


WENHAO DING

 <https://github.com/GilgameshD>

 www.wenhao.pub

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EDUCATION

Carnegie Mellon University, Pittsburgh, USA

Aug 2019 - May 2024 (Expected)

Ph.D. Mechanical Engineering

Carnegie Mellon University, Pittsburgh, USA

Jan 2021 - Dec 2022

M.S. Machine Learning

Tsinghua University, Beijing, China

Aug 2014 - July 2018

B.Eng. Electronic Engineering

RESEARCH INTERESTS

Critical Digital Twin:

Generating critical scenarios in digital twin for autonomy development.

Adversarial Machine Learning:

Improving robustness by training against semantic adversarial examples.

Causal Reinforcement Learning:

Making generalizable decisions by discovering the underlying causality.

HONORS & AWARDS

2022 - Qualcomm Innovation Fellowship Winner, North America

2022 - CMU K&L Gates Presidential Fellowship, College of Engineering nominee

2022 - NeurIPS Scholar Award

2019 - CMU Graduate Student Assembly/Provost Conference Funds

2018 - Tsinghua University Outstanding Undergraduate Thesis Award

2017 - 34th Tsinghua University Academic Challenge Cup (*Second prize*)

2016 - Fellowship of Spark Talents Program (*50 recipients in Tsinghua per year*)

PUBLICATION

Seeing is not Believing: Robust Reinforcement Learning against Spurious Correlation

Wenhao Ding, Laixi Shi, Yuejie Chi, Ding Zhao

Workshop on Spurious Correlations, Invariance and Stability at **ICML** 2023

Bayesian Reparameterization of Reward-Conditioned Reinforcement Learning
with Energy-based Models

***Wenhao Ding**, ***Tong Che**, Ding Zhao, Marco Pavone

International Conference on Machine Learning (**ICML**) 2023

Learning to View: Decision Transformers for Active Object Detection

Wenhao Ding, Nathalie Majcherczyk, Mohit Deshpande, Xuwei Qi, Ding Zhao, Rajasimman Madhivanan,
Arnie Sen

IEEE International Conference on Robotics and Automation (**ICRA**) 2023

Generalizing Goal-Conditioned Reinforcement Learning with Variational Causal Reasoning

Wenhao Ding, Haohong Lin, Bo Li, Ding Zhao

Conference on Neural Information Processing Systems (**NeurIPS**) 2022

SafeBench: A Benchmarking Platform for Safety Evaluation of Autonomous Vehicles

***Chejian Xu**, ***Wenhao Ding**, Weijie Lyu, Zuxin Liu, Shuai Wang, Yihan He, Hanjiang Hu, Ding Zhao, Bo Li

Conference on Neural Information Processing Systems (**NeurIPS**) 2022

CausalAF: Causal Autoregressive Flow for Goal-Directed Safety-Critical Scenes Generation

Wenhao Ding, Haohong Lin, Bo Li, Ding Zhao

Conference on Robot Learning (**CoRL**) 2022

A Survey on Safety-critical Scenario Generation for Autonomous Driving

– A Methodological Perspective

Wenhao Ding, Chejian Xu, Haohong Lin, Bo Li, Ding Zhao

IEEE Transactions on Intelligent Transportation Systems (**T-ITS**), March, 2023

Trustworthy Reinforcement Learning Against Intrinsic Vulnerabilities: Robustness, Safety, and Generalizability

*Mengdi Xu, *Zuxin Liu, *Peide Huang, **Wenhao Ding**, Zhepeng Cen, Bo Li, Ding Zhao

Preprint arXiv:2209.08025

Semantically Controllable Scene Generation with Guidance of Explicit Knowledge

Wenhao Ding, Bo Li, Kim Ji Eun, Ding Zhao

Environment Generation for Generalizable Robots (EGG) Workshop at **RSS** 2023

Knowledge and Logical Reasoning in the Era of Data-driven Learning Workshop at **ICML** 2023

Certifiable Deep Importance Sampling for Rare-Event Simulation of Black-Box Systems

Mansur Arief, Yuanlu Bai, **Wenhao Ding**, Shengyi He, Zhiyuan Huang, Henry Lam, Ding Zhao

Preprint arXiv:2111.02204

Multimodal Safety-Critical Scenarios Generation for Decision-Making Algorithms Evaluation

Wenhao Ding, Baiming Chen, Bo Li, Kim Ji Eun, Ding Zhao

IEEE Robotics and Automation Letters (**RA-L**)

Context-Aware Safe Reinforcement Learning for Non-Stationary Environments

Baiming Chen, Zuxin Liu, Jiacheng Zhu, Mengdi Xu, **Wenhao Ding**, Liang Li, Ding Zhao

IEEE International Conference on Robotics and Automation (**ICRA**) 2021

Task-Agnostic Online Reinforcement Learning with an Infinite Mixture of Gaussian Processes

Mengdi Xu, **Wenhao Ding**, Jiacheng Zhu, Zuxin Liu, Baiming Chen, Ding Zhao

Neural Information Processing Systems (**NeurIPS**) 2020

Deep Probabilistic Accelerated Evaluation: A Certifiable Rare-Event Simulation

Methodology for Black-Box Autonomy

Mansur Arief*, Zhiyuan Huang*, Guru Kumar, Yuanlu Bai, **Wenhao Ding**, Henry Lam, Ding Zhao

Artificial Intelligence and Statistics (**AISTATS**) 2021

Learning to Collide: An Adaptive Safety-Critical Scenarios Generating Method

Wenhao Ding, Baiming Chen, Minjun Xu and Ding Zhao

IEEE International Conference on Intelligent Robots and Systems (**IROS**) 2020

Adaptive Multi-scale Detection of Acoustic Events

Wenhao Ding and Liang He

IEEE/ACM Transactions on Audio, Speech, and Language Processing (**T-ASLP**)

CMTS: Conditional Multiple Trajectory Synthesizer for Generating Safety-critical Driving Scenarios

Wenhao Ding, Mengdi Xu and Ding Zhao

IEEE International Conference on Robotics and Automation (**ICRA**) 2020

A New Multi-vehicle Trajectory Generator to Simulate Vehicle-to-Vehicle Encounters

Wenhao Ding, Wenshuo Wang and Ding Zhao

IEEE International Conference on Robotics and Automation (**ICRA**) 2019

Prior Knowledge-based Regularization for Sound Event Localization and Detection

Wenhao Ding*, Jingyang Zhang* and Liang He

Detection and Classification of Acoustic Scenes and Events (**DCASE**) Challenge 2019 Task 3

Multi-Scale Time-Frequency Attention for Acoustic Event Detection

Jingyang Zhang, **Wenhao Ding**, Jintao Kang and Liang He

Interspeech 2019

MTGAN: Speaker Verification through Multitasking Triplet Generative Adversarial Networks

Wenhao Ding and Liang He

Interspeech 2018

Hierarchical Reinforcement Learning Framework towards Multi-agent Navigation

Wenhao Ding, Shuaijun Li and Huihuan Qian

IEEE International Conference on Robotics and Biomimetics (**ROBIO**) 2018

Vehicle Pose and Shape Estimation through Multiple Monocular Vision

Wenhao Ding, Shuaijun Li, Guilin Zhang, Xiangyu Lei and Huihuan Qian

IEEE International Conference on Robotics and Biomimetics (**ROBIO**) 2018

WORK EXPERIENCE

Amazon Lab126, Sunnyvale, CA, USA

Applied Scientist Intern

May 2022 - Aug 2022

Bosch Center for Artificial Intelligence, Pittsburgh, PA, USA

Machine Learning Research Intern

May 2021 - Aug 2021

Tsinghua University, Beijing, China

Research Engineer

July 2018 - Aug 2019

Chinese University of HongKong, HongKong, China

Research Assitant

July 2017 - Sep 2017

ACADEMIC SERVICES

Conference Reviewer: ICML 22-23, ICLR 22-23, NeurIPS 21-23 (top reviewer), ECCV 22, CVPR 22-23, ICCV 21-23, ICRA 20-23, IROS 20-23, ICME 20-23

Journal Reviewer: TMLR, IEEE RA-L, IEEE Access, IEEE T-ITS, IEEE TII, IEEE MM

Organizer: CVPR 2023 Secure and Safe Autonomous Driving Workshop and Challenge
ICRA 2022 SeasonDepth Challenge

Program Committee: NeurIPS 2022 ML4AD Workshop
NeurIPS 2022 TSRML Workshop
IJCAI 2022 AI4AD Workshop and Challenge

STUDENTS MENTORED

Miao Li, *Ph.D. student in CMU*

Aug 2022 - Now

Haohong Lin, *Ph.D. student in CMU*

Aug 2021 - Now

Shuai Wang, *Master's student in CMU*

Aug 2021 - May 2023

Guilin Zhang, *Master's student in CMU, now in Google*

Aug 2021 - May 2022

Yihan He, *Master's student in CMU, now in DeepRoute*

Aug 2021 - May 2022

Jiayi Xia, *Master's student in CMU, now in Zoox*

Oct 2021 - May 2022

Minjun Xu, *Master's student in CMU, now in Akuna Capital*

Oct 2020 - May 2021

Manoj Bhat, *Master's student in CMU, now in Amazon*

Oct 2020 - May 2021

INVITED TALKS

Critical Scenario Generation for Trustworthy Autonomy <i>ZhiDongXi MOOCs (online), more than 1000 audiences</i>	<i>June 8 2023</i>
Critical Scenario Generation for Trustworthy Autonomy <i>Department of Electronic Engineering, Tsinghua, China, host by Prof. Liang He (online)</i>	<i>Apr 12 2023</i>
Critical Scenario Generation for Trustworthy Autonomy <i>AISOC Lab, CMU, USA, host by Prof. Fei Fang</i>	<i>Mar 21 2023</i>
Generalizing Goal-Conditioned Reinforcement Learning with Variational Causal Reasoning <i>AI Timer, China (online)</i>	<i>Feb 16 2023</i>
Safety-critical Scenarios Generation with Causal Discovery <i>Wayve, UK (online)</i>	<i>Oct 26 2022</i>
Safety-Critical Driving Scenario Generation – and What Lessons We Have Learned <i>University of Pennsylvania, USA (online), host by Prof. Rahul Mangharam</i>	<i>Feb 28 2022</i>
Safety-critical Scenarios Generation for Autonomous Vehicles <i>Stanford University, USA (online), host by Prof. Mykel Kochenderfer</i>	<i>Jan 31 2022</i>