

lab 8 :

Aim: Implement Dijkstra's algorithm to compute the shortest path for a given topology.

```
#include <iostream>
```

```
#include <stdio.h>
```

```
using namespace std;
```

```
#define V 4
```

```
int minDistance (int dist[], bool sptSet[])
```

```
{ int min = INT_MAX, min_index;
```

```
for (int v=0; v<V; v++)
```

```
if (sptSet[v] == false && dist[v] <= min)
```

```
min = dist[v], min_index = v;
```

```
return min_index;
```

```
}
```

```
void minDistance dijkstra (int graph graph[V][V], int src)
```

```
{ int dist[V];
```

```
bool sptSet[V];
```

```
for (int i=0; i<V; i++)
```

```
dist[i] = INT_MAX, sptSet[i] = false;
```

```
dist[src] = 0;
```

```

for (int count=0; count<V-1; count++)
    int u = mindistance (dist, sptSet);
    sptSet[u] = true;

```

```

for (int v=0; v<V; v++)
    if (!sptSet[v] && graph[u][v] && dist[u]
        != INT_MAX && dist[u] + graph[u][v]
            < dist[v])
        dist[v] = dist[u] + graph[u][v];

```

```

    printSolution(dist);
}

```

End main

```

printSolution (int dist[])

```

predefined.

```

cout << "Vertex \t \t Distance from source is "

```

```

for (int i=0; i<V; i++)

```

```

    cout << " " << i << " " << dist[i] << " " << endl;

```

```

    cout << i << " " << dist[i] << " " << endl;

```



```

int main()
{
    int graph[V][V]
    cout << "Enter the graph" << endl;

    for (int i=0; i<V; i++)
    {
        for (int j=0; j<V; j++)
            cin >> graph[i][j];
    }

    shortestn(graph, 0);
    return 0;
}

```

Output :

Enter the graph

0 1 2 3

1 0 4 5

2 4 0 6

3 5 6 0

~~12/11/23~~
Vertex

0

1

2

3

Distance from source

0

1

2

3

