Formalizing the implementation of Streaming NESL

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Introduction

NESL

- A functional nested data-parallel language
- Developed by Guy Blelloch in 1990s at CMU
- Highlights:
 - Highly expressive for parallel algorithms.
 Data-parallel construct: apply-to-each

$$\{e_1(x): x \text{ in } e_0\}$$

Example: compute $(\sum_{i=0}^{k-1} i^2)$ for $k \in [2, 3, 4]$ (result: [1,3,6]):

$$sum(\{i \times i : i \text{ in iota}(k)\})$$

- An intuitive cost model for time complexity: work-step model
 - work cost t₁: total number of operations executed
 - step cost t_{∞} : the longest chain of sequential dependency

Streaming NESL (SNESL)

- Experimental refinement of NESL
- Aiming at improving space-usage efficiency
- Work from Frederik M. Madsen and Andrzej Filinski in 2010s at DIKU
- Highlights:
 - Streaming semantics

```
\pi ::= \mathbf{bool} \mid \mathbf{int} \mid \mathbf{char} \mid \mathbf{real} \mid \cdots \qquad \text{(scalar types)}
\tau ::= \pi \mid (\tau_1, ..., \tau_k) \mid [\tau] \qquad \text{(concrete types)}
\sigma ::= \tau \mid (\sigma_1, ..., \sigma_k) \mid {\sigma} \qquad \text{(streamable types)}
```

- A space cost model
 - sequential space s₁: the minimal space to perform the computation
 - parallel space s_{∞} : space needed to achieve the maximal parallel degree (NESL's case)

SNESL syntax

Expressions

```
\begin{array}{ll} e ::= a \mid x \mid (e_1,...,e_k) \mid \textbf{let} \ x = e_1 \ \textbf{in} \ e_2 \mid \phi(e_1,...,e_k) \\ \\ \mid \{e_1 : \ x \ \textbf{in} \ e_0\} & \text{(general comprehension)} \\ \\ \mid \{e_1 \mid e_0\} & \text{(restricted comprehension)} \end{array}
```

Primitive functions

```
\begin{array}{lll} \phi & ::= \oplus \mid \ \ \mbox{append} \mid \mbox{concat} \mid \mbox{zip} \mid \mbox{iota} \mid \mbox{part} \mid \mbox{scan}_{\otimes} \mid \mbox{reduce}_{\otimes} \\ & \mid \mbox{mkseq} \mid \mbox{the} \mid \mbox{empty} & (\mbox{sequence operations}) \\ & \mid \mbox{length} \mid \mbox{elt} & (\mbox{vector operations}) \\ & \mid \mbox{seq} \mid \mbox{tab} & (\mbox{convertion between vector and sequence}) \\ & \oplus ::= + \mid \times \mid / \mid \mbox{=} \mid \mbox{not} \mid \cdots & (\mbox{scalar operations}) \\ & \otimes ::= + \mid \times \mid \mbox{max} \mid \dots & (\mbox{associative binary operations}) \end{array}
```

SNESL primitive functions

$append: \big(\{\sigma\}, \{\sigma\}\big) \to \{\sigma\}$	append two sequences; syntactic sugar: ++
$concat: \{\{\sigma\}\} \to \{\sigma\}$	flatten a sequence of sequences
$zip \colon \left(\{\sigma_1\},, \{\sigma_k\} \right) \to $	$zip(\{1,2\}, \{F,T\}) = \{(1,F), (2,T)\}$
$\{(\sigma_1,,\sigma_k)\}$	
$iota(\&) : int \to \{int\}$	&5 = {0,1,2,3,4}
$part: (\{\sigma\}, \{bool\}) \to \{\{\sigma\}\}$	$part(\{3,1,4\}, \{\mathtt{F},\mathtt{F},\mathtt{T},\mathtt{F},\mathtt{T},\mathtt{T}\}) = \{\{3,1\}, \{4\}, \{\}\}\}$
$scan_\otimes: \{int\} o \{int\}$	$scan_{+}(\&5) = \{0,0,1,3,6\}$
$reduce_\otimes: \{int\} \to int$	$reduce_+(\&5) = 10$
$mkseq: (\overbrace{\sigma,,\sigma}^k) \to \{\sigma\}$	$mkseq(1,2,3) = \{1,2,3\}$
$\overline{length(\#) \colon [\tau] \to int}$	length of a vector
$elt(!) \colon ([\tau],int) \to \tau$	element indexing, $[3,8,2]$! $1=8$
the : $\{\sigma\} \to \sigma$	return the element of a singleton, $\mathbf{the}(\{10\}) = 10$
$\boxed{empty: \{\sigma\} \to bool}$	test a sequence empty or not
$\boxed{seq:[\tau] \to \{\tau\}}$	$seq([1,2]) = \{1,2\}$
$tab: \{\tau\} \to [\tau]$	$tab(\{1,2\}) = [1,2]$
(.) . [.]	[1,2] $[1,2]$ $[2,2]$ $[2,2]$

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??[optional] Example program: Splitting a string into words

Implementation

Source language

Simplified SNESL types

```
\begin{split} \pi &::= \mathbf{bool} \mid \mathbf{int} & \text{(only two scalar types)} \\ \tau &::= \pi \mid (\tau_1, \tau_2) \mid \{\tau\} & \text{(no vectors, change tuples to pairs)} \\ \varphi &::= (\tau_1, ..., \tau_k) \to \tau & \text{(support recursion)} \end{split}
```

Syntax

```
\begin{array}{l} t ::= \mathbf{eval} \ e \ | \ d \ t \\ e ::= a \ | \ x \ | \ (e_1, e_2) \ | \ \mathbf{let} \ x = e_1 \ \mathbf{in} \ e_2 \ | \ \phi(e_1, ..., e_k) \\ | \ \{ \} \tau \ | \ \{e_1, ..., e_k\} \quad \  \  (k \geq 1) \\ | \ \{ e_1 : x \ \mathbf{in} \ e_0 \ \mathbf{using} \ x_1, ..., x_k \} \ | \ \{ e_1 \ | \ e_0 \ \mathbf{using} \ x_1, ..., x_k \} \\ | \ f(e_1, ..., e_k) \qquad \qquad \qquad \qquad \text{(user-defined function call)} \\ d ::= \mathbf{function} \ f(x_1 : \tau_1, ..., x_k : \tau_k) \colon \tau = e \end{array}
```

Source language

Key typing rules:

$$\frac{\Gamma \vdash_{\Sigma} e_0 : \{\tau_0\} \qquad [x \mapsto \tau_0, (x_i \mapsto \tau_i)_{i=1}^k] \vdash_{\Sigma} e_1 : \tau}{\Gamma \vdash_{\Sigma} \{e_1 : x \text{ in } e_0 \text{ using } x_1, ..., x_k\} : \{\tau\}} \begin{pmatrix} (\Gamma(x_i) = \tau_i) \\ \tau_i \text{ concrete} \end{pmatrix}_{i=1}^k \end{pmatrix}$$

$$\frac{\Gamma \vdash_{\Sigma} e_0 : \text{bool} \qquad [(x_i \mapsto \tau_i)_{i=1}^k] \vdash_{\Sigma} e_1 : \tau}{\Gamma \vdash_{\Sigma} \{e_1 \mid e_0 \text{ using } x_1, ..., x_k\} : \{\tau\}} ((\Gamma(x_i) = \tau_i)_{i=1}^k)$$

• Key evaluation rules:

$$\frac{\rho \vdash_{\Phi} e_0 \downarrow \{v_1, ..., v_l\} \qquad ([x \mapsto v_i, (x_j \mapsto \rho(x_j))_{j=1}^k] \vdash_{\Phi} e_1 \downarrow v_i)_{i=1}^l}{\rho \vdash_{\Phi} \{e_1 : x \text{ in } e_0 \text{ using } x_1, ..., x_k\} \downarrow \{v_1, ..., v_l\}}$$

$$\frac{(\rho \vdash_{\Phi} e_i \downarrow v_i)_{i=1}^k \qquad [(x_i \mapsto v_i)_{i=1}^k] \vdash_{\Phi} e_0 \downarrow v}{\rho \vdash_{\Phi} f(e_1, ..., e_k) \downarrow v}$$
where $\Phi(f) = f(x_1 : \tau_1, ..., x_k : \tau_k) : \tau = e_0$

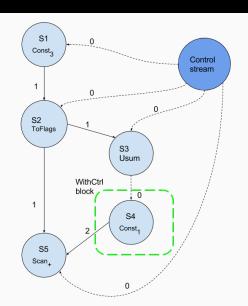
Target language: SVCODE

- SVCODE values:
 - primitive stream: $\vec{a} ::= \langle a_1, ..., a_l \rangle$ e.g., $\vec{a}_1 = \langle 1, 2 \rangle, \langle 0 | \vec{a}_1 \rangle = \langle 0, 1, 2 \rangle, \vec{b} = \langle F, T, F \rangle$
 - stream tree: $w := \vec{a} \mid (w_1, w_2)$
- SVCODE syntax

```
p ::= \epsilon \mid p_1; p_2
       | s := \psi(s_1, ..., s_k)
                                                                 (single stream definition)
       |S_{out}| := WithCtrl(s, S_{in}, p_1)
                                                                           (WithCtrl block)
       |(s'_1,...,s'_{k'}) := SCall f(s_1,...,s_k)
                                                                                 (function call)
s ::= 0 \mid 1 \mid \cdots \in \mathsf{SId} = \mathbb{N}
                                                                                    (stream ids)
S ::= \{s_1, ..., s_k\} \in \mathbb{S}
                                                                          (set of stream ids)
\psi ::= \mathtt{Const}_\mathtt{a} \mid \mathtt{ToFlags} \mid \mathtt{Usum} \mid \mathtt{Map}_\oplus \mid \mathtt{Scan}_+ \mid \mathtt{Reduce}_+ \mid \mathtt{Distr}
       | Pack | UPack | B2u | SegConcat | InterMerge | · · ·
                                                                                       (Xducers)
```

SVCODE dataflow

```
S1 := Const_3
S2 := ToFlags S1
S3 := Usum S2
[S4] := WithCtrl S3 []:
S4 := Const_1
S5 := ScanPlus S2 S4
```



Value representation

- Scalars are represented as singleton primitive streams: e.g., $3 \triangleright_{int} \langle 3 \rangle, T \triangleright_{bool} \langle T \rangle$
- A nested sequence with a nesting depth d is represented as a flattening data stream and d descriptor streams.

$$\begin{split} \left\{ \{3,1\}, \{4\} \right\} &\triangleright_{\left\{ \left\{ \text{int} \right\} \right\}} \left(\left(\langle 3,1,4 \rangle, \langle F,F,T,F,T \rangle \right), \langle F,F,T \rangle \right) \\ &\quad \left\{ T,F \right\} &\triangleright_{\left\{ \text{bool} \right\}} \left(\langle T,F \rangle, \langle F,F,T \rangle \right) \end{split}$$

A sequence of pairs is represented as a pair of sequences sharing one descriptor:

$$\{(1,T),(2,F),(3,F)\} \triangleright_{\{(\text{int},\text{bool})\}} ((\langle 1,2,3\rangle,\langle T,F,F\rangle),\langle F,F,F,T\rangle)$$

Translation

- **STree** \ni *st* ::= *s* | (*st*₁, *st*₂)
- Translation symbol table $\delta ::= [x_1 \mapsto st_1, ..., x_k \mapsto st_k]$
- General comprehension translation: {i+x: i in &3 using x} ⇒

```
1 ...
2 S4 := ... -- <1 > x
3 S5 := ... -- <F,F,F,T> descriptor of &3
4 S6 := ... -- <0,1,2> i
5 S7 := Usum S5; -- 1. generate new control: <() () ()>
6 S8 := Distr S4 S5; -- 2. replicate x 3 times: <1 1 1 >
7 [S9] := WithCtrl S7 [S6,S8]: -- 3. translate (i+x)
8 S9 := Map_+ S6 S8 -- <1,2,3>
```

 Restricted comprehension translation: Pack free variables instead of Distr

Translation continue

- Built-in function translation:
 - scan, reduce, concat, part, empty: translated to a single stream definition, e.g., $\operatorname{scan}_+((s_d, s_b)) \Rightarrow \operatorname{Scan}_+(s_b, s_d)$
 - the, iota translated to a few lines of code, e.g.,
 s₀ := ToFlags(s);

$$egin{align*} extbf{iota}(s) &\Rightarrow egin{align*} s_1 := exttt{Usum}(s_0); \ &\{s_2\} := exttt{WithCtrl}(s_1, \{\}, s_2 := exttt{Const}_1()); \ &s_3 := exttt{Scan}_+(s_0, s_2) \ \end{pmatrix}$$

- $++_{ au}$: translated recursively, depending on au
- User-defined functions: translated to SVCODE functions (i.e., SVCODE program with arguments), unfolded at runtime when interpreting a SCall

SVCODE interpreters

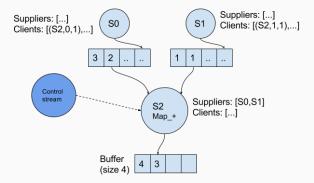
- Eager interpreter (NESL-like)
 - sufficient memory for allocating all streams at once
 - execute each instruction sequentially
 - an extreme/simplest case of the streaming one with the largest buffer size, used to compare results and analyze time complexity
- Streaming interpreter
 - limited buffer size, space-usage efficient
 - result is collected from each scheduling round
 - need effective scheduling strategy to avoid deadlock and guarantee cost preservation

SVCODE streaming interpreter

- Dataflow graph is similar to a Kahn process network
 - Graph node (a process): Proc = (BufState, S, Clis, Xducer)
 - Buffer state maintained by process:

BufState ::= Filling $\vec{a} \mid \text{Draining } \vec{a}' \ b$

A process example:



Recursion example

A function to compute factorial:

```
1 > function fact(x:int):int = if x <= 1 then 1 else x*fact(x-1)
2 > let x = {3,7,0,4} in {fact(y): y in x }
```

1st unfolding (will unfold 7 times in total):

```
-- Parameters: [S1]
                                         -- <3 7 0 4>
   ... -- compare parameters with 1, get S5 = <T T FT T>
   S6 := Usum S5; -- for elements <=1 -- < () >
   [S7] := WithCtrl S6 []: S7 := Const 1 -- < 1 >
5
   . . .
   S13 := Usum S11; -- for elementes >1 -- <()() ()>
   [S17] := WithCtrl S13 [S12]:
              S14 := Const 1
                                    -- <1 1 1>
              S15 := MapTwo Minus S12 S14 -- <2 6 3>
10
              [S16] := SCall fact [S15] -- <2 720 6>
                 recursive call
11
              S17 := MapTwo Times S12 S16 -- <6 5040 24>
12
   ... -- merge results
                                                                16/26
13
   S19 := PriSegInterS [(S7,S5),(S17,S11)]; -- <6 5040 1 24>
```

Formalization

Source language: SNESL₀

Types:

$$au ::= \mathsf{int} \mid \{ au_1\}$$

Expressions:

$$e ::= x \mid \text{let } x = e_1 \text{ in } e_2 \mid \phi(x_1, ..., x_k) \mid \{e : x \text{ in } y \text{ using } x_1, ..., x_k\}$$

 $\phi ::= \text{const}_n \mid \text{iota} \mid \text{plus}$

- Key evaluation rules with work cost W:
 - General comprehension:

$$\frac{([x \mapsto v_i, x_1 \mapsto n_1, ..., x_k \mapsto n_k] \vdash e \downarrow v_i \ \ \ W_i)_{i=1}^I}{\rho \vdash \{e : x \text{ in } y \text{ using } x_1, ..., x_k\} \downarrow \{v_1, ..., v_l\} \ \ \ W$$
where $\rho(y) = \{v_1, ..., v_l\}, (\rho(x_i) = n_i)_{i=1}^k$, and
$$W = (k+1) \cdot (l+1) + \sum_{i=1}^l W_i$$

Built-in function:

$$\frac{\phi(v_1,...,v_k) \downarrow v}{\rho \vdash \phi(x_1,...,x_k) \downarrow v \$ \left(\sum_{i=1}^k |v_i|\right) + |v|} \left((\rho(x_i) = v_i)_{i=1}^k \right)$$

Target language: SVCODE₀

syntax

$$p ::= \epsilon \mid s := \psi(s_1, ..., s_k) \mid S_{out} := \texttt{WithCtrl}(s, S_{in}, p_1) \mid p_1; p_2$$

- key semantics with work cost
 - Empty new control stream $(\sigma(s_c) = \langle \rangle)$:

$$\overline{\langle S_{out} := \mathtt{WithCtrl}(s_c, S_{\mathit{in}}, p_1), \sigma \rangle \Downarrow^{\vec{c}} \sigma[(s_i \mapsto \langle \rangle)_{i=1}^k] \$ \ 1}$$

where
$$\forall s \in \{s_c\} \cup S_{in}.\sigma(s) = \langle \rangle$$
, $S_{out} = \{s_1, ..., s_k\}$

Nonempty new control stream $(\sigma(s_c) = \vec{c}_1 \neq \langle \rangle)$: $\langle p_1, \sigma \rangle \Downarrow^{\vec{c}_1} \sigma'' \$ W_1$

$$\langle S_{out} := \mathtt{WithCtrl} \big(s_c, S_{in}, p_1 \big), \sigma \rangle \Downarrow^{\vec{c}} \sigma[\big(s_i \mapsto \sigma''(s_i) \big)_{i=1}^k \big] \ \$ \ W_1 + 1$$

 $\begin{array}{c} \bullet \quad \mathsf{Xducers,} \; ((\sigma(s_i) = \vec{a}_i)_{i=1}^k) \\ \qquad \qquad \qquad \psi(\vec{a}_1,...,\vec{a}_k) \Downarrow^{\vec{c}} \vec{a} \\ \hline \langle s := \psi(s_1,...,s_k), \sigma \rangle \Downarrow^{\vec{c}} \sigma[s \mapsto \vec{a}] \; \$ \; (\sum_{i=1}^k |\vec{a}_i|) + |\vec{a}| \end{array}$

Xducer semantics

• General semantics: **Judgment** $\psi(\vec{a}_1,...,\vec{a}_k) \Downarrow^{\vec{c}} \vec{a}$

$$\frac{\psi(\vec{a}_{11},...,\vec{a}_{k1})\downarrow\vec{a}_{01} \qquad \psi(\vec{a}_{12},...,\vec{a}_{k2})\Downarrow^{\vec{c}_0}\vec{a}_{02}}{\psi(\vec{a}_{1},...,\vec{a}_{k})\Downarrow^{\langle()|\vec{c}_0\rangle}\vec{a}_{0}}((\vec{a}_{i1}++\vec{a}_{i2}=\vec{a}_{i})_{i=0}^{k})$$

- $\bullet \quad \overline{\psi(\langle \rangle_1,...,\langle \rangle_k) \Downarrow^{\langle \rangle} \langle \rangle}$
- Specific semantics (part): **Judgment** $\psi(\vec{a}_1,...,\vec{a}_k)\downarrow\vec{a}$

$$\frac{}{\mathsf{Const}_{a}() \downarrow \langle a \rangle} \qquad \frac{}{\mathsf{ToFlags}(\langle n \rangle) \downarrow \langle F_{1}, ..., F_{n}, T \rangle} (n \geq 0)$$

$$\overline{\text{MapTwo}_{+}(\langle n_{1} \rangle, \langle n_{2} \rangle) \downarrow \langle n_{3} \rangle} (n_{3} = n_{1} + n_{2})$$

$$\frac{\mathtt{Usum}(\vec{b})\downarrow\vec{a}}{\mathtt{Usum}(\langle\mathtt{F}|\vec{b}\rangle)\downarrow\langle()|\vec{a}\rangle} \qquad \qquad \overline{\mathtt{Usum}(\langle\mathtt{T}\rangle)\downarrow\langle\rangle}$$

SVCODE_0 determinism

Definition (Stream prefix)

Judgment
$$\vec{a} \sqsubseteq \vec{a}'$$

$$\frac{\vec{a} \sqsubseteq \vec{a}'}{\langle \rangle \sqsubseteq \vec{a}'} \qquad \frac{\vec{a} \sqsubseteq \vec{a}'}{\langle a_0 | \vec{a} \rangle \sqsubseteq \langle a_0 | \vec{a}' \rangle}$$

Lemma (Blocks are self-delimiting)

If (i)
$$(\vec{a}'_i \sqsubseteq \vec{a}_i)_{i=1}^k$$
 and $\psi(\vec{a}'_1,...,\vec{a}'_k) \downarrow \vec{a}'$,
(ii) $(\vec{a}''_i \sqsubseteq \vec{a}_i)_{i=1}^k$ and $\psi(\vec{a}''_1,...,\vec{a}''_k) \downarrow \vec{a}''$,
then $(\vec{a}'_i = \vec{a}''_i)_{i=1}^k$, and $\vec{a}' = \vec{a}''$.

Lemma (Xducer determinism)

If
$$\psi(\vec{a}_1,...,\vec{a}_k) \Downarrow^{\vec{c}} \vec{a}_0$$
, and $\psi(\vec{a}_1,...,\vec{a}_k) \Downarrow^{\vec{c}} \vec{a}'_0$, then $\vec{a}_0 = \vec{a}'_0$.

Theorem (SVCODE₀ determinism)

If $\langle p, \sigma \rangle \Downarrow^{\vec{c}} \sigma' \$ W_1$ and $\langle p, \sigma \rangle \Downarrow^{\vec{c}} \sigma'' \$ W_2$, then $\sigma' = \sigma''$ and $W_1 = W_2$.

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Translation formalization

General comprehension translation:

$$\overline{S \Vdash s := \psi(s_1, ..., s_k) : \{s\}} \ (\{s_1, ..., s_k\} \subseteq S, s \notin S)$$

$$S_{in} \Vdash p_1 : S' \qquad ((S_i + i \in S)) \subseteq S \subseteq S \subseteq S' \subseteq S' \subseteq S' \subseteq S'$$

 $\frac{S_{in} \Vdash p_1 : S'}{S \Vdash S_{out} := \mathtt{WithCtrl}(s, S_{in}, p_1) : S_{out}} \left((S_{in} \cup \{s\}) \subseteq S, S_{out} \subseteq S', S \cap S' = \emptyset \right)$

Theorem

If $\delta \vdash e \Rightarrow_{s_1}^{s_0} (p, st), \forall x \in dom(\delta).\overline{\delta(x)} \subseteq S$, and $S \lessdot s_0$ 21/26 **then**, for some S', $S \Vdash p : S'$, $S' \subseteq \{s_0, s_0+1, ..., s_1-1\}$, and $\overline{st} \subseteq (S \cup S')$

Value representation formalization

• Value representation: **Judgment** $v \triangleright_{\tau} w$

$$\frac{(v_i \triangleright_{\tau} w_i)_{i=1}^l}{\{v_1, ..., v_l\} \triangleright_{\{\tau\}} (w, \langle F_1, ..., F_l, T \rangle)} (w = (++_{\tau} w_i)_{i=1}^l)$$

• Value recovery: **Judgment** $w \triangleleft_{\tau} v, w$

$$\frac{\langle n_0 | \vec{a} \rangle \triangleleft_{\mathbf{int}} n_0, \vec{a}}{\langle w \triangleleft_{\tau} v_1, w_1 w_1 \triangleleft_{\tau} v_2, w_2 \cdots w_{l-1} \triangleleft_{\tau} v_l, w_l} \frac{\langle w \triangleleft_{\tau} v_1, w_1 w_1 \triangleleft_{\tau} v_2, w_2 \cdots w_{l-1} \triangleleft_{\tau} v_l, w_l}{\langle w, \langle F_1, ..., F_l, T | \vec{b} \rangle \rangle \triangleleft_{\{\tau\}} \{v_1, ..., v_l\}, (w_l, \vec{b})}$$

Lemma (Recovery correctness)

If $v \triangleright_{\tau} w$, then $\forall w . (w + +_{\tau} w) \triangleleft_{\tau} v, w$.

Lemma (Recovery determinism)

If $w \triangleleft_{\tau} v, w'$, and $w \triangleleft_{\tau} v', w''$, then v = v', and w' = w''.

Corollary

If $v \triangleright_{\tau} w$, $v' \triangleright_{\tau} w$, then v = v'.

Parallelism fusion lemma

Definition (Store similarity)

$$\sigma_1 \overset{S}{\sim} \sigma_2$$
 iff $dom(\sigma_1) = dom(\sigma_2)$, and $\forall s \in S.\sigma_1(s) = \sigma_2(s)$

Definition (Store fusion)

For
$$\sigma_1 \stackrel{S}{\sim} \sigma_2$$
, $\sigma_1 \bowtie \sigma_2 = \sigma$ where $\sigma(s) = \begin{cases} \sigma_1(s) \ (= \sigma_2(s)), & s \in S \\ \sigma_1(s) + \sigma_2(s), & s \notin S \end{cases}$

Lemma (Xducer fusion)

If
$$\psi(\vec{a}_1,...,\vec{a}_k) \Downarrow^{\vec{c}} \vec{a}$$
, and $\psi(\vec{a}'_1,...,\vec{a}'_k) \Downarrow^{\vec{c}'} \vec{a}'$, then $\psi(\vec{a}_1++\vec{a}'_1,...,\vec{a}_k++\vec{a}'_k) \Downarrow^{\vec{c}++\vec{c}'} \vec{a}++\vec{a}'$.

Lemma (Parallelism fusion)

If (i)
$$S_1 \Vdash p: S_2$$
, (ii) $\sigma_1 \stackrel{S}{\sim} \sigma_2$, (iii) $\langle p, \sigma_1 \rangle \Downarrow^{\vec{c}_1} \sigma_1' \$ W_1$, (iv) $\langle p, \sigma_2 \rangle \Downarrow^{\vec{c}_2} \sigma_2' \$ W_2$, and (v) $(S_1 \cup S_2) \cap S = \emptyset$, then $\sigma_1' \stackrel{S}{\sim} \sigma_2'$, $\langle p, \sigma_1 \stackrel{S}{\bowtie} \sigma_2 \rangle \Downarrow^{\vec{c}_1 + + \vec{c}_2} \sigma_1' \stackrel{S}{\bowtie} \sigma_2' \$ W$, and $W \leq W_1 + W_2$

Correctness of translation and cost preservation

Theorem (Correctness for expressions)

```
For some constant C. if
(i) \Gamma \vdash e : \tau
(ii) \rho \vdash e \downarrow v \$ W^H
(iii) \delta \vdash e \Rightarrow_{s_1}^{s_0} (p, st)
(iv) \forall x \in dom(\Gamma). \vdash \rho(x) : \Gamma(x)
(v) \ \forall x \in dom(\Gamma).\overline{\delta(x)} \lessdot s_0
(vi) \forall x \in dom(\Gamma).\rho(x) \triangleright_{\Gamma(x)} \sigma^*(\delta(x))
then, for some \sigma' and W^L.
(vii) \langle p, \sigma \rangle \Downarrow^{\langle () \rangle} \sigma' \$ W^L
(viii) v \triangleright_{\tau} \sigma'^*(st)
(ix) W^{L} < C \cdot W^{H}
```

(In our implementation, we have proven that C can be any number > 7.)

Scaling up

- More scalar types and built-in operations: should be trivial
- Step/space cost: similar to work cost
- Pairs/tuples: require more value representation rules
- Restricted comprehension: similar to the general one, but need to take care of packing general types
- Recursion: consider termination preservation (from high-level to low-level) and reflection (from low-level to high-level)
- Error preservation: possible to support
- Streaming semantics: challenging, open problem

Conclusion

Conclusion

Main contributions:

- Extension of streaming dataflow model to account for recursion
- A formalization of the source and target language, and the correctness proof of the translation including work cost preservation

Future work:

- Formalization of the streaming semantics of the target language
- More investigation to schedulability, deadlock, etc.