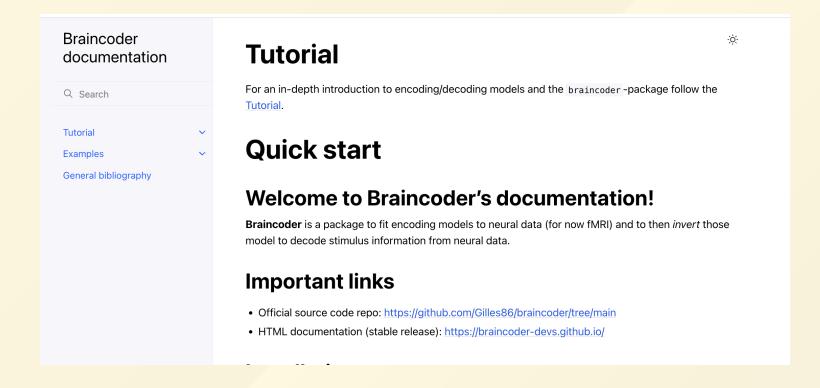
braincoder: (Encoding &) Decoding Neural Data



Gilles de Hollander

braincoder

- Developed at University of Amsterdam, Spinoza Centre for Neuroimaging and UZH
- Maintainer
 - Gilles de Hollander
- Contributors
 - Tomas Knapen (UvA/Spinoza Centre for Neuroimaging)
 - Marco Aqil (UvA/Spinoza Centre for Neuroimaging)
 - Maike Renkert (UZH)
- Upcoming paper
- Extensive documentation: <u>braincoder-devs.github.io</u>

braincoder

Key features:

- Massive computationa optimisation thanks to Tensorflow and GPUs
- Ease-of-use
- All standard models implemented
- Inversion of encoding models

1. Encoding Models: Mapping Stimulus → BOLD

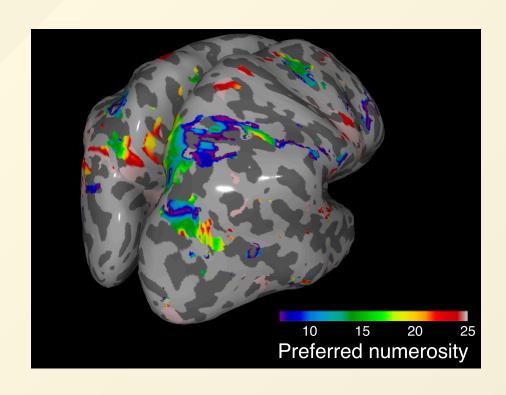
Deterministic mapping:

$$f(s; \theta): s \mapsto y$$

- s: Stimulus (e.g., orientation, numerosity, 2D image)
- y: BOLD response (single voxel y or pattern Y)
- θ: Parameters (e.g., PRF center/dispersion, amplitude, baseline)

Example: 1D Gaussian PRF

$$f(s; \boldsymbol{\mu}, \sigma, a, b) = a \cdot \mathcal{N}(s; \boldsymbol{\mu}, \sigma) + b$$



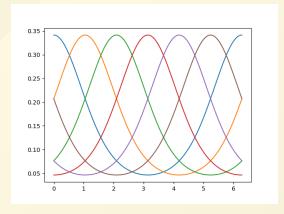
2. Linear Encoding Models

- "Jehee approach"
- Fixed neural populations (fixed θ) + linear weights:

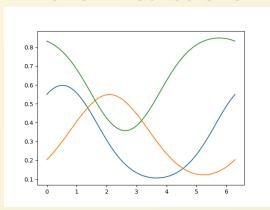
$$x_j = \sum_i W_{i,j} \cdot f_j(heta_j)$$

- Advantage: Fit weights (W) with linear regression (fast! Can be done with standard fMRI analyses packages.).
- Disadvantages:
 - Parameters are not interpretable
 - Model mispecification?
- **Example**: Von Mises tuning curves for orientation.

Basis Functions



Voxel Predictions



3. Building the Likelihood

• Add Gaussian noise to deterministic models:

$$p(x|s; heta) = f(s; heta) + \epsilon, \quad \epsilon \sim \mathcal{N}(0,\Sigma)$$

- Covariance matrix (Σ):
 - Regularized estimate (shrinkage + neural population overlap).
 - Accounts for voxel-to-voxel noise correlations.

Key:

• Enables Bayesian inversion (stimulus decoding).

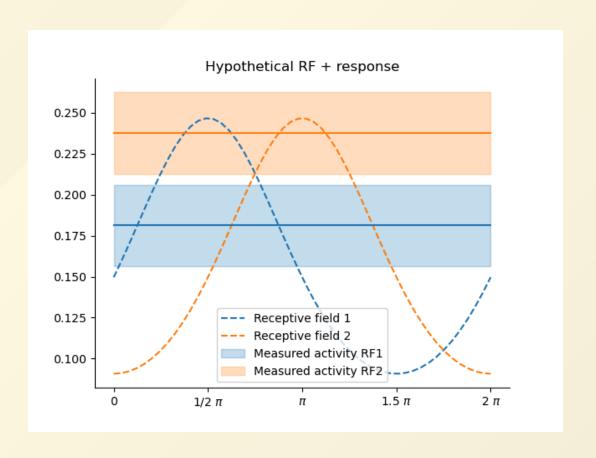
4. From Neural Responses → Stimulus Features

Bayes' Rule:

$$p(s|x, heta) = rac{p(x|s, heta)p(s)}{p(x)}$$

Approach:

• Keep θ and s fixed, and evalute/estimate/sample over s.



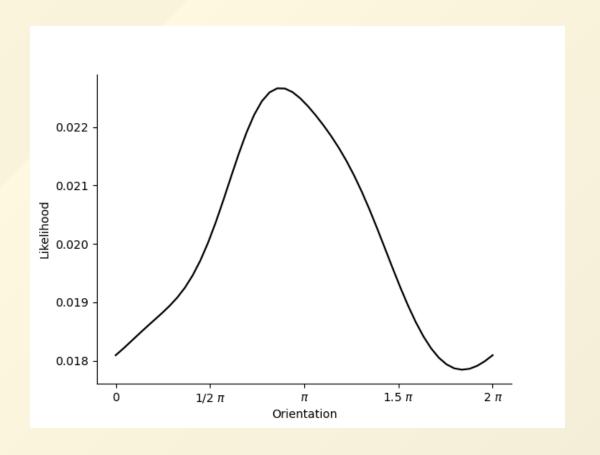
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5. Decoding Noisy Neural Data

Steps:

- 1. Fit encoding model (θ) (grid + gradient descent).
- 2. Estimate noise covariance (Σ).
- 3. Compute **posterior** $(p(s|x;\theta))$.
- 4. Extract mean posterior or MAP estimate.
- 5. (Extract uncertainy surrounding posterior)

Key Takeaways

- **Encoding**: Map stimuli to BOLD (linear/non-linear models).
- **Decoding**: Invert models using Bayesian inference + noise modeling.
- Tools:
 - braincoder can do all of this and leverages **TensorFlow** for fast,
 GPU-accelerated fitting.

Your Turn:

• Try fitting a PRF model to your own data!

Example code for PRF fit

```
from braincoder.models import GaussianPRF2DWithHRF
from braincoder.hrf import SPMHRFModel
from braincoder.optimize import ParameterFitter
# Set up model, including HRF
hrf_model = SPMHRFModel(tr=1.7)
model = GaussianPRF2DWithHRF(grid_coordinates=grid_coordinates, hrf_model=hrf_model)
# Set up fitter
fitter = ParameterFitter(data=v1_ts, model=model, paradigm=stimulus)
# Define grid search parameters
mu_x = np.linspace(-3, 3, 20, dtype=np.float32)
mu_y = np.linspace(-3, 3, 20, dtype=np.float32)
sigma = np.linspace(0.1, 5, 20, dtype=np.float32)
baselines = [0.0]
amplitudes = [1.0]
grid_pars = fitter.fit_grid(mu_x, mu_y, sigma, baselines, amplitudes, use_correlation_cost=True)
 # Refine baseline and amplitude using OLS
grid_pars = fitter.refine_baseline_and_amplitude(grid_pars)
gd_pars = fitter.fit(init_pars=grid_pars)
```

Assigment 4: Decoding visual stimuli

Open notebooks/4_decode.ipynb.