EE513 Project 2: A Digital Oscillator

Implementor's Notes

Matt Ruffner

matthew.ruffner@uky.edu

14

20

26

29

30

ABSTRACT

In this assignment, a multi-frequency digital oscillator was created utilizing the un-damped exponential impulse response of a marginally stable IIR filter. Second Order Sections are generated for each frequency of oscillation requested. These are then parallelized and converted to Direct Form coefficients representing the entire Transfer Function (TF).

1. APPROACH

The discrete time representation of a marginally stable transfer function can be seen in Eq. 1. Taking the Z-Transform yields Eq. 2.

$$y[n] = 2\cos(\alpha)y[n-1] - y[n-2] + kx[n]$$
 (1)

$$\hat{H}(z) = \frac{\hat{Y}(z)}{\hat{X}(z)} = \frac{Kz^2}{z^2 - 2\cos(\alpha) + 1}$$
 (2)

Where K represents the relative sinusoid amplitude, and α controls the frequency of oscillation.

$$\alpha = \frac{2\pi f_o}{f_s} \tag{3} 15$$

It turns out that in order to normalize the sinusoid amplitudes realtive to each other, all that is required is a scaling by alpha. Letting K represent the final coefficient in the TF, $_{18}$ and \bar{k} be the function input amplitude factor, Eq. 4 follows. 19

$$K = \alpha k \tag{4}$$

21 From this, the function with prototype seen in in Listing 1 is derived. A test MATLAB script, digosc_test.m is also supplied, which verifies the correct operation via spectral analysis. Parameters to the function are shown in Listing 1.

Listing 1: DIGOSC function prototype.

```
function [a,b] = digosc(freqs, amps, fs)
```

MATLAB SOURCE

Listing 2: Relevant code from the project source file digosc.m

```
% vector representing coeffecients for normalizing
    the calculation of frequencies and amplitudes
alphas=(2*pi.*freqs)/fs;
% where the TF of the digital oscillator is
(k*z^2) / (z^2 - 2*cos(alpha)*z + 1)
bs=[]; % vector to hold numerators
counter=1;
for n=amps % iterate through each specified
    amplitude
    bs=[bs; alphas(counter)*n 0 0]; % multiply
        coefficient for z^2 term by desired
        amplitude
    counter=counter+1;
end
as=[]; % vector to hold denominators
for n=alphas
    % create denominators based on calculated alpha
    as=[as; 1 -2*cos(n) 1];
dfilts = []; % vector to hold digital filter
    representations
for n=1:nfreqs % convert b/a num/denom coeffs to
    dfilt objects
   % build vector of direct form 1 representations
   dfilts=[dfilts, dfilt.df1(bs(n,1:end), as(n,1:end
end
% parallelize the individual transfer functions
fdf=dfilt.parallel(dfilts);
% extract the state space variables of the
    parallelized TFs
[A,B,C,D]=fdf.ss;
% use ss2tf to convert to one TF with unified
    numerators and denominators
[a,b]=ss2tf(A, B, C, D);
```