# SNESL formalization

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# 0 Level-0

Draft version 0.0.2

# 0.1 Source language syntax

(Ignore empty sequence for now)

Expressions:

$$e ::= x \mid \mathbf{let} \ x = e_1 \ \mathbf{in} \ e_2 \mid \varphi(x_1, ..., x_k) \mid \{e : x \ \mathbf{in} \ y \ \mathbf{using} \cdot \}$$

$$\varphi = \mathbf{const}_n \mid \mathbf{iota} \mid \mathbf{plus}$$

Values:

$$n \in \mathbf{Z}$$
$$v ::= n \mid \{v_1, ..., v_k\}$$

# 0.2 Type system

$$\tau ::= \mathbf{int} | \{ \tau_1 \}$$

Type environment  $\Gamma = [x_1 \mapsto \tau_1, ..., x_i \mapsto \tau_i].$ 

• Judgment  $\Gamma \vdash e : \tau$ 

$$\frac{\Gamma \vdash x : \tau}{\Gamma \vdash x : \tau} (\Gamma(x) = \tau) \qquad \frac{\Gamma \vdash e_1 : \tau_1 \qquad \Gamma[x \mapsto \tau_1] \vdash e_2 : \tau}{\Gamma \vdash \text{let } x = e_1 \text{ in } e_2 : \tau}$$

$$\frac{\vdash Typ_{\varphi}(\tau_1, ..., \tau_k) : \tau}{\Gamma \vdash \varphi(x_1, ..., x_k) : \tau} ((\Gamma(x_i) = \tau_i)_{i=1}^k) \qquad \frac{\Gamma[x \mapsto \tau_1] \vdash e : \tau}{\Gamma \vdash \{e : x \text{ in } y \text{ using } \cdot\} : \{\tau\}} (\Gamma(y) = \{\tau_1\})$$

• Auxiliary Judgment  $\ \vdash \ Typ_{\varphi}(\tau_1,...,\tau_k):\tau$ 

$$oxed{\vdash \mathbf{const}_n():\mathbf{int}} oxed{\vdash \mathbf{iota(int)}:\{\mathbf{int}\}} oxed{\vdash \mathbf{plus(int,int)}:\mathbf{int}}$$

#### 0.3 Source language semantics

• Judgment 
$$\rho \vdash e \downarrow v$$

$$\frac{\rho \vdash e_1 \downarrow v_1 \qquad \rho[x \mapsto v_1] \vdash e_2 \downarrow v}{\rho \vdash \text{let } e_1 = x \text{ in } e_2 \downarrow v}$$

$$\frac{\vdash Eva_{\varphi}(v_1, ..., v_k) \downarrow v}{\rho \vdash \varphi(x_1, ..., x_k) \downarrow v} ((\rho(x_i) = v_i)_{i=1}^k) \qquad \frac{([x \mapsto v_i] \vdash e \downarrow v_i')_{i=1}^k}{\rho \vdash \{e : x \text{ in } y \text{ using } \cdot\} \downarrow \{v_1', ..., v_k'\}} (\rho(y) = \{v_1, ..., v_k\})$$

• Auxiliary Judgment 
$$\vdash Eva_{\varphi}(v_1,...,v_k) \downarrow v$$

### 0.4 SVCODE syntax

Stream id:

$$s \in \mathbf{N} = \{0, 1, 2...\}$$

Stream tree:

$$st ::= s \mid (st_1, s)$$

SVCODE expressions:

$$arphi ::= \mathtt{Ctrl} \mid \mathtt{Const_a} \mid \mathtt{ToFlags} \mid \mathtt{Usum} \mid \mathtt{MapTwo} \mid \mathtt{ScanPlus}$$

SVCODE program:

$$\begin{split} p ::= \epsilon \\ \mid s := \psi(s_1, ..., s_i) \\ \mid st := \texttt{WithCtrl}(s, p) \\ \mid p_1; p_2 \end{split}$$

Target language values:

$$b \in \{\mathsf{T}, \mathsf{F}\}$$

$$a ::= n \mid b \mid ()$$

$$\vec{b} = \langle b_1, ..., b_i \rangle$$

$$\vec{a} = \langle a_1, ..., a_i \rangle$$

$$\vec{v} ::= \vec{a} \mid (\vec{v}, \vec{b})$$

Define some operations for convenience:

- ++:  $\vec{v} \to \vec{v} \to \vec{v}$   $\langle a_1, ..., a_i \rangle$  ++ $\langle a_2, ..., a_j \rangle$  =  $\langle \vec{a}_1, ..., a_i, a_2, ..., a_j \rangle$  $(\vec{v}_1, \vec{b}_1)$  ++ $(\vec{v}_2, \vec{b}_2)$  =  $(\vec{v}_1 + + \vec{v}_2, \vec{b}_1 + + \vec{b}_2)$
- tail :  $\vec{a} \rightarrow \vec{a}$  tail  $(\langle a_1, a_2, ..., a_i \rangle) = \langle a_2, ..., a_i \rangle$

### 0.5 SVCODE semantics

 $\sigma = [s_1 \mapsto \vec{a}_1, ..., s_i \mapsto \vec{a}_i]$  $\vec{a}_c$  is the control stream.

• Judgment  $\langle p, \sigma \rangle \downarrow^{\vec{a}_c} \sigma'$ 

$$\frac{SEva_{\varphi}(\vec{a}_1,...,\vec{a}_k)\downarrow^{\vec{a}_c}\vec{a}}{\langle s:=\varphi(s_1,...,s_k),\sigma\rangle\downarrow^{\vec{a}_c}\sigma[s\mapsto\vec{a}]}\;((\sigma(s_i)=\vec{a}_i)_{i=1}^k) \\ \\ \frac{\langle st:=\mathtt{WithCtrl}(s,p),\sigma\rangle\downarrow^{\vec{a}_c}\sigma[st\mapsto\langle\rangle]}{\langle st:=\mathtt{WithCtrl}(s,p),\sigma\rangle\downarrow^{\vec{a}_c}\sigma[st\mapsto\langle\rangle]}\;(\sigma(s)=\langle\rangle) \\ \\ \frac{\langle p,\sigma\rangle\downarrow^{\vec{a}_s}\sigma'}{\langle st:=\mathtt{WithCtrl}(s,p),\sigma\rangle\downarrow^{\vec{a}_c}\sigma'}\;(\sigma(s)=\vec{a}_s=\langle a_1,...,a_i\rangle)$$

$$\frac{\langle p_1, \sigma \rangle \downarrow^{\vec{a}_c} \sigma'' \qquad \langle p_2, \sigma'' \rangle \downarrow^{\vec{a}_c} \sigma'}{\langle p_1; p_2, \sigma \rangle \downarrow^{\vec{a}_c} \sigma'}$$

- Auxiliary Judgment  $SEva_{\varphi}(\vec{a}_1,...,\vec{a}_k)\downarrow^{\vec{a}_c}\vec{a}$ 

$$\frac{Block_{\varphi}(\vec{a}_{11},...,\vec{a}_{k1}) \Downarrow \vec{a}_{1} \qquad SEva_{\varphi}(\vec{a}_{12},...,\vec{a}_{k2}) \downarrow^{tail(\vec{a}_{c})} \vec{a}_{2}}{SEva_{\varphi}(\vec{a}_{11}++\vec{a}_{12},...,\vec{a}_{k1}++\vec{a}_{k2}) \downarrow^{\vec{a}_{c}} \vec{a}} (\vec{a}=\vec{a}_{1}++\vec{a}_{2})$$

$$SEva_{\varphi}(\vec{a}_1,...,\vec{a}_k)\downarrow^{\langle\rangle}\langle\rangle$$

- Auxiliary Judgment  $Block_{\varphi}(\vec{a}_1,...,\vec{a}_k) \Downarrow \vec{a}$ 

$$\frac{}{\mathsf{Const_a} \Downarrow \langle a \rangle} \qquad \frac{}{\mathsf{ToFlags}(\langle n \rangle) \Downarrow \langle \mathsf{F}_1, ..., \mathsf{F}_n, \mathsf{T} \rangle} \qquad \frac{}{\mathsf{MapTwo}(\langle n_1 \rangle, \langle n_2 \rangle) \Downarrow \langle n_3 \rangle} (n_3 = n_1 + n_2)$$

$$\frac{Unary_{\varphi}(\langle \mathtt{F} \rangle,...,\vec{a}_{k1}) \Downarrow \vec{a}_{1} \quad Block_{\varphi}(\vec{a}_{12},...,\vec{a}_{k2}) \Downarrow \vec{a}_{2}}{Block_{\varphi}(\langle \mathtt{F} \rangle + + \vec{a}_{12},...,\vec{a}_{k1} + + \vec{a}_{k2}) \Downarrow \vec{a}} (\vec{a} = \vec{a}_{1} + + \vec{a}_{2})$$

$$Unary_{\varphi}(\langle \mathtt{T} \rangle, ..., \vec{a}_k) \Downarrow \vec{a}$$
$$Block_{\varphi}(\langle \mathtt{T} \rangle, ..., \vec{a}_k) \Downarrow \vec{a}$$

$$\frac{Unary_{\varphi,n_0}(\langle \mathbf{F} \rangle,...,\vec{a}_{k1}) \Downarrow^{n_0'} \langle n_1 \rangle \quad Block_{\varphi,n_0'}(\vec{a}_{12},...,\vec{a}_{k2}) \Downarrow \vec{a}_2}{Block_{\varphi,n_0}(\langle \mathbf{F} \rangle + + \vec{a}_{12},...,\vec{a}_{k1} + + \vec{a}_{k2}) \Downarrow \langle n_1 \rangle + + \vec{a}_2}$$

$$Unary_{\varphi,n_0}(\langle \mathsf{T} \rangle, ..., \vec{a}_k) \Downarrow \langle n_1 \rangle$$
$$Block_{\varphi,n_0}(\langle \mathsf{T} \rangle, ..., \vec{a}_k) \Downarrow \langle n_1 \rangle$$

- Auxiliary Judgment  $\boxed{Unary_{\varphi}(\langle b \rangle,...,\vec{a}_k) \Downarrow \vec{a}}$ 

$$\overline{\texttt{Usum}(\langle F \rangle) \Downarrow \langle () \rangle} \qquad \overline{\texttt{Usum}(\langle T \rangle) \Downarrow \langle \rangle}$$

$$\overline{ \texttt{ScanPlus}_{n_0}(\langle \mathtt{F} \rangle, \langle n \rangle) \Downarrow^{n_0+n} \langle n_0 \rangle } \qquad \overline{ \texttt{ScanPlus}_{n_0}(\langle \mathtt{T} \rangle, \langle \rangle) \Downarrow \langle n_0 \rangle }$$

### 0.6 Translation

$$\delta = [x_1 \mapsto st_1, ..., x_i \mapsto st_i]$$

- (??not necessary)  $\delta \vdash e \xrightarrow[s_1]{s_0+1} (p, st)$   $\delta \vdash e \xrightarrow[s_1]{s_0} \mathsf{let} \ s_0 := \mathsf{Ctrl}; p \ \mathsf{in} \ st$
- Judgment  $\delta \vdash e \stackrel{s_0}{\underset{s_1}{\Longrightarrow}} (p, st)$

$$\frac{\delta \vdash x \stackrel{s_0}{\underset{s_0}{\rightleftharpoons}} (\epsilon, st)}{\delta \vdash x \stackrel{s_0}{\underset{s_0}{\rightleftharpoons}} (\epsilon, st)} (\delta(x) = st) \qquad \frac{\delta \vdash e_1 \stackrel{s_0}{\underset{s_0}{\rightleftharpoons}} (p_1, st_1) \qquad \delta[x \mapsto st_1] \vdash e_2 \stackrel{s_0}{\underset{s_1}{\rightleftharpoons}} (p_2, st)}{\delta \vdash \text{let } x = e_1 \text{ in } e_2 \stackrel{s_0}{\underset{s_1}{\rightleftharpoons}} (p_1; p_2, st)}$$

$$\frac{\vdash Trans_{\varphi}(st_1, ..., st_k) \stackrel{s_0}{\underset{s_1}{\rightleftharpoons}} (p, st)}{\delta \vdash \varphi(x_1, ..., x_k) \stackrel{s_0}{\underset{s_1}{\rightleftharpoons}} (p, st)} ((\delta(x_i) = st_i)_{i=1}^k)$$

$$\frac{[x \mapsto st_1] \ \vdash \ e \xrightarrow{s_0+1} (p,st)}{\delta \ \vdash \ \{e: x \ \textbf{in} \ y \ \textbf{using} \ \cdot\} \xrightarrow{s_0} (s_0 := \mathtt{Usum}(s_2); st := \mathtt{WithCtrl}(s_0,p), (st,s_2))} (\delta(y) = (st_1,s_2))$$

• Auxiliary Judgment  $\vdash Trans_{\varphi}(st_1,...,st_k) \stackrel{s_0}{\underset{s_1}{\Longrightarrow}} (p,st)$ 

### 0.7 Value representation

• Judgment  $v \triangleright_{\tau} \vec{v}$ 

$$\frac{(v_i \triangleright_{\tau} \vec{v_i})_{i=1}^k}{\{v_1, ..., v_k\} \triangleright_{\{\tau\}} (\vec{v}, \langle \mathbf{F}_1, ..., \mathbf{F}_k, \mathbf{T} \rangle)} (\vec{v} = \vec{v_1} + + \vec{v_2} + + ... + + \vec{v_k})$$

# 0.8 Correctness proof

#### Lemma 1. If

(i) 
$$\vdash Typ_{\varphi}(\tau_1,...,\tau_k) : \tau$$

(ii) 
$$\vdash Eva_{\varphi}(v_1,...,v_k) \downarrow v$$

$$(iii) \vdash Trans_{\varphi}(st_1,...,st_k) \stackrel{s_0}{\underset{s_1}{\rightleftharpoons}} (p,st)$$

(iv) 
$$(v_i \triangleright_{\tau_i} st_i)_{i=1}^k$$

(v) 
$$\operatorname{sids}((st_1,...,st_k)) \lessdot s_0$$

then

(i) 
$$\langle p, \sigma \rangle \downarrow^{\vec{a}_c} \sigma'$$
 (by  $\mathcal{P}$ )

(ii) 
$$v \triangleright_{\tau} \sigma'(st)$$
 (by  $V$ )

(iii) 
$$\sigma' \stackrel{\langle s_0 \rangle}{===} \sigma$$

$$(iv)$$
 sids $(st) \lessdot s_1$ 

$$(v)$$
  $s_0 \leq s_1$ 

#### Theorem 2. If

(i) 
$$\Gamma \vdash e : \tau$$
 (by some derivation  $T$ )

(ii) 
$$\rho \vdash e \downarrow v \ (by \ \mathcal{E})$$

(iii) 
$$\delta \vdash e \stackrel{s_0}{\Longrightarrow} (p, st) \ (by \ \mathcal{C})$$

$$(iv) \ \forall x \in dom(\Gamma).\rho(x): \Gamma(x) \land \mathtt{sids}(()\delta(x)) \lessdot s_0 \land \rho(x) \rhd_{\Gamma(x)} \sigma(\delta(x))$$

then

- (i)  $\langle p, \sigma \rangle \downarrow^{\vec{a}_c} \sigma' \ (by \ \mathcal{P})$
- (ii)  $v \triangleright_{\tau} \sigma(st)$  (by V)
- (iii)  $\sigma' \stackrel{\langle s_0 \rangle}{=\!=\!=} \sigma$
- $(iv) \ \mathtt{sids}(st) \lessdot s_1$
- $(v) \ s_0 \le s_1$