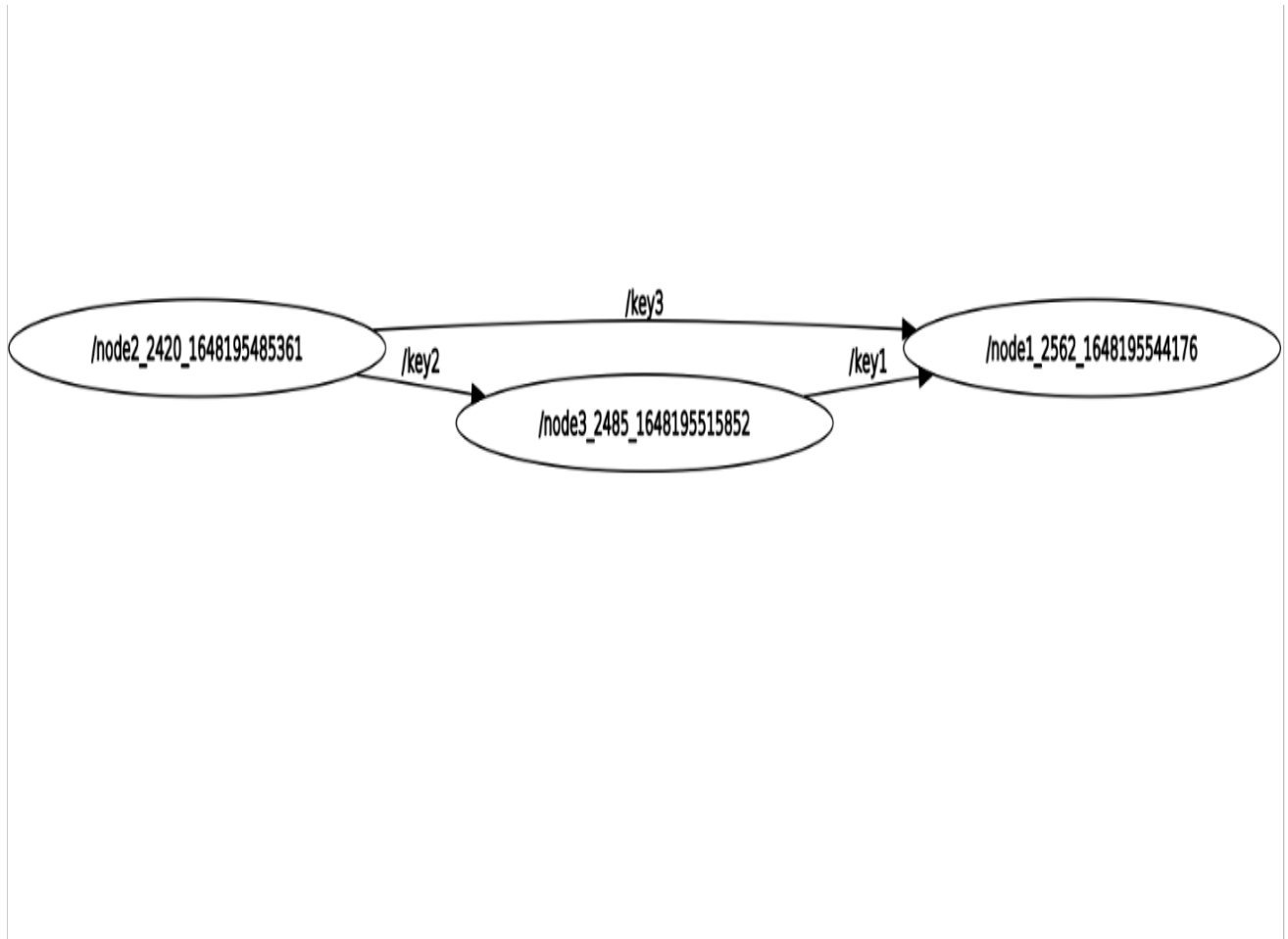


LABSHEET-2

1. Create a publisher node subscriber node to publishes consecutive integers on the topic counter at a rate of 2Hz and subscribe the count .
2. Create a Communication System in ROS with multiple publisher and subscriber.



Key1-int

Key2-float

Key3-String