

Uniroma1(2018-19) - Social and Behavioural Networks

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Chapter 1

Preamble

Questi appunti utilizzano una notazione personale che sto portando avanti da anni, con l'obiettivo di essere il meno ambiguo possibile. Un caso comune è il seguente: per definire una funzione, utilizzo questa sintassi:

$$f \in A \rightarrow B : a \mapsto f(a) \tag{1.1}$$

dove f è la funzione, $A \rightarrow B$ è il **tipo** di funzione, specificato dal dominio A e dal codominio B , ed è trattato come insieme di tutte le funzioni da A a B , giustificando l'uso dell'operatore di appartenenza. La parte che segue i due punti definisce la funzione attraverso la notazione di mappatura. Ad esempio, l'espressione seguente:

$$d \in \mathbb{N} \rightarrow \mathbb{N} : n \mapsto 2 \cdot n \tag{1.2}$$

si leggerebbe: "d è una funzione che va dai naturali ai naturali tale che ad n associa 2n"

Chapter 2

Introductory pills

2.1 Basic ideas

Note: "pick" and "sample" are used interchangeably.

About $E(X)$: It is called the "expected value" because it means the mid-point where all outcomes, compounded with their weight, contribute to the equilibrium.

Question: Can we still talk about expected value when the outcomes are not numeric? What could be a good bijection between a generic sample space Ω and \mathbb{N} ?

2.1.1 Sampling

Sampling is a simple algorithmic approach used for abstracting and estimating the percentage of elements of a certain type in a large set.

Example: If there is a huge number of black and white marbles in a (very big) bowl and you'd like to know the ratio of black marbles, you can't count all of them, so you extract a sample of marbles many times, until you have sufficient confidence in the obtained result.

2.1.2 Union bound

$$\Pr\left(\bigcup_{i=0}^n E_i\right) \leq \sum_{i=0}^n (\Pr(E_i)) \quad (2.1)$$

If the events are mutually disjoint, then the equality is strict.

2.1.3 Markov inequality

Let X be a non-negative random variable (RV) in a sample space Ω , and a an outcome in Ω , then:

$$\Pr(X \geq a) \leq \frac{E[X]}{a} \quad (2.2)$$

Proof:

$$\begin{aligned} E(X) &= \int_0^\infty x \Pr(X = x) dx \\ &\geq \int_a^\infty x \Pr(X = x) dx \\ &\geq \int_a^\infty a \Pr(X = x) dx \\ &= a \Pr(X \geq a) \end{aligned}$$

2.1.4 Moment generating functions

Moments, in a mathematical-analytical sense, are "quantitative measures" that describe characteristic of a shape. E.g.: a generic function's first moment is its slope (first derivative).

Given a random variable X , then its moment generating function is

$$M_X(t) = e^{tX}, t \in \mathbb{R} \quad (2.3)$$

To be continued...

Reminder! Power series of the e^x function: $e^x = \sum_{i=0}^{\infty} \frac{x^n}{n!}$

2.2 Chernoff bound

The Chernoff bound allows you to control how much a RV is close to its expected value.

Let $X_1, \dots, X_n \in \mathcal{Ber}(p)$ IID, i.e. X_1, \dots, X_n are n RV such that $\Pr(x_i = 1) = p$ and $\Pr(x_i = 0) = 1 - p$.
In other words, they are n independent coin throws of the same coin.

Let $X = \sum_{i=1}^n (X_i)$. X is essentially a binomial RV: $X \in \mathcal{Binom}(2^n, p)$, thus $E(X) = p \cdot n$.

It represents the number of times you get head with the aforesaid n throws.

So, given an error limit ε , we define the Chernoff bound as:

$$\Pr(|X - E[X]| \geq t) \leq e^{-2t^2/n} \quad (2.4)$$

where $t := \varepsilon n$.

In the binomial case, [2.4] translates to:

$$\Pr\left(\left|\sum_{i=1}^n (X_i) - p \cdot n\right| > t\right) = \Pr\left(\left|\frac{1}{n} \sum_{i=1}^n (X_i) - p\right| > \frac{t}{n}\right)$$

Then, replacing t with εn , we get

$$\Pr\left(\left|\frac{1}{n} \sum_{i=1}^n (X_i) - p\right| > \varepsilon\right) \leq 2e^{-2n^3\varepsilon^2} \quad (2.5)$$

Example: If you want to know how many Facebook users have more than 100 friends, you can't simply count, but you can obtain a good approximation sampling a reasonable number of profiles.

It's important to observe that the size of the sample we need in order to obtain a good approximation depends on the error we tolerate, not on the total population.

There are many possible formulations of the Chernoff bound, another one that can be useful is the following:

$$\Pr(|X - E[X]| \geq \varepsilon \cdot n) \leq 2e^{-\frac{\varepsilon^2}{3}n} \quad (2.6)$$

Example: Let be $E[X] = \frac{50}{100}$ and $\varepsilon = \frac{1}{100}$, the probability that $X \geq \frac{51}{100}$ or $X \leq \frac{49}{100}$ is less then or equal to $2e^{-\frac{1}{30000}n}$.

Chapter 3

Locality Sensitive Hashing

The goal of hashing techniques is to reduce a big "object" to a small "signature" or "fingerprint". In general, what happens in locality sensitive hashing (or LSH) is to have some notion of similarity, and then define a "scheme" which computes it. The process of creating a scheme usually involves some sort of preprocessing step, and a function family which, by choosing one or another function according to a probability distribution, statistically classifies the objects in the same way as the similarity function does. The bottom line of LSH schemes is: similar objects hash to similar values.

Here are some common similarities:

- **Jaccard similarity:** Given two sets of objects A and B, their Jaccard similarity is defined as follows:

$$\mathcal{Jacc}(A, B) = \frac{|A \cap B|}{|A \cup B|} \quad (3.1)$$

- **Hamming similarity:** Given two sets of objects A and B taken from a universal set U, their Hamming similarity is defined as follows:

$$\mathcal{Hamm}(A, B) = \frac{|A \cap B| + |\mathbb{C}_U(A \cup B)|}{|U|} \quad (3.2)$$

3.1 A case study: Web-page indexing

A search engine crawls periodically the Internet and stores valuable information in its own index for search optimization purposes.

An observation to make is the following: some kinds of documents, that are very similar to each other, are stored sparsely through the net; to save storage space, only one of a kind of document's info is stored in the index, whereas all others are linked to the first one, because of their similarity.

To find a useful hashing scheme, A. Broder came up with an idea. First off, let us fix some definitions:

- U : the set of all words, i.e. the English vocabulary
- U^* : the set of all strings composed of english words

The starting point is to treat web pages as strings:

T_1 : “*The black board is black*”

T_2 : “*The white board is white*”

Then, let $\text{distinct}(T)$ returns the set of distinct words appearing in a string (Ref. Bag of Words model)

So for example, by using the Jaccard similarity:

$$\mathcal{Jacc}(\text{distinct}(T_1), \text{distinct}(T_2)) = \frac{3}{5} \quad (3.3)$$

Over a half: they look close. If we used the Hamming distance instead, we would (almost always) get a number very close to 1, because we're using a minuscule part of the universe set (in our case, the English dictionary), thus (almost) all words are absent from the sets.

Now, our objective is to construct a scheme over web-pages that implement the Jaccard similarity. Our pre-processing step: Choose a permutation (or total ordering) $p \in \mathcal{Perm}(A \cup B)$ UAR. To construct said order is a simple task:

Algorithm (using u):

```

pi: empty sequence
while u is not empty:
    pick a word w from u UAR and remove it from u
    append w to pi
end
return pi

```

Proof of uniform choice: $\Pr(X = \pi) = \frac{1}{|u|} \cdot \frac{1}{|u| - 1} \cdot \dots \cdot 1 = \frac{1}{|u|!} \Rightarrow X \in \mathcal{Unif}(\mathcal{Perm}(A \cup B))$

From p , we define the hashing function as:

$$h_p \in \mathcal{P}(U) \rightarrow U : h_p(A) = \min_p(A) \quad (3.4)$$

In other words, we take the “minimum” in A according to the ordering specified by p . A simple but useful observation would be:

$$\forall A \subseteq U \Rightarrow h_p(A) \in A \quad (3.5)$$

E.g.: $p = (\text{black}, \text{the}, \text{is}, \text{white}, \text{board}) \wedge A = \{\text{black}, \text{board}\} \Rightarrow h_p(A) = \text{black}$

Thus, we can say that A is similar to B iff $h_p(A) = h_p(B)$. Recall that A and B are fixed, p is the focus of this definition. What can be said about $\Pr(h_p(A) = h_p(B))$? Looking at a corresponding Venn diagram:

- $A \cap B = \emptyset \Rightarrow \Pr(h_p(A) = h_p(B)) = 0$; they have no words in common, so their hashes must be different, independently of the chosen order;
- $A = B \Rightarrow \Pr(h_p(A) = h_p(B)) = 1$; this time, all words are in common, so their hashes must coincide, again, independently of the chosen order
- Otherwise, since p is chosen UAR, the probability that the hashes are equal has the same meaning of the probability of finding the lowest element of A and B in the intersection with respect of the union (and not in U as a whole, as our previous observation suggests) which is the Jaccard similarity of A and B by its very definition: $\Pr(h_p(A) = h_p(B)) = \mathcal{Jacc}(A, B)$

Possible question about third point: Why not respect to the universal set? because A and B will have hashes which, as we observed earlier, do not live outside the union: the union between A and B is our true set of outcomes when hashing either A or B .

Now, if h_p is evaluated only once over a given permutation, only a binary response can be obtained. In order to obtain the probability value without resorting to compute unions and intersections, we can repeat evaluation over different permutations; this can be regulated by the Chernoff-Hoeffding bound:

Let $A, B \subseteq U$, and $X_{1...n} \in \mathcal{Ber}(p)$ IID, each defined over a distinct element of $\Pi \subseteq \mathcal{Perm}(U)$ such that $X_i \mapsto 1 \Leftrightarrow A \sim_{\pi_i} B, 0 \text{ otherwise}$, then:

$$\Pr \left(\left| \text{avg}_{i=1}^n(X_i) - \frac{\sum E(X)}{n} \right| < \varepsilon \right) = \quad (3.6)$$

3.2 LSH formalization

First let us focus around the hash function as an object: its true purpose in a scheme is to classify objects based on how much they “look like”, whatever this means in the chosen similarity’s terms. Therefore, in our theoretical analysis, the codomain of a hash function is not that important; what is important is how the function partitions its own domain, U . In a sense, we’re interested only in the partitions of U themselves, not in the functions that generate them.

Why have we dealt with functions back then? Moving from a purely mathematical perspective to a more computational one, what is usually done for measuring similarities is sampling some object’s characteristics, and observe how “distant”, or else “similar” they are. This is done by means of some program; and programs are (oh so) easily associated with functions. The computational approach gives a more intuitive vision of the problem we’re confronting ourselves with.

Still, what could happen, is to have a couple of functions that map values into wildly different codomains, but partition U in exactly the same way! And in our journey, we’re just interested in classifying objects; so these kind of “duplicate” functions are, well, useless (unless we delve in complexity studies, but that’s out of the scope).

So, let us reform the foundations by taking as our core object a universe partition, instead of a universe-domained hash function. First, though, we need to formalize what a similarity is, and to get to a good definition, we have to carefully select them from their space $U^2 \rightarrow [0, 1]$. It should be noted that the codomain might very well be \mathbb{R} itself, but to get some bearings we’ll treat an image of 1 as a complete equivalence between two objects, and 0 for complete difference, with the interval expressing the degree of similarity.

Let U be a set, and $S \in U^2 \rightarrow [0, 1]$ a symmetric function; then S is called a similarity over U .

Tidbit: Let $f \in A^n \rightarrow B$, then f is **symmetric** iff *argument order does not change the image*

A LSH scheme over U is a probability distribution over U ’s partitions

Formal definition: Given $s \in U^2 \rightarrow [0, 1]$ a similarity. Then we define X to be a LSH scheme for s as the following:

$$X \in \text{Rand}(\mathcal{P}(U)) : \forall A, B \in U \implies \mathcal{E}(A \sim_X B) = S(A, B) \quad (3.7)$$

Challenge: Can we find a LSH scheme for an arbitrary S function? NO

E.g. $U = \{a, b, c\}$ $S \in U^2 \rightarrow [0, 1] : S(a, b) \mapsto 1, S(b, c) \mapsto 1, S(a, c) \mapsto 0$

Translating into probabilities and using equality's transitivity, we obtain:
 $\Pr(h(a), h(c)) = 1$, which contradicts the third mapping.

Chapter 4

Next

More distances:

Dice similarity

$$D(A, B) = \frac{|A \cap B|}{|A \cap B| + \frac{1}{2}|A \Delta B|} \quad (4.1)$$

Anderberg similarity

$$D(A, B) = \frac{|A \cap B|}{|A \cap B| + 2|A \Delta B|} \quad (4.2)$$

Generalizing Jaccard, Dice and Anderberg:

$$S_\gamma(A, B) = \frac{|A \cap B|}{|A \cap B| + \gamma|A \Delta B|} \quad (4.3)$$

Important lemma (Charikar): if a similarity S admits a (LSH) scheme, then $1 - (S)$ must satisfy the triangular inequality (trineq)

Proof:

Afterthought: Similarities are actually defined in most cases as the inverses of measures, which in turn give (oh so surprisingly!) a notion of distance

By Charikar's lemma, we can prove that Dice's similarity cannot admit a LSH scheme

Proof by counterexample: Assume $A = \{1\}, B = \{2\}, C = \{1, 2\}$, then use the trineq over the distances;

Parameterizing this counterexample with S_γ , we obtain a bounds for gamma:
 $1 \leq \frac{2\gamma}{1+\gamma} \Rightarrow \gamma \geq 1$

4.0.1 Probability generating functions

Intuition: A probability generating function (PGF) is a **power series representation** of a given probability distribution

Definition: Given a (discrete) RV X , its PGF is the function:

$$\mathcal{Gen}_X(\alpha) = \sum_{x=0}^{|\Omega|} \Pr(X=x) \alpha^x$$
 (note that all outcomes appear by their probability)

How to get back to pmf: $\Pr(X=x) = \frac{\mathcal{D}^x(\mathcal{Gen}_X(0))}{x!}$

Theorem: If a similarity S admits a LSH and a given function f is a PGF, then $f(S)$ admits a LSH

Afterthought: Are we "applying" a probability distribution over a similarity (which in turn, since it is lshable, means it has a probdist over a subset of hashfunctions)?

Proof: see below

Consequence: Applying the theorem to the Jaccard similarity:

Start with $f_\gamma(\alpha) = \sum_{x=1}^{\infty} \frac{(1 - \frac{1}{\gamma})^x}{\gamma - 1} \alpha^x$

We have to demonstrate that the coefficients represent a probability distribution: $\sum_{i=1}^{\infty} \frac{(1 - \frac{1}{\gamma})^i}{\gamma - 1} = 1 \Rightarrow \sum_{i=1}^{\infty} (1 - \frac{1}{\gamma})^i = \gamma - 1$

Now: $\sum_{i=1}^{\infty} (1 - \frac{1}{\gamma})^i = (1 - \frac{1}{\gamma}) \sum_{i=0}^{\infty} (1 - \frac{1}{\gamma})^i = (1 - \frac{1}{\gamma}) \frac{1}{1 - (1 - \frac{1}{\gamma})} = \frac{\gamma - 1}{\gamma} \frac{1}{1/\gamma} =$

$\gamma - 1$

Apply PGF to Jaccard: $f_\gamma(J(A, B)) = \dots$ algebristica... $= \frac{\cap}{\cap + \gamma \Delta} = S_\gamma(A, B)$, which in turn is LSH-able

4.1 181008

Recap: Given a universe U , a function $S \in U^2 \rightarrow [0, 1]$ is said to be a LSH-able similarity iff exists prob distr over (a family/subset of) the hash functions in U , such that:

$$\forall X, Y \in U \quad \Pr_h(h(X) = h(Y)) = S(X, Y) \quad (4.4)$$

Reprise: If a similarity S is LSHable and f is a PGF, then $f(S)$ is LSHable

Equivalent statement:

$$f(S) := T \in U^2 \rightarrow [0, 1] : \forall A, B \in U \quad T(A, B) = f(S(A, B)) \quad (4.5)$$

Lemma (1): The similarity $O \in U^2 \rightarrow [0, 1] : (A, B) \mapsto 1$ admits a LSH
Proof: Give prob. 1 to a constant function (duh!): $h \in U \rightarrow 1A \mapsto 0 \forall A \in U$

Purpose: This will be the base case for theorem proof...

Lemma(2): If S and T similarities over U have a scheme, then $S \cdot T : (S \cdot T)(A, B) = S(A, B) \cdot T(A, B)$ has a scheme

(I.E.): LSHability is preserved upon composition/multiplication

Proof by construction (Algorithm):

sample hash functions for $S \cdot T$ as follows

first, sample h_S for S ; then sample h_T independently for T return the function $h : A \mapsto (h_S(A), h_T(A))$

$\Pr_h(h(A) = h(B)) = \Pr_{h_S}(h_S(A) = h_S(B)) \cdot \Pr_{h_T}(h_T(A) = h_T(B)) = S(A, B) \cdot T(A, B) (\forall \{A, B\} \in \mathcal{P}_2(U))$ by independency

Lemma(3): if S is LSHable then $\forall i \in \mathbb{N}$ S^i is lshable

proof by induction:

base (Lemma1): $i=0$ and $S^0=O$ OK

ind: Use lemma 2 on S^i and S to obtain S^{i+1} ; S has a scheme by def, S^i has a scheme by induction hypothesis

lemma(4): if $p_0, \dots, p_i, \dots : \sum_{i=0}^{\infty} p_i = 1, \text{ and } p_i \geq 0 \forall i$, and S_0, \dots, S_i, \dots are

lshable similarities, then $\sum_{i=0}^{\infty} p_i S_i$ is lshable

scheme: first pick(sample, they are synonyms) i^* at random from \mathbb{N} with probability p_0, \dots, p_i, \dots then, sample h from the hash functions of S_{i^*}

$$\Pr(h(A) = h(B)) = \sum_{i=0}^{\infty} (p_i S_i(A, B))$$

$$\Pr(h(A) = h(B)) = \sum_{i=0}^{\infty} (\Pr(i = i^*) \Pr_h(h(A) = h(B) | i = i^*)), \Pr(i = i^*) = p_i, \text{ hash } h | i = i^* \rightarrow S_i(A, B)$$

Final proof: sum of $p_i S^i$ has a scheme

L3: S^i has a scheme

L4: the sum is lshable, proven

Example of a pgf: $\text{sum}(2^{-1} \text{ times } x^i)$

-----??sorensen dice??cosine similarity?? inner product??johnson-lindenstrauss??

a sketch is n instance of a pgf which can be used to implement other similarities NONONONONOO

PGF is an approach for making schemes for similarities from other schemes

4.2 181010

Let f a PGF, $\alpha \in [0, 1]$, ...?

$$\alpha f = \alpha f(S) \mid (1 - \alpha)T$$

$$T \in U^2 \rightarrow [0, 1] : \forall t, t' \in \mathcal{P}_2(U) T(t, t') = 0$$

for the 1 case we wanted a nbanal partition, now with 0 we want a punctual partition, so we need a hash function that assigns a distinct value to each argument. (You can actually use the identity)

Not a good scheme, because we're not shrinking data

GOTO

Approximation examples

Consider S_γ : $\gamma \geq 1 \Leftrightarrow S_\gamma$ is LSH-able

Focus on $\gamma < 1$

Definition: "Distortion of a similarity"

Let S be a similarity, then its distortion is "the minimum*(meaning inferior extremum) delta geq 1 : exists LSHABLE S' (forall A, B in P2U, $1/\delta \cdot S(A, B) \leq S'(A, B) \leq S(A, B)$)"

delta tends to 1 -> S is lshable

using jaccard to approximate sgamma we wold obtain 1/gamma

delta is the approximation factor

Centerlemma: Let S be a LSHable similarity : $\exists \chi \subseteq U : \forall \{x, x'\} \in \mathcal{P}_2(\chi) S(x, x') = 0$, then

$$\forall y \in U \text{avg}_{x \in \chi} (S(X, Y) \leq \frac{1}{|\chi|}); \text{ (it trivially follows that } \exists x^* \in \chi : S(x^*, Y) \leq \frac{1}{|\chi|} \text{))}$$

Proof: (Fix $y \in U$) If the hash function h has positive probability in the (chosen) lsh for S, then $\forall x, x' \in \mathcal{P}_2(\chi) (h(x) \neq h(x'))$

[χ is actually a (possibly incomplete) section of the partition of U induced by h]

thus, forall hash functions with positive probability, there can exist at most one x in calx st hx=hy (transitivity of equality)

$$\sum_{x \in \chi} S(x, y) = \sum_{x \in \chi} \Pr_h(h(x) = h(y)) = \sum_{x \in \chi} \sum_h \Pr(h \text{ is chosen})[h(x) = h(y)]$$

IMPORTANT: The brackets here are a boolean evaluation operator

$$= \sum prhischosen \sum evalhx = hy \leq \sum_h \Pr(h \text{ is chosen}) \leq 1$$

$$\text{Thus, } \sum_{x \in \chi} S(x, y) \leq 1 \Rightarrow avg(S(X, Y)) \leq \frac{1}{|\chi|}, \text{ proven}$$

$$S := S_\gamma, 0 < \gamma < 1, U = 2^{[n]} = S|S \subseteq [n]$$

$$\chi := \mathcal{P}_1([n]) \quad y = [n]$$

- let us assume that T finitely distorts sgamma, and T is lshable then $T(,) = 0$ for all i, j in $P_2(\text{mathbbm}(n))$

$$- \exists \{i\} in \chi : T(\{i\}, [n]) \leq \frac{1}{|\chi|} = \frac{1}{n}$$

$$S_\gamma(\{i\}, [n]) = \frac{1}{1 + \gamma(n-1)} = \frac{1}{\gamma n + (1-\gamma)}$$

... zenterlemma application ...

$$U =$$

Chapter 5

181015

First lesson reprise - Flow of memes

spread of memes/viruses from a website to another

so, we get traces

goal is to reconstruct graph from traces

Trace spreading model (from virology)

source chosen UARand edge traversal time chosen by (usually) $\text{Exp}(\lambda)$
trace starts from source

obs. the first two nodes of a trace are connected

pr a source is chosen: $1/n$ pr the edge's other endpoint: $1/\deg(\text{source})$ because of how traces work

n numero di tracce: $pr = (1 - 1/delta n)^{(3 delta n \log n)} = e^{(-3 lnn)simeq 1/n^3}$

5.0.1 another information spreading process

NPR chain letter

important observations: first name is fake, the others are plausibly real

asks to add own's name, and then forward to all friends

someone breaks the rules, and decides to publish their copy of the mail

those published mails reveal a subtree of the whole chainletter tree

revealed tree MUCH smaller, and extended in-depth

Let T be a tree, each node has a chance of being "exposed" by a probability p , and if so, reveals all ancestors

estimate the size of the tree

ALGO throw a coin on all the nodes of the chain tree, don't throw if node is parent of a revealed node (no need) := special nodes

special nodes are all iid from exposed ones; $\delta = n \text{ of special nodes} / \text{special nodes}$; revealed nodes = $\delta \cdot n$ (it's the expected value!!) -> from there estimate n

δ is the actual exposure probability

the two estimates can go wrong...

examples in nature suggest some bounds

Theorem: the algorithm correctly estimates n if $n > \omega(\max(1/\delta^2, k/\delta))$

IMPORTANT: Estimates can be redone, but reconstructing another revealed tree is impractical, so we're estimating a characteristic of a tree by observing a sample revealed one and making estimates

Single-child fraction

Fix a bound: a node's maximum degree must be lesser than k

partition unknown tree into subforests, each subforest has $1/\delta$ nodes and median height $\omega(\log(k-1)^{\delta-1})$

by exposing a node in a subforest's lower half, we're exposing a number of nodes equal to the sf's median height

Insight: δ is unknown too

Recap of revealed subtrees

Exposure prob: $\delta > 0$

$$E(\#exposednodes) = \delta n$$

Let $x \in RV$ be the set of nodes of the revealed tree. Let $Y \in \text{Coin}(p)$, where

$Y_v = 1$ if v is exposed, 0 otherwise.

$$E(Y_v) = \delta$$

$$\text{Let } Y = \sum_{v \in X} Y_v \Rightarrow E(Y) = \delta|X|$$

$$\text{OUTPUT: } \hat{\delta} = \frac{Y}{|X|}$$

Chernoff bound is applicable, the Y s are IID

Note: we can do the first substitution because of linearity (?)

$$\begin{aligned} \text{"Multiplicative approximation": } \Pr(|\hat{\delta} - \delta| \geq \varepsilon\delta) &= \Pr\left(\left|\frac{Y}{|X|} - \delta\right| \geq \varepsilon\delta\right) = \\ \Pr(|Y - \delta|X|| \geq \varepsilon\delta|X|) &= \Pr(|Y - E(Y)| \geq \varepsilon E(Y)) \leq 2e^{-\frac{\varepsilon^2}{3} E(Y)}, \forall \varepsilon \in (0, 1) \end{aligned}$$

This is the Multiplicative Chernoff Bound: Let $y_1 \dots y_n$ IID Coins, then (see above, last inequality)

we need $E(y)$ to be large in order to obtain a useful bound, for E close to 1, the bound itself goes over 1, becoming useless

$$2e^{-\frac{\varepsilon^2}{3} E(Y)} = 2e^{-\frac{\varepsilon^2}{3} \delta|X|}$$

$$\text{If } |X| \geq \frac{3}{\varepsilon^2 \delta} \ln 2/\eta, \text{ then } 2e^{-\frac{\varepsilon^2}{3} \delta|X|} \leq 2e^{-\ln 2/\eta} = 2\eta/2 = \eta$$

$$Y' = \sum_{v \in T} Y_v \Rightarrow E(Y') = \delta n$$

$$\Pr(\text{Chernoff on } Y') \leq 2e^{-\frac{\varepsilon^2}{3} \delta n}$$

Using the bound over $|X|$, then $\leq \eta$

$$\text{Final output: } \frac{Y'}{\Delta} (\leq \frac{(1+\varepsilon)\delta n}{(1-\varepsilon)\delta} = (1+O(\varepsilon))n)$$

Lower bound inverts the sign of bigOepsilon

$$\text{Insight: } \frac{Y'}{\Delta} = \frac{Y'}{Y}|X|$$

"An additive approximation is useless"

goodness of algorithm:

- nodes of unknown tree less than delta: revealed tree = 0 almost surely -

tree is a star -i almost surely get a bad approximation

what characteristics should the unknown tree have?

Claim: If the number of internal nodes of the revealed tree is at least $3/(\epsilon \sqrt{\delta} \ln(2/\epsilon))$ then our guess \hat{n} is going to satisfy $(1-\epsilon)n \leq \hat{n} \leq (1+\epsilon)n$ with probability at least $1-2\epsilon$

the three greek letters can change the goodness of our result

Next goal: find the probability that a node of the unknown tree will be an internal node of the revealed tree

Assumption: The unknown tree is such that none of its nodes has more than K children.

Let v be a node of the unknown tree with K children, then $\Pr(\text{at least 1 child in } K \text{ is exposed}) \geq 1 - \epsilon^{-1} \min(1, \delta K_v)$

K_v : expected number of children revealed

Let $Z_v \in \text{Coin}(p)$ where it is 1 if at least one child of v is exposed

$$E(Z_v) = 1 - (1 - \delta)^{K_v} = 1 - ((1 - \delta)^{1/\delta})^\delta K_v$$

$$\lim_{\epsilon \rightarrow 0^+} (1 - \epsilon)^{1/\epsilon} = 1/e$$

$$1 - ((1 - \delta)^{1/\delta})^\delta K_v \geq 1 - e^{-\delta K_v}$$

- if $\delta K_v \geq 1$ then $E(Z_v) \geq 1 - 1/e$
- else , geometric intuition... ?????????? ... $E(Z_v) \geq 1 - e^{-\delta K_v} \geq \delta K_v (1 - 1/e)$

Lemma is proven

Former insight: for revelation we care about children, not all of the descendants

By summing all children of all nodes, we get all the edges -i $n-1$

Lemma: Let Z be the set of nodes of which at least 1 child is exposed; then $\Pr(|Z| \geq 1/2(1 - 1/e) \min(K^{-1}, \delta)(n - 1)) \geq 1 - e^{-\Theta(n \min(1/K, \delta))}$

Proof: Let I be the set of internal nodes of T ; Let D subset I contain nodes with at least $1/\delta$ children; $E(|Z|) = \sum_{v \in I} E(Z_v) \geq (1 - 1/e) \min(1, K_v \delta) =$

$$(\dots)(|D| + \delta \sum_{v \in I-D} K_v)$$

obs1: $\sum_{v \in I} K_v = n-1$

$$\text{obs2: } |D| \geq \frac{\sum_{v \in D} K_v}{|K|}$$

$$\begin{aligned} \text{then : } (1 - 1/e)(|D| + \delta \sum_{v \in I-D} K_v) &\geq (1 - 1/e)(\sum_{v \in D} K_v/K + \delta \sum_{v \in I-D} K_v) \geq \\ (\dots) \min(1/K, \delta) \sum &= (\dots) \min(\dots)(n-1) \end{aligned}$$

Proven

see emergency notes!!

5.1 181022

-combinatoric optimization-

graph independent set - impractical example

An implicit opt problem.

unknown - partly known function, exp in the codomain

ex: describe SAT by means of truth tables - rows are exponential in variable number

"Modular set functions"

given $X = [n] f \in 2^X \rightarrow \mathbb{R}$

$$n = 3, w_1 = 1, w_2 = 5, w_3 = 1, f(S) = \sum_{i \in S}$$

max set: all domain

max set w neg values: exclude neg values

se ho un oracolo che mi calcola $f(s)$, ed io non conosco f , posso interrogare

l'oracolo sui singoletti, e poi applico le logiche precedenti

(Matroid) Ex tutte parti con al più k elementi (a partire da U)

"Ad placement" arriva un utente sul sito tipo Google, scegli quali ad mostrare in modo da guadagnare il più possibile

modello Independent Cascade Model ogni ad rappresentata da una coppia $AD_i = (v_i, p_i)$ accordo tra pubblicità e Google, $v_i \in \$$, p_i probabilità di click

$$Ad_{samsung} : (1\$, 0.1) \Rightarrow E[X_i] = 1 \cdot 0.1$$

Strategy: put highest expectation ads on top

third value, satisfaction factor (or the will to look other ads)

how to optimize f in order to maximize it

caso particolare "submodular set function" - analogo discreto delle funzioni convesse - can be misleading

given X, f is submodular iff $\forall S, T \in X, f(S) + f(T) \geq f(S \cap T) + f(S \cup T)$

modular is submodular: $\forall S, T \in X, f(S) + f(T) = f(S \cap T) + f(S \cup T)$

quanti bit servono per rappresentare tale funzione?

LAPSE

COVERAGE (function, submodular): $X = \{S_1, S_2 \dots S_m\}, S_i \subseteq [n]$

$$Y \subseteq X : c(Y) = \left| \bigcup_{S_i \in Y} S_i \right|$$

$$s(Y) = \sum_{S_i \in Y} |S_i|$$

proof that f (or c?) is submodular base case n=1: couple S T can assume 4 combinations: $cases, t = \{1\} \Rightarrow \text{union and intersection } f(\cdot) = 1 \text{ in } T, 1 \text{ not in } S \text{ then } 1 \text{ in union, } 1 \text{ not in intersection and } \emptyset$

induction: split a coverage function into two coverage functions: $c(Y) = \left| \bigcup_{S_i \in Y} S_i \right| = \left| \left(\bigcup_{S_i \in Y} S_i \right) - \{n+1\} \right| + \left| \left(\bigcup_{S_i \in Y} S_i \right) \cap \{n+1\} \right|$

Nemauser-W

If f is submodular nonnegative and monotone, it can be approx to $\max_{|S|} f(S) =$

$K\}(f(S))$ to a factor of $1 - \frac{1}{e}$

represent modulars as points of convex multidimensional functions

"maxcover" data una classe di sottoinsiemi di X , $S-1$, si trovino k insiemi in X tail che , insieme, coprono il massimo numero di elementi

Before proving, ALGORITHM (greedy), parameterized by f , X and k : trovare k sottoinsiemi di X che massimizzano f

$S_0 < -\emptyset$ for $i = 1 \rightarrow k$ let $x_i = \text{maximizer of } f(\{x_i\} \cup S_{i-1})$ $S_i < -\{x_i\} \cup S_{i-1}$ return S_k

again before proving, observation: diminishing returns (formalization)

$$\delta(x|S) = f(\{x\} \cup S) - f(S)$$

let f be submodular, $B \subseteq A, x \notin B \Rightarrow \Delta(x|A) \geq \Delta(x|B)$

submodular functions exhibit diminishing returns property

Now: $S = A \cup \{x\}, T = B \Rightarrow f(A \cup \{x\}) + f(B) \geq f(A) + f(B \cup \{x\}) \Rightarrow f(A \cup \{x\}) - f(A) \geq f(B \cup \{x\}) - f(B) \Rightarrow \Delta(x|A) \geq \Delta(x|B)$

proof of approximation:

take an optimal solution $S^* = \{x_1^*, \dots, x_k^*\}$

$$\forall i, f(S^*) \leq f(S^* \cup S_i)$$

$$= \dots f(S_i) + \sum_{j=1}^k \Delta(x_j^* | S_i \cup \{x_1^*, \dots, x_{j-1}^*\}) \leq (\text{by diminishing returns}) f(S_i) +$$

$$\sum_{j=1}^k \Delta(x_j^* | S_i) \leq (\text{by greediness}) f(S_i) + \sum_{j=1}^k \Delta(x_{i+1} | S_i) = f(S_i) + k(f(S_i \cup \{x_{i+1}\}) - f(S_i)) = kf(S_{i+1}) - (k-1)f(S_i)$$

$$\text{So: } f(S^*) - f(S_i) \leq k(f(S_{i+1}) - f(S_i))$$

$$\text{Def: } \delta_i = f(S^*) - f(S_i)$$

$$\text{Then: } \delta_i \leq k(\delta_i - \delta_{i+1} + 1) \Rightarrow k\delta_{i+1} \leq (k-1)\delta_i \Rightarrow \delta_{i+1} \leq (1 - \frac{1}{k})\delta_i$$

$$\delta_0 = f(S^*) - f(S_0) \leq f(S^*)$$

...

going to definition of e by its limit form $(1 - 1/k)^k$

5.2 181024

recap of yesterday:

given a ground set, and $f \in 2^X \rightarrow \mathbb{R}$, then f is modular iff $\forall S, T \subseteq X (f(S) + f(T) \geq f(s \cup t) + f(s \cap t))$

E.g.: coverage functions, X is a set system $c(X) = \left| \bigcup_{S \in X} S \right|$

”given a subset of sets, the coverage value would be the cardinality of the union”

claim: coverage function is submodular proof: $c(S) + c(T) \geq c(s \cup t) + c(s \cap t)$

proven case-by-case in the scope of where the elements are inside the subsets

if $f_1, \dots, f_k \in 2^X \rightarrow \mathbb{R}$ are submodular, $\alpha_1, \dots, \alpha_k \geq 0 \Rightarrow \sum_{i=1}^k \alpha_i f_i$ is submodular

proof: the i-th case is easily proven, then sum up; nonnegativity is essential here

algorithm for optimization (?): $GREEDY_f(X, K)$: $S_0 = \emptyset$ for $i = 1 \rightarrow K$ let $x_i = \text{maximize } f(\{x_i\} \cup S_{i-1})$ $S_i = S_{i-1} \cup \{x_i\}$ return S_K

if f is submodular, nonnegative and monotone, then $f(S_K) \geq (1 - 1/e) \max_{S \in \binom{X}{K}} f(S)$

another algorithm: $GREEDY_{\epsilon, f}(X, K)$: $S_0 = \emptyset$ for $i = 1 \rightarrow K$ let x_i be : $f(S_{i-1} \cup \{x_i\}) - f(S_{i-1}) \geq (1 - \epsilon) \max_{x \in X} (f(S_{i-1} \cup \{x\}) - f(S_{i-1}))$ $S_i = S_{i-1} \cup \{x_i\}$ return S_K

the difference is: we don't need to find the exact maximizer, but something (1-epsilon) close to it; and it may be MUCH easier to find such something instead of the actual maximizer.

the core of the discussion is approximating a (usually impracticable to compute) function to a (polynomial) one

Tidbit: proving correctness of this algorithm proves the previous one

Trail: KKT model

Hint(!): We don't need to find the maximum in this algorithm (otherwise, we are actually in the former case, why not use it directly?)

Theorem: ($\forall \varepsilon \in [0, 1)$), if f is submodular, nonnegative and monotone, then $f(S_k) \geq (1 - \varepsilon)(1 - 1/e) \max_{S \in \binom{X}{K}} f(S)$

Proof: $S^* = \operatorname{argmax} f(S), S \in \binom{X}{K}$

$\forall i \in \mathbb{k}$

$$f(S^*) \leq f(S_i) + \sum_{j=1}^k (f(S_i \cup \{x_1^*, \dots, x_j^*\}) - f(S_i \cup \{x_1^*, \dots, x_{j-1}^*\}))$$

[defining diminishing returns (or marginal increase of 1 having 2)]

$$\rightarrow = f(S_i) + \sum_{j=1}^k \Delta(x_j^* | S_i \cup \{x_1^*, \dots, x_{j-1}^*\})$$

$$\text{Because of submodularity, } \rightarrow \leq \sum_{j=1}^k \Delta(x_j^* | S_i)$$

-brainlapse-

$$\dots \text{at the end of the day } f(S^*) - f(S_i) \leq \frac{k}{1 - \varepsilon} \Delta(x_{i+1} | S_i)$$

$$\text{def } \delta_i = f(S^*) - f(S_i)$$

$$\delta_{i+1} \leq \delta_i \left(1 - \frac{1 - \varepsilon}{k}\right)$$

-SIGSEGV-

see previous day to get all deltas from 0 to k

$$\text{then } f(S_k) \geq \left(1 - \left(1 - \frac{1 - \varepsilon}{k}\right)^k\right) f(S^*) = \left(1 - \left(1 - \frac{1 - \varepsilon}{k}\right)^{\frac{k}{1 - \varepsilon}}\right)^{1 - \varepsilon} f(S^*) \geq$$

$$(1 - (1/e)^{1-\varepsilon})f(S^*)$$

more algebratta, use exponential convexity, get $f(S_k) \geq (1 - e^{\varepsilon-1})f(S^*)$,
over and out

Application: Kempe-Kleinberg-Tardos

Chapter 6

181105

Recall: densest subgraph (with maximum mean degree)

Technique: linear programming

Linear program: Primal

- Objective:

#Continued onto notes...