

Instruction Set Architecture

User Programmable Registers

Number	Nickname	Purpose
R0	zero	Zero
R1	-	General Purpose (Convention: Function Return Value)
R2-R12	-	General Purpose
R13	sp	Stack Pointer
R14	gp	Global Pointer
R15	pc	Program Counter

Instruction Formats

Register Type

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Opcode				Destination Register				Source Register 1				Source Register 2			

Immediate Type

* Register used for LD/ST operations

Jump Type

Instruction Set

Operand encodings are consistent across each format type. All register encoding results in a 4-bit binary number (since there are 16 registers). For the I-Type format there are 8-bit, signed binary numbers saved as the immediate/offset value. And for J-Type there are 12-bit, unsigned binary numbers saved for the address.

Instruction	Assembly	Format	Op-Code
No Operation	NOP	J-Type	0b0000
Addition	ADD	R-Type	0b0001
Subtraction	SUB	R-Type	0b0010
And	AND	R-Type	0b0011
Or	OR	R-Type	0b0100
Not	NOT	R-Type	0b0101
Move	MOV	I-Type	0b0110
Load	LD	R-Type	0b0111
Store	ST	R-Type	0b1000
Compare	CMP	R-Type	0b1001
Branch Equal	BEQ	I-Type	0b1010
Branch Not Equal	BNE	I-Type	0b1011
Jump	JMP	J-Type	0b1100
Jump Register	JR	R-Type	0b1101
Set Less Than	SLT	R-Type	0b1111

Examples

C	Assembly
short a = 5;	MOV r1, #5
short a,b=5,c=5; a=b+c;	MOV r2, #5 MOV r3, #5 ADD r1, r2, r3
short a,b=5,c=5; a=b-c;	MOV r2, #5 MOV r3, #5 SUB r1, r2, r3
short a = 3&5;	MOV r2, #3 MOV r3, #5 AND r1, r2, r3
short a = 3 5;	MOV r2, #3 MOV r3, #5 OR r1, r2, r3
short a = ~5;	MOV r2, #5 NOT r1, r2
short a = 3 == 3 ? 1 : 0;	MOV r1, #3 MOV r2, #3 CMP r1, r2 BEQ Equals MOV r3, #0 JMP Exit Equals: MOV r3, #1 Exit:
short a = 3 != 3 ? 1 : 0;	MOV r1, #3 MOV r2, #3 CMP r1, r2 BNE NotEquals MOV r3, #0 JMP Exit NotEquals: MOV r3, #1 Exit:

short a = 2 > 1 ? 1 : 0;	MOV r1, #1 MOV r2, #2 SLT r3, r1, r2 BNE TrueConditional MOV r1, #0 JMP Exit TrueConditional: MOV r1, #1 Exit:
short a = 2 <= 1 ? 1 : 0;	MOV r1, #1 MOV r2, #2 SLT r3, r1, r2 BEQ TrueConditional MOV r1, #0 JMP Exit TrueConditional: MOV r1, #1 Exit:
short a = 2 < 1 ? 1 : 0;	MOV r1, #1 MOV r2, #2 SLT r3, r2, r1 BNE TrueConditional MOV r1, #0 JMP Exit TrueConditional: MOV r1, #1 Exit:
short a = 2 >= 1 ? 1 : 0;	MOV r1, #1 MOV r2, #2 SLT r3, r2, r1 BEQ TrueConditional MOV r1, #0 JMP Exit TrueConditional: MOV r1, #1 Exit:

```
function my_function(int a) {  
    return a;  
}  
int main() {  
    short a = my_function(5);  
}
```

```
MOV r2, #5  
PUSH r2  
CALL my_function  
ADD r2, r1, zero  
  
my_function:  
POP r2  
ADD r1, r2, zero  
RET
```

```
function my_function(int *a) {  
    return *a;  
}  
int main() {  
    short a = 5;  
    short b = my_function(&a);  
}
```

```
# addr_a is the address of variable a  
# (named constant in this example code)  
MOV r2, #5  
ST [addr_a], r2  
ADD r3, zero, addr_a  
PUSH r3  
CALL my_function  
ADD r3, r1, zero  
JMP Exit  
  
my_function:  
POP r3  
LD r3, r3  
MOV r1, r3  
RET  
  
Exit:
```