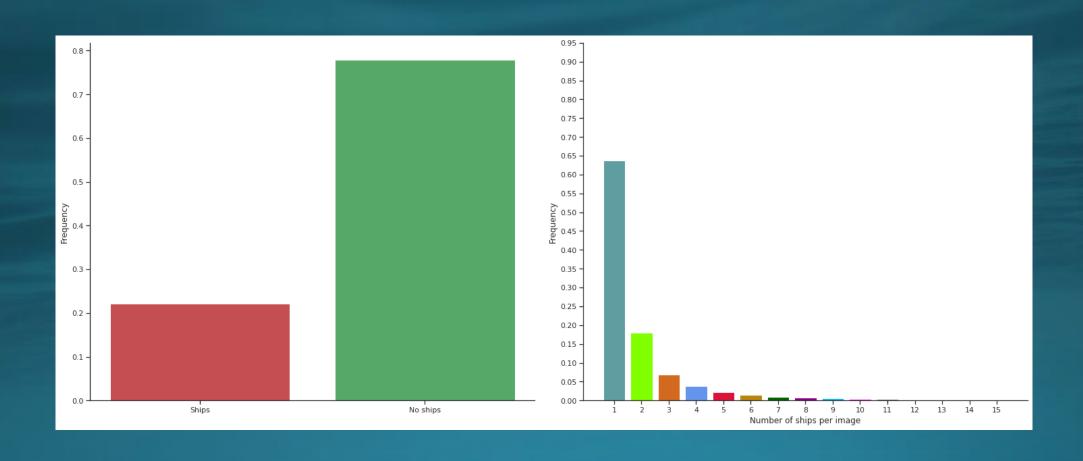
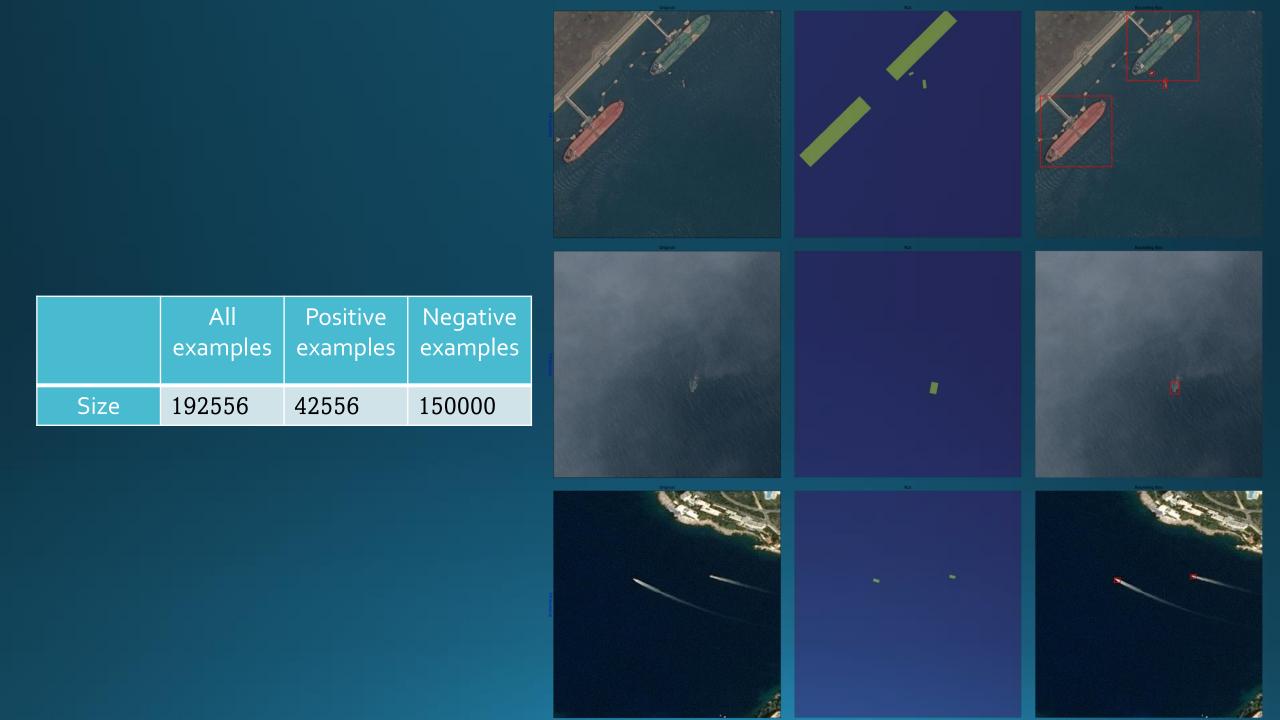


Airbus Ship Detection Challenge

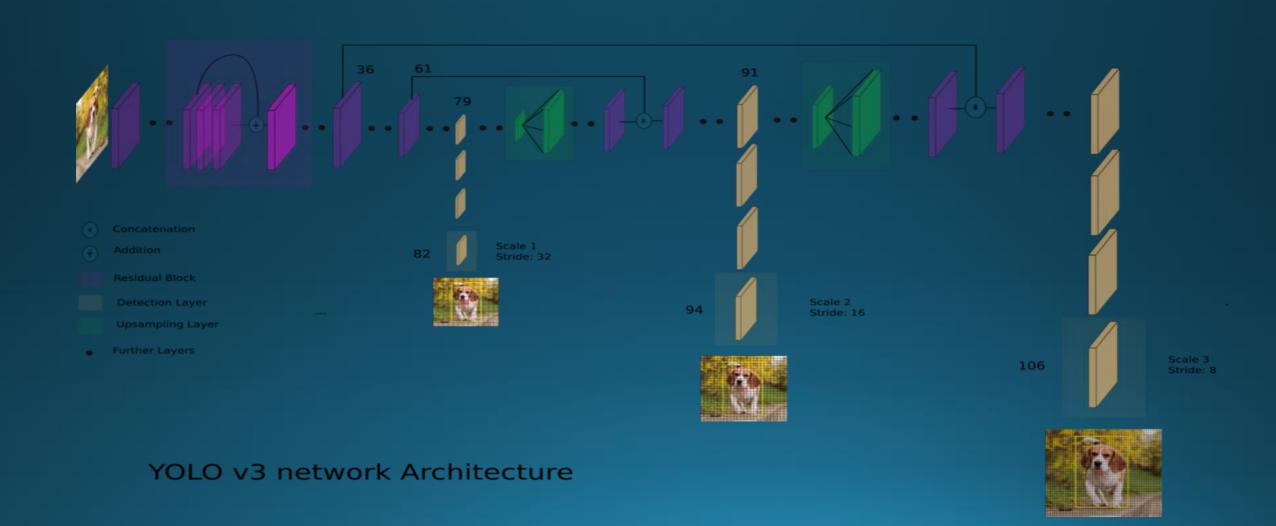
Giosuè Zannini matr. 873810 Academic year 2021/2022

Summary of DataSet



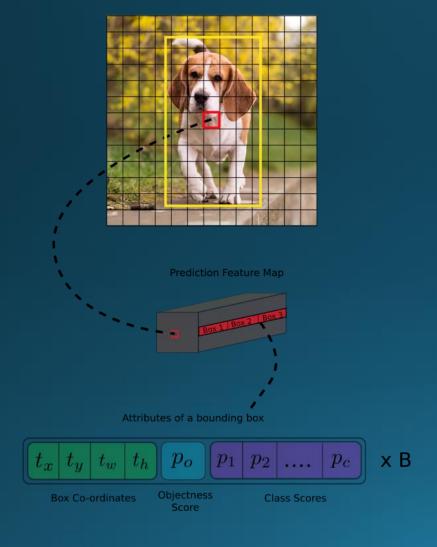


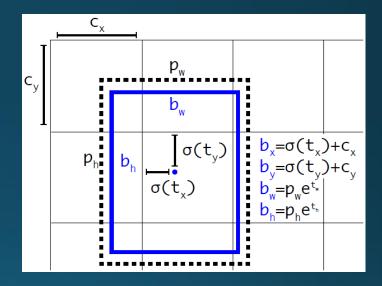
YOLO v3



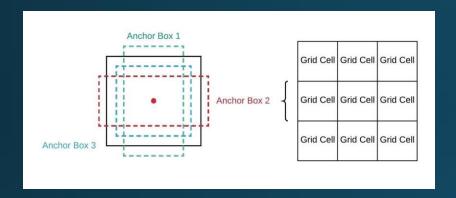
How it works

Image Grid. The Red Grid is responsible for detecting the dog

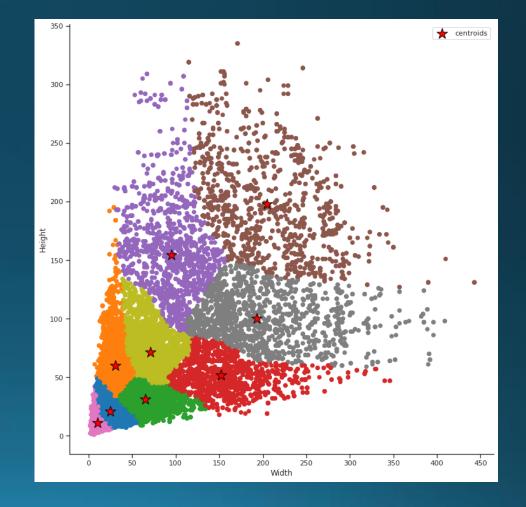




Determine Anchors



| | Scale 1 [width, height] | Scale 2 [width, height] | Scale 3 [width, height] |
|----------|----------------------------|----------------------------|----------------------------|
| Anchor 1 | [0.123, 0.200] | [0.084, 0.040] | [0.013, 0.014] |
| Anchor 2 | [0.251, 0.130] | [0.091, 0.092] | [0.031, 0.027] |
| Anchor 3 | [0.266, 0.257] | [0.198, 0.067] | [0.040, 0.078] |



Loss Function

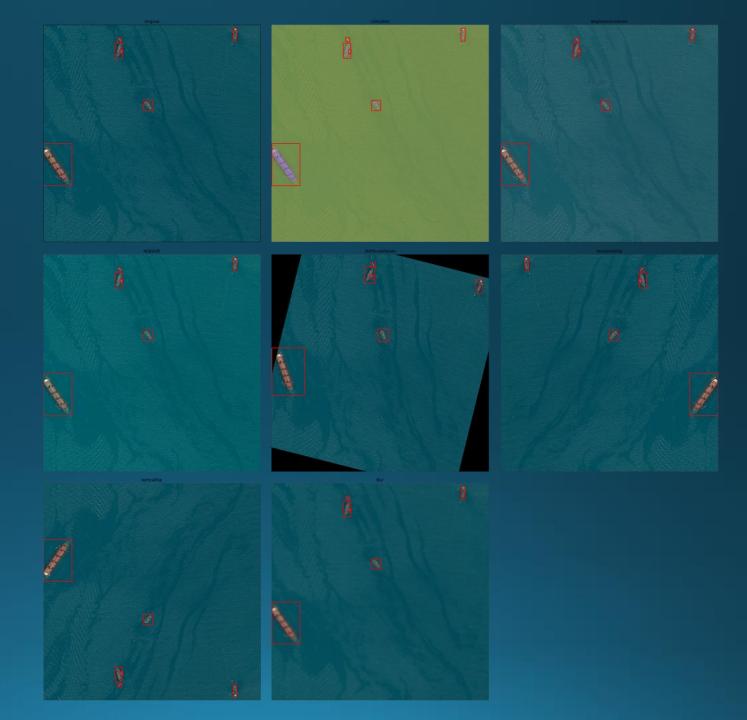
Regression Loss

$$\lambda_{coord} \sum_{i=0}^{S^{2}} \sum_{j=0}^{B} 1_{ij}^{obj} [(x_{i} - \widehat{x_{i}})^{2} + (y_{i} - \widehat{y_{i}})^{2}] + \lambda_{coord} \sum_{i=0}^{S^{2}} \sum_{j=0}^{B} 1_{ij}^{obj} \left[\left(\sqrt{w_{i}} - \sqrt{\widehat{w_{i}}} \right)^{2} + \left(\sqrt{h_{i}} - \sqrt{\widehat{h_{i}}} \right)^{2} \right] \\ + \lambda_{obj} \sum_{i=0}^{S^{2}} \sum_{j=0}^{B} 1_{ij}^{obj} (C_{i} - \widehat{C_{i}})^{2} + \lambda_{noobj} \sum_{i=0}^{S^{2}} \sum_{j=0}^{B} 1_{ij}^{noobj} (C_{i} - \widehat{C_{i}})^{2} + \sum_{i=0}^{Obj} 1_{ij}^{obj} \sum_{c \in classes} (p_{i}(c) - \widehat{p_{i}}(c))^{2}$$

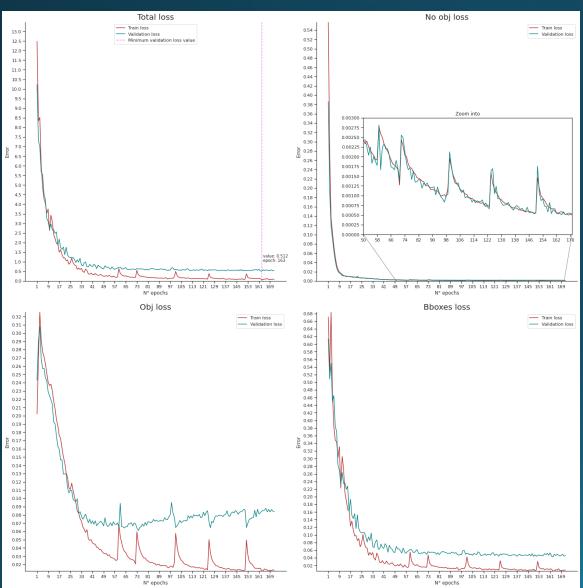
Confidence Loss

Classification Loss

Data Augmentation



Model tuning



| Obj confidence threshold | Overlap threshold | | | | | | |
|--------------------------|-------------------|-------|-------|-------|-------|--|--|
| | | 0,6 | 0,7 | 0,8 | 0,9 | | |
| | 0,6 | 0,814 | 0,816 | 0,814 | 0,79 | | |
| | 0,7 | 0,817 | 0,82 | 0,819 | 0,795 | | |
| | 0,8 | 0,822 | 0,821 | 0,821 | 0,799 | | |
| | 0,9 | 0,777 | 0,779 | 0,78 | 0,764 | | |
| | 1,0 | 0,247 | 0,245 | 0,245 | 0,247 | | |

NB: As metric I used Mean Average Precision

Model evaluation





MAP

MAP 50

MAP 75

0,825

0,904

0,857











