In class, we described an algorithm for constraint propagation and search that used an explicit assignment function (referred to as σ). Today, we'll describe an equivalent algorithm that doesn't require an assignment function, which is instead implicit in the domains. We'll refer to it as the "implied assignment" version of the algorithm. It is as follows:

```
solve(problem: unary and binary constraints)
   - domains = init_domains()
   unary_sat(problem, domains) (apply unary constraints)
   - initialize stack as an empty stack
   - while true:
        - result = binary_prop(problem, domains) (propagate binary constraints)
        - if result reports no conflict:
            - if |domains[var]| = 1 for all var, this is a consistent assignment
            - orig_domains = copy(domains)
            - var, val = search(domains)
            - add (var, val, orig_domains) to stack
        - otherwise:
            - if stack is empty, there is no consistent assignment
            - backtrack(stack, domains)
unary_sat(problem: unary and binary constraints, domains: tile domains)
   - for each unary constraint c \in problem on variable var:
        - restrict domains[var] to satisfy c
binary_prop(problem: unary and binary constraints, domains: tile domains)
   - do until domains doesn't change:
        - for each binary constraint c ∈ problem on variables var1, var2:
            - if there exists val1 ∈ domains[var1] which doesn't satisfy c for any val2 ∈
              domains[var2]:
                remove val1 from domains[var1]
                - if |domains[var1]| = 0, there is a conflict
search(domains: domains)

    var = an unassigned spot (according to domains)

   - val = a possible num for var (according to domains)
   - restrict the domain of var to val.
backtrack(stack: history stack, domains: domains)

    pop (var, val, orig_domains) from stack

   - replace domains with orig_domains
   - remove val from the domain of var
```

```
solve(problem: unary constraints)
   - domains = init_domains()
   - restrict_domains(problem, domains)
   - initialize stack as an empty stack
   - while true:
        - if propagate(domains) reports no conflict:
            - if |domains[spot]| = 1 for all spots, this is a consistent assignment
            - orig_domains = copy(domains)
            - spot, num = search(domains)
            - add (spot, num, orig_domains) to stack
        - otherwise:
            - if stack is empty, there is no consistent assignment
            - domains = backtrack(stack)
propagate(domains: tile domains)
   - do until domains doesn't change:
        - for each spot on the board:
            - if |domains[spot]| = 1, remove spot's num from its peers' domains
            - if the above caused any domain to be empty, there is a conflict
search(domains: domains)
   - spot = an unassigned spot (according to domains)
   - num = a possible num for spot (according to domains)
   - restrict the domain of spot to num.
backtrack(stack: history stack, domains: domains)
   pop (spot, num, orig_domains) from stack
   - replace domains with orig_domains
   - remove num from the domain of spot
```

To show this algorithm's version of binary_prop (propagate) is correct, we must show that at termination, we have established arc-consistency.

- Suppose that after propagate(domains), there exists peers spot1, spot2 violating arc-consistency.
- This requires some $num1 \in domains[spot1]$ such that num1 = num2 for all $num2 \in domains[spot2]$.
- However, this can only be true if |domains[spot2]| = 1, in which case num1 would have been removed from domains[spot1] in propagate(domains), a contradiction.

We can also see that no value is removed from a domain unless it specifically violates arc-consistency. Therefore, propagate(domains) correctly establishes arc-consistency without removing anything more than necessary.

Check out demo.pdf to see this algorithm in action on a game of "Quadoku" (a 4×4 version of Sudoku).

Having run through the demo, you'll notice that our algorithm is pretty inefficient in a few ways! Think about how you can optimize it.

Note that there's a lot of freedom in how you implement search. Consider the following: assuming that a solution exists for domains, we have that, for any spot, if we were to select a num at random from domains[spot], the probability of selecting correctly (i.e. selecting a num that is assigned in some solution) is bounded below by:

$$\Pr(\mathtt{num} \sim \mathtt{domains}[\mathtt{spot}] \text{ is } \mathrm{correct}) \geq \frac{1}{|\mathtt{domains}[\mathtt{spot}]|},$$

which follows from the fact that at least one such num is correct. Therefore, it's reasonable to optimize for this lower bound by selecting

$$\underset{\mathtt{spot}}{\operatorname{arg\,min}} |\mathtt{domains}[\mathtt{spot}]|.$$