

# PARALLEL COMPUTING FOR SCIENCE AND ENGINEERING

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Aren't there already enough books about parallel programming?

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# Chapter 1

## MPI

### 1.1 Basic concepts

#### 1.1.1 Initialization / finalization

Every program that uses MPI needs to initialize and finalize exactly once. In C, the calls are

```
ierr = MPI_Init(&argc, &argv);  
// your code  
ierr = MPI_Finalize();
```

where `argc` and `argv` are the arguments of the main program. The corresponding Fortran calls are

```
call MPI_Init(ierr)  
// your code  
call MPI_Finalize()
```

We make a few observations.

- MPI routines return an error code. In C, this is a function result; in Fortran it is the final parameter in the calling sequence.
- For most routines, this parameter is the only difference between the C and Fortran calling sequence, but some routines differ in some respect related to the languages. In this case, C has a mechanism for dealing with commandline arguments that Fortran lacks.
- This error parameter is zero if the routine completes successfully, and nonzero otherwise. You can write code to deal with the case of failure, but by default your program will simply abort on any MPI error. See section 1.2.1 for more details.

### 1.2 Errors and debugging

Errors in normal programs can be tricky to deal with; errors in parallel programs can be even harder. This is because in addition to everything that can go wrong with a single executable (floating point errors, memory violation) you now get errors that come from faulty interaction between multiple executables.

A few examples of what can go wrong:

- MPI errors: an MPI routine can abort for various reasons, such as receiving much more data than its buffer can accomodate. Such errors, as well as the more common type mentioned above, typically cause your whole execution to abort. That is, if one incarnation of your executable aborts, the MPI runtime will kill all others.
- Deadlocks and other hanging executions: there are various scenarios where your processes individually do not abort, but are all waiting for each other. This can happen if two processes are both waiting for a message from each other, and this can be helped by using non-blocking calls. In another scenario, through an error in program logic, one process will be waiting for more messages (including non-blocking ones) than are sent to it.

### 1.2.1 Error handling

The MPI library has a general mechanism for dealing with errors that it detects. The default behaviour, where the full run is aborted, is equivalent to your code having the following statement<sup>1</sup>:

```
MPI_Comm_set_errhandler_set (MPI_COMM_WORLD, MPI_ERRORS_ARE_FATAL) ;
```

Another simple possibility is to specify

```
MPI_Comm_set_errhandler_set (MPI_COMM_WORLD, MPI_ERRORS_RETURN) ;
```

which gives you the opportunity to write code that handles the error return value.

### 1.2.2 Debugging

## 1.3 Literature

Online resources:

- MPI 1 Complete reference:  
<http://www.netlib.org/utk/papers/mpi-book/mpi-book.html>
- Official MPI documents:  
<http://www.mpi-forum.org/docs/>
- List of all MPI routines:  
<http://www.mcs.anl.gov/research/projects/mpi/www/www3/>

Tutorial books on MPI:

- Using MPI [1] by some of the original authors.

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1. The routine `MPI_Errhandler_set` is deprecated.

## **Appendix A**

### **Practical tutorials**

here are some tutorials



## A.1 Debugging

When a program misbehaves, *debugging* is the process of finding out *why*. There are various strategies of finding errors in a program. The crudest one is debugging by print statements. If you have a notion of where in your code the error arises, you can edit your code to insert print statements, recompile, rerun, and see if the output gives you any suggestions. There are several problems with this:

- The edit/compile/run cycle is time consuming, especially since
- often the error will be caused by an earlier section of code, requiring you to edit, compile, and rerun repeatedly. Furthermore,
- the amount of data produced by your program can be too large to display and inspect effectively, and
- if your program is parallel, you probably need to print out data from all processors, making the inspection process very tedious.

For these reasons, the best way to debug is by the use of an interactive *debugger*, a program that allows you to monitor and control the behaviour of a running program. In this section you will familiarize yourself with *gdb*, which is the open source debugger of the *GNU* project. Other debuggers are proprietary, and typically come with a compiler suite. Another distinction is that *gdb* is a commandline debugger; there are graphical debuggers such as *ddd* (a frontend to *gdb*) or *DDT* and *TotalView* (debuggers for parallel codes). We limit ourselves to *gdb*, since it incorporates the basic concepts common to all debuggers.

In this tutorial you will debug a number of simple programs with *gdb* and *valgrind*. The files can be downloaded from <http://tinyurl.com/ISTC-debug-tutorial>.

### A.1.1 Invoking *gdb*

There are three ways of using *gdb*: using it to start a program, attaching it to an already running program, or using it to inspect a *core dump*. We will only consider the first possibility.

Here is an example of how to start *gdb* with program that has no arguments (Fortran users, use `hello.F`):

```
tutorials/gdb/c/hello.c
%% cc -g -o hello hello.c
# regular invocation:
%% ./hello
hello world
# invocation from gdb:
%% gdb hello
GNU gdb 6.3.50-20050815 # ..... version info
Copyright 2004 Free Software Foundation, Inc. .... copyright info ....
(gdb) run
Starting program: /home/eijkhout/tutorials/gdb/hello
Reading symbols for shared libraries +. done
hello world

Program exited normally.
```

```
(gdb) quit
%%
```

Important note: the program was compiled with the *debug flag* `-g`. This causes the *symbol table* (that is, the translation from machine address to program variables) and other debug information to be included in the binary. This will make your binary larger than strictly necessary, but it will also make it slower, for instance because the compiler will not perform certain optimizations<sup>1</sup>.

To illustrate the presence of the symbol table do

```
%% cc -g -o hello hello.c
%% gdb hello
GNU gdb 6.3.50-20050815 # ..... version info
(gdb) list
```

and compare it with leaving out the `-g` flag:

```
%% cc -o hello hello.c
%% gdb hello
GNU gdb 6.3.50-20050815 # ..... version info
(gdb) list
```

For a program with commandline input we give the arguments to the `run` command (Fortran users use `say.F`):

tutorials/gdb/c/say.c

```
%% cc -o say -g say.c
%% ./say 2
hello world
hello world
%% gdb say
.... the usual messages ...
(gdb) run 2
Starting program: /home/eijkhout/tutorials/gdb/c/say 2
Reading symbols for shared libraries +. done
hello world
hello world

Program exited normally.
```

---

1. Compiler optimizations are not supposed to change the semantics of a program, but sometimes do. This can lead to the nightmare scenario where a program crashes or gives incorrect results, but magically works correctly with compiled with debug and run in a debugger.

## A.1.2 Finding errors

Let us now consider some programs with errors.

### A.1.2.1 C programs

```
tutorials/gdb/c/square.c
```

```
%% cc -g -o square square.c
%% ./square
5000
Segmentation fault
```

The *segmentation fault* (other messages are possible too) indicates that we are accessing memory that we are not allowed to, making the program abort. A debugger will quickly tell us where this happens:

```
%% gdb square
(gdb) run
50000
```

```
Program received signal EXC_BAD_ACCESS, Could not access memory.
Reason: KERN_INVALID_ADDRESS at address: 0x000000000000eb4a
0x00007fff824295ca in __svfscanf_l ()
```

Apparently the error occurred in a function `__svfscanf_l`, which is not one of ours, but a system function. Using the `backtrace` (or `bt`, also `where` or `w`) command we quickly find out how this came to be called:

```
(gdb) backtrace
#0  0x00007fff824295ca in __svfscanf_l ()
#1  0x00007fff8244011b in fscanf ()
#2  0x0000000100000e89 in main (argc=1, argv=0x7fff5fbfc7c0) at square.c:7
```

We take a close look at line 7, and see that we need to change `nmax` to `&nmax`.

There is still an error in our program:

```
(gdb) run
50000
```

```
Program received signal EXC_BAD_ACCESS, Could not access memory.
Reason: KERN_PROTECTION_FAILURE at address: 0x000000010000f000
0x0000000100000ebe in main (argc=2, argv=0x7fff5fbfc7a8) at square1.c:9
9          squares[i] = 1./(i*i); sum += squares[i];
```

We investigate further:

```
(gdb) print i
$1 = 11237
(gdb) print squares[i]
Cannot access memory at address 0x10000f000
```

and we quickly see that we forgot to allocate `squares`.

By the way, we were lucky here: this sort of memory errors is not always detected. Starting our program with a smaller input does not lead to an error:

```
(gdb) run
50
Sum: 1.625133e+00

Program exited normally.
```

### A.1.2.2 Fortran programs

Compile and run the following program:

`tutorials/gdb/f/square.F` It should abort with a message such as ‘Illegal instruction’. Running the program in gdb quickly tells you where the problem lies:

```
(gdb) run
Starting program: tutorials/gdb//fsquare
Reading symbols for shared libraries +++. done

Program received signal EXC_BAD_INSTRUCTION, Illegal instruction/operand.
0x0000000100000da3 in square () at square.F:7
7           sum = sum + squares(i)
```

We take a close look at the code and see that we did not allocate `squares` properly.

### A.1.3 Memory debugging with Valgrind

Insert the following allocation of `squares` in your program:

```
squares = (float *) malloc( nmax*sizeof(float) );
```

Compile and run your program. The output will likely be correct, although the program is not. Can you see the problem?

To find such subtle memory errors you need a different tool: a memory debugging tool. A popular (because open source) one is *valgrind*; a common commercial tool is *purify*.

`tutorials/gdb/c/square1.c` Compile this program with `cc -o square1 square1.c` and run it with `valgrind square1` (you need to type the input value). You will lots of output, starting with:

```

%% valgrind square1
==53695== Memcheck, a memory error detector
==53695== Copyright (C) 2002-2010, and GNU GPL'd, by Julian Seward et al.
==53695== Using Valgrind-3.6.1 and LibVEX; rerun with -h for copyright info
==53695== Command: a.out
==53695==
10
==53695== Invalid write of size 4
==53695==    at 0x100000EB0: main (square1.c:10)
==53695==   Address 0x10027e148 is 0 bytes after a block of size 40 alloc'd
==53695==    at 0x1000101EF: malloc (vg_replace_malloc.c:236)
==53695==   by 0x100000E77: main (square1.c:8)
==53695==
==53695== Invalid read of size 4
==53695==    at 0x100000EC1: main (square1.c:11)
==53695==   Address 0x10027e148 is 0 bytes after a block of size 40 alloc'd
==53695==    at 0x1000101EF: malloc (vg_replace_malloc.c:236)
==53695==   by 0x100000E77: main (square1.c:8)

```

Valgrind is informative but cryptic, since it works on the bare memory, not on variables. Thus, these error messages take some exegesis. They state that a line 10 writes a 4-byte object immediately after a block of 40 bytes that was allocated. In other words: the code is writing outside the bounds of an allocated array. Do you see what the problem in the code is?

Note that valgrind also reports at the end of the program run how much memory is still in use, meaning not properly freed.

If you fix the array bounds and recompile and rerun the program, valgrind still complains:

```

==53785== Conditional jump or move depends on uninitialised value(s)
==53785==    at 0x10006FC68: __dtoa (in /usr/lib/libSystem.B.dylib)
==53785==    by 0x10003199F: __vfprintf (in /usr/lib/libSystem.B.dylib)
==53785==    by 0x1000738AA: vfprintf_l (in /usr/lib/libSystem.B.dylib)
==53785==    by 0x1000A1006: printf (in /usr/lib/libSystem.B.dylib)
==53785==    by 0x100000EF3: main (in ./square2)

```

Although no line number is given, the mention of `printf` gives an indication where the problem lies. The reference to an ‘uninitialized value’ is again cryptic: the only value being output is `sum`, and that is not uninitialized: it has been added to several times. Do you see why valgrind calls is uninitialized all the same?

#### A.1.4 Stepping through a program

Often the error in a program is sufficiently obscure that you need to investigate the program run in detail. Compile the following program

`tutorials/gdb/c/roots.c` and run it:

```
%% ./roots
```

```
sum: nan
```

Start it in gdb as follows:

```
%% gdb roots
GNU gdb 6.3.50-20050815 (Apple version gdb-1469) (Wed May  5 04:36:56 UTC 20
Copyright 2004 Free Software Foundation, Inc.
....
(gdb) break main
Breakpoint 1 at 0x100000ea6: file root.c, line 14.
(gdb) run
Starting program: tutorials/gdb/c/roots
Reading symbols for shared libraries +. done

Breakpoint 1, main () at roots.c:14
14          float x=0;
```

Here you have done the following:

- Before calling `run` you set a *breakpoint* at the main program, meaning that the execution will stop when it reaches the main program.
- You then call `run` and the program execution starts;
- The execution stops at the first instruction in main.

If execution is stopped at a breakpoint, you can do various things, such as issuing the `step` command:

```
Breakpoint 1, main () at roots.c:14
14          float x=0;
(gdb) step
15          for (i=100; i>-100; i--)
(gdb)
16          x += root(i);
(gdb)
```

(if you just hit return, the previously issued command is repeated). Do a number of steps in a row by hitting return. What do you notice about the function and the loop?

Switch from doing `step` to doing `next`. Now what do you notice about the loop and the function?

Set another breakpoint: `break 17` and do `cont`. What happens?

Rerun the program after you set a breakpoint on the line with the `sqrt` call. When the execution stops there do `where` and `list`.

- If you set many breakpoints, you can find out what they are with `info breakpoints`.
- You can remove breakpoints with `delete n` where `n` is the number of the breakpoint.
- If you restart your program with `run` without leaving `gdb`, the breakpoints stay in effect.
- If you leave `gdb`, the breakpoints are cleared but you can save them: `save breakpoints <file>`. Use `source <file>` to read them in on the next `gdb` run.

### A.1.5 Inspecting values

Run the previous program again in gdb: set a breakpoint at the line that does the `sqrt` call before you actually call `run`. When the program gets to line 8 you can do `print n`. Do `cont`. Where does the program stop?

If you want to repair a variable, you can do `set var=value`. Change the variable `n` and confirm that the square root of the new value is computed. Which commands do you do?

If a problem occurs in a loop, it can be tedious keep typing `cont` and inspecting the variable with `print`. Instead you can add a condition to an existing breakpoint: the following:

```
condition 1 if (n<0)
```

or set the condition when you define the breakpoint:

```
break 8 if (n<0)
```

Another possibility is to use `ignore 1 50`, which will not stop at breakpoint 1 the next 50 times.

Remove the existing breakpoint, redefine it with the condition `n<0` and rerun your program. When the program breaks, find for what value of the loop variable it happened. What is the sequence of commands you use?

### A.1.6 Further reading

A good tutorial: <http://www.dirac.org/linux/gdb/>.

Reference manual: [http://www.ofb.net/gnu/gdb/gdb\\_toc.html](http://www.ofb.net/gnu/gdb/gdb_toc.html).

## Appendix B

### Codes

#### B.1 TAU profiling and tracing

TAU <http://www.cs.uoregon.edu/Research/tau/home.php> is a utility for profiling and tracing your parallel programs. Profiling is the gathering and displaying of bulk statistics, for instance showing you which routines take the most time, or whether communication takes a large portion of your runtime. When you get concerned about performance, a good profiling tool is indispensable.

Tracing is the construction and displaying of time-dependent information on your program run, for instance showing you if one process lags behind others. For understanding a program's behaviour, and the reasons behind profiling statistics, a tracing tool can be very insightful.

TAU works by adding *instrumentation* to your code: in effect it is a source-to-source translator that takes your code and turns it into one that generates run-time statistics. Doing this instrumentation is fortunately simple: start by having this code fragment in your makefile:

```
ifdef TACC_TAU_DIR
    CC = tau_cc.sh
else
    CC = mpicc
endif

% : %.c
${CC} -o $@ $^
```



## Bibliography

- [1] W. Gropp, E. Lusk, and A. Skjellum. *Using MPI*. The MIT Press, 1994.

## **Appendix C**

### **Index and list of acronyms**

**AMR** Adaptive Mesh Refinement

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