

Figure 1: Results of the proposed method on the KITTI dataset. The figure is divided into two main sections, (a) and (b), each showing a sequence of images and corresponding depth maps.

(a) KITTI dataset results. The top row shows four pairs of images (original image and depth map) for different frames. The bottom row shows a sequence of depth maps for a specific frame, with a color bar indicating depth values from 0 to 100 meters. Below the images, there is a detailed table of parameters and settings for the proposed method.

(b) KITTI dataset results. The top row shows four pairs of images (original image and depth map) for different frames. The bottom row shows a sequence of depth maps for a specific frame, with a color bar indicating depth values from 0 to 100 meters. Below the images, there is a detailed table of parameters and settings for the proposed method.

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