SNESL formalization

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0 Level-0

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0.1 Source language syntax

(Ignore empty sequence for now)

Expressions:

$$e ::= x \mid \mathbf{let} \ x = e_1 \ \mathbf{in} \ e_2 \mid \varphi(x_1, ..., x_k) \mid \{e : x \ \mathbf{in} \ y \ \mathbf{using} \cdot \}$$

$$\varphi = \mathbf{const}_n \mid \mathbf{iota} \mid \mathbf{plus}$$

Values:

$$n \in \mathbf{Z}$$
$$v ::= n \mid \{v_1, ..., v_k\}$$

0.2 Type system

$$\tau ::= \mathbf{int} | \{ \tau_1 \}$$

Type environment $\Gamma = [x_1 \mapsto \tau_1, ..., x_i \mapsto \tau_i].$

• Judgment $\Gamma \vdash e : \tau$

$$\frac{\Gamma \vdash x : \tau}{\Gamma \vdash x : \tau} (\Gamma(x) = \tau) \qquad \frac{\Gamma \vdash e_1 : \tau_1 \qquad \Gamma[x \mapsto \tau_1] \vdash e_2 : \tau}{\Gamma \vdash \text{let } x = e_1 \text{ in } e_2 : \tau}$$

$$\frac{\vdash Typ_{\varphi}(\tau_1, ..., \tau_k) : \tau}{\Gamma \vdash \varphi(x_1, ..., x_k) : \tau} ((\Gamma(x_i) = \tau_i)_{i=1}^k) \qquad \frac{\Gamma[x \mapsto \tau_1] \vdash e : \tau}{\Gamma \vdash \{e : x \text{ in } y \text{ using } \cdot\} : \{\tau\}} (\Gamma(y) = \{\tau_1\})$$

• Auxiliary Judgment $\ \vdash \ Typ_{\varphi}(\tau_1,...,\tau_k):\tau$

$$oxed{\vdash \mathbf{const}_n():\mathbf{int}} oxed{\vdash \mathbf{iota(int)}:\{\mathbf{int}\}} oxed{\vdash \mathbf{plus(int,int)}:\mathbf{int}}$$

0.3 Source language semantics

• Judgment
$$\rho \vdash e \downarrow v$$

$$\frac{\rho \vdash e_1 \downarrow v_1 \qquad \rho[x \mapsto v_1] \vdash e_2 \downarrow v}{\rho \vdash \text{let } e_1 = x \text{ in } e_2 \downarrow v}$$

$$\frac{\vdash Eva_{\varphi}(v_1, ..., v_k) \downarrow v}{\rho \vdash \varphi(x_1, ..., x_k) \downarrow v} ((\rho(x_i) = v_i)_{i=1}^k) \qquad \frac{([x_i \mapsto v_i] \vdash e \downarrow v_i')_{i=1}^k}{\rho \vdash \{e : x \text{ in } y \text{ using } \cdot\} \downarrow \{v_1', ..., v_k'\}} (\rho(y) = \{v_1, ..., v_k\})$$

• Auxiliary Judgment $\vdash Eva_{\varphi}(v_1,...,v_k) \downarrow v$

$$\vdash \mathbf{const}_n() \downarrow n \qquad \qquad \vdash \mathbf{iota}(n) \downarrow \{0, 1, ..., n-1\} \qquad \qquad \vdash \mathbf{plus}(n_1, n_2) \downarrow n_3 \qquad (n_3 = n_1 + n_2)$$

0.4 SVCODE syntax

Stream id:

$$s \in \mathbf{N} = \{0, 1, 2...\}$$

Stream tree:

$$st ::= s \mid (st_1, s)$$

SVCODE expressions:

$$arphi ::= \mathtt{Ctrl} \mid \mathtt{Const_a} \mid \mathtt{ToFlags} \mid \mathtt{Usum} \mid \mathtt{MapTwo} \mid \mathtt{ScanPlus}$$

SVCODE program:

$$\begin{split} p ::= \epsilon \\ \mid s := \psi(s_1, ..., s_i) \\ \mid st := \texttt{WithCtrl}(s, p) \\ \mid p_1; p_2 \end{split}$$

Target language values:

$$b \in \{\mathsf{T},\mathsf{F}\}$$

$$a ::= n \mid b \mid ()$$

$$\neg v ::= \langle a_1,...,a_i \rangle$$

Define some operations on $\rightharpoonup v$ for convenience:

- $\rightharpoonup v_1 + + \rightharpoonup v_2$: append $\rightharpoonup v_2$ to $\rightharpoonup v_1$
- $tail(\langle a_1, a_2, ..., a_i \rangle) = \langle a_2, ..., a_i \rangle$

0.5 SVCODE semantics

• Judgment $\langle p, \sigma \rangle \downarrow^{\rightharpoonup v_c} \sigma'$

$$\frac{SEva_{\varphi}(\rightharpoonup v_1, ..., \rightharpoonup v_k) \downarrow^{\rightharpoonup v_c} \rightharpoonup v}{\langle s := \varphi(s_1, ..., s_k), \sigma \rangle \downarrow^{\rightharpoonup v_c} \sigma[s \mapsto \rightharpoonup v]} ((\sigma(s_i) = \rightharpoonup v_i)_{i=1}^k)$$

$$\frac{\langle p,\sigma\rangle \downarrow^{\rightharpoonup v_s} \sigma'}{\langle st := \mathtt{WithCtrl}(s,p),\sigma\rangle \downarrow^{\rightharpoonup v_c} \sigma'} \left(\sigma(s) = \rightharpoonup v_s = \langle a_1,...,a_i\rangle\right)$$

$$\frac{\langle p_1, \sigma \rangle \downarrow^{\rightharpoonup v_c} \sigma'' \qquad \langle p_2, \sigma'' \rangle \downarrow^{\rightharpoonup v_c} \sigma'}{\langle p_1; p_2, \sigma \rangle \downarrow^{\rightharpoonup v_c} \sigma'}$$

• Auxiliary Judgment $SEva_{\varphi}(\rightharpoonup v_1,...,\rightharpoonup v_k)\downarrow^{\rightharpoonup v_c} \rightharpoonup v$

$$\frac{Block_{\varphi}(\rightharpoonup v_{11},...,\rightharpoonup v_{k1}) \Downarrow \rightharpoonup v_{1} \qquad SEva_{\varphi}(\rightharpoonup v_{12},...,\rightharpoonup v_{k2}) \downarrow^{\mathtt{tail}(\rightharpoonup v_{c})} \rightharpoonup v_{2}}{SEva_{\varphi}(\rightharpoonup v_{11}++\rightharpoonup v_{12},...,\rightharpoonup v_{k1}++\rightharpoonup v_{k2}) \downarrow^{\rightharpoonup v_{c}} \rightharpoonup v} \ (\rightharpoonup v = \rightharpoonup v_{1}++\rightharpoonup v_{2})$$

$$SEva_{\varphi}(\rightharpoonup v_1, ..., \rightharpoonup v_k) \downarrow^{\langle \rangle} \langle \rangle$$

• Auxiliary Judgment
$$Block_{\varphi}(\rightharpoonup v_1, ..., \rightharpoonup v_k) \Downarrow \rightharpoonup v$$

$$\frac{Unary_{\varphi}(\langle \mathsf{F} \rangle, ..., \rightharpoonup v_{k1}) \Downarrow \rightharpoonup v_{1} \qquad Block_{\varphi}(\rightharpoonup v_{12}, ..., \rightharpoonup v_{k2}) \Downarrow \rightharpoonup v_{2}}{Block_{\varphi}(\langle \mathsf{F} \rangle + + \rightharpoonup v_{12}, ..., \rightharpoonup v_{k1} + + \rightharpoonup v_{k2}) \Downarrow \rightharpoonup v} (\rightharpoonup v = \rightharpoonup v_{1} + + \rightharpoonup v_{2})$$

$$Unary_{\varphi}(\langle \mathsf{T} \rangle, ..., \rightharpoonup v_k) \Downarrow \rightharpoonup v$$
$$Block_{\varphi}(\langle \mathsf{T} \rangle, ..., \rightharpoonup v_k) \Downarrow \rightharpoonup v$$

$$\frac{Unary_{\varphi,n_0}(\langle F \rangle, ..., \rightharpoonup v_{k1}) \Downarrow^{n'_0} \langle n_1 \rangle \quad Block_{\varphi,n'_0}(\rightharpoonup v_{12}, ..., \rightharpoonup v_{k2}) \Downarrow \rightharpoonup v_2}{Block_{\varphi,n_0}(\langle F \rangle ++ \rightharpoonup v_{12}, ..., \rightharpoonup v_{k1} ++ \rightharpoonup v_{k2}) \Downarrow \langle n_1 \rangle ++ \rightharpoonup v_2}$$

$$\frac{Unary_{\varphi,n_0}(\langle \mathtt{T} \rangle,...,\rightharpoonup v_k) \Downarrow \langle n_1 \rangle}{Block_{\varphi,n_0}(\langle \mathtt{T} \rangle,...,\rightharpoonup v_k) \Downarrow \langle n_1 \rangle}$$

- Auxiliary Judgment $\boxed{Unary_{\varphi}(\langle b \rangle, ..., \rightharpoonup v_k) \Downarrow \rightharpoonup v}$

$$Usum(\langle F \rangle) \downarrow \langle () \rangle$$
 $Usum(\langle T \rangle) \downarrow \langle \rangle$

$$\overline{\text{ScanPlus}_{n_0}(\langle \mathtt{F} \rangle, \langle n \rangle) \Downarrow^{n_0 + n} \langle n_0 \rangle} \qquad \overline{\text{ScanPlus}_{n_0}(\langle \mathtt{T} \rangle, \langle \rangle) \Downarrow \langle n_0 \rangle}$$

0.6 Translation

$$\delta \vdash e \xrightarrow{s_0 + 1 \atop s_1} (p, st)$$

$$\delta \vdash e \xrightarrow{s_0 \atop s_1} \text{let } s_0 := \text{Ctrl}; p \text{ in } st$$

• Judgment $\delta \vdash e \stackrel{s_0}{\underset{s_1}{\Longrightarrow}} (p, st)$

$$\frac{\delta \vdash x \stackrel{s_0}{\Longrightarrow} (p, st)}{\delta \vdash x \stackrel{s_0}{\Longrightarrow} (p, st)} (\delta(x) = st) \qquad \frac{\delta \vdash e_1 \stackrel{s_0}{\Longrightarrow} (p_1, st_1) \qquad \delta[x \mapsto st_1] \vdash e_2 \stackrel{s'_0}{\Longrightarrow} (p_2, st)}{\delta \vdash \text{let } x = e_1 \text{ in } e_2 \stackrel{s_0}{\Longrightarrow} (p_1; p_2, st)}$$

$$\frac{Trans_{\varphi}(st_1, ..., st_k) \stackrel{s_0}{\underset{s_1}{\rightleftharpoons}} (p, st)}{\delta \vdash \varphi(x_1, ..., x_k) \stackrel{s_0}{\underset{s_1}{\rightleftharpoons}} (p, st)} ((\delta(x_i) = st_i)_{i=1}^k)$$

$$\frac{[x \mapsto st_1] \ \vdash \ e \xrightarrow[s_1]{s_0} (p,st)}{\delta \ \vdash \ \{e : x \ \textbf{in} \ y \ \textbf{using} \ \cdot\} \xrightarrow[s_1]{s_0} (s_0 := \texttt{Usum}(s_2); st := \texttt{WithCtrl}(s_0,p), st)} (\delta(y) = (st_1,s_2))$$

• Auxiliary Judgment $Trans_{\varphi}(st_1,...,st_k) \stackrel{s_0}{=} (p,st)$

$$\mathbf{const}_a() \xrightarrow[s_0+1]{s_0} (s_0 := \mathsf{Const}_\mathtt{a}, s_0)$$

$$\frac{1}{\mathbf{iota}(s) \overset{s_0}{\underset{s_4}{\Longrightarrow}} (p,(s_3,s_0))} \begin{pmatrix} s_{i+1} = s_i + 1 \\ p = s_0 := \mathtt{ToFlags}(s); \\ s_1 := \mathtt{Usum}(s_0); \\ s_2 := \mathtt{WithCtrl}(s_1,s_2 := \mathtt{Const}_1); \\ s_3 := \mathtt{ScanPlus}(s_0,s_2) \end{pmatrix}$$

$$\frac{\mathbf{plus}(s_1,s_2) \overset{s_0}{\underset{s_0}{\Longrightarrow}} (s_0 := \mathtt{MapTwo}(s_1,s_2),s_0)}{\mathbf{plus}(s_1,s_2) \overset{s_0}{\underset{s_0}{\Longrightarrow}} (s_0 := \mathtt{MapTwo}(s_1,s_2),s_0)}$$

0.7 Value representation

$$TODO: define \ \sigma(st)$$

$$Judgment \ \sigma \vdash v \triangleright_{\tau} st$$

$$\frac{\sigma \vdash n \triangleright_{\mathbf{int}} s}{\sigma \vdash \{n_1, ..., n_k\} \triangleright_{\{\mathbf{int}\}} (s, s')} \left(\begin{matrix} \sigma(s) = \sigma(s_1) + \sigma(s_2) + + ... + \sigma(s_k) \\ \sigma(s') = \langle F_1, ..., F_k, T \rangle \end{matrix} \right)$$

$$\frac{(\sigma \vdash v_i \triangleright_{\tau} (st_i, s_i))_{i=1}^k}{\sigma \vdash \{v_1, ..., v_k\} \triangleright_{\{\tau\}} ((st, s), s')} \left(\begin{matrix} \tau \neq \mathbf{int} \\ \sigma(st) = \sigma(st_1) + \sigma(st_2) + + ... + \sigma(st_k) \\ \sigma(s) = \sigma(s_1) + + \sigma(s_2) + + ... + \sigma(st_k) \\ \sigma(s) = \sigma(s_1) + \sigma(s_2) + + ... + \sigma(s_k) \\ \sigma(s') = \langle F_1, ..., F_k, T \rangle \end{matrix} \right)$$

$$\mathbf{0.8} \quad \mathbf{Correctness proof}$$

0.8 Correctness proof