

```
import numpy as np
import matplotlib.pyplot as plt

# Define the original rectangle (x, y, width, height)
x1, y1, x2, y2 = 0, 0, 2, 1

# Define the transformation matrix
def translation_matrix(tx, ty):
    return np.array([
        [1, 0, tx],
        [0, 1, ty],
        [0, 0, 1]
    ])

def scaling_matrix(sx, sy):
    return np.array([
        [sx, 0, 0],
        [0, sy, 0],
        [0, 0, 1]
    ])

def rotation_matrix(angle):
    angle = np.radians(angle)
    return np.array([
        [np.cos(angle), -np.sin(angle), 0],
        [np.sin(angle), np.cos(angle), 0],
        [0, 0, 1]
    ])

def reflection_matrix(axis):
    if axis == 'x':
        return np.array([
            [-1, 0, 0],
            [0, 1, 0],
            [0, 0, 1]
        ])
    elif axis == 'y':
        return np.array([
            [1, 0, 0],
            [0, -1, 0],
            [0, 0, 1]
        ])
    elif axis == 'xy':
        return np.array([
            [-1, 0, 0],
            [0, -1, 0],
            [0, 0, 1]
        ])

def shearing_matrix(sx, sy):
    return np.array([
        [1, sy, 0],
        [0, 1, 0],
        [0, 0, 1]
    ])

# Apply transformation function
def apply_transformation(object_coords, transformation_matrix):
    return np.dot(object_coords, transformation_matrix.T)

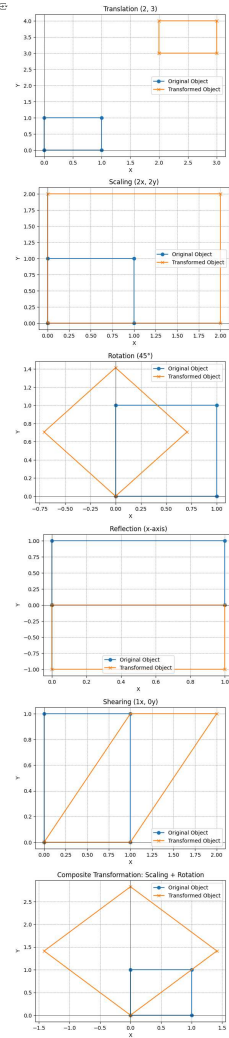
# Plot function
def plot_transformation(original, transformed, title):
    plt.figure()
    plt.plot(original[:, 0], original[:, 1], label='Original Object', marker='x')
    plt.plot(transformed[:, 0], transformed[:, 1], label='Transformed Object', marker='x')
    plt.axis('equal')
    plt.grid(True)
    plt.xlabel('x')
    plt.ylabel('y')
    plt.title(title)
    plt.legend()

# Define transformations
translation = translation_matrix(2, 3)
scaling = scaling_matrix(2, 3)
rotation = rotation_matrix(45)
reflection_x = reflection_matrix('x')
shear_x = shearing_matrix(1, 0)

# Composite transformation: Scaling followed by Rotation
composite_transformation = np.dot(scaling, rotation)

# Apply each transformation
original_coords = np.array([[0, 0], [2, 0], [2, 1], [0, 1]])
transformed_translation = apply_transformation(original_coords, translation)
transformed_scaling = apply_transformation(original_coords, scaling)
transformed_rotation = apply_transformation(original_coords, rotation)
transformed_reflection_x = apply_transformation(original_coords, reflection_x)
transformed_shear_x = apply_transformation(original_coords, shear_x)
transformed_composite = apply_transformation(original_coords, composite_transformation)

# Plot each transformation
plot_transformation(original_coords, transformed_translation, 'Translation (2, 3)')
plot_transformation(original_coords, transformed_scaling, 'Scaling (2x, 3y)')
plot_transformation(original_coords, transformed_rotation, 'Rotation (45°)')
plot_transformation(original_coords, transformed_reflection_x, 'Reflection (x-axis)')
plot_transformation(original_coords, transformed_shear_x, 'Shearing (1x, 0y)')
plot_transformation(original_coords, transformed_composite, 'Composite Transformation: Scaling + Rotation')
```



```
import cv2
import numpy as np
import matplotlib.pyplot as plt

# Function to display images
def display_images(img1, img2):
    plt.figure(figsize=(10, 6))
    plt.subplot(1, 2, 1)
    plt.imshow(img1)
    plt.subplot(1, 2, 2)
    plt.imshow(img2)
    plt.show()

# Load the image
img = cv2.imread('img.jpg')

# Define the transformation matrix
def translation_matrix(tx, ty):
    return np.array([
        [1, 0, tx],
        [0, 1, ty],
        [0, 0, 1]
    ])

# Apply the transformation
def apply_transformation(image, matrix):
    rows, cols = image.shape[:2]
    transformed_image = cv2.warpAffine(image, matrix, (cols, rows))
    return transformed_image

# Translate the image
translated_image = apply_transformation(img, translation_matrix(100, 100))

# Display the original and translated images
display_images(img, translated_image)

# Rotate the image
def rotation_matrix(angle):
    angle = np.radians(angle)
    return np.array([
        [np.cos(angle), -np.sin(angle), 0],
        [np.sin(angle), np.cos(angle), 0],
        [0, 0, 1]
    ])

# Apply the transformation
def apply_transformation(image, matrix):
    rows, cols = image.shape[:2]
    transformed_image = cv2.warpAffine(image, matrix, (cols, rows))
    return transformed_image

# Rotate the image
rotated_image = apply_transformation(img, rotation_matrix(45))

# Display the original and rotated images
display_images(img, rotated_image)
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display_image(reflected_image, axis='x') # Reflect across the x-axis
display_image(reflected_image [0:rows], reflected)

# Image Rotation
def rotate_image(image, angle):
    rows, cols = image.shape[0]
    center = (cols // 2, rows // 2)
    rot_matrix = cv2.getRotationMatrix2D(center, angle, 1.0)
    rotated_image = cv2.warpAffine(image, rot_matrix, (cols, rows))
    return rotated_image

rotated = rotate_image(image, 45) # Rotate 45 degrees
display_image(rotated_image, 45°, rotated)

# Image Scaling
def scale_image(image, fx, fy):
    scaled_image = cv2.resize(image, None, None, fx=fx, fy=fy, interpolation=cv2.INTER_LINEAR)
    return scaled_image

scale = scale_image(image, 1.5, 1.5) # Scale by 1.5x
display_image(scaled_image [0:rows], scaled)

# Image Cropping
def crop_image(image, start_x, start_y, end_x, end_y):
    cropped_image = image[start_x:end_x, start_y:end_y]
    return cropped_image

cropped = crop_image(image, 50, 50, 300, 300) # Crop a region
display_image(cropped_image, cropped)

# Image Shearing in x-axis
def shear_image(image, shear_factor):
    rows, cols = image.shape[0]
    shear_matrix = cv2.getAffineTransform([0, 0], [1, shear_factor], [0, 1], [0, 0])
    sheared_image = cv2.warpAffine(image, shear_matrix, (cols, int(rows * (1 + shear_factor))), None)
    return sheared_image

sheared_x = shear_image(image, 0.5) # Shear by 0.5 along the x-axis
display_image(sheared_image [0:rows], sheared_x)

# Image Shearing in y-axis
def shear_image(image, shear_factor):
    rows, cols = image.shape[0]
    shear_matrix = cv2.getAffineTransform([0, 0], [0, 0], [1, shear_factor], [0, 1], [0, 0])
    sheared_image = cv2.warpAffine(image, shear_matrix, (cols, int(rows * (1 + shear_factor))), None)
    return sheared_image

sheared_y = shear_image(image, 0.5) # Shear by 0.5 along the y-axis
display_image(sheared_image [0:rows], sheared_y)

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Original Image



Translated Image



Reflected Image (X-axis)



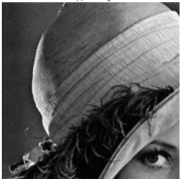
Rotated Image (45°)



Scaled Image (1.5x)



Cropped Image



Sheared Image (X-axis)



Sheared Image (Y-axis)

