Wenhao Ding

Ph.D. at Carnegie Mellon University

(+1) 412-616-6807
⋈ wenhaod@andrew.cmu.edu
' www.wenhao.pub
https://github.com/GilgameshD
in wenhaoding

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2019 – 2024 **Ph.D. Mechanical Engineering**, *Carnegie Mellon University*, Pittsburgh, the U.S.

2021 – 2022 **Secondary M.S. Machine Leaning**, Carnegie Mellon University, Pittsburgh, the U.S.

2019 – 2021 M.S. Mechanical Engineering, Carnegie Mellon University, Pittsburgh, the U.S.

Honors: 2019 Graduate Student Assembly/Provost Conference Funds

2014 – 2018 B.Eng. Electronic Engineering, Tsinghua University, Beijing, China.

Honors: Outstanding Undergraduate Thesis Award

Tsinghua University Technology Innovation Excellence Award (2016, 2017)

——— Publications

2021.1 Semantically Controllable Scene Generation with Guidance of Explicit Knowledge, Wenhao Ding, Bo Li, Kim Ji Eun, Ding Zhao, Preprint arXiv:2106.04066.

2020.10 Multimodal Safety-Critical Scenarios Generation for Decision-Making Algorithms Evaluation.

Wenhao Ding, Baimimng Chen, Bo Li, Kim Ji Eun, Ding Zhao,

IEEE Robotics and Automation Letters (RA-L)

IEEE International Conference on Robotics and Automation (ICRA) 2021, Xi'an, China.

- 2020.10 Context-Aware Safe Reinforcement Learning for Non-Stationary Environments, Baiming Chen, Zuxin Liu, Jiacheng Zhu, Mengdi Xu, Wenhao Ding, Liang Li, Ding Zhao, IEEE International Conference on Robotics and Automation (ICRA) 2021, Xi'an, China.
- 2020.6 Task-Agnostic Online Reinforcement Learning with an Infinite Mixture of Gaussian Processes,

Mengdi Xu, Wenhao Ding, Jiacheng Zhu, Zuxin Liu, Baiming Chen, Ding Zhao, Neural Information Processing Systems (NeurIPS) 2020, Vancouver.

2020.6 Deep Probabilistic Accelerated Evaluation: A Certifiable Rare-Event Simulation Methodology for Black-Box Autonomy,

Mansur Arief*, Zhiyuan Huang*, Guru Kumar, Yuanlu Bai, Wenhao Ding, Henry Lam, Ding Zhao, Artificial Intelligence and Statistics (AISTATS) 2021.

2020.3 Learning to Collide: An Adaptive Safety-Critical Scenarios Generating Method, Wenhao Ding, Baiming Chen, Minjun Xu and Ding Zhao,

IEEE International Conference on Intelligent Robots and Systems (IROS) 2020, Las Vegas.

2019.11 Adaptive Multi-scale Detection of Acoustic Events,

Wenhao Ding and Liang He,

IEEE/ACM Transactions on Audio, Speech, and Language Processing (T-ASLP).

2019.9 CMTS: Conditional Multiple Trajectory Synthesizer for Generating Safety-critical Driving Scenarios.

Wenhao Ding, Mengdi Xu and Ding Zhao,

IEEE International Conference on Robotics and Automation (ICRA) 2020, Paris, France.

2019.5 Prior Knowledge-based Regularization for Sound Event Localization and Detection, Wenhao Ding*, Jingyang Zhang* and Liang He,

Detection and Classification of Acoustic Scenes and Events Challenge 2019 (Task 3).

2019.2 Multi-Scale Time-Frequency Attention for Acoustic Event Detection, Jingyang Zhang, Wenhao Ding, Jintao Kang and Liang He, Interspeech 2019, Graz, Austria.

2018.7 A New Multi-vehicle Trajectory Generator to Simulate Vehicle-to-Vehicle Encounters, Wenhao Ding, Wenshuo Wang and Ding Zhao, IEEE International Conference on Robotics and Automation (ICRA) 2019, Montreal, Canada.

2018.1 MTGAN: Speaker Verification through Multitasking Triplet Generative Adversarial Networks.

Wenhao Ding and Liang He, Interspeech 2018, Hyderabad, India..

2018.4 Hierarchical Reinforcement Learning Framework towards Multi-agent Navigation, Wenhao Ding, Shuaijun Li and Huihuan Qian, IEEE International Conference on Robotics and Biomimetics (ROBIO) 2018, Malaysia.

2017.6 Vehicle Pose and Shape Estimation through Multiple Monocular Vision, Wenhao Ding, Shuaijun Li, Guilin Zhang, Xiangyu Lei and Huihuan Qian, IEEE International Conference on Robotics and Biomimetics (ROBIO) 2018, Malaysia.

Work experience

2018.11 Bosch Center for Artificial Intelligence, Pittsburgh, USA,

Machine Learning Research Intern.

Worked on the topic of traffic semantic understanding.

2018.11 Tsinghua University, Beijing, China,

Research Engineer.

Worked on the topic of acoustic event detection, especially abnormal sound detection in factories and railways.

2018.1 HongKong University of Science and Technology, HongKong, China,

Research Assistant.

Worked on the memory-based reinforcement learning methods for robots navigation.

2017.7 Chinese University of HongKong, HongKong, China,

Research Assistant.

Worked on robot localization in the Robotics and Artificial Intelligence Laboratory.

Technical ability

English: TOEFL: 108(S: 25), GRE: 151(V)+168(Q)+3.0

Languages: C/C++, Python, Matlab, Verilog

Technologies: ROS, CARLA Simulator, PyTorch, Altium Designer, STM32