Formalizing the implementation of Streaming NESL

Master's Thesis

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Introduction

NESL

- A functional nested data-parallel language
- Developed by Guy Blelloch in 1990s at CMU
- Highlights:
 - Highly expressive for parallel algorithms.
 - Data-parallel construct: apply-to-each

$$\{e_1(x): x \text{ in } e_0\}$$

• Ex: compute $\sum_{i=1}^{2} \vec{r}^2$ and $\sum_{i=3}^{10} \vec{r}^2$:

$$\{ \mathbf{sum} \big(\{ i \times i : i \text{ in } s \} \big) : s \text{ in } [[1,2],[3,4,5,6,7,8,9,10]] \}$$

- ! Allocate 10 size of space for intermediate data
- An intuitive cost model for time complexity: work-step model
 - work cost t₁: total number of operations executed
 - step cost t_{∞} : the longest chain of sequential dependency

Streaming NESL (SNESL)

- Experimental refinement of NESL
- Aiming at improving space-usage efficiency
- Work by Frederik Madsen and Andrzej Filinski in 2010s at DIKU
- Highlights:
 - Streaming semantics

```
\pi ::= \mathbf{bool} \mid \mathbf{int} \mid \mathbf{char} \mid \mathbf{real} \mid \cdots \qquad \text{(scalar types)}
\tau ::= \pi \mid (\tau_1, ..., \tau_k) \mid [\tau] \qquad \text{(concrete types)}
\sigma ::= \tau \mid (\sigma_1, ..., \sigma_k) \mid {\sigma} \qquad \text{(streamable types)}
```

- A space cost model
 - sequential space s₁: the minimal space to perform the computation
 - parallel space s_{∞} : space needed to achieve the maximal parallel degree (NESL's case)

SNESL syntax

Expressions

```
\begin{array}{ll} e ::= a \mid x \mid (e_1,...,e_k) \mid \textbf{let} \ x = e_1 \ \textbf{in} \ e_2 \mid \phi(e_1,...,e_k) \\ \\ \mid \{e_1 : x \ \textbf{in} \ e_0\} & \text{(general comprehension)} \\ \\ \mid \{e_1 \mid e_0\} & \text{(restricted comprehension)} \end{array}
```

SNESL syntax

Expressions

```
\begin{split} e &::= a \mid x \mid (e_1,...,e_k) \mid \textbf{let} \ x = e_1 \ \textbf{in} \ e_2 \mid \phi(e_1,...,e_k) \\ & \mid \{e_1 : x \ \textbf{in} \ e_0\} & \text{(general comprehension)} \\ & \mid \{e_1 \mid e_0\} & \text{(restricted comprehension)} \end{split}
```

Primitive functions

```
\begin{array}{lll} \phi & ::= \oplus \mid \ \mbox{append} \mid \mbox{concat} \mid \mbox{zip} \mid \mbox{iota} \mid \mbox{part} \mid \mbox{scan}_{\otimes} \mid \mbox{reduce}_{\otimes} \\ & \mid \mbox{mkseq} \mid \mbox{the} \mid \mbox{empty} \mid \mbox{length} \mid \mbox{elt} \mid \mbox{seq} \mid \mbox{tab} \mid \cdots \\ \oplus & ::= + \mid \times \mid / \mid \mbox{} = \mid \mbox{not} \mid \cdots \\ \otimes & ::= + \mid \times \mid \mbox{max} \mid \cdots \end{array}
```

SNESL syntax

Expressions

```
\begin{array}{ll} e ::= a \mid x \mid (e_1,...,e_k) \mid \textbf{let} \ x = e_1 \ \textbf{in} \ e_2 \mid \phi(e_1,...,e_k) \\ \\ \mid \{e_1 : x \ \textbf{in} \ e_0\} & \text{(general comprehension)} \\ \\ \mid \{e_1 \mid e_0\} & \text{(restricted comprehension)} \end{array}
```

Primitive functions

```
\begin{array}{lll} \phi & ::= \oplus \mid & append \mid concat \mid zip \mid iota \mid part \mid scan_{\otimes} \mid reduce_{\otimes} \\ & \mid & mkseq \mid the \mid empty \mid length \mid elt \mid seq \mid tab \mid \cdots \\ \\ \oplus & ::= + \mid \times \mid / \mid == \mid not \mid \cdots \\ \\ \otimes & ::= + \mid \times \mid max \mid \cdots \end{array}
```

• if e_0 then e_1 else $e_2 \equiv \text{let } b = e_0$ in $\text{the}(\{e_1 \mid b\} + + \{e_2 \mid \text{not}(b)\})$

SNESL primitive functions

$append: \big(\{\sigma\}, \{\sigma\}\big) \to \{\sigma\}$	syntactic sugar ++; $\{3,1\}$ ++ $\{4\}$ = $\{3,1,4\}$	
$concat: \{\{\sigma\}\} \to \{\sigma\}$	$concat(\{\{3,1\},\{4\}\}) = \{3,1,4\}$	
$ \overline{zip \colon \left(\{ \sigma_1 \},, \{ \sigma_k \} \right)} \rightarrow $	$zip(\{1,2\}, \{\mathtt{F},\mathtt{T}\}) = \{(1,\mathtt{F}), (2,\mathtt{T})\}$	
$\{(\sigma_1,,\sigma_k)\}$		
$iota(\&) : int o \{int\}$	&5 = {0,1,2,3,4}	
$part: (\{\sigma\}, \{bool\}) \to \{\{\sigma\}\}$	$part(\{3,1,4\}, \{F,F,T,F,T,T\}) = \{\{3,1\}, \{4\}, \{\}\}\}$	
$scan_\otimes: \{int\} o \{int\}$	$scan_{+}(\&5) = \{0,0,1,3,6\}$	
$reduce_\otimes: \{int\} o int$	$reduce_{+}(\&5) = 10$	
k		
$mkseq : (\overbrace{\sigma,, \sigma}) \to \{\sigma\}$	$mkseq(1,2,3) = \{1,2,3\}$	
$length(\#) \colon [au] o int$	#[10,20] = 2	
$elt(!) \colon ([\tau],int) \to \tau$	[3,8,2] ! 1 = 8	
the : $\{\sigma\} \to \sigma$	return the element of a singleton, $\mathbf{the}(\{10\}) = 10$	
$\overline{empty : \{\sigma\} \to bool}$	$empty(\{1,2\}) = \mathtt{F}, empty(\&0) = \mathtt{T}$	
$seq: [\tau] \to \{\tau\}$	$seq([1,2]) = \{1,2\}$	
$tab: \{\tau\} \to [\tau]$	$tab(\{1,2\}) = [1,2]$	
	5/23	

5/23

SNESL example: word count

```
-- split a string into words (delimited by spaces)
function str2wds_snesl(str) =
let flags = { x == ' ' : x in str};
   nonsps = concat({{x | x != ' '} : x in v})
   in concat({{x|not(empty(x))}: x in part(nonsps,flags ++ {T})})
-- count the length of a stream
function slength(s) = reduce({1 : _ in s})
```

```
$> slength(str2wds_snesl(read_file(filename)))
```

SNESL example: word count

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```

```
$> slength(str2wds_snesl(read_file(filename)))
```

- Takes constant space
- Speedups of a similar word count program from [MF16]:

Speedup	Chunk size	Milliseconds
0.65	N/A	19760
1.00	163840	12770
2.06	163840	6214
3.54	327680	3607
4.73	655360	2700
5.84	655360	2188
6.74	1310720	1894
	0.65 1.00 2.06 3.54 4.73 5.84	0.65 N/A 1.00 163840 2.06 163840 3.54 327680 4.73 655360 5.84 655360

Implementation

Source language

Simplified SNESL types

$$\begin{split} \pi &::= \mathbf{bool} \mid \mathbf{int} \\ \tau &::= \pi \mid (\tau_1, \tau_2) \mid \{\tau\} \\ \varphi &::= (\tau_1, ..., \tau_k) \to \tau \end{split} \qquad \text{(no vectors)}$$

Source language

Simplified SNESL types

```
\begin{array}{l} \pi ::= \mathbf{bool} \mid \mathbf{int} \\ \tau ::= \pi \mid (\tau_1, \tau_2) \mid \{\tau\} \\ \varphi ::= (\tau_1, ..., \tau_k) \rightarrow \tau \end{array} \qquad \text{(no vectors)}
```

Syntax

```
e ::= \cdots \mid f(e_1, ..., e_k) (user-defined function call) d ::= function f(x_1 : \tau_1, ..., x_k : \tau_k) : \tau = e
```

Source language

• Key typing rules, $\Gamma \vdash_{\Sigma} e : \tau$:

$$\frac{\Gamma \vdash_{\Sigma} e_0 : \{\tau_0\} \qquad [x \mapsto \tau_0, (x_i \mapsto \tau_i)_{i=1}^k] \vdash_{\Sigma} e_1 : \tau}{\Gamma \vdash_{\Sigma} \{e_1 : x \text{ in } e_0 \text{ using } x_1, ..., x_k\} : \{\tau\}} \begin{pmatrix} (\Gamma(x_i) = \tau_i, \\ \tau_i \text{ concrete})_{i=1}^k \end{pmatrix}$$

• Key evaluation rules, $\rho \vdash_{\Phi} e \downarrow v$:

$$\frac{\rho \vdash_{\Phi} e_0 \downarrow \{v_1, ..., v_l\} \qquad ([x \mapsto v_i, (x_j \mapsto \rho(x_j))_{j=1}^k] \vdash_{\Phi} e_1 \downarrow v_i)_{i=1}^l}{\rho \vdash_{\Phi} \{e_1 : x \text{ in } e_0 \text{ using } x_1, ..., x_k\} \downarrow \{v_1', ..., v_l'\}}$$

Target language: SVCODE

- SVCODE values:
 - primitive stream: $\vec{a} := \langle a_1, ..., a_l \rangle$ e.g., $\vec{a}_1 = \langle 1, 2 \rangle, \langle 0 | \vec{a}_1 \rangle = \langle 0, 1, 2 \rangle, \ \vec{b} = \langle F, T, F \rangle$
 - stream tree: $w := \vec{a} \mid (w_1, w_2)$

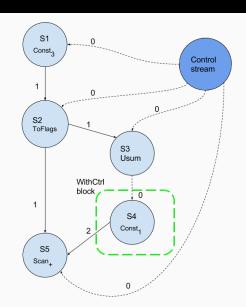
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 - stream tree: $w := \vec{a} \mid (w_1, w_2)$
- SVCODE syntax:

$$\begin{array}{lll} \rho & ::= & \epsilon \mid \rho_1; \rho_2 \\ & \mid s := & \psi(s_1,...,s_k) & \text{(single stream definition)} \\ & \mid S_{out} := & \text{WithCtrl}(s,S_{in},\rho_1) & \text{(WithCtrl block)} \\ & \mid (s_1',...,s_{k'}') := & \text{SCall } f(s_1,...,s_k) & \text{(function call)} \\ \psi & ::= & \text{Const}_a \mid & \text{ToFlags} \mid & \text{Usum} \mid & \text{Map}_{\oplus} \mid & \text{Scan}_+ \mid & \text{Reduce}_+ \mid & \text{Distr} \\ & \mid & \text{Pack} \mid & \text{UPack} \mid & \text{B2u} \mid & \text{SegConcat} \mid & \text{InterMerge} \mid & \cdots & \text{(Xducers)} \\ s & ::= & 0 \mid & 1 \mid & \cdots \in & \text{SId} = & \mathbb{N} & \text{(stream ids)} \\ S & ::= & \{s_1,...,s_k\} \in & \mathbb{S} & \text{(set of stream ids)} \end{array}$$

SVCODE dataflow DAG

```
S1 := Const_3
S2 := ToFlags S1
S3 := Usum S2
[S4] := WithCtrl S3 []:
S4 := Const_1
S5 := ScanPlus S2 S4
```



Value representation

 A nested sequence with a nesting depth d is represented as a flattened data stream and d segment descriptor streams.

$$\begin{split} &\left\{3,1,4\right\} \rhd_{\left\{\text{int}\right\}} \left(\langle 3,1,4\rangle,\langle F,F,F,T\rangle\right) \\ &\left\{\left\{3,1\right\},\left\{4\right\}\right\} \rhd_{\left\{\left\{\text{int}\right\}\right\}} \left(\left(\langle 3,1,4\rangle,\langle F,F,T,F,T\rangle\right),\langle F,F,T\rangle\right) \end{split}$$

Translation

- **STree** \ni *st* ::= *s* | (*st*₁, *st*₂)
- Translation symbol table $\delta ::= [x_1 \mapsto st_1, ..., x_k \mapsto st_k]$
- General comprehension translation:

```
\{i+x: i \text{ in \&3 using } x\} \Rightarrow
```

```
S4 := ... -- <10 > x

S5 := ... -- <F,F,F,T> descriptor of &3

S6 := ... -- <0,1,2> i

S7 := Usum S5; -- 1. generate new control: <() () () >

S8 := Distr S4 S5; -- 2. replicate x 3 times: <10 10 10>

[S9] := WithCtrl S7 [S6,S8]: -- 3. translate (i+x)

S9 := Map_+ S6 S8 -- <10,11,12>
```

Translation continued

- Built-in function translation:
 - scan, reduce, concat, part, empty: translated to a single stream definition, e.g., $\operatorname{scan}_+((s_d, s_b)) \Rightarrow \operatorname{Scan}_+(s_b, s_d)$
 - the, iota translated to a few lines of code, e.g.,

$$extbf{iota}(s) \Rightarrow egin{pmatrix} s_0 := exttt{ToFlags}(s); \ s_1 := exttt{Usum}(s_0); \ \{s_2\} := exttt{WithCtrl}(s_1, \emptyset, s_2 := exttt{Const}_1()); \ s_3 := exttt{Scan}_+(s_0, s_2) \end{pmatrix}$$

• $++_{ au}$: translated recursively, depending on au

Translation continued

- Built-in function translation:
 - scan, reduce, concat, part, empty: translated to a single stream definition, e.g., $\operatorname{scan}_+((s_d, s_b)) \Rightarrow \operatorname{Scan}_+(s_b, s_d)$
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- $++_{\tau}$: translated recursively, depending on τ
- User-defined functions: translated to SVCODE functions, unfolded at runtime when interpreting a SCall

SVCODE interpreters

- Eager interpreter (NESL-like)
 - assumes sufficient memory for allocating all streams at once
 - executes each instruction sequentially
- Streaming interpreter
 - limited buffer size, space-usage efficient
 - result is collected from each scheduling round
 - DAG dynamically completed
 - need effective scheduling strategy to avoid deadlock and guarantee cost preservation
- Both instrumented with cost metrics (work, step), compared with the high-level one

Recursion example

A function to compute factorial:

```
> function fact(x:int):int = if x <= 1 then 1 else x*fact(x-1)
> let s = {3,7,0,4} in {fact(n): n in s}
```

Recursion example

A function to compute factorial:

```
> function fact(x:int):int = if x <= 1 then 1 else x*fact(x-1)
> let s = {3,7,0,4} in {fact(n): n in s}
```

1st unfolding (will unfold 7 times in total):

```
-- Parameters: [S1]
                                     -- <3 7 0
                                                   4>
...- compare parameters with 1,B2u: S5 = \langle T | T | FT | T \rangle
S6 := Usum S5; -- for elements <=1 -- < () >
[S7] := WithCtrl S6 []: S7 := Const 1 -- <
. . .
S13 := Usum S11; -- for elementes >1 -- <() ()
                                                  ()>
[S17] := WithCtrl S13 [S12]:
                                -- <1 1 1 >
          S14 := Const 1
          S15 := MapTwo Minus S12 S14 -- <2 6 3 >
          [S16] := SCall fact [S15] -- <2 720 6 >
          S17 := MapTwo Times S12 S16 -- <6 5040 24>
... -- merge results
S19 := PriSegInterS [(S7,S5),(S17,S11)]; -- <6 5040 1 24>
```

Formalization

Source language: SNESL₀

Types:

$$\tau ::= \mathsf{int} \mid \{\tau_1\}$$

- Key evaluation rules with work cost, $\rho \vdash e \downarrow v \$ W$:
 - General comprehension:

$$\frac{([x \mapsto v_i, x_1 \mapsto \rho(x_1), ..., x_k \mapsto \rho(x_k)] \vdash e \downarrow v_i \ \$ \ W_i)_{i=1}^{l}}{\rho \vdash \{e : x \text{ in } y \text{ using } x_1, ..., x_k\} \downarrow \{v_1', ..., v_l'\} \ \$ \ W}$$
where $\rho(y) = \{v_1, ..., v_l\}$, and $W = (k+1) \cdot (l+1) + \sum_{i=1}^{l} W_i$

Built-in function:

$$\frac{\phi(v_1,...,v_k) \downarrow v}{\rho \vdash \phi(x_1,...,x_k) \downarrow v \$ \left(\sum_{i=1}^k |v_i|\right) + |v|} \left((\rho(x_i) = v_i)_{i=1}^k \right)$$

Target language: SVCODE₀

- key semantics with work cost, $|\langle p, \sigma \rangle \downarrow ^{\vec{c}} \sigma' \$ W|$:
 - Empty new control stream $(\sigma(s_c) = \langle \rangle)$:

$$\frac{1}{\langle S_{out} := \mathtt{WithCtrl}(s_c, S_{in}, p_1), \sigma \rangle \Downarrow^{\vec{c}} \sigma[(s_i \mapsto \langle \rangle)_{i=1}^k] \$ 1}}{\mathsf{where} \ \forall s \in \{s_c\} \cup S_{in}.\sigma(s) = \langle \rangle, \ S_{out} = \{s_1, ..., s_k\}}$$

Target language: SVCODE₀

- key semantics with work cost, $|\langle p,\sigma\rangle \Downarrow^{\vec{c}} \sigma' \$ W|$:
 - Empty new control stream $(\sigma(s_c) = \langle \rangle)$:

• Nonempty new control stream $(\sigma(s_c) = \vec{c}_1 \neq \langle \rangle)$:

Target language: SVCODE₀

- key semantics with work cost, $\left| \langle p, \sigma \rangle \downarrow^{\vec{c}} \sigma' \right. \left. \right. \left. \right. W \left| \right. :$
 - Empty new control stream $(\sigma(s_c) = \langle \rangle)$:

• Nonempty new control stream $(\sigma(s_c) = \vec{c}_1 \neq \langle \rangle)$:

$$\frac{\langle p_1, \sigma \rangle \ \Downarrow^{\vec{c}_1} \ \sigma'' \ \$ \ W_1}{\langle S_{out} := \texttt{WithCtrl}(s_c, S_{in}, p_1), \sigma \rangle \ \Downarrow^{\vec{c}} \sigma[(s_i \mapsto \sigma''(s_i))_{i=1}^k] \ \$ \ W_1 + 1}$$

$$\begin{array}{c} \blacksquare \quad \mathsf{Xducers,} \; ((\sigma(s_i) = \vec{a}_i)_{i=1}^k) \\ \qquad \qquad \psi(\vec{a}_1,...,\vec{a}_k) \Downarrow^{\vec{c}} \vec{a} \\ \hline \langle s := \psi(s_1,...,s_k), \sigma \rangle \Downarrow^{\vec{c}} \sigma[s \mapsto \vec{a}] \; \$ \; (\sum_{i=1}^k |\vec{a}_i|) + |\vec{a}| \end{array}$$

Xducer semantics

• General semantics, $\left| \psi(\vec{a}_1,...,\vec{a}_k) \downarrow^{\vec{c}} \vec{a} \right|$

$$\frac{\psi(\vec{a}_{11},...,\vec{a}_{k1})\downarrow\vec{a}_{01} \qquad \psi(\vec{a}_{12},...,\vec{a}_{k2}) \Downarrow^{\vec{c}_{0}} \vec{a}_{02}}{\psi(\vec{a}_{1},...,\vec{a}_{k}) \Downarrow^{\langle ()|\vec{c}_{0}\rangle} \vec{a}_{0}} ((\vec{a}_{i1}++\vec{a}_{i2}=\vec{a}_{i})_{i=0}^{k})$$

•
$$\psi(\langle\rangle_1,...,\langle\rangle_k) \Downarrow^{\langle\rangle} \langle\rangle$$

Xducer semantics

ullet General semantics, $\psi(ec{a}_1,...,ec{a}_k) \Downarrow^{ec{c}} ec{a}$

$$\frac{\psi(\vec{a}_{11},...,\vec{a}_{k1})\downarrow\vec{a}_{01} \quad \psi(\vec{a}_{12},...,\vec{a}_{k2})\Downarrow^{\vec{c}_0}\vec{a}_{02}}{\psi(\vec{a}_{1},...,\vec{a}_{k})\Downarrow^{\langle()|\vec{c}_0\rangle}\vec{a}_{0}} ((\vec{a}_{i1}++\vec{a}_{i2}=\vec{a}_{i})_{i=0}^{k})$$

$$\frac{\psi(\langle\rangle_{1},...,\langle\rangle_{k})\Downarrow^{\langle\rangle}\langle\rangle}{\psi(\langle\rangle_{1},...,\langle\rangle_{k})\Downarrow^{\langle\rangle}\langle\rangle}$$

Block semantics (part), $\psi(\vec{a}_1,...,\vec{a}_k)\downarrow\vec{a}$:

$$\frac{\text{Const}_{a}() \downarrow \langle a \rangle}{\text{Const}_{a}() \downarrow \langle a \rangle} \frac{\text{ToFlags}(\langle n \rangle) \downarrow \langle F_{1}, ..., F_{n}, T \rangle}{\text{ToFlags}(\langle n \rangle) \downarrow \langle F_{1}, ..., F_{n}, T \rangle} (n \geq 0)$$

$$\frac{\text{MapTwo}_{+}(\langle n_{1} \rangle, \langle n_{2} \rangle) \downarrow \langle n_{3} \rangle}{\text{Usum}(\langle \vec{b} \rangle) \downarrow \vec{a}} \frac{(n_{3} = n_{1} + n_{2})}{\text{Usum}(\langle T \rangle) \downarrow \langle \rangle}$$

Translation formalization

• General comprehension, $\delta \vdash e \Rightarrow_{s_1}^{s_0} (p, st)$:

$$\begin{split} & [x \mapsto st_1, (x_i \mapsto s_i')_{i=1}^k] \ \vdash \ e_1 \Rightarrow_{s_1''}^{s_i'+1} (p_1, st_2) \\ \hline \\ \delta \ \vdash \ \{e_1 : x \ \text{in} \ y \ \text{using} \ x_1, ..., x_k\} \Rightarrow_{s_1''}^{s_0'} (p, (st_2, s_b)) \\ \\ \begin{pmatrix} \delta(y) = (st_1, s_b), (\delta(x_i) = s_i)_{i=1}^k \\ p = (s_0' := \text{Usum}(s_b); \\ (s_i' := \text{Distr}(s_b, s_i);)_{i=1}^k \\ S_{out} := \text{WithCtrl}(s_0', S_{in}, p_1)) \\ S_{in} = \overline{st_1} \cup \{s_1', ..., s_k'\} \\ S_{out} = \{s \mid s \in \overline{st_2}, s \geq s_k' + 1\} \\ s_{i+1}' = s_i' + 1, \forall i \in \{0, ..., k-1\} \end{split}$$

Value representation formalization

■ Value representation, $v \triangleright_{\tau} w$:

$$\frac{\overline{n} \triangleright_{\mathsf{int}} \langle n \rangle}{\frac{v_1 \triangleright_{\tau} w_1 \cdots v_l \triangleright_{\tau} w_l}{\{v_1, \dots, v_l\} \triangleright_{\{\tau\}} (w, \langle F_1, \dots, F_l, T \rangle)}} (w = w_1 + +_{\tau} \dots + +_{\tau} w_l)$$

■ Value recovery, $w \triangleleft_{\tau} v, w'$:

$$\overline{\langle n_0 | \vec{a} \rangle} \triangleleft_{\mathbf{int}} n_0, \vec{a}$$

$$\frac{w \triangleleft_{\tau} v_{1}, w_{1} w_{1} \triangleleft_{\tau} v_{2}, w_{2} \cdots w_{l-1} \triangleleft_{\tau} v_{l}, w_{l}}{(w, \langle F_{1}, ..., F_{l}, T | \vec{b} \rangle) \triangleleft_{\{\tau\}} \{v_{1}, ..., v_{l}\}, (w_{l}, \vec{b})}$$

 Both representation and recovery are deterministic; high-level values and low-level ones are 1-1 corresponding.

Ex. let x = 10 in $\{i + x : i \text{ in } \& 3 \text{ using } x\} \Rightarrow$:

Ex. let x = 10 in $\{i + x : i$ in &3 using $x\} \Rightarrow$:

 σ_1

```
S6 := <0>
S7 := <()>
S8 := <10>
```

```
\langle p, \sigma_1 \rangle \Downarrow^{s_7} \sigma_1' \$ W_1
```

```
S9 := <10>
```

Ex. let x = 10 in $\{i + x : i \text{ in } \& 3 \text{ using } x\} \Rightarrow$:

```
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```

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```

 σ_2

```
S6 := <1,2>
S7 := <(),()>
S8 := <10,10>
```

$$\langle p, \sigma_1 \rangle \Downarrow^{s_7} \sigma'_1 \$ W_1$$

```
...
S9 := <10>
```

$$\langle p, \sigma_2 \rangle \Downarrow^{s_7} \sigma_2' \$ W_2$$

Ex. let x = 10 in $\{i + x : i \text{ in } \& 3 \text{ using } x\} \Rightarrow$:

 σ_1

```
S6 := <0>
S7 := <()>
S8 := <10>
```

 σ_2

```
S6 := <1,2>
S7 := <(),()>
S8 := <10,10>
```

 $\sigma_1 \bowtie \sigma_2$

```
S6 := <0,1,2>
S7 := <(),(),()>
S8 := <10,10,10>
```

 $\langle p, \sigma_1 \rangle \Downarrow^{s_7} \sigma_1' \$ W_1$

```
...
S9 := <10>
```

 $\langle p, \sigma_2 \rangle \Downarrow^{s_7} \sigma_2' \$ W_2$

```
S9 := <11,12>
```

 $\langle p, \sigma_1 \bowtie \sigma_2 \rangle \Downarrow^{s_7} \sigma'_1 \bowtie \sigma'_2 \$ W$

```
S9 := <10,11,12>
```

Ex. let x = 10 in $\{i + x : i \text{ in } \& 3 \text{ using } x\} \Rightarrow$:

 σ_1

```
S6 := <0>
S7 := <()>
S8 := <10>
```

 σ_2

```
S6 := <1,2>
S7 := <(),()>
S8 := <10,10>
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 $\sigma_1 \bowtie \sigma_2$

```
S6 := <0,1,2>
S7 := <(),(),()>
S8 := <10,10,10>
```

 $\langle p, \sigma_1 \rangle \Downarrow^{s_7} \sigma_1' \$ W_1$

```
...
S9 := <10>
```

 $\langle p, \sigma_2 \rangle \Downarrow^{s_7} \sigma_2' \$ W_2$

```
S9 := <11,12>
```

 $\langle p, \sigma_1 \bowtie \sigma_2 \rangle \Downarrow^{s_7} \sigma'_1 \bowtie \sigma'_2 \$ W$

```
S9 := <10,11,12>
```

Lemma (Parallelism fusion, simplified version)

Correctness theorem

• If e (as well as its free variables) is well-typed, and can be evaluated to v with cost W^H, and translated to p, then executing p will generate streams that can represent v, and the cost is bounded by a constant C times W^H:

Theorem (Translation correctness, simplified version)

```
\begin{array}{lll} \textbf{if } (i) \ \Gamma \ \vdash \ e:\tau \quad \  (ii) \ \rho \ \vdash \ e \downarrow v \ \$ \ W^H \quad \  (iii) \ \delta \ \vdash \ e \Rightarrow_{s_1}^{s_0} (p,st) \\ (iv) \ \forall x \in dom(\Gamma).\rho(x) \triangleright_{\Gamma(x)} \sigma^*(\delta(x)) \\ \textbf{then, } (vii) \ \langle p,\sigma \rangle \downarrow^{\langle () \rangle} \sigma' \ \$ \ W^L \quad (viii) \ v \triangleright_{\tau} \sigma'^*(st) \quad (ix) \ W^L \leq C \cdot W^H \end{array}
```

• Note: $C \ge 7$ (only for **iota**; other cases $C \sim 2$)

Correctness theorem

• If e (as well as its free variables) is well-typed, and can be evaluated to v with cost W^H, and translated to p, then executing p will generate streams that can represent v, and the cost is bounded by a constant C times W^H:

Theorem (Translation correctness, simplified version)

- Note: $C \ge 7$ (only for **iota**; other cases $C \sim 2$)
- Corollary: Implementation correctness
 - (i) if e is well-typed, closed, evaluated to v with cost W^H
 - (ii) then e can be translated to p; executing p generates st that can recover v, with cost W^L bounded by $C \times W^H$
 - (iii) translation, execution of p, recovery are all determinisite

Conclusion

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Main contributions:

- Extension of streaming dataflow model to account for recursion
- A formalization of a subset of the source and target language, and the correctness proof of the translation including work cost preservation

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Future work:

- Extending the proof system to support more types, primitive functions, recursion, step & space preservation, etc.
- Formalization of the streaming semantics of the target language
- Formalization of parallel Xducers
- Investigation of schedulability, deadlock, etc.
 - a characterization of streamability
 - streamable programs do not deadlock