Lecture 13: Optimization

CS 105 Fall 2023

Under the Abstraction Barrier

```
#include<stdio.h>
                            pushq %rbp
                                                         55
                                    %rsp, %rbp
                                                         48 89 e5
                            movq
                            subq $32, %rsp
                                                         48 83 ec 20
int main(int argc,
        char ** argv) {
                            leaq L .str(%rip), %rax
                                                         48 8d 05 25 00 00 00
                            movl $0, -4(%rbp)
                                                         c7 45 fc 00 00 00 00
 printf("Hello world!\n");
                            movl %edi, -8(%rbp)
                                                         89 7d f8
                            movq %rsi, -16(%rbp)
                                                         48 89 75 f0
 return 0;
                            movq %rax, %rdi
                                                         48 89 c7
                            movb $0, %al
                                                         b0 00
                            callq printf
                                                         e8 00 00 00 00
                            xorl %ecx, %ecx
                                                         31 c9
                            movl %eax, -20(%rbp)
                                                         89 45 ec
                            movl %ecx, %eax
                                                         89 c8
                            addq $32, %rsp
                                                         48 83 c4 20
                            popq %rbp
                                                          5d
                                                         с3
                            retq
```







Techniques for Improving Performance

1. Use better algorithms/data structures

2. Compile to efficient byte code

3. Write code that compiles to efficient byte code

4. Parallelize your execution

Optimizing Compilers

- Provide efficient mapping of program to machine code
 - register allocation
 - code selection and ordering (scheduling)
 - eliminating minor inefficiencies
- Compiler optimization flags
 - -00, -01, -02, -03, -0s, -0g
- Seldom improve asymptotic efficiency
 - up to programmer to select best overall algorithm
 - big-O savings are (often) more important than constant factors
 - but constant factors also matter

Eliminating Dead Code (-00)

```
int dead_code(int input) {
  if(47 > 0) {
    return input;
  } else {
    return -1 *input;
  }
}
```

```
int dead_code(int input) {
    return input;
}
```





```
dead_code:
   movl %edi, %eax
   ret
```

Code Motion (-O1)

- Reduce frequency with which computation is performed
- For example, move code out of a loop

```
void set row(int* a, int* b,
void set row(int* a, int* b,
            int i, int n) {
                                                     int i, int n) {
                                          int ni = n*i;
  for (int j = 0; j < n; j++) {
                                          for (int j = 0; j < n; j++) {
   a[n*i+j] = b[j]
                                            a[ni+j] = b[j];
                   set row:
                                   %ecx
                           testl
                                   .L1
                           ile
                           imull
                                   %ecx, %edx
                                   %edx, %ecx
                           addl
                    .L3:
                           movl (%rsi), %r8d
                           movslq %edx, %rax
                                   %r8d, (%rdi,%rax,4)
                           movl
                           addl $1, %edx
                           addq $4, %rsi
                           cmpl %ecx, %edx
                                   .L3
                           jne
                    .L1:
                           rep ret
```

Factoring out Subexpressions (-O1)

- Share common subexpressions
 - Gcc will do this with –O1

```
/* Sum neighbors of i,j */
up = val[(i-1)*n + j ];
down = val[(i+1)*n + j ];
left = val[i*n + j-1];
right = val[i*n + j+1];
sum = up + down + left + right;
```

long inj = i*n + j;
up = val[inj - n];
down = val[inj + n];
left = val[inj - 1];
right = val[inj + 1];
sum = up + down + left + right;

3 multiplications

1 multiplication

```
imulq %rcx, %rsi  # i*n
addq %rdx, %rsi  # i*n+j
movq %rsi, %rax
subq %rcx, %rax  # i*n+j-n
leaq (%rsi,%rcx), %rcx # i*n+j+n
```

Loop Elimination (-O1)

```
int loop_while(int a) {
  int b = 4;
  int i = 0;
  int result = 0;
  while (i < 16) {
    result += a;
    a -= b;
    i += b;
  }
  return result;
}</pre>
```

```
int loop_while(int a) {
  return 4*a-24;
}
```

```
loop_while:
    leal -24(,%rdi,4), %eax
    ret
```

Reduction in Strength (-O2)

- Replace costly operation with simpler one
- For example, replace multiplication with shift or addition

```
void set matrix(long* a, long* b,
                                      void set matrix(long* a, long* b,
                 long n) {
                                                        long n) {
                                         int ni = 0;
                                         for (long i = 0; i < n; i++) {
  for (long i = 0;
                     set matrix:
    long ni = n*i;
                             xorl
    for (long j =
                                           for (long j = 0; j < n; j++) {
                             testq
      a[ni + j] = k
                                             a[ni + j] = b[j];
                             leaq
                             jle
                     .L6:
                             xorl
                                           ni += n;
                     .L3:
                             movq
                             movq
}
                             addq
                                    %rax, %rdx
                             cmpq
                             jne
                                    . L3
                             addq
                                    $1, %r8
                                    %r9, %rdi
                             addq
                                    %r8, %rdx
                             cmpq
                                     .L6
                             ine
                      .L1:
                             rep ret
```

Machine Independent Optimization

- Compilers optimize assembly code
 - Dead code elimination
 - Code motion
 - Factoring out common subexpressions
 - Loop elimination
 - Reduction in Strength

Case Study: Vector Data Type

```
/* data structure for vectors */
typedef struct{
   long len;
   data_t* data;
} vec;
```

data_t will vary by example

- int
- long
- float
- double

```
/* get length of vector */
long vec_length(vec* v) {
   return v->len;
}
```

```
/* get address of vector element */
data_t* get_vec_elem(vec* v, long idx) {
    if (idx >= v->len) {
        return NULL;
    }
    return &(v->data[idx]);
}
```

Benchmark Computation

```
void combine1(vec* v, data_t* dest) {
    *dest = IDENT;

for(long i = 0; i < vec_length(v); i++) {
    data_t* val = get_vec_elem(v, i);
    *dest = *dest OP *val;
}
</pre>
```

Sum or product of vector elements

IDENT/OP may be 0/+ or 1/*

Metric: CPE, cycles per element

Time = CPE * n + Overhead

Benchmark Performance

```
void combine1(vec* v, data_t* dest) {
    *dest = IDENT;

for(long i = 0; i < vec_length(v); i++) {
    data_t* val = get_vec_elem(v, i);
    *dest = *dest OP *val;
}
</pre>
```

Method	Inte	ger	Double FP		
Operation	Add	Mult	Add	Mult	
Combine1 –O0	22.68	20.02	19.98	20.18	
Combine1 –O1	10.12	10.12	10.17	11.14	

Question: how could you optimize this code to get even better performance?

Limitations of Optimizing Compilers

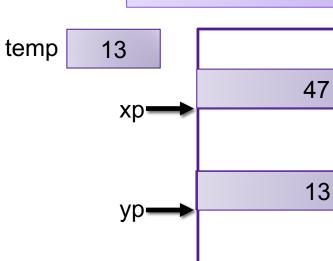
- 1. Must not cause any change in program behavior
 - Often prevents optimizations that would only affect behavior under pathological conditions.
 - Data ranges may be more limited than variable type suggests
 - Compiler cannot know run-time inputs
 - When in doubt, the compiler must be conservative

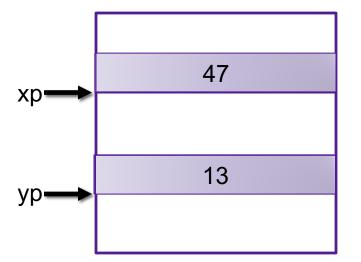
Limitations of Optimizing Compilers

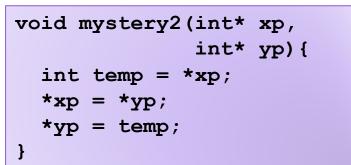


Exercise: What do each of these programs do? Do they do the same thing?

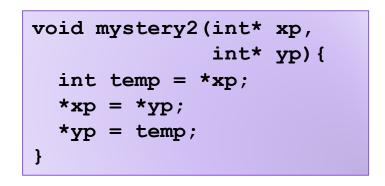
Comparing Programs

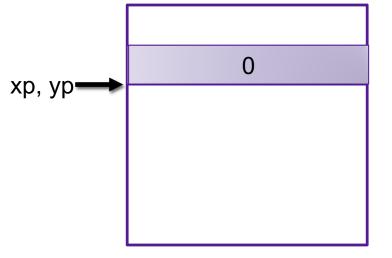


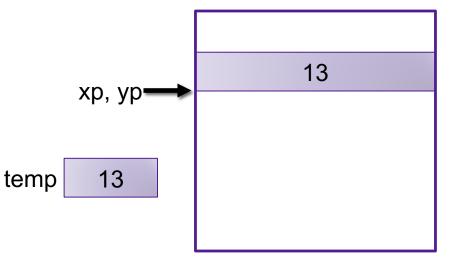




Comparing Programs





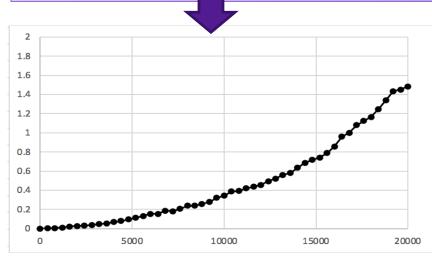


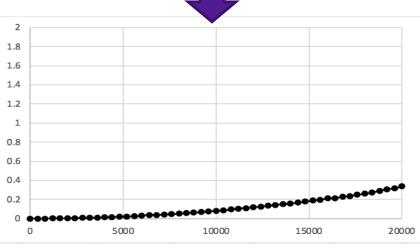
Optimization Blocker 1

- Aliasing: Two different references to a single location
 - Easy to happen in C

- Develop habit of introducing local variables
 - To accumulate within loops, for example
 - Your way of telling the compiler not to check for aliasing

Example: Summing Matrix Rows





Limitations of Optimizing Compilers

- 1. Must not cause any change in program behavior
 - Often prevents optimizations that would only affect behavior under pathological conditions.
 - Data ranges may be more limited than variable type suggests
 - Compiler cannot know run-time inputs
 - When in doubt, the compiler must be conservative
- 2. Most analysis is performed only within procedures
 - Whole-program analysis is too expensive in most cases
 - Newer versions of gcc do inter-procedural analysis within files

Exercise 2: Procedure Calls

Consider the following two functions. What do each of these programs do? Do they do the same thing?

```
long f1();
long f2(){
  return f1() + f1();
}
```



```
long f1();
long f2() {
  return 2*f1();
}
```

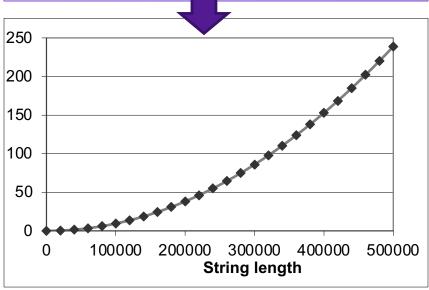
Optimization Blocker 2

- Compiler treats procedure calls as black boxes
 - Unknown side-effects
 - strlen may not always return the same value
- Alternatives:
 - Do your own code motion (necessary here)
 - Use inline keyword when declaring functions
 - gcc will optimize within a single file with -01

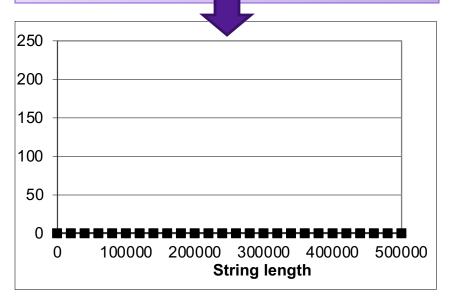
Example: Lowering Case

```
void lower(char* s) {
  int i;

for (i = 0; i < strlen(s); i++) {
   if (s[i] >= 'A' && s[i] <= 'Z') {
      s[i] -= ('A' - 'a');
    }
}</pre>
```



```
void lower(char* s) {
  int i;
  int len = strlen(s);
  for (i = 0; i < len; i++) {
    if (s[i] >= 'A' && s[i] <= 'Z') {
       s[i] -= ('A' - 'a');
    }
  }
}</pre>
```



Machine Independent Optimization

- Compilers optimize assembly code
 - Dead code elimination
 - Code motion
 - Factoring out common subexpressions
 - Loop elimination
 - Reduction in Strength
- Optimization blockers:
 - Aliasing
 - Use local variables
 - Procedure calls
 - Move them yourself

Exercise: Code-Level Optimizations

```
void combine1(vec* v, data_t* dest) {
   *dest = IDENT;

for(long i = 0; i < vec_length(v); i++) {
    data_t* val = get_vec_elem(v, i);
    *dest = *dest OP *val;
}
</pre>
```

Method	Inte	ger	Double FP		
Operation	Add Mult		Add	Mult	
Combine1 –O0	22.68	20.02	19.98	20.18	
Combine1 –O1	10.12	10.12	10.17	11.14	

Exercise: how could you optimize this code to get even better performance?

Exercise: Code-Level Optimizations

```
void combine1(vec* v, data t*
               dest) {
  *dest = IDENT;
  for(long i=0;i<vec length(v);</pre>
      i++) {
    data t* val=get vec elem(v,i);
    *dest = *dest OP *val;
```

Code-Level Optimizations

```
void combine2(vec* v, data_t* dest) {

  data_t x = IDENT;
  long length = vec_length(v);
  data_t* d = get_vec_element(v,0);
  for(long i = 0; i < length; i++) {
    x = x OP d[i];
  }
  *dest = x;
}</pre>
```

Method	Integer		Double FP		
Operation	Add	Mult	Add	Mult	
Combine1 –O0	22.68	20.02	19.98	20.18	
Combine1 –O1	10.12	10.12	10.17	11.14	
Combine2	1.27	3.01	3.01	5.01	

Loop Unrolling

```
int psum1(int a[],int sums[],int n) {
  int i;
  sums[0] = a[0];
  for(i = 1; i < n; i++) {
    sums[i] = sums[i-1] + a[i];
  }
}</pre>
```



```
int psum2(int a[],int sums[],int n) {
  int i;
  sums[0] = a[0];
  for(i = 1; i < n-1; i+=2) {
    sums[i] = sums[i-1] + a[i];
    sums[i+1] = sums[i] + a[i+1];
  }
  if (i < n) { // handle odd #iterations
    sums[i] = sum[i-1] + a[i];
  }
}</pre>
```

Combine with Unrolling

```
void unroll2_combine(vec* v, data_t* dest){
  long length = vec_length(v);
  long limit = length-1;
  data_t* d = get_vec_element(v,0);
  data_t x = IDENT;
  /* Combine 2 elements at a time */
  for(long i = 0; i < limit; i+=2) {
     x = (x OP d[i]) OP d[i+1];
  }
  /* Finish any remaining elements */</pre>
```

Method	Inte	eger	Double FP		
Operation	Add	Add Mult		Mult	
Combine1 –O0	22.68	20.02	19.98	20.18	
Combine1 –O1	10.12	10.12	10.17	11.14	
Combine2	1.27	3.01	3.01	5.01	
Unroll 2	1.01	3.01	3.01	5.01	
Latency Bound	1.00	3.00	3.00	5.00	

Reassociation

```
x = (x OP d[i]) OP d[i+1];
  1 d_0
```

x = x OP (d[i] OP d[i+1]);

Effect of Reassociation

Method	Inte	ger	Double FP		
Operation	Add	Mult	Add	Mult	
Combine1 –O0	22.68	20.02	19.98	20.18	
Combine1 –O1	10.12	10.12	10.17	11.14	
Combine2	1.27	3.01	3.01	5.01	
Unroll 2	1.01	3.01	3.01	5.01	
Unroll 2a	1.01	1.51	1.51	2.51	
Latency Bound	1.00	3.00	3.00	5.00	
Throughput Bound	0.50	1.00	1.00	0.50	

- Nearly 2x speedup for Int *, FP +, FP
 - Reason: Breaks sequential dependency

$$x = x OP (d[i] OP d[i+1]);$$

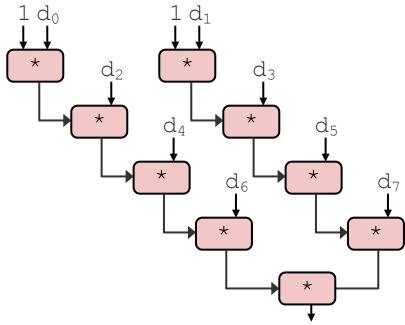
2 func. units for FP * 2 func. units for load

pipelined processor

4 func. units for int + 2 func. units for load

Separate Accumulators

```
void unroll2a combine (vec ptr v,
                        data t* dest)
    long length = vec length(v);
    long limit = length-1;
    data t* d = get vec element(v,0);
    data t x0 = IDENT;
    data t x1 = IDENT;
    long i;
    /* Combine 2 elements at a time */
    for (i = 0; i < limit; i+=2) {
       x0 = x0 \text{ OP } d[i];
       x1 = x1 \text{ OP } d[i+1];
    /* Finish any remaining elements */
    for (; i < length; i++) {
        x0 = x0 \text{ OP d[i]};
    *dest = x0 OP x1;
```



Two independent streams of operation

Effect of Separate Accumulators

Method	Inte	eger	Double FP		
Operation	Add	Mult	Add	Mult	
Combine1 –O0	22.68	20.02	19.98	20.18	
Combine1 –O1	10.12	10.12	10.17	11.14	
Combine2	1.27	3.01	3.01	5.01	
Unroll 2	1.01	3.01	3.01	5.01	
Unroll 2a	1.01	1.51	1.51	2.51	
Unroll 2x2	0.81	1.51	1.51	2.51	
Latency Bound	1.00	3.00	3.00	5.00	
Throughput Bound	0.50	1.00	1.00	0.50	

```
x0 = x0 \text{ OP d[i]};

x1 = x1 \text{ OP d[i+1]};
```

- Int + makes use of two load units
- for Int *, FP +, FP *, speedup similar to unroll with reassociation

Accumulators

Machine-Dependent Optimization

Integer Addition

FP *	Unrolling Factor L								
K	1	2	3	4	6	8	10	12	
1	1.27	1.01	1.01	1.01	1.01	1.01	1.01		
2		0.81		0.69		0.54			
3			0.74						
4				0.69		1.24			
6					0.56			0.56	
8						0.54			
10							0.54		
12								0.56	
6 8 10				0.09	0.56		0.54		

Float Multiplication

FP *	Unrolling Factor L									
K	1	2	3	4	6	8	10	12		
1	5.01	5.01	5.01	5.01	5.01	5.01	5.01			
2		2.51		2.51		2.51				
3			1.67							
4				1.25		1.26				
6					0.84			0.88		
8						0.63				
10							0.51			
12								0.52		
	K 1 2 3 4 6 8 10	K 1 1 5.01 2 3 4 6 8 10	K 1 2 1 5.01 5.01 2 2.51 3 4 6 8 10	K 1 2 3 1 5.01 5.01 5.01 2 2.51 3 1.67 4 6 8 10	K 1 2 3 4 1 5.01 5.01 5.01 5.01 2 2.51 2.51 3 1.67 4 1.25 6 8 10	K 1 2 3 4 6 1 5.01 5.01 5.01 5.01 2 2.51 2.51 3 1.67 4 1.25 6 0.84 8 10	K 1 2 3 4 6 8 1 5.01 5.01 5.01 5.01 5.01 5.01 2 2.51 2.51 2.51 3 1.67 4 1.25 1.26 6 0.84 8 0.63 10	K 1 2 3 4 6 8 10 1 5.01 5.01 5.01 5.01 5.01 5.01 2 2.51 2.51 2.51 2.51 3 1.67 1.26 0.84 6 0.84 0.63 10 0.51		

Machine-Dependent Optimization

Method	Integer		Doub	le FP
Operation	Add	Mult	Add	Mult
Combine1 –O0	22.68	20.02	19.98	20.18
Combine1 –O1	10.12	10.12	10.17	11.14
Combine2	1.27	3.01	3.01	5.01
Unroll 2	1.01	3.01	3.01	5.01
Unroll 2a	1.01	1.51	1.51	2.51
Unroll 2x2	0.81	1.51	1.51	2.51
Optimal Unrolling	0.54	1.01	1.01	0.51
Latency Bound	1.00	3.00	3.00	5.00
Throughput Bound	0.50	1.00	1.00	0.50

- Limited only by throughput of hardware
- Up to 42X improvement over original, unoptimized code