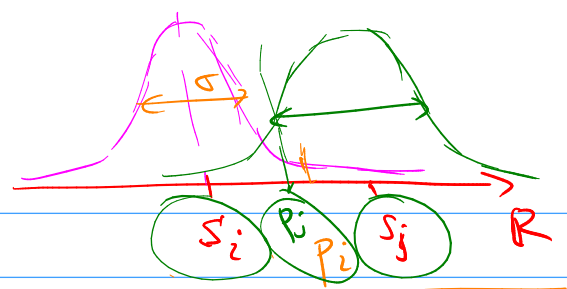


$$X = \{x_1, \dots, x_n\} \rightarrow \mathbb{R}$$



Bradley-Terry models

$$i \rightarrow \delta_i$$

$$p(i \succ j) = \frac{\delta_i}{\delta_i + \delta_j}$$

$$p_i > p_j + \epsilon \Rightarrow i \text{ temp.}$$

$$p_j > p_i + \epsilon \Rightarrow j \text{ --}$$

$$|p_i - p_j| \leq \epsilon \Rightarrow \text{unstable}$$

TrueSkill  
Expectation Propagation

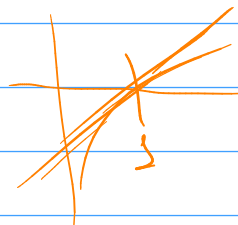
$$p(D|\bar{\delta}) = \prod_{(i,j) \in D} \frac{\delta_i}{\delta_i + \delta_j} \xrightarrow{\bar{\delta}} \max$$

$$\prod_i \prod_j \left( \frac{\delta_i}{\delta_i + \delta_j} \right)^{w_{ij}}$$

$$\log p(D|\bar{\delta}) = \sum_i \sum_j (w_{ij} \log \delta_i - w_{ij} \log(\delta_i + \delta_j)) \xrightarrow{\bar{\delta}} \max$$

MM-aly

minorization -  
maximization



$$\log a \leq a - 1$$

$$a = 1$$

$$a = \frac{\delta_i + \delta_j}{\delta_i^{(m)} + \delta_j^{(m)}}$$

$$\log \frac{\delta_i + \delta_j}{\delta_i^{(m)} + \delta_j^{(m)}} \leq \frac{\delta_i + \delta_j}{\delta_i^{(m)} + \delta_j^{(m)}} - 1$$

$$\log \frac{\delta_i}{\delta_i + \delta_j} = \log \delta_i - \log(\delta_i + \delta_j) \geq \log \delta_i - \frac{\delta_i + \delta_j}{\delta_i^{(m)} + \delta_j^{(m)}} + 1 - \log(\delta_i^{(m)} + \delta_j^{(m)})$$

$$L(\bar{\delta}, \bar{\delta}^{(m)}) \leq \log p(D|\bar{\delta})$$

$$\bar{\delta}^{(m+1)} := \operatorname{argmax}_{\bar{\delta}} L(\bar{\delta}, \bar{\delta}^{(m)})$$

$$\sum_i \sum_j w_{ij} \left( \log \delta_i - \frac{\delta_i + \delta_j}{\delta_i^{(m)} + \delta_j^{(m)}} + 1 - \log(\delta_i^{(m)} + \delta_j^{(m)}) \right)$$

$$\frac{\partial L}{\partial \gamma_k} = \sum_i \sum_j w_{ij} \left( \frac{[i=k]}{\gamma_k} - \frac{[i=k] + [j=k]}{\gamma_i^{(m)} + \gamma_j^{(m)}} \right) = 0$$

$= w_{kj} + w_{jk}$

$$\frac{1}{\gamma_k} \left( \sum_i w_{ki} \right) - \sum_{\text{neighbors } k \rightarrow o} \frac{N_{kj}}{\gamma_k^{(m)} + \gamma_j^{(m)}} = 0$$

$\sum_i w_{ki} \equiv W_k$

$$\gamma_k^{(m+1)} = W_k \cdot \left( \sum_j \frac{N_{kj}}{\gamma_k^{(m)} + \gamma_j^{(m)}} \right)^{-1}$$

$$p(i > j) = \frac{\gamma_i}{\gamma_i + \theta \gamma_j}$$

$$p(j > i) = \frac{\gamma_j}{\gamma_j + \theta \gamma_i}$$

$$p(i \equiv j) = 1 - \frac{(\dots)(\dots) - \gamma_i(\dots) - \gamma_j(\dots)}{(\gamma_j + \theta \gamma_i)(\gamma_i + \theta \gamma_j)}$$

$$p(\pi(z_{1:n}))$$

Generalized EM



$$\theta^{(m+1)}: Q(\theta^{(m+1)}, \theta^{(m)}) > Q(\theta^{(m)}, \theta^{(m)})$$

Monte Carlo EM

$$Q(\theta, \theta^{(m)}) = \mathbb{E}_{z \sim p(z|x, \theta^{(m)})} [\log p(x, z | \theta)] \approx \frac{1}{R} \sum_{r=1}^R \log p(x, z^{(r)} | \theta) \quad z^{(r)} \sim p(z|x, \theta^{(m)})$$

$\theta \rightarrow \max$

EM = emp. param.

~~EM~~

$$\theta_{MAP} = \arg \max_{\theta} p(\theta | X) = \arg \max_{\theta} (\log p(X | \theta) + \log p(\theta))$$

E-voor

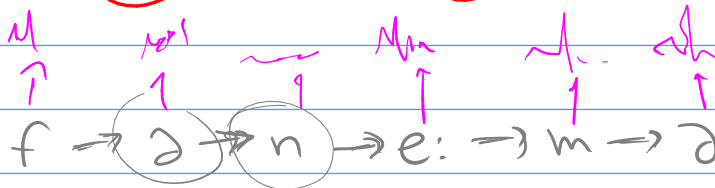
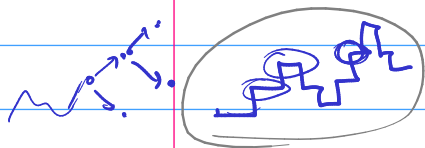
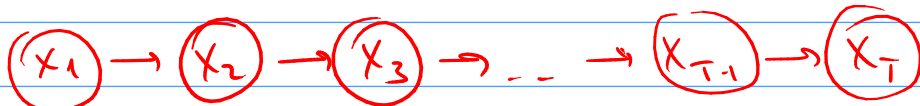
$$Q(\theta, \theta^{(m)}) = E_z [\log p(X, z | \theta)]$$

M-was

$$\theta^{(m+1)} = \arg \max_{\theta} (Q(\theta, \theta^{(m)}) + \log p(\theta))$$

## Hidden Markov models

Markov chain:



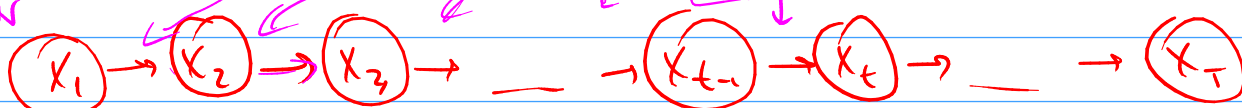
$$p(x_t | x_1, \dots, x_{t-2}, x_{t-1}) = p(x_t | x_{t-1})$$

Language model:

$$p(w_n | w_{n-1})$$

$$p(w_n | w_{n-1}, w_{n-2})$$

$$p(x_1) = \pi$$



$$x_t \in \{1, \dots, n\}$$

$$p(x_t = i) = \pi_i$$

$$p(x_t = j | x_{t-1} = i) = a_{ij}$$

$$\pi_i^* = \frac{[x_1 = i] + 1}{N + n}$$

$$(\pi, A)$$

$$A = \begin{pmatrix} & j \\ i & a_{ij} \end{pmatrix}$$

$$a_{ij}^* = \frac{[x_t = j, x_{t-1} = i] + 1}{[x_{t-1} = i] + n}$$

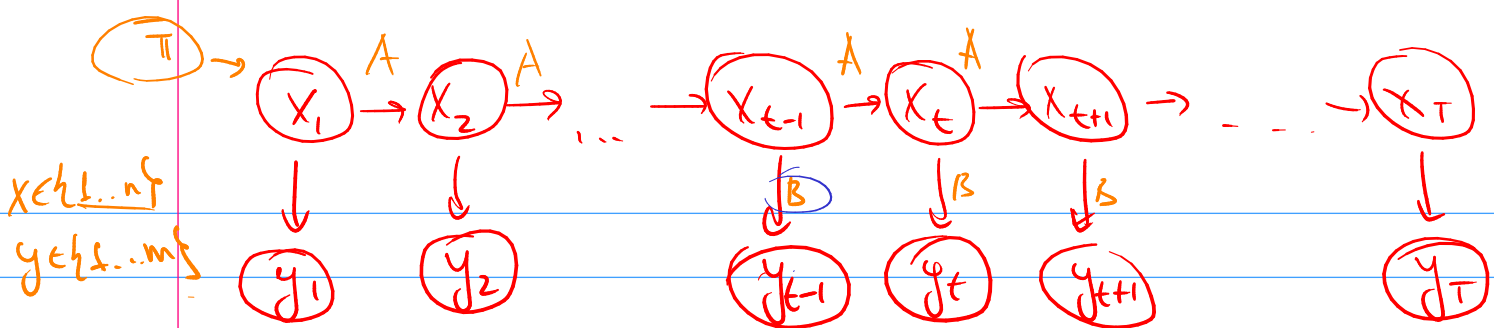
CG-content

$x_1, x_2, x_3$   
↓ ↓ ↓

$x_{t-1}, x_t$

$x_{t-1} \rightarrow x_t$

ATCGCGAGCAGTTATGTACGCGCTCC

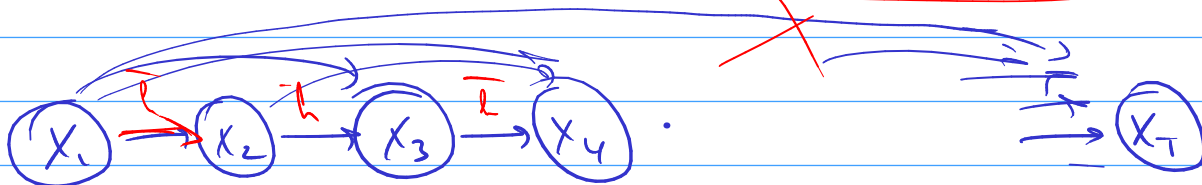


$$\pi_i = p(x_1 = i)$$

$$p(x_t = j | x_{t-1} = i) = a_{ij}$$

$$b_j(k) = p(y_t = k | x_t = j)$$

$$p(x_1, x_2, \dots, x_{T-1}, x_T) = p(x_1) p(x_2 | x_1) p(x_3 | x_1, x_2) \dots p(x_T | x_1, \dots, x_{T-1})$$

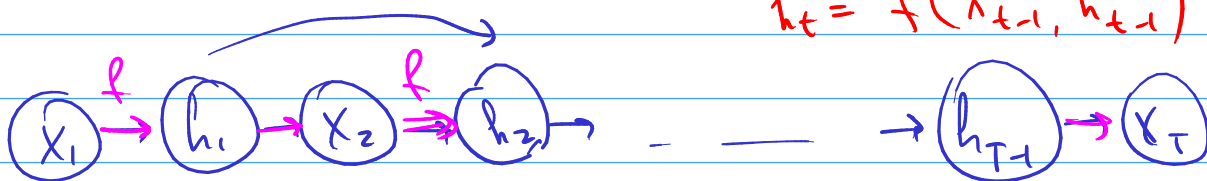


Markov chain  $p(x_t | x_1, \dots, x_{t-1}) = p(x_t | x_{t-1})$

RNN:

$$p(x_t | x_1, \dots, x_{t-1}) = p(x_t | h_t)$$

$$h_t = f(x_{t-1}, h_{t-1})$$



$$D = d_1, \dots, d_T$$

$$p(D, Q | \pi, A, B) = \pi_{q_1} \cdot b_{q_1}(d_1) \cdot a_{q_1, q_2} \cdot$$

$$Q = q_1, \dots, q_T$$

$$\cdot b_{q_2}(d_2) a_{q_2, q_3} \dots a_{q_{T-1}, q_T} b_{q_T}(d_T)$$

$$p(D | \pi, A, B) = \sum_{q_1, \dots, q_T} \pi_{q_1} b_{q_1}(d_1) a_{q_1, q_2} \dots a_{q_{T-1}, q_T} b_{q_T}(d_T) \rightarrow \max_{\pi, A, B}$$

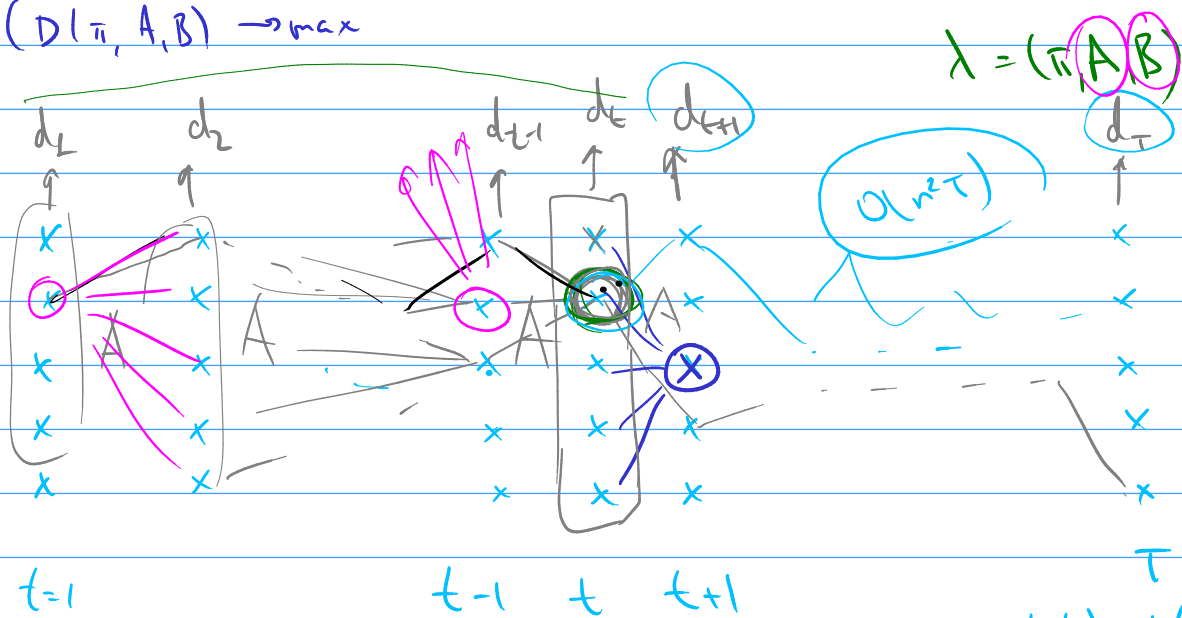
$$\pi \quad 1 \times n \quad A \quad n \times n \quad B \quad n \times m$$

$x \in \{1..n\}$   
 $y \in \{1..m\}$

1)  $p(D|\pi, A, B) = ?$

$$2) \quad p(Q | D, \pi, A, B) \xrightarrow{Q} \max$$

$$3) \quad p(D|\pi, A, B) \rightarrow \max$$



1)  $p(D|\pi, A, B)$

$$\alpha_t(i) = p(d_1, \dots, d_t, q_t = i \mid \lambda)$$

$$\alpha_1(i) = p(d_1, q_1=i | \lambda) = \pi_i b_i(d_1)$$

$$L_{t+1}(i) = p(d_t, d_{t+1}, q_{t+1} = i | \lambda) =$$

$$= \sum_j p(\underbrace{d_{t-1}, d_t, d_{t+1}}_{\text{past, present, future}}, \underbrace{q_{t+1}=i}_{\text{next}}, \underbrace{q_t=j}_{\text{current}} | \lambda) =$$

$$= \sum_j p(d_{t-1}, q_t = j | \lambda) p(d_{t+1}, q_{t+1} = i | q_t = j, d_{t-1}, \lambda)$$

$$= \sum_j \alpha_t(j) a_{ji} b_i(d_{t+1})$$

$$\alpha_i(i) = \pi_i b_i(d_i)$$

$$d_{t+1}(i) = \sum_j d_t(j) a_{ji} b_i(d_{t+1})$$

$$p(D|\lambda) = \prod_i \alpha_{\tau}(i)$$

$$\beta_t(i) = p(d_{t+1}, \dots, d_T | q_t = i, \lambda)$$

$$\beta_T(i) = 1$$

$$\beta_t(i) = \sum_j p(d_{t+1}, \overbrace{d_{t+2}, \dots, d_T}^{}, q_{t+1}=j | q_t=i, \lambda) =$$

$$= \sum_j p(d_{t+2}, \dots, d_T | \underline{q_{t+1}=j}, \cancel{d_{t+1}}, \cancel{q_t=i}, \lambda) \cdot$$

$$\underbrace{\beta_T(i)=1}_{\beta_t(i)=1} \cdot p(d_{t+1}, q_{t+1}=j | q_t=i, \lambda) =$$

$$\boxed{\beta_t(i) = \sum_{j=1}^n \beta_{t+1}(j) a_{ij} b_j(d_{t+1})}$$

$$\beta_1(i) = p(d_2, \dots, d_T | \textcircled{q_1=i}, \lambda)$$

$$\underbrace{p(D|\lambda)} = \sum_i p(d_1, d_2, \dots, d_T, q_1=i | \lambda) =$$

$$= \sum_i \pi_i b_i(d_1) \beta_1(i)$$

$$\left. \begin{array}{l} 2) p(Q | D, \lambda) \xrightarrow{Q} \max \\ p(q_t | D, \lambda) \xrightarrow{q_t} \max \end{array} \right\} \text{inference b HMM}$$

$$p(q_t=i | D, \lambda) = \frac{p(D, q_t=i | \lambda)}{p(D|\lambda)} = \frac{p(d_1, \dots, d_t, q_t=i, d_{t+1}, \dots, d_T | \lambda)}{p(D|\lambda)}$$

$$= \frac{p(d_1, \dots, d_t, q_t=i | \lambda) \cdot p(d_{t+1}, \dots, d_T | \textcircled{q_t=i}, \cancel{d_1}, \dots, \cancel{d_t}, \lambda)}{p(D|\lambda)}$$

$$\gamma_t(i) = p(q_t=i | D, \lambda) \propto \alpha_t(i) \cdot \beta_t(i)$$

$$Q^* = \arg \max p(q_1 - q_T | D, \lambda) = \arg \max p(q_1 - q_T, D | \lambda)$$

Viterbi algorithm

$$\delta_t(i) = \max_{q_1 \dots q_{t-1}} p(q_1 q_2 \dots q_{t-1}, q_t = i, d_1 \dots d_t | \lambda)$$

$$\delta_1(i) = \pi_i b_i(d_1)$$

$$\delta_{t+1}(i) = \max_{q_1 \dots q_t} p(q_1 \dots q_t, q_{t+1} = i, d_1 \dots d_{t+1} | \lambda) =$$

$$= \max_j \left[ \max_{q_1 \dots q_{t-1}} p(q_1 \dots q_{t-1}, q_t = j, d_1 \dots d_t | \lambda) \cdot a_{ji} b_i(d_{t+1}) \right]$$

$$\delta_{t+1}(i) = \max_j \left[ \delta_t(j) a_{ji} b_i(d_{t+1}) \right]$$

$$3) p(D | \lambda) \xrightarrow{\lambda \leftarrow \pi, A, B} \max$$

Q

$$p(D, Q | \lambda) = \pi_{q_1} a_{q_1 q_2} b_{q_1}(d_1) \dots a_{q_{T-1} q_T} b_{q_T}(d_T)$$

$$L(\lambda, \lambda^{(m)}) = E_{Q \sim \lambda^{(m)}} [\ln p(D, Q | \lambda)] = E_{Q \sim \lambda^{(m)}} [\ln \pi_{q_1} + \ln a_{q_1 q_2} + \ln b_{q_1}(d_1) + \dots] \xrightarrow{\max}$$

$\ln p(y=d_1 | x=q_1)$

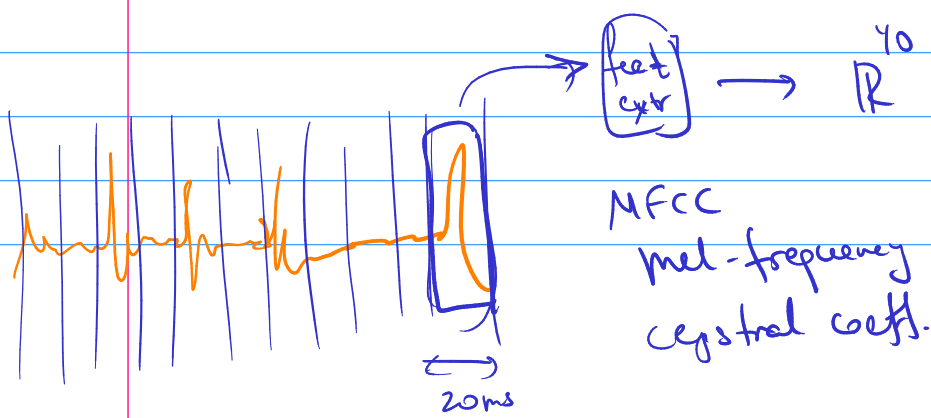
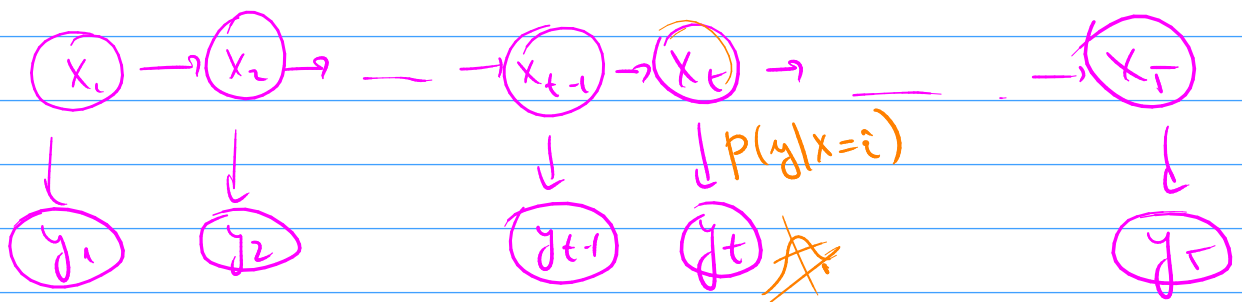
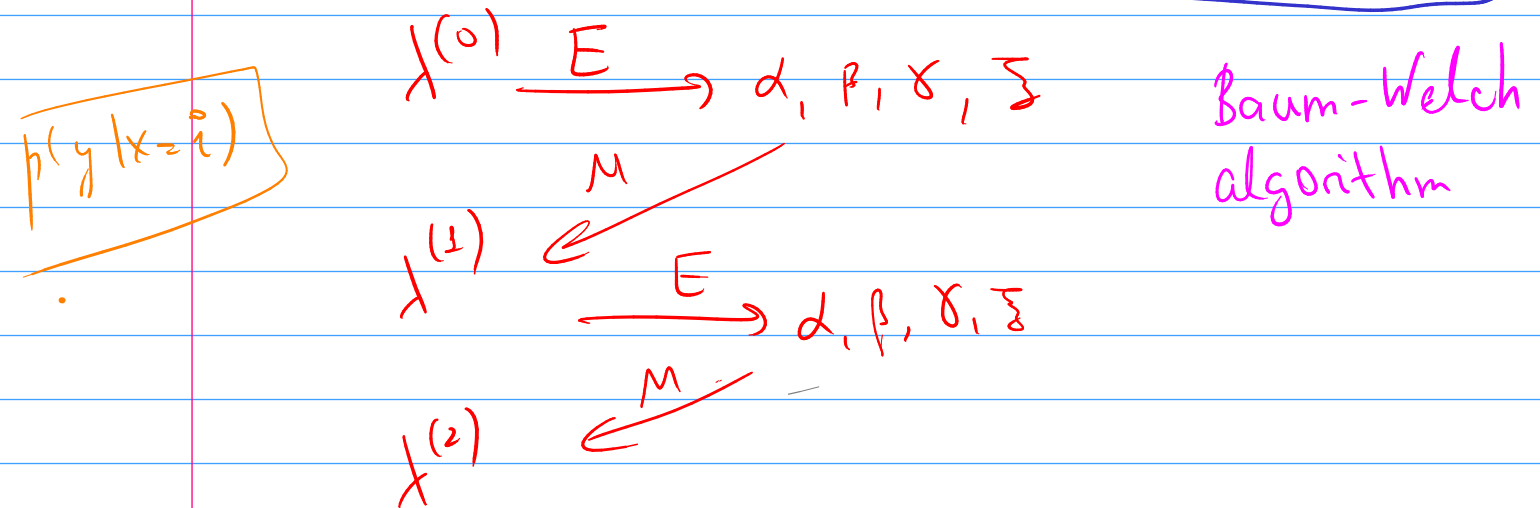
$$\pi_i^{(m+1)} = \frac{E[\# [q_1 = i]]}{N} = p(q_1 = i | D, \lambda^{(m)}) = \delta_1(i)$$

$$a_{ij}^{(m+1)} = \frac{\sum_t p(q_t = i, q_{t+1} = j | D, \lambda^{(m)})}{\sum_t p(q_t = i | D, \lambda^{(m)})} = \frac{\sum_t \delta_t(i, j)}{\sum_t \delta_t(i)}$$

$$\begin{aligned} \xi_t(i, j) &= p(q_t=i, q_{t+1}=j | D, \lambda^{(m)}) \propto p(q_t=i, q_{t+1}=j, D | \lambda^{(m)}) = \\ &= p(d_1-d_t, q_t=i | \lambda) p(q_{t+1}=j | q_t=i, \lambda) p(d_{t+1} | q_{t+1}=j) \end{aligned}$$

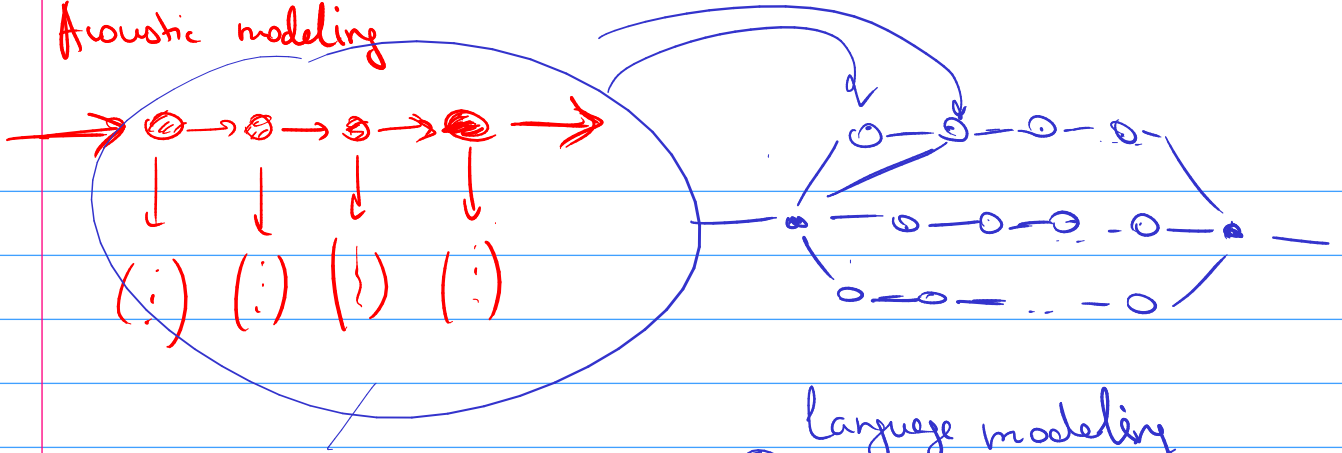
$$\begin{aligned} p(d_{t+2} \dots d_T | q_{t+1}=j, \lambda) &= \\ &= \alpha_t(i) a_{ij} b_j(d_{t+1}) \beta_{t+1}(j) \end{aligned}$$

$$\boxed{b_i(k) = \frac{\sum_t p(q_t=i, d_t=k | D, \lambda^{(m)})}{\sum_t p(q_t=i | D, \lambda^{(m)})} = \frac{\sum_{t: d_t=k} \gamma_t(i)}{\sum_t \gamma_t(i)}}$$





Acoustic modeling



[0. 1. 0]

$$CE \quad \sum_{i=1}^N p_i \log q_i$$

$$H(p, q) = KL(P||Q) + H(Q)$$

$$p = \frac{e^{a_i}}{\sum_j e^{a_j}}$$

softmax

$$a_i = \ln \left( \sum_j e^{a_j} \right)$$

↑  
logaddexp

exp, ln