

115A/4 , Winter 2023

Lecture 7

Wed, Jan 25



- Last time we saw that "a few" vectors  $v_1, \dots, v_m$  in a vector space  $V$  could generate (span) the entire  $V$ , i.e. any other vector  $v \in V$  can be written as a linear combination of  $v_1, \dots, v_m$ . For instance, any matrix  $A \in M_{2 \times 2}(\mathbb{R})$  is a linear combination of  $\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$

- it is important to find "small" sets of vectors in  $V$  that span  $V$ , in other words "optimal", "most economical" ways to generate  $V$ .

Linear dependence & linear independence of vectors (§1.5)

7.1 Definition A subset of vectors  $S$  in a vector space  $V$  is linearly dependent if there

exist finitely many distinct vectors  $v_1, \dots, v_m \in S$  and scalars  $c_1, \dots, c_m \in F$  not all of them 0, such that  $c_1 v_1 + c_2 v_2 + \dots + c_m v_m = 0$

In other words: if one can express the vector 0 as a linear combination of distinct vectors in  $S$  with non-zero coefficients.

## 7.2 Example.

The set

$$S = \{ \underbrace{(-1, 1, 0)}_{v_1}, \underbrace{(1, -3, 2)}_{v_2}, \underbrace{(0, 1, -1)}_{v_3} \}$$

in  $\mathbb{R}^3$  is linearly dependent

because  $v_1 + v_2 + 2v_3 = 0$

$$\begin{aligned} \text{Indeed } & (-1, 1, 0) + (1, -3, 2) + 2(0, 1, -1) \\ &= (-1, 1, 0) + (1, -3, 2) + (0, 2, -2) \\ &= (-1, -3+2, 0+2-2) = (0, 0, 0) \end{aligned}$$

### 7.3. Definition

A subset  $S$  of

a vector space  $V$  is linearly independent if it is not linearly dependent.  
We then also say that the vectors in  $V$  are linearly independent.

### 7.4. Theorem. The set $S \subset V$ $\neq \emptyset$

is linearly independent iff  
a linear combination  $c_1v_1 + c_2v_2 + \dots + c_nv_n$   
of distinct vectors  $v_1, \dots, v_n \in S$   
with  $c_1, \dots, c_n \in F$  is equal to  
the vector  $0$  only when all  
coefficients  $c_1, \dots, c_n$  are zero,  
i.e.  $\sum_{i=1}^n c_i v_i = 0$  implies  $c_i = 0$   $\forall i$ .

Proof

By definition,  $S$  linearly independent means it is not linearly dependent. In other words,

The only way to write the vector

① as a linear combination of some distinct vectors  $v_1, \dots, v_m \in S$

is if we take all coefficients  $c_1, \dots, c_m \in F$  equal to 0.



### 7.5 Example

Let  $S = \{(1, 0, 0, -1), (0, 1, 0, -1), (0, 0, 1, -1), (0, 0, 0, 1)\} \subset \mathbb{R}^4$ .

Show that  $S$  is linearly independent.

Solution By Thm 7.4, we need to show that the only linear combination of  $v_1, v_2, v_3, v_4$  that equals 0 is the one in which all coefficients are 0, i.e. to prove that if

$$\left\{ \begin{array}{l} c_1(1, 0, 0, -1) + c_2(0, 1, 0, -1) + c_3(0, 0, 1, -1) \\ + c_4(0, 0, 0, 1) = 0 \end{array} \right.$$

Then  $c_1 = c_2 = c_3 = c_4 = 0$ .

Indeed  $\textcolor{blue}{(*)} = (c_1, 0, 0, -c_1)$   
 $+ (0, c_2, 0, -c_2) + (0, 0, c_3, -c_3)$   
 $+ (0, 0, 0, c_4) = (c_1, c_2, c_3, -c_1 - c_2 - c_3 + c_4)$

so  $\textcolor{blue}{(*)} = 0$  means

$$(c_1, c_2, c_3, -c_1 - c_2 - c_3 + c_4) = (0, 0, 0, 0)$$

i.e.  $c_1 = 0, c_2 = 0, c_3 = 0, -c_1 - c_2 - c_3 + c_4 = 0$

thus  $c_4 = 0$  as well.

so all coefficients  $c_1, c_2, c_3, c_4$  must be equal to 0, showing that indeed the set  $S$  is linearly independent.

### 7.6 Example

A set  $S$  consisting of just one non-zero vector,

$S = \{v\}$  with  $v \neq 0$ , is always linearly independent, because the only possible linear combination with vectors in  $S$  is  $c v$  with  $c \in F$ , and if  $c v = 0$  then  $c = 0$ . indeed,

for if  $c \neq 0$  then  $c v = 0$  implies

$$c^{-1}(c v) = 0$$

"

$(c^{-1}c)v = 0 \Rightarrow 1 \cdot v = v = 0$ , contradiction.



7.7. Theorem. Let  $V$  be a vector

space and  $S_1 \subset S_2 \subset V$  subsets of  $V$ .

(a) If  $S_2$  is linearly independent then  $S_1$  is linearly independent.

(b) If  $S_1$  is linearly dependent then  $S_2$  is linearly dependent.

Proof, we only need to prove (b)

because (a) is logically equivalent to (b).

If  $S_1$  is lin. dependent Then there exist distinct vectors  $v_1, \dots, v_m \in S_1$  and non-zero scalars  $c_1, \dots, c_m \in F$  such that  $c_1 v_1 + c_2 v_2 + \dots + c_m v_m = 0$ .

But because  $S_1 \subset S_2$ , the vectors  $v_1, \dots, v_m$  are in  $S_2$  as well, so in  $S_2$  we have  $c_1 v_1 + \dots + c_m v_m = 0$  with  $c_i \neq 0$  and  $v_i$  distinct, thus  $S_2$  lin. dependent



- The above Thm says that every subset of a lin. independent set is lin. independent

7.8 Theorem. Let  $V$  be a vector space and  $S \subset V$  a subset. Then  $S$  is linearly independent iff

for any (strictly) smaller subset  
 $S' \subsetneq S$ , we have  $\text{span}(S') \neq \text{span}(S)$

Proof. " $\Rightarrow$ " Assume  $S$  lin. indep. and let  $S' \subsetneq S$  be a subset,  $S' \neq S$ . Let  $v \in S \setminus S'$ . If by contradiction we assume  $\text{span}(S') = \text{span}(S)$ , then there exist  $v_1, \dots, v_m \in S'$  distinct and  $c_1, \dots, c_m \in F$  such that  $v = \sum_{i=1}^m c_i v_i$ . Thus,

$$c_1 v_1 + c_2 v_2 + \dots + c_m v_m - 1 \cdot v = 0$$

with  $v_1, \dots, v_m, v \in S$  distinct vectors

and  $c_1, c_2, \dots, c_m, -1$  not all  $= 0$

contradicting the fact that  $S$  is lin-indep.

" $\Leftarrow$ " Assume that  $\nexists S' \subsetneq S$  we have  $\text{span}(S') \neq \text{span}(S)$ . If  $S$  would be lin. dependent (by contradiction) then  $\exists v_1, \dots, v_m \in S$  distinct and  $c_1, \dots, c_m \in F$ ,  $\neq 0$ , such that  $c_1 v_1 + \dots + c_m v_m = 0$ . By Z.G

we know that we must have  $n \geq 2$ .

so  $c_1 v_1 = -c_2 v_2 - \dots - c_n v_n$

and multiplying both sides by  $\bar{c}_1$  we get

$$v_1 = -\frac{c_2}{c_1} v_2 - \dots - \frac{c_n}{c_1} v_n$$

Thus, if we take  $S' = S \setminus \{v_1\}$

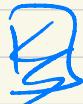
then  $v_1$  is in the linear span

of  $\{v_2, \dots, v_n\} \subset S'$ , thus

$$v_1 \in \text{span}(S')$$

so  $\text{span}(S') = \text{span}(S)$ ,

contradiction



• Another way to state Theorem 7.8 is this:

7.8' Let  $V$  be a vector space and  $S \subset V$  a linearly independent subset. Let  $v \in V$  be a vector that's not in  $S$ . Then  $S \cup \{v\}$

is linearly dependent iff  $v \in \text{span}(S)$

and  $S \cup \{v\}$  is linearly independent if  $v \notin \text{span}(S)$ .



7.9 Exercise.

Label the hell.

Statements as true/false with justification.

(a). Any set  $S \subset V$  with  $0 \in S$  is linearly dependent.

Answer: YES, because for any distinct  $x_1 = 0, x_2, \dots, x_n \in S$

we can take  $c_1 = 1, c_2 = c_3 = \dots = c_n = 0$  and get  $1 \cdot 0 + 0 \cdot x_1 + \dots + 0 \cdot x_n = 0$

(b). Subsets of linearly dependent sets are lin. dependent

Answer: NO For the subset

$$S = \{(1,0), (0,1), (-1,-1)\} \subset \mathbb{R}^2 \text{ is}$$

linearly dependent set, because  $x_1 + x_2 + x_3 = 0$ . But  $S' = \{(1,0), (0,1)\}$

is a linearly independent subset of  $S$

(c) subsets of lin. indep. sets are lin. indep.

Answer: YES thus it is part

Theorem 7.7



7.10 Exercise. Show that

$$S = \left\{ \begin{pmatrix} 1 & 1 \\ 0 & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 1 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 1 & 1 \end{pmatrix}, \begin{pmatrix} 1 & 0 \\ 1 & 0 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 0 & 1 \\ 0 & 1 \end{pmatrix} \right\}$$

$\subset M_{3 \times 2}(\mathbb{R})$  are linearly dependent

solution In general, to check

that  $v_1, \dots, v_5$  are lin. dep/indep we have to solve the system of equations resulting from

$$c_1 v_1 + c_2 v_2 + c_3 v_3 + c_4 v_4 + c_5 v_5 = 0$$

with the unknowns  $c_1, c_2, \dots, c_5$ .

if one gets just the only solution is when  $c_1 = c_2 = \dots = c_5 = 0$

Then  $\{v_1, \dots, v_5\}$  lin. indep.

If one gets more other solutions, where some  $c_i \neq 0$ , Then lin. dep.

In our case though one sees right away that

$$v_1 + v_2 + v_3 = \begin{pmatrix} 1 & 1 \\ 0 & 0 \\ 0 & 0 \end{pmatrix} + \begin{pmatrix} 0 & 0 \\ 1 & 1 \\ 0 & 0 \end{pmatrix} + \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 1 & 1 \end{pmatrix}$$
$$= \begin{pmatrix} 1 & 1 \\ 1 & 1 \\ 1 & 1 \end{pmatrix}$$

and also  $v_4 + v_5 = \begin{pmatrix} 1 & 0 \\ 1 & 0 \\ 1 & 0 \end{pmatrix} + \begin{pmatrix} 0 & 1 \\ 0 & 1 \\ 0 & 1 \end{pmatrix} =$ 
$$= \begin{pmatrix} 1 & 1 \\ 1 & 1 \\ 1 & 1 \end{pmatrix}$$
. Thus

$$v_1 + v_2 + v_3 = v_4 + v_5, \text{ in other words } v_1 + v_2 + v_3 - v_4 - v_5 = 0$$

so  $\{v_1, \dots, v_5\}$  lin. dep.

