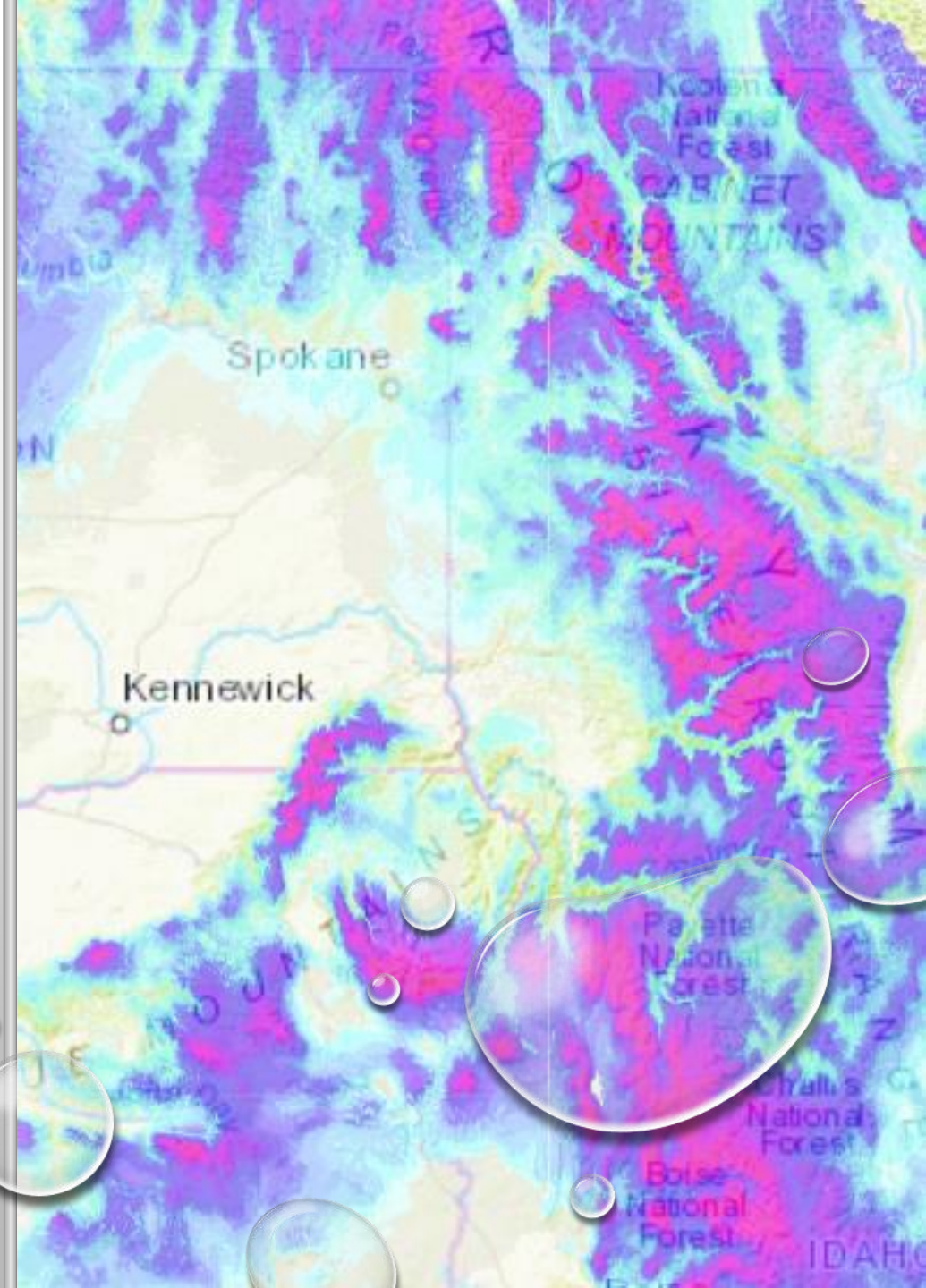


# Snowpack Prediction Challenge

By Git Forked - Team 2

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# Our Goal

- Create a spatio-temporal neural network trained on SNOTEL and meteorological data
- Would allow users to predict Snowpack trends in a given location throughout the year





# **Drive Behind the Snowpack challenge**

- Deploying an application to see Snowpack trends that provides reliable and accurate insights into the water cycle of the Western US to inform decisions on water storage, irrigation, and agriculture.
  - Monitor the effects of climate change on the local environment
  - Gain experience with neural networking
- 

# Tools

- **PyTorch**: Train our Neural Network model
- **GeoPandas**: Used to handle our large geospatial data set
- **Scikit-learn**: Used to pre-process data before modeling

# Data Cleanup & Research

- We first used GeoPandas to format the data, before using a spatial join to combine the SNOTEL Locations with related meteorological data based on their coordinates and date
- Once combined, we identified empty values and used mean imputation to fill them with an estimate based on recent data from the same location
- Pulled site number data from the NRCS and added them to our database for reference



# MODEL DESIGN

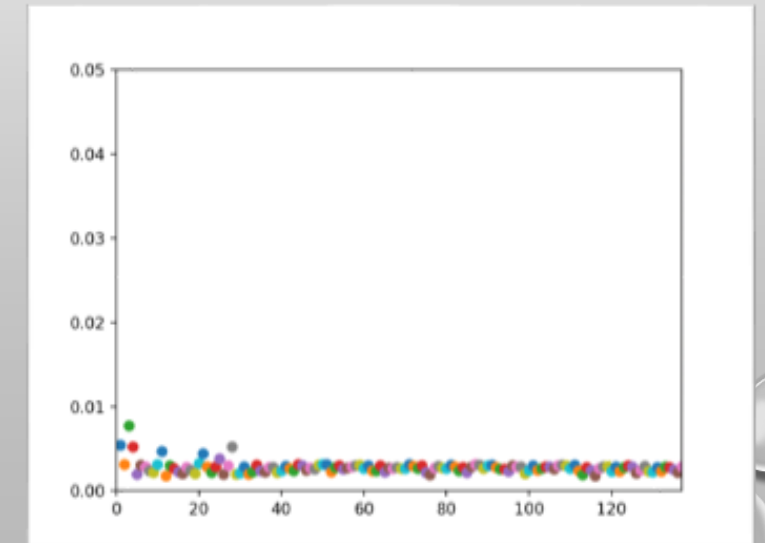
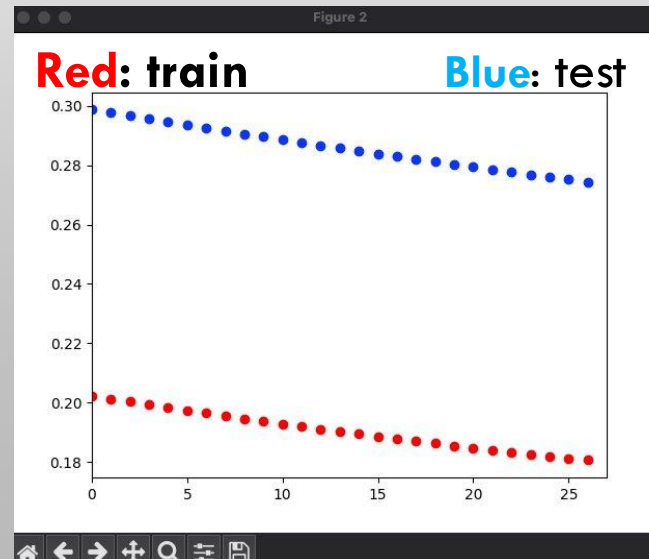
- LSTM MODEL FOR MAKING PREDICTIONS BASED ON PAST DATA
  - CUSTOM DATASET CALLED SWE DATASET CREATED TO LOAD WEATHER DATA
  - MAKES PREDICTIONS OF FUTURE SWE VALUES
  - NORMALIZE DATA IN SWE DATASET

```
class WeatherLSTM(nn.Module):
    def __init__(self, input_size, hidden_size, num_layers, output_size):
        super(WeatherLSTM, self).__init__()
        self.hidden_size = hidden_size
        self.num_layers = num_layers
        self.lstm = nn.LSTM(input_size, hidden_size, num_layers, batch_first=True)
        self.fc = nn.Sequential(
            nn.Linear(hidden_size, self.hidden_size, bias=True),
            nn.ReLU(),
            nn.Linear(self.hidden_size, output_size, bias=True),
        )

    def forward(self, x, h0=None, c0=None):
        if h0 is None or c0 is None:
            h0 = torch.zeros(self.num_layers, x.size(0), self.hidden_size).to(x.device)
            c0 = torch.zeros(self.num_layers, x.size(0), self.hidden_size).to(x.device)

        out, (hn, cn) = self.lstm(x) # lstm_out will have shape (batch_size, seq_len, hidden_size)
        # print(out)
        out = self.fc(out)
        # out = self.fc(out[-1, :])

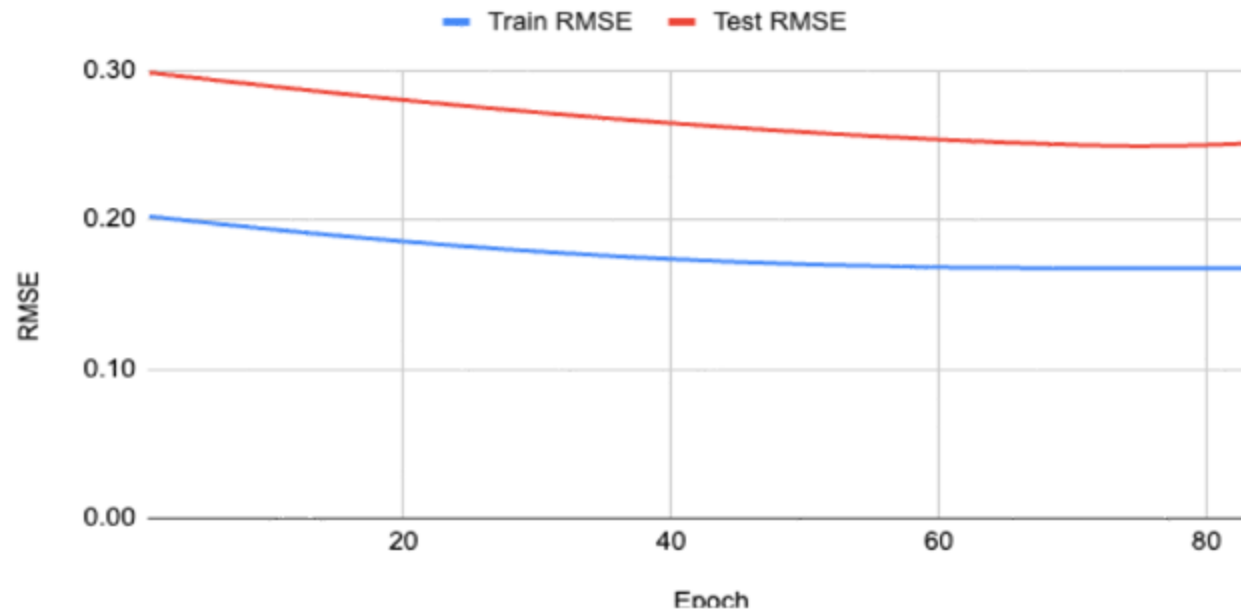
        return out, hn, cn
```



# Model info

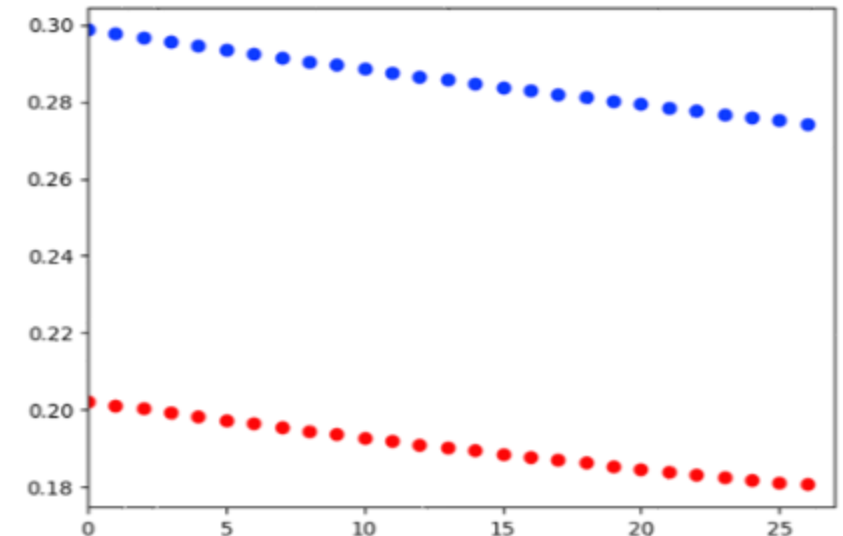
- Preprocessing: MinMaxScaler() from SciKitLearn: normalize each feature into a fixed range [0,1] to allow for faster training and predictions.
- Root Mean Square Error (RMSE)
  - Accuracy results inconclusive
  - Tested on Kamiak HPC

RMSE vs. Epoch



Blue: test

Red: train

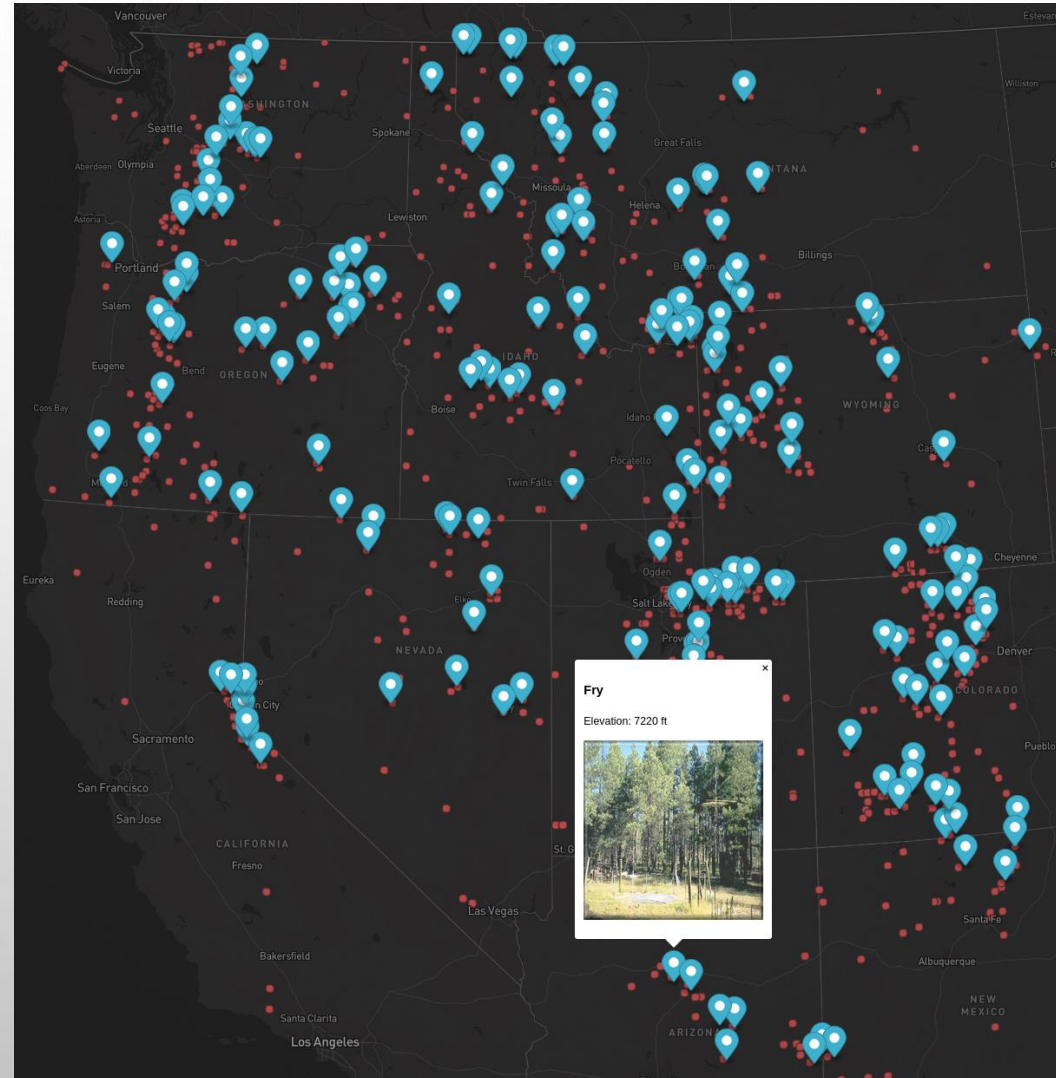


# Results

- Data Pre-processing pipeline
- Trained Models
  - Mixed Accuracy results
- Pipeline needs fine-tuning then ready for app implementation



# INTERACTIVE MAP



# CONCLUSION

