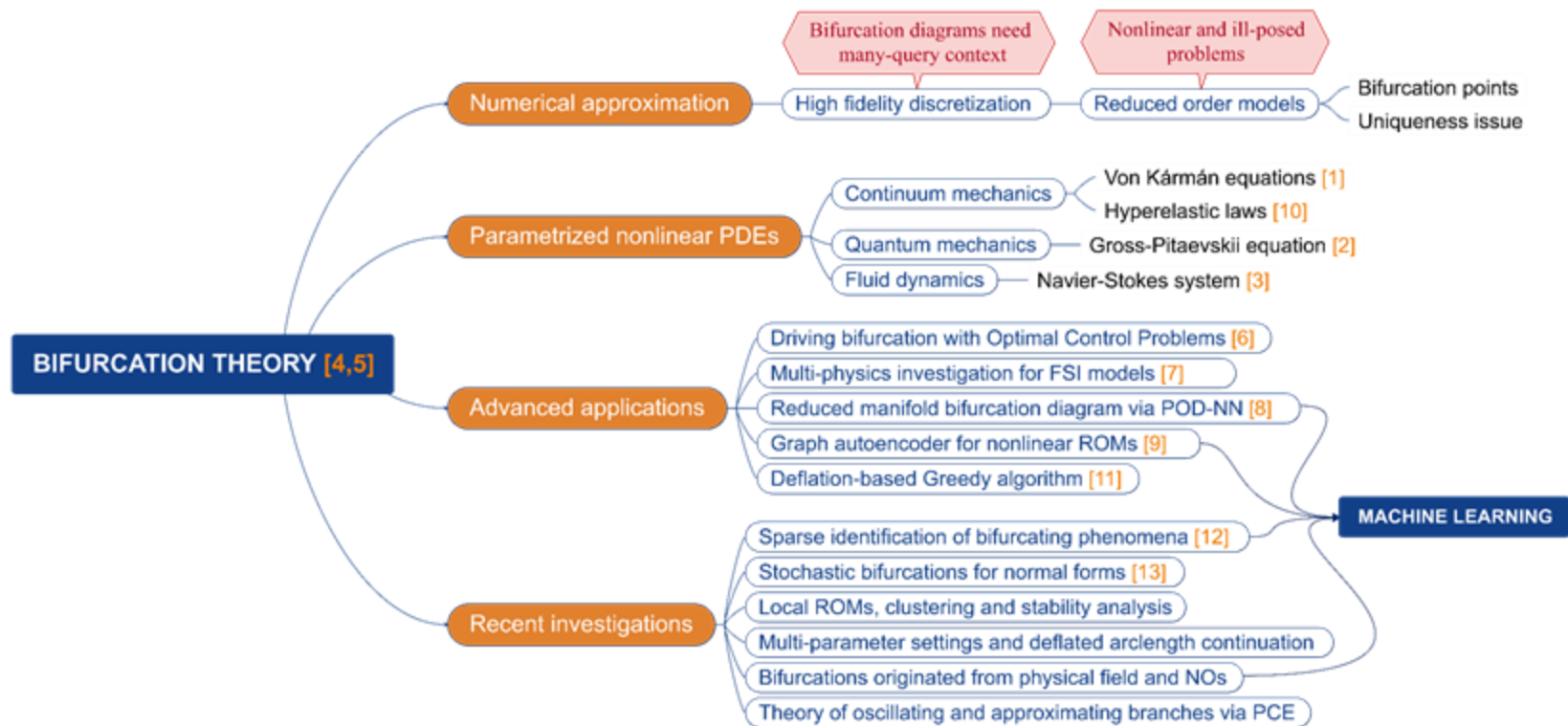


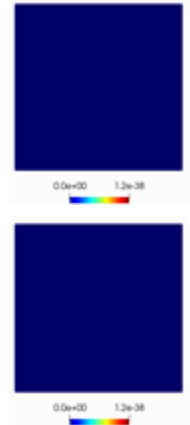
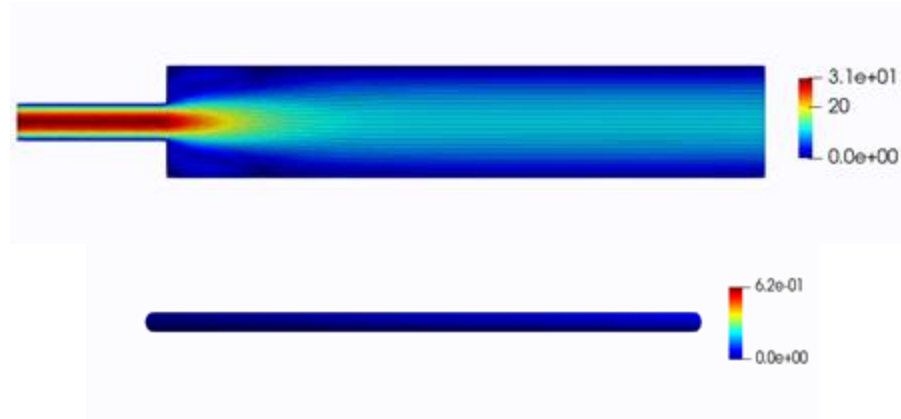
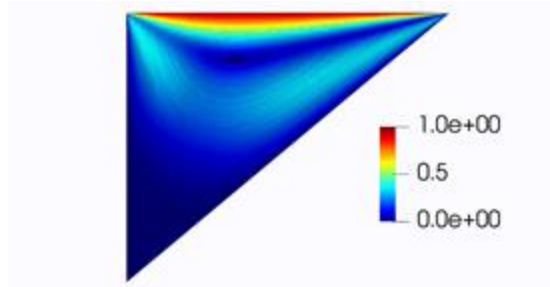
From Bifurcations to Machine Learning

Federico Pichi

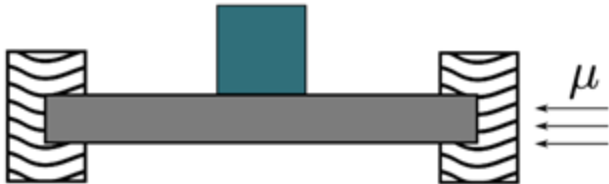
Exploring multiple directions



What are bifurcations?



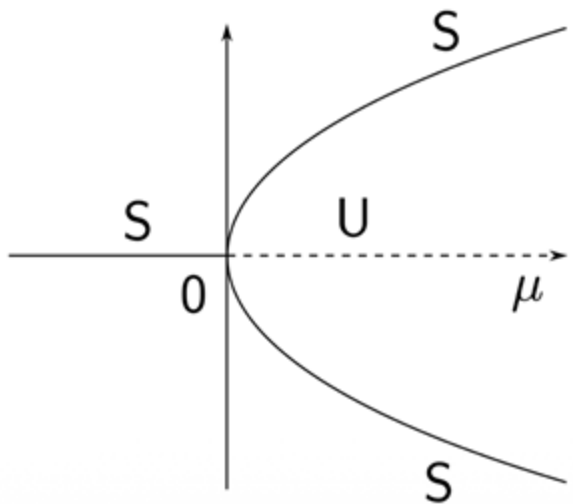
Example: A beam under compression **buckles** at a **critical load**



Example from ODEs

Landau's model describes **hydrodynamical instabilities**:

$$\frac{du}{dt} = \mu u - u^3$$



Supercritical pitchfork bifurcation

$$\mu^* = 0$$

- $\mu \leq 0 \rightarrow \exists! \text{ solution } u \equiv 0$
- $\mu > 0 \rightarrow 3 \text{ coexisting solutions}$

Projection-based Reduced Order Models (ROMs)

Common issues in the for bifurcating nonlinear PDEs context:

- Unbearable **computational cost** with nonlinear solver for **fine meshes** and **nested loops**
- Choice of the **initial guess** and **continuation method** to completely reconstruct the **bifurcation diagram**
- Identification of the **bifurcation points/curves/surfaces** in multi-parametric setting

$$\underbrace{G(X(\mu); \mu) = 0}_{\text{Partial differential equation}} \rightsquigarrow \underbrace{G_N(X_N(\mu); \mu) = 0}_{\text{High Fidelity approximation}} \rightsquigarrow \underbrace{G_N(X_N(\mu); \mu) = 0}_{\text{Reduced Basis approximation}}$$

$$G_N^q = V^T \begin{matrix} \text{Red Box} \\ G_N^q \end{matrix} V$$



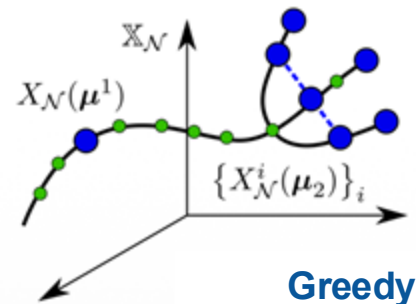
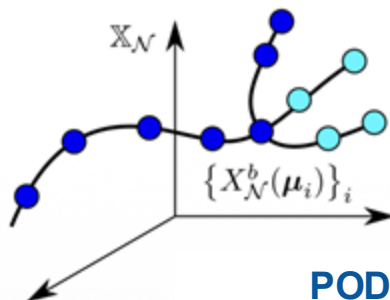
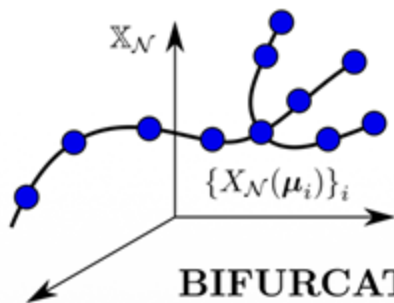
$$G_N(\mu) = \sum_q \theta^q(\mu) G_N^q$$

Projection-based Reduced Order Models (ROMs)

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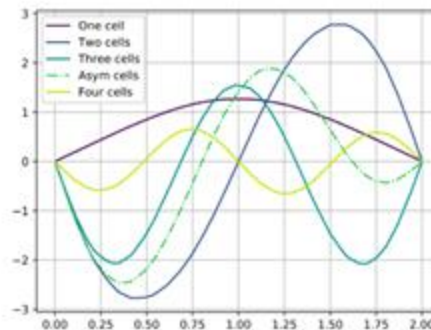
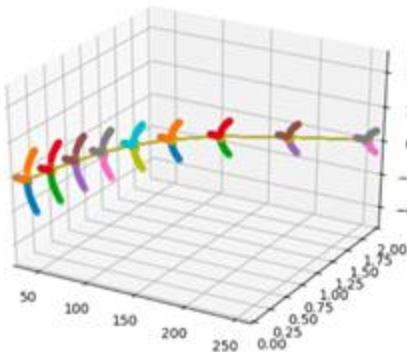
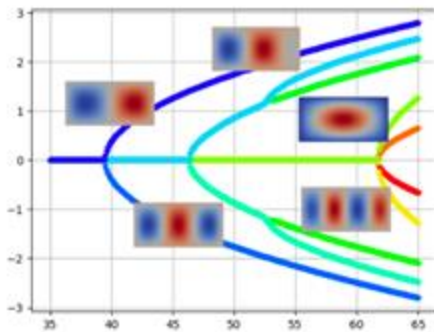
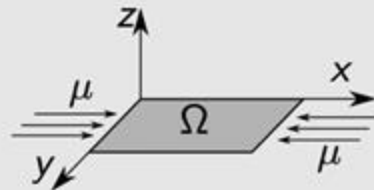


Bifurcation Problems

Von Kármán's buckling plate

Efficient **POD-based** computation of **multiple** and **secondary** bifurcation branches in the **multi-parametric** setting coupled with **spectral analysis**.

$$\begin{cases} \Delta^2 u + \mu u_{xx} = [\phi, u] & \text{in } \Omega, \\ \Delta^2 \phi = -[u, u] & \text{in } \Omega, \end{cases}$$



[1] FP, Rozza (2019). “Reduced basis approaches for parametrized bifurcation problems held by non-linear Von Kármán equations”. Journal of Scientific Computing

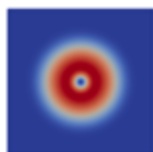
Gross-Pitaevskii BEC equation

Branch-wise approach with **Hermite** guesses detecting **(D)EIM** instabilities.

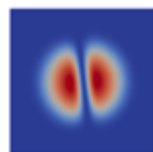
$$-\frac{1}{2}\Delta\phi + |\phi|^2\phi + W(\Omega)\phi - \mu\phi = 0$$



(a) ground state



(b) single vortex



(c) 1-dark stripe



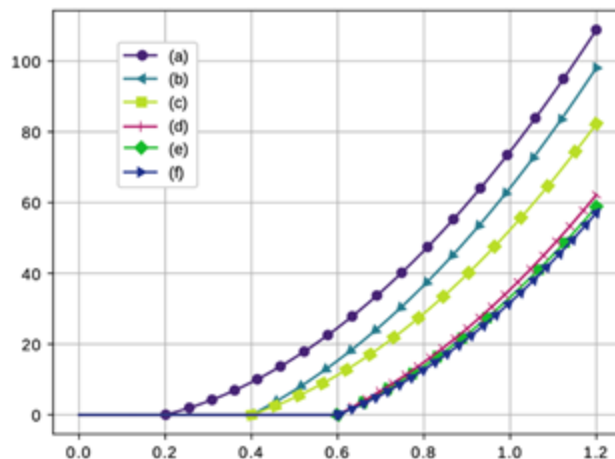
(d) 2-dark stripe



(e) soliton ring

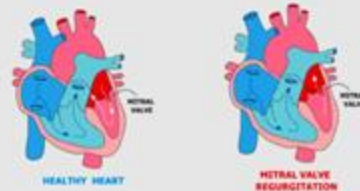


(f) soliton cross

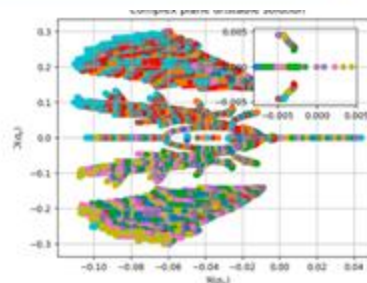
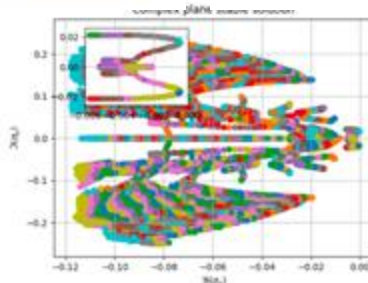
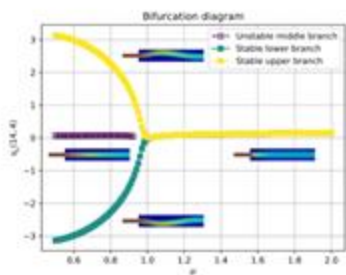
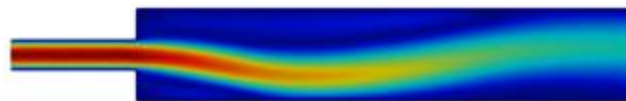
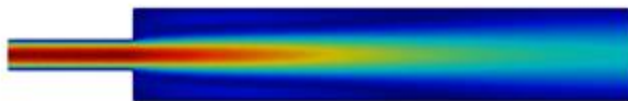


Navier-Stokes and the Coanda effect

$$\begin{cases} -\mu\Delta\mathbf{v} + \mathbf{v} \cdot \nabla\mathbf{v} + \nabla p = 0 & \text{in } \Omega, \\ \nabla \cdot \mathbf{v} = 0 & \text{in } \Omega, \end{cases}$$



Detection of **multiple wall-hugging** phenomena exploiting **deflation strategy**.



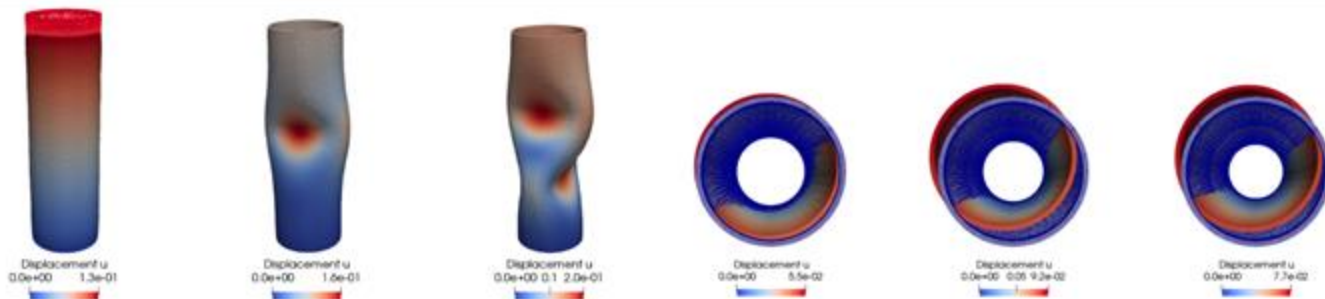
[3] Pintore, FP, Hess, Rozza, Canuto (2020). "Efficient computation of bifurcation diagrams with a deflated approach to RB spectral element method". ACOM

Buckling of hyper-elastic beams

Question: How **BCs** and **geometrical parameters** affect the bifurcation?

How: **Speedup** for realistic **SVK 3D** models with **Dirichlet** and **Neumann** compression for Norwegian petroleum industry.

$$-\operatorname{div} \left(\frac{\partial \psi(F)}{\partial F} \right) = f \quad \text{in } \Omega, \quad \text{where} \quad \psi(F) = \lambda_1 \mathcal{E} : \mathcal{E} + \frac{\lambda_2}{2} (\operatorname{tr}(\mathcal{E}))^2$$



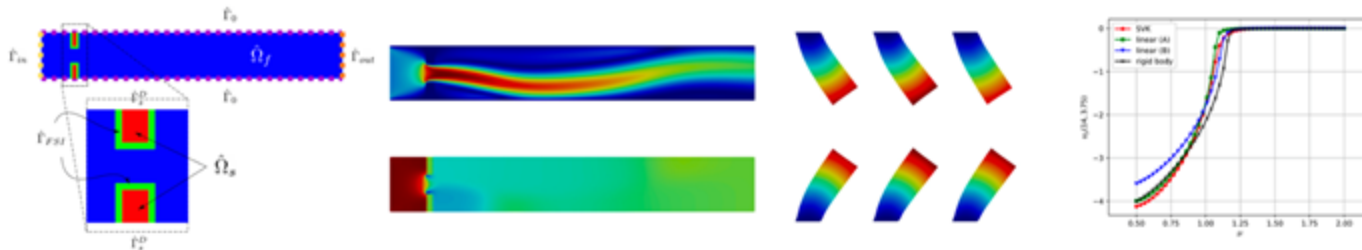
[10] FP, Rozza (2024). "Reduced Order Models for the Buckling of Hyperelastic Beams". RAMSES

Multi-physics bifurcations

Question: How does the **elastic structure** influence the bifurcating behavior?

How: **ALE** coupled system with **nonlinear** constitutive relations for the leaflets.

$$\begin{cases} \rho_f J \nabla \mathbf{u}_f \mathbf{F}^{-1} \mathbf{u}_f - \operatorname{div}(J \boldsymbol{\sigma}_f(\mathbf{u}_f, p_f) \mathbf{F}^{-T}) = 0 & \text{in } \Omega_f, \\ \operatorname{div}(J \mathbf{F}^{-1} \mathbf{u}_f) = 0 & \text{in } \Omega_f, \\ \Delta \mathbf{d}_f = 0 & \text{in } \Omega_f, \\ -\operatorname{div} \mathbf{P}(\mathbf{d}_s) = 0 & \text{in } \Omega_s, \end{cases} \quad \text{with} \quad \begin{cases} \mathbf{d}_f = \mathbf{d}_s \\ \mathbf{u}_f = 0 \\ \mathbf{P} \mathbf{n} = (J \boldsymbol{\sigma}_f \mathbf{F}^{-T}) \mathbf{n} \end{cases} \quad \text{on } \hat{\Gamma}_{FSI}$$

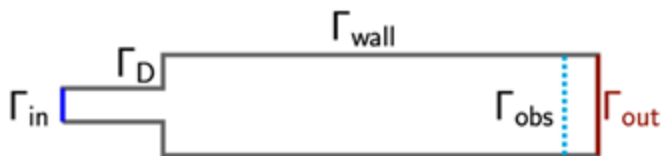


[7] Khamlich, FP, Rozza (2021). "Model order reduction for bifurcating phenomena in Fluid-Structure Interaction problems". IJNMF

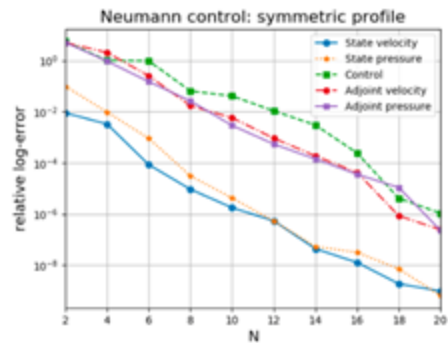
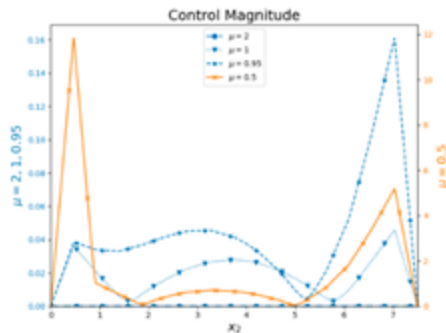
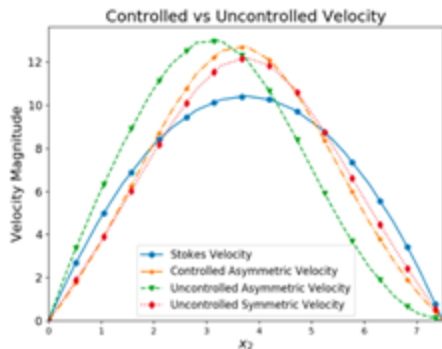
Advanced Applications and Machine Learning

Optimal Control Problems to steer bifurcations

- Questions:
- Can we influence the bifurcating behavior of the system?
 - How do the stability properties of the system change?



Goal: Recover a desired v_d on Γ_{obs}
 \rightsquigarrow symmetric Stokes solution



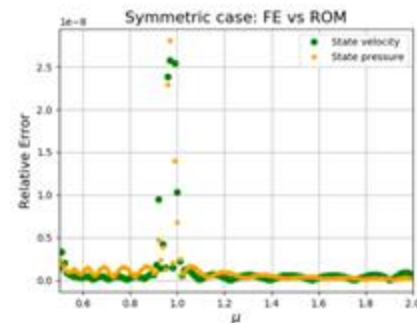
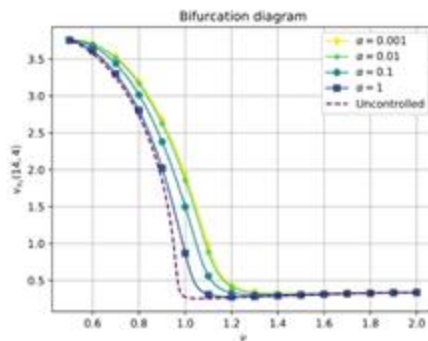
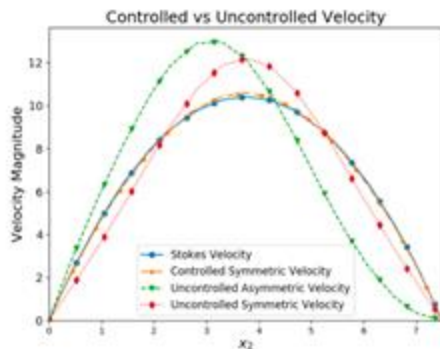
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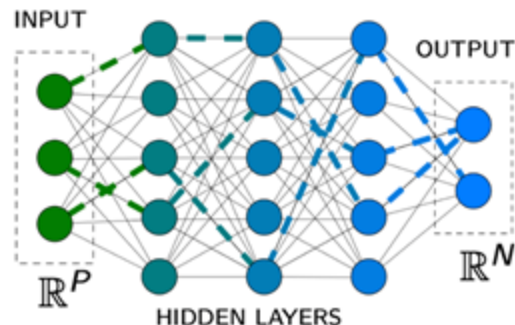
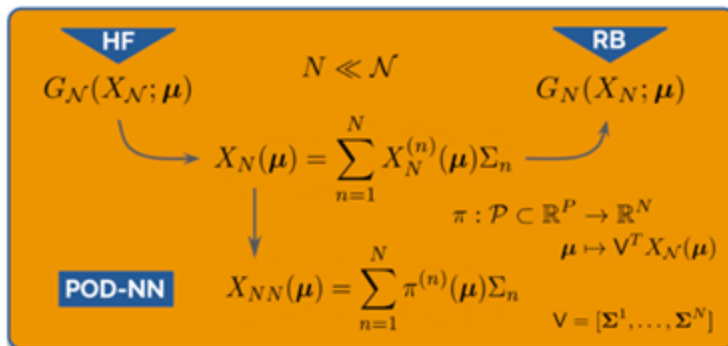


[5] FP, Strazzullo, Ballarin, and Rozza (2022). "Driving bifurcating parametrized nonlinear PDEs by optimal control strategies". ESAIM: M2AN

Data-driven and non-intrusive linear ROMs

Goal: Investigate efficiently complex **bifurcating** behavior in **real-time**.

How: Combining **ROMs** and **deep learning** of reduced coefficients.



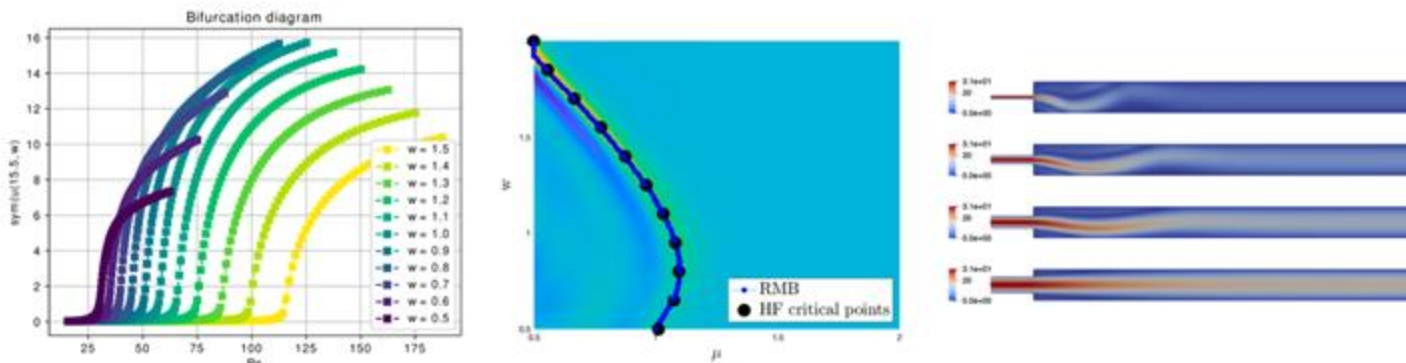
POD-NN approach:

approximate $\pi : \mathcal{P} \subset \mathbb{R}^P \rightarrow \mathbb{R}^N$ such that $\mu \mapsto \pi(\mu)$ from a training set given by the pairs $\{(\mu^i, V^T X_N(\mu^i))\}_{i=1}^{N_{tr}}$ obtained from the offline POD procedure.

Data-driven and non-intrusive linear ROMs

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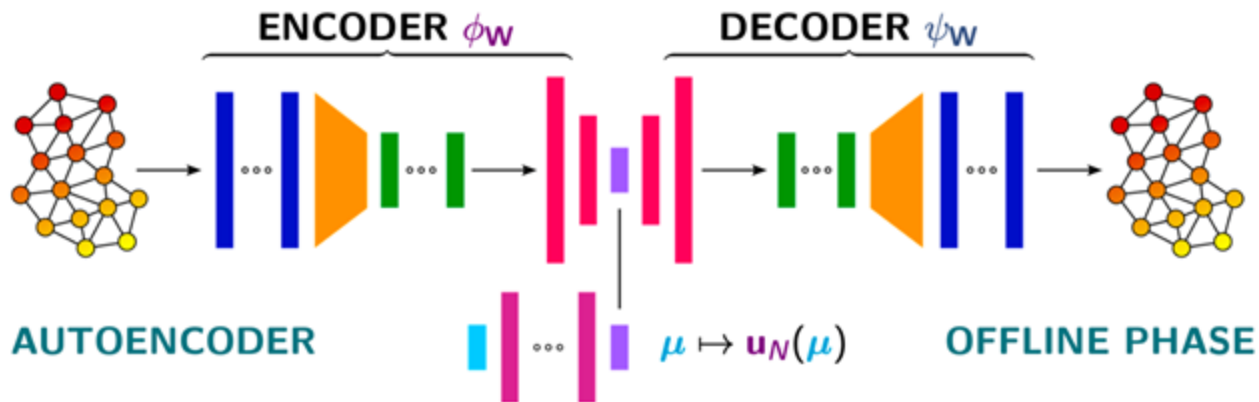
Reduced manifold based (RMB) bifurcation diagram:

Curvature-based detection tool exploiting the **non-smoothness** of the reduced manifold to track **critical points** evolution.

[8] FP, Ballarin, Rozza, and Hesthaven (2022). "An artificial neural network approach to bifurcating phenomena in computational fluid dynamics". C&F

Nonlinear graph-based ROM

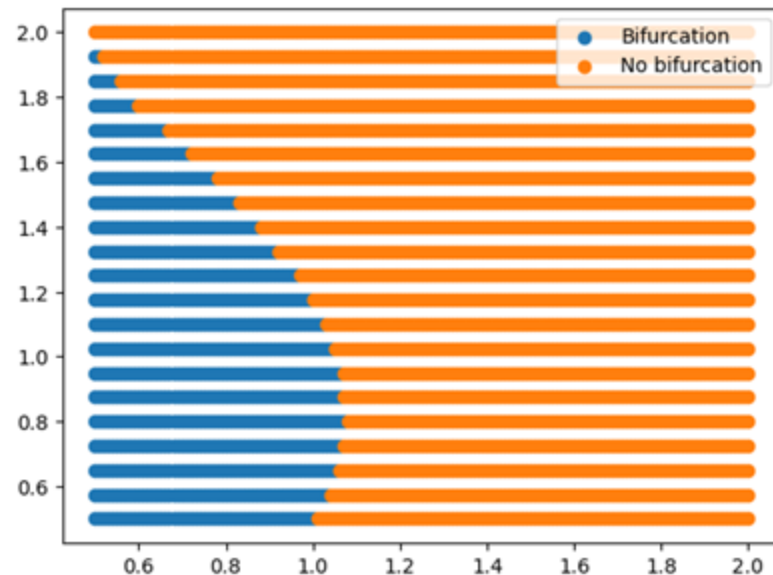
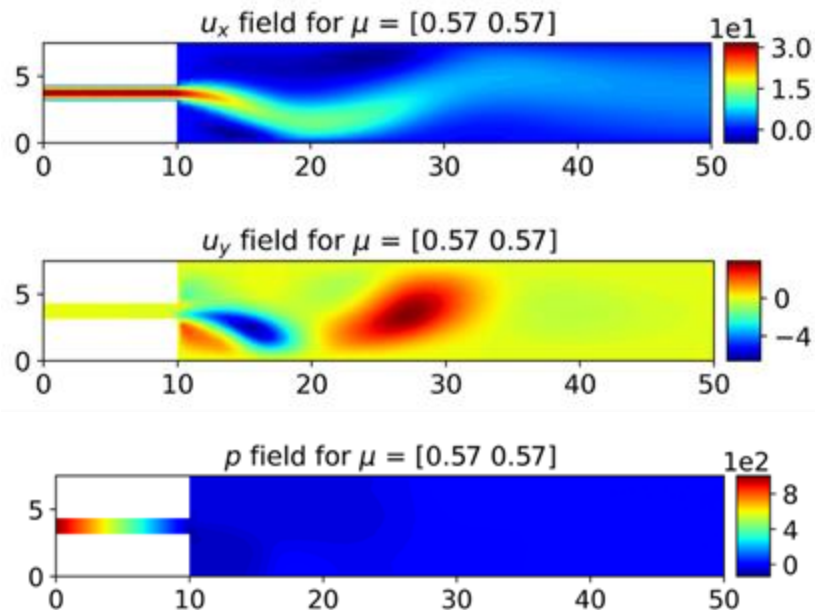
Graph Convolutional Autoencoder as efficient and **geometrically-consistent** nonlinear ROM for complex and **varying domains** with unstructured meshes.



Dataset: $\{u_{\mathcal{N}}(\mu^i), \Omega_{\mathcal{N}}(\mu^i)\}_{i=1}^{N_s} \rightsquigarrow$ approximate $\tilde{u}_{\mathcal{N}}(\mu) = \psi_{\mathbf{W}}(\phi_{\mathbf{W}}(u_{\mathcal{N}}(\mu)))$

$$\text{LOSS: } \mathcal{L} = \frac{1}{N_{\text{tr}}} \sum_{i=1}^{N_{\text{tr}}} \|\mathbf{u}_{\mathcal{N}}(\mu^i) - \tilde{\mathbf{u}}_{\mathcal{N}}(\mu^i)\|_2^2 + \frac{1}{N_{\text{tr}}} \sum_{i=1}^{N_{\text{tr}}} \|\tilde{u}_{\mathcal{N}}(\mu^i) - u_{\mathcal{N}}(\mu^i)\|_2^2$$

Nonlinear graph-based ROM



[9] FP, Moya, Hesthaven (2024). "A convolutional graph neural network approach to model order reduction to non-linear parametrized PDEs". JCP

Collaborators on bifurcating phenomena

- F. Ballarin
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- I.C. Gonnella
- M. Hess
- J.S. Hesthaven
- A. Kabalan
- M. Khamlich
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- M. Pintore
- B. Moya
- A. Quaini
- G. Rozza
- M. Strazzullo
- L. Tomada
- G. Venier
- N. Zhang

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- D.B.P. Huynh
- G. Noselli
- O. Morrison
- L. Mosconi
- O. Mula
- D. Oberto
- A. Orunnukaran
- M. Ramadan
- S. Rathore
- F. Romor
- L. Scandurra
- C. Schwab
- G. Stabile
- N. Tonicello
- D. Torlo
- C. Valentino

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- [3] Pintore, M., Pichi, F., Hess, M., Rozza, G., Canuto, C., 2021. **Efficient computation of bifurcation diagrams with a deflated approach to reduced basis spectral element method**. Adv Comput Math 47, 1. <https://doi.org/10.1007/s10444-020-09827-6>
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- [5] Pichi, F., Ballarin, F., Rozza, G., 2022. **Chapter 5: Reduced Basis Approaches to Bifurcating Nonlinear Parametrized Partial Differential Equations**, in: AROMA-CFD, Computational Science & Engineering. Society for Industrial and Applied Mathematics, pp. 97–123. <https://doi.org/10.1137/1.9781611977257.ch5>
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- [9] Pichi, F., Moya, B., Hesthaven, J.S., 2024. **A graph convolutional autoencoder approach to model order reduction for parametrized PDEs**. Journal of Computational Physics 501, 112762. <https://doi.org/10.1016/j.jcp.2024.112762>
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Thank you for your attention!

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