Formalizing the implementation of Streaming NESL

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Contents

1. Introduction

- NESL
- Streaming NESL (SNESL)

2. Implementation

- Extended target language (supporting recursion)
- Translation
- Streaming SVCODE interpreter

3. Formalization

- Source and target language semantics
- Target language well-formedness, determinism
- Translation correctness (including work preservation)

4. Conclusion

Introduction

NESL

- A functional nested data-parallel language
- Developed by Guy E. Blelloch in 1990s at CMU
- Highlights:
 - Highly expressive for parallel algorithms.
 Main data-parallel construct: apply-to-each,

$$\{e_1(x): x \text{ in } e_0\}$$

Example: compute $\sum_{i=0}^{k-1}$ for $k \in [2,3,4]$ (result: [1,3,6]):

$$\{\mathbf{sum}(\&x): x \ \mathbf{in} \ [2,3,4]\}$$

- An intuitive cost model for time complexity: work-step model
 - work cost t1: total number of operations executed
 - step cost t_{∞} : the longest chain of sequential dependency

Streaming NESL (SNESL)

- Experimental refinement of NESL
- Aiming at improving space-usage efficiency
- Work from Frederik M. Madsen and Andrzej Filinski in 2010s at DIKU
- Highlights:
 - Streaming semantics

```
\begin{split} \pi &::= \mathbf{bool} \mid \mathbf{int} \mid \mathbf{char} \mid \mathbf{real} \mid \cdots & \text{(scalar types)} \\ \tau &::= \pi \mid (\tau_1, ..., \tau_k) \mid [\tau] & \text{(concrete types)} \\ \sigma &::= \tau \mid (\sigma_1, ..., \sigma_k) \mid \{\sigma\} & \text{(general types)} \end{split}
```

- A space cost model
 - sequential space s₁: the minimal space to perform the computation
 - parallel space s_{∞} : space needed to achieve the maximal parallel degree (NESL's case)

SNESL syntax

Expressions

```
\begin{array}{ll} e ::= a \mid x \mid (e_1,...,e_k) \mid \textbf{let} \ x = e_1 \ \textbf{in} \ e_2 \mid \phi(e_1,...,e_k) \\ \\ \mid \{e_1 : \ x \ \textbf{in} \ e_0\} & \text{(general comprehension)} \\ \\ \mid \{e_1 \mid e_0\} & \text{(restricted comprehension)} \end{array}
```

Primitive functions

```
\begin{array}{lll} \phi & ::= \oplus \mid \ \ \mbox{append} \mid \mbox{concat} \mid \mbox{zip} \mid \mbox{iota} \mid \mbox{part} \mid \mbox{scan}_{\otimes} \mid \mbox{reduce}_{\otimes} \\ & \mid \mbox{mkseq} \mid \mbox{the} \mid \mbox{empty} & (\mbox{sequence operations}) \\ & \mid \mbox{length} \mid \mbox{elt} & (\mbox{vector operations}) \\ & \mid \mbox{seq} \mid \mbox{tab} & (\mbox{convertion between vector and sequence}) \\ & \oplus ::= + \mid \times \mid / \mid \mbox{=} \mid \mbox{not} \mid \cdots & (\mbox{scalar operations}) \\ & \otimes ::= + \mid \times \mid \mbox{max} \mid \dots & (\mbox{associative binary operations}) \end{array}
```

SNESL primitive functions

$++: (\{\sigma\}, \{\sigma\}) \rightarrow \{\sigma\}$	append two sequences
$\mathbf{concat}: \{\{\sigma\}\} \to \{\sigma\}$	flatten a sequence of sequences
$ \overline{zip \colon \left(\{ \sigma_1 \},, \{ \sigma_k \} \right)} \rightarrow $	$zip(\{1,2\},\{F,T\}) = \{(1,F),(2,T)\}$
$\{(\sigma_1,,\sigma_k)\}$	
$\&:int\to\{int\}$	&5 = {0,1,2,3,4}
$part: (\{\sigma\}, \{bool\}) \to \{\{\sigma\}\}$	$part(\{3,1,4\}, \{F,F,T,F,T,T\}) = \{\{3,1\}, \{4\}, \{\}\}\}$
$scan_\otimes: \{int\} o \{int\}$	$scan_{+}(\&5) = \{0,0,1,3,6\}$
$reduce_\otimes: \{int\} \to int$	$reduce_{+}(\&5) = 10$
$mkseq: (\overbrace{\sigma,,\sigma}^k) \to \{\sigma\}$	$mkseq(1,2,3) = \{1,2,3\}$
$\# \colon [au] o int$	length of a vector
$!: ([\tau], int) \to \tau $	element indexing, $[3,8,2]$! $1=8$
the : $\{\sigma\} \to \sigma$	return the element of a singleton, $\mathbf{the}(\{10\}) = 10$
$empty: \{\sigma\} \to bool$	test a sequence empty or not
$seq: [au] o \{ au\}$	$seq([1,2]) = \{1,2\}$
$\frac{seq: [\tau] \to \{\tau\}}{tab: \{\tau\} \to [\tau]}$	$\begin{split} & seq([1,2]) = \{1,2\} \\ & tab(\{1,2\}) = [1,2] \end{split}$

5/26

??[optional] Example program: Splitting a string into words

Implementation

Source language

Simplified SNESL types

```
\begin{split} \pi &::= \mathbf{bool} \mid \mathbf{int} & \text{(only two scalar types)} \\ \tau &::= \pi \mid (\tau_1, \tau_2) \mid \{\tau\} & \text{(no vectors, tuples to pairs)} \\ \varphi &::= (\tau_1, ..., \tau_k) \to \tau & \text{(support recursion)} \end{split}
```

Syntax

```
\begin{array}{l} t ::= \mathbf{eval} \ e \ | \ d \ t \\ e ::= a \ | \ x \ | \ (e_1, e_2) \ | \ \mathbf{let} \ x = e_1 \ \mathbf{in} \ e_2 \ | \ \phi(e_1, ..., e_k) \\ | \ \{ \} \tau \ | \ \{e_1, ..., e_k\} \quad (k \geq 1) \\ | \ \{ e_1 : x \ \mathbf{in} \ e_0 \ \mathbf{using} \ x_1, ..., x_k \} \ | \ \{ e_1 \ | \ e_0 \ \mathbf{using} \ x_1, ..., x_k \} \\ | \ f(e_1, ..., e_k) \qquad \qquad \qquad \qquad \text{(user-defined function call)} \\ d ::= \mathbf{function} \ f(x_1 \colon \tau_1, ..., x_k \colon \tau_k) \colon \tau = e \\ \phi ::= \oplus \ | \ \ +\!\!\!+_{\tau} \ | \ \mathbf{concat}_{\tau} \ | \ \& (\mathbf{iota}) \ | \ \mathbf{part}_{\tau} \ | \ \mathbf{scan}_{+} \ | \ \mathbf{reduce}_{+} \ | \cdots \end{array}
```

Source language

Key typing rules:

$$\frac{\Gamma \vdash_{\Sigma} e_{0} : \{\tau_{0}\} \qquad [x \mapsto \tau_{0}, (x_{i} \mapsto \tau_{i})_{i=1}^{k}] \vdash_{\Sigma} e_{1} : \tau}{\Gamma \vdash_{\Sigma} \{e_{1} : x \text{ in } e_{0} \text{ using } x_{1}, ..., x_{k}\} : \{\tau\}} \begin{pmatrix} (\Gamma(x_{i}) = \tau_{i}) \\ \tau_{i} \text{ concrete} \end{pmatrix}_{i=1}^{k} \end{pmatrix}}$$

$$\frac{\Gamma \vdash_{\Sigma} e_{0} : \text{bool} \qquad [(x_{i} \mapsto \tau_{i})_{i=1}^{k}] \vdash_{\Sigma} e_{1} : \tau}{\Gamma \vdash_{\Sigma} \{e_{1} \mid e_{0} \text{ using } x_{1}, ..., x_{k}\} : \{\tau\}} ((\Gamma(x_{i}) = \tau_{i})_{i=1}^{k})$$

$$\frac{\Gamma \vdash_{\Sigma} e_{1} : \tau_{1} \qquad \cdots \qquad \Gamma \vdash_{\Sigma} e_{k} : \tau_{k}}{\Gamma \vdash_{\Sigma} f(e_{1}, ..., e_{k}) : \tau} (\Sigma(f) = (\tau_{1}, ..., \tau_{k}) \to \tau)$$

Key evaluation rules:

$$\frac{\rho \vdash_{\Phi} e_0 \downarrow \{v_1, ..., v_l\} \qquad ([x \mapsto v_i, x_j \mapsto \rho(x_j))_{j=1}^k] \vdash_{\Phi} e_1 \downarrow v_i')_{i=1}^l}{\rho \vdash_{\Phi} \{e_1 : x \text{ in } e_0 \text{ using } x_1, ..., x_k\} \downarrow \{v_1', ..., v_l'\}}$$

$$\frac{(\rho \vdash_{\Phi} e_i \downarrow v_i)_{i=1}^k \qquad [(x_i \mapsto v_i)_{i=1}^k] \vdash_{\Phi} e_0 \downarrow v}{\rho \vdash_{\Phi} f(e_1, ..., e_k) \downarrow v}$$
where $\Phi(f) = f(x_1 : \tau_1, ..., x_k : \tau_k) : \tau = e_0$

Target language: SVCODE

- SVCODE values:
 - primitive stream: $\vec{a} := \langle a_1, ..., a_l \rangle$, e.g., $\langle 1, 2, 3 \rangle$, $\langle F, T, F, F, T \rangle$
 - stream tree: $w := \vec{a} \mid (w_1, w_2)$
- SVCODE syntax

```
p ::= \epsilon \mid p_1; p_2
       | s := \psi(s_1, ..., s_k)
                                                                   (single stream definition)
       |S_{out}| := WithCtrl(s, S_{in}, p_1)
                                                                             (WithCtrl block)
       (s'_1,...,s'_{k'}) := SCall f(s_1,...,s_k)
                                                                                   (function call)
s ::= 0 \mid 1 \mid \cdots \in \mathsf{SId} = \mathbb{N}
                                                                                      (stream ids)
S ::= \{s_1, ..., s_k\} \in \mathbb{S}
                                                                             (set of stream ids)
\psi ::= \mathtt{Const}_\mathtt{a} \mid \mathtt{ToFlags} \mid \mathtt{Usum} \mid \mathtt{Map}_{\scriptscriptstyle \square} \mid \mathtt{Scan}_+ \mid \mathtt{Reduce}_+ \mid \mathtt{Distr}
       | Pack | UPack | B2u | SegConcat | InterMerge | ...
                                                                                          (Xducers)
```

SVCODE dataflow

```
S1 := Const_3

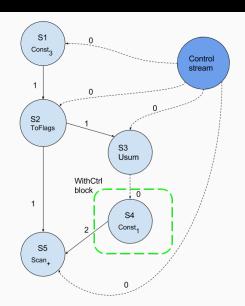
S2 := ToFlags S1

S3 := Usum S2

[S4] := WithCtrl S3 []:

S4 := Const_1()

S5 := ScanPlus S2 S4
```



Value representation

- Scalars are represented as singleton primitive streams: e.g., $3 \triangleright_{int} \langle 3 \rangle, T \triangleright_{bool} \langle T \rangle$
- A nested sequence with a nesting depth d is represented as a flattening data stream and d descriptor streams.

$$\begin{split} \left\{ \left\{3,1\right\}, \left\{4\right\} \right\} &\triangleright_{\left\{\left\{\text{int}\right\}\right\}} \left(\left(\left\langle 3,1,4\right\rangle, \left\langle F,F,T,F,T\right\rangle \right), \left\langle F,F,T\right\rangle \right) \\ &\left\{T,F\right\} &\triangleright_{\left\{\text{bool}\right\}} \left(\left\langle T,F\right\rangle, \left\langle F,F,T\right\rangle \right) \end{split}$$

 A pair of SNESL values is represented as a pair of stream trees.

$$\big(\{\mathtt{T},\mathtt{F}\},2\big) \triangleright_{(\{\textbf{bool}\},\textbf{int})} \big(\big(\langle\mathtt{T},\mathtt{F}\rangle,\langle\mathtt{F},\mathtt{F},\mathtt{T}\rangle\big),\langle 2\rangle\big)$$

A sequence of pairs is represented as a pair of sequences sharing one descriptor:

$$\{(1,\mathsf{T}),(2,\mathsf{F}),(3,\mathsf{F})\} \triangleright_{\{(\mathsf{int},\mathsf{bool})\}} ((\langle 1,2,3\rangle,\langle \mathsf{T},\mathsf{F},\mathsf{F}\rangle),\langle \mathsf{F},\mathsf{F},\mathsf{F},\mathsf{T}\rangle)_{11/26}$$

Translation

- **STree** \ni *st* ::= *s* | (*st*₁, *st*₂)
- Translation symbol table $\delta ::= [x_1 \mapsto st_1, ..., x_k \mapsto st_k]$
- General comprehension translation: {i+x: i in &3 using x} ⇒

```
1 ...
2 S4 := ... -- <1 > x
3 S5 := ... -- <F,F,F,T> descriptor of &3
4 S6 := ... -- <0,1,2> i
5 S7 := Usum S5; -- 1. generate new control: <() () ()>
6 S8 := Distr S4 S5; -- 2. replicate x 3 times: <1 1 1 >
7 [S9] := WithCtrl S7 [S6,S8]: -- 3. translate (i+x)
8 S9 := Map_+ S6 S8 -- <1,2,3>
```

 Restricted comprehension translation: Pack free variables instead of Distr

Translation continue

- Built-in function translation:
 - scan, reduce, concat, part, empty: translated to a single stream definition, e.g., $\operatorname{scan}_+((s_d, s_b)) \Rightarrow \operatorname{Scan}_+(s_b, s_d)$
 - the, iota translated to a few lines of code, e.g.,

```
egin{aligned} s_0 &:= 	exttt{ToFlags}(s); \ & s_1 := 	exttt{Usum}(s_0); \ & \{s_2\} := 	exttt{WithCtrl}(s_1, \{\}, s_2 := 	exttt{Const}_1()); \ & s_3 := 	exttt{Scan}_+(s_0, s_2) \end{aligned}
```

- $++_{\tau}$: translated recursively, depending on τ
- User-defined functions: translated to SVCODE functions, unfolded at runtime when interpreting a SCall

SVCODE interpreters

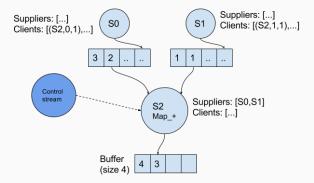
- Eager interpreter (NESL-like)
 - sufficient memory for allocating all streams at once
 - execute each instruction sequentially
 - an extreme/simplest case of the streaming one with the largest buffer size, used to compare results and analyze time complexity
- Streaming interpreter
 - limited buffer size, space-usage efficient
 - result is collected from each scheduling round
 - need effective scheduling strategy to avoid deadlock and guarantee cost preservation

SVCODE streaming interpreter

- Dataflow graph is similar to a Kahn process network
 - Graph node (a process): Proc = (BufState, S, Clis, Xducer)
 - Buffer state maintained by process:

BufState ::= Filling $\vec{a} \mid \text{Draining } \vec{a}' \ b$

A process example:



Recursion example

A function to compute factorial:

```
1  > function fact(x:int):int = if x <= 1 then 1 else x*fact(x-1)
2  > let x = {3,7,0,4} in {fact(y): y in x }
```

1st unfolding (will unfold 7 times in total):

```
-- Parameters: [S1]
                                         -- <3 7 0 4>
   ... -- compare parameters with 1, get S5 = <T T FT T>
   S6 := Usum S5; -- for elements <=1 -- < () >
   [S7] := WithCtrl S6 []: S7 := Const 1 -- < 1 >
5
   . . .
   S13 := Usum S11; -- for elementes >1 -- <()() ()>
   [S17] := WithCtrl S13 [S12]:
              S14 := Const 1
                                    -- <1 1 1>
              S15 := MapTwo Minus S12 S14 -- <2 6 3>
10
              [S16] := SCall fact [S15] -- <2 720 6>
                 recursive call
11
              S17 := MapTwo Times S12 S16 -- <6 5040 24>
12
   ... -- merge results
                                                                16/26
13
   S19 := PriSegInterS [(S7,S5),(S17,S11)]; -- <6 5040 1 24>
```

Formalization

Source language: SNESL₀

Types:

$$au ::= \mathsf{int} \mid \{ au_1\}$$

Expressions:

$$e ::= x \mid \text{let } x = e_1 \text{ in } e_2 \mid \phi(x_1, ..., x_k) \mid \{e : x \text{ in } y \text{ using } x_1, ..., x_k\}$$

 $\phi ::= \text{const}_n \mid \text{iota} \mid \text{plus}$

- Key evaluation rules with work cost W:
 - General comprehension:

$$\frac{([x \mapsto v_i, x_1 \mapsto n_1, ..., x_k \mapsto n_k] \vdash e \downarrow v_i' \$ W_i)_{i=1}^l}{\rho \vdash \{e : x \text{ in } y \text{ using } x_1, ..., x_k\} \downarrow \{v_1', ..., v_l'\} \$ W}$$
where $\rho(y) = \{v_1, ..., v_l\}, (\rho(x_i) = n_i)_{i=1}^k$, and
$$W = (k+1) \cdot (l+1) + \sum_{i=1}^l W_i$$

Built-in function:

$$\frac{\phi(v_1,...,v_k) \downarrow v}{\rho \vdash \phi(x_1,...,x_k) \downarrow v \$ (\sum_{i=1}^k |v_i|) + |v|} ((\rho(x_i) = v_i)_{i=1}^k)$$

Target language: SVCODE₀

syntax

$$p ::= \epsilon \mid s := \psi(s_1, ..., s_k) \mid S_{out} := \texttt{WithCtrl}(s, S_{in}, p_1) \mid p_1; p_2$$

- key semantics with work cost
 - Empty new control stream $(\sigma(s_c) = \langle \rangle)$:

$$\overline{\langle \mathcal{S}_{out} := \mathtt{WithCtrl}(s_c, \mathcal{S}_{\mathit{in}}, p_1), \sigma \rangle \Downarrow^{\vec{c}} \sigma[(s_i \mapsto \langle \rangle)_{i=1}^k] \$ \ 1}$$

where
$$\forall s \in \{s_c\} \cup S_{in}.\sigma(s) = \langle \rangle$$
, $S_{out} = \{s_1, ..., s_k\}$

Nonempty new control stream $(\sigma(s_c) = \vec{c}_1 \neq \langle \rangle)$: $\langle p_1, \sigma \rangle \Downarrow^{\vec{c}_1} \sigma'' \$ W_1$

$$\langle S_{out} := \texttt{WithCtrl}(s_c, S_{in}, p_1), \sigma \rangle \Downarrow^{\vec{c}} \sigma[(s_i \mapsto \sigma''(s_i))_{i=1}^k] \$ W_1 + 1$$

* Xducers, $((\sigma(s_i) = \vec{a}_i)_{i=1}^k)$ $\psi(\vec{a}_1, ..., \vec{a}_k) \Downarrow^{\vec{c}} \vec{a}$ $\langle s := \psi(s_1, ..., s_k), \sigma \rangle \Downarrow^{\vec{c}} \sigma[s \mapsto \vec{a}] \$ (\sum_{i=1}^k |\vec{a}_i|) + |\vec{a}|$

Xducer semantics

• General semantics: **Judgment** $\psi(\vec{a}_1,...,\vec{a}_k) \Downarrow^{\vec{c}} \vec{a}$

$$\frac{\psi(\vec{a}_{11},...,\vec{a}_{k1})\downarrow\vec{a}_{01} \qquad \psi(\vec{a}_{12},...,\vec{a}_{k2})\Downarrow^{\vec{c}_0}\vec{a}_{02}}{\psi(\vec{a}_{1},...,\vec{a}_{k})\Downarrow^{\langle()|\vec{c}_0\rangle}\vec{a}_{0}}\left((\vec{a}_{i1}+\!\!\!+\!\!\!\vec{a}_{i2}=\vec{a}_i)_{i=0}^k\right)$$

- $\bullet \quad \overline{\psi(\langle \rangle_1,...,\langle \rangle_k) \Downarrow^{\langle \rangle} \langle \rangle}$
- Specific semantics (part): **Judgment** $\psi(\vec{a}_1,...,\vec{a}_k)\downarrow\vec{a}$

$$\frac{}{\mathsf{Const}_{a}() \downarrow \langle a \rangle} \qquad \frac{}{\mathsf{ToFlags}(\langle n \rangle) \downarrow \langle F_{1}, ..., F_{n}, T \rangle} (n \geq 0)$$

$$\overline{\text{MapTwo}_{+}(\langle n_{1} \rangle, \langle n_{2} \rangle) \downarrow \langle n_{3} \rangle} (n_{3} = n_{1} + n_{2})$$

$$\frac{\mathtt{Usum}(\vec{b})\downarrow\vec{a}}{\mathtt{Usum}(\langle\mathtt{F}|\vec{b}\rangle)\downarrow\langle()|\vec{a}\rangle} = \frac{}{\mathtt{Usum}(\langle\mathtt{T}\rangle)\downarrow\langle\rangle}$$

SVCODE_0 determinism

Definition (Stream prefix)

Judgment
$$\vec{a} \sqsubseteq \vec{a}'$$

$$\frac{\vec{a} \sqsubseteq \vec{a}'}{\langle \rangle \sqsubseteq \vec{a}'} \qquad \frac{\vec{a} \sqsubseteq \vec{a}'}{\langle a_0 | \vec{a} \rangle \sqsubseteq \langle a_0 | \vec{a}' \rangle}$$

Lemma (Blocks are self-delimiting)

If (i)
$$(\vec{a}'_i \sqsubseteq \vec{a}_i)_{i=1}^k$$
 and $\psi(\vec{a}'_1,...,\vec{a}'_k) \downarrow \vec{a}'$,
(ii) $(\vec{a}''_i \sqsubseteq \vec{a}_i)_{i=1}^k$ and $\psi(\vec{a}''_1,...,\vec{a}''_k) \downarrow \vec{a}''$,
then $(\vec{a}'_i = \vec{a}''_i)_{i=1}^k$, and $\vec{a}' = \vec{a}''$.

Lemma (Xducer determinism)

If
$$\psi(\vec{a}_1,...,\vec{a}_k) \Downarrow^{\vec{c}} \vec{a}_0$$
, and $\psi(\vec{a}_1,...,\vec{a}_k) \Downarrow^{\vec{c}} \vec{a}'_0$, then $\vec{a}_0 = \vec{a}'_0$.

Theorem (SVCODE₀determinism)

If
$$\langle p, \sigma \rangle \Downarrow^{\vec{c}} \sigma' \$ W$$
 and $\langle p, \sigma \rangle \Downarrow^{\vec{c}} \sigma'' \$ W$, then $\sigma' = \sigma''$ and $W = W'$.

Translation formalization

General comprehension translation:

translation well-formedness

Lemma

If $\phi(st_1,...,st_k) \Rightarrow_{s_1}^{s_0} (p,st), \bigcup_{i=1}^k \overline{\overline{st_i}} \subseteq S$, and $S \lessdot s_0$, **then**, for some S', $S \Vdash p : S'$, $S' \subseteq \{s_0, s_0+1, ..., s_1-1\}$, and $\overline{\overline{st}} \subseteq (S \cup S')$

Theorem

If $\delta \vdash e \Rightarrow_{s_1}^{s_0} (p, st), \forall x \in dom(\delta).\overline{\delta(x)} \subseteq S$, and $S \lessdot s_0$ **then**, for some S', $S \Vdash p : S'$, $S' \subseteq \{s_0, s_0+1, ..., s_1-1\}$, and $\overline{\overline{st}} \subseteq (S \cup S')$

21/26

Value representation formalization

• Value representation rules: **Judgment** $v \triangleright_{\tau} w$

$$\frac{(v_i \triangleright_{\tau} w_i)_{i=1}^l}{\{v_1, ..., v_l\} \triangleright_{\{\tau\}} (w, \langle F_1, ..., F_l, T \rangle)} (w = (++_{\tau} w_i)_{i=1}^l)$$

■ Value recovery rules: **Judgment** $w \triangleleft_{\tau} v, w$

$$\frac{}{\langle n_0 | \vec{a} \rangle \triangleleft_{\mathbf{int}} n_0, \vec{a}} \quad \frac{w \triangleleft_{\tau} v_1, w_1 \qquad w_1 \triangleleft_{\tau} v_2, w_2 \qquad \cdots \qquad w_{l-1} \triangleleft_{\tau} v_l, w_l}{\left(w, \langle F_1, ..., F_l, T | \vec{b} \rangle\right) \triangleleft_{\{\tau\}} \left\{v_1, ..., v_l\right\}, \left(w_l, \vec{b}\right)}$$

Lemma (Recovery correctness)

If $v \triangleright_{\tau} w$, then $\forall w . (w + +_{\tau} w) \triangleleft_{\tau} v, w'$.

Lemma (Recovery determinism)

If $w \triangleleft_{\tau} v, w'$, and $w \triangleleft_{\tau} v', w''$, then v = v', and w' = w''.

Corollary

If $v \triangleright_{\tau} w$, $v' \triangleright_{\tau} w$, then v = v'.

Parallelism fusion lemma

Definition (Store similarity)

$$\sigma_1 \overset{S}{\sim} \sigma_2$$
 iff $dom(\sigma_1) = dom(\sigma_2)$, and $\forall s \in S.\sigma_1(s) = \sigma_2(s)$

Definition (Store Concatenation)

For
$$\sigma_1 \stackrel{S}{\sim} \sigma_2$$
, $\sigma_1 \bowtie \sigma_2 = \sigma$ where $\sigma(s) = \begin{cases} \sigma_1(s) \ (= \sigma_2(s)), & s \in S \\ \sigma_1(s) + \sigma_2(s), & s \notin S \end{cases}$

Lemma (Xducer concatenation)

If
$$\psi(\vec{a}_1,...,\vec{a}_k) \Downarrow^{\vec{c}} \vec{a}$$
, and $\psi(\vec{a}_1',...,\vec{a}_k') \Downarrow^{\vec{c}'} \vec{a}'$, then $\psi(\vec{a}_1++\vec{a}_1',...,\vec{a}_k++\vec{a}_k') \Downarrow^{\vec{c}++\vec{c}'} \vec{a}++\vec{a}'$.

Lemma (Parallelism fusion)

If (i)
$$S_1 \Vdash p: S_2$$
, (ii) $\sigma_1 \stackrel{S}{\sim} \sigma_2$, (iii) $\langle p, \sigma_1 \rangle \Downarrow^{\vec{c}_1} \sigma_1' \$ W_1$, (iv) $\langle p, \sigma_2 \rangle \Downarrow^{\vec{c}_2} \sigma_2' \$ W_2$, and (v) $(S_1 \cup S_2) \cap S = \emptyset$, then $\sigma_1' \stackrel{S}{\sim} \sigma_2'$, $\langle p, \sigma_1 \stackrel{S}{\bowtie} \sigma_2 \rangle \Downarrow^{\vec{c}_1 + + \vec{c}_2} \sigma_1' \stackrel{S}{\bowtie} \sigma_2' \$ W$, and $W \leq W_1 + W_2$

Correctness of translation and cost preservation

Theorem (Correctness for expressions)

```
For some constant C. if
(i) \Gamma \vdash e : \tau
(ii) \rho \vdash e \downarrow v \$ W^H
(iii) \delta \vdash e \Rightarrow_{s_1}^{s_0} (p, st)
(iv) \forall x \in dom(\Gamma). \vdash \rho(x) : \Gamma(x)
(v) \ \forall x \in dom(\Gamma).\overline{\delta(x)} \lessdot s_0
(vi) \forall x \in dom(\Gamma).\rho(x) \triangleright_{\Gamma(x)} \sigma^*(\delta(x))
then. for some \sigma' and W^{L}.
(vii) \langle p, \sigma \rangle \Downarrow^{\langle () \rangle} \sigma' \$ W^L
(viii) v \triangleright_{\tau} \sigma'^*(st)
(ix) W^L < C \cdot W^H
```

Scaling up

- More scalar types and built-in operations: should be trivial
- Step/space cost: similar to work cost
- Pairs/tuples: require more value representation rules
- Restricted comprehension: similar to the general one, but need some thinking about packing general types
- Error preservation: possible to support
- Recursion: consider termination preservation (from high-level to low-level) and reflection (from low-level to high-level)
- Streaming semantics: challenging, open problem

Conclusion

Conclusion

Main contributions:

- Extension of streaming dataflow model to account for recursion
- A formalization of the source and target language, and the correctness proof of the translation including working cost preservation

Future work:

- Formalization of the streaming semantics of the target language
- More investigation to schedulability, deadlock, etc.