

Different components of RootSkel

Component	File name	Description
1	Main script	Main file that calls all subfunctions via the internal <i>MATLAB</i> callback
	Root_image_GUI.m	
2	Log files	Log files documenting all changes including dates so changes can be undone and future developers can build upon the existing version
	Log.txt	Since the last version
	Old_Versions_log.txt	All previous versions
	CurrentVersion.txt	A shorter version of previous log files including bug fixes
3	Functions	Folder containing the 18 subfunctions
	▶ var_saver.m	★ Creates a variable <i>varnames</i> which contains the names of the relevant variables (<i>skelmatR</i> , <i>skelmatR_simp</i> , <i>max_curv_point</i> , <i>savename</i>); it then pulls them from the base workspace and lets the user save them in a .mat file. ★ <i>skelmatR</i> or <i>skelmatR_simp</i> include the skeleton of the root (their x and y coordinates), <i>max_curv_point</i> includes the user's input for the possible turning point or an empty set, <i>savename</i> includes the name of the image (date and hour) and the number of the roots which is used for names of figures, first column in .csv file and default of <i>var_saver.m</i>
	▶ var_loader.m	★ Allows the user to load the .mat files including the relevant objects from the workspace ★ Contains the enabling of appropriate angle calculation buttons; buttons are disabled to avoid bugs and errors (eg angle computation on nothing should not work)
	▶ skel_crop.m	★ Contains the optional free hand cropping of the skeleton
	▶ skel_clean.m	★ Loops on optional additional cleaning, ie bigger and bigger objects are removed, until user is satisfied
	▶ savename_crea.m	★ Saves the label of the root or root number the user chooses in order to keep track of which root is analysed ★ Combines the label with the name of the file and saves it as a folder where the variables (see above) would go
	▶ root_skel.m	★ Takes results from <i>image_process.m</i> ★ Applied more fine-tuned filtering ★ Applies more cleaning steps ★ Tries to makes sure that the root tip is in the skeleton ★ Combines approach 1 and 2 ★ Returns the skeleton
	▶ point_get.m	★ Asks the user for points as long as she does not provide the required number (defined as a number of points between minimum and maximum) ★ The user's input is stored in the strings <i>srcx</i> and <i>srcy</i> are strings with the name of the variable that will receive the data in the base workspace; they tell <i>assignin</i> in which variable in the caller to store the data
	▶ point_choose.m	★ Collects the necessary points from the user: 5 points close to the tip, 5 - 10 evenly spaced points on the desired root starting with the tip, the tip of the root ★ Each step can be redone
	▶ image_zoom.m	★ Inverts the image ★ Lets the user zoom in (and zoom out via right click)
	▶ image_process.m	★ Extracts the cropped image ★ Extracts the colours from the sample pixels and averages it with a certain neighbourhood (3x3) ★ Takes a brightness range, an average of the three filters used ★ Approach 1: Colour separation filtering <ul style="list-style-type: none">• based on RGB values of points• gray scales image ★ Approach 2: Brightness filtering (intensity-based approach) <ul style="list-style-type: none">• enhances brightness• eliminates too bright spots
	▶ image_crop.m	★ Optional free hand cropping
	▶ image_choose.m	★ Allows the user to choose an image ★ Modifies the image using various filter to help the user discern the root
	▶ getAngle.m	★ Takes the skeleton as input ★ Computes the curvature and angle of the root tip
	▶ force_tip.m	★ Prompts user to create an open polygon between the edge of the current skeleton and the tip ★ In order to make sure that the tip of the root is definitely included in the skeleton
	▶ final_prep.m	★ Extracts only the tip of the root and the respective x and y values which are passed on to <i>getAngle.m</i> ★ User can choose to select the turning point, ie point with highest local curvature, which can serve as another verification of the computed turning point; it does not have to be exactly on the root as the point in the skeleton that is closest to the chosen point is used
	▶ fig_saver.m	★ Saves the relevant objects upon clicking different buttons
	▶ fig_loader.m	★ Loads respective figures
	▶ angle_file.m	★ Creates a .txt file containing the label of the root (picture name and root number) and the angle ★ Creates a file <i>root_angles.csv</i> or <i>user_assisted.csv</i> depending on <i>user_flag</i> and prints the label of the root and the angle; this file can be appended for consecutive angle calculations of the same root in other images