

$$\langle F \rangle = \text{Tr}[\rho F] = -\frac{\hbar \Omega^*}{2} \left( \frac{\nabla |\Omega|}{|\Omega|} - i \nabla \phi \right) \langle \sigma \rangle + \text{c.c.}$$

$$\tilde{\rho}_{eg} = -\frac{i\Omega}{\Gamma} \frac{1 + \frac{i2\delta}{\Gamma}}{1 + \left(\frac{2\delta}{\Gamma}\right)^2 + 2\frac{|\Omega|^2}{\Gamma^2}} = -\frac{i\Omega}{2(\Gamma/2 - i\delta)(1+s)}$$

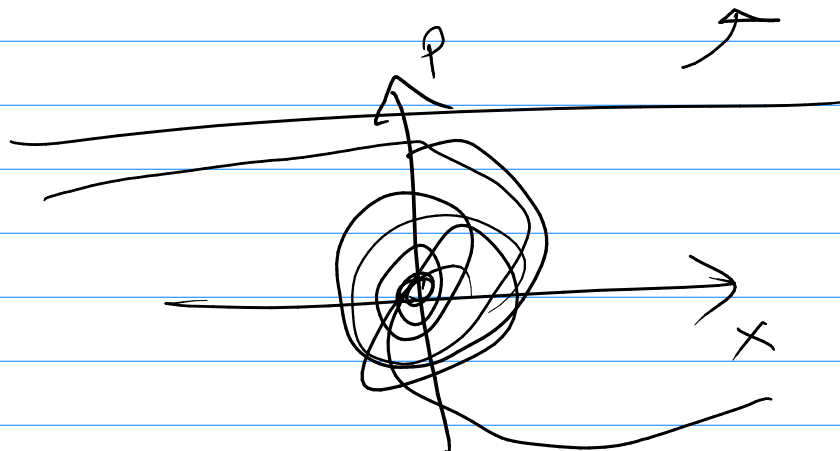
$$\tilde{\rho}_{ge} = \frac{i\Omega^*}{2(\Gamma/2 + i\delta)(1+s)},$$

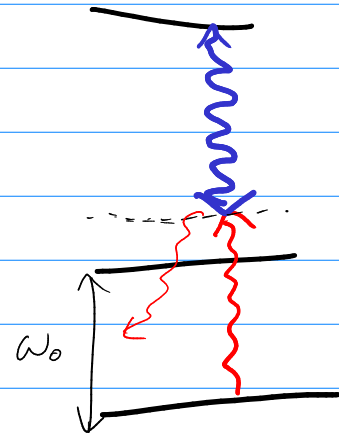
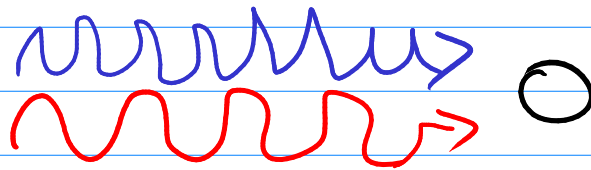
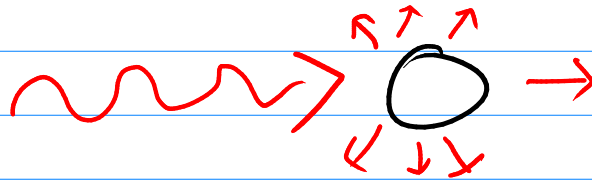
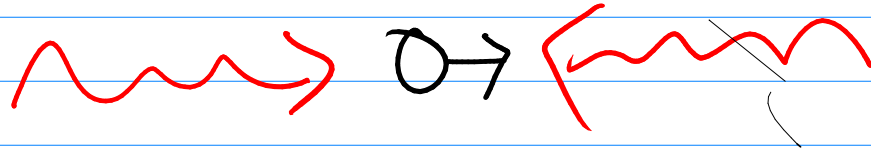
$$\rightarrow \delta_{\text{eff}}^{\text{mot}} = \delta - kv - \beta x$$

$$\text{Tr}[F_S(t \rightarrow \infty)] = F(v, x) = m \dot{x}$$

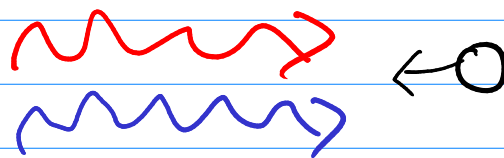
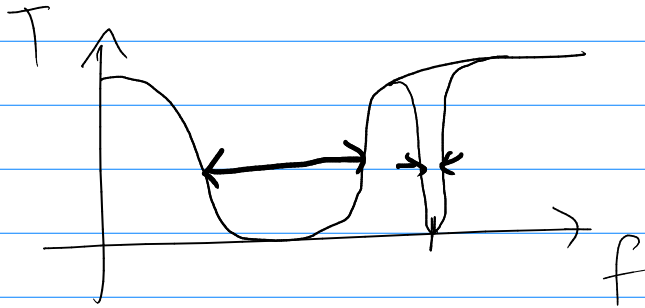
$$\dot{\tilde{g}} = -\frac{i}{\hbar} [\tilde{H}, \tilde{g}] + \Gamma \mathcal{L}$$

$$\tilde{H} = \hbar \begin{pmatrix} 0 & \frac{\Omega}{2} \\ \frac{\Omega}{2} & -\delta(x, v) \end{pmatrix}$$



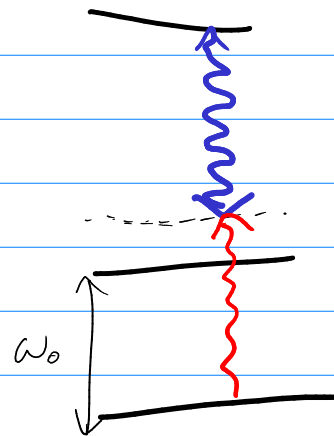


$$\vec{k} + \vec{k} - \vec{k} + \vec{k}'$$



$$\delta^{480} = K_{480} \cdot V$$

$$\delta^{780} = K_{780} \cdot V$$

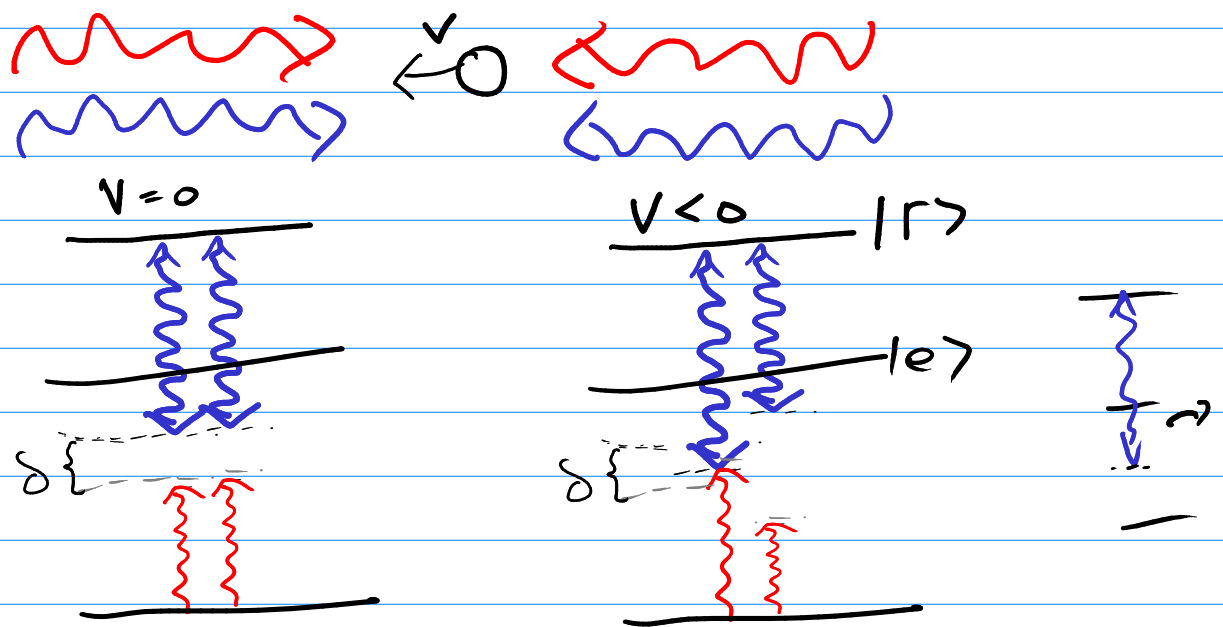


$$\frac{\delta^{480}}{\delta^{780}} = \frac{K_{480}}{K_{780}} = \frac{780}{480} = 1.625$$

$$\delta_{\text{eff}} = \delta + \delta^{480} + \delta^{780}$$

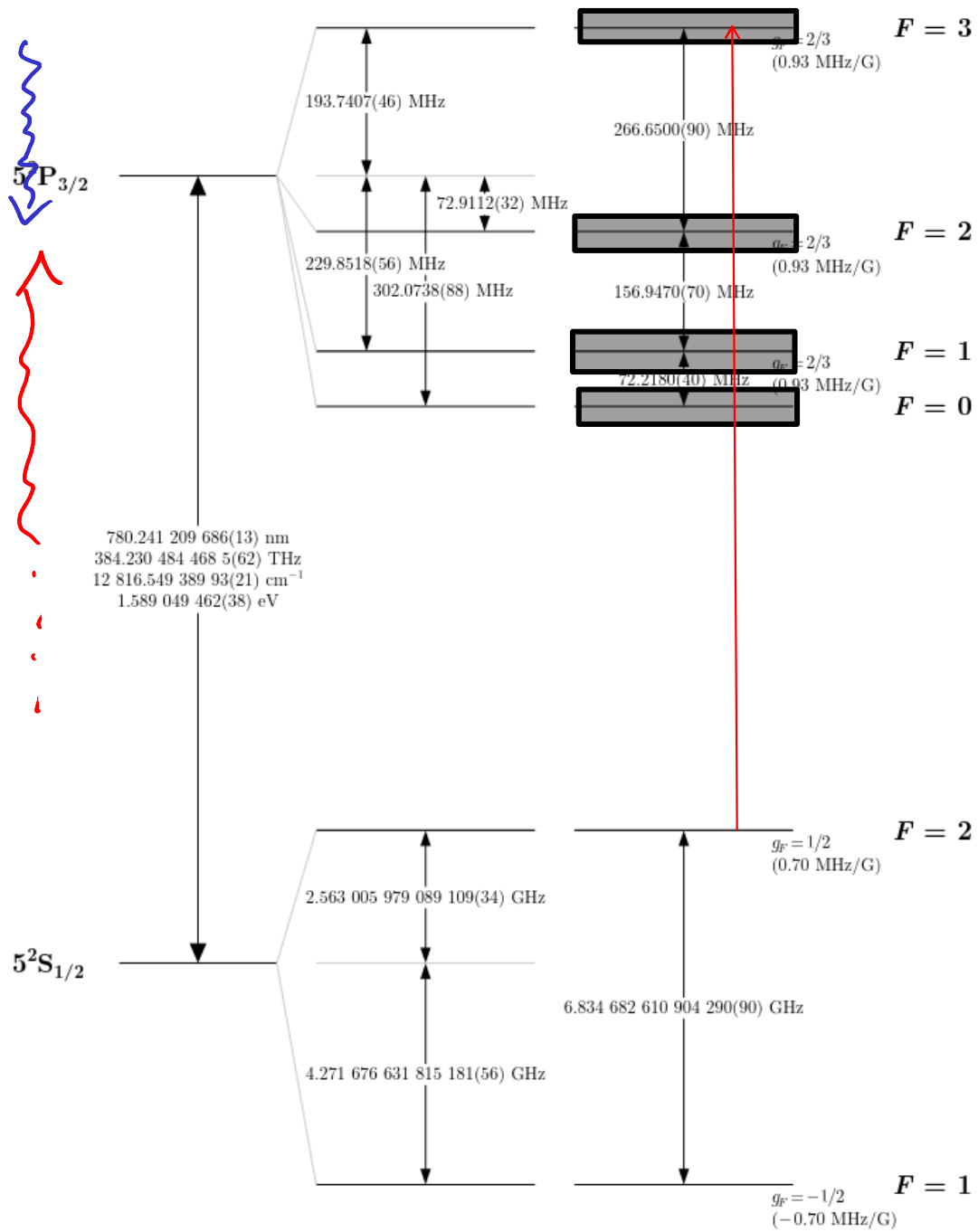
$$0 = \delta_{\text{res}} + \delta^{480} + \delta^{780}$$

$$\delta = \omega_{780} + \omega_{480} - \omega_{01} - \omega_{12}$$



$$T_D = \frac{\hbar \gamma}{2k_B}$$

$$\Gamma \approx 6 \text{ MHz}$$



obtenes

$F(x, v)$  usando qutip para

obtener  $f(t \rightarrow \infty, x, v)$   
y así calcular  $\bar{F}$

def  $F(x, v)$ :

llamar qutip

steadystate

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$$\frac{d\vec{y}}{dt} = \vec{f}(t, \vec{y})$$

$$F(x(t), v(t)) = m\ddot{x}(t)$$

$$v = \dot{x}$$

$$\dot{v} = \ddot{x}$$

$$\vec{y} = \begin{pmatrix} x \\ v \end{pmatrix}$$

$$\frac{1}{m}F(x(t), v(t)) = \dot{v}(t)$$

$$\frac{d\vec{y}}{dt} = \begin{pmatrix} \dot{x} \\ \dot{v} \end{pmatrix} = \begin{pmatrix} v \\ \frac{1}{m}F(x, v) \end{pmatrix} = f(\vec{y})$$

