

# GIOVANNI MICHEL

## Electrical Engineering

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### Education

**Master of Science in Electrical Engineering** **Cumulative GPA: 3.4**  
Northwestern University, Evanston, IL. Graduation date: May 2025  
**Master of Science in Artificial Intelligence** **Cumulative GPA: 3.7**  
Florida Atlantic University, Boca Raton, FL. Graduation date: August 2023  
**Bachelor of Science in Computer Engineering** **Cumulative GPA: 3.4**  
Florida Atlantic University, Boca Raton, FL. Graduation date: August 2022

### Technical Skills

**Programming Languages:** C/C++, C#, MATLAB, Simulink, HTML, Python, VHDL and Verilog, VLSI, PSPICE, JavaScript, Quartus

**Skills & Technologies:** ROS, Microsoft Office Suite (Word, Excel, PowerPoint), Oscilloscopes, DMM, Soldering, PCB Design, Linux, Virtuoso

**Controllers:** TI MSP430, ARM Cortex-M3, Raspberry Pi, Nexys4 DDR FPGA, Intel Loihi

### Professional Experience

**Graduate Research Assistant, Los Alamos National Laboratory | Los Alamos, NM** **April 2022 – Present Day**  
*Engage in research, design and development for Spiking Neural Networks (SNNs) using the Intel neuromorphic research processor, Loihi.*

- Implemented Q-learning using neuromorphic translatable design methods, this resulted in solving the cartpole problem with a mean average score of 200 over 200 episodes. Designed an information processing circuit out of SNNs to control information in neuronal circuit.
- Designed and implemented encoding methods for representing cartpole dynamics to be used as input to 2-layer SNN that ran on Loihi. [Poster for ICONS 2023](#)

**Graduate Research Assistant, Grayson Group | Evanston, IL** **December 2023 – Present Day**  
*Made experiments to model dynamics of different electronic devices at cryogenic temperatures down to 1.5K.*

- Designed experiments to model signal stability and temperature dependence for VCOs by modeling modified Allan variance, power spectral density, and phase noise.
- Designed experiments to model the temperature dependence for the voltage threshold, Fermi energy, leakage current, and insulator capacitance.

**Software Engineer (Internship), GRUBBRR | Boca Raton, FL** **September 2021 – February 2022**  
*Responsible for performing Q&A automation duties for unit test and functional test assigned by Project Management.*

- Implemented standardized processes for Q&A group, which lead to efficient product testing for and design of end-to-end product release.
- Engage in onsite coordination, progress, planning, closeout, & quality control to add support to project development.
- Led teams for client integrations using technical communications skills, Scrum, and Agile methodologies.

### Relevant Projects

**NFC Wireless Temperature Sensor | VLSI Group Project** **June 2024**

- Designed schematics of an IC that converts an analog input (temperature) into a digital output using Near Field Communication (NFC), to power the circuit.
- Designed schematic and testbench for temperature sensor, low-dropout regulators, power rectifier, and demodulation rectifier.
- Designed and tested power harvesting component, made multistage rectifiers that worked with bandgap reference circuit to generate stable signal.
- This resulted in learning about RC response, impedance matching, and designing an ADC.

**4x4 6T SRAM | VLSI Project** **March 2024**

- Designed schematics and testbench for 4x4 6T SRAM Array with Sense Amplifier, bitline precharge and write circuits for each column.
- Designed layout for 6T SRAM with dimensions  $1.495\mu\text{m} \times 0.3825\mu\text{m} = 0.5718375\mu\text{m}^2$ . This passed all DRC and LVS test.
- Designed layout for sense amplifier, write circuit, precharging circuit.
- The energy consumption: 34.31uW (schematic) and 45uW (layout) for the entire writing and reading of the 16bit SRAM. Divided down, for one single bit read/write it consumes 2.14uW and 2.81uW.

**Autonomous Robot Manipulator | Senior Design Project** **May 2022**

- Integration between Raspberry Pi and Arduino Mega for robotic car and robotic arm that would pick and place water bottles and cans.
- Developed obstacle avoidance and autonomous navigation algorithm using LIDAR, IMU, and ROS for navigating and avoiding obstacles while navigating to user dependent locations.
- Create an innovative & responsive solar tracker using linear actuators for position optimization for solar panel sunlight exposure.

**Digilent Nexys 4 DDR FPGA Projects with VHDL | Design of Digital Systems** **May 2022**

- Built Register Files with 8 and 16 registers on Xilinx Vivado.
- Built an ALU and a Parameterized Carry Save Multiplier on Xilinx Vivado
- Built a Vending Machine Subsystem using a Finite State Machine and Arithmetic State Machine on Xilinx Vivado.
- Learned about different ASIC, FPGAs, BIST, Timing Analysis, and different architectures for VHDL FPGA design.

### Leadership

**VP Society of Hispanic Professional Engineers (SHPE) | FAU** **August 2022 – August 2023**  
**Marketing Chair Machine Perception Cognition Robotics Lab (MPCR) | FAU** **August 2022 – August 2023**