



Competitive Programming

From Problem 2 Solution in $O(1)$

Computational Geometry

Point in Polygon

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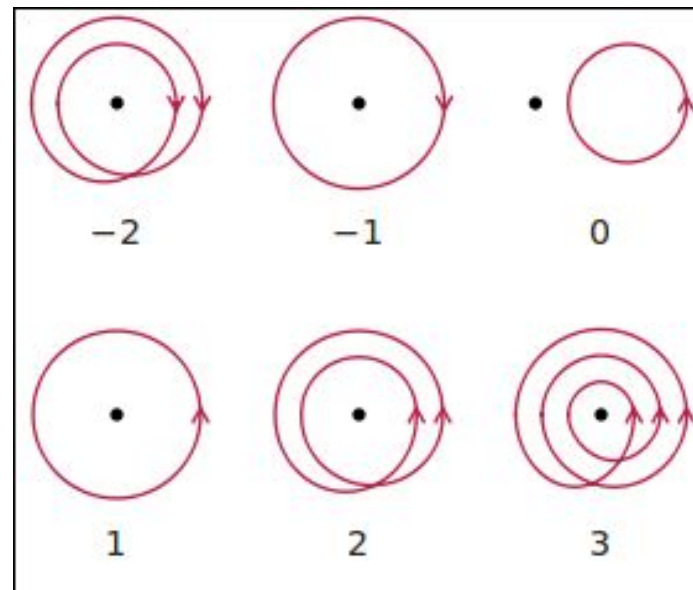
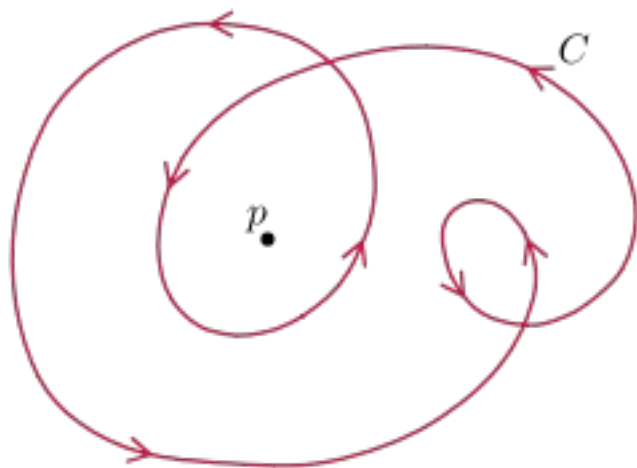


Is point in polygon (pip)?

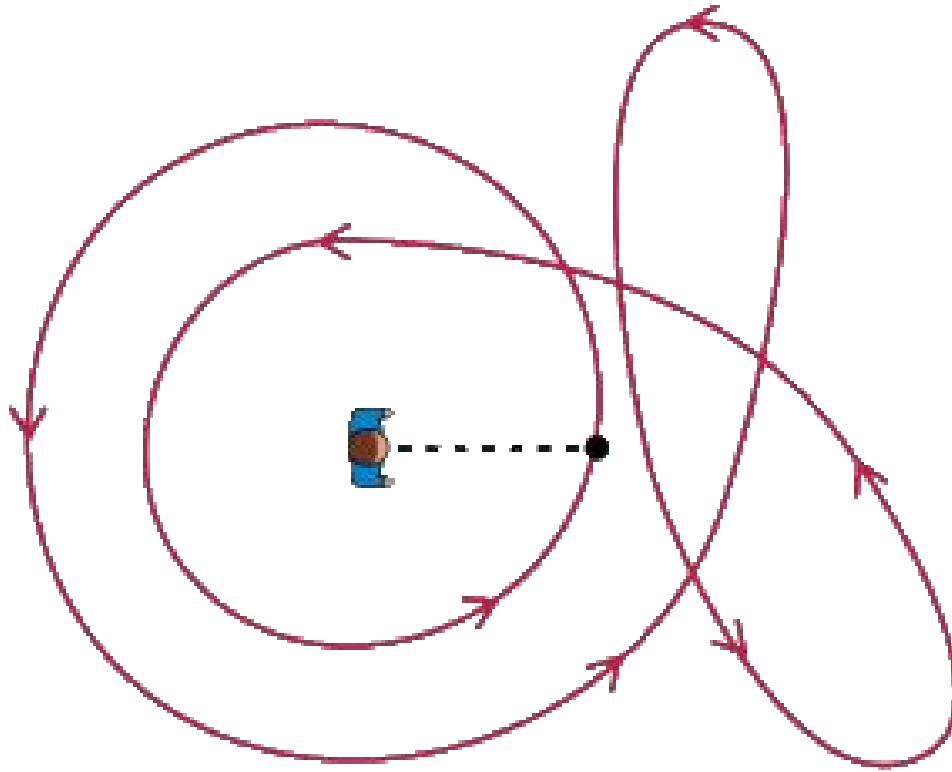
- Given point and polygon, is it inside it?
 - Lots of Materials: [See1](#), [See2](#), [See3](#), [See4](#)
- **Winding number algorithm**
 - One of most efficient and accurate algorithms
 - Originally was based on heavy *Angles Summation Test*
 - Then a more efficient way is invented
- Others [Not covered]
 - Crossing number algorithm

The winding number

- The total number of times that **curve/polygon** winds/travels around the point
 - counterclockwise motion +1
 - clockwise motion -1



The winding number



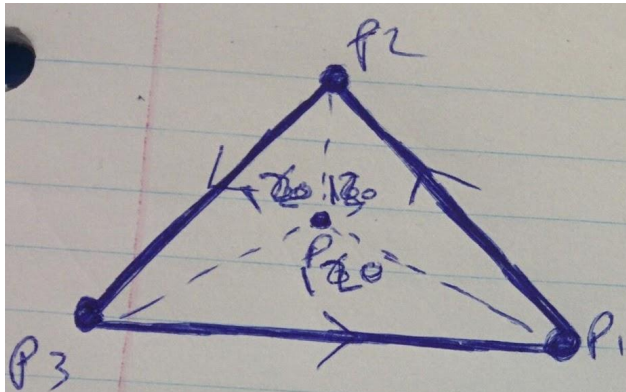
Src: https://en.wikipedia.org/wiki/Winding_number

The winding number

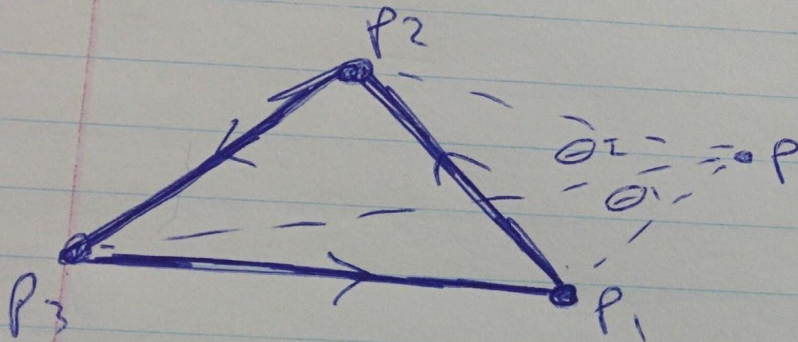
- Similar to iterating on edges to count rounds, one can iterate to sum the signed angles of point p with the polygon edges
 - Think in **signed angles** similar to computing Polygon area
 - E.g. areas cancellations similar to cancelling angles
- The summation will be either
 - 0 if point outside polygon
 - Multiple of 2π if inside polygon

$$\mathbf{wn}(P, \mathbf{C}) = \frac{1}{2\pi} \sum_{i=0}^{n-1} \theta_i$$

The winding number

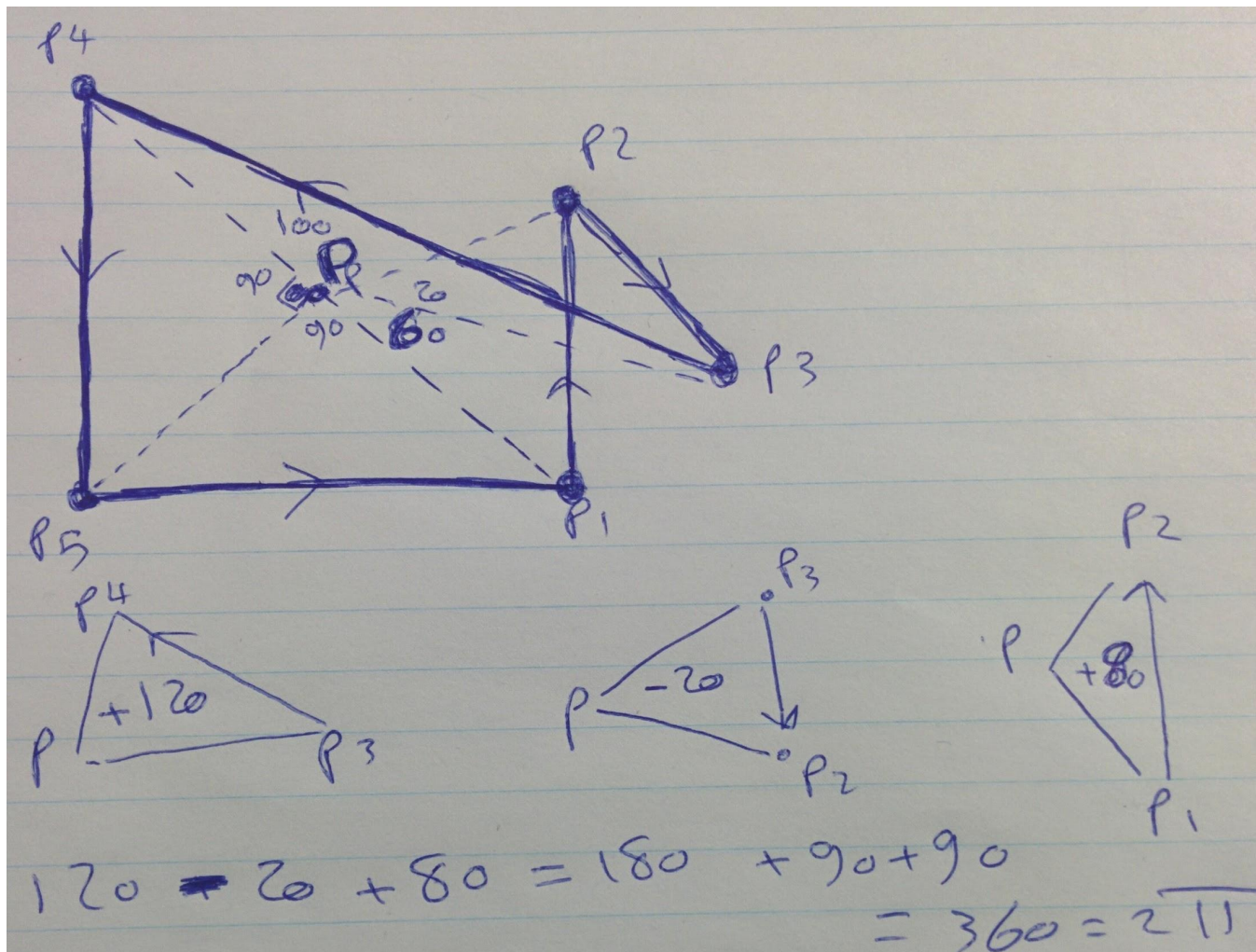


p creates 3 triangles
 p like circle
 has angles sum 360
 signed angle $p_1 p_2 p$ the
 wind number = 1

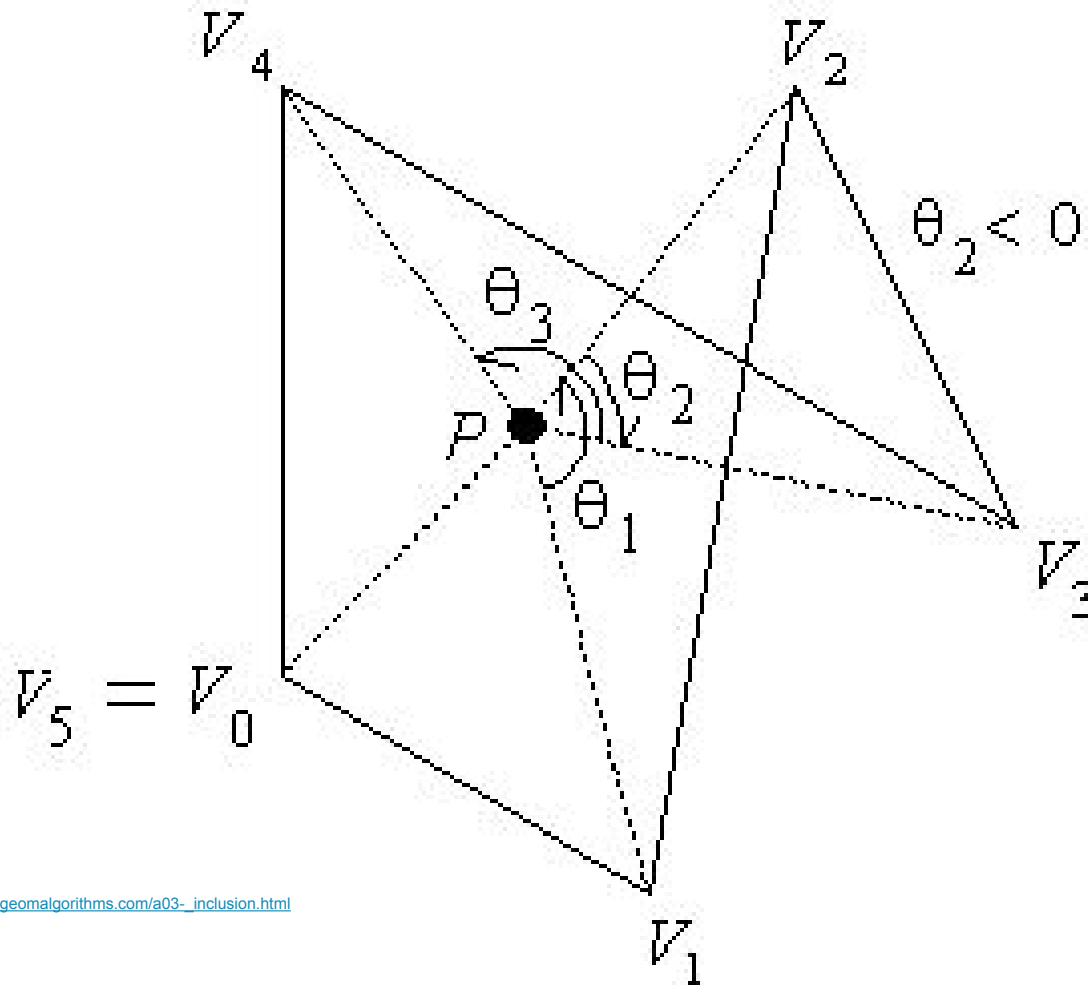


$\text{Area}(p_1 p_2 p) = -\theta_1 - \theta_2$
 $\text{Area}(p_2 p_3 p) = \theta_2$
 $\text{Area}(p_3 p_1 p) = \theta_1$
 Sum = Zero
 wind Number = 0

The winding number



The winding number



Src: <http://geomalgorithms.com/a03-inclusion.html>

The winding number: angle

■ Computing Min Angle between 2 vectors?

- Dot product theta is simply that

```
double fixAngle(double A) {  
    return A > 1 ? 1 : (A < -1 ? -1 : A);  
}  
  
// return min angle: a0b / b0a  
// dp(v1, v2) = |v1|*|v2|*cos(theta)  
double angle0(point a, point O, point b) {  
    point v1(a - O), v2(b - O);  
    return acos( fixAngle ( dp(v1, v2) / length(v1) / length(v2) ) );  
}
```

■ Or directly compute signed angle

- It uses 2 atan calls

The winding number: algorithm

```
// Easy idea, multiple precision concerns
bool isInsidePoly(vector<point> &p, point pt) {
    double anglesSum = 0;

    p.push_back(p[0]);
    for (int i = 0; i < sz(p) - 1; i++) {
        if (ccw(p[i], p[i + 1], pt) == 0) { // is pt on segment pi-pj?
            p.pop_back();
            return true;
        }
        anglesSum += angle0(p[i], pt, p[i + 1]) *
            ccw(pt, p[i], p[i + 1]); // angle pt-pi-pj is ccw?
    }
    p.pop_back();
    // Answer is either 0 (outside) or 2PI (inside)
    // return fabs(fabs(anglesSum) - 2 * PI) < EPS;
    return fabs(anglesSum) > PI; // let's avoid EPS comparison :)
}
```

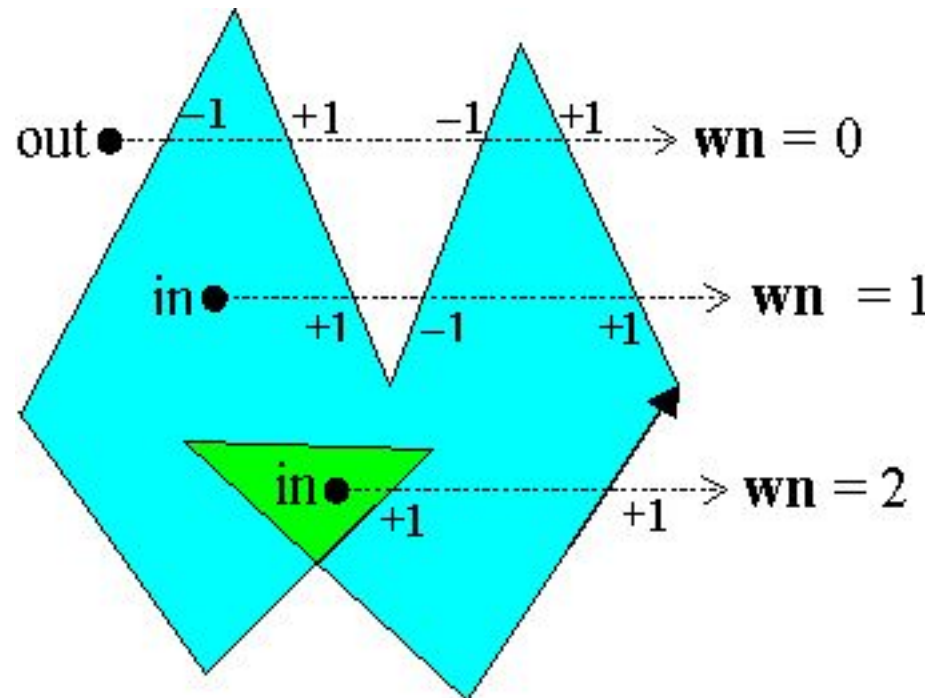
Note on the angles based style

- Easy idea, need careful implementation
 - In dp style, if did not fix angle before $\text{acos} \Rightarrow \text{nan}$
 - Be careful: 2 ccw calls with different points arrangement
 - Mistake: anglesSum shouldn't be initialized with 2PI
- Slow and precision concerns
 - Our code has much angles +/-
 - A very small EPS can causes WA (e.g. 1e-15 vs use **1e-8**)
 - But, Comparing against PI resolves EPS problem
- Summary
 - If coded correctly, the actual problem is being **slow**
 - Good lesson for how easy geom idea can be code killer

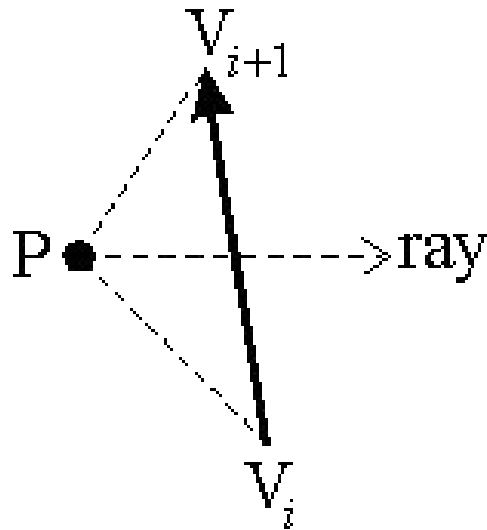
Equivalent Approach

- Draw horizontal ray from p to +ve x-axis
- Count signed edges. 0 means outside
- Special case

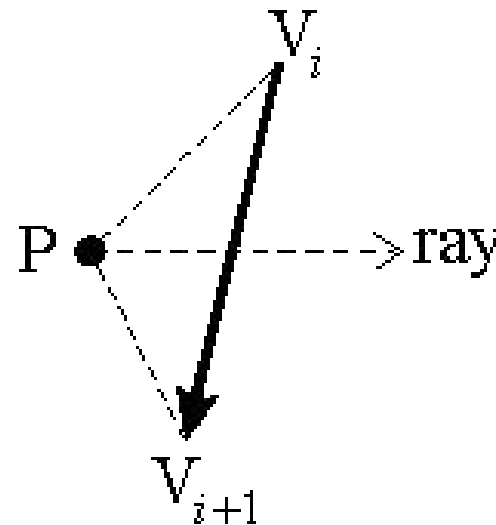
- the horizontal line
with horizontal edge
so test on edge
independently



How to check up/down ward?



upward
edge



downward
edge

- Using $P.Y$ verse $v1.Y$ can help know if it upward or downward
- Make sure using the $V2.Y$ to make sure P is between the edge 2 points
- Avoid Horizontal edges
- Test separately if point on segment

The winding number: algorithm

```
int isInsidePoly(vector<point> p, point p0) {  
    int wn = 0; // the winding number counter  
  
    for (int i = 0; i < sz(p); i++) {  
        point cur = p[i], nxt = p[(i + 1) % sz(p)];  
        if (isPointOnSegment(cur, nxt, p0))  
            return true;  
        if (cur.Y <= p0.Y) { // Upward edge  
            if (nxt.Y > p0.Y && cp(nxt-cur, p0-cur) > EPS)  
                ++wn;  
        } else { // Downward edge  
            if (nxt.Y <= p0.Y && cp(nxt-cur, p0-cur) < -EPS)  
                --wn;  
        }  
    }  
    return wn != 0;  
}
```

Optimizations for PIP test

- One easy optimization in case of too many such tests is to create a bounding box around the polygon
 - The tightest rectangle around polygon
 - If it is inside the box \Rightarrow call the test
 - If it is outside the box \Rightarrow false
 - Similar to Bbox, one can use Circle
- For convex polygon, we can do it in $O(\log n)$
 - See note about Preparata [algorithm](#). Also [Read](#) here

تم بحمد الله

علمكم الله ما ينفعكم

ونفعكم بما تعلمتم

وزادكم علماً