Using STL Containers to Implement a Sparse Matrix Class

April 22, 2016

Sparse Matrices

- A sparse (square) matrix is a matrix that has a number of non-zero coefficients proportional to n rather than n²
- ▶ It is not convenient to store all entries including zeros
- It is not convenient to include zero entries when doing algebra with sparse matrices

A Sparse Matrix Class Based on STL Containers

Consider the following class:

class sparse_matrix : public std::vector<std::map<unsigned int, double> >

▶ What happens if we do:

```
A = sparse_matrix (4); auto x = A[2][2]
```

What happens if we do:

```
A = sparse_matrix (4); A[2][2] = 1.0;
```

Cool! This features make class sparse_matrix: public std::vector<std::map<unsigned int, double> > a great candidate for the implementation of a (row oriented) sparse matrix!

Useful things to know about the std::map container

- mapped_type& std::map::operator[] (const key_type& k);, A call to this function is equivalent to: (*((this->insert(make_pair(k,mapped_type()))).first)). second
- ➤ A similar member function, std::map::at, has the same behavior when an element with the key exists, but throws an exception when it does not.
- iterator find (const key_type& k); const_iterator find (const key_type& k) const; Searches the container for an element with a key equivalent to k and returns an iterator to it if found, otherwise it returns an iterator to map::end ().
- size_type count (const key_type& k) const; Searches the container for elements with a key equivalent to k and returns the number of matches. Because all elements in a map container are unique, the function can only return 1 (if the element is found) or zero (otherwise).

A recap example about inheritance I

```
#include <iostream>
class A_t
public:
  void
  A_m () { std::cout << "calling_A_t::A_m" << std::endl; };
  virtual
  void
  B_m () { std::cout << "calling_A_t::B_m" << std::endl; };
};
class B t :
  public A<sub>t</sub>
public:
  void
  B_m () { std::cout << "calling_B_t::B_m" << std::endl; };
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```

A recap example about inheritance II

```
void
 A_m () { std::cout << "calling_B_t::A_m" << std::endl; };
};
int
main (void)
  B_t b:
  A_t *a = \&b:
  // b is of class B_t, derived from A_t
  // therefore it has method A<sub>m</sub> definide in B<sub>t</sub>
  // but also the implementation defined in A_m
  b.A<sub>m</sub> ();
  b. A_t::A_m ();
  // Also A_t::B_m even though it is virtual can be
  // accessed via a qualifier
  b.A_t::B_m ();
```

A recap example about inheritance III

```
// a is a pointer to an object of class A_{-}t
// if I invoke method A<sub>m</sub> the compiler chooses
// the implementation given in A_t
a\rightarrow A_m ();
// to access the method B_t::A_m I need to use a cast
static\_cast < B_t*> (a) -> A_m ();
// If I invoke method B<sub>-</sub>m through
// the pointer a, instead, the compiler chooses B_t::B_m
// instead of A_t::B_m because A_t::B_m is virtual
a \rightarrow B_m ():
// to access method A_t::A_m I need to add a qualifier
a \rightarrow A_t :: A_m ();
return 0;
```

Exercises

- ► Implement a libary providing a sparse_matrix class inheriting from std::vector<std::map<unsigned int, double>>
 - A basic implementation is already given as a starting point
 - Write the makefile
 - Adapt fem1d to use this class
- Create an abstract interface class general_matrix and derive both matrix and sparse_matrix from it
- Change fem1d so that the type of matrix can be selected by the user at run time.