WENHAO DING

https://github.com/GilgameshD

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EDUCATION

Carnegie Mellon University, Pittsburgh, USA

Aug 2019 - May 2024 (Expected)

Ph.D. Mechanical Engineering

Carnegie Mellon University, Pittsburgh, USA

Jan 2021 - Dec 2022

M.S. Machine Leaning

Tsinghua University, Beijing, China

Aug 2014 - July 2018

B.Eng. Electronic Engineering

RESEARCH INTERESTS

Critical Scenario Generation: Generate critical scenarios in digital twins for data collection.

Causal Discovery: Discover underlying causality for making interpretable decisions.

Improve generalization and robustness of autonomous agents.

HONORS & AWARDS

2022 - Qualcomm Innovation Fellowship Winner, North America

2022 - CMU K&L Gates Presidential Fellowship, College of Engineering nominee

2022 - NeurIPS Scholar Award

2019 - CMU Graduate Student Assembly/Provost Conference Funds

2018 - Tsinghua University Outstanding Undergraduate Thesis Award

2017 - 34th Tsinghua University Academic Challenge Cup (Second prize)

2016 - Fellowship of Spark Talents Program (50 recipients in Tsinghua per year)

PUBLICATION

Seeing is not Believing: Robust Reinforcement Learning against Spurious Correlation

*Wenhao Ding, *Laixi Shi, Yuejie Chi, Ding Zhao

Conference on Neural Information Processing Systems (NeurIPS) 2023

Bayesian Reparameterization of Reward-Conditioned Reinforcement Learning with Energy-based Models

*Wenhao Ding, *Tong Che, Ding Zhao, Marco Pavone

International Conference on Machine Learning (ICML) 2023

What Went Wrong? Closing the Sim-to-Real Gap via Differentiable Causal Discovery

Peide Huang, Xilun Zhang, Ziang Cao, Shiqi Liu, Mengdi Xu, **Wenhao Ding**, Jonathan Francis, Bingqing Chen, Ding Zhao

Conference on Robot Learning (CoRL) 2023

Learning to View: Decision Transformers for Active Object Detection

Wenhao Ding, Nathalie Majcherczyk, Mohit Deshpande, Xuewei Qi, Ding Zhao, Rajasimman Madhivanan, Arnie Sen

IEEE International Conference on Robotics and Automation (ICRA) 2023

Generalizing Goal-Conditioned Reinforcement Learning with Variational Causal Reasoning

Wenhao Ding, Haohong Lin, Bo Li, Ding Zhao

Conference on Neural Information Processing Systems (NeurIPS) 2022

SafeBench: A Benchmarking Platform for Safety Evaluation of Autonomous Vehicles *Chejian Xu, *Wenhao Ding, Weijie Lyu, Zuxin Liu, Shuai Wang, Yihan He, Hanjiang Hu, Ding Zhao, Bo Li Conference on Neural Information Processing Systems (NeurIPS) 2022

CausalAF: Causal Autoregressive Flow for Goal-Directed Safety-Critical Scenes Generation *Wenhao Ding*, *Haohong Lin*, *Bo Li*, *Ding Zhao* Conference on Robot Learning (**CoRL**) 2022

A Survey on Safety-critical Scenario Generation for Autonomous Driving

- A Methodological Perspective

Wenhao Ding, Chejian Xu, Haohong Lin, Bo Li, Ding Zhao

IEEE Transactions on Intelligent Transportation Systems (T-ITS), March, 2023

Semantically Controllable Scene Generation with Guidance of Explicit Knowledge *Wenhao Ding*, *Bo Li*, *Kim Ji Eun*, *Ding Zhao*

Environment Generation for Generalizable Robots (EGG) Workshop at **RSS** 2023 Knowledge and Logical Reasoning in the Era of Data-driven Learning Workshop at **ICML** 2023

Certifiable Deep Importance Sampling for Rare-Event Simulation of Black-Box Systems *Mansur Arief, Yuanlu Bai, Wenhao Ding, Shengyi He, Zhiyuan Huang, Henry Lam, Ding Zhao* Preprint arXiv:2111.02204

Trustworthy Reinforcement Learning Against Intrinsic Vulnerabilities: Robustness, Safety, and Generalizability

*Mengdi Xu, *Zuxin Liu, *Peide Huang, **Wenhao Ding**, Zhepeng Cen, Bo Li, Ding Zhao Preprint arXiv:2209.08025

Multimodal Safety-Critical Scenarios Generation for Decision-Making Algorithms Evaluation *Wenhao Ding*, *Baimimng Chen*, *Bo Li*, *Kim Ji Eun*, *Ding Zhao*IEEE Robotics and Automation Letters (**RA-L**)

Context-Aware Safe Reinforcement Learning for Non-Stationary Environments Baiming Chen, Zuxin Liu, Jiacheng Zhu, Mengdi Xu, Wenhao Ding, Liang Li, Ding Zhao IEEE International Conference on Robotics and Automation (ICRA) 2021

Task-Agnostic Online Reinforcement Learning with an Infinite Mixture of Gaussian Processes Mengdi Xu, Wenhao Ding, Jiacheng Zhu, Zuxin Liu, Baiming Chen, Ding Zhao Neural Information Processing Systems (NeurIPS) 2020

Deep Probabilistic Accelerated Evaluation: A Certifiable Rare-Event Simulation Methodology for Black-Box Autonomy

Mansur Arief*, Zhiyuan Huang*, Guru Kumar, Yuanlu Bai, Wenhao Ding, Henry Lam, Ding Zhao Artificial Intelligence and Statistics (AISTATS) 2021

Learning to Collide: An Adaptive Safety-Critical Scenarios Generating Method Wenhao Ding, Baiming Chen, Minjun Xu and Ding Zhao

IEEE International Conference on Intelligent Robots and Systems (IROS) 2020

Adaptive Multi-scale Detection of Acoustic Events

Wenhao Ding and Liang He

IEEE/ACM Transactions on Audio, Speech, and Language Processing (T-ASLP)

CMTS: Conditional Multiple Trajectory Synthesizer for Generating Safety-critical Driving Scenarios *Wenhao Ding*, *Mengdi Xu and Ding Zhao*

IEEE International Conference on Robotics and Automation (ICRA) 2020

A New Multi-vehicle Trajectory Generator to Simulate Vehicle-to-Vehicle Encounters

Wenhao Ding, Wenshuo Wang and Ding Zhao

IEEE International Conference on Robotics and Automation (ICRA) 2019

Prior Knowledge-based Regularization for Sound Event Localization and Detection

Wenhao Ding*, Jingyang Zhang* and Liang He

Detection and Classification of Acoustic Scenes and Events (DCASE) Challenge 2019 Task 3

Multi-Scale Time-Frequency Attention for Acoustic Event Detection

Jingyang Zhang, Wenhao Ding, Jintao Kang and Liang He

Interspeech 2019

MTGAN: Speaker Verification through Multitasking Triplet Generative Adversarial Networks

Wenhao Ding and Liang He

Interspeech 2018

Hierarchical Reinforcement Learning Framework towards Multi-agent Navigation

Wenhao Ding, Shuaijun Li and Huihuan Qian

IEEE International Conference on Robotics and Biomimetics (ROBIO) 2018

Vehicle Pose and Shape Estimation through Multiple Monocular Vision

Wenhao Ding, Shuaijun Li, Guilin Zhang, Xiangyu Lei and Huihuan Qian

IEEE International Conference on Robotics and Biomimetics (ROBIO) 2018

WORK EXPERIENCE

NVIDIA Research (Autonomous Vehicle Group), Santa Clara, CA, USA Research Scientist Intern	June 2023 - Now
Amazon Lab126, Sunnyvale, CA, USA Applied Scientist Intern	May 2022 - Aug 2022
Bosch Center for Artificial Intelligence, Pittsburgh, PA, USA Machine Learning Research Intern	May 2021 - Aug 2021
Tsinghua University, Beijing, China Research Engineer	July 2018 - Aug 2019
Chinese University of HongKong, HongKong, China Research Assitant	July 2017 - Sep 2017

ACADEMIC SERVICES

Conference Reviewer: ICML 22-23, ICLR 22-23, NeurIPS 21-23 (top reviewer), ECCV 22, CVPR 22-23,

ICCV 21-23, ICRA 20-23, IROS 20-23, ICME 20-23

Journal Reviewer: TMLR, IEEE RA-L, IEEE Access, IEEE T-ITS, IEEE TII, IEEE MM

Organizer: CVPR 2023 Secure and Safe Autonomous Driving Workshop and Challenge

ICRA 2022 SeasonDepth Challenge

Program Committee: NeurIPS 2022 ML4AD Workshop

NeurIPS 2022 TSRML Workshop

IJCAI 2022 AI4AD Workshop and Challenge

STUDENTS MENTORED

Miao Li, Ph.D. student in CMU	Aug 2022 - Now
Haohong Lin, Ph.D. student in CMU	Aug 2021 - Now
Shuai Wang, Master's student in CMU	Aug 2021 - May 2023
Guilin Zhang, Master's student in CMU, now in Google	Aug 2021 - May 2022
Yihan He, Master's student in CMU, now in DeepRoute	Aug 2021 - May 2022
Jiayi Xia, Master's student in CMU, now in Zoox	Oct 2021 - May 2022
Minjun Xu, Master's student in CMU, now in Akuna Capital	Oct 2020 - May 2021
Manoj Bhat, Master's student in CMU, now in Amazon	Oct 2020 - May 2021

INVITED TALKS

Critical Scenario Generation for Trustworthy Autonomy ZhiDongXi MOOCs (online), more than 1000 audiences	June 8 2023
Critical Scenario Generation for Trustworthy Autonomy Department of Electronic Engineeing, Tsinghua, China, host by Prof. Liang He (online)	Apr 12 2023
Critical Scenario Generation for Trustworthy Autonomy AISOC Lab, CMU, USA, host by Prof. Fei Fang	Mar 21 2023
Generalizing Goal-Conditioned Reinforcement Learning with Variational Causal Reaso AI Timer, China (online)	ning Feb 16 2023
Safety-critical Scenarios Generation with Causal Discovery Wayve, UK (online)	Oct 26 2022
Safety-Critical Driving Scenario Generation – and What Lessons We Have Learned University of Pennsylvania, USA (online), host by Prof. Rahul Mangharam	Feb 28 2022
Safety-critical Scenarios Generation for Autonomous Vehicles Stanford University, USA (online), host by Prof. Mykel Kochenderfer	Jan 31 2022