Question 1

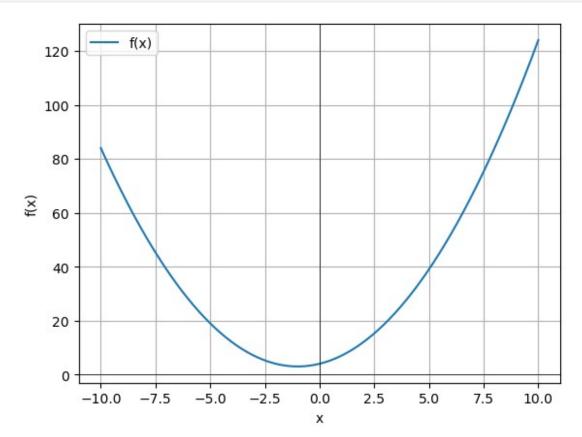
```
import numpy as np
import matplotlib.pyplot as plt
```

```
a, b, c = 4, 2, 1

def f(x):
    return a + b * x + c * x ** 2

x_range = np.linspace(-10, 10, 400)
plt.plot(x_range, f(x_range), label='f(x)')
plt.xlabel('x')
plt.ylabel('f(x)')

plt.axhline(0, color='black',linewidth=0.5)
plt.axvline(0, color='black',linewidth=0.5)
plt.grid(True)
plt.legend()
plt.show()
```



```
2.
```

```
f'=b+2cx=2+2x

def grad_f(x):
    return b + 2 * c * x

3.
0 = b + 2cx = 2 + 2x
    argmin(f(x)) = -1
    min(f(x)) = 3
4.
def grad_update(grad, x, eta):
```

5.

return x - eta * grad

The value is very close to the actual minimum of our function. This is what we expected, since gradient descent is used in order to find minimum of convex functions (each iteration going against the gradient to find the lowest point on graph).

```
xk_dict = {}

xs = [-42, 1251, 999]

etas = [0.001, 0.01, 0.1]

epss = [1e-6, 1e-5, 1e-4]
```

```
for x in xs:
    for et in etas:
        for ep in epss:
            xk \ dict[(x, et, ep)] = [x, grad update(grad f(x), x, et)]
            prev = xk dict[(x, et, ep)][-2]
            cur = xk_dict[(x, et, ep)][-1]
            while abs(f(cur) - f(prev)) > ep:
                xk_dict[(x, et, ep)].append(grad_update(grad_f(cur),
cur, et))
                prev = cur
                cur = xk dict[(x, et, ep)][-1]
xk list = sorted(xk dict.items(), key=lambda item: len(item[1]))
for (x, et, ep), x iter in xk list:
    print(f'for x = \{x\}, eta = \{et\}, ep = \{ep\} it takes \{len(x_iter)\}\
iterations (x = {x iter[-1]})')
for x = -42, eta = 0.1, ep = 0.0001 it takes 37 iterations (x = -
1.0133052606999953)
for x = -42, eta = 0.1, ep = 1e-05 it takes 43 iterations (x = -
1.0034878942609395)
for x = -42, eta = 0.1, ep = 1e-06 it takes 48 iterations (x = -
1.0011429131914247)
for x = 999, eta = 0.1, ep = 0.0001 it takes 52 iterations (x = -
0.9885820184583524)
for x = 1251, eta = 0.1, ep = 0.0001 it takes 53 iterations (x = -
0.9885637496878856)
for x = 999, eta = 0.1, ep = 1e-05 it takes 57 iterations (x = -
0.9962585558084329)
for x = 1251, eta = 0.1, ep = 1e-05 it takes 58 iterations (x = -
0.9962525694977263)
for x = 999, eta = 0.1, ep = 1e-06 it takes 62 iterations (x = -
0.9987740035673073)
for x = 1251, eta = 0.1, ep = 1e-06 it takes 63 iterations (x = -
0.9987720419730151)
for x = -42, eta = 0.01, ep = 0.0001 it takes 334 iterations (x = -
1.0490983686379647)
for x = -42, eta = 0.01, ep = 1e-05 it takes 391 iterations (x = -6
1.015522203641003)
for x = -42, eta = 0.01, ep = 1e-06 it takes 448 iterations (x = -
1.0049072670346617)
for x = 999, eta = 0.01, ep = 0.0001 it takes 492 iterations (x = -
0.9507956878460939)
for x = 1251, eta = 0.01, ep = 0.0001 it takes 504 iterations (x = -
0.9516584688229491)
for x = 999, eta = 0.01, ep = 1e-05 it takes 549 iterations (x = -
0.9844443028463915)
```

```
for x = 1251, eta = 0.01, ep = 1e-05 it takes 561 iterations (x = -
0.9847170667363508)
for x = 999, eta = 0.01, ep = 1e-06 it takes 606 iterations (x = -
0.9950821441588718)
for x = 1251, eta = 0.01, ep = 1e-06 it takes 618 iterations (x = -
0.9951683770982406)
for x = -42, eta = 0.001, ep = 0.0001 it takes 2778 iterations (x = -
1.1578690558902842)
for x = -42, eta = 0.001, ep = 1e-05 it takes 3354 iterations (x = -
1.0498297597515271)
for x = -42, eta = 0.001, ep = 1e-06 it takes 3929 iterations (x = -
1.0157597757502377)
for x = 999, eta = 0.001, ep = 0.0001 it takes 4374 iterations (x = -
0.8422907923943299)
for x = 1251, eta = 0.001, ep = 0.0001 it takes 4486 iterations (x = -
0.8422090820341461)
for x = 999, eta = 0.001, ep = 1e-05 it takes 4949 iterations (x = -
0.9501209366048236)
for x = 1251, eta = 0.001, ep = 1e-05 it takes 5061 iterations (x = -
0.9500950938763143)
for x = 999, eta = 0.001, ep = 1e-06 it takes 5524 iterations (x = -
0.9842246308699947)
for x = 1251, eta = 0.001, ep = 1e-06 it takes 5636 iterations (x = -
0.9842164575292421)
```

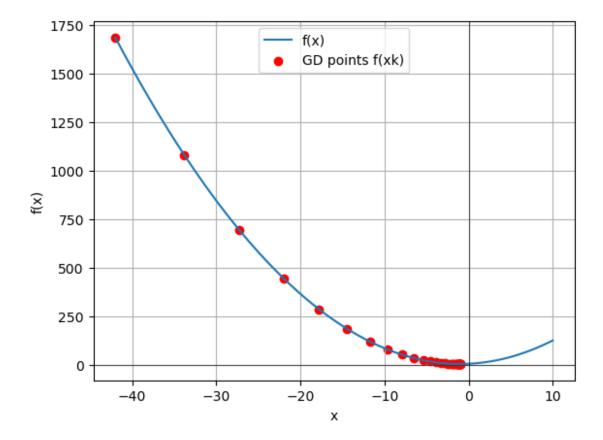
As we can see, out of the set of hyperparameters that we defined, for starting point -42, with step 0.1 and epsilon = 0.0001 it took us 37 iterations to meet the stopping condition. It took the closest point to minimum, with largest possible step out of the options we've set.

```
x_range = np.linspace(-42, 10, 400)
plt.plot(x_range, f(x_range), label='f(x)')

# Take the value (list of iterations x) of the configuration with
lowest T

x_t = xk_list[0][1]
plt.scatter(x_t, [f(i) for i in x_t], label='GD points f(xk)',
color='red')

plt.xlabel('x')
plt.ylabel('f(x)')
plt.axhline(0, color='black',linewidth=0.5)
plt.axvline(0, color='black',linewidth=0.5)
plt.grid(True)
plt.legend()
plt.show()
```



S(W,b) = Max Eo, 1-4; ((w,x;)+3) + > 1/W112 To 15x0) .2 - rover of limity=(x)4 amps x milling of line & care h(x)=1/21/11 for 12 -שקיא צירא של של פונקציות קמיות נגפרל קמורה. - פיני בוברצ קמיחת בל המורה ונכה מוניני של שני בוברצ קמיחת לב מניטן לבים: (לנט) פונוג לבירון של בונוג לשווא לפתוכלה להיואל בינולים של בונוג לשווא לפתוכלה 904 (1919) 2006 (1919) Pod ع، رمام الهرورية عنه المام = > 10-01 = 11 m2- will-max like 11 : 12 (1) 5 () 31 (2) 0く1-らっといんう ラインカー | (U, x;y;)=0=> Hr, W, € IRd; | (W, x; y;) - 1(W2, x; y;) | 3me 1-5. (M1)x1)60 " ((M2) x6) > Q1(1) ((M1) x9.):00 (1) Q10 + 4/16 -11 (- y = wa, x, >) 11 = 11 4: (w1, x;) - 5: (w2, x;) 11 = 11 (w1- V2, y: x;) 11 ξι (1 μι- ωλ) | 1ω; χι (1 ξ 1(ω, - ν) 1). ανχηχι 11

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9 = { 0 -5 ((u , x > + b) < 0													
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		: W	i bo	^{C' K	7127	SgJ							
	5° - (-5;x;+7W	1- 90 ((W she))+b)<9										
	Uw (SixiTAW	1- 9; (CV,	x5>16)>(0									

rgufdxuwz

July 26, 2024

Q2 Code - Stochastic Gradient Descent

```
[1]: import random
  import numpy as np
  from sklearn.datasets import load_iris
  from sklearn.model_selection import train_test_split
  import matplotlib.pyplot as plt
```

```
[2]: def sgd_b(yi, xi, w, b):
         return 0 if 1 - yi * (np.dot(w, xi) + b) <= 0 else -yi
     def sgd_w(yi, xi, w, b, lamb):
         return lamb * w if 1 - yi * (np.dot(w, xi) + b) \leq 0 else -yi * xi + lamb *
      ∽W
     def sub_gradients_calc(yi, xi, w, b, lamb, l_rate):
         w_grad = sgd_w(yi, xi, w, b, lamb)
         b_grad = sgd_b(yi, xi, w, b)
         w = w - l_rate * w_grad
         b = b - l_rate * b_grad
         return w, b
     def svm_with_sgd(X, Y, lam=0.0, epochs=1000, l_rate=0.01, sgd_type='practical'):
         m, d = X.shape
         w = np.random.uniform(0, 1, d)
         b = np.random.uniform(0, 1)
         w_ls, b_ls = [w], [b]
         epoch_train, epoch_test = [], []
         if sgd_type == 'theory':
             for j in range(epochs+1):
                 randomize = np.arange(m)
                 np.random.shuffle(randomize)
                 X_shuffled = X[randomize]
                 Y_shuffled = Y[randomize]
```

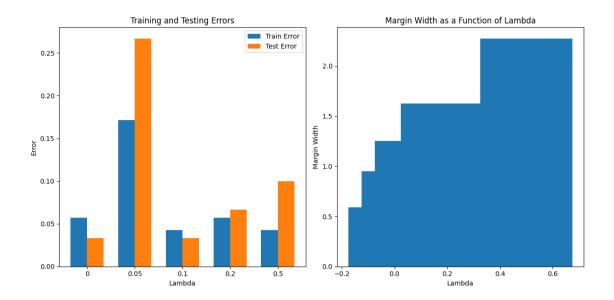
```
for xi, yi in zip(X shuffled, Y shuffled):
                     w, b = sub_gradients_calc(yi, xi, w, b, lam, l_rate)
                     w_ls.append(w)
                     b_ls.append(b)
                 if 10 <= j <= 1000 and j % 10 == 0:</pre>
                     epoch_train.append(calculate_error(sum(w_ls) / len(w_ls),__
      \rightarrowsum(b_ls) / len(b_ls), X, Y))
                     epoch_test.append(calculate_error(sum(w_ls) / len(w_ls),_
      ⇒sum(b_ls) / len(b_ls), X_test, y_test))
             return sum(w_ls) / (m * epochs), sum(b_ls) / (m * epochs), epoch_train,__
      ⇔epoch test
         elif sgd_type == 'practical':
             for i in range(epochs + 1):
                 for j in range(m):
                     idx = random.choice(range(m))
                     w, b = sub_gradients_calc(Y[idx], X[idx], w, b, lam, l_rate)
                 if 10 <= i <= 1000 and i % 10 == 0:
                     epoch_train.append(calculate_error(w, b, X, Y))
                     epoch_test.append(calculate_error(w, b, X_test, y_test))
             return w, b, epoch_train, epoch_test
         return 0, 0, 0
     def calculate_error(w, bias, X, Y):
         predictions = np.sign(np.dot(X, w) + bias)
         accuracy = np.mean(predictions == Y)
         return 1 - accuracy
[4]: if __name__ == "__main__":
        np.random.seed(2)
         X, y = load_iris(return_X_y=True)
         X = X[y != 0]
         y = y[y != 0]
```

```
np.random.seed(2)
X, y = load_iris(return_X_y=True)
X = X[y != 0]
y = y[y != 0]
y[y == 2] = -1
X = X[:, 2:4]
X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.3,u)
arandom_state=0)

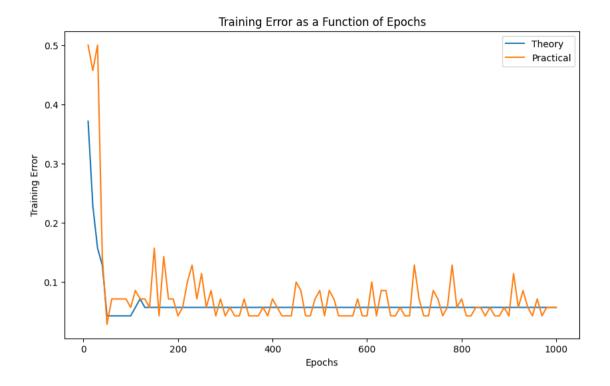
lambdas = [0, 0.05, 0.1, 0.2, 0.5]
train_errors = []
test_errors = []
margin_widths = []
```

Part 4 - Training Models and reporting train, test error and the margin width

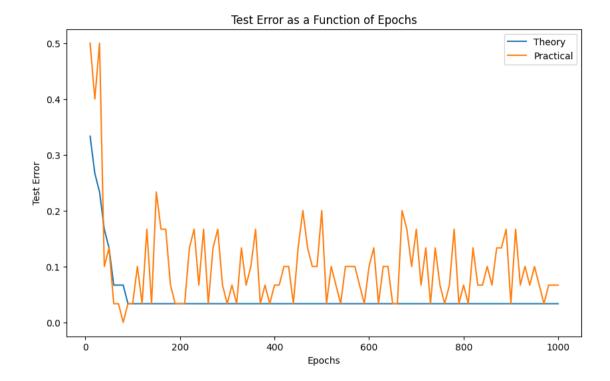
```
[8]: plt.figure(figsize=(12, 6))
      plt.subplot(1, 2, 1)
       bar_width = 0.35
       index = np.arange(len(lambdas))
      plt.bar(index, train errors, bar width, label='Train Error')
      plt.bar(index + bar_width, test_errors, bar_width, label='Test Error')
      plt.xlabel('Lambda')
      plt.ylabel('Error')
      plt.title('Training and Testing Errors')
      plt.xticks(index + bar_width / 2, lambdas)
      plt.legend()
      plt.subplot(1, 2, 2)
      plt.bar(lambdas, margin_widths, bar_width)
      plt.xlabel('Lambda')
      plt.ylabel('Margin Width')
      plt.title('Margin Width as a Function of Lambda')
      plt.tight_layout()
       plt.show()
```



We can see that the model with lambda = 0.1 looks the best. It has the lowest training error out of all the models. With the right lambda the training set will not overfit, we can see for lambda = 0.05, 0.2, 0.5 the model overfits since the training error is better than the test error. for lambda = 0.05, 0.2 they get similar test error but lambda = 0.1 has a better training error.



```
[12]: # Part 7b
plt.figure(figsize=(10, 6))
plt.plot(epochs, epoch_errors_theory_test, label='Theory')
plt.plot(epochs, epoch_errors_practical_test, label='Practical')
plt.xlabel('Epochs')
plt.ylabel('Test Error')
plt.title('Test Error as a Function of Epochs')
plt.legend()
plt.show()
```



The results are logical since the practical method is more hands on and computes until it converges to the result and thus it makes sense that it would take longer to converge in comparison to the theoretical method. The theoretical method as can be seen by it's name uses calculations and proofs that state it's structure and thus it makes sense that it will converge pretty early as we can see in the resulting graphs.

Question 3

```
def cross_validation_error(X, y, model, folds):
    fold_size = X.shape[0] // folds
    sum train error = 0
    sum val error = 0
    # Shuffle data (no bias by the initial order)
    permutation = np.random.permutation(len(y))
    X = X[permutation]
    y = y[permutation]
    for i in range(folds):
        v start = i * fold size
        v_{end} = (i + 1) * fold_size
        X_{val} = X[v_{start}:v_{end}]
        y_val = y[v_start:v_end]
        X train = np.concatenate((X[:v start], X[v end:]), axis=0)
        y train = np.concatenate((y[:v start], y[v end:]), axis=0)
        model.fit(X_train, y_train)
        y_val_pred = model.predict(X_val)
        y_train_pred = model.predict(X_train)
```

```
sum_train_error += 1 - np.mean(y_train == y_train_pred)
sum_val_error += 1 - np.mean(y_val == y_val_pred)
return sum_train_error / folds, sum_val_error / folds
```

2.

```
from sklearn.svm import SVC

def svm_results(X_train, y_train, X_test, y_test):
    folds = 5
    lambdas = [1e-4, 1e-2, 1, 1e2, 1e4]
    svm_errors = {}

    for l in lambdas:
        model = SVC(kernel='linear', C=1/l)
        train_error, val_error = cross_validation_error(X_train, y_train, model, folds)
        model.fit(X_train, y_train)
        y_test_pred = model.predict(X_test)
        test_error = 1 - np.mean(y_test == y_test_pred)
        svm_errors[f'{l}'] = (train_error, val_error, test_error)

return svm_errors
```

```
from sklearn.datasets import load_iris
from sklearn.model_selection import train_test_split

np.random.seed(1)

iris_data = load_iris()
X, y = iris_data['data'], iris_data['target']

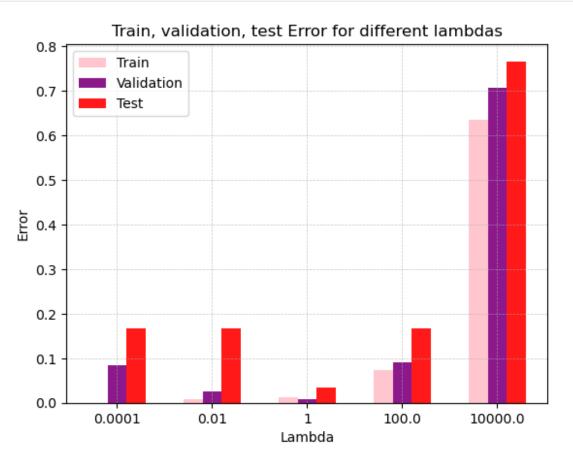
X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.2, random_state=7)

svm_errors = svm_results(X_train, y_train, X_test, y_test)

fig, ax = plt.subplots()

train_errors = [v[0] for v in svm_errors.values()]
val_error = [v[1] for v in svm_errors.values()]
test_errors = [v[2] for v in svm_errors.values()]
bar_width = 0.2
index = np.arange(len(svm_errors.keys()))
ax.grid(True, which='both', linestyle='--', linewidth=0.5, alpha=0.7)
```

```
bar_train = ax.bar(index - bar_width, train_errors, bar_width,
label='Train', color='pink', alpha=0.9)
bar_val = ax.bar(index, val_error, bar_width, label='Validation',
color='purple', alpha=0.9)
bar_test = ax.bar(index + bar_width, test_errors, bar_width,
label='Test', color='red', alpha=0.9)
ax.set_xlabel('Lambda')
ax.set_ylabel('Error')
ax.set_title('Train, validation, test Error for different lambdas')
ax.set_xticks(index)
ax.set_xticklabels(svm_errors.keys())
ax.legend()
plt.show()
```



According to the CV approach, the model with lambda=1 is the best, giving us an error of 0.0083 on validation set. It is also the best model for test set, giving us 0.0333 error.

This result might be because usually for smaller error on validation set we expect smaller error on test set. As we can see, for smaller values of lambda our model overfits, which leads to increase both in validation and test error. Similarly, we have even greater error for bigger lambda's (our model underfits). Lambda=1 is optimal in this case.

	j Engrax g: (w)	a, y	9(w) = max	9:(4)	W	<i>′</i> λλ	(4
				u e k	2 ^{cd} :	167	
g(w)+	(۱۰۷ ر۵-۱۷ و ۲ ر۵-۱۷ کر کرنه	∠ g;	(w) + (u.				
		of 9					
= 9	; (u) ≤ g(u)						
	9(w)=maxgi=9;	•					
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