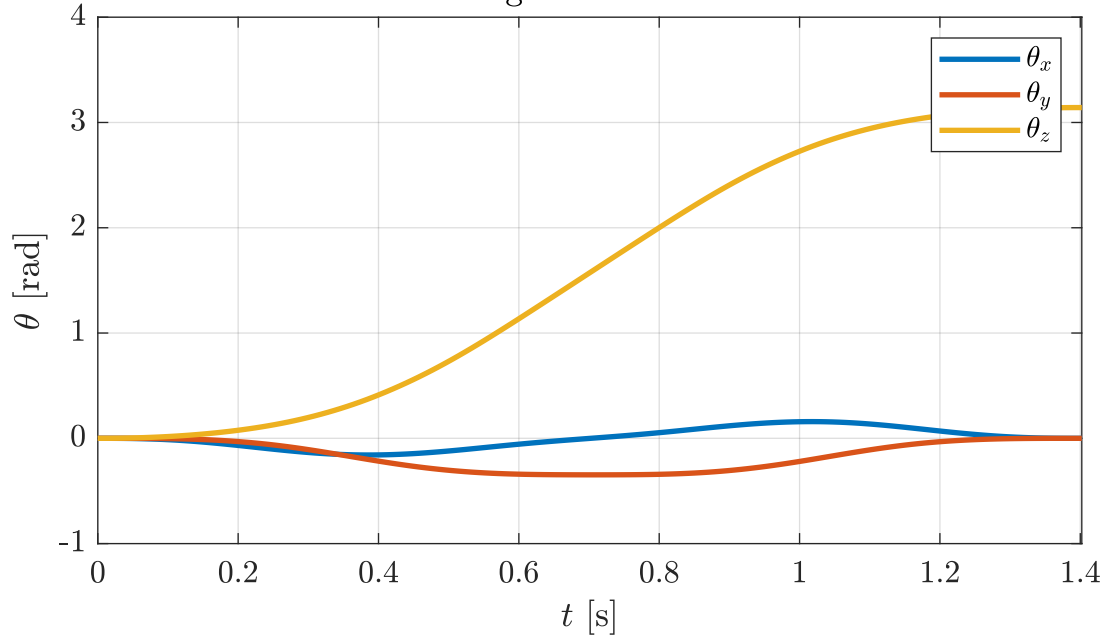
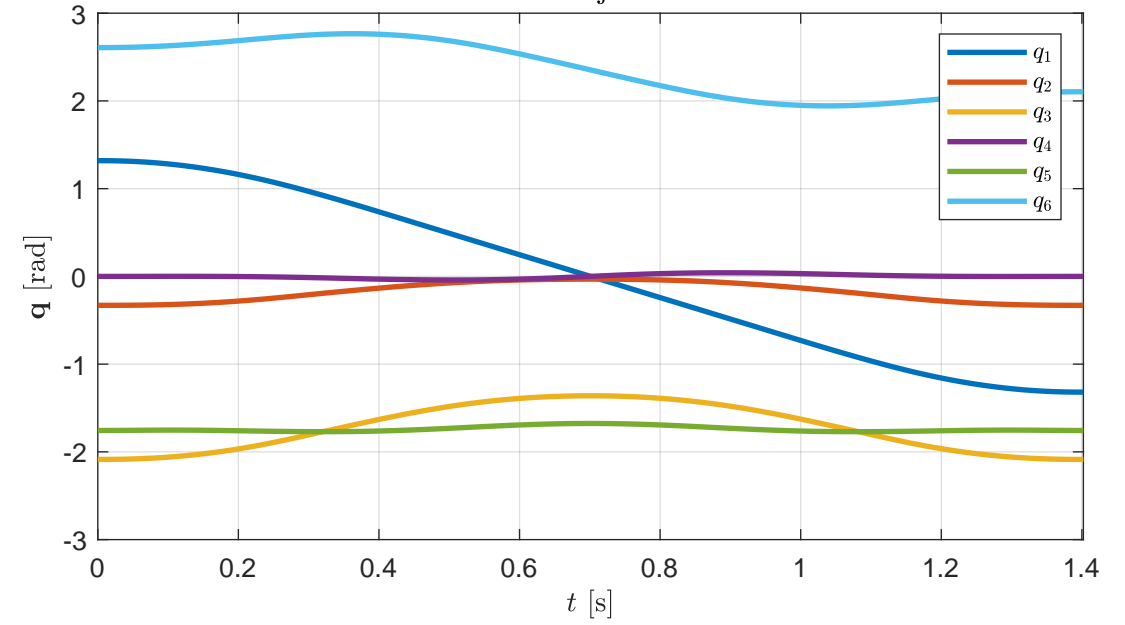


# TO\_arc\_4containers\_180\_deg

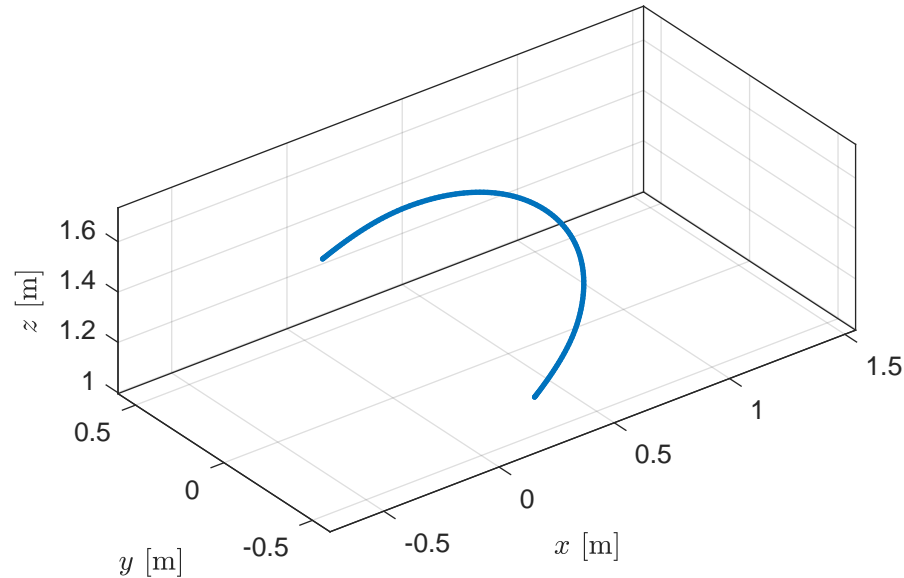
Angular Position



Joint Trajectories



Geometric Path



Computation Time: 29.68 s

End Time: 1.40 s

Max Acceleration: 6.03 m/s<sup>2</sup>

Max Angular Acc.: 11.10 rad/s<sup>2</sup>

$\theta_z$ : 3.14 rad