

# Group Project Notebook

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## 1 Group Project

### 1.1 Loading the libraries

We first start by checking that all the necessary libraries are all downloaded, and we then load them

```
[1]: listofpackages <- c(
  "MASS",
  "WDI",
  "tidyr",
  "dplyr",
  "VIM",
  "httr",
  "jsonlite",
  "lmtest",
  "forecast",
  "nlme",
  "car",
  "ggplot2",
  "metafor",
  "maps",
  "tseries"
)
if (!require("democracyData")) {
  remotes::install_github("xmarquez/democracyData")
}
newpackages <- listofpackages[!(listofpackages %in% installed.
  ↪packages()[, "Package"])]
if(length(newpackages)) install.packages(newpackages,
  dependencies = TRUE,
  repos = "http://cran.us.r-project.org"
)
```

Loading required package: democracyData

```
[2]: library(MASS)
library(WDI)
library(tidyr)
```

```

library(dplyr)
library(VIM)
library(httr)
library(jsonlite)
library(lmtest)
library(forecast)
library(nlme)
library(car)
library(ggplot2)
library(metafor)
library(democracyData)
library(maps)
library(tseries)

```

## 1.2 Data Retrieval

We retrieve data from 1995 to 2023 on the following indicators:

- GDP per capita (constant 2010 US\$) - NY.GDP.PCAP.CD
- Gross national savings (% of GNI) - NY.GNS.ICTR.ZS
- Population growth (annual %) - SP.POP.GROW
- Fertility rate (total births per woman) - SP.DYN.TFRT.IN
- CO2 emissions (metric tons per capita) - EN.ATM.CO2E.PC
- Political Stability and Lack of Violence - PV.PER.RNK.LOWER, PV.PER.RNK.UPPER
- Research and development expenditure (% of GDP) - GB.XPD.RSDV.GD.ZS
- Freedom status estimation from the Freedom House
- World map data from the maps library

1995 was chosen as the starting point as this is after the fall of the Soviet Union and the end of the Yugoslav wars

```

[3]: start_date <- 1995
     end_date <- 2023

gdp_per_capita <- WDI(country = "all",
  "NY.GDP.PCAP.CD",
  start = start_date,
  end = end_date
)

saving_rate <- WDI(country = "all",
  "NY.GNS.ICTR.ZS",
  start = start_date,
  end = end_date
)

```

```

)

population_growth <- WDI(country = "all",
  "SP.POP.GROW",
  start = start_date,
  end = end_date
)

fertility <- WDI(country = "all",
  "SP.DYN.TFRT.IN",
  start = start_date,
  end = end_date
)

co2_emission <- WDI(country = "all",
  "EN.ATM.CO2E.PC",
  start = start_date,
  end = end_date
)

pol_stability_lower <- WDI(country = "all",
  "PV.PER.RNK.LOWER",
  start = start_date,
  end = end_date
)

pol_stability_upper <- WDI(country = "all",
  "PV.PER.RNK.UPPER",
  start = start_date,
  end = end_date
)

research <- WDI(country = "all",
  "GB.XPD.RSDV.GD.ZS",
  start = start_date,
  end = end_date
)

dem_data <- download_fh()

world_map <- map_data("world")

print("Downloaded the dataset")

```

Downloading data...

[1] "Downloaded the dataset"

We create dummy variables for Free and Partially Free countries

```
[4]: dem_data <- dem_data %>% select(fh_country, year, status)
dem_data$dummy_PF <- ifelse(dem_data$status == "PF", 1, 0)
dem_data$dummy_F <- ifelse(dem_data$status == "F", 1, 0)
colnames(dem_data)[1] <- "country"
dem_data$status <- NULL
```

We create two dummy variables: one for countries whose centroid distance from the equator is  $\geq 60$  and one for countries whose centroids distance from the equator is  $\geq 30$  and  $< 60$

```
[5]: country_centroids <- aggregate(
  cbind(long, lat) ~ region,
  data = world_map,
  FUN = function(x) median(range(x))
)
colnames(country_centroids) <- c("country", "longitude", "latitude")
country_centroids$longitude <- NULL
country_centroids$dummy_30_60 = ifelse(
  abs(country_centroids$latitude) >= 30 & abs(country_centroids$latitude) < 60,
  1,
  0
)
country_centroids$dummy_60_plus = ifelse(
  abs(country_centroids$latitude) >= 60,
  1,
  0
)
country_centroids$latitude <- NULL
```

We now merge and clean all the datasets

```
[6]: data_regression <- merge.data.frame(gdp_per_capita, saving_rate)
data_regression <- merge.data.frame(data_regression, population_growth)
data_regression <- merge.data.frame(data_regression, co2_emission)
data_regression <- merge.data.frame(data_regression, fertility)
data_regression <- merge.data.frame(data_regression, pol_stability_lower)
data_regression <- merge.data.frame(data_regression, research)
data_regression <- merge.data.frame(data_regression, pol_stability_upper)
data_regression <- merge.data.frame(data_regression, country_centroids)
last_year_observed <- max(data_regression$year)
dem_data <- dem_data %>% filter(year >= start_date & year <= last_year_observed)
data_regression <- merge.data.frame(data_regression, dem_data)
subsetting_data_regression = subset(data_regression, year == last_year_observed)
in_subset <- data_regression$country %in% subsetting_data_regression$country
data_regression <- data_regression[in_subset, ]
print("Merged the dataset")
```

```
[1] "Merged the dataset"
```

Sanity check to be sure that only countries are in the dataframe

```
[7]: print(paste("Number of unique countries:",  

  ↪length(unique(data_regression$country))))  

print(unique(data_regression$country))
```

```
[1] "Number of unique countries: 163"
 [1] "Afghanistan"      "Albania"
 [3] "Algeria"          "Andorra"
 [5] "Angola"           "Argentina"
 [7] "Armenia"          "Australia"
 [9] "Austria"          "Azerbaijan"
[11] "Bahrain"          "Bangladesh"
[13] "Barbados"         "Belarus"
[15] "Belgium"          "Belize"
[17] "Benin"            "Bhutan"
[19] "Bolivia"          "Bosnia and Herzegovina"
[21] "Botswana"         "Brazil"
[23] "Bulgaria"         "Burkina Faso"
[25] "Burundi"          "Cambodia"
[27] "Cameroon"         "Canada"
[29] "Central African Republic" "Chad"
[31] "Chile"            "China"
[33] "Colombia"         "Comoros"
[35] "Costa Rica"       "Croatia"
[37] "Cuba"             "Cyprus"
[39] "Denmark"          "Djibouti"
[41] "Dominica"         "Dominican Republic"
[43] "Ecuador"          "El Salvador"
[45] "Equatorial Guinea" "Eritrea"
[47] "Estonia"          "Ethiopia"
[49] "Fiji"             "Finland"
[51] "France"           "Gabon"
[53] "Georgia"          "Germany"
[55] "Ghana"            "Greece"
[57] "Grenada"          "Guatemala"
[59] "Guinea"           "Guinea-Bissau"
[61] "Guyana"           "Haiti"
[63] "Honduras"         "Hungary"
[65] "Iceland"          "India"
[67] "Indonesia"        "Iraq"
[69] "Ireland"          "Israel"
[71] "Italy"            "Jamaica"
[73] "Japan"            "Jordan"
[75] "Kazakhstan"       "Kenya"
[77] "Kiribati"         "Kosovo"
[79] "Kuwait"           "Latvia"
[81] "Lebanon"          "Lesotho"
[83] "Liberia"          "Libya"
[85] "Liechtenstein"    "Lithuania"
```

[87]	"Luxembourg"	"Madagascar"
[89]	"Malawi"	"Malaysia"
[91]	"Maldives"	"Mali"
[93]	"Malta"	"Marshall Islands"
[95]	"Mauritania"	"Mauritius"
[97]	"Mexico"	"Moldova"
[99]	"Monaco"	"Mongolia"
[101]	"Montenegro"	"Morocco"
[103]	"Mozambique"	"Myanmar"
[105]	"Namibia"	"Nauru"
[107]	"Nepal"	"Netherlands"
[109]	"New Zealand"	"Nicaragua"
[111]	"Niger"	"Nigeria"
[113]	"North Macedonia"	"Norway"
[115]	"Oman"	"Pakistan"
[117]	"Palau"	"Panama"
[119]	"Papua New Guinea"	"Paraguay"
[121]	"Peru"	"Philippines"
[123]	"Poland"	"Portugal"
[125]	"Qatar"	"Romania"
[127]	"Rwanda"	"Samoa"
[129]	"San Marino"	"Sao Tome and Principe"
[131]	"Saudi Arabia"	"Senegal"
[133]	"Serbia"	"Seychelles"
[135]	"Sierra Leone"	"Singapore"
[137]	"Slovenia"	"Solomon Islands"
[139]	"Somalia"	"South Africa"
[141]	"South Sudan"	"Spain"
[143]	"Sri Lanka"	"Sudan"
[145]	"Suriname"	"Sweden"
[147]	"Switzerland"	"Tajikistan"
[149]	"Tanzania"	"Thailand"
[151]	"Timor-Leste"	"Togo"
[153]	"Tonga"	"Tunisia"
[155]	"Turkmenistan"	"Uganda"
[157]	"Ukraine"	"United Arab Emirates"
[159]	"Uruguay"	"Uzbekistan"
[161]	"Vanuatu"	"Zambia"
[163]	"Zimbabwe"	

To remove any NaNs present in the data, we use k-Nearest Neighbours(kNN), a non-parametric model that imputes the value of a point based on the average values of the  $k$  nearest points in the dataset. Mathematically what it does is the following:

For an observation  $X_i$  with missing data, calculate the distance between  $X_i$  and all other observations in the dataset that have a value for the missing feature. The distance  $R$  uses is euclidian and in an  $n$ -dimensional space is given by:

$$d(X_i, X_j) = \sqrt{\sum_{k=1}^n (X_{ik} - X_{jk})^2} \quad (1)$$

Then the  $k$  observations closest to  $X_i$  based on the calculated distances are selected and the missing value in  $X_i$  are substituted with the mean of the observed values from the  $k$  nearest neighbors. By using the most similar observations for imputation, kNN ensures that the imputed values are more contextually appropriate, preserving the data's underlying structure and relationships.

We chose kNN because, unlike model-based approaches that require assumptions about the distribution of data or the relationship between variables, kNN's non-parametric nature makes it robust to deviations from such assumptions.

```
[8]: data_regression <- kNN(data_regression, k = 10)
```

As there are a lot of extreme values in the political stability estimate, we decided it was best to aggregate them using a weighted average, where the weights are calculated as followed

- For the lower bound it is:  $\frac{1}{2} + \frac{\text{political stability}_*}{200}$ , which means that it starts at  $\frac{1}{2}$  and linearly increases up to 1, when  $\text{political stability}_* = 100$  where  $\text{political stability}_*$  is the lower bound of the political stability estimation
- For the upper bound it is:  $\frac{1}{2} + \frac{100 - \text{political stability}^*}{200}$ , which means that it starts at 1 and linearly decreases up to  $\frac{1}{2}$ , when  $\text{political stability}^* = 100$  where  $\text{political stability}^*$  is the upper bound of the political stability estimation

This is done because linear models can struggle with extreme values, and these extremes can skew the estimation, making it difficult to accurately assess the impact of political stability on GDP.

```
[10]: weighted_average <- function(lower, upper) {
  weight_l <- 0.5 + (lower / 200)
  weight_u <- 0.5 + ((100 - upper) / 200)
  rtv <- (lower * weight_l + upper * weight_u) / (weight_l + weight_u)
  return(rtv)
}
data_regression$pol_stability <- mapply(
  weighted_average,
  data_regression$PV.PER.RNK.LOWER,
  data_regression$PV.PER.RNK.UPPER
)
```

We now ensure that all the necessary columns are in numerical form and remove any that are unnecessary for the assignment

```
[11]: data_regression$gdp <- as.numeric(data_regression$NY.GDP.PCAP.CD)
data_regression$saving <- as.numeric(data_regression$NY.GNS.ICTR.ZS)
data_regression$pop_growth <- as.numeric(data_regression$SP.POP.GROW)
data_regression$fertility <- as.numeric(data_regression$SP.DYN.TFRT.IN)
data_regression$co2_emission <- as.numeric(data_regression$EN.ATM.CO2E.PC)
data_regression$pol_stability <- as.numeric(data_regression$pol_stability)
```

```
data_regression$research <- as.numeric(data_regression$GB.XPD.RSDV.GD.ZS)
```

```
[12]: data_regression$iso2c <- NULL
data_regression$iso3c <- NULL
data_regression$NY.GDP.PCAP.CD <- NULL
data_regression$NY.GNS.ICTR.ZS <- NULL
data_regression$SP.POP.GROW <- NULL
data_regression$SP.DYN.TFRT.IN <- NULL
data_regression$EN.ATM.CO2E.PC <- NULL
data_regression$PV.PER.RNK.LOWER <- NULL
data_regression$PV.PER.RNK.UPPER <- NULL
data_regression$GB.XPD.RSDV.GD.ZS <- NULL
data_regression$country_imp <- NULL
data_regression$NY.GDP.PCAP.CD_imp <- NULL
data_regression$NY.GNS.ICTR.ZS_imp <- NULL
data_regression$SP.POP.GROW_imp <- NULL
data_regression$SP.DYN.TFRT.IN_imp <- NULL
data_regression$EN.ATM.CO2E.PC_imp <- NULL
data_regression$iso2c_imp <- NULL
data_regression$iso3c_imp <- NULL
data_regression$year_imp <- NULL
data_regression$PV.PER.RNK.LOWER_imp <- NULL
data_regression$PV.PER.RNK.UPPER_imp <- NULL
data_regression$GB.XPD.RSDV.GD.ZS_imp <- NULL
data_regression$dummy_F_imp <- NULL
data_regression$dummy_PF_imp <- NULL
data_regression$dummy_30_60_imp <- NULL
data_regression$dummy_60_plus_imp <- NULL
```

Taking the logarithms, removing any  $\pm\infty$  generated by taking the logarithm and imputing the NaNs created

```
[13]: data_regression$gdp <- log(data_regression$gdp)
data_regression$saving <- log(data_regression$saving)
data_regression$pop_growth <- log(data_regression$pop_growth)
data_regression$co2_emission <- log(data_regression$co2_emission)
data_regression$fertility <- log(data_regression$fertility)
data_regression$research <- log(data_regression$research)
```

Warning message in log(data\_regression\$saving):

“NaNs produced”

Warning message in log(data\_regression\$pop\_growth):

“NaNs produced”

```
[14]: data_regression$co2_emission <- ifelse(
  is.infinite(
    data_regression$co2_emission
  ),
```



```

    NA,
    data_regression$co2_emission
)
data_regression$fertility <- ifelse(
  is.infinite(
    data_regression$fertility
  ),
  NA,
  data_regression$fertility
)
data_regression$research <- ifelse(
  is.infinite(
    data_regression$research
  ),
  NA,
  data_regression$research
)

```

```

[15]: data_regression <- kNN(data_regression, k = 10)
data_regression$country_imp <- NULL
data_regression$saving_imp <- NULL
data_regression$pop_growth_imp <- NULL
data_regression$gdp_imp <- NULL
data_regression$year_imp <- NULL
data_regression$co2_emission_imp <- NULL
data_regression$fertility_imp <- NULL
data_regression$pol_stability_imp <- NULL
data_regression$research_imp <- NULL
data_regression$dummy_PF_imp <- NULL
data_regression$dummy_F_imp <- NULL
data_regression$dummy_30_60_imp <- NULL
data_regression$dummy_60_plus_imp <- NULL

```

Sanity check to be sure that our dataset follows our expectations

```

[16]: print(colnames(data_regression))
print(summary(data_regression))

```

```

[1] "country"      "year"         "dummy_30_60"  "dummy_60_plus"
[5] "dummy_PF"     "dummy_F"      "pol_stability" "gdp"
[9] "saving"       "pop_growth"   "fertility"     "co2_emission"
[13] "research"

  country      year  dummy_30_60  dummy_60_plus
Length:4508   Min.   :1995   Min.   :0.0000   Min.   :0.00000
Class :character 1st Qu.:2002   1st Qu.:0.0000   1st Qu.:0.00000
Mode  :character Median :2009   Median :0.0000   Median :0.00000
              Mean  :2009   Mean  :0.3647   Mean  :0.03106
              3rd Qu.:2016   3rd Qu.:1.0000   3rd Qu.:0.00000

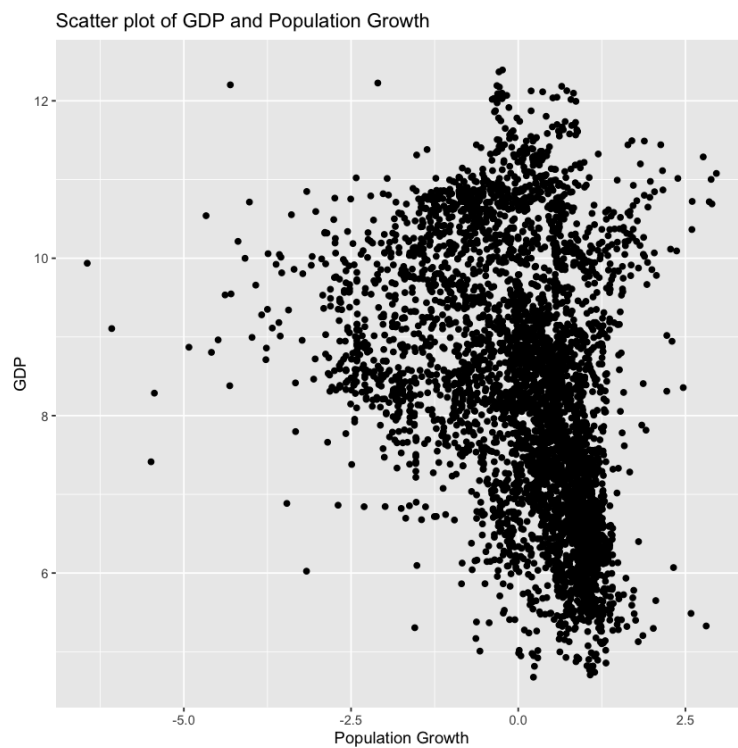
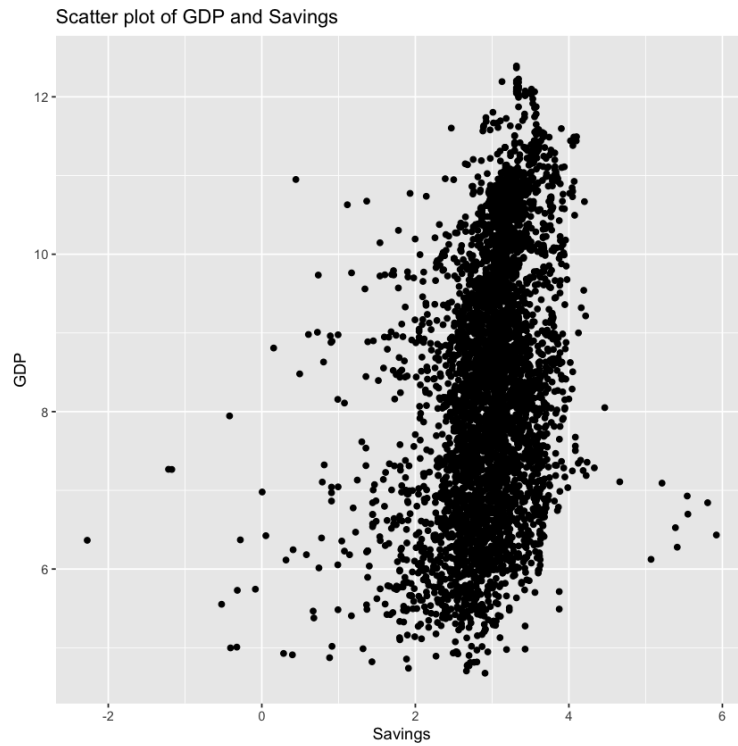
```

	Max. :2022	Max. :1.0000	Max. :1.00000
dummy_PF	dummy_F	pol_stability	gdp
Min. :0.0000	Min. :0.0000	Min. : 0.00	Min. : 4.676
1st Qu.:0.0000	1st Qu.:0.0000	1st Qu.:28.82	1st Qu.: 6.969
Median :0.0000	Median :0.0000	Median :47.78	Median : 8.268
Mean :0.3321	Mean :0.4439	Mean :48.03	Mean : 8.271
3rd Qu.:1.0000	3rd Qu.:1.0000	3rd Qu.:70.74	3rd Qu.: 9.470
Max. :1.0000	Max. :1.0000	Max. :96.35	Max. :12.392
saving	pop_growth	fertility	co2_emission
Min. :-2.274	Min. :-6.44493	Min. :-0.1625	Min. :-3.8263
1st Qu.: 2.724	1st Qu.: -0.42255	1st Qu.: 0.5365	1st Qu.: -0.5622
Median : 3.040	Median : 0.34207	Median : 0.9365	Median : 0.8563
Mean : 2.971	Mean : 0.08756	Mean : 0.9857	Mean : 0.5316
3rd Qu.: 3.292	3rd Qu.: 0.86320	3rd Qu.: 1.4237	3rd Qu.: 1.8252
Max. : 5.922	Max. : 2.96323	Max. : 2.0510	Max. : 3.8640
research			
Min. :-5.2140			
1st Qu.: -1.6810			
Median : -1.1316			
Mean : -1.0095			
3rd Qu.: -0.3806			
Max. : 1.7414			

### 1.3 Data Exploration

We will now explore the distributions of the various variables to better understand the data we have at hand

```
[17]: ggplot(data_regression, aes(x = saving, y = gdp)) +
  geom_point() +
  labs(title = "Scatter plot of GDP and Savings",
        x = "Savings",
        y = "GDP")
ggplot(data_regression, aes(x = pop_growth, y = gdp)) +
  geom_point() +
  labs(title = "Scatter plot of GDP and Population Growth",
        x = "Population Growth",
        y = "GDP")
```

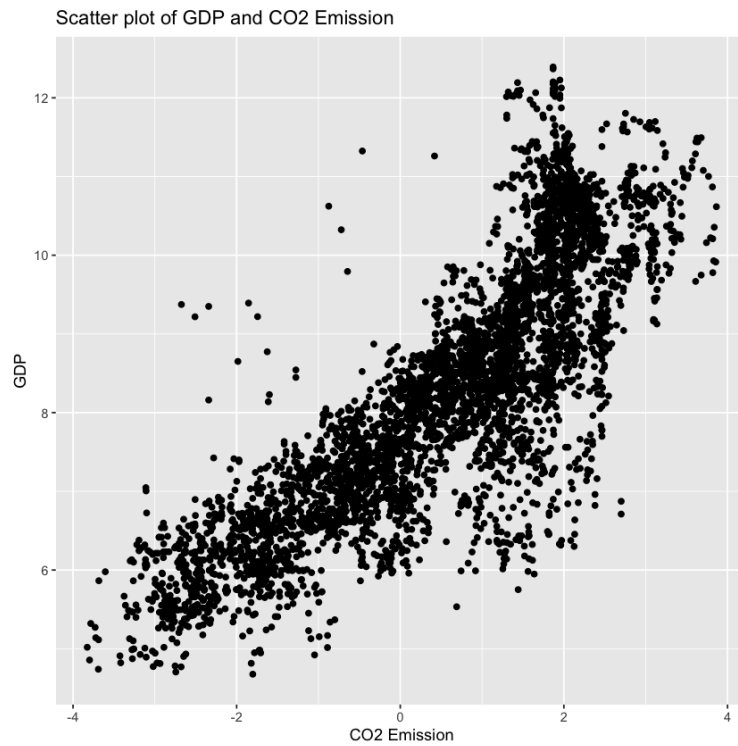


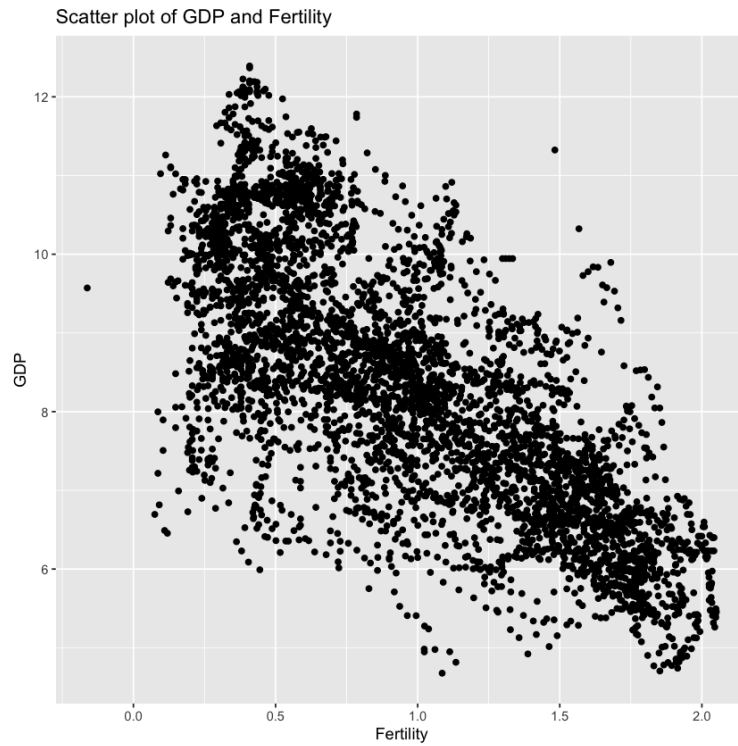
```
[18]: ggplot(data_regression, aes(x = co2_emission, y = gdp)) +  
      geom_point() +  
      labs(title = "Scatter plot of GDP and CO2 Emission",  
           x = "CO2 Emission",
```

```

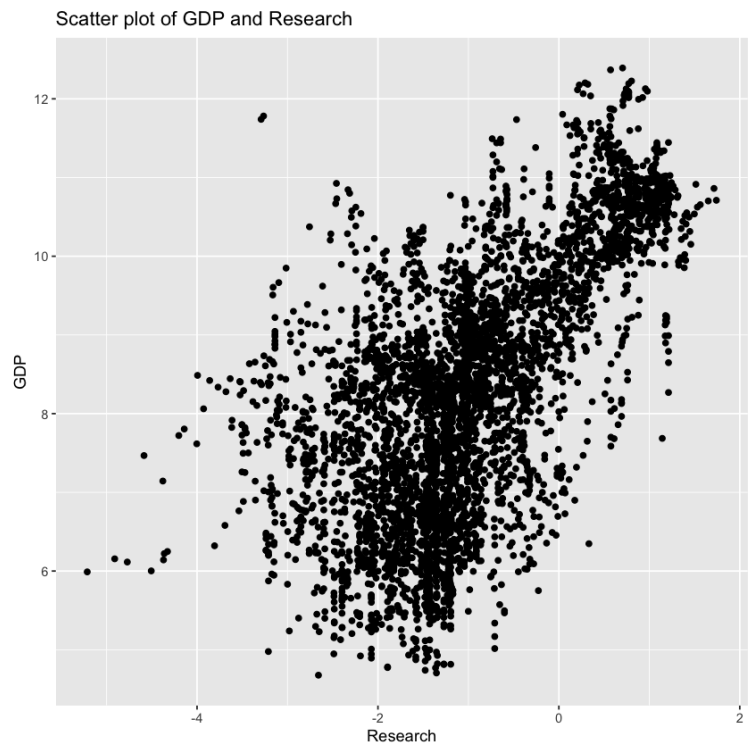
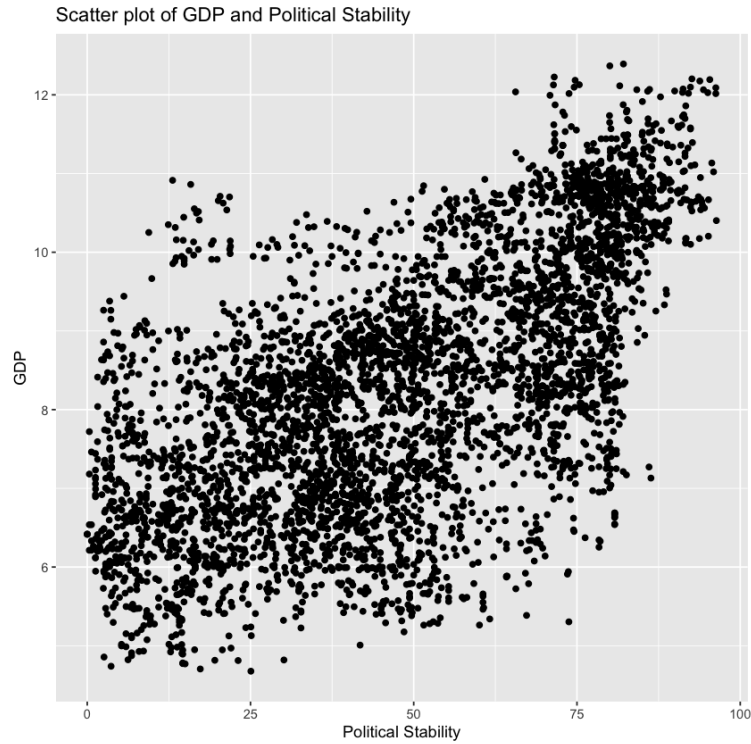
    y = "GDP")
ggplot(data_regression, aes(x = fertility, y = gdp)) +
  geom_point() +
  labs(title = "Scatter plot of GDP and Fertility",
    x = "Fertility",
    y = "GDP")

```





```
[19]: ggplot(data_regression, aes(x = pol_stability, y = gdp)) +  
      geom_point() +  
      labs(title = "Scatter plot of GDP and Political Stability",  
           x = "Political Stability",  
           y = "GDP")  
ggplot(data_regression, aes(x = research, y = gdp)) +  
      geom_point() +  
      labs(title = "Scatter plot of GDP and Research",  
           x = "Research",  
           y = "GDP")
```



From the plots we can infer that: - GDP and Savings are mostly uncorrelated, with most observations of Saving being around 3 - There seems to be a correlation between GDP and the other predictors, with varying degree of variance

From here we can infer that all predictors display significant skewness

## 1.4 Linear Regression

We now do a linear regression. We start from the model given by the assignment, i.e.

$$\log(gdp) = \log(savings) + \log(population\ growth)$$

```
[30]: model <- lm(gdp ~ saving + pop_growth, data = data_regression)
```

We now check the summary of the model

```
[31]: summary(model)
```

Call:

```
lm(formula = gdp ~ saving + pop_growth, data = data_regression)
```

Residuals:

Min	1Q	Median	3Q	Max
-4.4033	-1.0207	-0.1898	0.9567	5.4765

Coefficients:

	Estimate	Std. Error	t value	Pr(> t )
(Intercept)	5.38067	0.11555	46.56	<2e-16 ***
saving	0.98910	0.03823	25.87	<2e-16 ***
pop_growth	-0.55795	0.01972	-28.30	<2e-16 ***

---

Signif. codes: 0 '\*\*\*' 0.001 '\*\*' 0.01 '\*' 0.05 '.' 0.1 ' ' 1

Residual standard error: 1.396 on 4505 degrees of freedom

Multiple R-squared: 0.2517, Adjusted R-squared: 0.2514

F-statistic: 757.7 on 2 and 4505 DF, p-value: < 2.2e-16

As the residuals are very spread out we check that there's no outliers by running the Breusch-Pagan test. The Breusch-Pagan test for homoscedasticity is designed to assess the presence of heteroscedasticity in a regression model. The null hypothesis ( $H_0$ ) of the test is that the variance of the errors ( $\sigma_i^2$ ) is constant across observations, implying homoscedasticity ( $\sigma_i^2 = \sigma^2$ ). The alternative hypothesis ( $H_1$ ) suggests the existence of a relationship between the variance of the errors and one or more explanatory variables

$$\sigma_i^2 = f(\gamma + \delta Z) \quad (2)$$

where  $Z$  could be any subset of the explanatory variables in the model, their transformations, or even different variables not included in the regression model.

```
[32]: bptest(model)
```

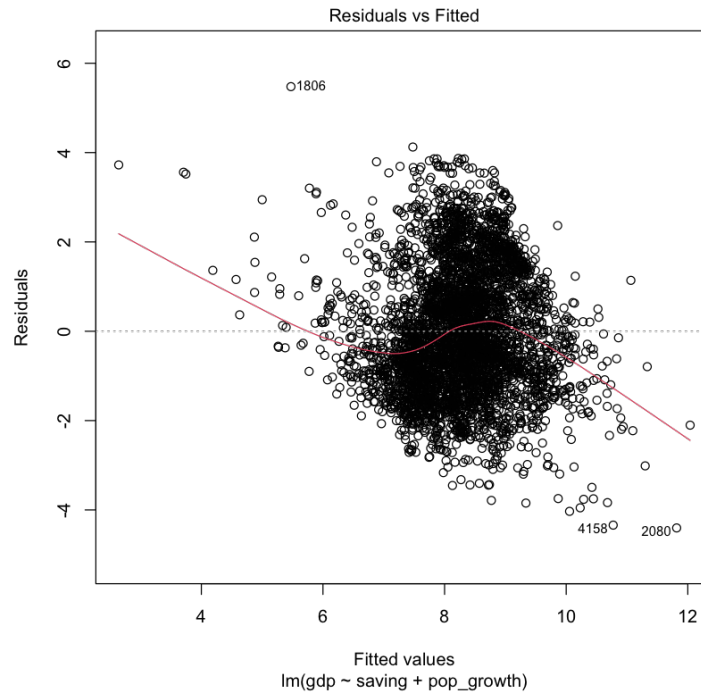
studentized Breusch-Pagan test

data: model

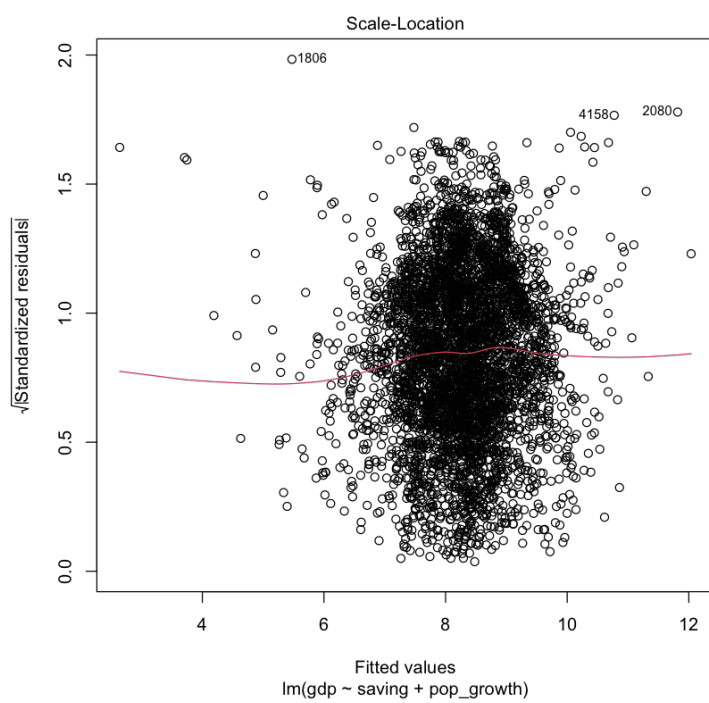
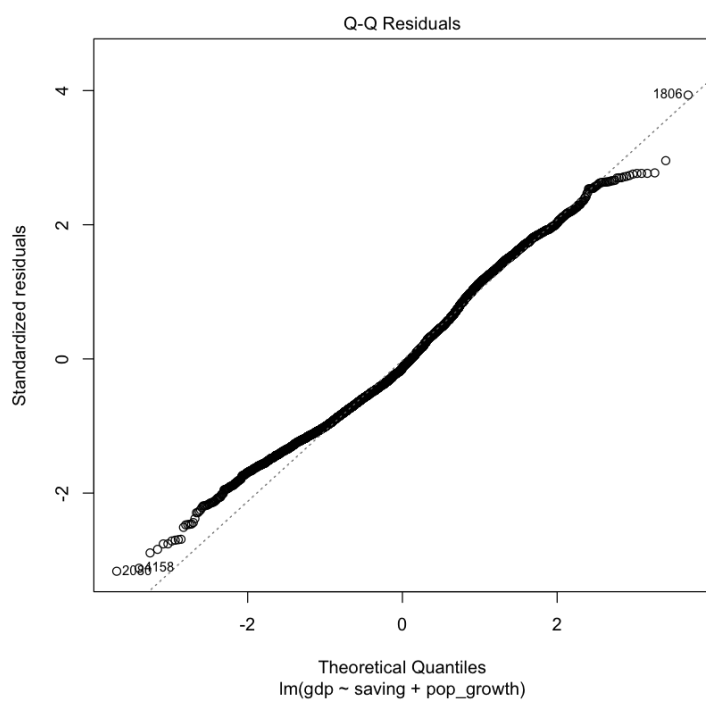
BP = 125.53, df = 2, p-value < 2.2e-16

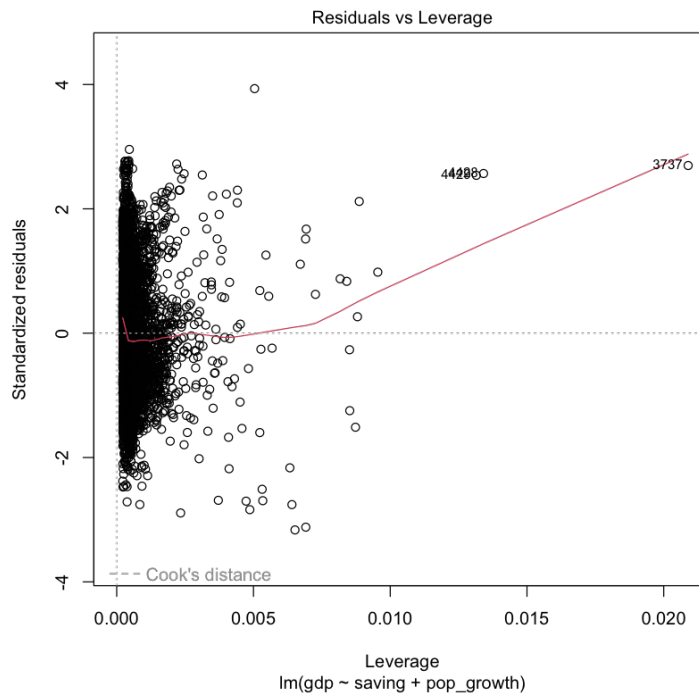
As the null hypothesis is rejected, we plot the model to understand what may be causing the problem

```
[33]: plot(model)
```









The spread observed in both the Residuals vs Fittedplot and Scale Locationplot follow what we observed in the scatter plot of GDP and Savings.

For this reason we change the model to

$\log(gdp) = \log(co2\ emissions) + \log(fertility) + political\ stability + \log(research) + \log(population\ growth)$

Accounting for the dummy variables created

```
[34]: model <- lm(gdp ~ co2_emission + fertility + pol_stability + research +  
  ↪pop_growth + dummy_F + dummy_PF + dummy_60_plus + dummy_30_60, data =  
  ↪data_regression)
```

Now we check the summary of the model and run again the BP Test

```
[35]: summary(model)  
bptest(model)
```

Call:

```
lm(formula = gdp ~ co2_emission + fertility + pol_stability +  
  research + pop_growth + dummy_F + dummy_PF + dummy_60_plus +  
  dummy_30_60, data = data_regression)
```

Residuals:

Min	1Q	Median	3Q	Max
-3.1681	-0.4047	0.0662	0.4601	3.3950

Coefficients:

	Estimate	Std. Error	t value	Pr(> t )	
(Intercept)	8.3503332	0.0677577	123.238	< 2e-16	***
co2_emission	0.5379689	0.0119790	44.909	< 2e-16	***
fertility	-0.6604054	0.0450969	-14.644	< 2e-16	***
pol_stability	0.0085936	0.0006652	12.919	< 2e-16	***
research	0.2851603	0.0149724	19.046	< 2e-16	***
pop_growth	0.1404303	0.0143011	9.820	< 2e-16	***
dummy_F	0.3218108	0.0360009	8.939	< 2e-16	***
dummy_PF	0.1571861	0.0322934	4.867	1.17e-06	***
dummy_60_plus	0.3663217	0.0718106	5.101	3.51e-07	***
dummy_30_60	-0.1595034	0.0309982	-5.146	2.78e-07	***

---

Signif. codes: 0 '\*\*\*' 0.001 '\*\*' 0.01 '\*' 0.05 '.' 0.1 ' ' 1

Residual standard error: 0.7425 on 4498 degrees of freedom

Multiple R-squared: 0.7886, Adjusted R-squared: 0.7882

F-statistic: 1864 on 9 and 4498 DF, p-value: < 2.2e-16

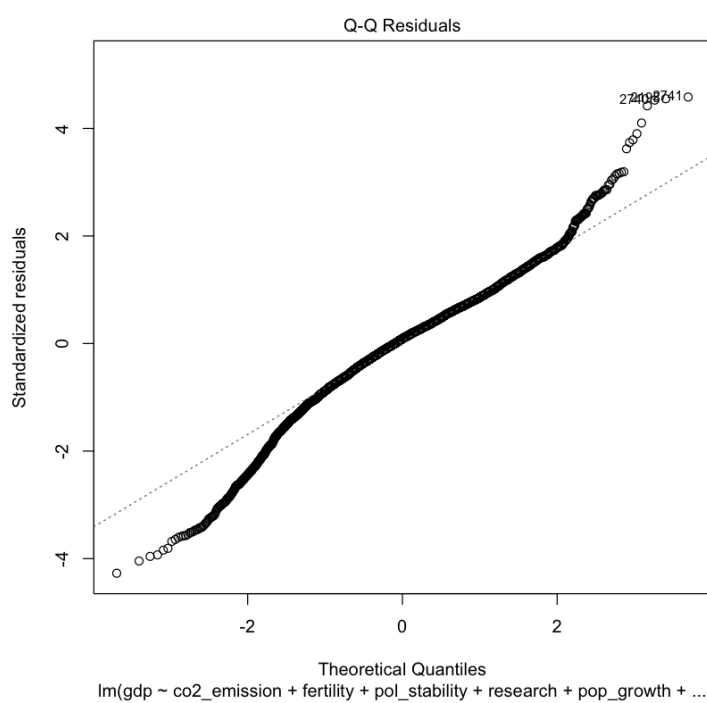
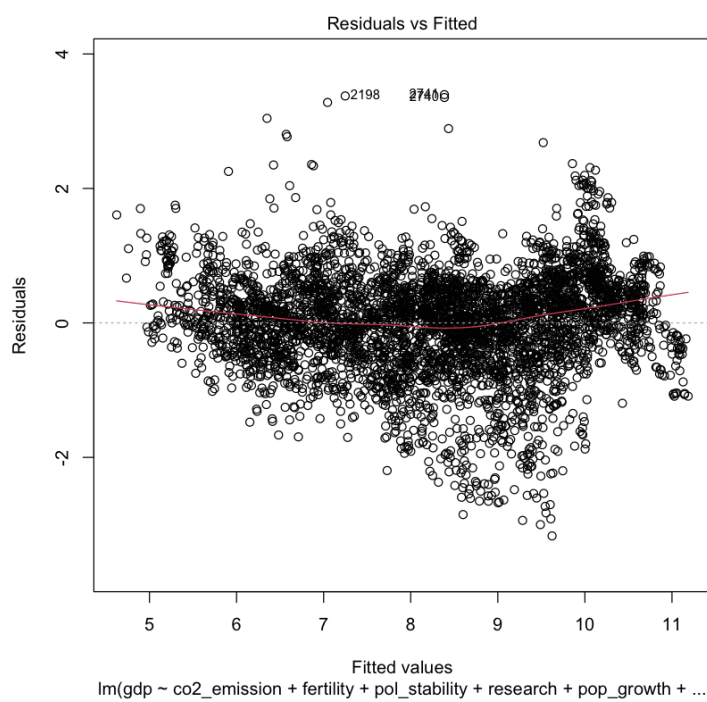
studentized Breusch-Pagan test

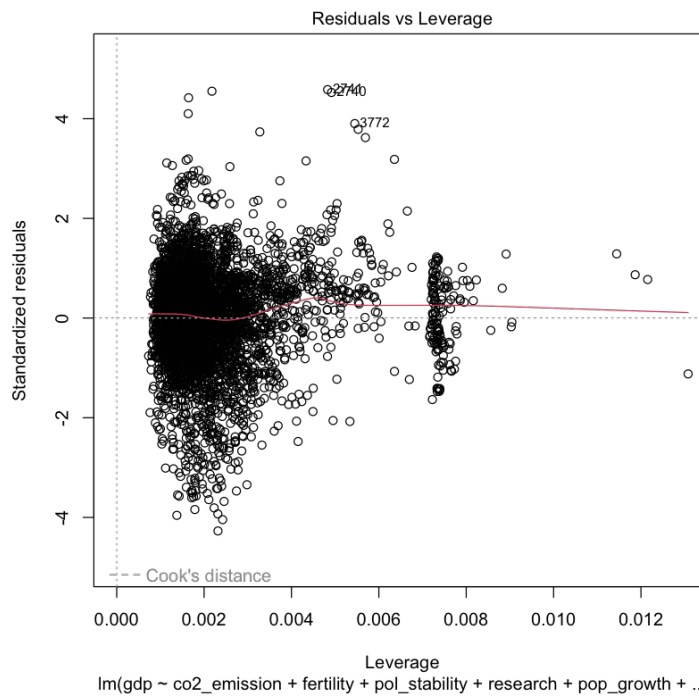
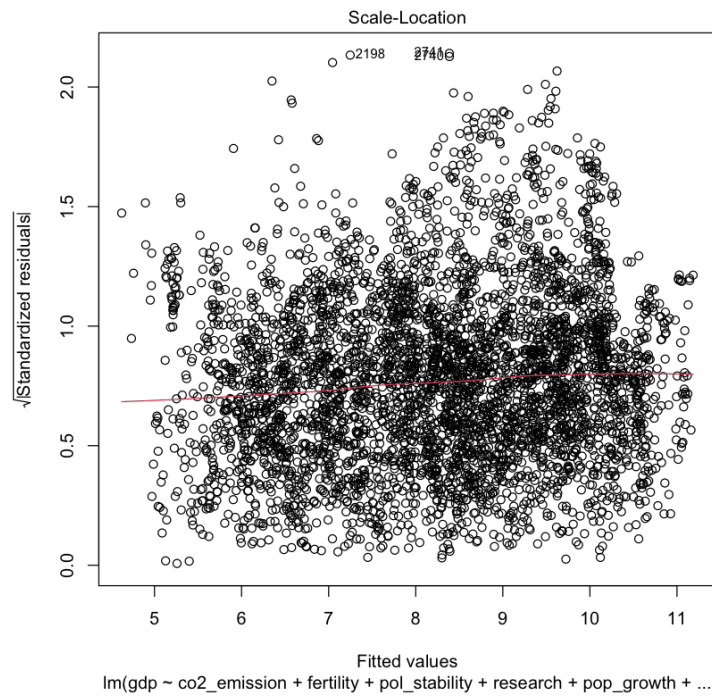
data: model

BP = 283.92, df = 9, p-value < 2.2e-16

The null hypothesis is still rejected, however all chosen parameters are statistically significant, and the residuals are less spread out. We once again plot the residuals to check what the problem might be

```
[36]: plot(model)
```

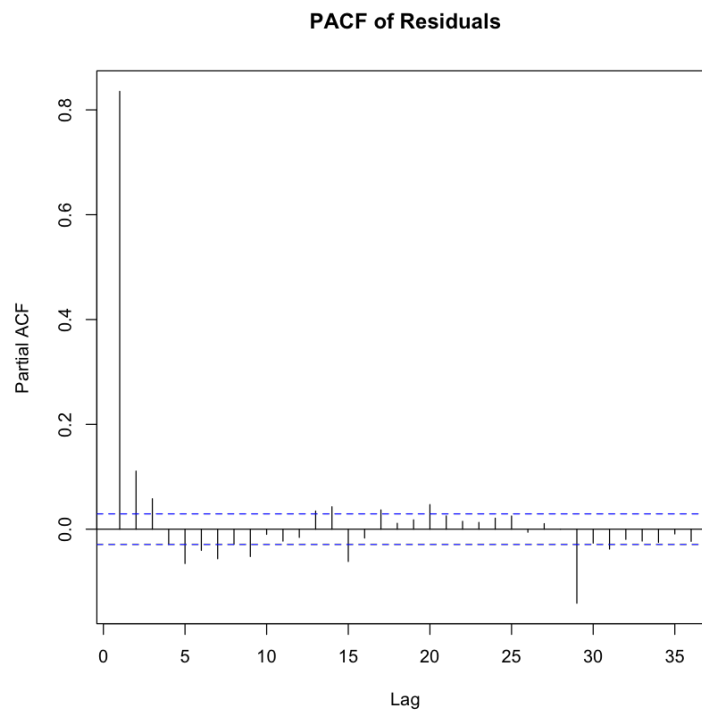
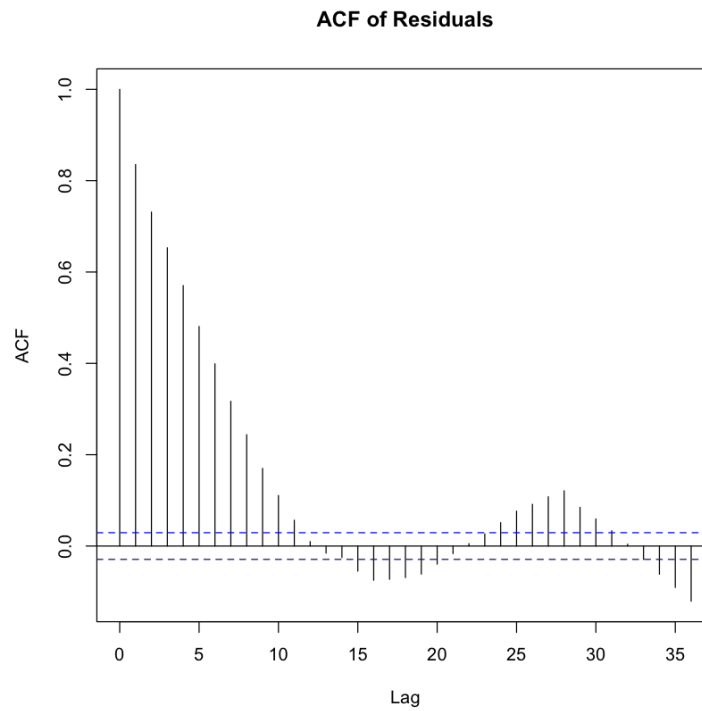




From the **Residuals vs Fitted** we can see that there's a slight correlation and from the Q-Q plot we can see that the residuals diverge from a normal distribution.

As we fear that there may be some autocorrelation between the errors, we check the plot of the ACF (autocorrelation function) and PACF (partial autocorrelation function)

```
[37]: residuals <- residuals(model)
      acf(residuals, main="ACF of Residuals")
      pacf(residuals, main="PACF of Residuals")
```



As there seems to be significant correlation, we now move to use the Ljung-Box Q-test to check for

autocorrelation in the residuals at different lags collectively, not just individually. The Ljung-Box test's primary purpose is to test the null hypothesis that the autocorrelations of the series up to lag  $k$  are all zero (i.e., there is no autocorrelation in the series). The test statistic for the Ljung-Box test is defined as:

$$Q = n(n+2) \sum_{k=1}^h \frac{\hat{\rho}_k^2}{n-k} \quad (3)$$

where:

- $n$  is the sample size (number of observations in the time series),
- $h$  is the number of lags being tested, -  $\hat{\rho}_k$  is the estimated autocorrelation at lag  $k$
- $Q$  is the test statistic.

The test is applied to residuals of a model to check whether the model has left any autocorrelation structure unmodeled. If the null hypothesis is not rejected, it suggests that the model has successfully captured the time-dependent structure of the data.

```
[38]: Box.test(residuals, type = "Ljung-Box")
```

Box-Ljung test

```
data: residuals
X-squared = 3148, df = 1, p-value < 2.2e-16
```

As the p-value is close to 0, we reject the hypothesis that there's no autocorrelation. For this reason we decided it was best to move away from an OLS model.

## 1.5 Generalised Least Squared Model

As the model with new predictors is still heteroskedastic, due to autocorrelation, we decided it was best to use a Generalized Least Squares model. Unlike OLS, GLS acknowledges that the variance of the error terms may not be constant (heteroscedasticity) or that errors may be correlated over time or across observations (autocorrelation). To address these issues, GLS transforms the original model using a provided variance-covariance matrix of the errors, leading to accurate and unbiased estimators even in the presence of heteroscedasticity. This approach involves pre-multiplying the model by the inverse square root of the variance-covariance matrix to produce homoscedastic and uncorrelated error terms, allowing the application of OLS to this transformed model. The transformed model's estimators, obtained through OLS, are the GLS estimators for the original model, providing more reliable coefficient estimates under the specific violations of OLS assumptions.

As there is autocorrelation within the model, we decided to use an autoregressive of order 1 correlation structure (`corAR1`). The intuition is that each observation is correlated to its preceding observation, implying that the current value can be partly predicted by its immediate past value. Mathematically, the variance-covariance matrix  $\Sigma$  can be seen as:

$$\Sigma = (X^T W^{-1} X)^{-1} X^T W^{-1} V W^{-1} X (X^T W^{-1} X)^{-1} \quad (4)$$

Where:

- $X$  is the matrix of independent variables, so in our case intercept, corruption, co2 emission, research, fertility and population growth
- $W$  is a diagonal weight matrix used to account for heteroscedasticity, in this case  $W = \sigma^2 \cdot I$
- $V$  represents the covariance matrix that models the correlation between the observations. For `corAR1`, this correlation is modeled as decaying exponentially with the distance between observations, which is parameterized by the correlation coefficient  $\rho$ . Mathematically:

$$\rho(y_i, y_j) = \rho^{|i-j|} \quad (5)$$

```
[39]: gls_model <- gls(gdp ~ pol_stability + co2_emission + research + fertility +
  ↪ pop_growth + dummy_F + dummy_PF + dummy_30_60 + dummy_60_plus,
  data = data_regression,
  corr = corAR1(),
  control = glsControl(
    maxIter = 1000,
    msMaxIter = 100,
    returnObject = TRUE,
    tolerance = 1e-6,
    msTol = 1e-6
  ),
  verbose = TRUE
)
```

We now check the summary of the model

```
[40]: summary(gls_model)
```

Generalized least squares fit by REML

```
Model: gdp ~ pol_stability + co2_emission + research + fertility + pop_growth +
  ↪ dummy_F + dummy_PF + dummy_30_60 + dummy_60_plus
```

Data: data\_regression

AIC	BIC	logLik
3570.465	3647.401	-1773.232

Correlation Structure: AR(1)

Formula: ~1

Parameter estimate(s):

Phi
0.9144551

Coefficients:

	Value	Std.Error	t-value	p-value
(Intercept)	9.216946	0.09928995	92.82860	0.0000



pol_stability	0.004938	0.00058547	8.43428	0.0000
co2_emission	0.224587	0.01279419	17.55381	0.0000
research	0.058513	0.01105590	5.29245	0.0000
fertility	-1.329224	0.05232644	-25.40253	0.0000
pop_growth	0.002456	0.01034193	0.23749	0.8123
dummy_F	0.251617	0.04208140	5.97929	0.0000
dummy_PF	0.023927	0.03201914	0.74727	0.4549
dummy_30_60	-0.205493	0.05258678	-3.90769	0.0001
dummy_60_plus	0.789015	0.12016880	6.56589	0.0000

Correlation:

	(Intr)	pl_stb	c2_mss	resrch	frtlty	pp_grw	dmmy_F	dmm_PF	d_30_6
pol_stability	-0.275								
co2_emission	-0.242	-0.117							
research	0.120	-0.074	-0.001						
fertility	-0.674	0.070	0.430	0.090					
pop_growth	0.089	0.037	-0.049	0.000	-0.222				
dummy_F	-0.235	-0.236	-0.072	-0.084	0.127	-0.010			
dummy_PF	-0.218	-0.085	0.102	0.130	0.097	0.010	0.576		
dummy_30_60	-0.419	0.053	-0.054	-0.133	0.402	0.060	-0.073	-0.075	
dummy_60_plus	-0.133	-0.044	-0.068	-0.136	0.124	-0.022	-0.094	-0.035	0.278

Standardized residuals:

	Min	Q1	Med	Q3	Max
	-3.49264276	-0.60845157	-0.03293112	0.58357503	4.15505714

Residual standard error: 0.8810338

Degrees of freedom: 4508 total; 4498 residual

How to interpret the output:

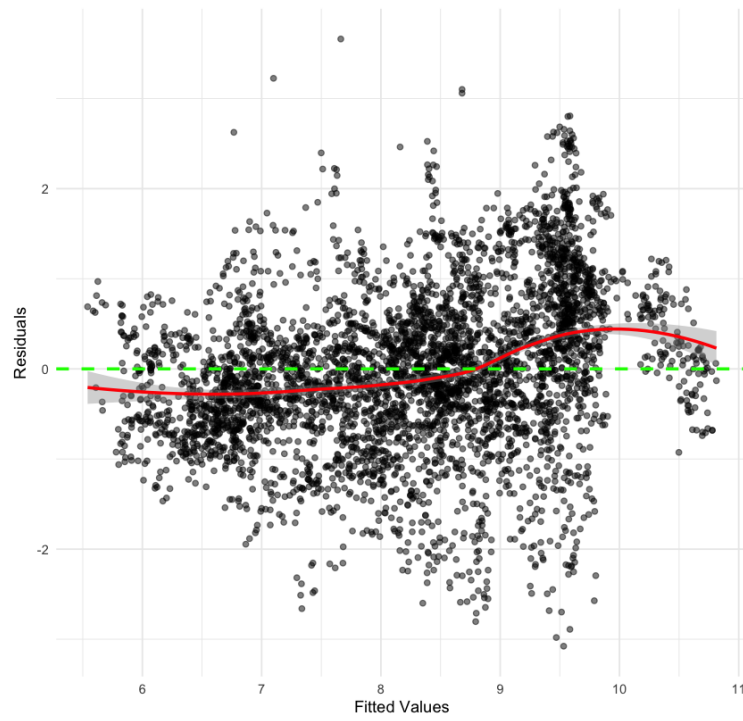
- Generalized least squares fit by REML” - The model was fitted using the Restricted Maximum Likelihood method
- “Model” - The model used
- “AIC” - Akaike Information Criterion, a measure of the model quality that balances model fit and complexity. Lower values are better
- “BIC” - Bayesian Information Criterion, similar to AIC but with a stronger penalty for model complexity. Lower values are better
- “logLik” - The log-likelihood of the model, a measure of how well the model fits the data. Higher values are better
- “Correlation Structure”: type of correlation used
- Parameter estimate(s) - range: The estimated range parameter for the correlation structure
- “Coefficients” - Same as simple lm except that the indicators of significance aren’t present
- “Correlation” - Shows the correlation between the predictors

- “Standardized residuals” - The residuals of the model, which are the differences between the observed and predicted values of the dependent variable, standardized by the standard deviation of the residuals
- “Residual standard error” - The standard deviation of the residuals, a measure of the model’s accuracy. Lower values are better
- “Degrees of freedom” - The number of observations minus the number of parameters in the model

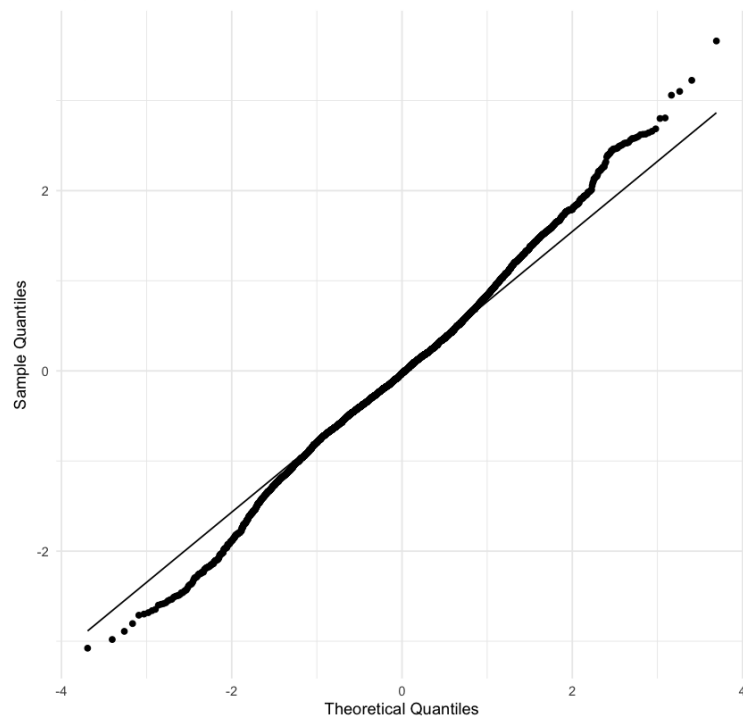
To check if we have removed the problem of heteroskedasticity, we will plot the residuals of the model, as the Breusch-Pagan Test is not available for GLS models

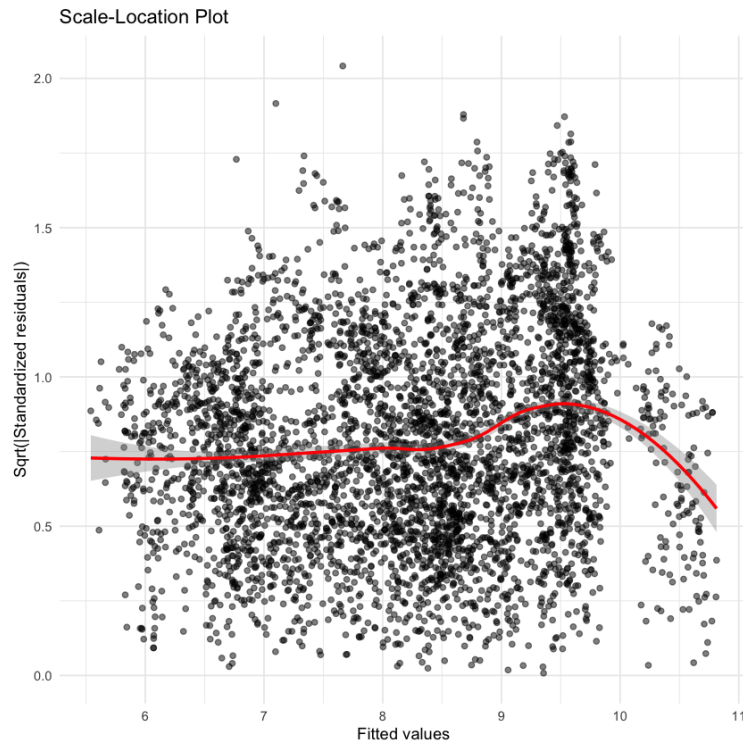
```
[41]: data_for_ggplot <- data.frame(
  Fitted = fitted(gls_model),
  Residuals = residuals(gls_model)
)
ggplot(data_for_ggplot, aes(x = Fitted, y = Residuals)) +
  geom_point(alpha = 0.5) +
  geom_smooth(aes(y = Residuals), method = "loess", formula = 'y ~ x', color = "red") +
  geom_hline(yintercept = 0, color = "green", linetype = "dashed", size = 1) +
  labs(x = "Fitted Values", y = "Residuals", title = "Fitted vs. Residuals") +
  theme_minimal()
ggplot(mapping = aes(sample = residuals(gls_model))) +
  stat_qq() +
  stat_qq_line() +
  labs(title = "QQ Plot of Residuals", x = "Theoretical Quantiles", y = "Sample Quantiles") +
  theme_minimal()
std_resid <- resid(gls_model, type = "pearson") / sd(resid(gls_model, type = "pearson"))
data_for_plot <- data.frame(
  Fitted = fitted(gls_model),
  SqrtAbsStdResid = sqrt(abs(std_resid))
)
ggplot(data_for_plot, aes(x = Fitted, y = SqrtAbsStdResid)) +
  geom_point(alpha = 0.5) +
  geom_smooth(aes(y = SqrtAbsStdResid), method = "loess", formula = 'y ~ x', color = "red") +
  labs(x = "Fitted values", y = "Sqrt(|Standardized residuals|)", title = "Scale-Location Plot") +
  theme_minimal()
```

Fitted vs. Residuals



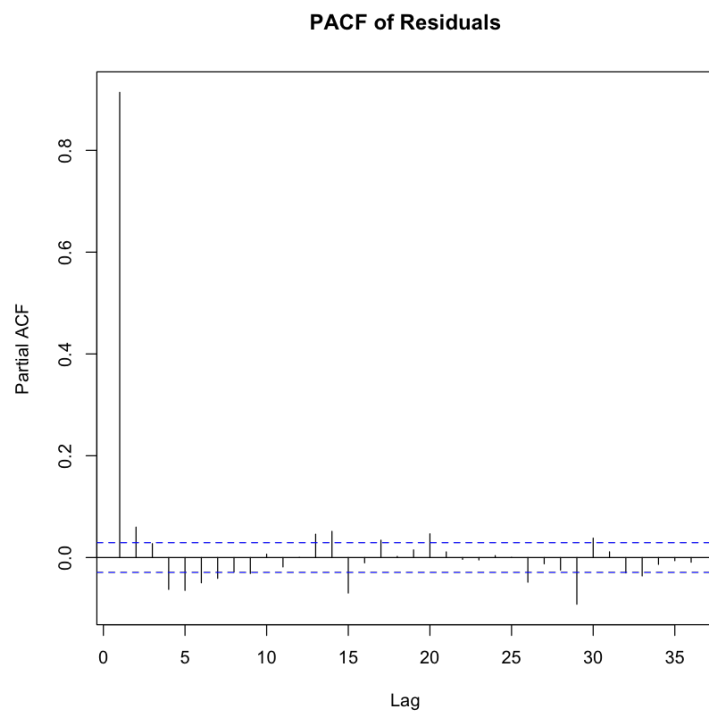
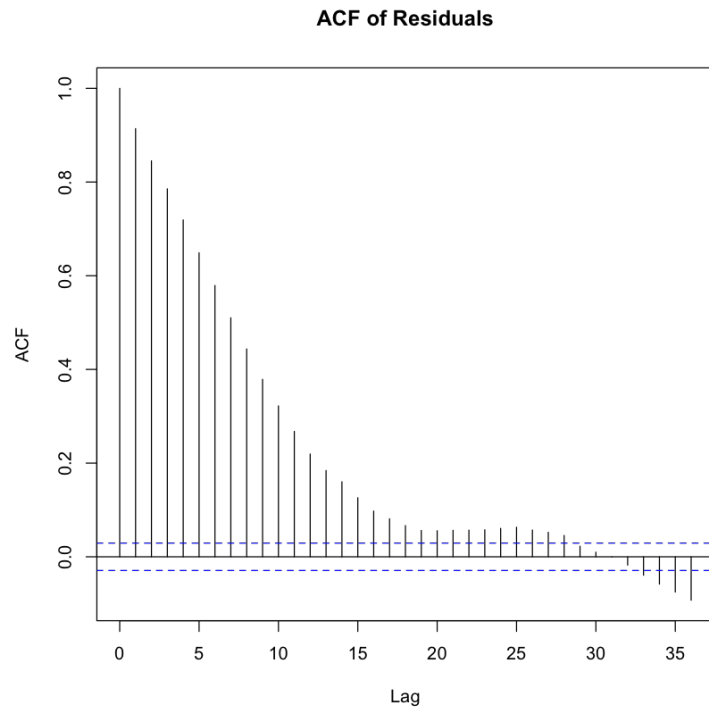
QQ Plot of Residuals





The model is quite better than the OLS one, with quite a lot of improvement on the distribution of the errors, although there's some amount of heteroskedasticity not explained by the current model, with errors following a rather unusual patterns, as demonstrated by the Scale-Location plot and the Fitted against Residual Plot. For this reason, we check whether our model is able to catch all the autocorrelation we observed in the OLS model.

```
[42]: residuals <- residuals(gls_model)
      acf(residuals, main="ACF of Residuals")
      pacf(residuals, main="PACF of Residuals")
```



```
[43]: Box.test(residuals, type = "Ljung-Box")
```

Box-Ljung test

```
data: residuals
X-squared = 3768.5, df = 1, p-value < 2.2e-16
```

From the Ljung-Box Q-test test, it is clear that we need a better model. From the summary, we can see that population growth and the dummy variable for the Partially Free countries are not significant, we will drop them.

Furthermore, as there seems to be a correlation between fertility, CO2 Emissions and the dummy for countries between 30 and 60 degrees of latitude from the equator, we will decorrelate them, using as a predictor the residuals of the following model:

$$fertility = \beta_0 + \beta_1 \cdot \text{Dummy for distance from equator} + \beta_2 \cdot \text{CO2 Emission}$$

```
[34]: decorr_model <- lm(fertility ~ dummy_30_60 + co2_emission, data = data_regression)
      data_regression$decorr_fertility <- residuals(decorr_model)
```

We now try to fit another GLS model, this time trying to also model the variance of the error terms changes as a power function of the fitted values. Mathematically:

$$W_{i,i} = |\hat{y}_i|^\theta \quad (6)$$

Where  $\hat{y}_i$  is the fitted value of the  $i$ th observation and  $\theta$  is estimated by the model

```
[45]: gls_model_2 <- gls(gdp ~ pol_stability + co2_emission + research + dummy_F + dummy_30_60 + dummy_60_plus + decorr_fertility,
  data = data_regression,
  corr = corAR1(),
  weights = varPower(form = ~fitted(.)),
  control = glsControl(
    maxIter = 1000,
    msMaxIter = 100,
    returnObject = TRUE,
    tolerance = 1e-6,
    msTol = 1e-6
  ),
  verbose = TRUE
)
```

We once again check the summary, and plot the residuals to check whether heteroskedasticity is still present

```
[46]: summary(gls_model_2)
```

Generalized least squares fit by REML

```
Model: gdp ~ pol_stability + co2_emission + research + dummy_F + dummy_30_60 + dummy_60_plus + decorr_fertility
Data: data_regression
      AIC      BIC    logLik
```

3556.71 3627.24 -1767.355

Correlation Structure: AR(1)

Formula: ~1

Parameter estimate(s):

Phi

0.9144376

Variance function:

Structure: Power of variance covariate

Formula: ~fitted(.)

Parameter estimates:

power

0.01070032

Coefficients:

	Value	Std.Error	t-value	p-value
(Intercept)	7.637016	0.07155278	106.73262	0e+00
pol_stability	0.004958	0.00058248	8.51209	0e+00
co2_emission	0.488707	0.01242834	39.32202	0e+00
research	0.057313	0.01095593	5.23122	0e+00
dummy_F	0.233378	0.03437766	6.78864	0e+00
dummy_30_60	0.186288	0.04774464	3.90175	1e-04
dummy_60_plus	0.792647	0.12031890	6.58788	0e+00
decorr_fertility	-1.331481	0.05073539	-26.24363	0e+00

Correlation:

	(Intr)	pl_stb	c2_mss	resrch	dmmy_F	d_30_6	dm_60_
pol_stability	-0.336						
co2_emission	0.110	-0.184					
research	0.275	-0.064	-0.080				
dummy_F	-0.111	-0.230	-0.235	-0.196			
dummy_30_60	-0.248	0.021	-0.321	-0.162	-0.065		
dummy_60_plus	-0.084	-0.047	-0.170	-0.133	-0.091	0.266	
decorr_fertility	-0.057	0.090	-0.378	0.080	0.085	0.169	0.127

Standardized residuals:

	Min	Q1	Med	Q3	Max
	-3.48044113	-0.60793526	-0.03313992	0.58655835	4.17418388

Residual standard error: 0.8612087

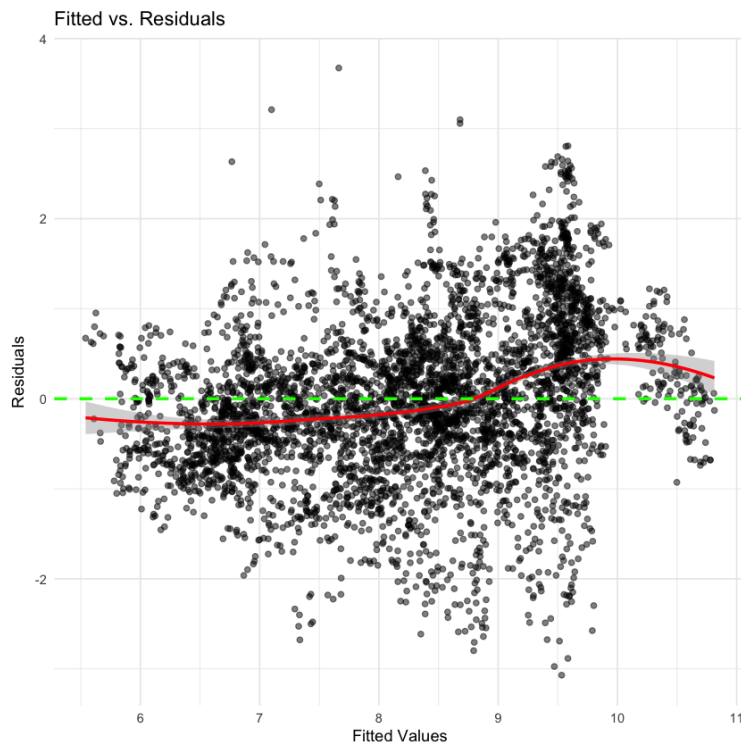
Degrees of freedom: 4508 total; 4500 residual

```
[47]: data_for_ggplot <- data.frame(  
  Fitted = fitted(gls_model),  
  Residuals = residuals(gls_model_2)  
)  
ggplot(data_for_ggplot, aes(x = Fitted, y = Residuals)) +
```

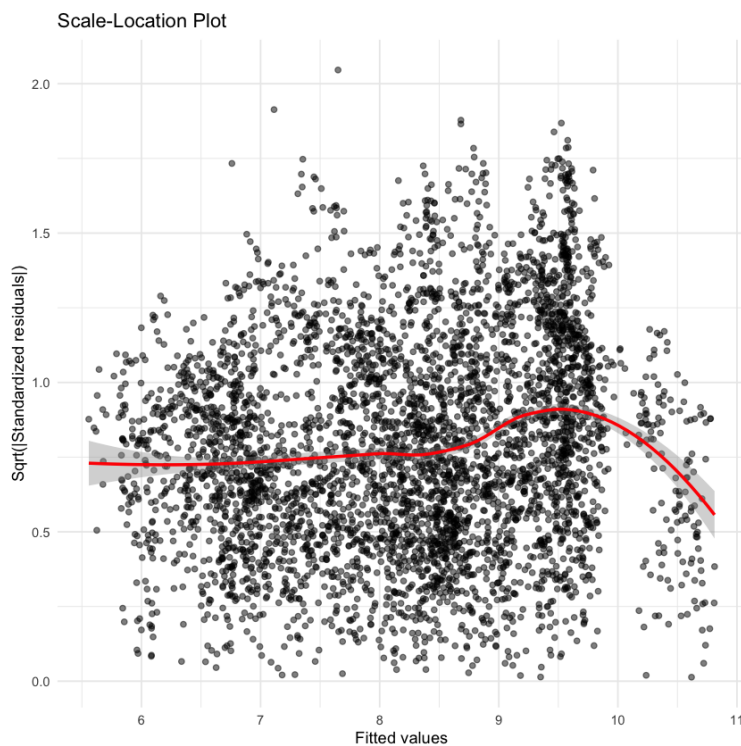
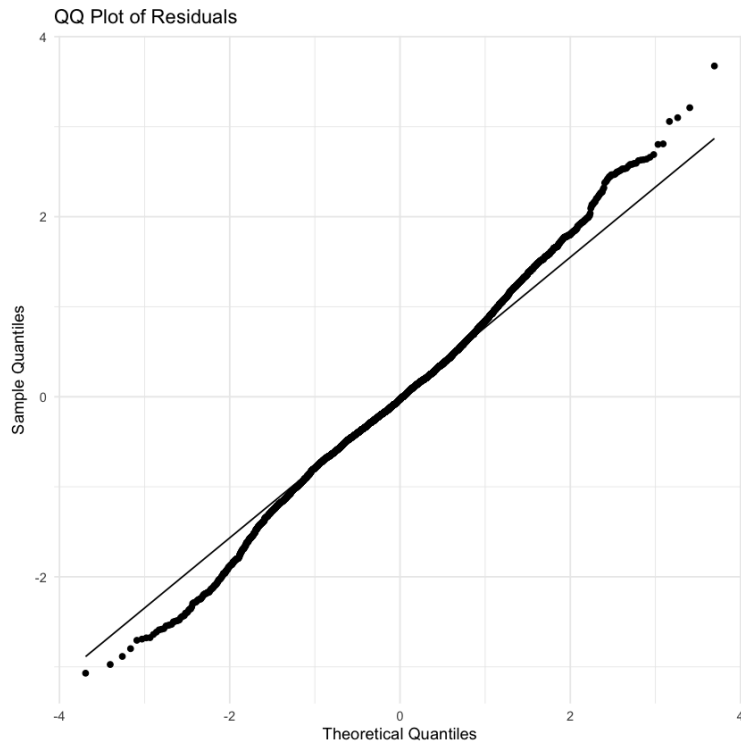
```

geom_point(alpha = 0.5) +
geom_smooth(aes(y = Residuals), method = "loess", formula = 'y ~ x', color = "red") +
geom_hline(yintercept = 0, color = "green", linetype = "dashed", size = 1) +
labs(x = "Fitted Values", y = "Residuals", title = "Fitted vs. Residuals") +
theme_minimal()
ggplot(mapping = aes(sample = residuals(gls_model_2))) +
stat_qq() +
stat_qq_line() +
labs(title = "QQ Plot of Residuals", x = "Theoretical Quantiles", y = "Sample Quantiles") +
theme_minimal()
std_resid <- resid(gls_model_2, type = "pearson") / sd(resid(gls_model_2, type = "pearson"))
data_for_plot <- data.frame(
  Fitted = fitted(gls_model_2),
  SqrtAbsStdResid = sqrt(abs(std_resid))
)
ggplot(data_for_plot, aes(x = Fitted, y = SqrtAbsStdResid)) +
geom_point(alpha = 0.5) +
geom_smooth(aes(y = SqrtAbsStdResid), method = "loess", formula = 'y ~ x', color = "red") +
labs(x = "Fitted values", y = "Sqrt(|Standardized residuals|)", title = "Scale-Location Plot") +
theme_minimal()

```

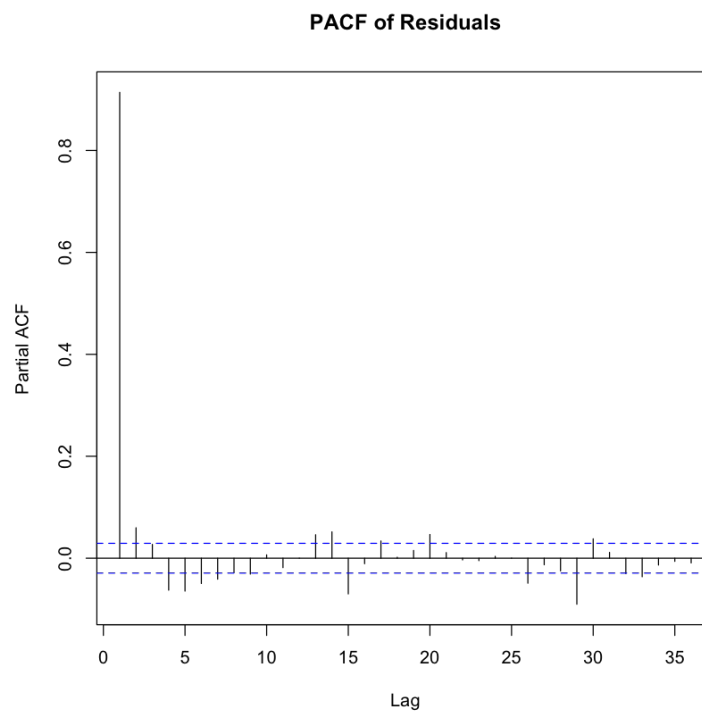
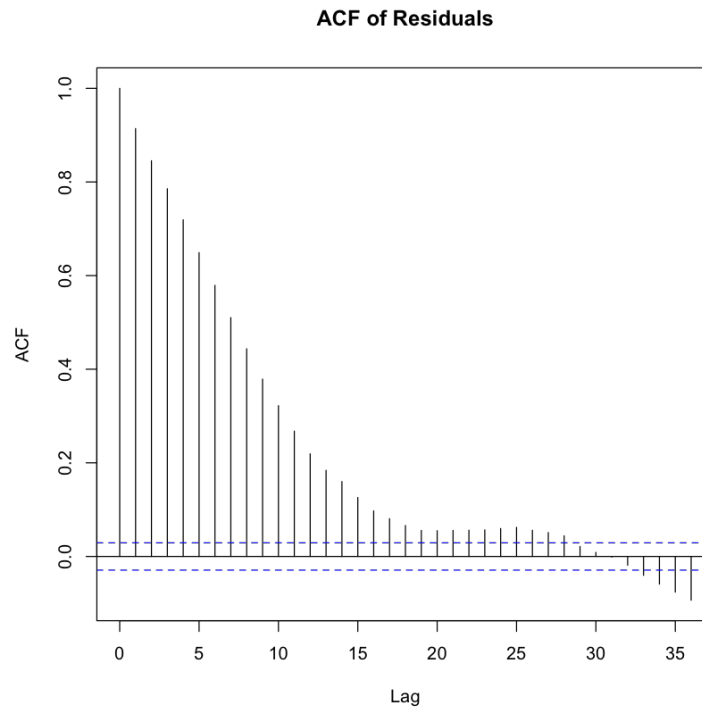






As the model hasn't quite improved, we now move on to test whether autocorrelation is still present

```
[48]: residuals <- residuals(gls_model_2)
      acf(residuals, main="ACF of Residuals")
      pacf(residuals, main="PACF of Residuals")
```



```
[49]: Box.test(residuals, type = "Ljung-Box")
```

Box-Ljung test

```
data: residuals
X-squared = 3768.9, df = 1, p-value < 2.2e-16
```

As the autocorrelation is still there, we choose to move to another model, built just to handle autocorrelation

## 1.6 AutoRegressive Integrated Moving Average with eXogenous variables

Given the limitations observed in the GLS approach for addressing all forms of autocorrelation, we try using an AutoRegressive Integrated Moving Average with eXogenous variables (ARIMAX) model. This model extends the ARIMA (AutoRegressive Integrated Moving Average) framework by incorporating external (exogenous) variables into the equation. The ARIMAX model is constructed as follows:

- AR (AutoRegressive): models the current value of the series as a function of its previous values. The autoregressive part indicates that the evolving variable of interest is regressed on its own lagged values.
- I (Integrated): deals with differencing the observational data to achieve stationarity, although in our case, as we will see, the data is already stationary
- MA (Moving Average): captures the dependency between an observation and a residual error from a moving average model applied to lagged observations. It helps in smoothing out the series and addressing short-term correlations.
- X (Exogenous Variables): allows the ARIMAX model to account for the influence of outside factors on the time series of interest. These variables are not modeled within the time series dynamics but are considered additional inputs that impact the series.

Transitioning to an ARIMAX model facilitates a more nuanced understanding of time series data by allowing the incorporation of external factors that influence the series, alongside modeling the intricate autocorrelation patterns not adequately captured by GLS.

But first, we check for stationarity using the Augmented Dick Fuller Test (ADF), which is a statistical test used to determine whether a time series is stationary, specifically whether it has a unit root, which is indicative of non-stationarity. The ADF test is a hypothesis test where the null hypothesis ( $H_0$ ) says that the time series has a unit root (and is thus non-stationary). The alternative hypothesis ( $H_1$ ) suggests that the time series does not have a unit root, implying it is stationary or can be made stationary through differencing.

```
[50]: adf.test(data_regression$gdp)
      adf.test(data_regression$pol_stability)
      adf.test(data_regression$co2_emission)
      adf.test(data_regression$research)
      adf.test(data_regression$decorr_fertility)
```

### Augmented Dickey-Fuller Test

```
data: data_regression$gdp
Dickey-Fuller = -9.8752, Lag order = 16, p-value < 0.01
```

alternative hypothesis: stationary

#### Augmented Dickey-Fuller Test

```
data: data_regression$pol_stability
Dickey-Fuller = -10.723, Lag order = 16, p-value < 0.01
alternative hypothesis: stationary
```

#### Augmented Dickey-Fuller Test

```
data: data_regression$co2_emission
Dickey-Fuller = -10.474, Lag order = 16, p-value < 0.01
alternative hypothesis: stationary
```

#### Augmented Dickey-Fuller Test

```
data: data_regression$research
Dickey-Fuller = -9.9602, Lag order = 16, p-value < 0.01
alternative hypothesis: stationary
```

#### Augmented Dickey-Fuller Test

```
data: data_regression$decorr_fertility
Dickey-Fuller = -10.84, Lag order = 16, p-value < 0.01
alternative hypothesis: stationary
```

As the p-value is  $< 0.01$ , we reject the null hypothesis and know that the series is stationary, or can be made stationary. Now we move on to implementing the ARIMAX model, using `auto.arima`, which is a function of the forecast package that finds the best hyper-parameters  $p, q, d$  for a given model. An ARIMA model is described by three parameters,  $(p, d, q)$ , where:

- $p$  is the order of the autoregressive (AR) part,
- $d$  is the degree of differencing required to make the series stationary,
- $q$  is the order of the moving average (MA) part

The mathematical representation of an ARIMA model is:

$$\Phi(B)\Delta^d y_t = \delta + \theta(B)\epsilon_t \quad (7)$$

where:

- $y_t$  is the time series at time  $t$
- $B$  is the backshift operator, such that  $B^k y_t = y_{t-k}$

- $\Delta^d = (1B)^d$  represents the differencing operator to achieve stationarity,
- $\Phi(B) = 1\phi_1B\phi_2B^2 - \dots - \phi_pB^p$  is the AR polynomial of order  $p$ ,
- $\theta(B) = 1 + \theta_1B + \theta_2B^2 + \dots + \theta_qB^q$  is the MA polynomial of order  $q$
- $\delta$  is a constant (intercept term),
- $\epsilon_t$  is the error term, which is assumed to be white noise.

`auto.arima` also estimates the best lambda for the Box-Cox transformation, a transformation that was designed to stabilize the variance and make a dataset more closely conform to the assumption of normality. Mathematically, given a dataset  $y$  with  $y_i \geq 0 \forall i$  and parameter  $\lambda$ ,

$$y(\lambda) = \begin{cases} \frac{y^\lambda - 1}{\lambda} & \text{if } \lambda > 0 \\ \log(y) & \text{if } \lambda = 0 \end{cases}$$

```
[51]: gdp_ts <- ts(data_regression$gdp)
      exog_vars <- as.matrix(data_regression[, c("pol_stability", "co2_emission",
      ↪ "research", "dummy_F", "dummy_30_60", "dummy_60_plus", "decorr_fertility")])
      arimax_model <- auto.arima(gdp_ts, xreg = exog_vars, max.p = 7, max.q = 7, max.P
      ↪ = 7, max.Q = 7, max.order = 21, max.d = 7, max.D = 7, lambda = "auto")
      summary(arimax_model)
```

Series: gdp\_ts

Regression with ARIMA(1,0,1) errors

Box Cox transformation: lambda= -0.8451986

Coefficients:

	ar1	ma1	intercept	pol_stability	co2_emission	research
	0.9149	-0.0774	0.9657	1e-04	0.0123	8e-04
s.e.	0.0068	0.0166	0.0031	0e+00	0.0003	3e-04
	dummy_F	dummy_30_60	dummy_60_plus	decorr_fertility		
	0.0048	0.0018	0.0073	-0.0316		
s.e.	0.0008	0.0011	0.0027	0.0012		

sigma^2 = 6.507e-05: log likelihood = 15336.13

AIC=-30650.26 AICc=-30650.21 BIC=-30579.72

Training set error measures:

	ME	RMSE	MAE	MPE	MAPE	MASE
Training set	0.02038114	0.371539	0.1807438	0.0109281	2.273556	1.05521
	ACF1					
Training set	-0.03127374					

How to interpret the results:

- Series: it is the series the model is predicting, in this case gdp per capita
- Regression with ARIMA(p,d,q) errors: indicates the model being fitted

- Box Cox transformation:  $\lambda = n$ : indicates the  $\lambda$  used for the Box-Cox transformation
- Coefficients: Enumeration of coefficients and s.e.
- $\sigma^2$ : the variance of the errors
- log likelihood: The log of the likelihood function, a measure of model fit. The higher, the better
- AIC (Akaike Information Criterion), AICc (Corrected Akaike Information Criterion), and BIC (Bayesian Information Criterion) are measures used to compare models. Lower values suggest a better model fit, considering the trade-off between goodness of fit and complexity
- Training error measures: evaluate how well the model has performed on the training dataset

Now we check that all the parameters are statistically significant

```
[52]: coefficients <- coef(arimax_model)
var_coefficients <- summary(arimax_model)$var.coef
std_errors <- sqrt(diag(var_coefficients))
t_stats <- coefficients / std_errors
degrees_of_freedom <- length(residuals(arimax_model)) - length(coefficients) #L
  ↪degrees of freedom approximation
p_values <- 2 * pt(-abs(t_stats), df=degrees_of_freedom)
results <- data.frame(Coefficients = coefficients,
                      StdError = std_errors,
                      TStatistic = t_stats,
                      PValue = p_values)
print(results)
```

	Coefficients	StdError	TStatistic	PValue
ar1	9.148805e-01	6.785058e-03	134.837538	0.000000e+00
ma1	-7.740546e-02	1.660254e-02	-4.662265	3.218045e-06
intercept	9.657357e-01	3.068716e-03	314.703535	0.000000e+00
pol_stability	8.497375e-05	3.037885e-05	2.797135	5.177712e-03
co2_emission	1.228039e-02	2.891518e-04	42.470394	0.000000e+00
research	8.151699e-04	2.541598e-04	3.207313	1.349204e-03
dummy_F	4.820674e-03	7.785880e-04	6.191559	6.488404e-10
dummy_30_60	1.832892e-03	1.075666e-03	1.703960	8.845756e-02
dummy_60_plus	7.312241e-03	2.696310e-03	2.711944	6.714422e-03
decorr_fertility	-3.163406e-02	1.152313e-03	-27.452668	1.556455e-153

As all the coefficients are significant at the 0.05 level, we will move on to plot the model

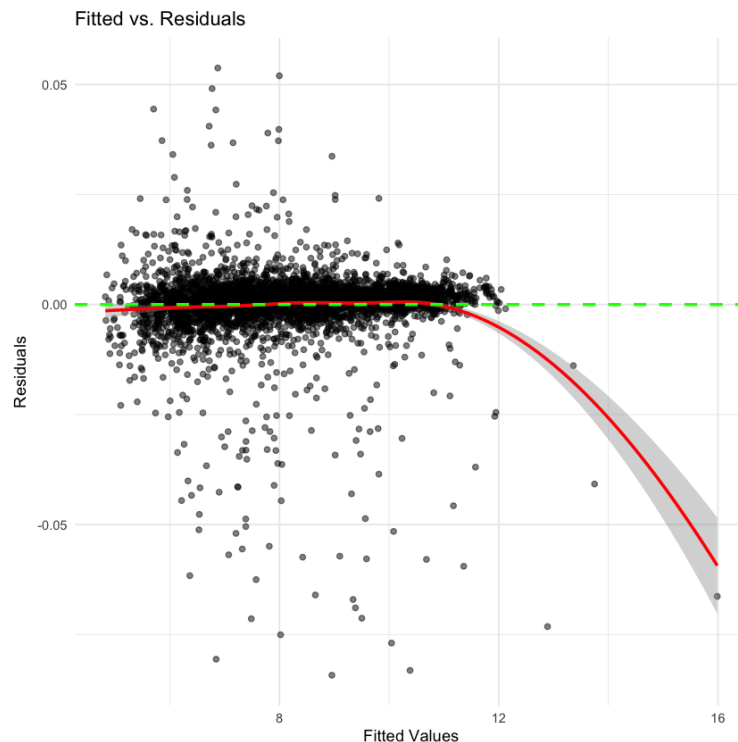
```
[53]: data_for_ggplot <- data.frame(
  Fitted = fitted(arimax_model),
  Residuals = residuals(arimax_model)
)
ggplot(data_for_ggplot, aes(x = Fitted, y = Residuals)) +
  geom_point(alpha = 0.5) +
```

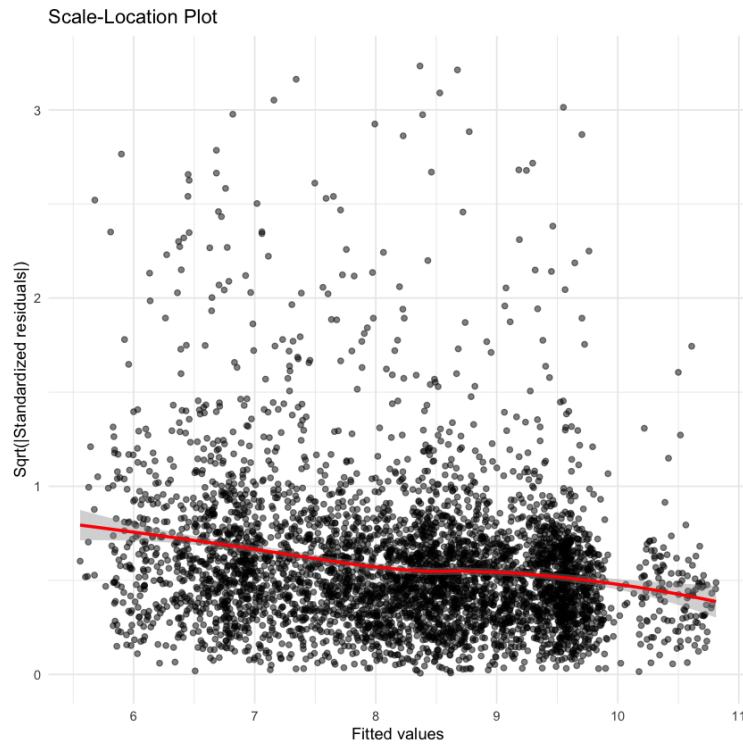
```

geom_smooth(aes(y = Residuals),
             method = "loess",
             formula = "y ~ x",
             color = "red"
) +
geom_hline(yintercept = 0, color = "green", linetype = "dashed", size = 1) +
labs(x = "Fitted Values", y = "Residuals", title = "Fitted vs. Residuals") +
theme_minimal()
std_resid <- resid(arimax_model) / sd(resid(arimax_model))
data_for_plot <- data.frame(
  Fitted = fitted(gls_model_2),
  SqrtAbsStdResid = sqrt(abs(std_resid))
)

ggplot(data_for_plot, aes(x = Fitted, y = SqrtAbsStdResid)) +
  geom_point(alpha = 0.5) +
  geom_smooth(aes(y = SqrtAbsStdResid),
             method = "loess",
             formula = "y ~ x",
             color = "red"
) +
  labs(x = "Fitted values",
       y = "Sqrt(|Standardized residuals|)",
       title = "Scale-Location Plot"
) +
  theme_minimal()

```

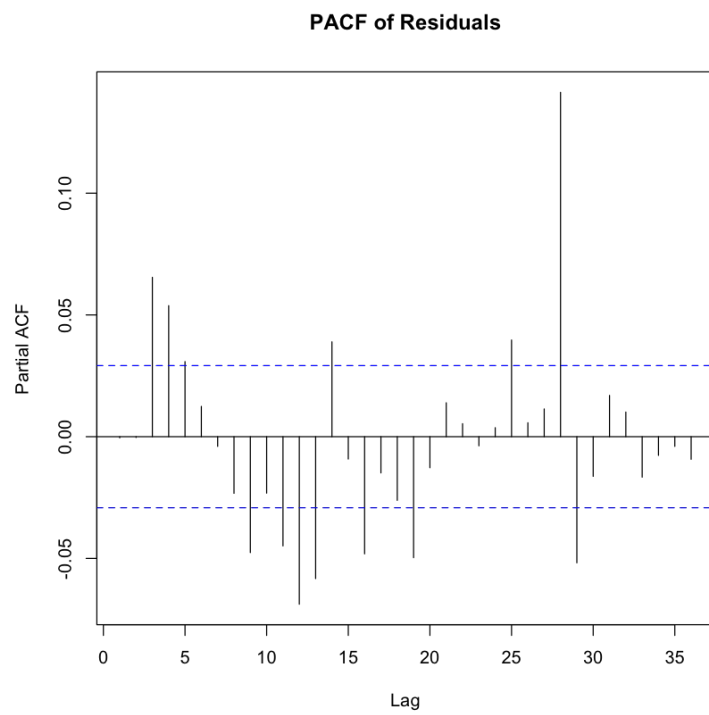
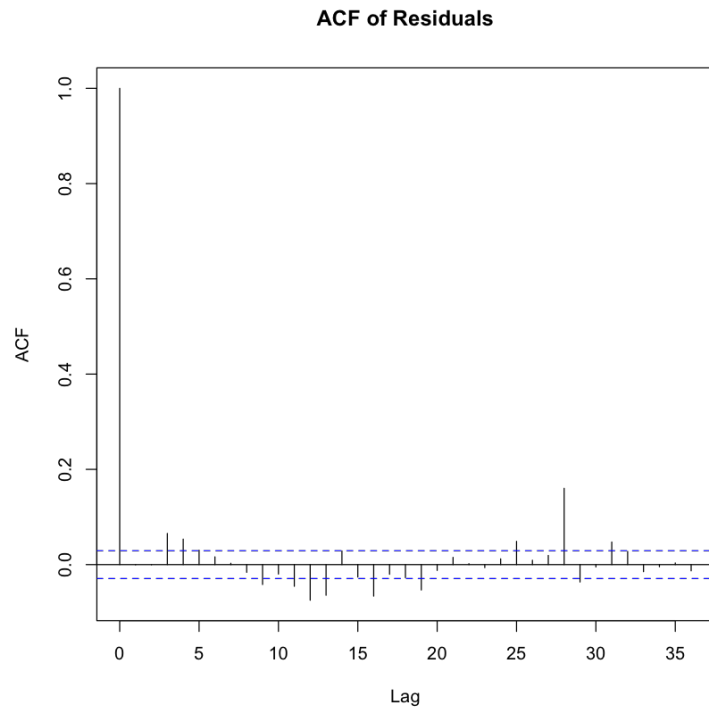




As the model is exceedingly close to having no errors, we plot the ACF and PACF, and run the Ljung-Box Q-test to ensure that no autocorrelation is present

```
[54]: residuals <- residuals(arimax_model)
      acf(residuals, main = "ACF of Residuals")
      pacf(residuals, main = "PACF of Residuals")
```





```
[55]: Box.test(residuals, type = "Ljung-Box")
```

Box-Ljung test

```
data: residuals
X-squared = 0.0010359, df = 1, p-value = 0.9743
```

The errors of the model are negligible and there isn't any correlation, we can draw some conclusions from the model:

- AR1 coefficient: indicates a strong positive correlation between observations at time  $t$  and  $t - 1$ , aligning with expectations. This is consistent with the nature of GDP, where its value at any given moment tends to be significantly influenced by its immediate past;
- MA coefficient: although modest, its negative value indicates that errors from the immediate past tend to slightly decrease the current value. This suggests a corrective mechanism in the model, where past prediction errors are taken into account to adjust the current GDP estimate downwards;
- Intercept: significantly lower compared to all previously estimated intercepts, which we believe more accurately reflects reality, historically, it's evident that an economy consisting solely of a population, without the integration of factors like technology, governance, and infrastructure, tends to be less productive;
- Political stability: small, yet positive influence, aligning with the expectation that a nation with greater stability tends to have a higher GDP per capita on average; the minimal magnitude could stem from the aggregation of upper and lower estimates, however this approach was necessitated by the absence of more refined data, with fewer extreme values
- CO2 Emissions per capita: seems to be slightly positive correlated with gdp, which is to be expected
- Decorrelated Fertility: when accounted for CO2 Emission, fertility is quite negatively correlated, with a decrease in Fertility leading to quite a significant increase in GDP - Research: There is a slight positive correlation between research expenditure and GDP per capita, which is to be expected
- Dummy Free: being classified as a free country shows a slight positive correlation with a higher GDP, although the magnitude of this effect is not as substantial as anticipated. This observation may reflect a narrowing gap between free and less free economies, potentially due to the emergence and success of hybrid authoritarian regimes (such as those in China, Singapore, etc.), which have managed to achieve significant economic growth despite limited political freedoms
- Dummy\_30\_60 and Dummy\_60\_plus: indicates a slight economic advantage for countries situated further from the equator, revealing a 'Goldilocks' zone for economic prosperity situated between 30 and 60 degrees latitude, countries within this optimal latitude range tend to demonstrate superior economic performance; this advantage marginally declines for countries located beyond 60 degrees latitude, however this reduction may be influenced by nations in the southern parts of Africa and South America, suggesting geographical location plays a significant role in economic outcomes, with certain latitudes offering more favorable conditions than others