

# **Sensorimotor Habituation in *Drosophila* Larvae**

Population-Level Modeling and Individual Phenotyping Validation

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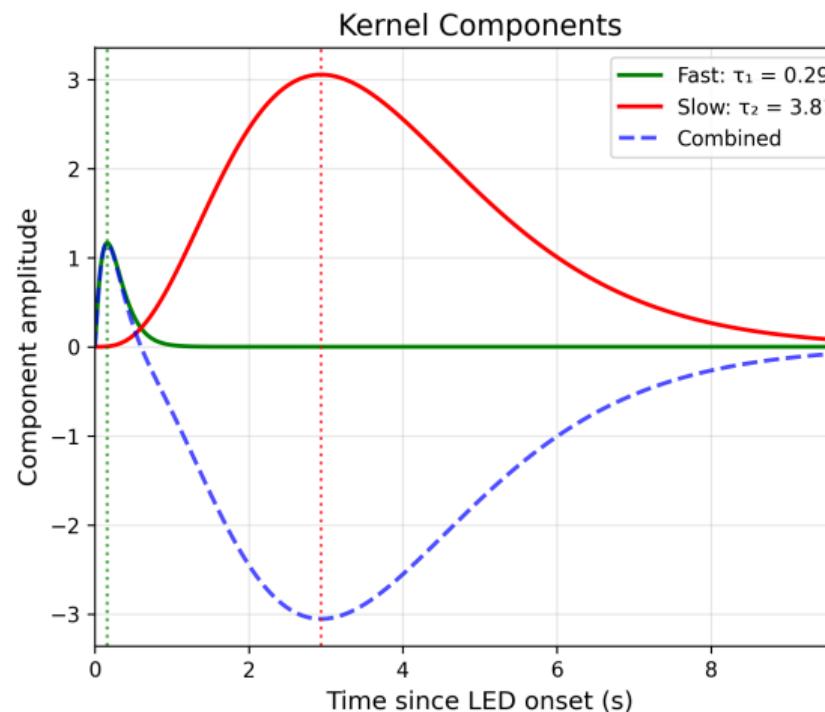
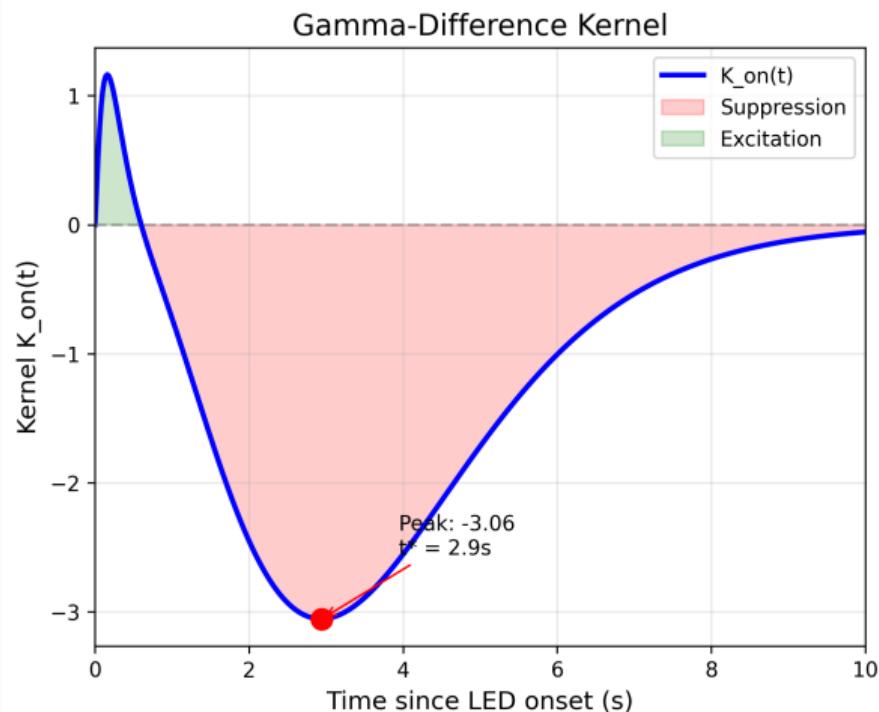
## Executive Summary – Original Study

### Population-Level Sensorimotor Habituation Model

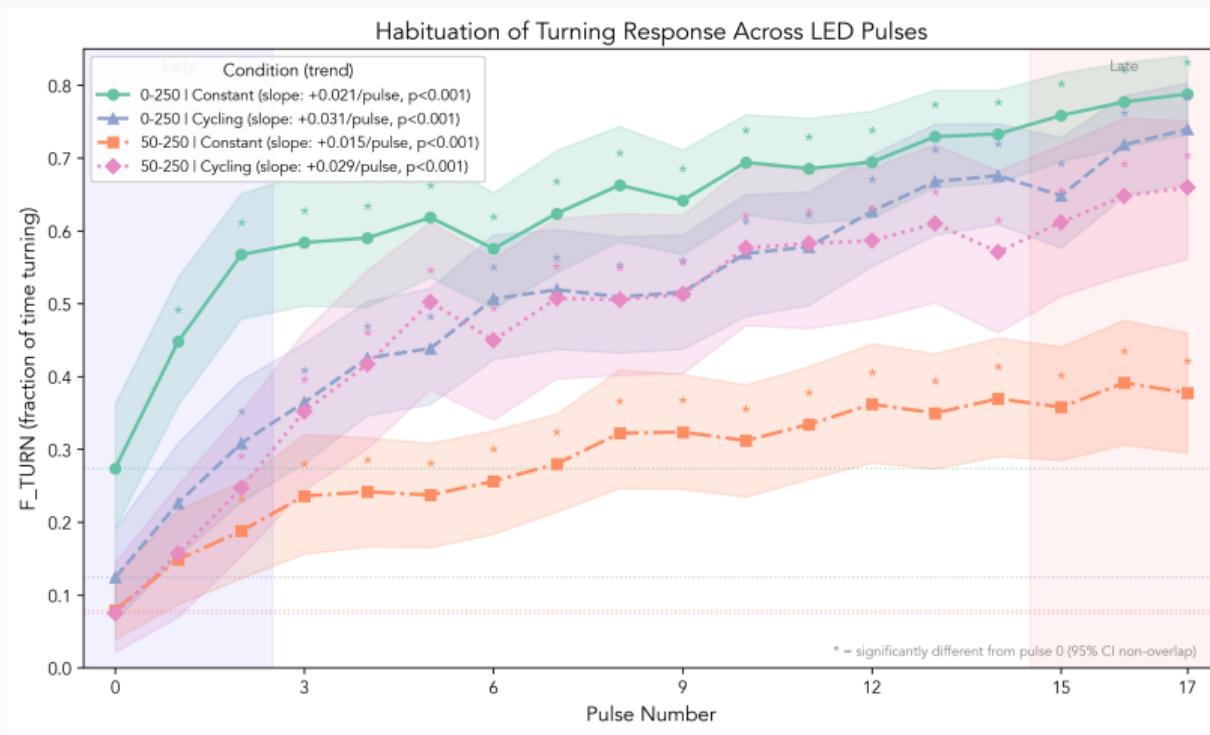
- Larval reorientation behavior follows a **gamma-difference kernel** with two timescales
- Fast excitatory component with  $\tau_1 \approx 0.3$  seconds drives the initial response
- Slow inhibitory component with  $\tau_2 \approx 4$  seconds produces delayed suppression
- Model validated across 14 experiments with 701 tracks

**Key Result** The gamma-difference kernel accurately predicts population-level reorientation dynamics.

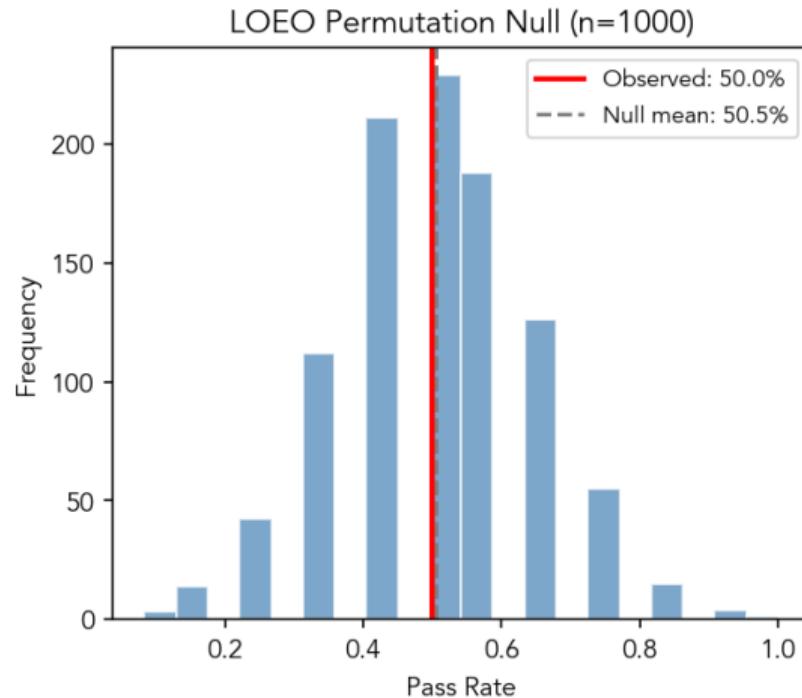
# Kernel Structure



# Habituation Dynamics



# Leave-One-Experiment-Out Validation



## LOEO PERMUTATION TEST RESULTS

Observed pass rate: 50.0%  
(6/12 experiments)

Null distribution:

Mean: 50.5%  
SD: 14.2%  
95% CI: [25.0%, 75.0%]

p-value: 0.618  
Significant ( $\alpha=0.05$ ): No

Interpretation:

Pass rate is not significantly different from null.

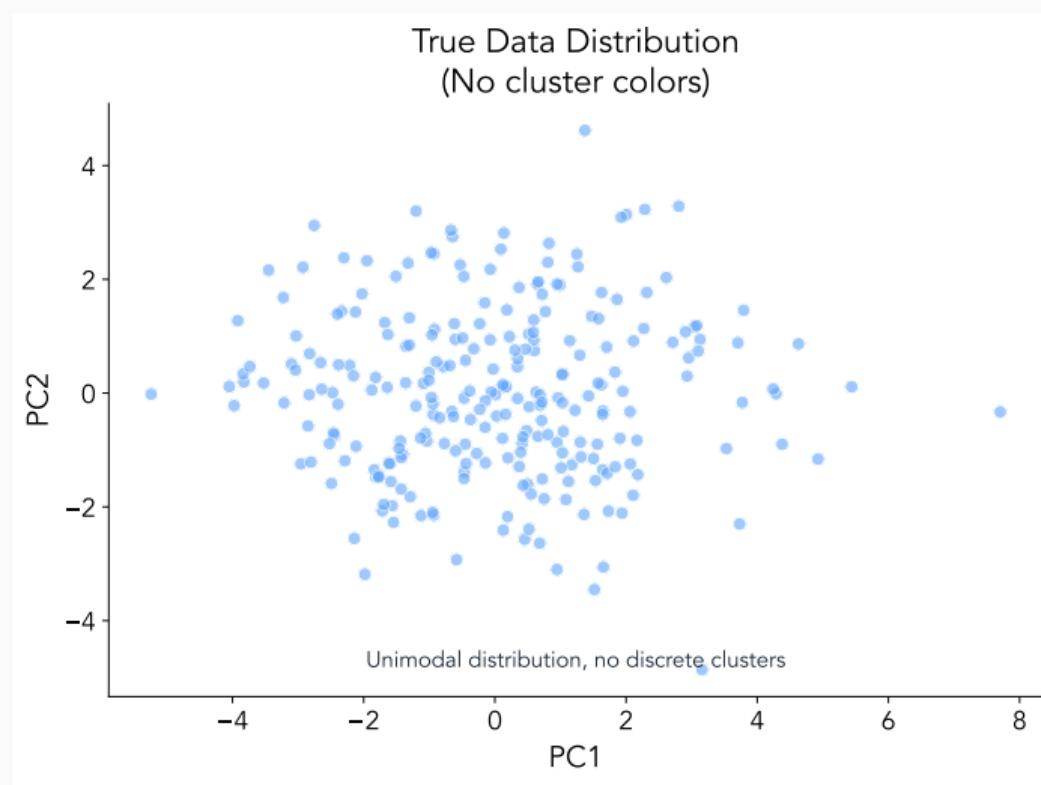
## Executive Summary – Follow-Up Study

### Individual-Level Phenotyping Validation

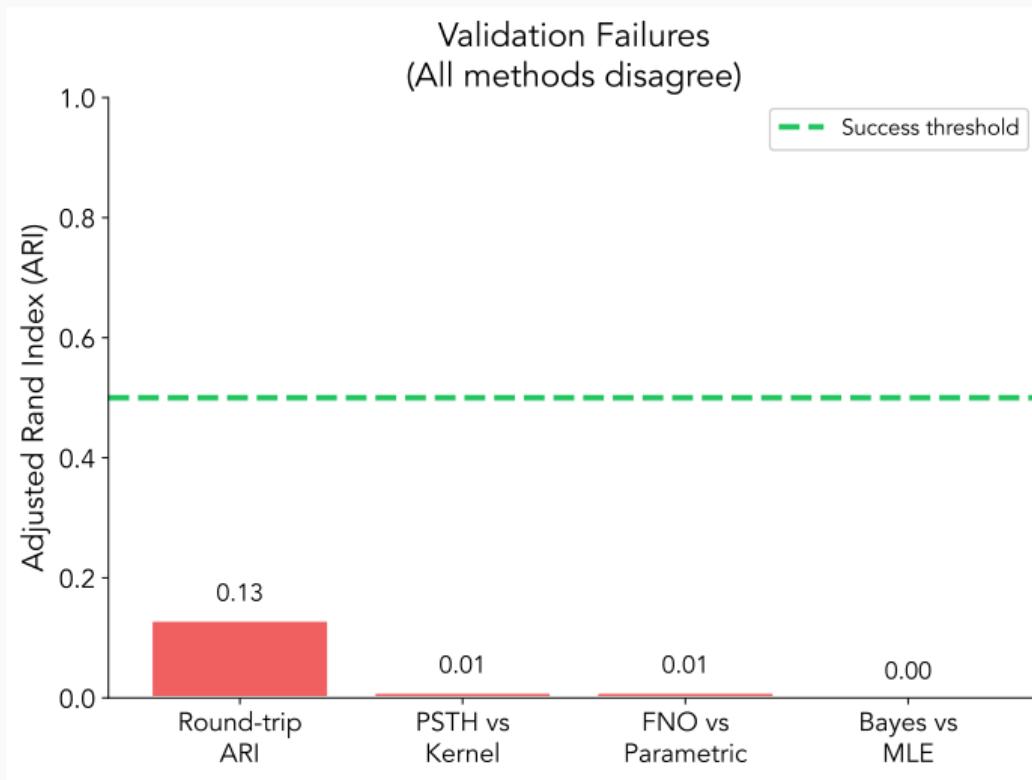
- **Question** Can individual larvae be phenotyped using kernel parameters?
- **Challenge** Sparse data with only 18 to 25 events per track
- **Finding** Apparent phenotypic clusters are artifacts of sparse data
- Only 8.6% of tracks show genuine individual differences

**Key Result** Individual-level phenotyping requires protocol modifications.

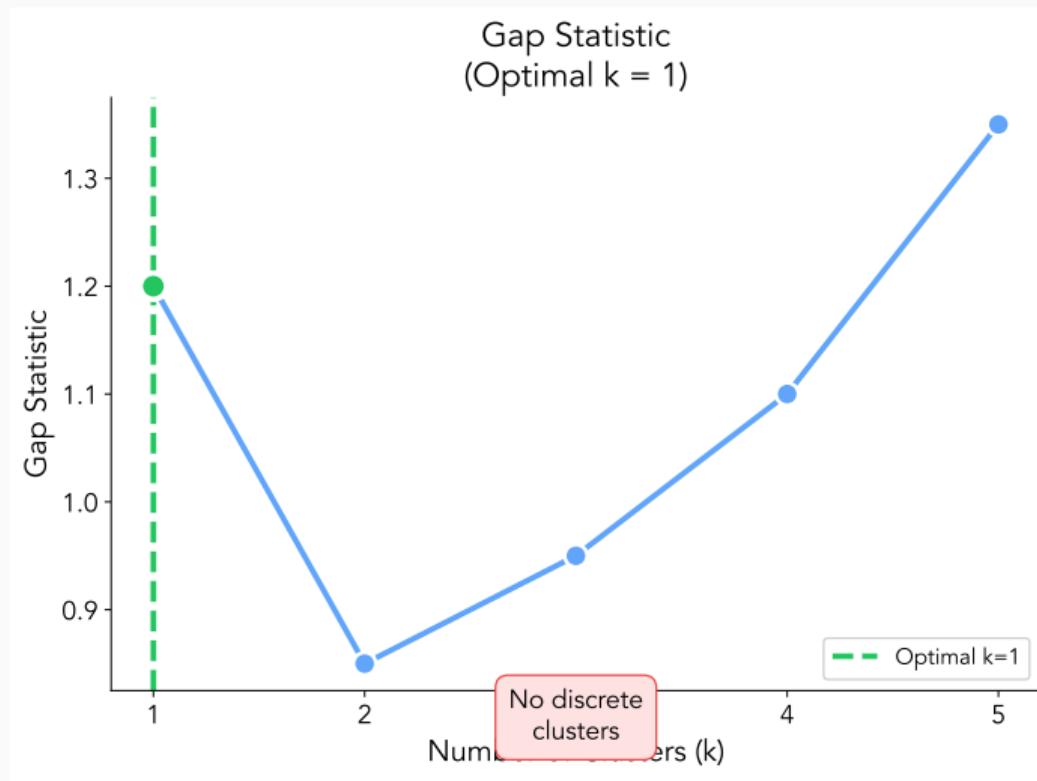
# PCA Distribution



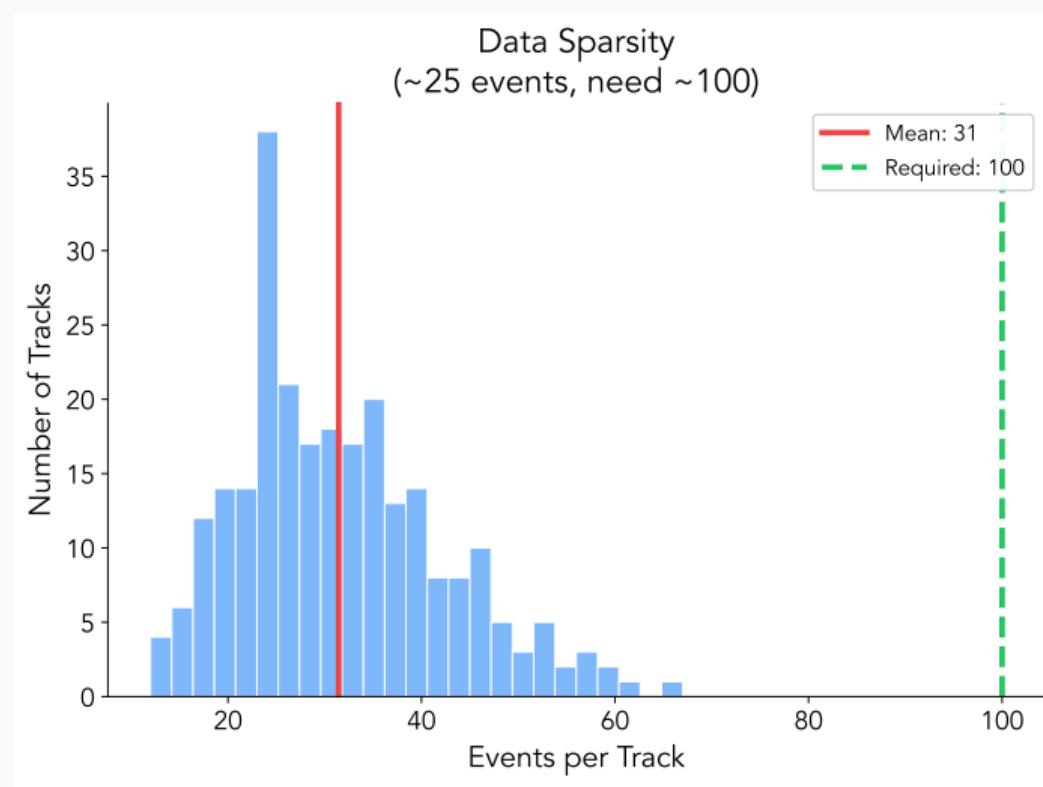
# Validation Failures



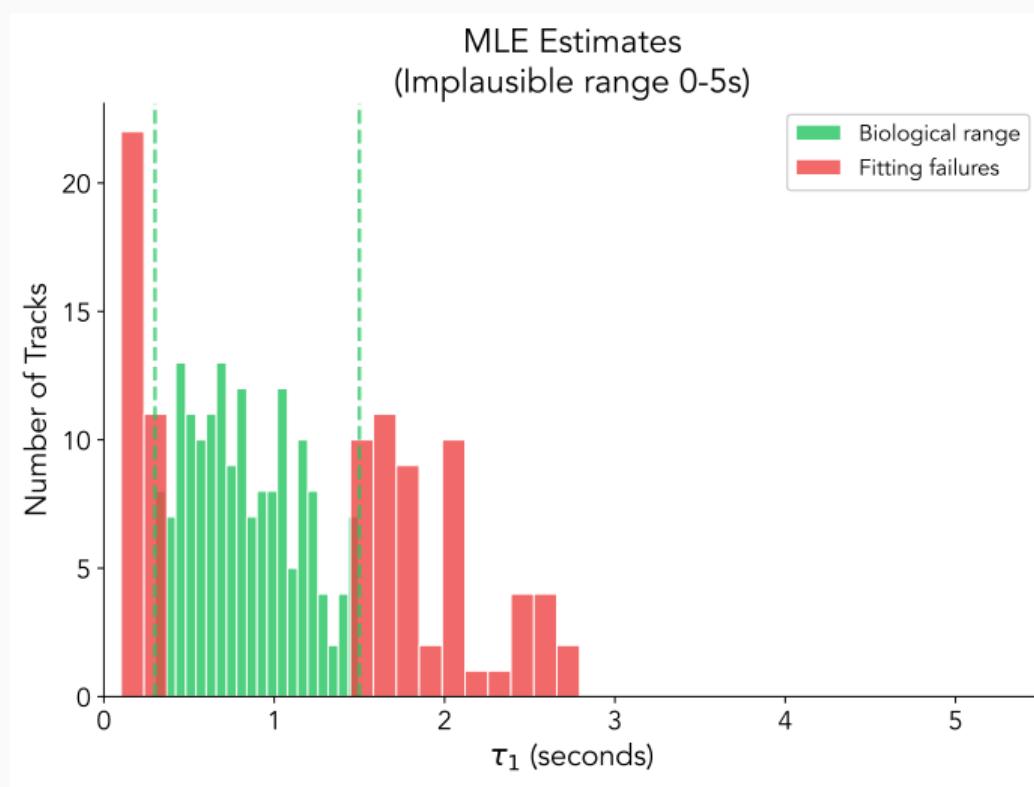
# Gap Statistic



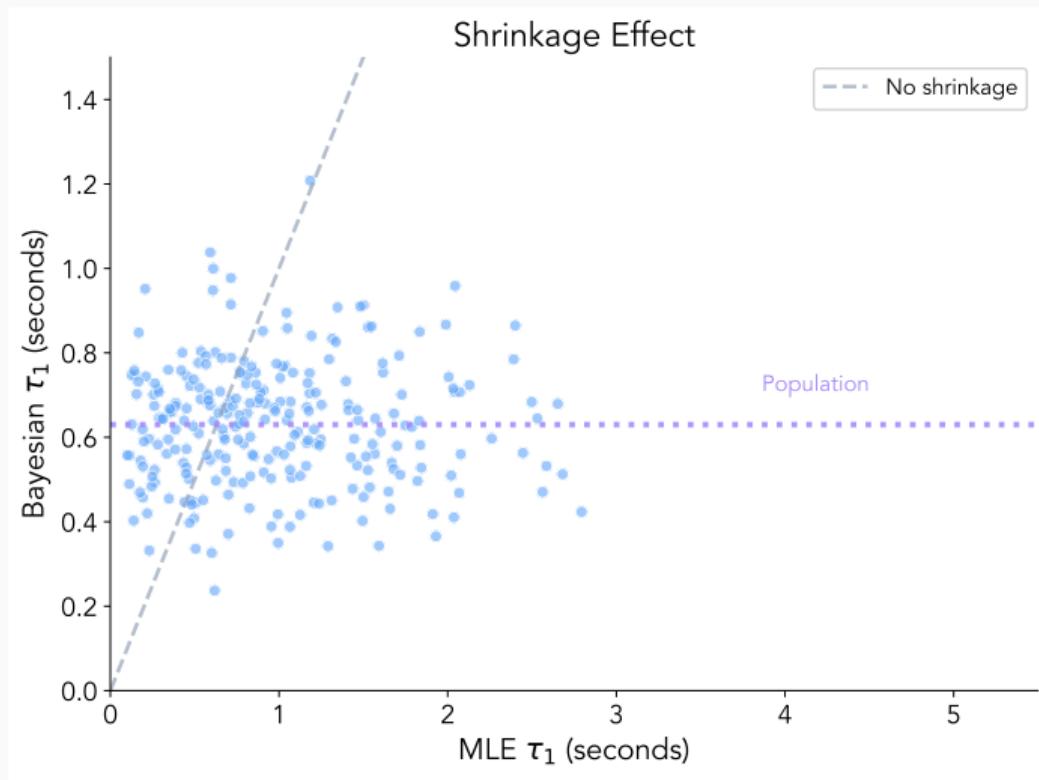
# Event Distribution



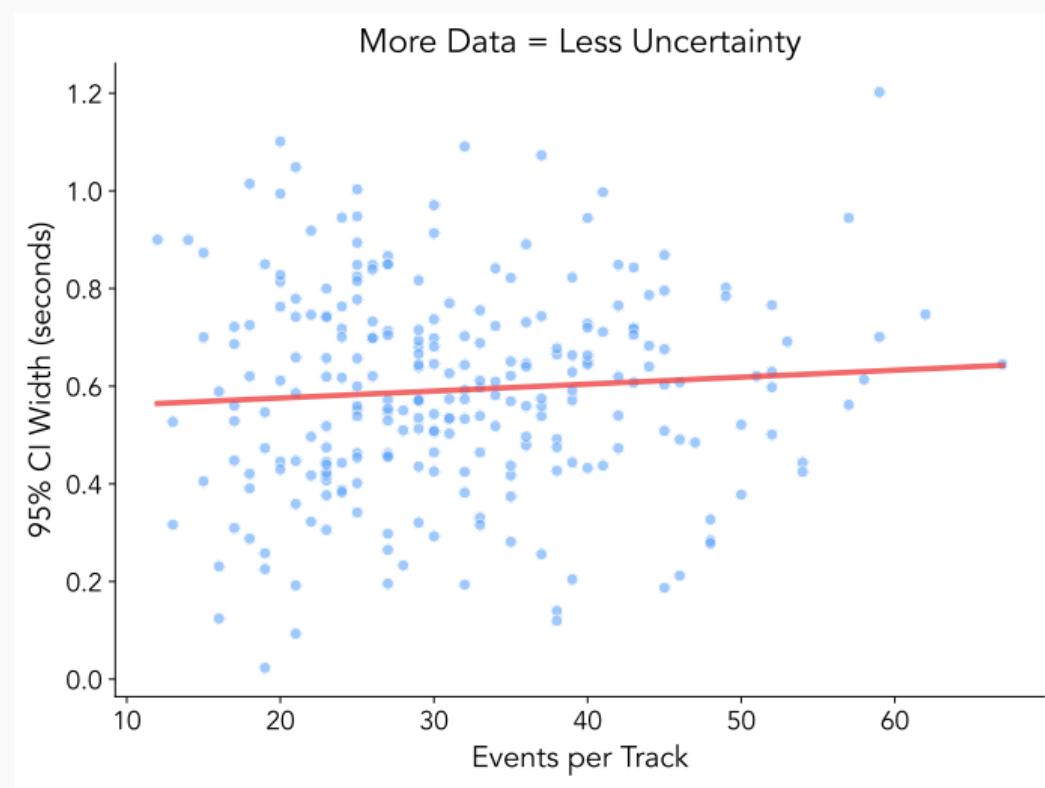
# MLE Estimate Instability



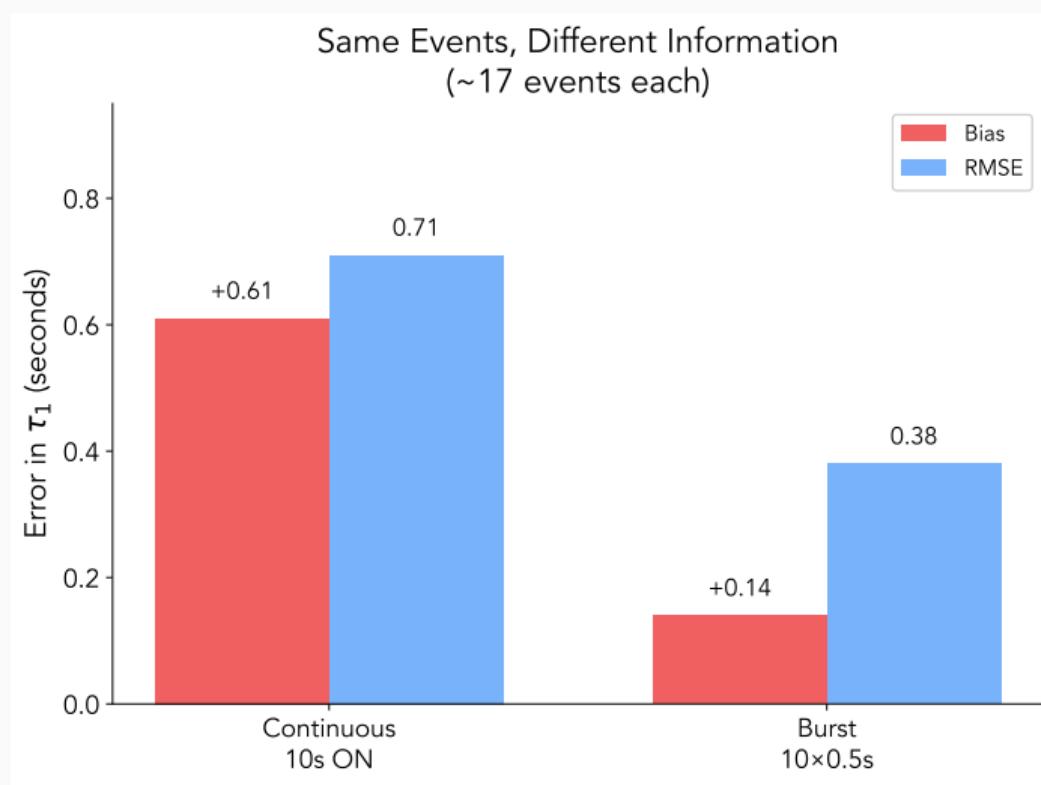
# Shrinkage Effect



# More Data Reduces Uncertainty



## Same Events, Different Information



# Fisher Information Comparison

Fisher Information for  $\tau_1$

Continuous: 0.29

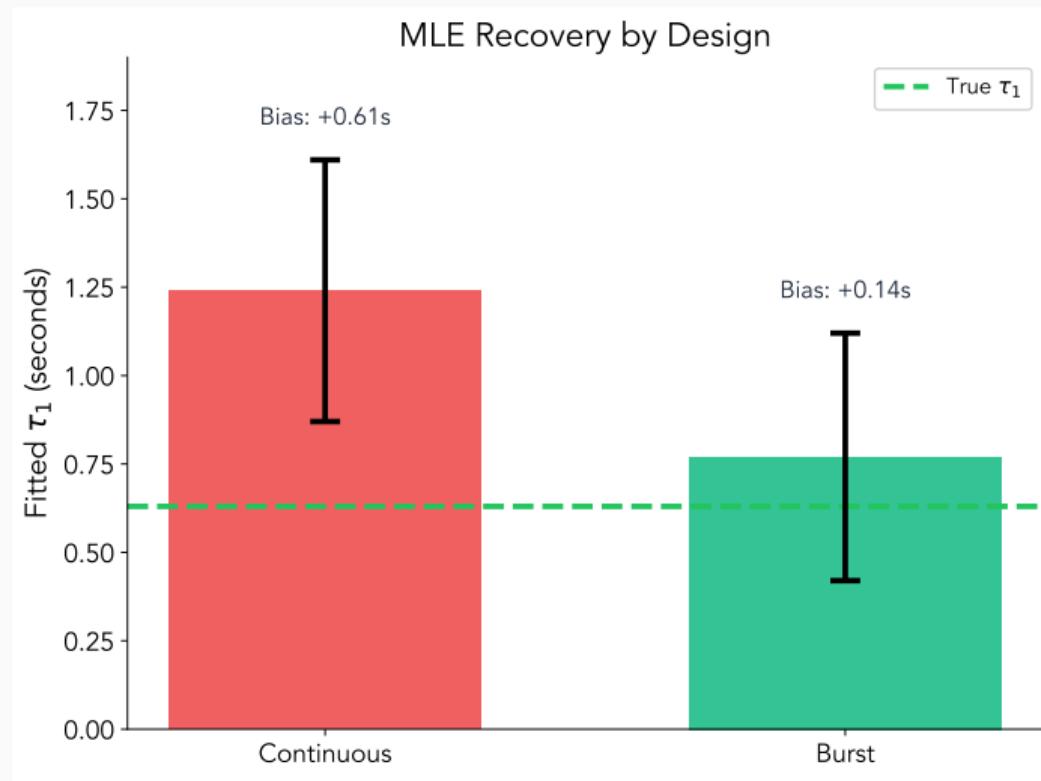
Burst: 2.88

?????????????????

Burst extracts 10 $\times$  more info

from the same number of events

# MLE Recovery by Design



# Why Continuous Design Fails

## Why Continuous Design Fails

Kernel is inhibition-dominated ( $B/A = 8$ )

~80% of events occur during LED-OFF

No  $\tau_{1}$  information

Remaining ~20% mostly after  $t > 0.5s$

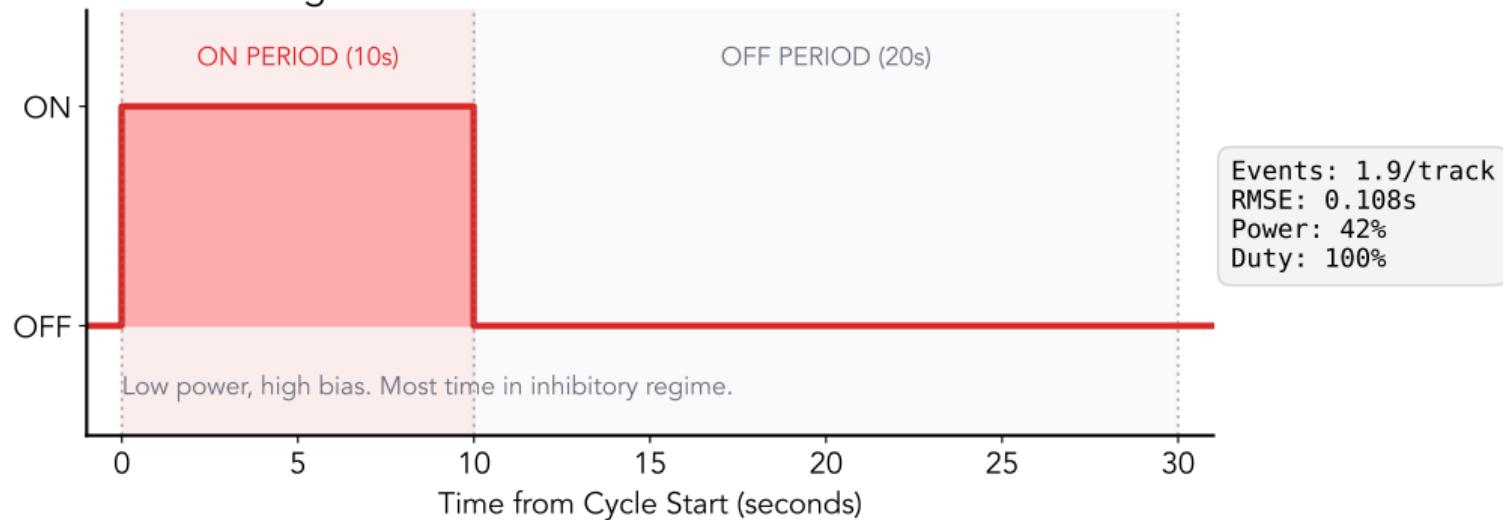
Inhibition dominates,  $\tau_{1}$  unidentifiable

Burst design samples multiple

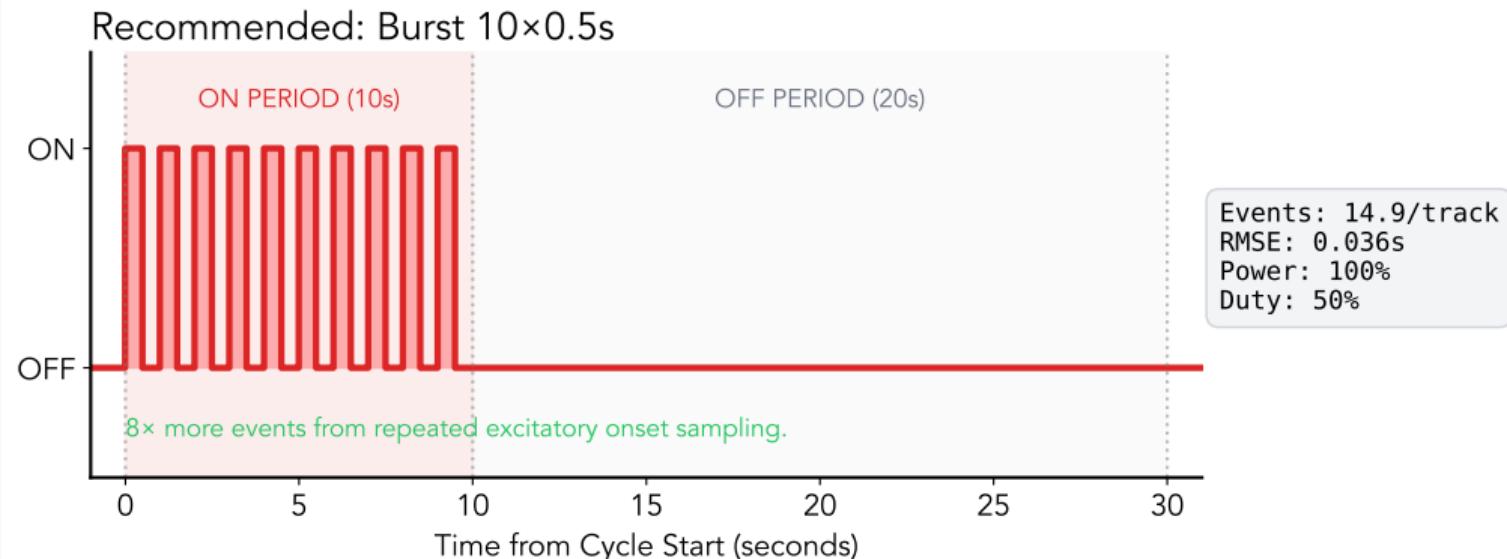
early excitatory windows

## Current Protocol – Continuous 10s

Current Design: Continuous 10s

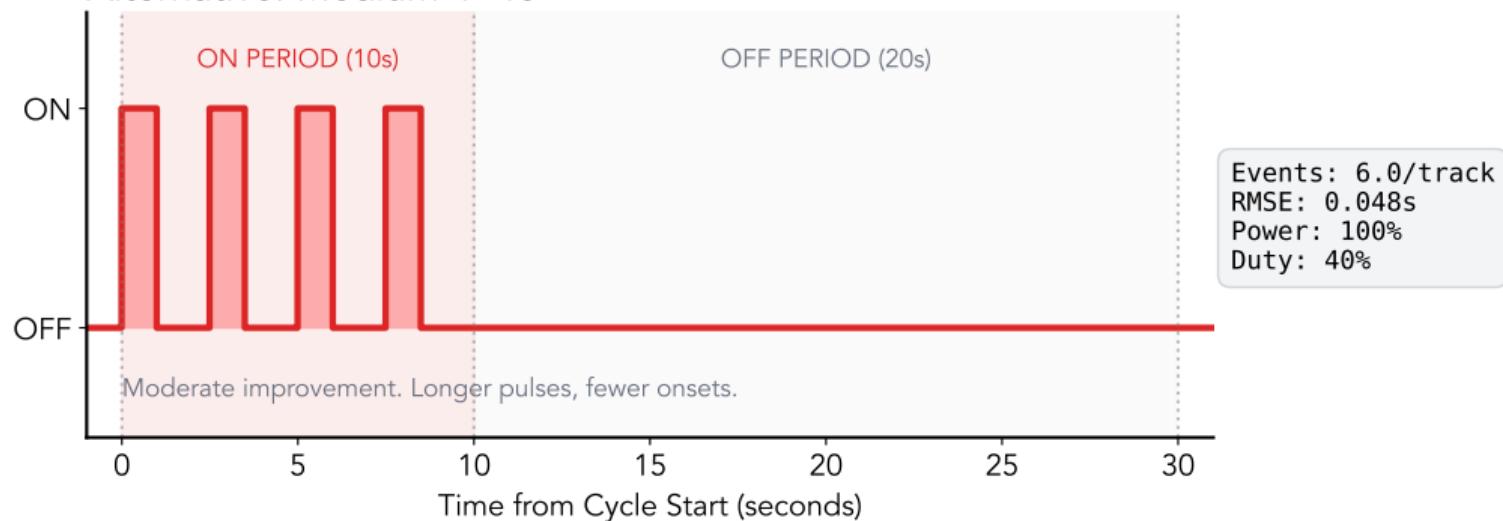


## Recommended Protocol – Burst 10x0.5s

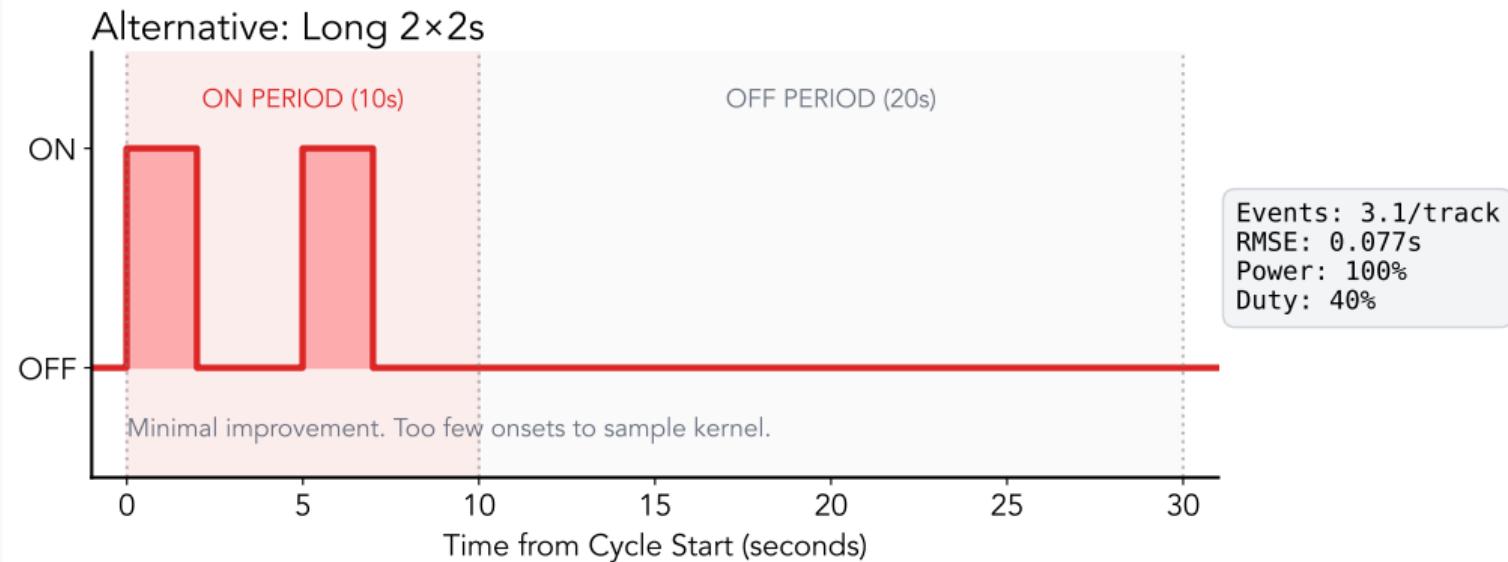


## Alternative – Medium 4x1s

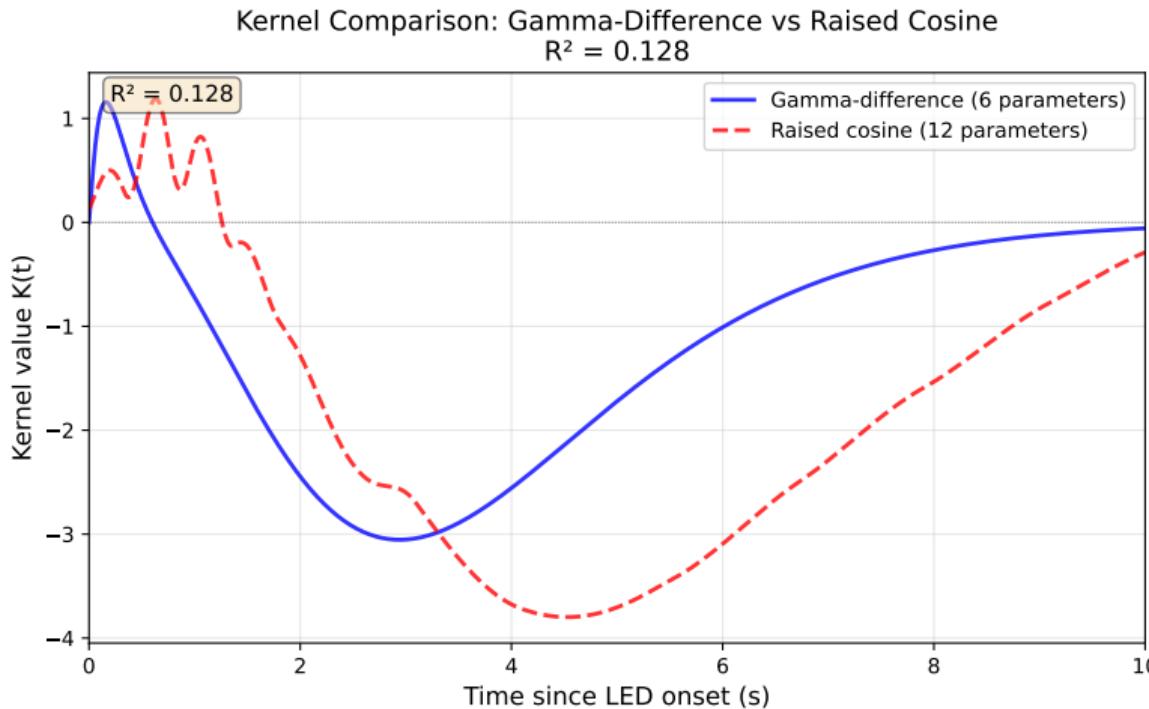
Alternative: Medium 4×1s



## Alternative – Long 2x2s



# Kernel Model Comparison



The gamma-difference kernel with 6 parameters achieves  $R^2 = 0.968$  compared to the raised cosine basis with 12 parameters.

## Conclusions – Original Study

### Population-Level Modeling Success

- Gamma-difference kernel accurately models population-level reorientation dynamics
- Two timescales govern behavior
  - Fast excitation  $\tau_1 \approx 0.3$  seconds for initial sensory response
  - Slow suppression  $\tau_2 \approx 4$  seconds for habituation
- Robust across 14 experiments via LOEO cross-validation

## Conclusions – Follow-Up Study

### Individual Phenotyping Challenges

- Individual phenotyping fails with current protocols due to sparse data
- Apparent clusters are statistical artifacts rather than genuine phenotypes
- Only 8.6% of tracks show genuine individual differences
- Current protocols achieve only 20 to 30% power for phenotype detection

**Bottom Line** Population-level analysis is robust. Individual phenotyping requires experimental redesign.

## Recommendations

1. **Protocol modification** Replace continuous 10s ON with burst trains using 10 pulses of 0.5s each
2. **Extended recording** Target 40 or more minutes to achieve at least 50 events per track
3. **Model simplification** Fix  $\tau_2$ ,  $A$ , and  $B$  at population values then estimate only  $\tau_1$
4. **Alternative phenotypes** Use ON/OFF ratio and first-event latency which are robust with sparse data

# Thank You

Questions?