

# Applications of Machine Learning to particle physics

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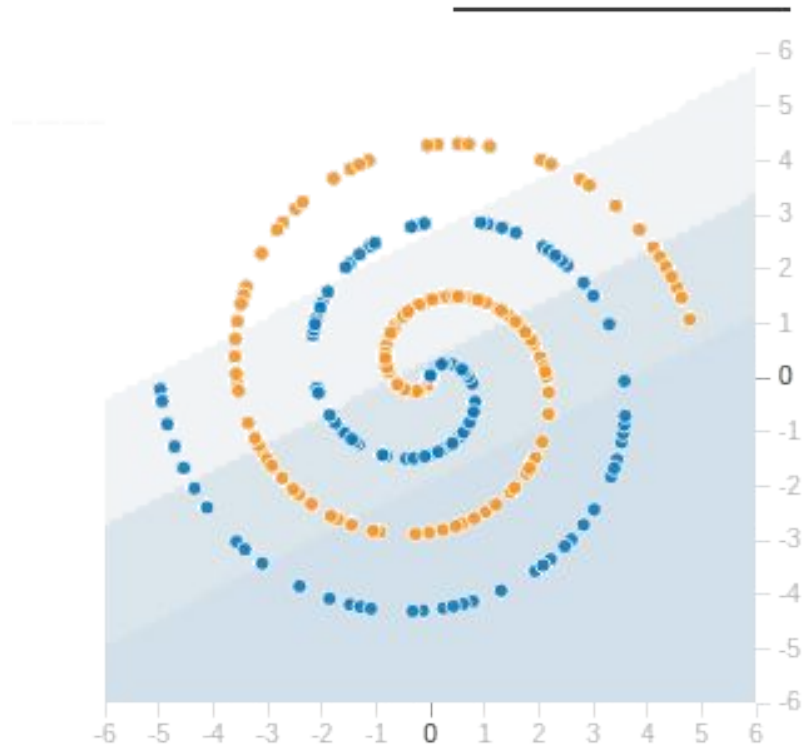


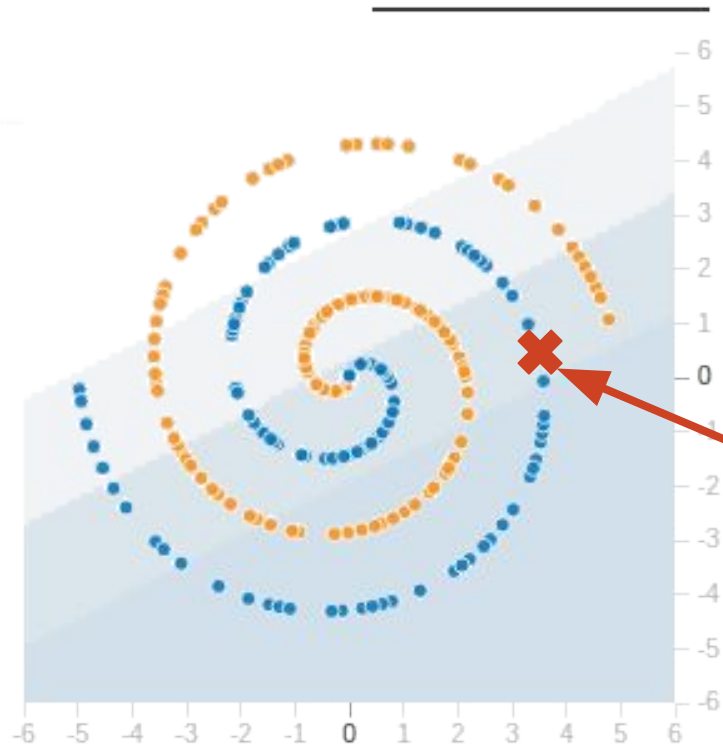
# What is machine learning?



# What is machine learning?

Automated model building

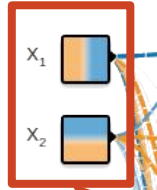




Is a point here  
blue or orange?

## FEATURES

Which properties do  
you want to feed in?



$X_1^2$



$X_2^2$



$X_1 X_2$



$\sin(X_1)$



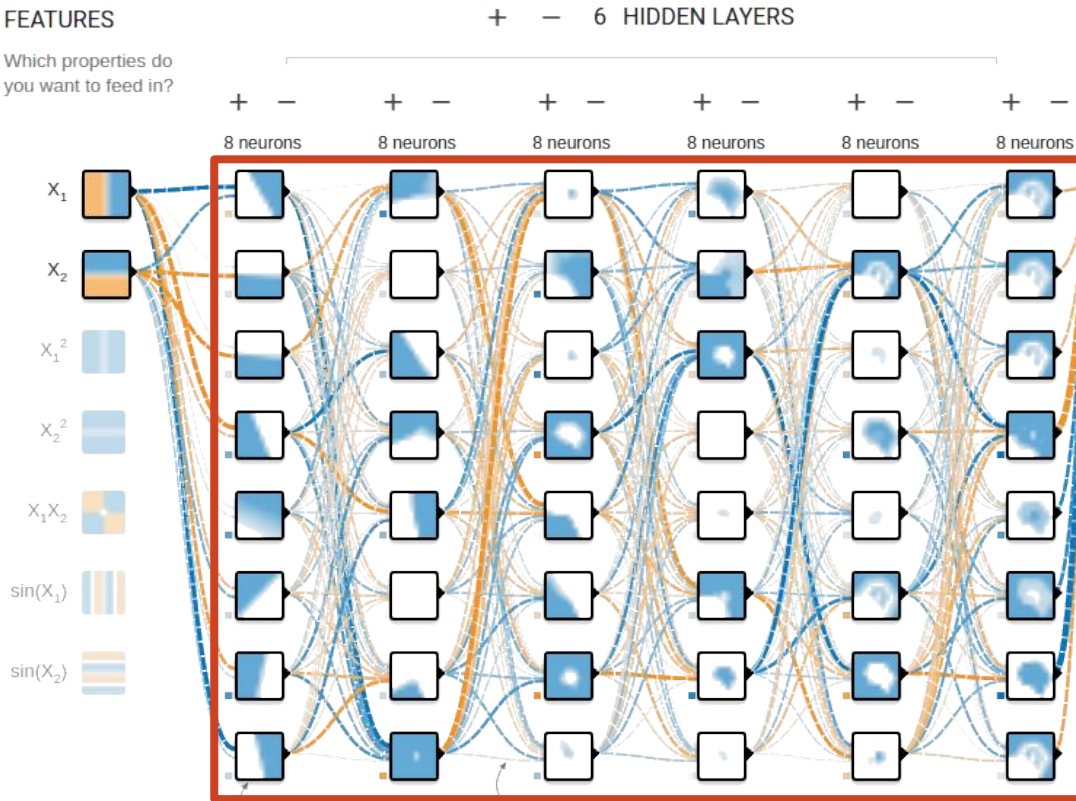
$\sin(X_2)$



Low-level  
information - X and  
Y coordinates

## FEATURES

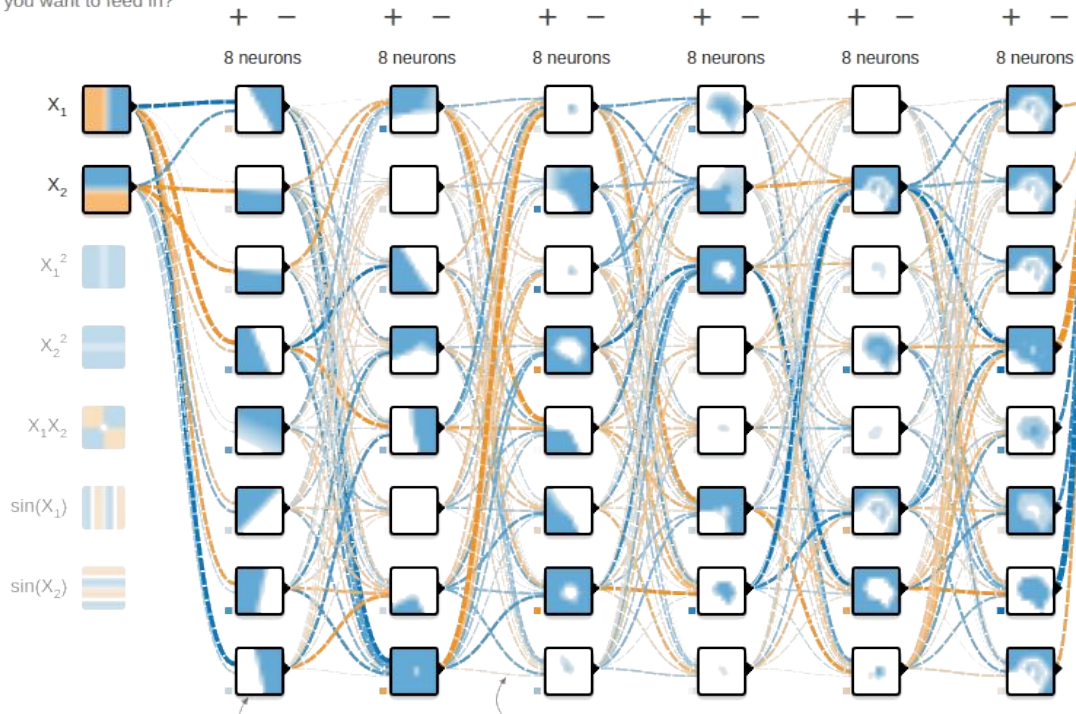
Which properties do you want to feed in?



Flexible system to learn map between inputs and target function:  
 $X, Y \rightarrow \text{blue/orange}$

## FEATURES

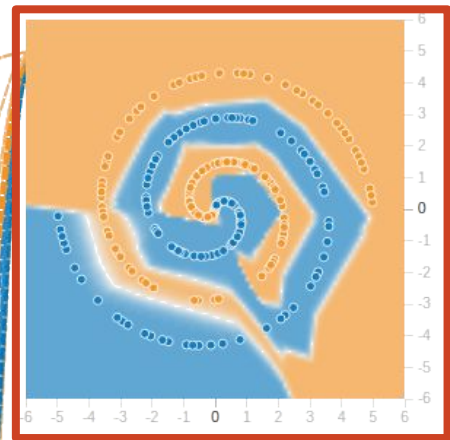
Which properties do you want to feed in?



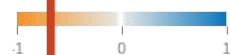
## OUTPUT

Test loss 0.056

Training loss 0.001



Colors shows data, neuron and weight values.



☐ Show test data

☐ Discretize output

Train on example data






Simple  
example



High-energy  
physics



Simple  
example



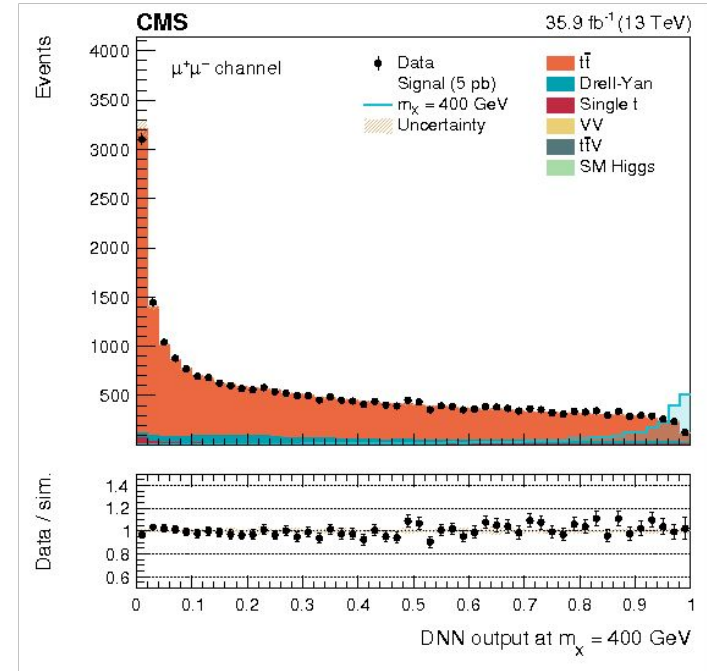
High-energy  
physics

Data and desired outputs are  
more complex

Underlying principle is the same

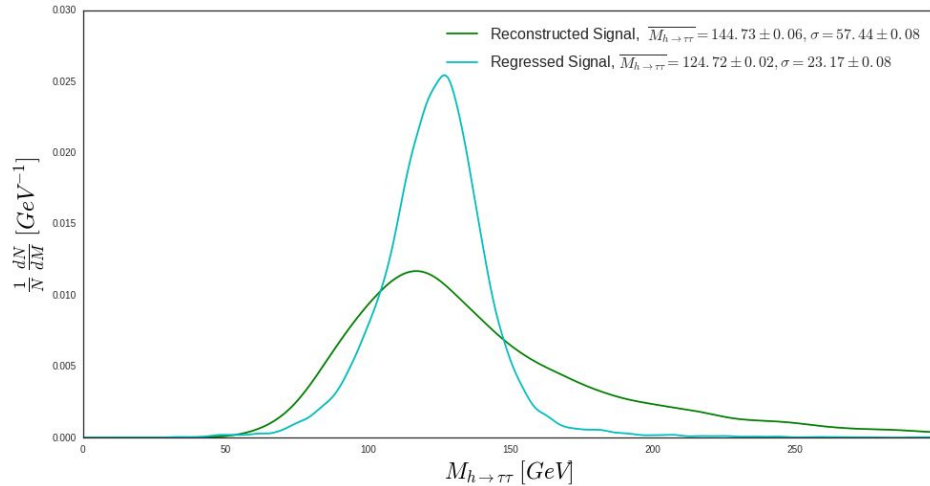
# Event classification

- Search for rare processes by predicting what process occurs in a particle collision
- E.g. Di-Higgs production - [1708.04188](#)



# Mass regression

- Predict the mass of a decayed particle from knowledge of its decay products
- E.g. Higgs to tau tau -  
AMVA<sub>4</sub>NP:WP1-D1



# Reduce systematic uncertainties

- Use *adversarial training* to build classifiers which are immune to unknown model parameters
- Helps improve inference of other model parameters, e.g. cross-section of a particular process
- E.g. [Learning to Pivot with Adversarial Networks](#) and [Adversarial learning to eliminate systematic errors: a case study in High Energy Physics](#)

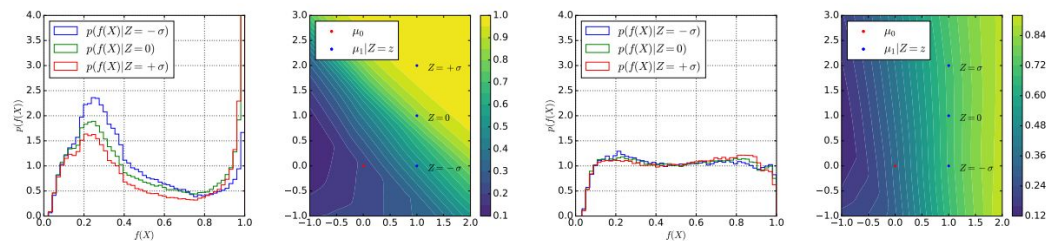


Figure 2: Toy example. (Left) Conditional probability densities of the decision scores at  $Z = -\sigma, 0, \sigma$  without adversarial training. The resulting densities are dependent on the continuous parameter  $Z$ , indicating that  $f$  is not pivotal. (Middle left) The associated decision surface, highlighting the fact that samples are easier to classify for values of  $Z$  above  $\sigma$ , hence explaining the dependency. (Middle right) Conditional probability densities of the decision scores at  $Z = -\sigma, 0, \sigma$  when  $f$  is built with adversarial training. The resulting densities are now almost identical to each other, indicating only a small dependency on  $Z$ . (Right) The associated decision surface, illustrating how adversarial training bends the decision function vertically to erase the dependency on  $Z$ .

# Jet physics

- Use convolutional and recurrent networks to classify jets according to origin process: [DeepJet](#)
- Recluster event using QCD-aware recursive networks to provide jet embeddings: [QCD-Aware Recursive Neural Networks for Jet Physics](#)

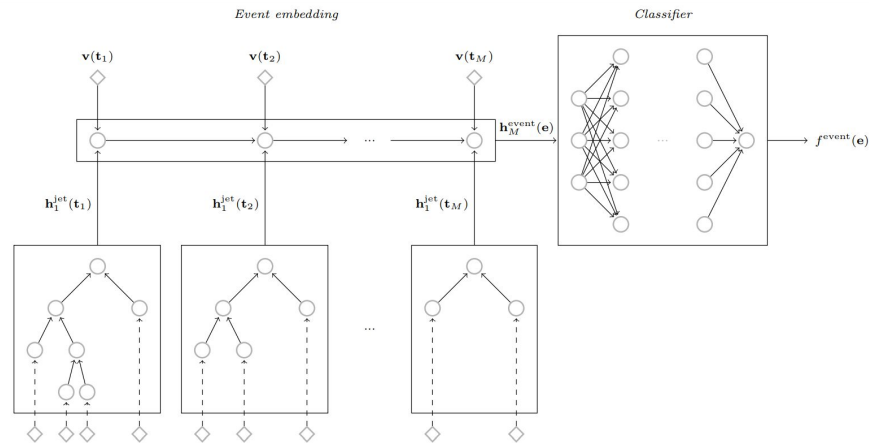


FIG. 2. QCD-motivated event embedding for classification. The embedding of an event is computed by feeding the sequence of pairs  $(\mathbf{v}(t_j), \mathbf{h}_1^{\text{jet}}(t_j))$  over the jets it is made of, where  $\mathbf{v}(t_j)$  is the unprocessed 4-momentum of the jet  $t_j$  and  $\mathbf{h}_1^{\text{jet}}(t_j)$  is its embedding. The resulting event-level embedding  $\mathbf{h}_M^{\text{event}}(\mathbf{e})$  is chained to a subsequent classifier, as illustrated in the right part of the figure.



# Many possible applications

Jet tagging

Particle ID

Event classification

Event triggering

Kinematic regression

Simulation

Detector design

Inference

# Further reading

- Play in browser: [Tensorflow playground](#), [gradient boosting playground](#)
- Seminars and lectures: [MLHEP-17](#), [Karpathy](#), [Hastie](#), [HEP repository](#)
- My resources: [NN summary posts](#), [example classifier](#)