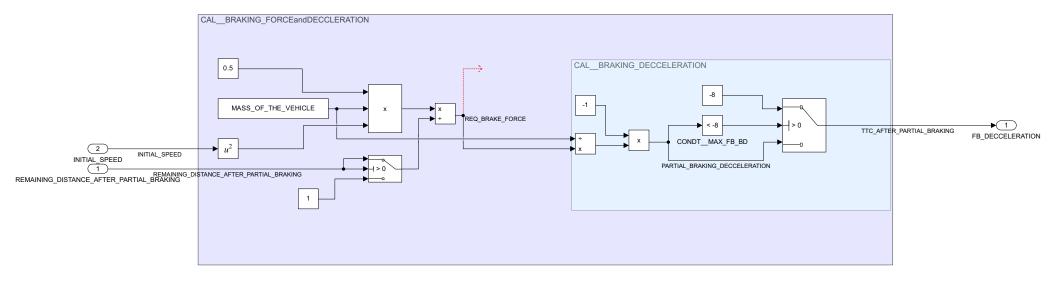
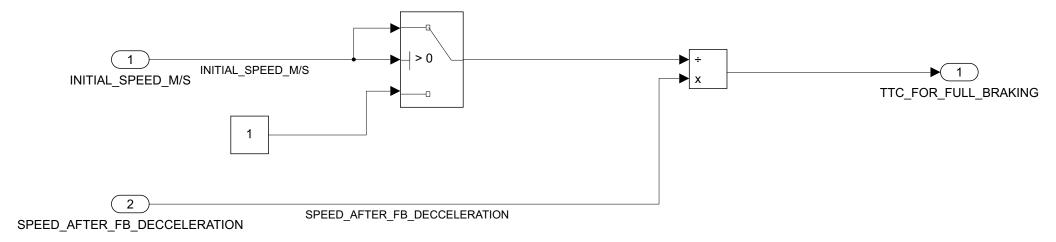
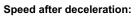


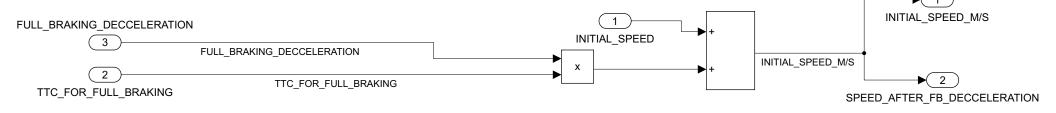
# BRAKING FORCE =0.5\*MASS OF THE VEHICLE\*INITIAL SPEED^2/DISTANCE TO AVOID COLLISION BRAKING DECCELERATION=MASS OF THE VEHICLE/BRAKING FORCE

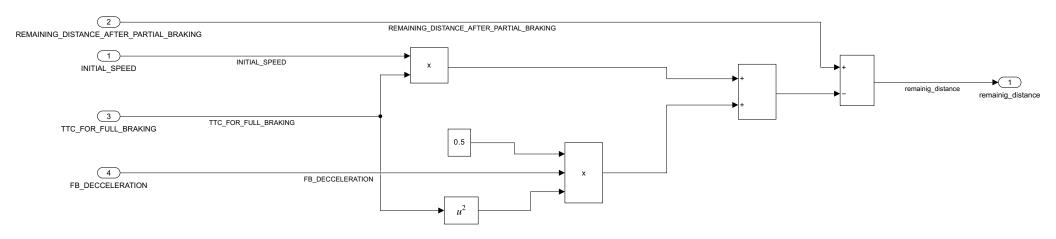


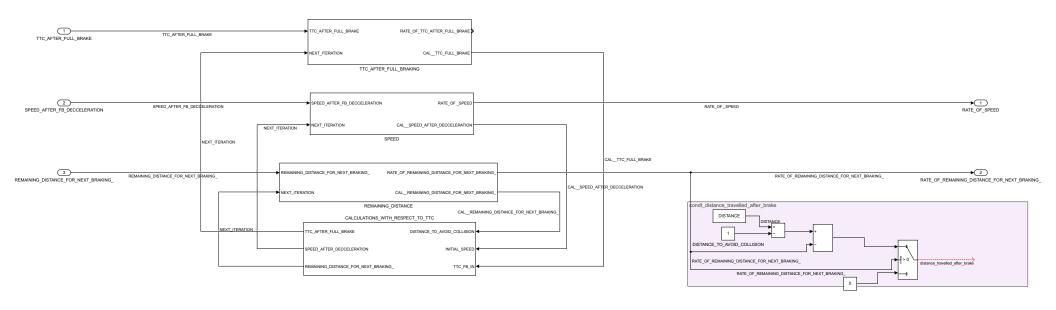


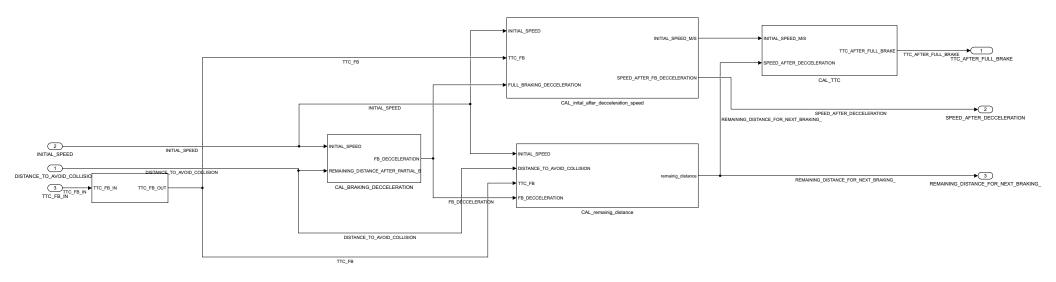


V = u + at

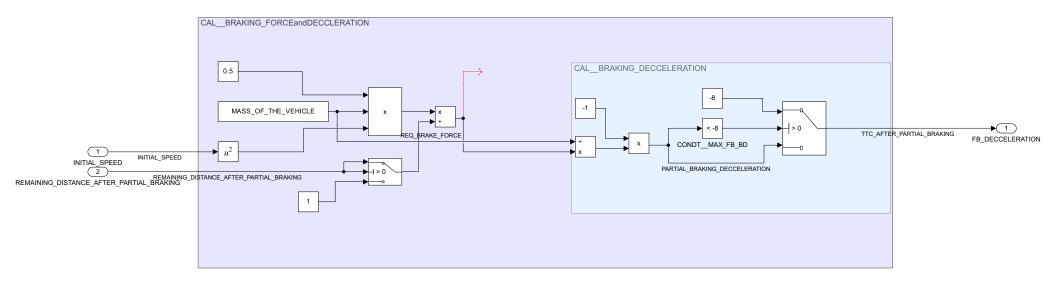


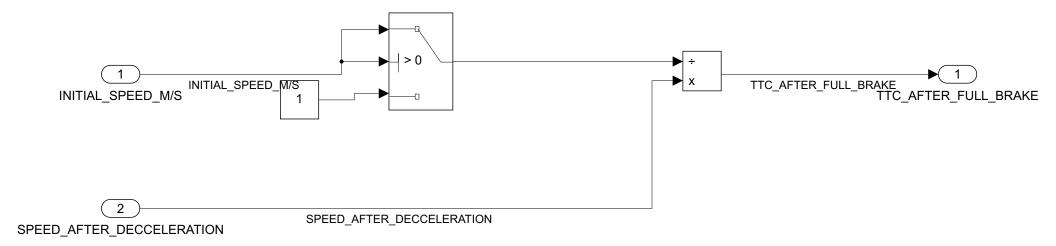


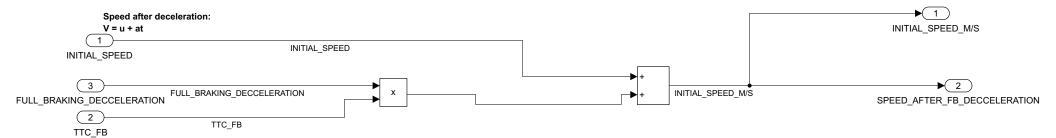


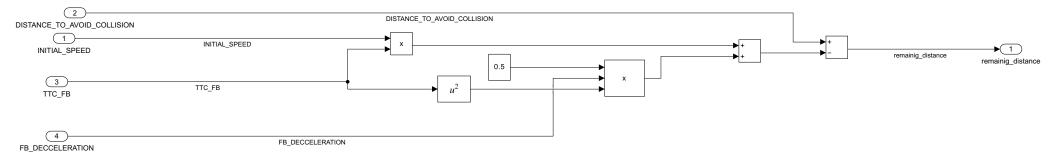


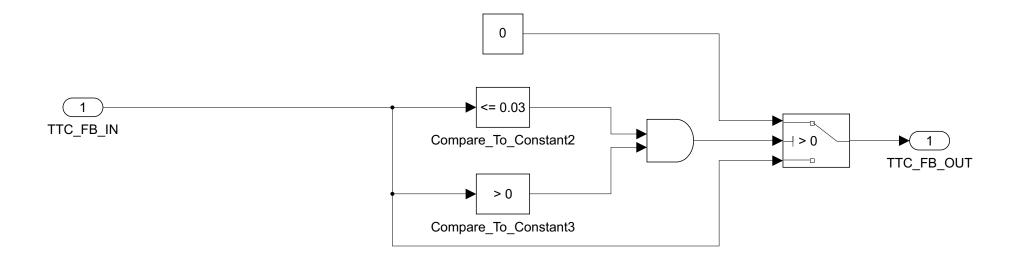
# BRAKING FORCE =0.5\*MASS OF THE VEHICLE\*INITIAL SPEED^2/DISTANCE TO AVOID COLLISION BRAKING DECCELERATION=MASS OF THE VEHICLE/BRAKING FORCE

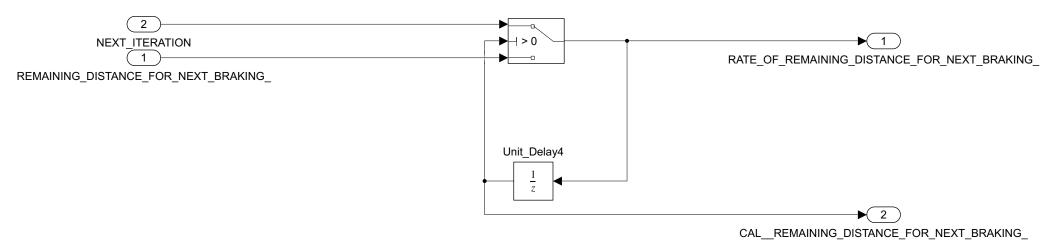


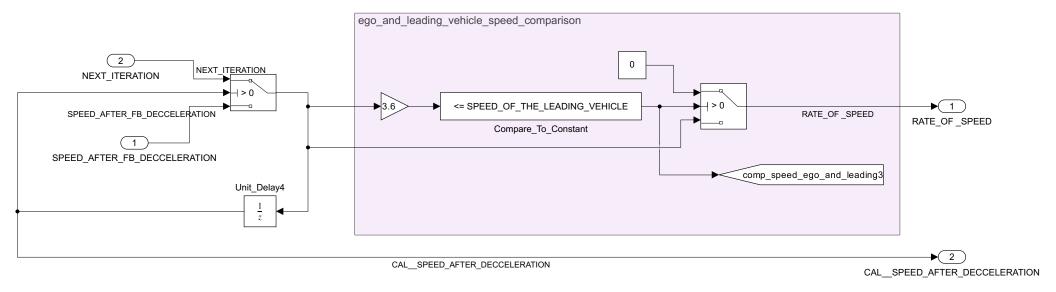


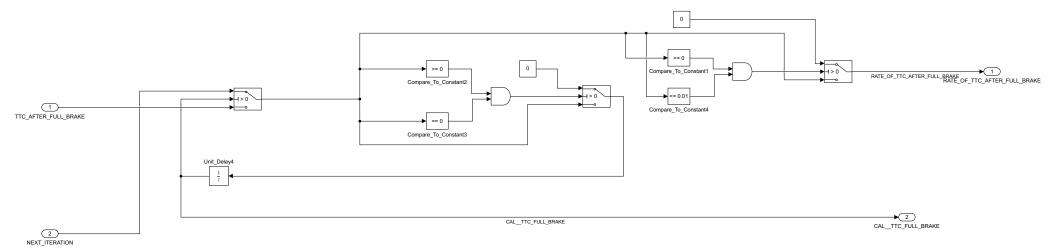


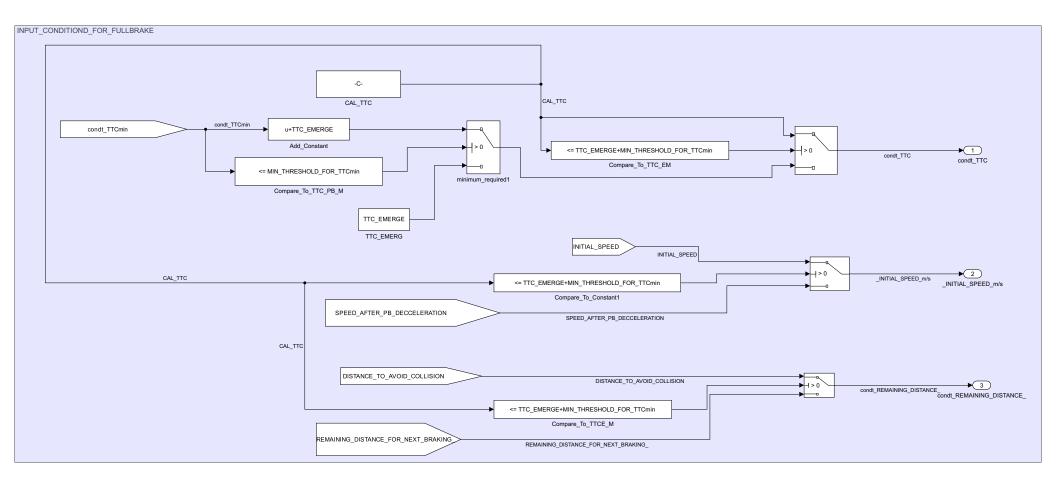




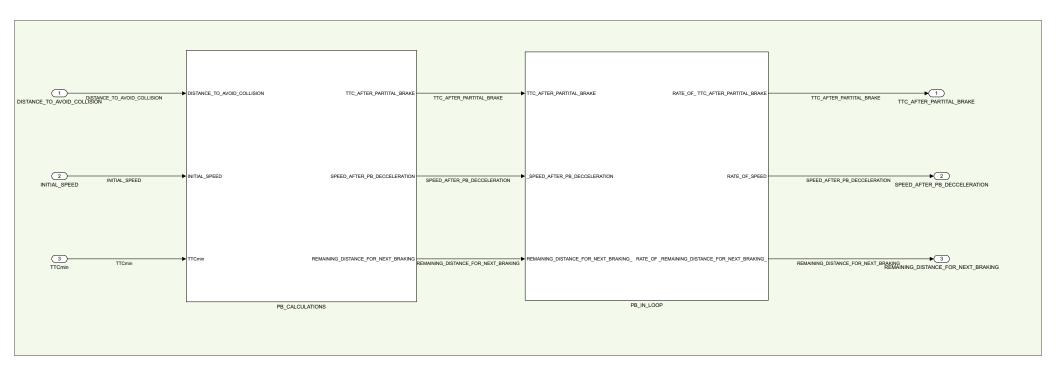


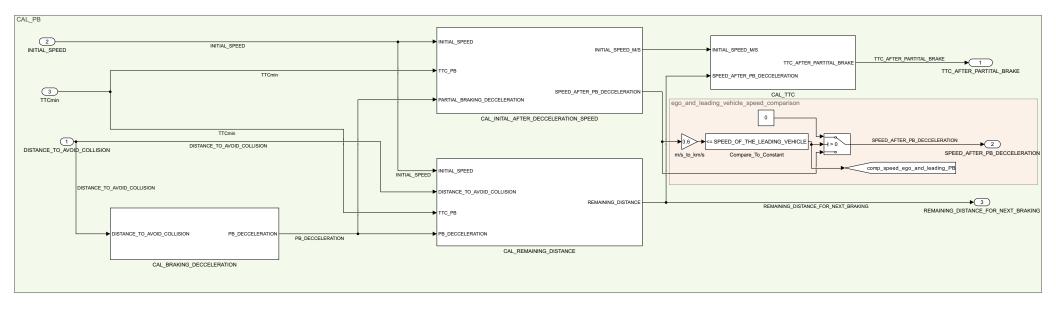






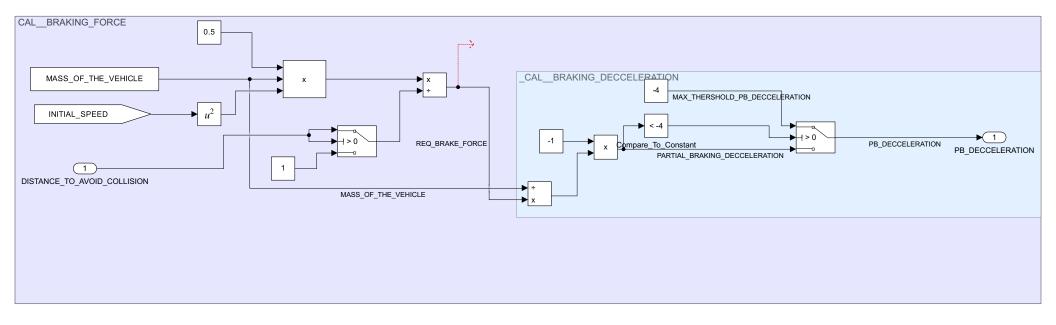
## PARTIAL\_BRAKING INPUT OUTPUT\_ DISTANCE\_TO\_AVOID\_COLLISION DISTANCE\_TO\_AVOID\_COLLISION DISTANCE\_TO\_AVOID\_COLLISION TTC\_AFTER\_PARTITAL\_BRAKE TTC\_AFTER\_PARTITAL\_BRAKE DISTANCE\_TO\_AVOID\_COLLISION TTC\_AFTER\_PARTITAL\_BRAKE condt\_\_TTC\_EMERGE INITIAL\_SPEED INITIAL\_SPEED SPEED\_AFTER\_PB\_DECCELERATION SPEED\_AFTER\_PB\_DECCELERATION INITIAL\_SPEED → INITIAL\_SPEED SPEED\_AFTER\_PB\_DECCELERATION TTCmin TTCmin REMAINING\_DISTANCE\_FOR\_NEXT\_BRAKING REMAINING\_DISTANCE\_FOR\_NEXT\_BRAKING\_REMAINING\_DISTANCE\_FOR\_NEXT\_BRAKING TTCmin PARTIAL\_BRAKING



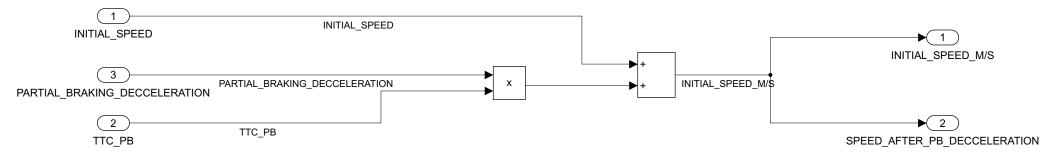


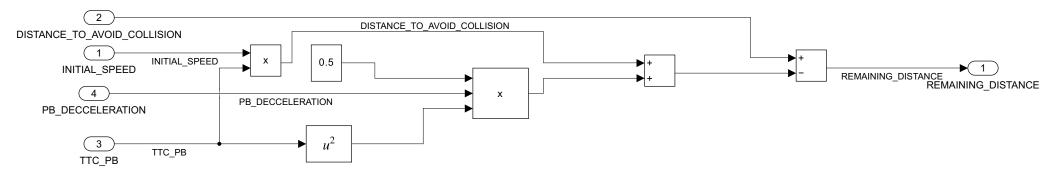
## BRAKING FORCE =0.5\*MASS OF THE VEHICLE\*INITIAL SPEED^2/DISTANCE TO AVOID COLLISION

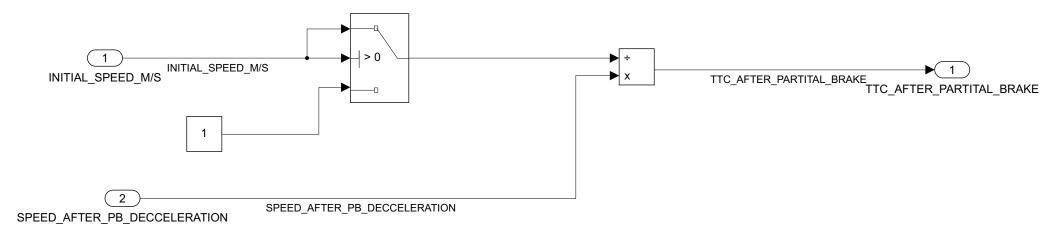
#### BRAKING DECCELERATION=MASS OF THE VEHICLE/BRAKING FORCE

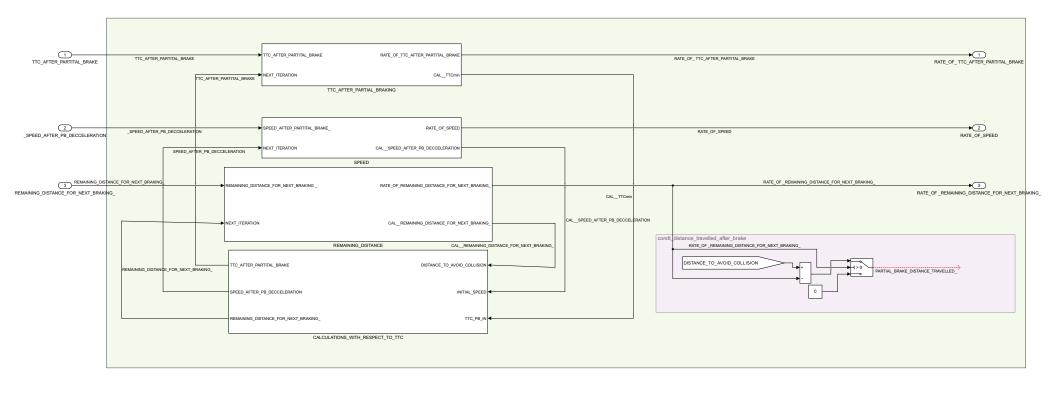


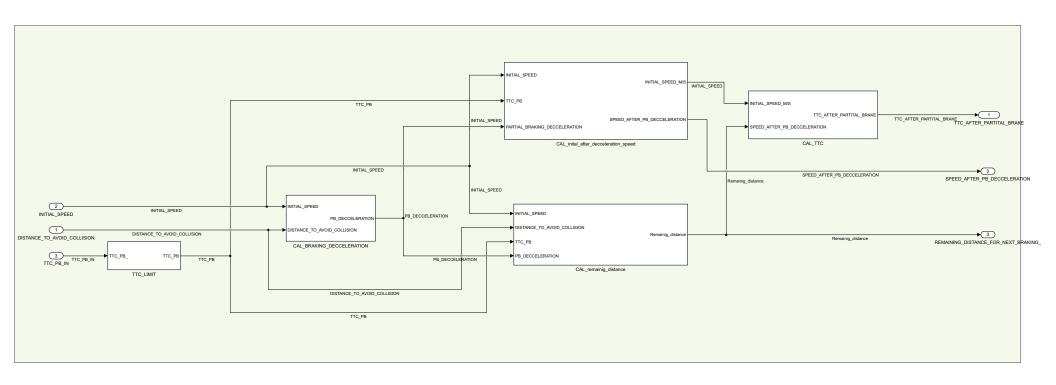
# Speed after deceleration: V = u + at

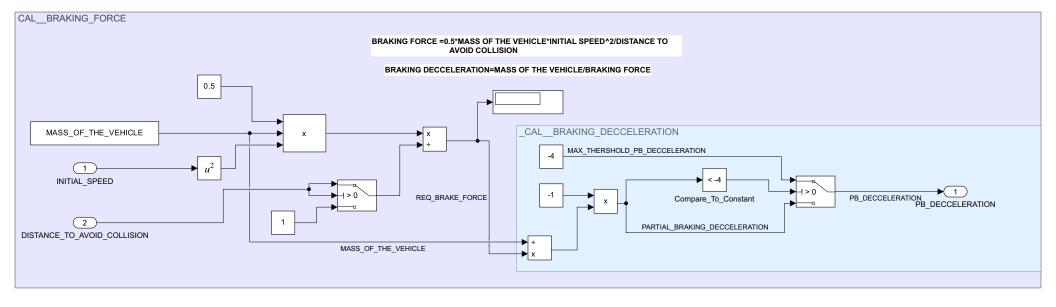


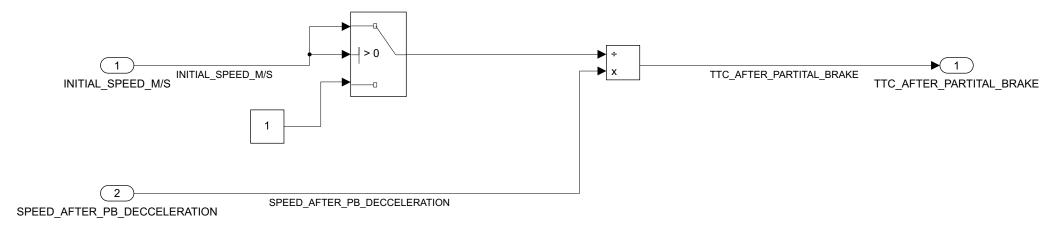












## Speed\_after\_deceleration:V=u+at

