

Math115A 2/06 notes

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2023-02-07

Recall that we defined the notion of linear transformation from one vector space V to a vector space W , $T : V \rightarrow W$, when it satisfies $T(v_1 + v_2) = T(v_1) + T(v_2)$, $T(cv) = cT(v) \forall v_1, v_2, v \in V, \forall c \in F$

We also defined the null space (or kernel) of a linear $T : V \rightarrow W$ by $N(T) = \{v \in V : T(v) = 0_w\}$ and range of T , by $R(T) = \{T(v) : v \in V\}$

We proved in Theorem 11.12 that $N(T), R(T)$ are subspace of V respectively W

12.1 Theorem

Let V, W be vector spaces and $T : V \rightarrow W$ linear. If $S = \{v_1, \dots, v_m\} \subset V$ is a basis for V , then $R(T) = \text{span}(T(S)) = \text{span}\{T(v_1), T(v_2), \dots, T(v_n)\}$

Proof: We have $T(S) \subset T(V) = R(T)$ by the definitions, so $T(v_1), \dots, T(v_n) \in R(T)$ and since $R(T)$ is a subspace we get $\text{span}(\{T(v_1), \dots, T(v_n)\}) \subset R(T)$.

If $w \in R(T)$ is a vector in the range of T , then there exists $v \in V$ such that $T(v) = w$. But V is spanned by $\{v_1, \dots, v_n\}$ (because $\{v_1, \dots, v_n\}$ is a basis for V), so $\exists c_1, \dots, c_n \in F$ such that $v = \sum_{i=1}^n c_i v_i$. Thus $w = T(v) = T(\sum_{i=1}^n c_i v_i) = \sum_{i=1}^n c_i T(v_i) \in \text{span}\{T(v_1), \dots, T(v_n)\}$

12.2 Definitions

Let V, W be vector spaces and $T : V \rightarrow W$ linear. If $N(T), R(T)$ are finite dimensional then we define the nullity of T , denoted $\text{nullity}(T)$, to be the dimension of $N(T)$ and the rank of T , denoted $\text{rank}(T)$, to be the dimension of $R(T)$

So $\text{nullity}(T) = \dim(N(T))$, $\text{rank}(T) = \dim(R(T))$

12.3 Theorem (Dimension Theorem)

Let V, W be vector spaces and $T : V \rightarrow W$ linear. If V is finite dimensional then $\text{nullity}(T) + \text{rank}(T) = \dim(V)$

Proof: Let n denote the dimension of V and k then dimensional of $N(T)$, i.e. $n = \dim(V), k = \dim(N(T))$. Let $\{v_1, \dots, v_k\} \subset N(T)$ be a basis for $N(T)$. By corollary 11.3 $\{v_1, \dots, v_k\}$ can be extended to a basis $S = \{v_1, \dots, v_k, v_{k+1}, \dots, v_n\}$ for V

We'll show that $S_0 = \{T(v_{k+1}), T(v_{k+2}), \dots, T(v_n)\} \subset R(T) \subset W$ is a basis for $R(T)$

To see this, we need to show that the set S_0 spans $R(T)$ and is linearly independent

Indeed, since $v_1, \dots, v_k \in N(T)$ we have $T(v_1) = T(v_2) = \dots = T(v_k) = 0$

Thus $R(T) = \text{span}\{T(v_1), T(v_2), \dots, T(v_n)\} = \text{span}\{T(v_{k+1}), \dots, T(v_n)\} = \text{span}(S_0)$

To see that S_0 is linear independent assume $\sum_{i=k+1}^n c_i T(v_i) = 0$ for some $c_i \in F$ using linearity of T we get $T(\sum_{i=k+1}^n c_i v_i) = 0$ implying that $\sum_{i=k+1}^n c_i v_i \in N(T)$

Since $\{v_1, \dots, v_k\} \subset N(T)$ is a basis for $N(T)$ this implies $\exists c_1, \dots, c_k \in F$ such that $\sum_{i=1}^k c_i v_i = \sum_{i=k+1}^n c_i v_i$

Thus $\sum_{i=1}^n (-c_i) v_i + \sum_{i=k+1}^n c_i v_i = 0$ Since $S = \{v_1, \dots, v_k, v_{k+1}, \dots, v_n\}$ is a basis for V , this implies $c_i = 0$ for all $i = 1, 2, \dots, n$ in particular $c_{k+1}, \dots, c_n = 0$

Showing that $S_0 = \{T(v_{k+1}), \dots, T(v_n)\}$ is indeed linearly independent

Thus, S_0 is a basis for $R(T)$ and so $\dim(R(T))$ equals the number of elements in S_0 , which is $n - k$

Thus $\dim(V) = k + (n - k) = \dim(N(T)) + \dim(R(T))$

12.4 Theorem

Let V, W be vector spaces and $T : V \rightarrow W$ linear. Then T is one to one iff $N(T) = \{0\}$

Proof: if T is one to one and $v \in N(T)$, then $T(v) = 0_w$ implies $v = 0_v$, so we get $N(T) = \{0\}$

If conversely $N(T) = \{0\}$ and we have $T(v_1) = T(v_2)$ for some $v_1, v_2 \in V$, then $0_w = T(v_1) - T(v_2) = T(v_1 - v_2)$ so $v_1 - v_2 \in N(T) = \{0\}$, Thus $v_1 - v_2 = 0_v$, implying $v_1 = v_2$, Thus showing T is one to one.

12.5 Theorem

Let V, W be finite dimensional vector space with $\dim(V) = \dim(W)$ and $T : V \rightarrow W$ linear. Then the following conditions are equivalent:

a) T is one to one (T is injective)

b) T is onto (T is surjective)

c) $\text{rank}(T) = \dim(V)$

Proof: From dimension Theorem 12.3 we have $\text{rank}(T) + \text{nullity}(T) = \dim(V)$ we showed in Theorem 12.4 that T is one to one iff $N(T) = \{0\}$ iff $\text{nullity}(T) = 0$

Thus, by $\text{rank}(T) + \text{nullity}(T) = \dim(V)$ we get T one to one iff $\text{rank}(T) = \dim(V)$ so (a) is equivalent to (c)

On the other hand, we have T is onto iff $R(T) = W$ iff $\text{rank}(T) = \dim(W)$ and from $\text{rank}(T) + \text{nullity}(T) = \dim(V)$ we get $\dim(W) = \dim(V)$ iff $\text{nullity}(T) = 0$ i.e. iff T is one to one

Thus shows that (b) is equivalent to (a), so all together (a)(b)(c) are all equivalent

12.6 Exercise

Show that $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ defined by $T(a, b, c) = (a - b, 2c)$ is onto

Solution It is easier to see what the kernel of T is: $N(T) = \{(a, b, c) \in \mathbb{R}^3 : T(a, b, c) = 0\}$ which by the definition of T means $(a, b, c) \in N(T)$ iff $a - b = 0, 2c = 0$ so $c = 0$ and $a = b$ so $N(T) = \{(a, a, 0) : a \in \mathbb{R}\}$. Thus $\text{nullity}(N(T)) = 1$ so by 12.3 $3 = \dim, \mathbb{R}^3 = \dim(N(T)) + \dim(R(T)) = 1 + \dim(R(T))$. SO $\dim(R(T)) = 3 - 1 = 2$