribution  $p_{\text{data}}(\mathbf{x})$ .
- Update the discriminator by ascending its stochastic gradient:

$$\nabla_{\theta_d} \frac{1}{m} \sum_{i=1}^m \left[ \log D_{\theta_d}(\mathbf{x}^{(i)}) + \log(1 - D_{\theta_d}(G_{\theta_g}(\mathbf{z}^{(i)}))) \right]$$

**end for**

- Sample minibatch of  $m$  noise samples  $\{\mathbf{z}^{(1)}, \dots, \mathbf{z}^{(m)}\}$  from noise prior  $p_g(\mathbf{z})$ .
- Update the generator by ascending its stochastic gradient (improved objective):

$$\nabla_{\theta_g} \frac{1}{m} \sum_{i=1}^m -\log(D_{\theta_d}(G_{\theta_g}(\mathbf{z}^{(i)})))$$

**end for**



# Training GANs: Two-player game

- Putting it together: GAN training algorithm

for number of training iterations do  
  for  $k$  steps do

Some find  $k=1$  more stable, others use  $k > 1$ , no best rule.

- Sample minibatch of  $m$  noise samples  $\{z^{(1)}, \dots, z^{(m)}\}$  from noise prior  $p_g(z)$ .
- Sample minibatch of  $m$  examples  $\{x^{(1)}, \dots, x^{(m)}\}$  from data generating distribution  $p_{\text{data}}(x)$ .
- Update the discriminator by ascending its stochastic gradient:

$$\nabla_{\theta_d} \frac{1}{m} \sum_{i=1}^m \left[ \log D_{\theta_d}(x^{(i)}) + \log(1 - D_{\theta_d}(G_{\theta_g}(z^{(i)}))) \right]$$

Recent work (e.g. Wasserstein GAN) alleviates this problem, better stability!

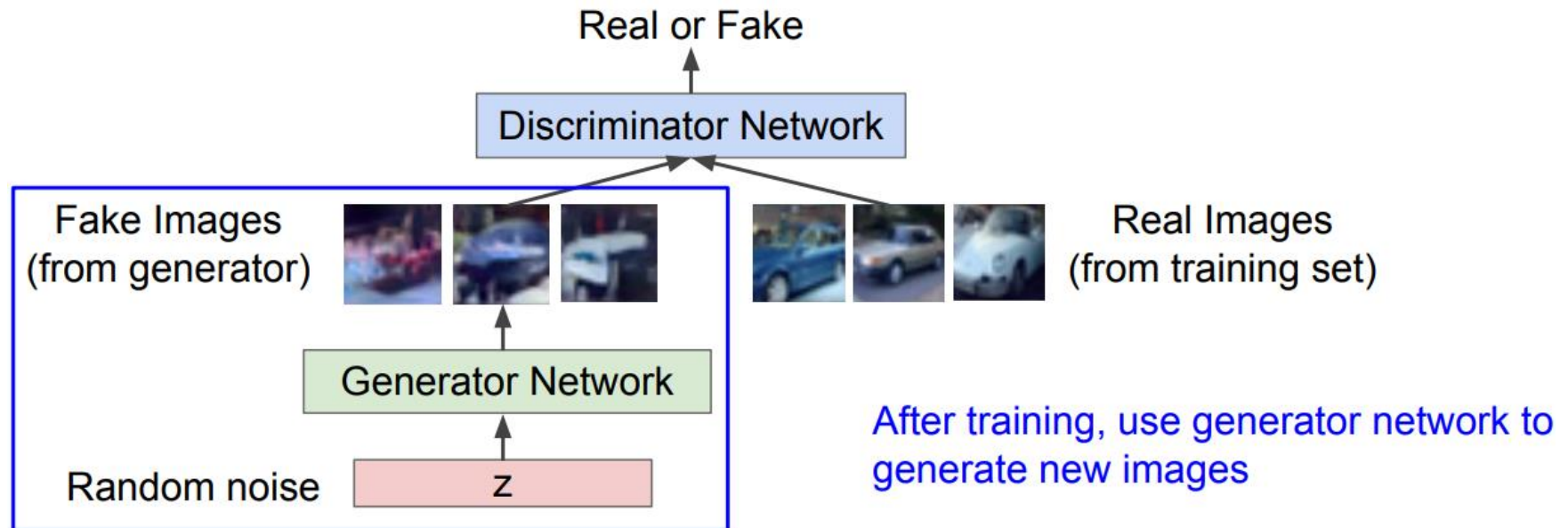
- Update the generator by ascending its stochastic gradient (improved objective):

$$\nabla_{\theta_g} \frac{1}{m} \sum_{i=1}^m \log(D_{\theta_d}(G_{\theta_g}(z^{(i)})))$$

end for  
end for

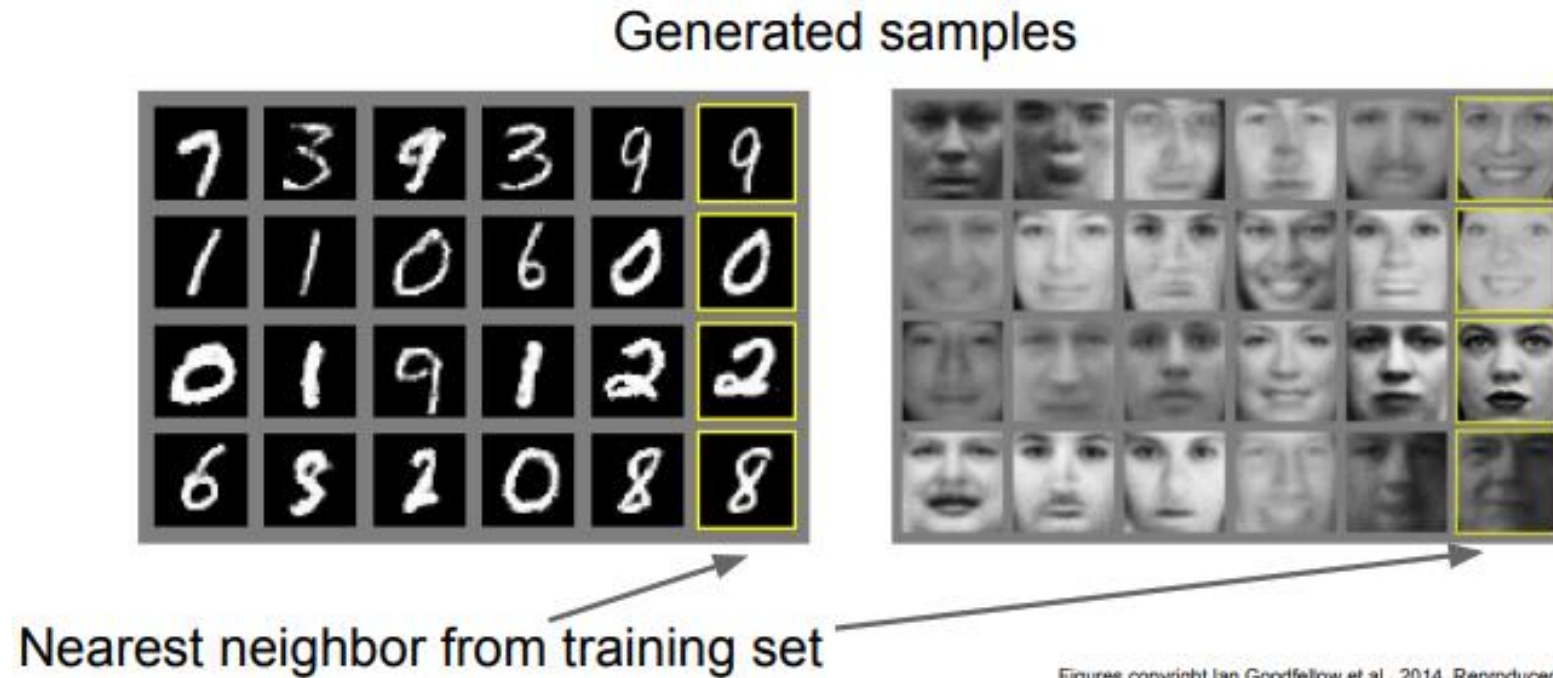
# Training GANs: Two-player game

- **Generator network:** try to fool the discriminator by generating real-looking images
- **Discriminator network:** try to distinguish between real and fake images



# Generative Adversarial Nets

Ian Goodfellow et al., "Generative Adversarial Nets", NIPS 2014



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# Generative Adversarial Nets

Ian Goodfellow et al., “Generative Adversarial Nets”, NIPS 2014

Generated samples (CIFAR-10)

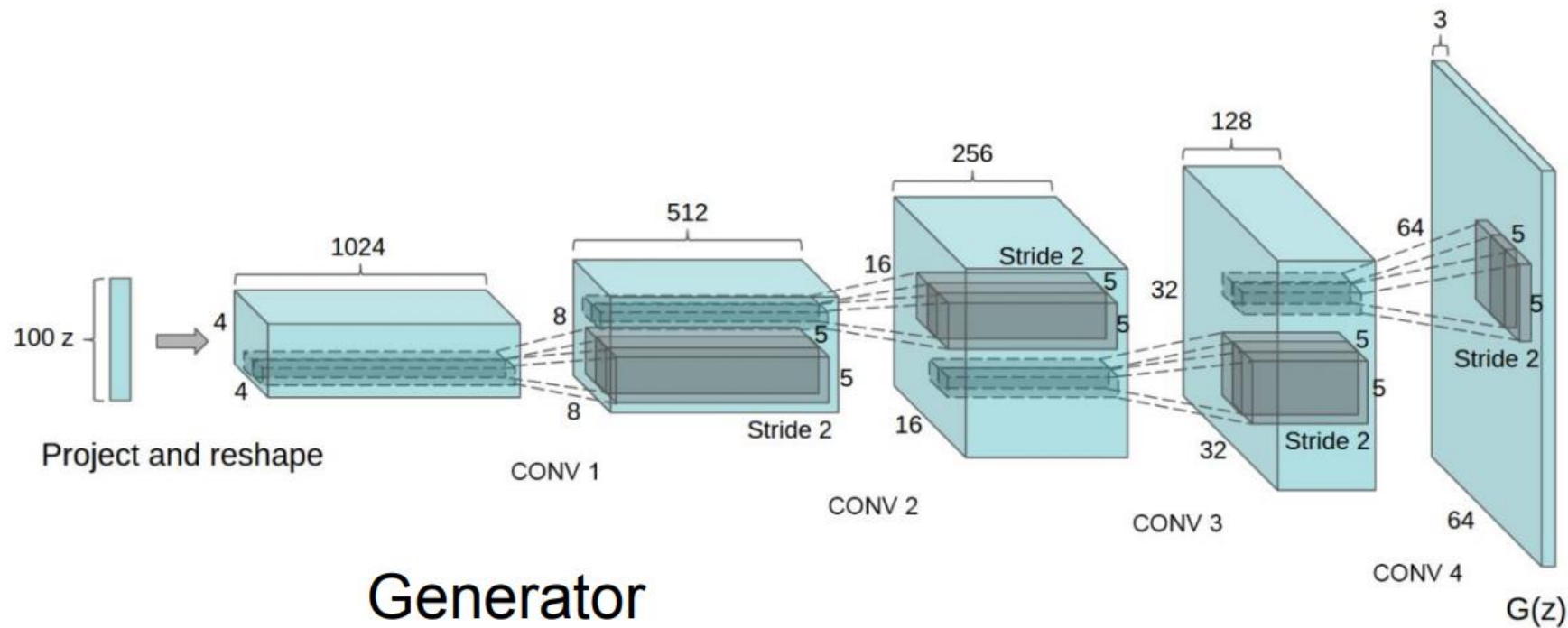


Nearest neighbor from training set

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# Generative Adversarial Nets: Deep Convolutional (DC)-GAN

- Generator is an upsampling network with **fractionally-strided convolutions**  
Discriminator is a **convolutional network**.





# Generative Adversarial Nets: DC-GAN

Samples  
from the  
model look  
amazing!

Radford et al,  
ICLR 2016



# Generative Adversarial Nets: Interpolation

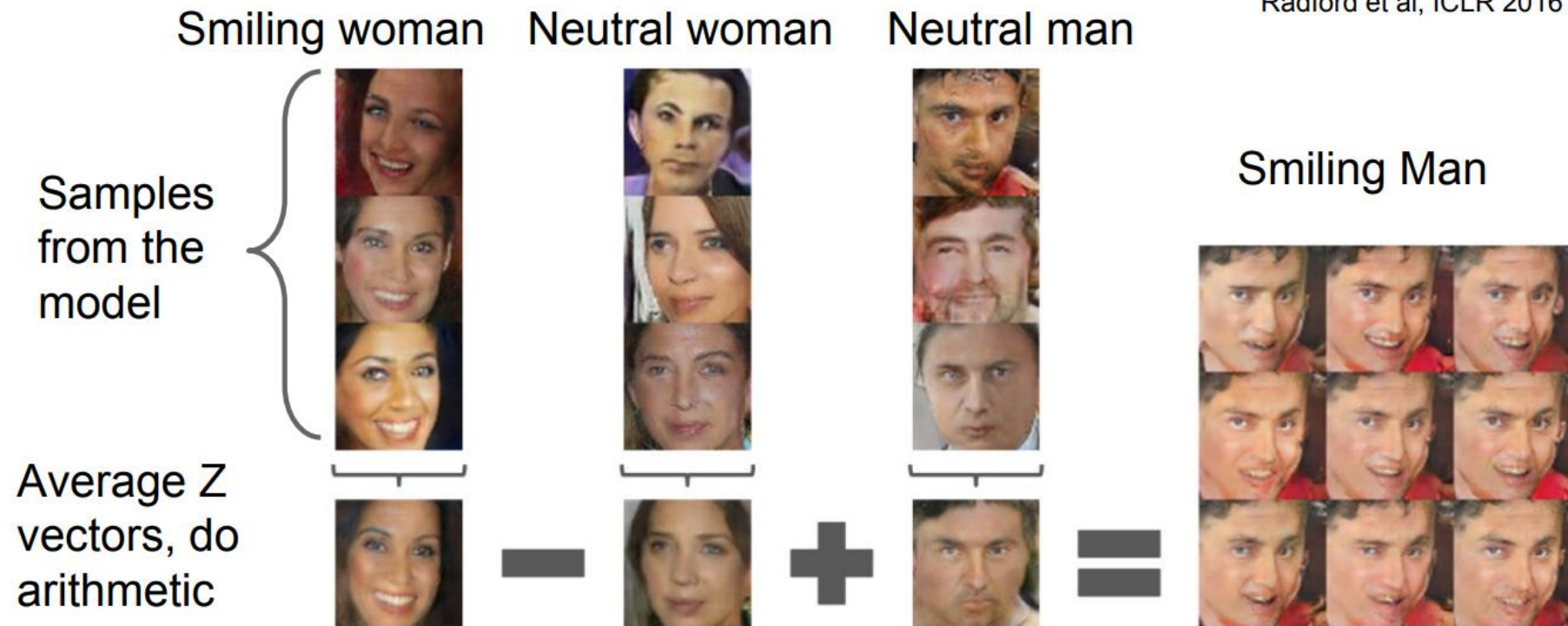
Interpolating  
between points in  
latent  $z$  space.





# Generative Adversarial Nets: Interpretable Vector Math

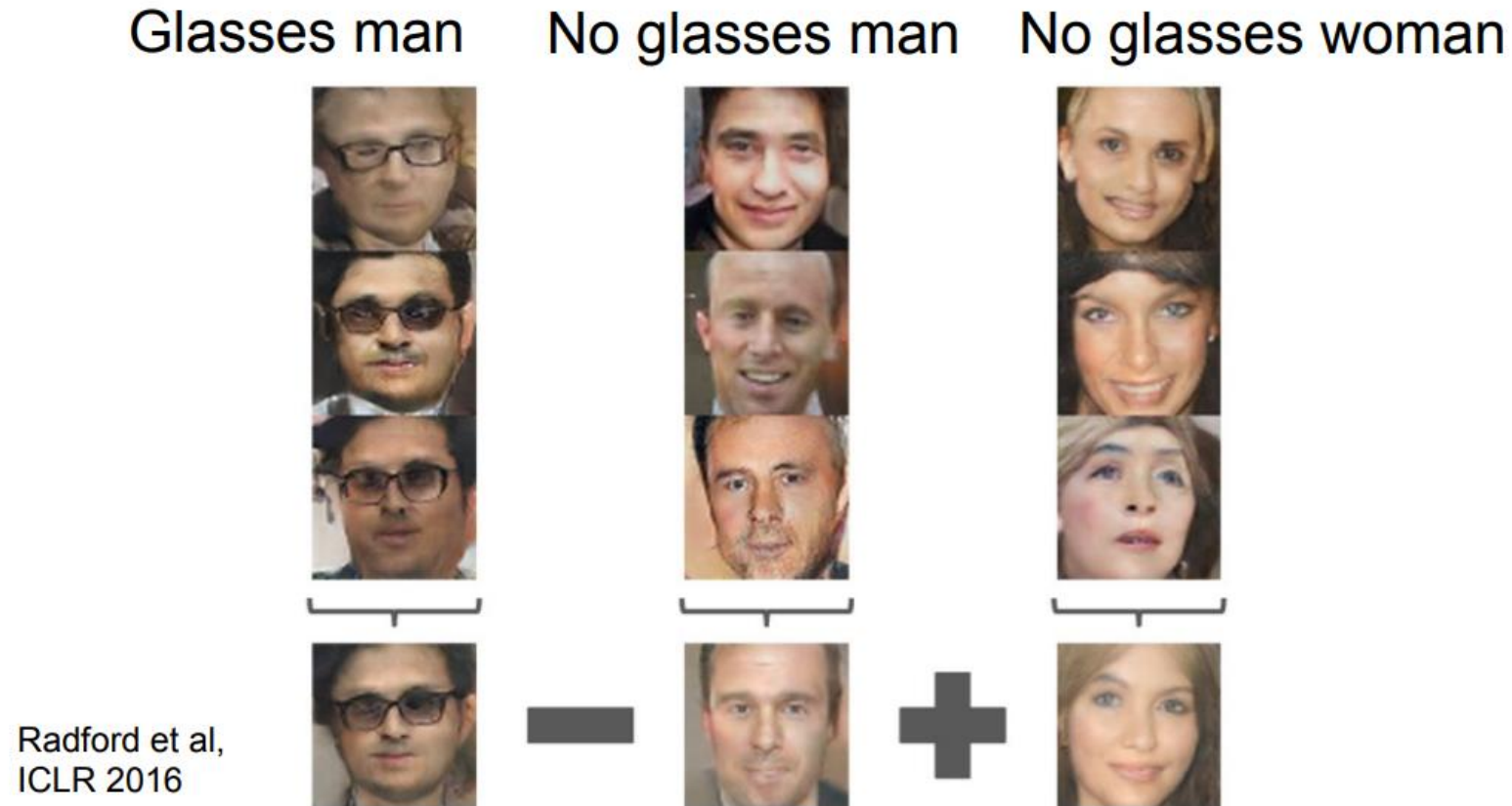
Radford et al, ICLR 2016



$$z_{\text{smiling\_man}} = \text{avg}(z_{\text{smiling\_women}}) - \text{avg}(z_{\text{neutral\_women}}) + \text{avg}(z_{\text{neutral\_men}})$$



# Generative Adversarial Nets: Interpretable Vector Math



# Generative Adversarial Nets: Interpretable Vector Math

Glasses man



No glasses man



No glasses woman



Radford et al,  
ICLR 2016

Woman with glasses

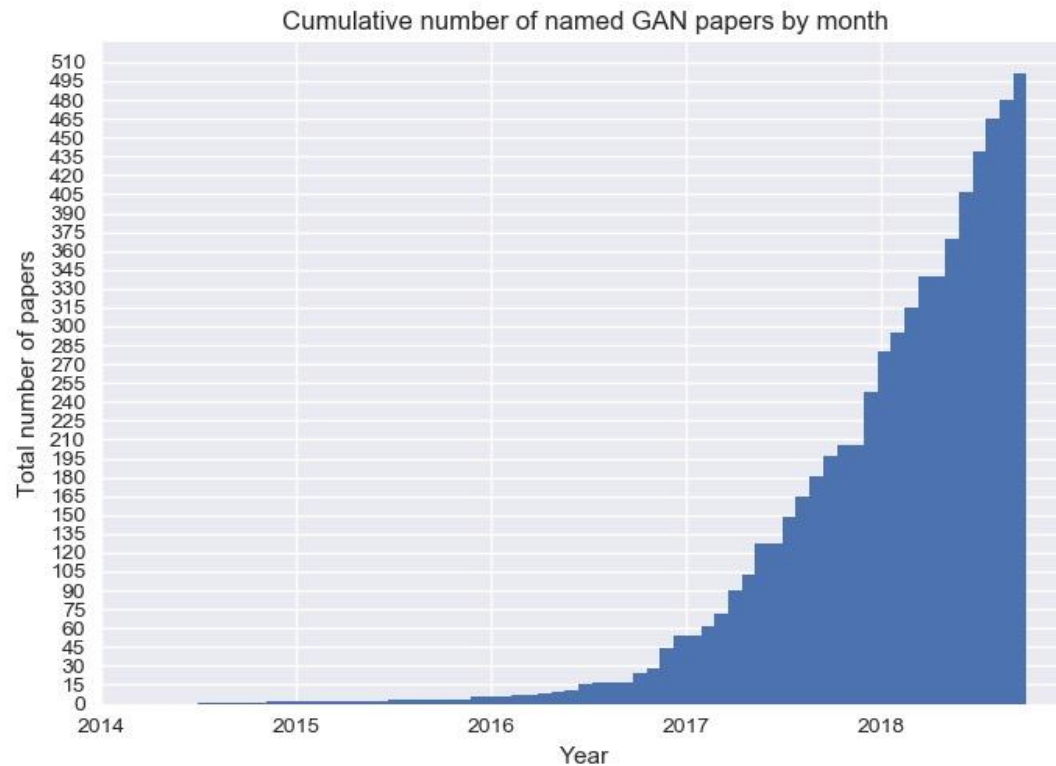


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# 2017 to present: Explosion of GANs



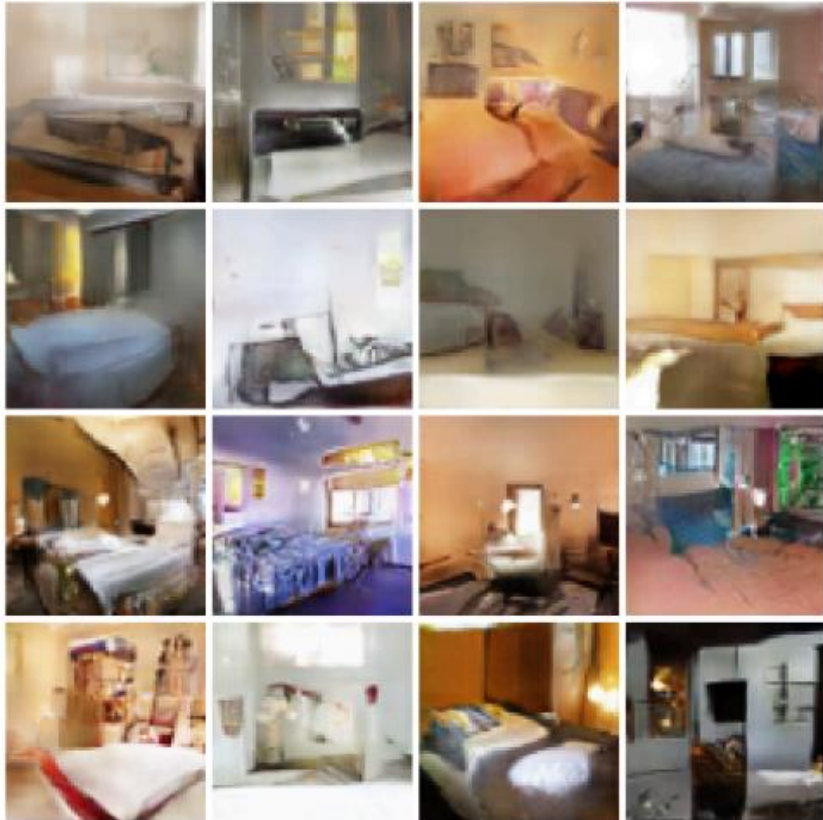
- 3D-ED-GAN - Shape inpainting using 3D Generative Adversarial Network and Recurrent Convolutional Networks
- 3D-GAN - Learning a Probabilistic Latent Space of Object Shapes via 3D Generative-Adversarial Modeling (github)
- 3D-rwGAN - Improved Adversarial Systems for 3D Object Generation and Reconstruction (github)
- 3D-PhysNet - 3D-PhysNet: Learning the Intuitive Physics of Non-Rigid Object Deformations
- 3D-RecGAN - 3D Object Reconstruction from a Single Depth View with Adversarial Learning (github)
- ABC-GAN - ABC-GAN: Adaptive Blur and Control for Improved training stability of Generative Adversarial Networks (github)
- ABC-GAN - GANs for LIFE: Generative Adversarial Networks for Likelihood Free Inference
- AC-GAN - Conditional Image Synthesis With Auxiliary Classifier GANs
- acGAN - Face Aging With Conditional Generative Adversarial Networks
- ACGAN - Coverless Information Hiding Based on Generative adversarial networks
- acGAN - On-line Adaptive Curriculum Learning for GANs
- ActUAL - ActUAL: Actor-Critic Under Adversarial Learning
- AdaGAN - AdaGAN: Boosting Generative Models
- Adaptive GAN - Customizing an Adversarial Example Generator with Class-Conditional GANs
- AdvEntRite - AdvEntRite: Adversarial Training for Textual Entailment with Knowledge-Guided Examples
- AdvGAN - Generating adversarial examples with adversarial networks
- AE-GAN - AE-GAN: adversarial eliminating with GAN
- AE-OT - Latent Space Optimal Transport for Generative Models
- AEGAN - Learning Inverse Mapping by Autoencoder based Generative Adversarial Nets
- AF-DCGAN - AF-DCGAN: Amplitude Feature Deep Convolutional GAN for Fingerprint Construction in Indoor Localization System
- AtGAN - Amortised MAP Inference for Image Super-resolution
- AIM - Generating Informative and Diverse Conversational Responses via Adversarial Information Maximization
- AL-CGAN - Learning to Generate Images of Outdoor Scenes from Attributes and Semantic Layouts
- ALI - Adversarially Learned Inference (github)
- AlignGAN - AlignGAN: Learning to Align Cross-Domain Images with Conditional Generative Adversarial Networks
- AlphaGAN - AlphaGAN: Generative adversarial networks for natural image matting
- AM-GAN - Activation Maximization Generative Adversarial Nets
- AmbientGAN - AmbientGAN: Generative models from lossy measurements (github)
- AMC-GAN - Video Prediction with Appearance and Motion Conditions
- AnGAN - Unsupervised Anomaly Detection with Generative Adversarial Networks to Guide Marker Discovery
- APD - Adversarial Distillation of Bayesian Neural Network Posteriors
- APE-GAN - APE-GAN: Adversarial Perturbation Elimination with GAN
- ARAE - Adversarially Regularized Autoencoders for Generating Discrete Structures (github)
- ARDA - Adversarial Representation Learning for Domain Adaptation
- ARIGAN - ARIGAN: Synthetic Arabidopsis Plants using Generative Adversarial Network
- ArtGAN - ArtGAN: Artwork Synthesis with Conditional Generative Adversarial Networks
- ASDL-GAN - Automatic Steganographic Distortion Learning Using a Generative Adversarial Network
- ATA-GAN - Attention-Aware Generative Adversarial Networks (ATA-GANs)
- Attention-GAN - Attention-GAN for Object Transfiguration in Wild Images
- AttGAN - Arbitrary Facial Attribute Editing: Only Change What You Want (github)
- AttGAN - AttGAN: Fine-Grained Text to Image Generation with Attentional Generative Adversarial Networks (github)
- AVID - AVID: Adversarial Visual Irregularity Detection
- B-DCGAN - B-DCGAN: Evaluation of Binarized DCGAN for FPGA
- b-GAN - Generative Adversarial Nets from a Density Ratio Estimation Perspective
- BAGAN - BAGAN: Data Augmentation with Balancing GAN
- Bayesian GAN - Deep and Hierarchical Implicit Models
- Bayesian GAN - Bayesian GAN (github)
- BCGAN - Bayesian Conditional Generative Adversarial Networks
- BCGAN - Bidirectional Conditional Generative Adversarial networks
- BEAM - Boltzmann Encoded Adversarial Machines
- BEGAN - BEGAN: Boundary Equilibrium Generative Adversarial Networks
- BEGAN-CS - Escaping from Collapsing Modes in a Constrained Space
- Belman GAN - Distributional Multivariate Policy Evaluation and Exploration with the Belman
- BGAN - Binary Generative Adversarial Networks for Image Retrieval (github)
- Bi-GAN - Autonomously and Simultaneously Refining Deep Neural Network Parameters by a Bi-Generative Adversarial Network Aided Genetic Algorithm
- BicycleGAN - Toward Multimodal Image-to-Image Translation (github)
- BiGAN - Adversarial Feature Learning
- BiGAN - BiGAN: Learning Compact Binary Descriptors with a Regularized GAN
- BourGAN - BourGAN: Generative Networks with Metric Embeddings
- BranchGAN - Branched Generative Adversarial Networks for Multi-Scale Image Manifold Learning
- BRE - Improving GAN Training via Binarized Representation Entropy (BRE) Regularization (github)
- BridgeGAN - Generative Adversarial Frontal View to Bird View Synthesis
- BS-GAN - Boundary-Seeking Generative Adversarial Networks
- BubGAN - BubGAN: Bubble Generative Adversarial Networks for Synthesizing Realistic Bubbly Flow Images
- BWGAN - Barach Wasserstein GAN
- C-GAN - Face Aging with Contextual Generative Adversarial Nets
- C-RNN-GAN - C-RNN-GAN: Continuous recurrent neural networks with adversarial training (github)
- CA-GAN - Composition-aided Sketch-realistic Portrait Generation
- CalGAN - CalGAN: Simulating 3D High Energy Particle Showers in Multi-Layer Electromagnetic Calorimeters with Generative Adversarial Networks (github)
- CAN - CAN: Creative Adversarial Networks, Generating Art by Learning About Styles and Deviating from Style Norms
- CapGAN - CapGAN: Using Dynamic Routing for Generative Adversarial Networks
- CapsuleGAN - CapsuleGAN: Generative Adversarial Capsule Network
- CatGAN - Unsupervised and Semi-supervised Learning with Categorical Generative Adversarial Networks
- CatGAN - CatGAN: Coupled Adversarial Transfer for Domain Generation
- CausalGAN - CausalGAN: Learning Causal Implicit Generative Models with Adversarial Training
- CC-GAN - Semi-Supervised Learning with Context-Conditional Generative Adversarial Networks (github)
- cG-GAN - Conditional Image-to-Image Translation
- CDGAN - Simultaneously Color-Depth Super-Resolution with Conditional Generative Adversarial Network
- CE-GAN - Deep Learning for Imbalance Data Classification using Class Expert Generative Adversarial Network
- CFG-GAN - Composite Functional Gradient Learning of Generative Adversarial Models
- CGAN - Conditional Generative Adversarial Nets
- CGAN - Controllable Generative Adversarial Network
- Chekhov GAN - An Online Learning Approach to Generative Adversarial Networks
- cGAN - Conditional Infilling GANs for Data Augmentation in Mammogram Classification
- CnCGAN - Unsupervised Image Super-Resolution using Cycle-in-Cycle Generative Adversarial Networks
- CipherGAN - Unsupervised Cipher Cracking Using Discrete GANs
- ClusterGAN - ClusterGAN: Latent Space Clustering in Generative Adversarial Networks
- CM-GAN - CM-GANs: Cross-modal Generative Adversarial Networks for Common Representation Learning
- CoAtt-GAN - Are You Talking to Me? Reasoned Visual Dialog Generation through Adversarial Learning
- CoGAN - Coupled Generative Adversarial Networks
- CombaGAN - CombaGAN: Unrestricted Scalability for Image Domain Translation (github)
- ConceptGAN - Learning Compositional Visual Concepts with Mutual Consistency
- Conditional CycleGAN - Conditional CycleGAN for Attribute Guided Face Image Generation
- contrast-GAN - Generative Semantic Manipulation with Contrasting GAN
- Context-RNN-GAN - Contextual RNN-GANs for Abstract Reasoning Diagram Generation
- CorrGAN - Correlated discrete data generation using adversarial training
- Coulomb GAN - Coulomb GANs: Provably Optimal Nash Equilibria via Potential Fields
- Cover-GAN - Generative Steganography with Kerckhoffs' Principle based on Generative Adversarial Networks
- cowboy - Defending Against Adversarial Attacks by Leveraging an Entire GAN
- CR-GAN - CR-GAN: Learning Complete Representations for Multi-view Generation
- Cramer GAN - The Cramer Distance as a Solution to Biased Wasserstein Gradients
- Cross-GAN - Crossing Generative Adversarial Networks for Cross-View Person Re-identification
- crVAE-GAN - Channel-Recurrent Variational Autoencoders
- CS-GAN - Improving Neural Machine Translation with Conditional Sequence Generative Adversarial Nets
- CSG - Speech-Driven Expressive Talking Lips with Conditional Sequential Generative Adversarial Networks
- CT-GAN - CT-GAN: Conditional Transformation Generative Adversarial Network for Image Attribute Modification
- CVAE-GAN - CVAE-GAN: Fine-Grained Image Generation through Asymmetric Training
- CycleGAN - Unpaired Image-to-Image Translation using Cycle-Consistent Adversarial Networks

<https://github.com/hindupuravinash/the-gan-zoo?tab=readme-ov-file>



# GAN Improvements: Improved Loss Functions

## Wasserstein GAN (WGAN)



Arjovsky, Chintala, and Bottou, "Wasserstein GAN", 2017

## WGAN with Gradient Penalty (WGAN-GP)



Gulrajani et al, "Improved Training of Wasserstein GANs", NeurIPS 2017

# GAN Improvements: Higher Resolution

256 x 256 bedrooms



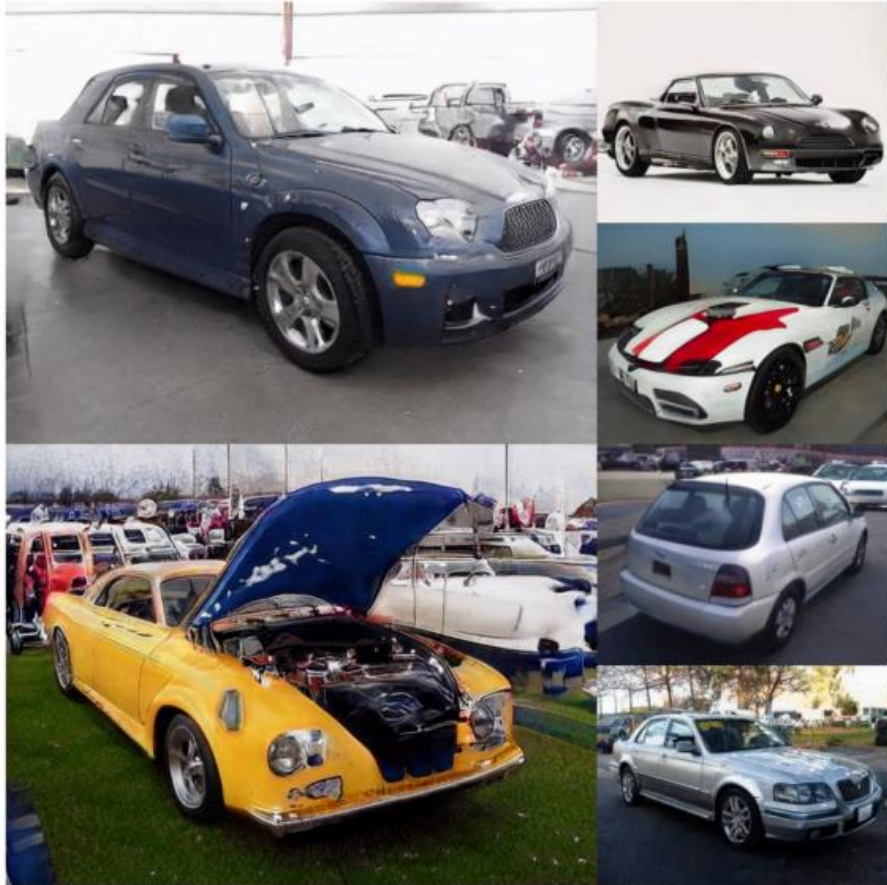
1024 x 1024 faces





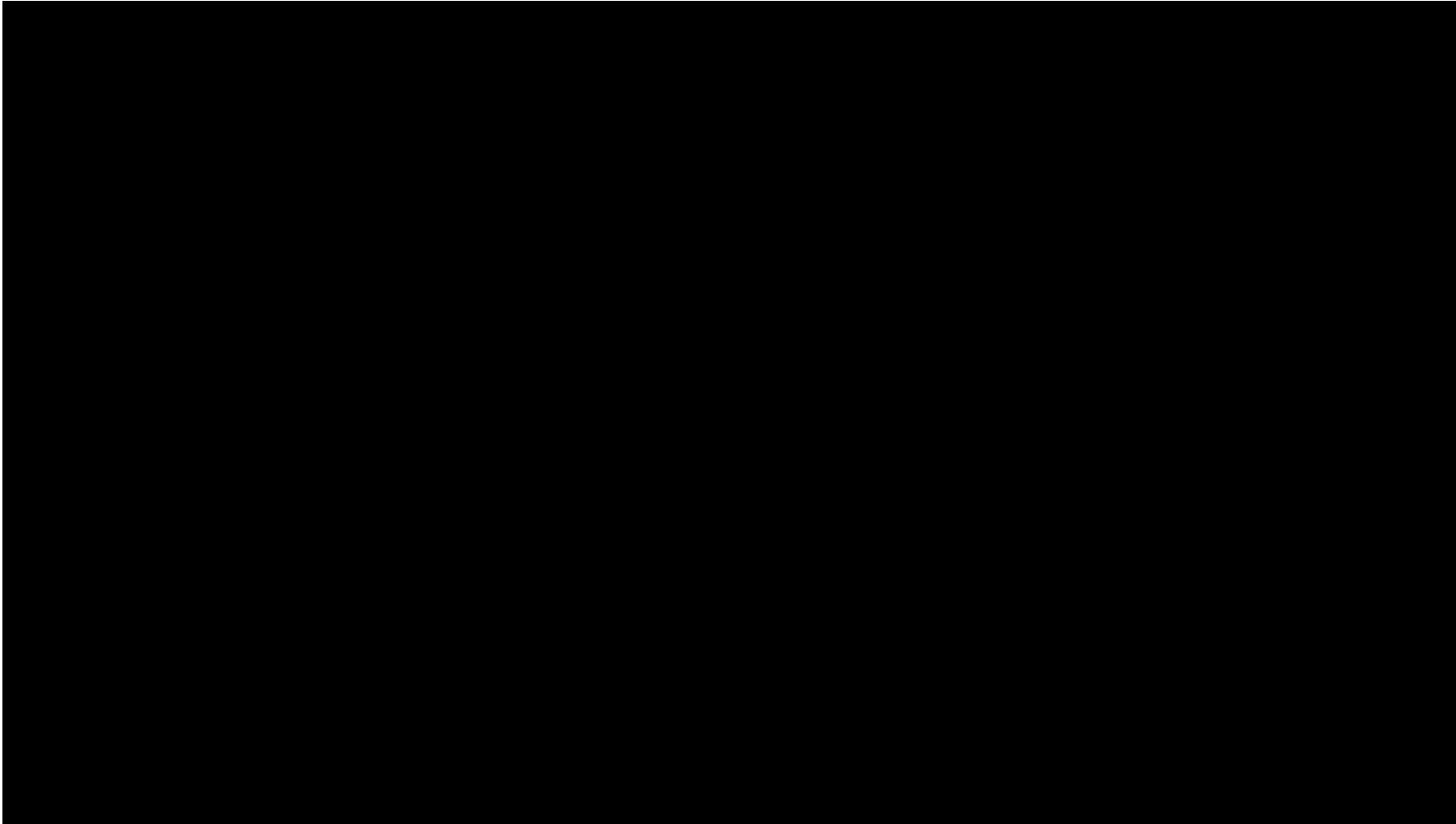
# GAN Improvements: Higher Resolution

512 x 384 cars



1024 x 1024 faces

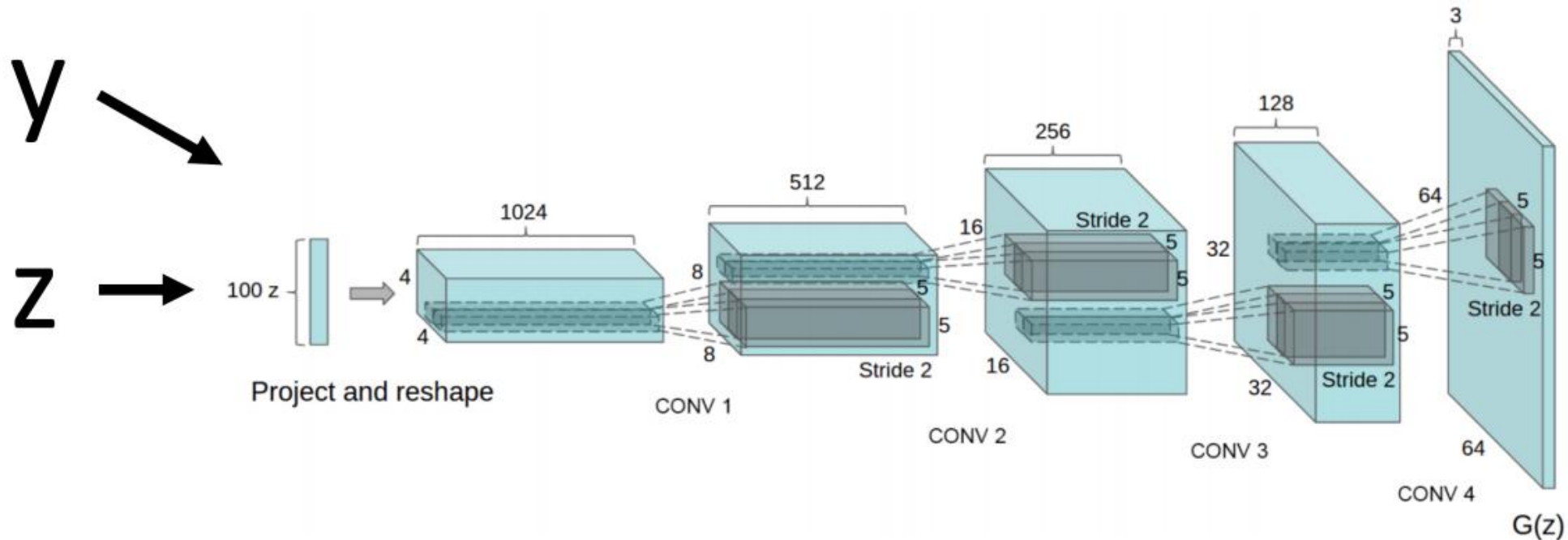




- Interpolating the latent space to the high resolution that has been generated by style GAN.

# Conditional GANs

- Make generator and discriminator both take label  $y$  as an additional input!





# Conditional GANs: Spectral Normalization

Welsh springer spaniel



Fire truck



Daisy



- We give the model both random noise and which category want to generate.

128x128 images on ImageNet



# Conditional GANs: Self-Attention

Goldfish



Indigo bunting



Redshank



Saint Bernard



128x128 images on ImageNet

# Conditional GANs: BigGAN

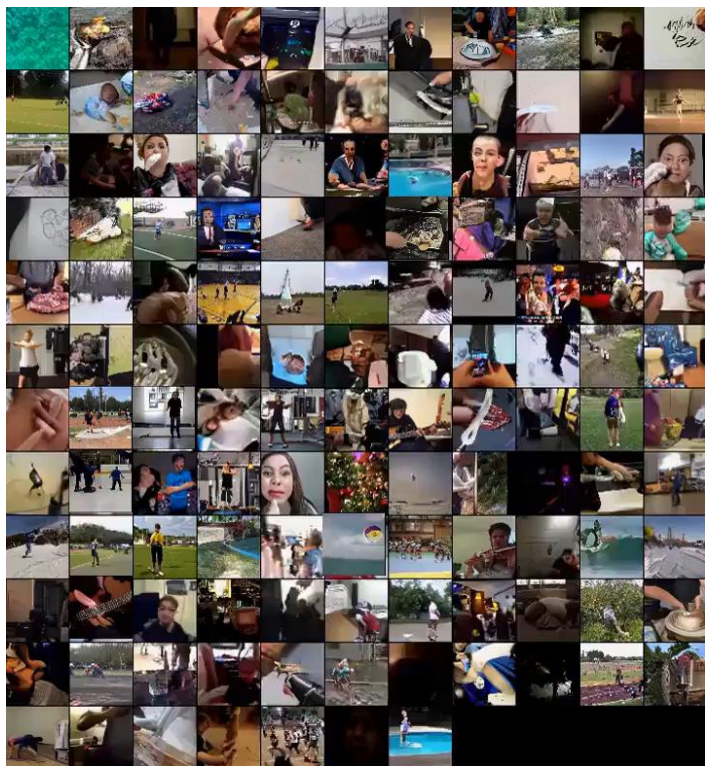


512x512 images on ImageNet

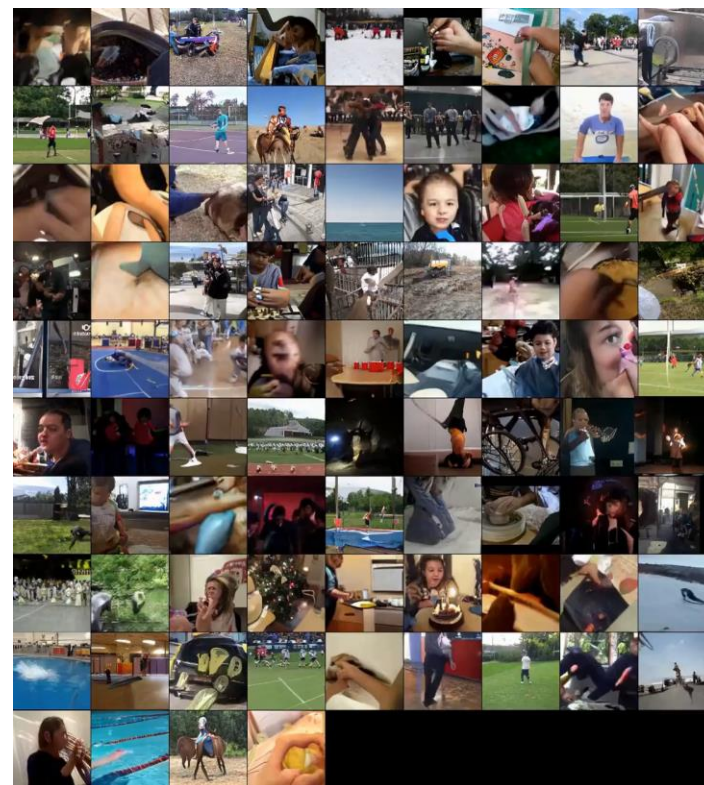


# Generating Videos with GANs

Clark et al, "Adversarial Video  
Generation on Complex  
Datasets", arXiv 2019



64x64 images, 48 frames



128x128 images, 12 frames

<https://drive.google.com/file/d/1FjOQYdUuxPXvS8yeOhXdPQMapUQakLI/view>

[https://drive.google.com/file/d/165Yxuvvu3viOy-39LhhSDGtczbWphj\\_i/view](https://drive.google.com/file/d/165Yxuvvu3viOy-39LhhSDGtczbWphj_i/view)

# Conditioning on more than labels! Text to Image



Zhang et al, "StackGAN++: Realistic Image Synthesis with Stacked Generative Adversarial Networks.", TPAMI 2018

Zhang et al, "StackGAN: Synthesis with Stacked Generative Adversarial Networks.", ICCV 2017

Reed et al, "Generative Adversarial Text-to-Image Synthesis", ICML 2016



# Image Super-Resolution: Low-Res to High-Res

bicubic  
(21.59dB/0.6423)



SRResNet  
(23.53dB/0.7832)



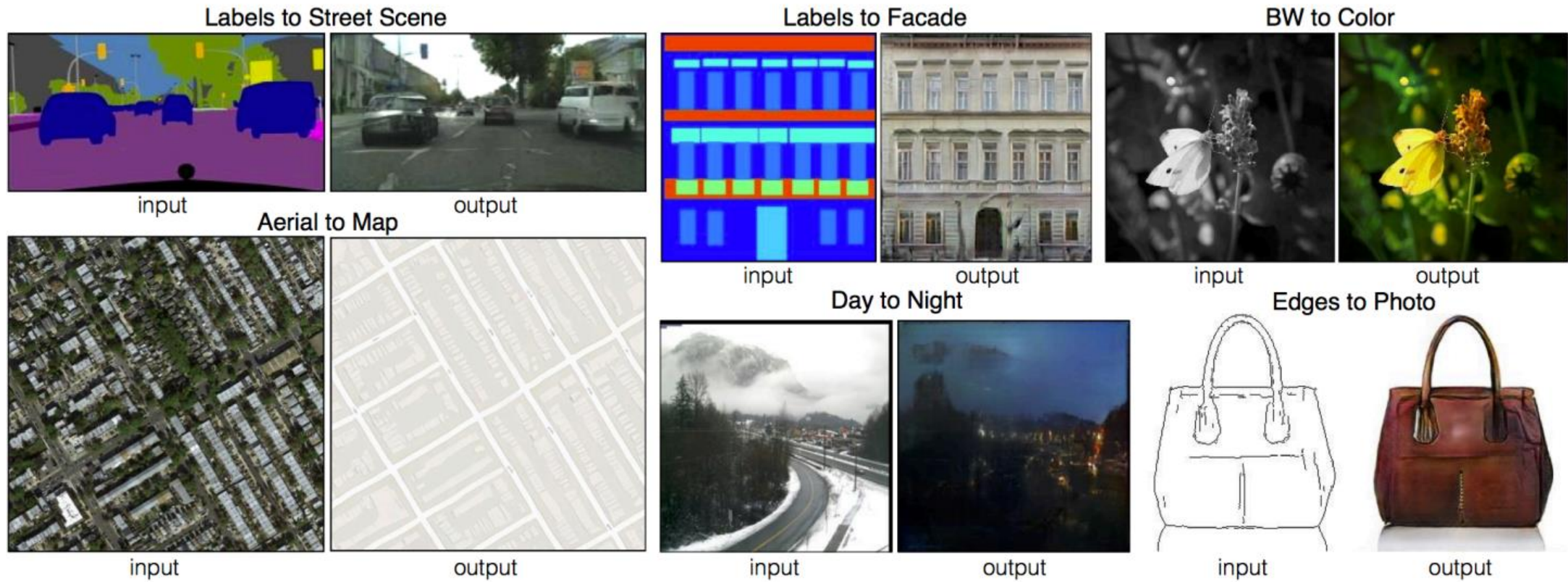
SRGAN  
(21.15dB/0.6868)



original



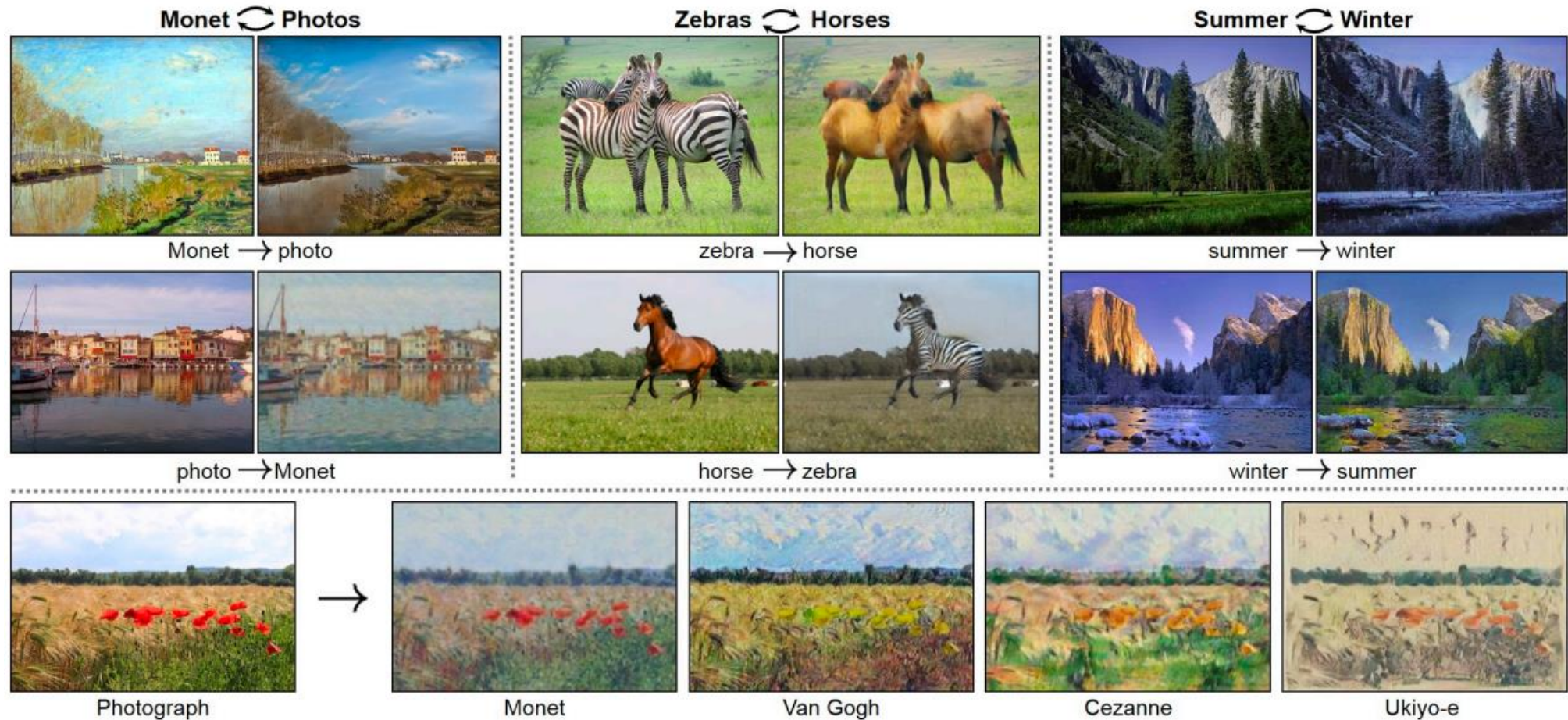
# Image-to-Image Translation: Pix2Pix



Isola et al, "Image-to-Image Translation with Conditional Adversarial Nets", CVPR 2017



# Unpaired Image-to-Image Translation: CycleGAN





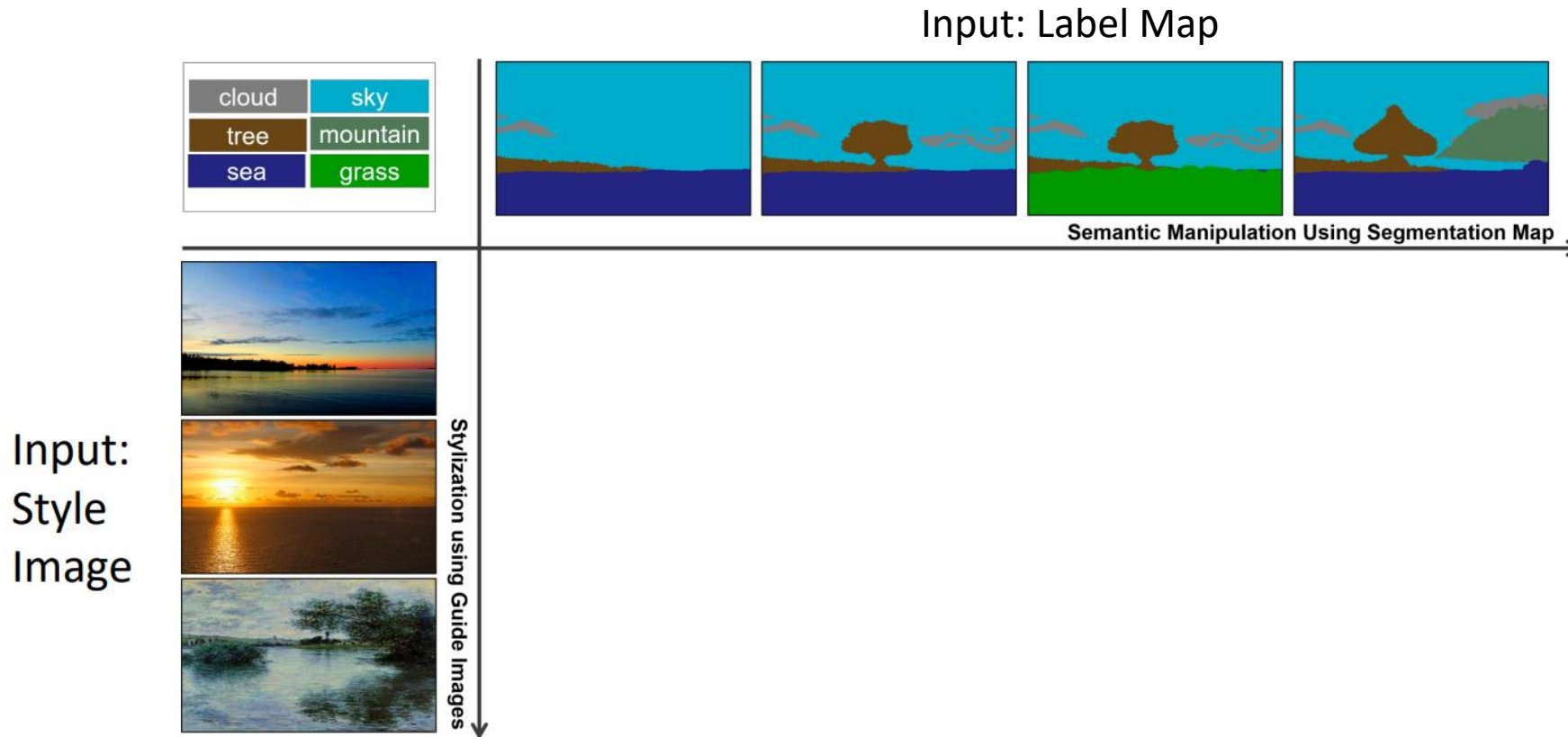
# Unpaired Image-to-Image Translation: CycleGAN



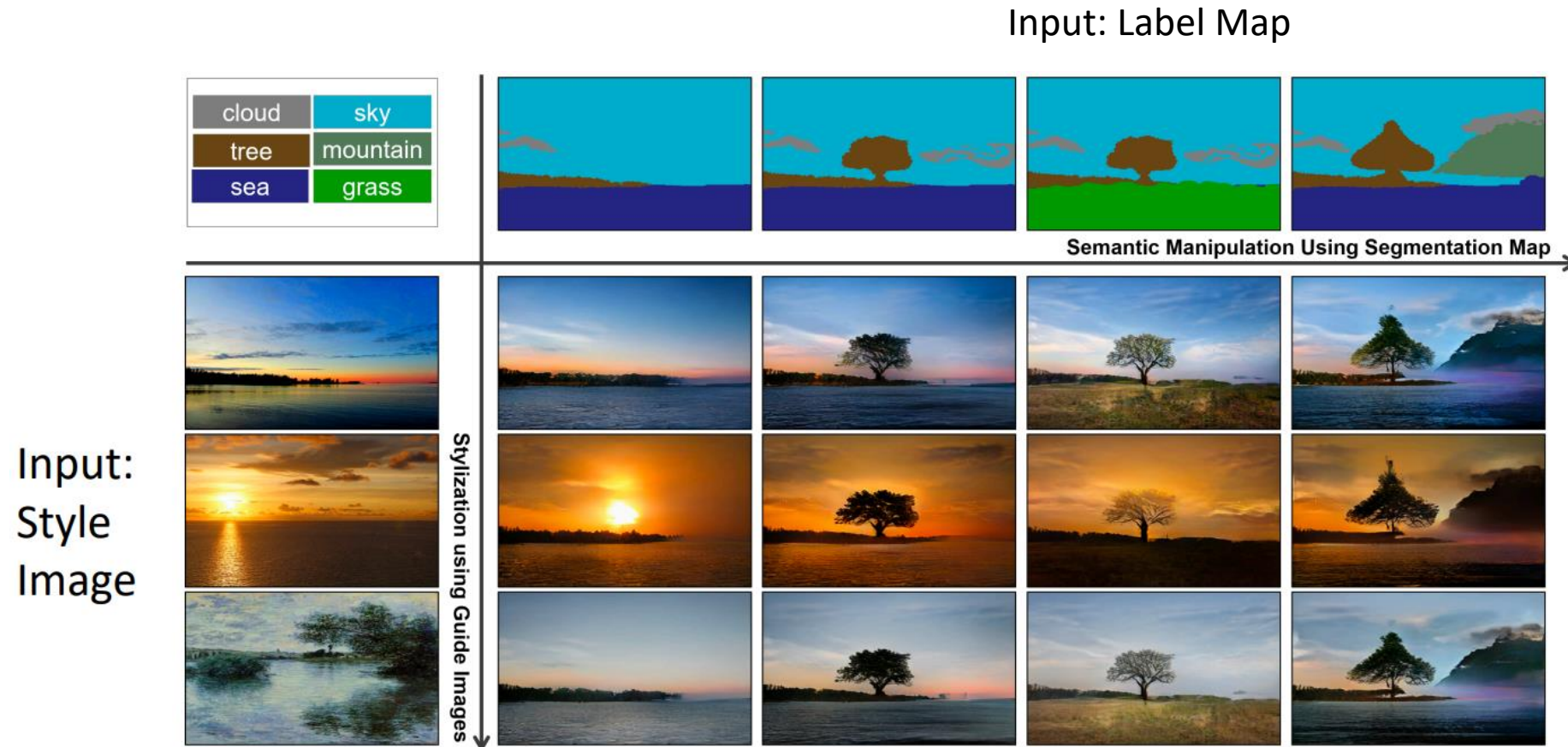
<https://www.youtube.com/watch?v=9reHvktowLY>

Zhu et al, "Unpaired Image-to-Image Translation using Cycle-Consistent Adversarial Networks", ICCV 2017

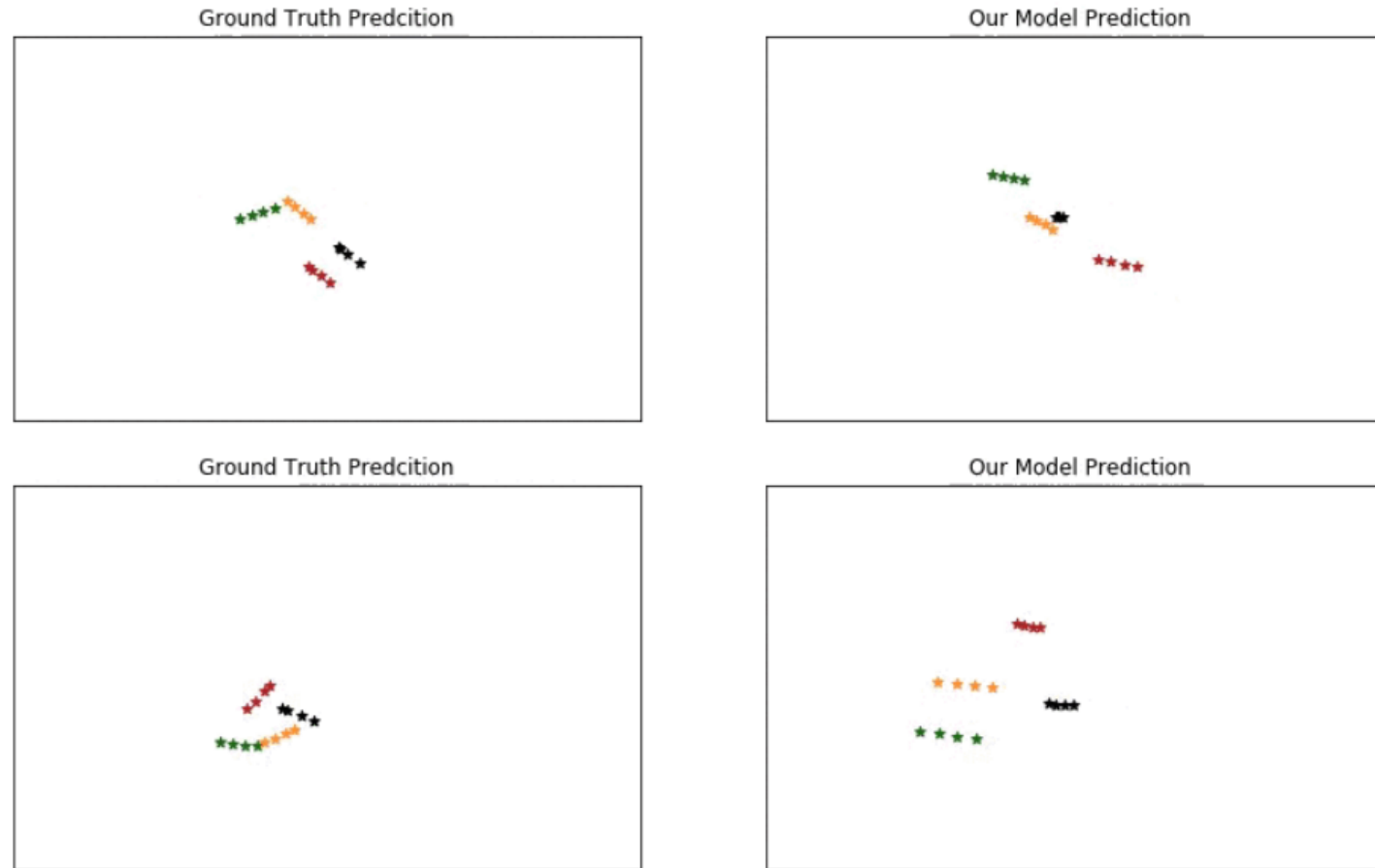
# Label Map to Image



# Label Map to Image

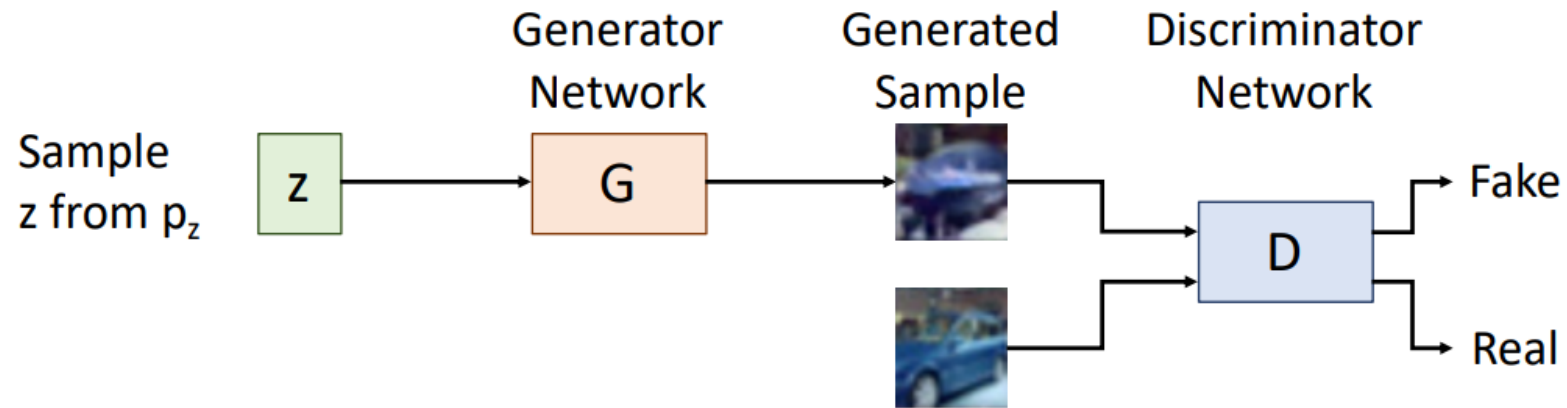


# GANs: Not just for images! Trajectory Prediction



# GAN Summary

- Jointly train two networks:
  - **Discriminator:** Classify data as real or fake
  - **Generator:** Generate data that fools the discriminator



- Many applications! Very active area of research!

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