



# Competitive Programming

From Problem 2 Solution in  $O(1)$

## Coordinate Compression

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# Max people in room problem

- Given N pairs
  - each pair represents time someone enter/exit a room
- Given queries: query interval(start, end)
  - What is max # of people in room in the given interval?
- Input
  - (100, 150) (200, 300), (120, 450), (100, 300)
  - E.g. 1st user entered at  $t=100$ , leave at  $t=150$
  - Assume the times are big (e.g.  $10^{12}$ ), but  $N < 100$
- Query: 120 to 160

# Max people in room problem

|     |     |     |     |     |     |     |
|-----|-----|-----|-----|-----|-----|-----|
| 100 | 120 | 150 | 160 | 200 | 300 | 450 |
|-----|-----|-----|-----|-----|-----|-----|



Max # of people in the room from time=120 to time 160 = 3 persons

# Problem to solve

- Many algorithms can solve the problem well, if  $t$  is small (e.g.  $10^5$ )
- Coordinate Compression is to **simply** compress the values if we care about relative values NOT exact ones
- E.g. Sort all given distinct input values
  - 100, 120, 150, **160**, 200, 300, 450
- Map old values to the sorted order positions
  - 100=0, 120=1, 150 =2, 160=3, 200=4, 300=5, 450=6
- Recompute the input and solve problem

# Max people in room problem

|   |   |   |   |   |   |   |
|---|---|---|---|---|---|---|
| 0 | 1 | 2 | 3 | 4 | 5 | 6 |
|---|---|---|---|---|---|---|



Max # of people in the room from time=1 to time 3 = 3 persons

Now, you can just count ++ for the intervals in an array and compute answer

# Coordinate Compression

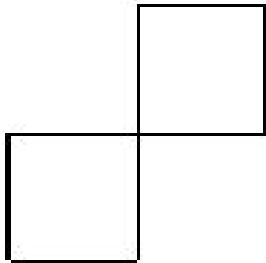
- A simple technique we apply by re-assigning **smaller** values to given input
- Typically happens when actual values are not needed (or not fully needed)
- We just compress it, **preserving** orders
  - E.g. if  $p1 < p2 \Rightarrow$  remains so
  - E.g. if line 1 above line 2  $\Rightarrow$  remains so
- Read all input/queries...sort them...reassign

# Count Holes Problem

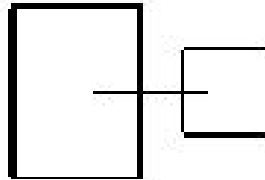
Given tin plates (rectangular e.g. 10000 x 10000)

Given series of horizontal or vertical segment cuts in it

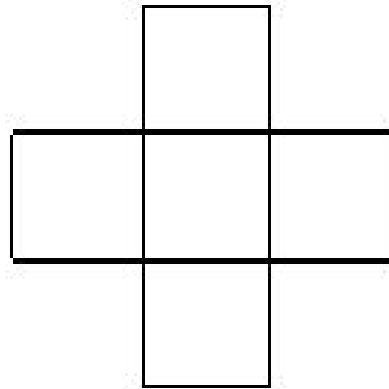
The cuts will cause **holes** in rectangular grid...How many?



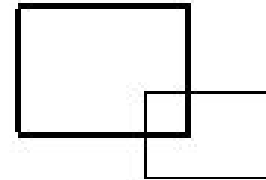
2 holes



2 holes

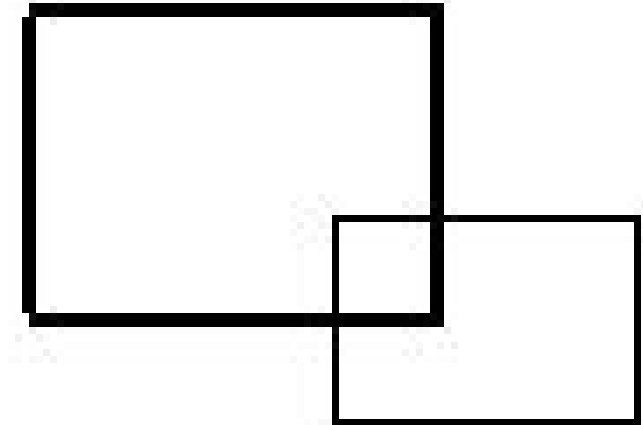
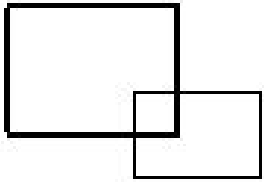


1 hole



1 hole

# Count Holes Problem



Assume we are given above 2 cases

- one of them has small 2 boxes...and one with 2 very big boxes (e.g. covering  $10^{18}$  area)
- The answer is **SAME!**
- If we can mark the given lines in 2D array...we can do BFS to compute holes

Key: **Compress coordinates** first

- Get all X's ... compress them
- Get all Y's ... compress them
- Reindex given input lines
- Mark lines in small 2D matrix...BFS to compute answer (avoid DFS, space large)



# Coordinate Compression

```
/*
 * {300, 10000, -5, -100, 300}
 *     start = 0, step = 1 ==> 2 3 1 0 2
 *     start = 2, step = 2 ==> 6 8 4 2 6
 */
vector<int> coordinate_compress(vector<int> x, int start = 0, int step = 1)
{
    set<int> unique(x.begin(), x.end());
    map<int, int> valPosMap;

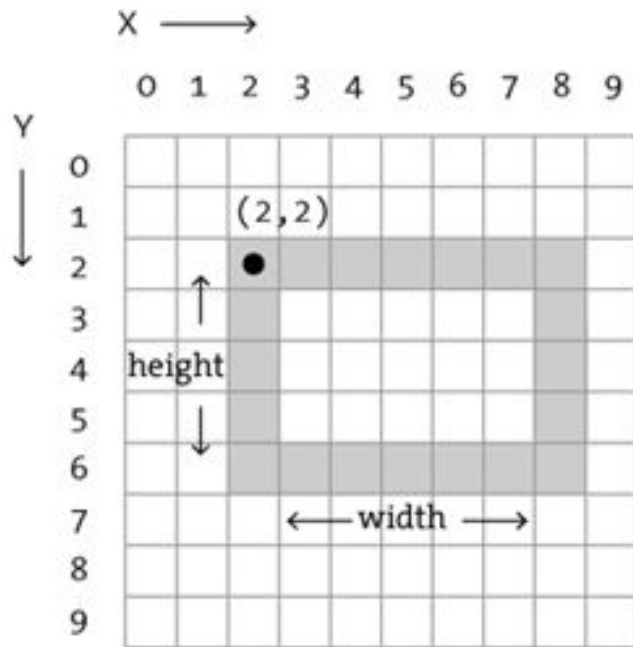
    int idx = 0;
    for(auto val : unique)
    {
        valPosMap[val] = start + idx * step;
        ++idx;
    }
    for(auto &x_pos : x)
        x_pos = valPosMap[x_pos];
    return x;
}
```

- In 1D, also known as “Interval Compression”
- Call it once for X..once for Y
- Sometimes we need to return **map** itself (e.g. map query indices)
- Start and step is based on problem
- Generally, start with 2 and step with 2 is cool

# Coordinate Compression

```
void coordinate_compress(vector<int> &axis, vector<int> &iToV,  
    map<int, int> &vToI, int start = 0, int step = 1) {  
    for (auto &x_pos : axis)  
        vToI[x_pos] = 0;  
  
    iToV.resize(start + step * vToI.size());  
    int idx = 0;  
  
    for (auto &entry : vToI)  
    {  
        entry.second = start + step * idx;  
        iToV[entry.second] = entry.first;  
        ++idx;  
    }  
    for (auto &x_pos : axis)  
        x_pos = vToI[x_pos];  
}
```

# Rectangle Vs Array Grid



`rect(x,y,width,height)`

Example:

`rect(2,2,7,5)`

Notice:

Lattice grid of **2x2**  
corresponds to **3x3 array**

If we interested in area..and marked in  
2d array, we will have larger area

solution: mark from start to end-1

```
// Mark rectangle (x1, y1) (x2, y2) in 2d array
// start inclusive and end exclusive
// line 0-2 is 2 units in array -> cell 0 and 1
for (int i = x1; i < x2; ++i)
    for (int j = y1; j < y2; ++j)
        grid[i][j] = 1;
```

# Overlapping Rectangles Area

- Given set of 2D axis aligned rectangles, find their area
  - Notice, we need original positions!
- Compress coordinates
  - Mark in 2D array
  - iterate on grid
  - If cell is covered, get its corresponding rectangle

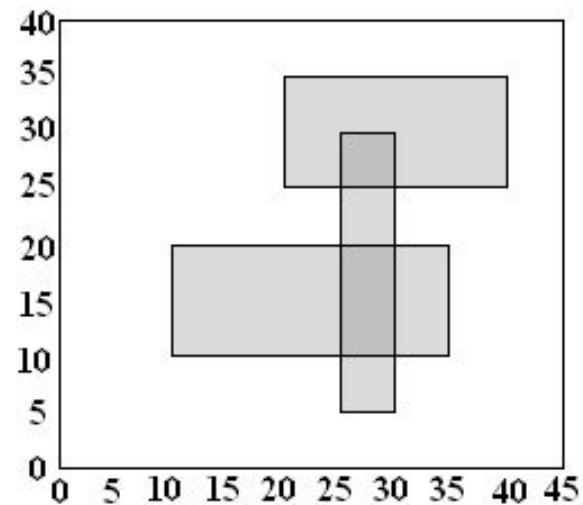
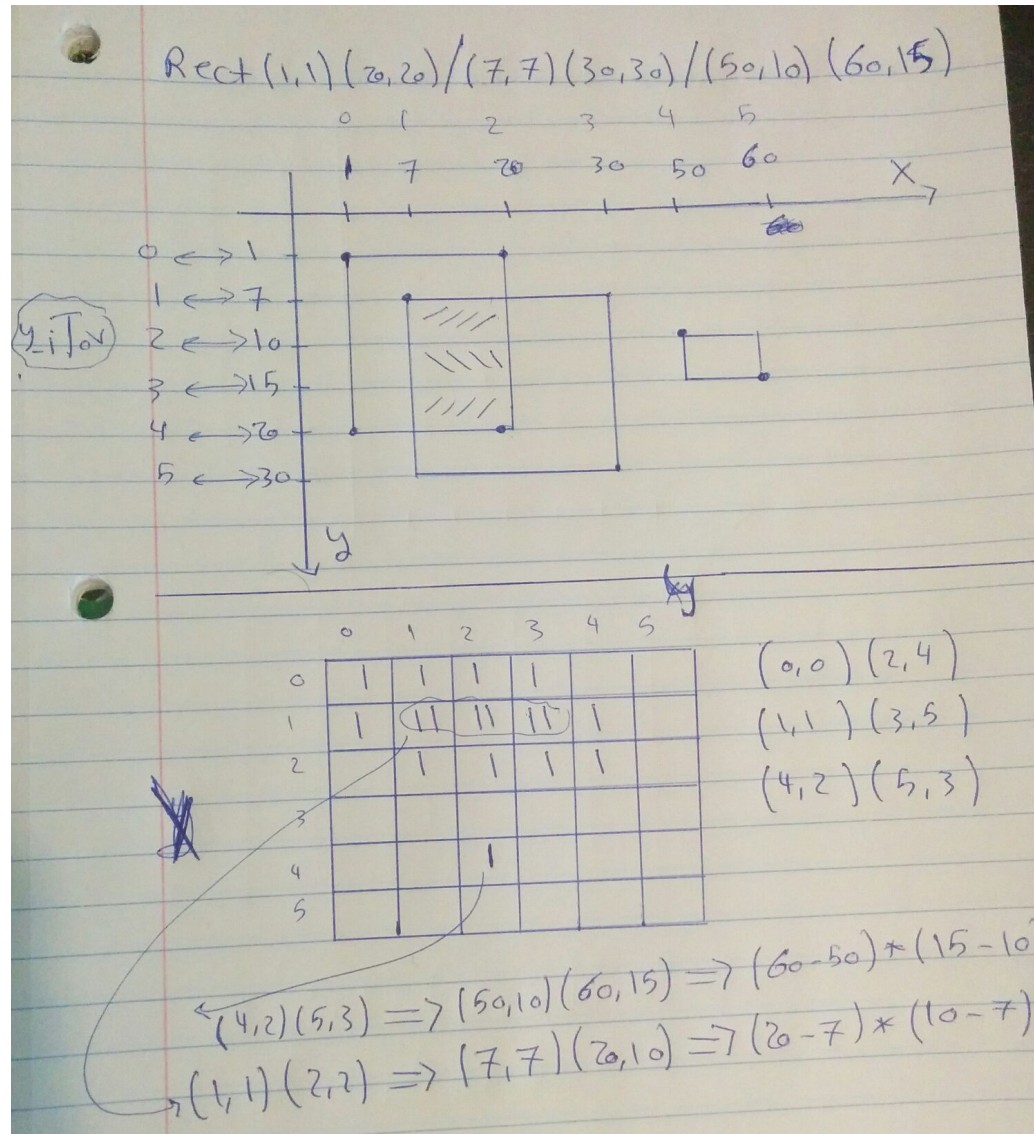


Photo Src: <https://icpcarchive.ecs.baylor.edu/external/41/p4171.png>

# Overlapping Rectangles Area



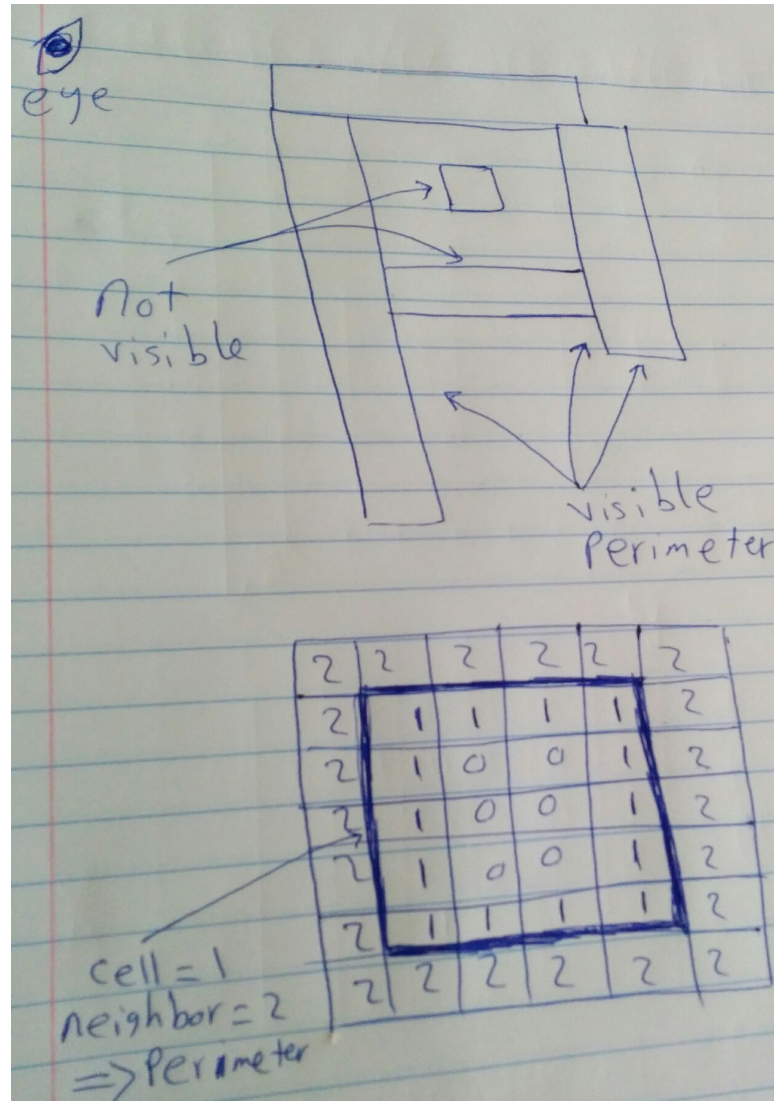
# Overlapping Rectangles Area

```
// To calc area of a shape, iterate on compressed grid,  
// i, +1 and j, j+1 forms 1x1 compressed rectangle  
// x_iToV is the mapping of i to it original coordinate  
int calArea(vector<int> & x_iToV, vector<int> & y_iToV) {  
    int area = 0;  
    rep(i, grid) rep(j, grid[0])  
        if (grid[i][j])  
            area += (x_iToV[i+1] - x_iToV[i]) *  
                    (y_iToV[j+1] - y_iToV[j]);  
    return area;  
}
```

# Overlapping Rectangles Perimeter

- Simply find positions where  $(x, y)$  is marked and then for each 4 directions find  $(xs, ys)$  that is not marked.
  - Then we have side (in the direction) to cover
- What about **visible** perimeter?
  - If looking to shapes from outside, enclosed perimeter not considered
  - Let 1 be marked, 0 inclosed, 2 visible (but not marked)
  - Run BFS from any external point, mark them 2
  - If  $p = 1$  and neighbour = 2  $\Rightarrow$  consider perimeter
- What about volumes? same logic

# Overlapping Rectangles Perimeter

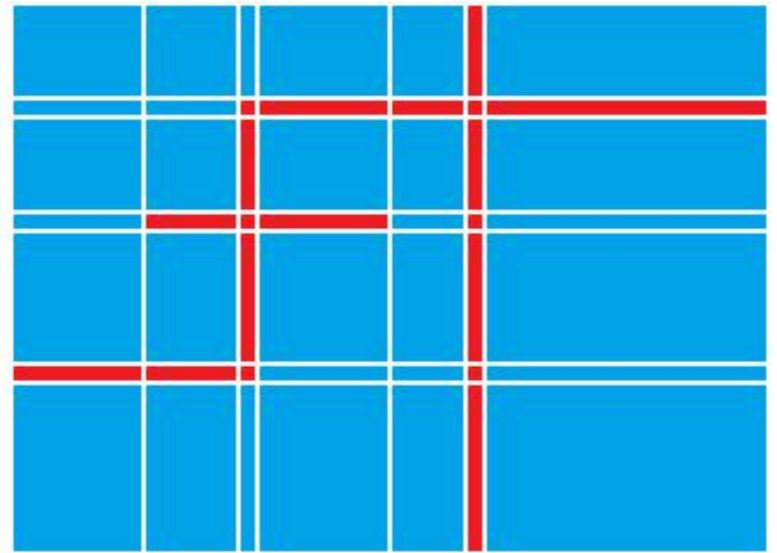
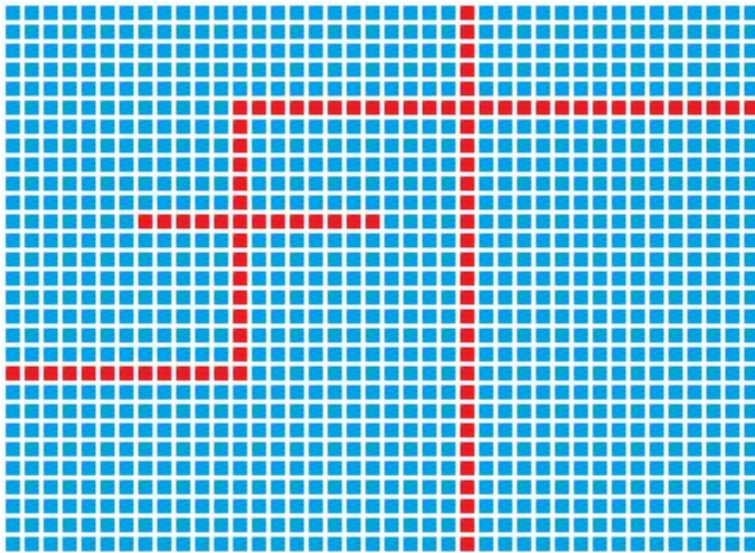




# 3D cubes volume surface

```
lp(i, MX) lp(j, MY) lp(k, MZ) {  
    ll x = ix[i + 1] - ix[i], y = iy[j + 1] - iy[j], z = iz[k + 1] - iz[k];  
    // (1 -> occupied), (0 -> space enclosed), (2, visible, not marked)  
    if (grid[i][j][k] != 2)  
    {  
        volume += x * y * z;  
        continue;  
    }  
  
    lp(d, 6) {  
        int nx = i + dx[d], ny = j + dy[d], nz = k + dz[d];  
        if (nx >= 0 && ny >= 0 && nz >= 0 && nx < MX &&  
            ny < MY && nz < MZ) {  
            if (grid[nx][ny][nz] != 2) //one face outside and another inside  
                surfacesArea += dx[d] ? y * z : dy[d] ? x * z : x * y;  
        }  
    }  
}
```

# Summary



# Summary

- Very large 1D/2D/3D inputs
- We only need relative positions
- Or relative positions are enough and map back to original values
- Start/Step between points based on problem
- Code may vary from problem to another

# تم بحمد الله

علمكم الله ما ينفعكم

ونفعكم بما تعلمتم

وزادكم علماً

# Problems

- SRM(277-D1-1000), Live Archive (4787)
- UVA (308, 10864)
- [3289 Robots inside the Labyrinth](#)
- [1019 Tin Cutter](#)
- [870 Intersecting Rectangles](#)
- [4171 Bulletin Board](#)
- [4291 Sculpture](#)
- [https://www.google.com.au/?client=firefox-a&hs=gi#hl=en&safe=off&q=coordinate+compression+site%3Aatopcoder.com&meta=&gws\\_rd=ssl](https://www.google.com.au/?client=firefox-a&hs=gi#hl=en&safe=off&q=coordinate+compression+site%3Aatopcoder.com&meta=&gws_rd=ssl)