

Hoang Nguyen

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[Git-cpu17 \(Hoang Nguyen\) Ramieb/clinic-database-and-website.github.io](https://Git-cpu17(Hoang Nguyen).Ramieb/clinic-database-and-website.github.io)

EDUCATION

University of Houston, Houston, TX

Bachelor of Science, Computer Science

Expected May 2026

Lone Star College, Houston, Texas

Associate of Science, Computer Science

May 2024

GPA: 3.6

Relevant Coursework: Fundamentals of Operating Systems, Database Systems, Statistics for Science, Computer Organization, Programming Fundamentals III, Programming and Data Structure

PROJECT EXPERIENCE

Image Forgery Detection, University of Houston

Sept 2024-Dec 2024

- Developed and tested scalable image forgery detection models capable of analyzing 1,000+ images, addressing limitations of human visual inspection for large datasets.
 - Implemented forensic analysis tools to identify and mitigate digital image tampering, ensuring the authenticity and integrity of digital media.

Library Management, Personal Project

Jan 2024 – March 2024

- Engineered a command-line Library Management System in Python, streamlining book cataloging and circulation processes without requiring additional installations.
 - Implemented a greedy algorithm to optimize book search and management, enhancing user experience and operational efficiency.
 - Adhered to best practices and licensed the project under the MIT License, facilitating seamless user adoption and modification.

SKILLS & COMPETENCIES

Programming

Technical Replit, GitHub, MS Office, Data Processing, Front End

Language Bilingual in English & Vietnamese

HONORS

- Dean's list of NSM University of Houston 2024-2025
 - Champions Sunrise Rotary Club University Park Aug 2023 - Aug 2024
 - President's list of Lone Star University Park Aug 2021- May 2024

ACTIVITIES

Robotics Club

Sept 2023 - Aug 2024

- Engineered a 3D material transformation system, enhancing machine performance by 30% through data-driven optimizations and error reduction.
 - Developed autonomous navigation algorithms, enabling robots to efficiently clear obstacles and resolve path conflicts during transportation.