



# Competitive Programming

From Problem 2 Solution in  $O(1)$

## Graph Theory

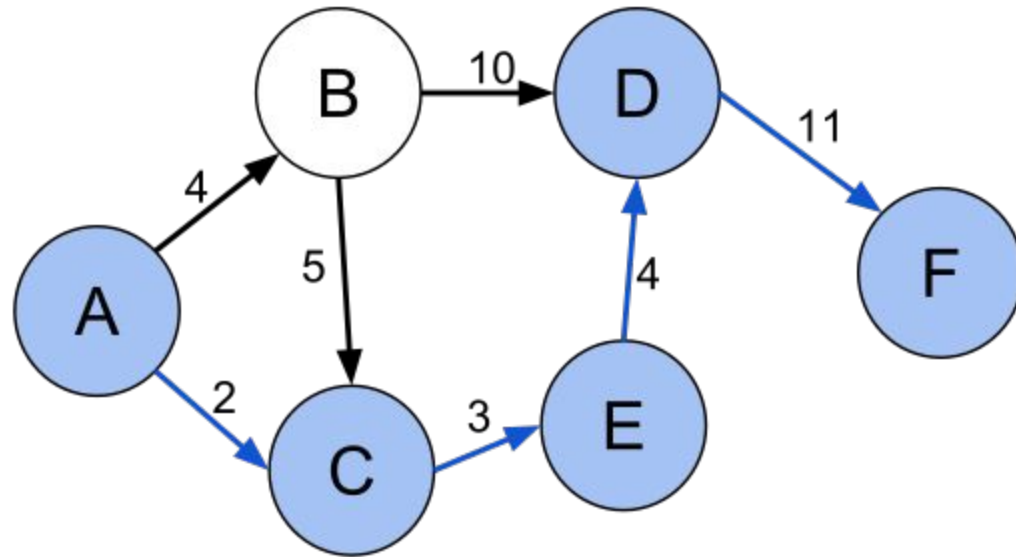
### Min Cost Max Flow using SSP

**Mostafa Saad Ibrahim**

PhD Student @ Simon Fraser University

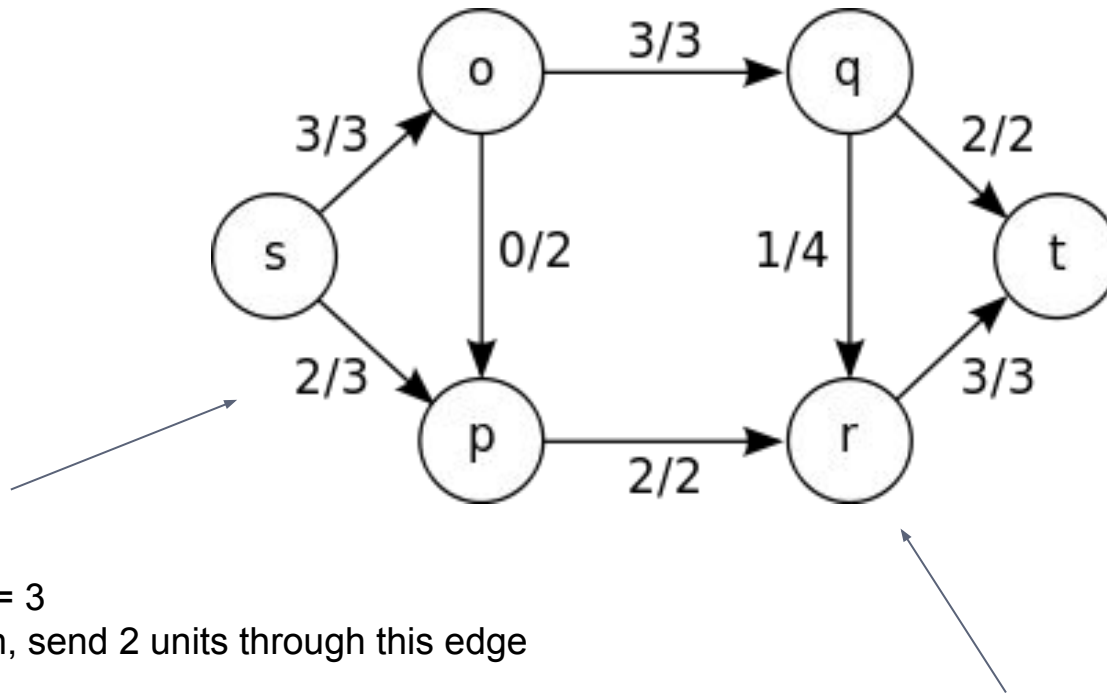


# Recall: Shortest Path



Path cost:  $2 + 3 + 4 + 11$

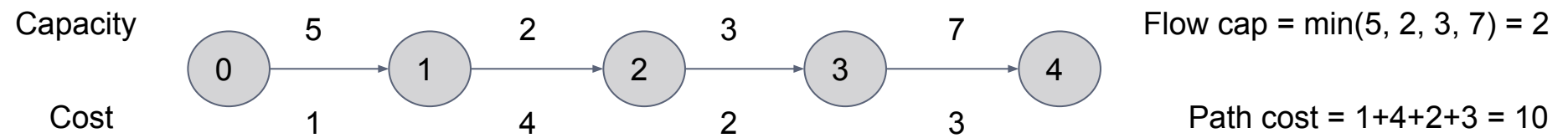
# Recall: Max Flow



Edge capacity = 3  
optimal solution, send 2 units through this edge

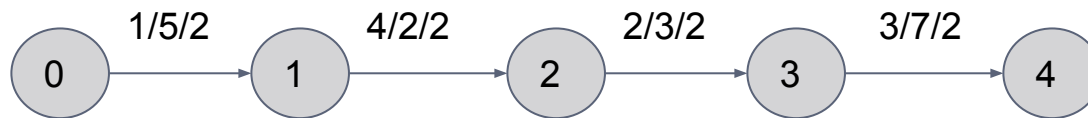
Input flow for r = 3 units  $\Rightarrow$  same as output

# Path Flow & Cost

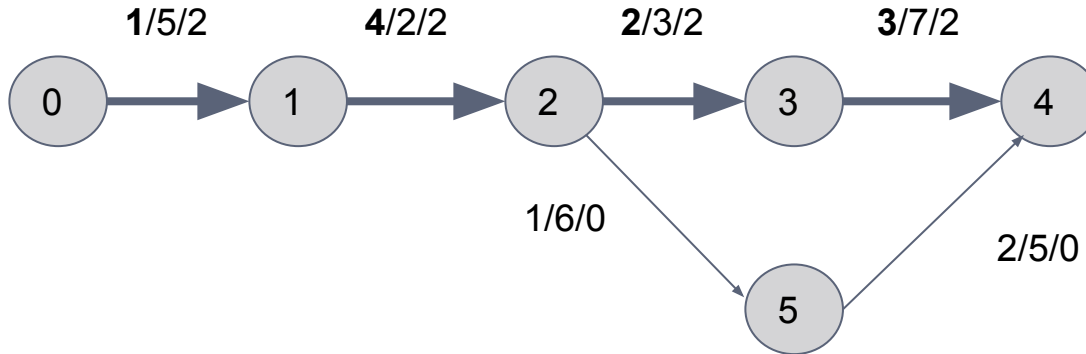


$$\text{Flow cost} = \sum \text{edge cost} * \text{flow} = 2 * 10 = 20$$

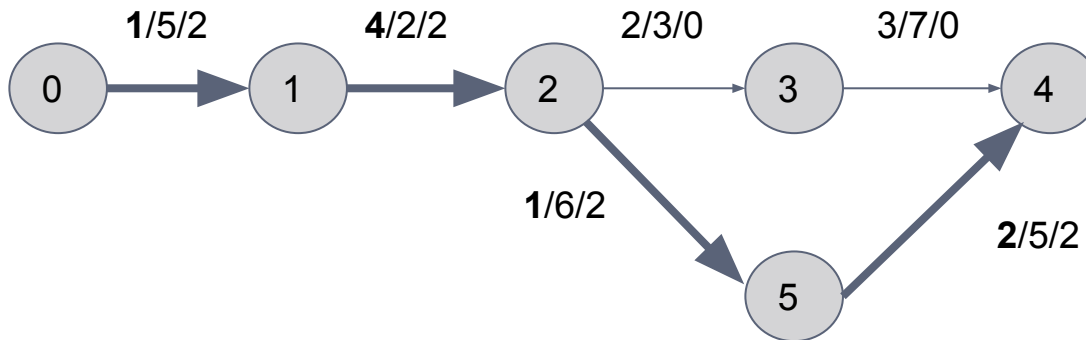
Notation: edge cost / edge cap / edge flow



# Multiple Max-Flow solutions!



Max Flow = 2, Cost =  $2 \cdot 10 = 20$



Max Flow = 2, Cost =  $2 \cdot 8 = 16$

Set all costs = 0  
⇒ Max Flow Problem

Remove Capacity Constraint  
⇒ Shortest Path Problem

# Min Cost Max Flow

- Among different **max** flow solutions, select one with min cost
- E.g. **first** criteria **max flow**, second min cost

# Successive shortest path algorithm

- Generalization of Ford–Fulkerson algorithm
- Instead of finding any path, find **shortest path**
- So keep finding optimal flow, but one with shortest value, hence lowest flow cost
- $O(n^2mB)$  using bellmanford
  - B is assigned to an upper bound on the largest supply of any node
  - Efficient Dijkstra with potentials:
  - $O(m \cdot \log(m) * \min(\text{flow}, n \cdot \text{flow\_cost}) )$

# Code consideration

- Recall, augmenting path can partially go with original edge  $(i, j)$  or cancel flow in edge  $(j, i)$ 
  - So cost of reverse edge need to be -ve
- For input edge  $(i, j)$ : Flow =  $f$ , Cost =  $c$ 
  - $\text{cap}[i][j] = f$ ,  $\text{cost}[i][j] = c$ ,  $\text{cost}[j][i] = -\text{cost}[i][j]$
- Then, every edge causes a cycle in cost matrix, but its sum is zero (e.g. no negative cycle)
  - However, this cycle doesn't exist in FIRST iteration as the flow in back edges is zero [Dijkstra with potentials]
- We need bellman ford algorithm (-ve values)

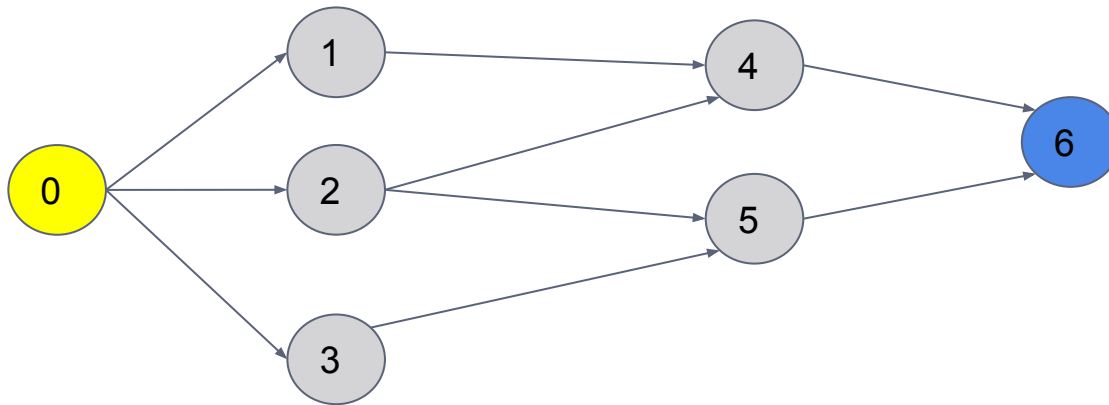


# Nodes indexing

- Same experience as max flow
- From graph to another, you may need to index
- For simplicity, assume following graph
  - Src node, sink node
  - R starting nodes, C ending nodes
  - Src connects to R nodes, C nodes connect to sink
  - Total:  $R+C+2$  nodes
  - Let  $\text{src} = 0$ ,  $\text{sink} = r+c+1$
  - R nodes indexed 1 to r
  - C nodes indexed  $r+1$ ,  $r+c$

# Nodes indexing

- Let  $R = 3$ ,  $C = 2$ , 5 edges between them



# Flow values

- Some flow values will be given, others won't
- Src/Sink edges may have value  $\infty$
- Intermediate edges typically have flow = 1
- Overall
  - Draw graph and index it based on problem nature
  - Think in missing flow values
  - Usually either  $\infty$  or some constant
- When computing shortest path
  - Ignore any edge with **capacity** = 0

# MCMF

## ■ Code

- As same as Ford code, just shortest path / cost added

## ■ while(true)

- Get **shortest path** from (src to dest)
  - Use only edges that has capacity > 0
- If no path = done
- Compute path flow (min value)
- Compute path cost: flow value \* shortest path value
- Augment path ( -flow, +flow)

# MCMF

```
pair<int, int> mcmf(vector< vi > capMax, vector< vector<int> > & costMax,
    int src, int dest)
{
    int maxFlow = 0, minCost = 0;
    while(true) {
        vector<edge> edgeList;

        repa(capMax) if(capMax[i][j] > 0)
            edgeList.push_back( edge(i, j, costMax[i][j]) );

        // return 2 vectors: first distances, 2nd previous array for paths
        pair<vi, vi> p = BellmanFord(edgeList, sz(capMax), src, dest);
        if(p.first[dest] >= +00)
            break; // no more paths

        int bottleNeck = 00; // get path flow
        lp(i, sz(p.second)-1 ) {
            int f = p.second[i], t = p.second[i+1];
            bottleNeck = min(bottleNeck, capMax[f][t]);
        }

        lp(i, sz(p.second)-1 ) { // augment path
            int f = p.second[i], t = p.second[i+1];
            minCost += bottleNeck * costMax[f][t];
            capMax[f][t] -= bottleNeck, capMax[t][f] += bottleNeck;
        }
        maxFlow += bottleNeck;
    }
    return make_pair(maxFlow, minCost);
}
```

# MCMF

```
lp(i, r)
    cin>>cap[0][i+1];
lp(j, c)
    cin>>cap[j+r+1][r+c+1];

int m;
cin>>m;

lp(k, m) {
    int i, j, cost;
    cin>>i>>j>>cost
    // Flow could be 1, 2...or could be given
    cap[i+1][j+r+1] = 00;
    cost[i+1][j+r+1] = v, cost1[j+r+1][i+1] = -cost[i+1][j+r+1];
}
```

# Min cost bipartite matching

## ■ Assignment problem

Persons	Job			
	J1	J2	J3	J4
I	86	78	62	81
II	55	79	65	60
III	72	65	63	80
IV	86	70	65	71
V	72	70	71	60

Src: <http://statistics-assignment.com/wp-content/uploads/2012/10/1285.png>

# Min cost bipartite matching

- Recall bipartite matching?
  - Once solved it by reducing it to max flow
  - Once solved it based on bipartite graph nature
- Minimum cost bipartite matching
  - Very similar style
  - Can be solved by reducing to MCMF .. just construct graph
  - Or solve based on bipartite graph nature (Hungarian)
- Hungarian algorithm solves it in  $O(N^3)$ 
  - [Link](#), [Russian site - explain/code](#), [Other code](#)



# Max Cost Max Flow

- And Max cost bipartite matching
- Recall that graph has no -ve cycles
- Hence, just multiple all costs with -1
- Compute cost, and multiply -1
  - E.g. Graph Costs  $\ast = -1$
  - $\text{ComputeMCMF} \Rightarrow \text{Flow} = 10, \text{cost} = -20$
  - $\text{cost} \ast = -1 \Rightarrow \text{cost} = 20 = \text{Max Cost Max Flow}$

# Reading

- Topcoder has 3 parts to [read](#)
- Bellman TLE?
  - Dijkstra with potentials. [Code](#). Very special case, as 1st iteration has no -ve values. In next iterations, we can control with potentials arrays
  - [SPFA](#). Same worst complexity, but generally faster. [Code](#).
- Your TODOs: Min-cost circulation
- More readings:
  - [Link 1](#). [Link 2](#).
  - [Cycle-Canceling Algorithm](#)

# تم بحمد الله

علمكم الله ما ينفعكم

ونفعكم بما تعلمتم

وزادكم علماً